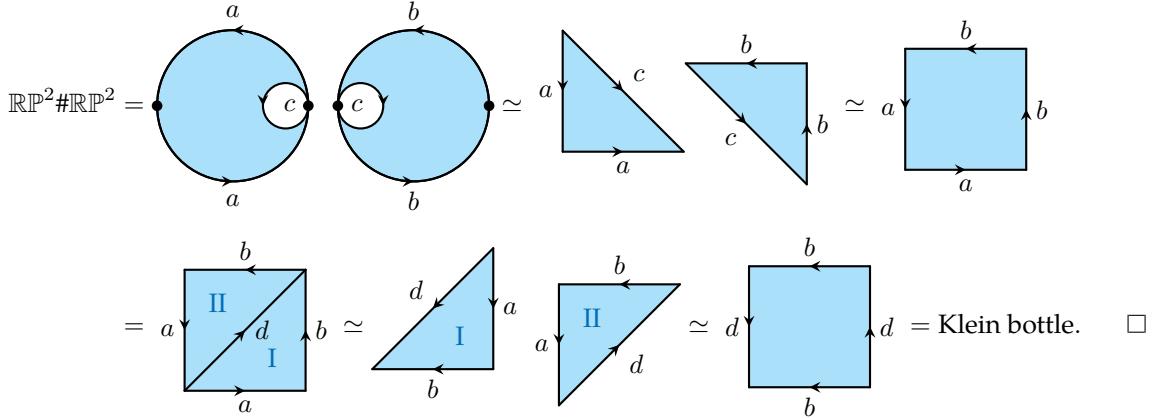


For latest updates of this note, visit <https://xiaoshuo-lin.github.io/001707E>.

**Problem 1** Show that  $\mathbb{RP}^2 \# \mathbb{RP}^2$  is homeomorphic to the Klein bottle.

**Proof** Viewing  $\mathbb{RP}^2$  as a unit disk with antipodal points on the boundary identified, one gets



**Problem 2** Show that the **comb space**

$$C := (\{0\} \times [0, 1]) \cup (\{1/n : n \in \mathbb{N}\} \times [0, 1]) \cup ([0, 1] \times \{0\}) \subset \mathbb{R}^2$$

is not triangulable.

**Proof** By investigating the neighborhood of the point  $(0, 1/2)$ , one sees that  $C$  is not locally path-connected. However, any simplicial complex is locally path-connected, so  $C$  cannot be homeomorphic to the underlying space of any simplicial complex.  $\square$

**Problem 3** For any triangulation of a *closed* surface with  $v$  vertices,  $e$  edges, and  $f$  faces, show that

- (1)  $3f = 2e$ .
- (2)  $e = 3(v - \chi)$ .
- (3)  $v \geq \frac{1}{2}(\sqrt{49 - 24\chi} + 7)$ .

Here  $\chi := v - e + f$  is the **Euler characteristic** of the surface.

**Proof** (1) Each face has three edges, and each edge is shared by two faces, so  $3f = 2e$ .

(2) From the definition of  $\chi$  and the result in (1), we have  $\chi = v - e + \frac{2}{3}e = v - \frac{1}{3}e$ .

(3) Using the result in (1), we have

$$\begin{aligned} (2v - 7)^2 - (49 - 24\chi) &= 4(v^2 - 7v + 6\chi) \\ &= 4[v^2 - 7v + 6(v - e + \frac{2}{3}e)] \\ &= 4[(v - e)]. \end{aligned}$$

Since any two vertices can be connected by at most one edge, we have  $e \leq \binom{v}{2}$ , so  $(2v - 7)^2 \geq 49 - 24\chi$ . Solving this inequality for  $v$  gives the desired result.  $\square$

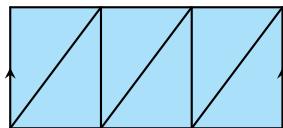
**Remark** Combining these results, one obtains

$$f = 2v - 2\chi \geq 2 \left[ \frac{1}{2} \left( \sqrt{49 - 24\chi} + 7 \right) \right] - 2\chi. \quad (\text{P3-1})$$

The results of Ringel and Jungerman<sup>1</sup> show that the equality in (P3-1) is attained for all closed surfaces except for  $\mathbb{T}^2 \# \mathbb{T}^2$ ,  $\mathbb{RP}^2 \# \mathbb{RP}^2$  (the Klein bottle), and  $\mathbb{RP}^2 \# \mathbb{RP}^2 \# \mathbb{RP}^2$ . In these three exceptional cases, the minimal number of faces in a triangulation is 24, 16, and 20, respectively. //

**Problem 4** Construct a triangulation for the cylinder.

**Solution** A triangulation for the cylinder is given by



□

**Remark** Some might think that somewhat simpler choices exist, Figure 1, for example. This is, however, not a triangulation since, for  $\sigma_2 = \langle A, B, C \rangle$  and  $\sigma'_2 = \langle C, D, A \rangle$ , we find that  $\sigma_2 \cap \sigma'_2 = \langle A \rangle \cup \langle C \rangle$  is not a face of either  $\sigma_2$  or  $\sigma'_2$ .

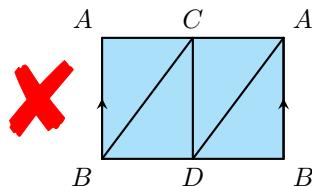
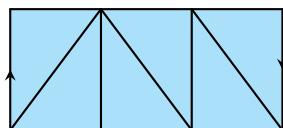


Figure 1: An **incorrect** triangulation for the cylinder

**Problem 5** Construct a triangulation for the Möbius strip.

**Solution** A triangulation for the Möbius strip is given by



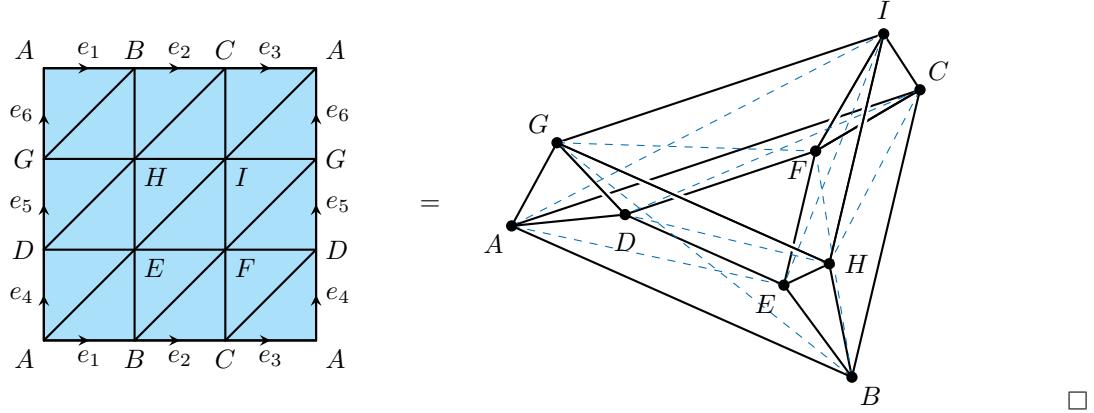
□

**Problem 6** Construct a triangulation for the torus  $\mathbb{T}^2$ .

---

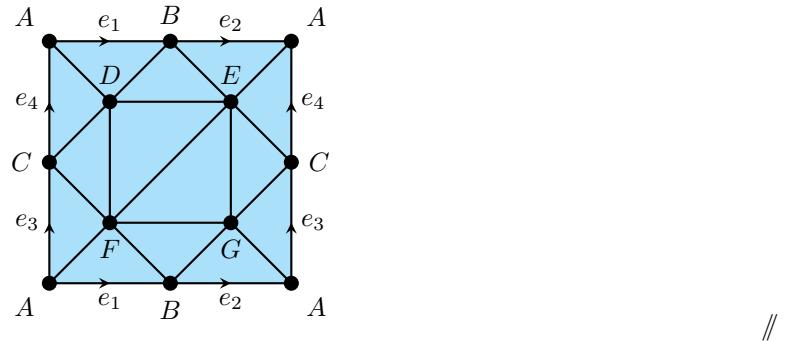
<sup>1</sup>Ringel, G. Wie man die geschlossenen nichtorientierbaren Flächen in möglichst wenig Dreiecke zerlegen kann. *Math. Ann.* 130, 317–326 (1955). <https://doi.org/10.1007/BF01343898>; Jungerman, M., Ringel, G. Minimal triangulations on orientable surfaces. *Acta Math.* 145, 121–154 (1980). <https://doi.org/10.1007/BF02414187>.

**Solution** A triangulation for the  $\mathbb{T}^2$  is given by



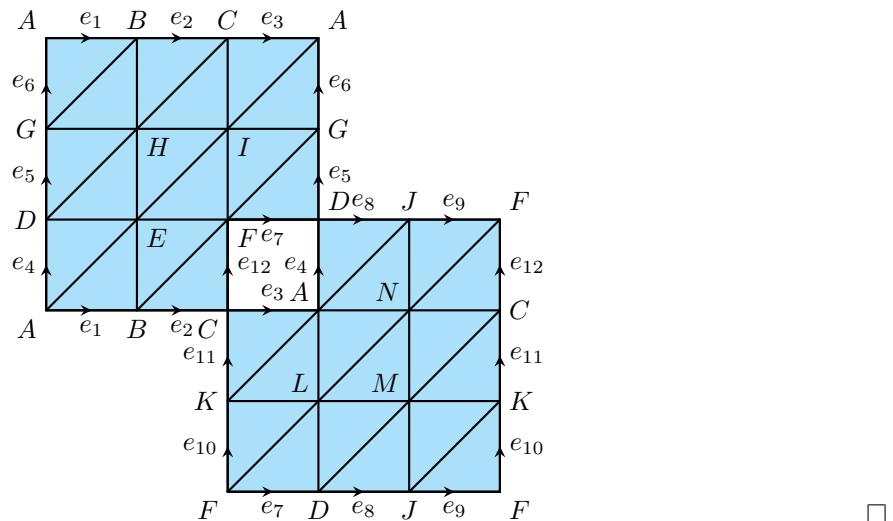
□

**Remark** Since  $\chi(\mathbb{T}^2) = 0$ , by Problem 3 any triangulation of the torus must have at least 7 vertices, 21 edges, and 14 faces. Such a minimal triangulation is given below:



**Problem 7** Construct a triangulation for the double torus  $\mathbb{T}^2 \# \mathbb{T}^2$ .

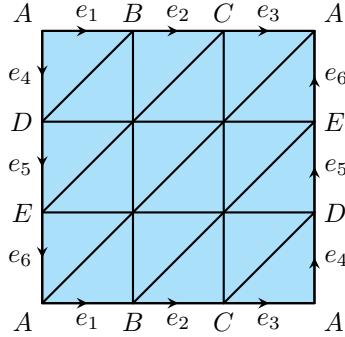
**Solution** Based on the triangulation of the torus in Problem 6, one can construct a triangulation for the double torus as follows:



□

**Problem 8** Construct a triangulation for the Klein bottle.

**Solution** A triangulation for the Klein bottle is given by



□

**Problem 9** Show that the Klein bottle depicted in Problem 8 is homeomorphic to the quotient of the torus of revolution in Problem 6 by the action of the antipodal map.

**Proof** The torus  $\mathbb{T}^2$  in Problem 6 is the quotient space

$$\mathbb{T}^2 = \frac{[0, 1] \times [0, 1]}{(s, 0) \sim (s, 1), (0, t) \sim (1, t)}.$$

The action of the antipodal map (see Figure 2) gives on  $\mathbb{T}^2$  the equivalence relation

$$(s, t) \sim \begin{cases} (1 - s, t + 1/2), & \text{if } 0 \leq s \leq 1/2, \\ (1 - s, t - 1/2), & \text{if } 1/2 \leq s \leq 1. \end{cases}$$

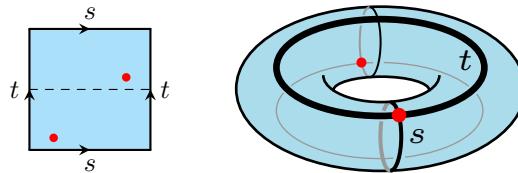


Figure 2: Antipodal map on the torus

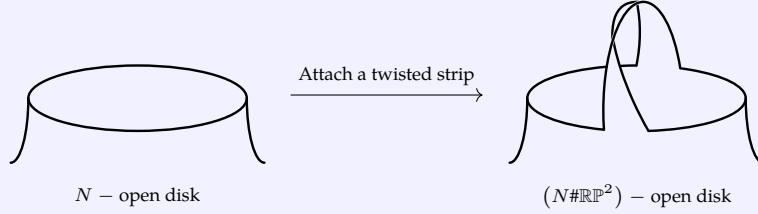
Since every point in the upper half  $[0, 1] \times [1/2, 1]$  is identified with a point in the lower half  $[0, 1] \times [0, 1/2]$ , and since those two halves are compact<sup>2</sup>, we can rewrite the quotient by discarding the upper half and adjusting the identifications on the edges:

$$\mathbb{T}^2 / \sim = \frac{[0, 1] \times [0, 1/2]}{(s, 0) \sim (1 - s, 1/2), (0, t) \sim (1, t)} = \begin{array}{c} \text{square} \\ \text{with} \\ \text{opposite} \\ \text{edges} \\ \text{glued} \end{array} = \text{Klein bottle.}$$

□

<sup>2</sup>The restriction of the quotient map to  $[0, 1] \times [1/2, 1]$  is a continuous bijection from a compact space to a Hausdorff space, hence a homeomorphism.

**Problem 10** Let  $N$  be a surface without boundary. Show that if one removes an open disk (whose closure is homeomorphic to a closed disk) from  $N$  and then attaches the ends of a twisted strip to the resulting boundary circle, the resulting surface is homeomorphic to  $N \# \mathbb{RP}^2$  with an open disk removed.



\*This result is used in the classification of compact surfaces with boundary via Morse theory.

**Proof** We can assume  $N = \mathbb{S}^2$  since removing an open disk and attaching a twisted strip are local operations that do not depend on the global topology of  $N$ . Then it suffices to show that attaching a twisted strip to a closed disk results in  $\mathbb{RP}^2$  with an open disk removed, or equivalently, that if we further attach a disk to the boundary circle of the resulting surface, we obtain  $\mathbb{RP}^2$  (see Figure 3).

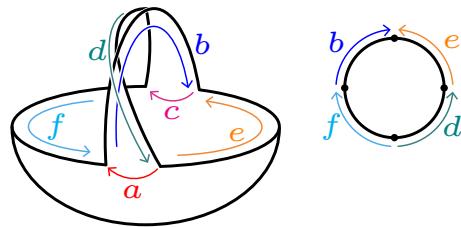
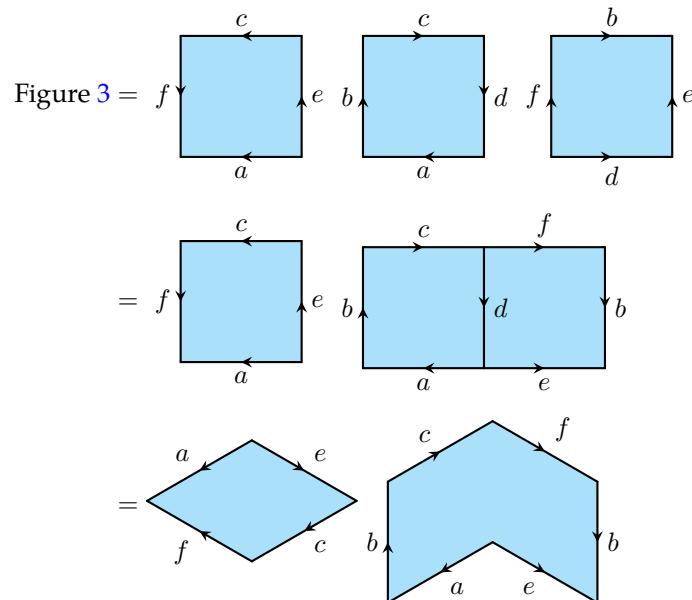
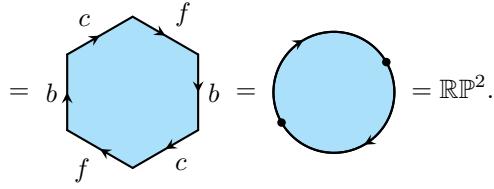


Figure 3: Attaching a disk to the boundary circle of the resulting surface

This can be seen by using polygonal presentations of surfaces:





For a smooth function  $f: M \rightarrow \mathbb{R}$  on a smooth  $n$ -manifold  $M$ , a point  $p \in M$  is called a **critical point** of  $f$  if the differential  $d f_p: T_p M \rightarrow T_{f(p)} \mathbb{R} \simeq \mathbb{R}$  is the zero map. In local coordinates  $(x^1, \dots, x^n)$  around  $p$ , this is equivalent to the vanishing of all partial derivatives at  $p$ :

$$\frac{\partial f}{\partial x^1}(p) = \dots = \frac{\partial f}{\partial x^n}(p) = 0.$$

The real number  $f(p)$  is called a **critical value** of  $f$ . A critical point  $p$  is called **non-degenerate** if the Hessian

$$\text{Hess } f(p) = \left( \frac{\partial^2 f}{\partial x^i \partial x^j}(p) \right)_{1 \leq i, j \leq n}$$

is invertible. The **index** of a non-degenerate critical point  $p$  is the number of negative eigenvalues of  $\text{Hess } f(p)$ . The degeneracy and index of a critical point are independent of the choice of the local coordinate system used, as shown by [Sylvester's law of inertia](#).

A smooth function  $f: M \rightarrow \mathbb{R}$  is called a **Morse function** if all its critical points are non-degenerate.

**Problem 11 (Morse lemma)** Let  $p$  be a non-degenerate critical point of a smooth function  $f: M \rightarrow \mathbb{R}$  on a smooth  $n$ -manifold  $M$ , with index  $\lambda$ . Show that there exist local coordinates  $(x^1, \dots, x^n)$  in an open neighborhood  $U$  of  $p$  such that  $x^i(p) = 0$  for all  $i$  and

$$f(x) = f(p) - (x^1)^2 - \dots - (x^\lambda)^2 + (x^{\lambda+1})^2 + \dots + (x^n)^2.$$

**Remark** (1) The proof of the Morse lemma can be found in John Milnor's *Morse Theory*, Lemma 2.2.

(2) As a consequence of the Morse lemma, non-degenerate critical points are isolated. //

**Problem 12** Find a Morse function on the torus  $\mathbb{T}^2$  with exactly 4 critical points.

**Solution** Embed  $\mathbb{T}^2$  in  $\mathbb{R}^3$  as a standing torus (see Figure 4) by

$$X(u, v) = ((R + r \cos v) \cos u, r \sin v, (R + r \cos v) \sin u), \quad u, v \in [0, 2\pi),$$

with  $R > r > 0$ .

The height function is the projection onto the  $z$ -axis, which restricted to  $\mathbb{T}^2$  is given by

$$h(u, v) = (R + r \cos v) \sin u.$$

The partial derivatives are

$$\frac{\partial h}{\partial u} = (R + r \cos v) \cos u, \quad \frac{\partial h}{\partial v} = -r \sin v \sin u.$$

Thus

$$\nabla h = 0 \iff \cos u = 0 \text{ and } \sin v = 0 \iff u = \frac{\pi}{2} \text{ or } \frac{3\pi}{2}, v = 0 \text{ or } \pi.$$

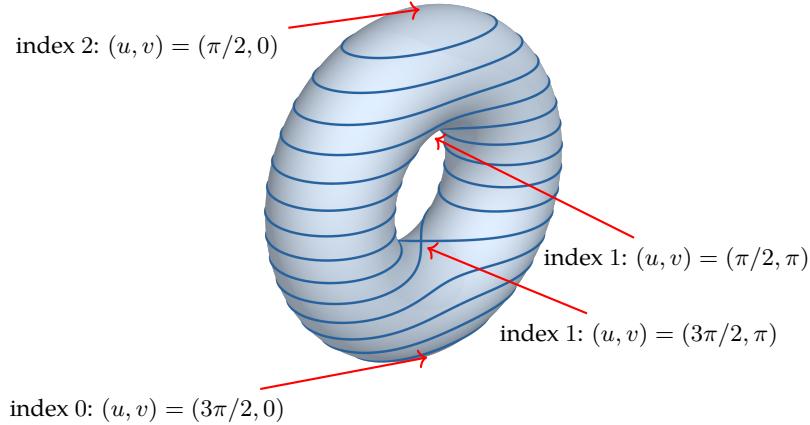


Figure 4: Height function on the standing torus with 4 critical points

The Hessian is

$$\text{Hess } h(u, v) = \begin{pmatrix} -(R + r \cos v) \sin u & -r \sin v \cos u \\ -r \sin v \cos u & -r \cos v \sin u \end{pmatrix}.$$

Evaluating at the critical points, we find that they are all non-degenerate:

$$\begin{aligned} \text{Hess } h\left(\frac{\pi}{2}, 0\right) &= \begin{pmatrix} -(R + r) & 0 \\ 0 & -r \end{pmatrix}, & \text{Hess } h\left(\frac{\pi}{2}, \pi\right) &= \begin{pmatrix} -(R - r) & 0 \\ 0 & r \end{pmatrix}, \\ \text{Hess } h\left(\frac{3\pi}{2}, 0\right) &= \begin{pmatrix} R + r & 0 \\ 0 & r \end{pmatrix}, & \text{Hess } h\left(\frac{3\pi}{2}, \pi\right) &= \begin{pmatrix} R - r & 0 \\ 0 & -r \end{pmatrix}. \end{aligned}$$

Therefore,  $h$  is a Morse function with exactly 4 critical points.  $\square$

**Remark** The Morse property of the height function can be entirely determined by the function's behavior on the fundamental polygon  $[0, 2\pi] \times [0, 2\pi]$  used to represent the torus. Since the function  $h(u, v)$  respects the equivalence relations of the torus, one only needs to ensure that the critical points—treated as points in the  $(u, v)$ -plane—have a non-vanishing Hessian determinant, effectively ignoring the specific embedding geometry. //

**Problem 13** Find a Morse function on the Klein bottle.

**Solution** Represent the Klein bottle as the square  $[0, 2\pi] \times [0, 2\pi]$  with the identifications  $(0, v) \sim (2\pi, v)$  and  $(u, 0) \sim (2\pi - u, 2\pi)$ . Consider the function  $f(u, v) = \cos u + \cos v$  defined on the square. It respects the equivalence relations of the Klein bottle since

$$f(0, v) = 1 + \cos v = f(2\pi, v), \quad f(u, 0) = \cos u + 1 = f(2\pi - u, 2\pi).$$

The partial derivatives of  $f$  are

$$\frac{\partial f}{\partial u} = -\sin u, \quad \frac{\partial f}{\partial v} = -\sin v.$$

Thus

$$\nabla f = 0 \iff \sin u = 0 \text{ and } \sin v = 0 \iff u = 0 \text{ or } \pi, v = 0 \text{ or } \pi.$$

The Hessian is

$$\text{Hess } f(u, v) = \begin{pmatrix} -\cos u & 0 \\ 0 & -\cos v \end{pmatrix}.$$

Evaluating at the critical points, we find that they are all non-degenerate. Therefore,  $f$  is a Morse function on the Klein bottle.  $\square$

**Remark** For a closed connected  $n$ -manifold  $M$ , the torsion subgroup of  $H_{n-1}(M; \mathbb{Z})$  is trivial if  $M$  is orientable, and  $\mathbb{Z}_2$  if  $M$  is nonorientable. Hence by [Alexander duality](#), a closed<sup>3</sup> nonorientable  $n$ -manifold cannot be embedded as a subspace of  $\mathbb{R}^{n+1}$ . In particular, the Klein bottle cannot be embedded in  $\mathbb{R}^3$ . Therefore, unlike the torus, we cannot use a height function derived from an embedding in  $\mathbb{R}^3$  to obtain a Morse function on the Klein bottle. However, one can easily verify that the function

$$g: \mathbb{R}^2 \rightarrow \mathbb{R}^4, \quad (u, v) \mapsto \left( \sin v \sin \frac{u}{2}, \sin v \cos \frac{u}{2}, (2 + \cos v) \sin u, (2 + \cos v) \cos u \right)$$

descends to an embedding<sup>4</sup> of the Klein bottle

$$K = \frac{[0, 2\pi] \times [0, 2\pi]}{(u, 0) \times (u, 2\pi), (0, v) \sim (2\pi, 2\pi - v)}$$

into  $\mathbb{R}^4$ . Composing this embedding with the projection onto the fourth coordinate gives the function  $h(u, v) = (2 + \cos v) \cos u$ , with

$$\nabla h = 0 \iff -(2 + \cos v) \sin u = 0 \text{ and } -\cos u \sin v = 0 \iff u = 0 \text{ or } \pi, v = 0 \text{ or } \pi.$$

The Hessian is

$$\text{Hess } h(u, v) = \begin{pmatrix} -(2 + \cos v) \cos u & \sin u \sin v \\ \sin u \sin v & -\cos u \cos v \end{pmatrix}.$$

Evaluating at the critical points, we find that they are all non-degenerate:

$$\begin{aligned} \text{Hess } h(0, 0) &= \begin{pmatrix} -3 & 0 \\ 0 & -1 \end{pmatrix}, & \text{Hess } h(0, \pi) &= \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}, \\ \text{Hess } h(\pi, 0) &= \begin{pmatrix} 3 & 0 \\ 0 & 1 \end{pmatrix}, & \text{Hess } h(\pi, \pi) &= \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}. \end{aligned}$$

Hence,  $h$  is another Morse function on the Klein bottle, with exactly 4 critical points. In particular,

- ◊ The index-0 critical point corresponds to height  $h(\pi, 0) = -3$ .
- ◊ The two index-1 critical points correspond to heights  $h(0, \pi) = 1$  and  $h(\pi, \pi) = -1$  (see Figure 5).
- ◊ The index-2 critical point corresponds to height  $h(0, 0) = 3$ .  $\//$

---

<sup>3</sup>Here *closed* means compact and without boundary. For example, the Möbius band is not closed, and can be embedded in  $\mathbb{R}^3$ .

<sup>4</sup>Indeed, to show the injectivity of the induced map, notice that the  $(2 + \cos v)$  factors in the last two coordinates are always positive, so the ratio of the last two coordinates determines  $u$  within  $[0, 2\pi]$ . Then, knowing  $u$ , the last two coordinates determine  $\cos v$  and the first two coordinates determine  $\sin v$ , which together determine  $v$  within  $[0, 2\pi]$ .

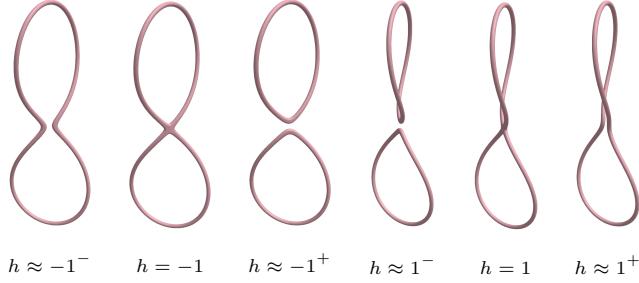


Figure 5: Hyperplane sections<sup>5</sup> of the embedded Klein bottle near index-1 critical points

**Problem 14** Prove that the fundamental group of any compact orientable 3-manifold is the free product of fundamental groups of prime 3-manifolds.

**Proof** According to the [Kneser–Milnor prime decomposition theorem](#) for 3-manifolds, any compact orientable 3-manifold is the connected sum of a unique (up to homeomorphism) finite collection of prime 3-manifolds. By induction on the number of summands, it suffices to show that if

$$\pi_1(M \# N) = \pi_1(M) * \pi_1(N)$$

for any two 3-manifolds  $M$  and  $N$ .

Let  $M \# N$  be obtained by removing an open 3-ball from each of  $M$  and  $N$  and gluing along the resulting boundary 2-spheres. Choose a collar neighborhood  $\mathbb{S}^2 \times [0, 1]$  of the gluing sphere, and set

$$U = (M \setminus \mathbb{B}^3) \cup (\mathbb{S}^2 \times [0, 3/4]), \quad V = (N \setminus \mathbb{B}^3) \cup (\mathbb{S}^2 \times (1/4, 1]).$$

Then  $U$  and  $V$  are open and path-connected,  $U \cup V = M \# N$ , and  $U \cap V$  is homotopy equivalent to  $\mathbb{S}^2$ , which is simply connected. Moreover, removing a 3-ball does not change the fundamental group<sup>6</sup>, so

$$\pi_1(U) \cong \pi_1(M), \quad \pi_1(V) \cong \pi_1(N).$$

Now, the desired result follows directly from van Kampen’s theorem. □

**Problem 15** The **compact-open topology** on the set  $C(X, Y)$  of continuous maps from a topological space  $X$  to a topological space  $Y$  is defined by taking as a subbasis the sets of the form

$$M(K, U) := \{f \in C(X, Y) : f(K) \subset U\}$$

where  $K \subset X$  is compact and  $U \subset Y$  is open. In this problem, we always endow  $C(X, Y)$  with the compact-open topology.

(1) The evaluation map

$$\text{ev}: X \times C(X, Y) \rightarrow Y, \quad (x, f) \mapsto f(x)$$

is continuous if  $X$  is **locally compact** (i.e., for each point  $x \in X$  and each neighborhood  $U$  of  $x$  there is a compact

<sup>5</sup>By the [regular level set theorem](#), the preimage of a regular value of  $h$  is a 1-manifold. A visualization of hyperplane sections of the embedded Klein bottle is available at <https://github.com/Xiaoshuo-Lin/4D-Klein-Sliced>.

<sup>6</sup>Try to prove this fact using van Kampen’s theorem.

neighborhood  $V$  of  $x$  contained in  $U$ ).

- (2) If  $f: X \times Z \rightarrow Y$  is continuous then so is the map  $\hat{f}: Z \rightarrow C(X, Y)$ ,  $\hat{f}(z)(x) = f(x, z)$ .
- (3) The converse to (2) holds when  $X$  is locally compact.

**Proof** (1) For  $(x, f) \in X \times C(X, Y)$  let  $U \subset Y$  be an open neighborhood of  $f(x)$ . Since  $X$  is locally compact, continuity of  $f$  implies there is a compact neighborhood  $K \subset X$  of  $x$  such that  $f(K) \subset U$ . Then  $K \times M(K, U)$  is a neighborhood of  $(x, f)$  in  $X \times C(X, Y)$  taken to  $U$  by  $\text{ev}$ , so  $\text{ev}$  is continuous at  $(x, f)$ .

- (2) Suppose  $f: X \times Z \rightarrow Y$  is continuous. To show continuity of  $\hat{f}$  it suffices to show that for a subbasic set  $M(K, U) \subset C(X, Y)$ , the set  $\hat{f}^{-1}(M(K, U)) = \{z \in Z : f(K, z) \subset U\}$  is open in  $Z$ . Let  $z \in \hat{f}^{-1}(M(K, U))$ . Since  $f^{-1}(U)$  is an open neighborhood of the compact set  $K \times \{z\}$ , by the **tube lemma** there exist open sets  $V \subset X$  and  $W \subset Z$  such that

$$K \times \{z\} \subset V \times W \subset f^{-1}(U).$$

So  $W$  is a neighborhood of  $z$  contained in  $\hat{f}^{-1}(M(K, U))$ , proving that  $\hat{f}^{-1}(M(K, U))$  is open in  $Z$ .

- (3) Note that  $f: X \times Z \rightarrow Y$  is the composition of  $\text{Id} \times \hat{f}$  and the evaluation map:

$$\begin{array}{ccc} X \times Z & \xrightarrow{f} & Y \\ & \searrow \text{Id} \times \hat{f} & \swarrow \text{ev} \\ & X \times C(X, Y) & \end{array}$$

So part (1) gives the result. □

**Problem 16** Show that if  $q: X \rightarrow Y$  is a quotient map then so is  $q \times \text{Id}: X \times Z \rightarrow Y \times Z$  whenever  $Z$  is locally compact.

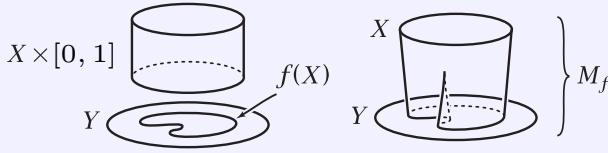
**Proof** Consider the diagram below, where  $W$  is  $Y \times Z$  with the quotient topology from  $X \times Z$ , with  $g$  the quotient map and  $h$  the identity.

$$\begin{array}{ccc} X \times Z & \xrightarrow{q \times \text{Id}} & Y \times Z \\ & \searrow g & \swarrow h \\ & W & \end{array}$$

Every open set in  $Y \times Z$  is open in  $W$  since  $q \times \text{Id}$  is continuous, so it will suffice to show that  $h$  is continuous.

Since  $g$  is continuous, so is the associated map  $\hat{g}: X \rightarrow C(Z, W)$ , by Problem 15 (2). This implies that  $\hat{h}: Y \rightarrow C(Z, W)$  is continuous since  $q$  is a quotient map. Applying Problem 15 (3), we conclude that  $h$  is continuous. □

**Problem 17** For a continuous map  $f: X \rightarrow Y$ , the **mapping cylinder**  $M_f$  is the quotient space of the disjoint union  $(X \times [0, 1]) \sqcup Y$  obtained by identifying each  $(x, 1) \in X \times [0, 1]$  with  $f(x) \in Y$ .



Show that  $Y$  is a deformation retract of  $M_f$ , where we identify  $Y$  with its image in  $M_f$ .

**Proof** Let  $W = (X \times [0, 1]) \sqcup Y$  be the disjoint union before taking the quotient. Define the continuous map  $\tilde{H}: W \times [0, 1] \rightarrow W$  by

$$\begin{aligned}\tilde{H}((x, s), t) &= (x, s(1-t)+t), \quad \text{for } (x, s) \in X \times [0, 1], \\ \tilde{H}(y, t) &= y, \quad \text{for } y \in Y.\end{aligned}$$

Let  $q: W \rightarrow M_f$  be the quotient map defining the mapping cylinder. By Problem 16, the map  $q \times \text{Id}: W \times [0, 1] \rightarrow M_f \times [0, 1]$  is a quotient map since  $[0, 1]$  is locally compact.

$$\begin{array}{ccc} W \times [0, 1] & \xrightarrow{\tilde{H}} & W \\ q \times \text{Id} \downarrow & & \downarrow q \\ M_f \times [0, 1] & \dashrightarrow_{H} & M_f \end{array}$$

Note that  $q \circ \tilde{H}$  is constant on the fibers of  $q \times \text{Id}$ :

$$q(\tilde{H}((x, 1), t)) = q(x, 1) = [f(x)] = q(f(x)) = q(\tilde{H}(f(x), t)), \quad \text{for } x \in X \text{ and } t \in [0, 1].$$

Thus, by the universal property of quotient maps, there is a unique continuous map  $H: M_f \times [0, 1] \rightarrow M_f$  such that  $H \circ (q \times \text{Id}) = q \circ \tilde{H}$ . This map  $H$  is the desired deformation retraction of  $M_f$  onto  $Y$  since

$$\begin{aligned}H([x, s], 0) &= q(\tilde{H}((x, s), 0)) = [x, s] \quad \text{for } x \in X \text{ and } s \in [0, 1], \\ H([x, s], 1) &= q(\tilde{H}((x, s), 1)) = [x, 1] = [f(x)] \in Y \quad \text{for } x \in X \text{ and } s \in [0, 1], \\ H([y], t) &= q(\tilde{H}(y, t)) = [y] \in Y \quad \text{for } y \in Y \text{ and } t \in [0, 1].\end{aligned}$$

□

**Problem 18** For a continuous map  $f: X \rightarrow X$ , the **mapping torus**  $T_f$  is the quotient space of  $X \times [0, 1]$  obtained by identifying each  $(x, 1)$  with  $(f(x), 0)$  for  $x \in X$ .

Suppose  $X$  is path-connected with basepoint  $x_0$  and  $f: X \rightarrow X$  is a homeomorphism with  $f(x_0) = x_0$ . Moreover, assume that  $x_0$  has a contractible open neighborhood  $N$  in  $X$ , and let  $\tau_0 = [x_0, 1/2] \in T_f$  be the basepoint of  $T_f$ . Show that the fundamental group of the mapping torus  $T_f$  is a semidirect product:

$$\pi_1(T_f, \tau_0) \simeq \pi_1(X, x_0) \rtimes_{f_*} \mathbb{Z}.$$

**Proof** Denote by  $q: X \times [0, 1] \rightarrow T_f$  the quotient map defining the mapping torus. Consider the open cover of  $T_f$  given by the sets  $U$  and  $V$  defined below:

$$U = q(X \times (0, 1)), \quad V = q((X \times [0, 1/3]) \cup (X \times (2/3, 1]) \cup (N \times [0, 1])).$$

Then  $U$  and  $V$  are path-connected,  $U \cup V = T_f$ , and  $U \cap V$  is homotopy equivalent to the wedge sum of

two copies of  $X$ . Thus,

$$\pi_1(U \cap V, \tau_0) \simeq \pi_1(X, x_0) * \pi_1(X, x_0) =: G_1 * G_2,$$

where  $G_1$  represents loops in the lower part (near 0) and  $G_2$  represents loops in the upper part (near 1).

It is clear that  $\pi_1(U, \tau_0) \simeq \pi_1(X, x_0)$  since  $U$  deformation retracts onto  $X \times \{1/2\}$ . For  $V$ , we can decompose it as the union of  $q(N \times [0, 1])$  (which is homeomorphic to  $N \times \mathbb{S}^1$ ) and  $q((X \times [0, 1/3]) \cup (X \times (2/3, 1]))$ . Define

$$\Phi: q((X \times [0, 1/3]) \cup (X \times (2/3, 1))) \rightarrow X \times (2/3, 4/3), \quad [x, t] \mapsto \begin{cases} (x, t+1), & t \in [0, 1/3], \\ (f(x), t), & t \in (2/3, 1]. \end{cases}$$

Note that  $\Phi([x, 1]) = (f(x), 1) = \Phi([f(x), 0])$ , so  $\Phi$  is well-defined and continuous. Since  $f$  is a homeomorphism,  $\Phi$  has an inverse given by

$$\Psi: X \times (2/3, 4/3) \rightarrow q((X \times [0, 1/3]) \cup (X \times (2/3, 1))), \quad (y, s) \mapsto \begin{cases} [f^{-1}(y), s], & s \in (2/3, 1], \\ [y, s-1], & s \in [1, 4/3]. \end{cases}$$

The continuity of  $\Psi$  follows from the gluing lemma. Thus,  $\Phi$  is a homeomorphism. Moreover, the intersection of  $q(N \times [0, 1])$  and  $q((X \times [0, 1/3]) \cup (X \times (2/3, 1)))$  is contractible since  $N$  is contractible. Therefore, by van Kampen's theorem,

$$\pi_1(V, \tau_0) \simeq \pi_1(X, x_0) * \mathbb{Z}.$$

Now, the inclusion map  $i_U: U \cap V \rightarrow U$  induces the homomorphism<sup>7</sup>

$$(i_U)_*: G_1 * G_2 \rightarrow \pi_1(X, x_0), \quad g \mapsto \begin{cases} g, & g \in G_1, \\ f_*(g), & g \in G_2. \end{cases}$$

Here  $f_*: \pi_1(X, x_0) \rightarrow \pi_1(X, x_0)$  is the isomorphism induced by the basepoint-preserving homeomorphism  $f$ . Similarly, the inclusion map  $i_V: U \cap V \rightarrow V$  induces the homomorphism<sup>8</sup>

$$(i_V)_*: G_1 * G_2 \rightarrow \pi_1(X, x_0) * \mathbb{Z}, \quad g \mapsto \begin{cases} g, & g \in G_1, \\ tgt^{-1}, & g \in G_2, \end{cases}$$

where  $t$  is a generator of the  $\mathbb{Z}$  factor in  $\pi_1(V, \tau_0)$ .

By van Kampen's theorem, the fundamental group  $\pi_1(T_f, \tau_0)$  is the free product  $\pi_1(U, \tau_0) * \pi_1(V, \tau_0)$  modulo the relations  $(i_U)_*(\omega) = (i_V)_*(\omega)$  for all  $\omega \in G_1 * G_2$ .

- ◊ From  $G_1$ , we get  $g = g$ , which identifies the  $\pi_1(X, x_0)$  factors in  $\pi_1(U, \tau_0)$  and  $\pi_1(V, \tau_0)$ .
- ◊ From  $G_2$ , we get  $f_*(g) = tgt^{-1}$ .

---

<sup>7</sup>To see why  $(i_U)_*(g) = f_*(g)$  for  $g \in G_2$ , observe that an element  $g \in G_2$  is represented by a loop  $\gamma$  in  $X \times \{1 - \varepsilon\}$ . As  $\varepsilon \rightarrow 0$ , the quotient map  $q$  identifies the points  $(x, 1)$  with  $(f(x), 0)$ . Thus, the loop at the top of the cylinder  $U$  is identified with the loop  $f \circ \gamma$  at the bottom of the cylinder.

<sup>8</sup>With the decomposition of  $V$  into two parts as above, to reach the upper copy of  $X$  from our basepoint at  $t = 0$ , we must travel through the bridge  $q(N \times [0, 1])$ . This path is precisely the generator  $t$ .

Therefore,<sup>9</sup>

$$\pi_1(T_f, \tau_0) \simeq \langle \pi_1(X, x_0), t \mid tgt^{-1} = f_*(g), \forall g \in \pi_1(X, x_0) \rangle \simeq \pi_1(X, x_0) \rtimes_{f_*} \mathbb{Z}.$$

□

**Remark** (1) Since  $f: X \rightarrow X$  is a homeomorphism, there is a natural projection

$$p: T_f \rightarrow \mathbb{S}^1, \quad [x, t] \mapsto e^{2\pi i t},$$

which makes  $T_f$  into a **fiber bundle** over  $\mathbb{S}^1$  with fiber  $X$ . If we identify the fiber  $p^{-1}(1)$  with  $X$ , then the long exact sequence of homotopy groups for this **fibration** yields

$$\cdots \longrightarrow \pi_2(\mathbb{S}^1, 1) \longrightarrow \pi_1(X, x_0) \xrightarrow{i_*} \pi_1(T_f, [x_0, 0]) \xrightarrow{p_*} \pi_1(\mathbb{S}^1, 1) \longrightarrow \pi_0(X)$$

where  $i: X \rightarrow T_f$  is the inclusion map. Since  $\pi_2(\mathbb{S}^1, 1) = 0$  and  $\pi_0(X) = 0$  (as  $X$  is path-connected), we have the short exact sequence

$$0 \longrightarrow \pi_1(X, x_0) \xrightarrow{i_*} \pi_1(T_f, [x_0, 0]) \xrightarrow{p_*} \mathbb{Z} \longrightarrow 0$$

Choose  $t \in \pi_1(T_f, [x_0, 0])$  mapping to the generator  $1 \in \mathbb{Z}$ . The action of  $\mathbb{Z} = \pi_1(\mathbb{S}^1, 1)$  on  $\pi_1(X, x_0)$  is given by **monodromy**: lifting the generator of  $\pi_1(\mathbb{S}^1, 1)$  to a path in  $T_f$  transports loops in the fiber by the map  $f$ . Thus, this short exact sequence splits, and we recover the semidirect product structure as before.

(2) Let us illustrate the result with some examples:

◊ When  $f = \text{Id}_X$ , the mapping torus  $T_f$  is homeomorphic to the product space  $X \times \mathbb{S}^1$ , and  $f_*$  is the identity automorphism of  $\pi_1(X)$ . In this case,

$$\pi_1(T_f) \simeq \langle \pi_1(X), t \mid tg = gt, \forall g \in \pi_1(X) \rangle \simeq \pi_1(X) \times \mathbb{Z} \simeq \pi_1(X) \times \pi_1(\mathbb{S}^1).$$

◊ When  $X = \mathbb{S}^1 \subset \mathbb{C}$  and  $f: \mathbb{S}^1 \rightarrow \mathbb{S}^1$  is the conjugation map  $f(z) = \bar{z}$ , the mapping torus  $T_f$  is homeomorphic to the Klein bottle  $K$ , and  $f_*$  acts on  $\pi_1(\mathbb{S}^1)$  by inversion. In this case,

$$\pi_1(T_f) \simeq \langle s, t \mid tst^{-1} = s^{-1} \rangle \simeq \pi_1(K).$$

//

---

<sup>9</sup>Suppose that we are given a group  $G$  with a normal subgroup  $N$  and a subgroup  $H$ , such that every element  $g \in G$  may be written uniquely in the form  $g = nh$  where  $n \in N$  and  $h \in H$ . Let  $\varphi: H \rightarrow \text{Aut}(N)$  be the homomorphism (written  $\varphi(h) = \varphi_h$ ) given by  $\varphi_h(n) = hnh^{-1}$  for all  $n \in N$  and  $h \in H$ . Then  $G$  is isomorphic to the semidirect product  $N \rtimes_{\varphi} H$ . The isomorphism  $\lambda: G \rightarrow N \rtimes_{\varphi} H$  is well-defined by  $\lambda(g) = (n, h)$  where  $g = nh$  due to the uniqueness of the decomposition. In  $G$ , we have

$$(n_1h_1)(n_2h_2) = n_1h_1n_2(h_1^{-1}h_1)h_2 = (n_1\varphi_{h_1}(n_2))(h_1h_2).$$

Thus, for  $g_1 = n_1h_1$  and  $g_2 = n_2h_2$  in  $G$ , we obtain

$$\lambda(g_1g_2) = \lambda(n_1\varphi_{h_1}(n_2)h_1h_2) = (n_1\varphi_{h_1}(n_2), h_1h_2) = (n_1, h_1) \bullet (n_2, h_2) = \lambda(g_1) \bullet \lambda(g_2),$$

which shows that  $\lambda$  is a homomorphism. Since  $\lambda$  is clearly bijective, it is an isomorphism.

**Problem 19** Let  $f \in C(\mathbb{S}^1, \mathbb{S}^1)$  and  $p: \mathbb{R} \rightarrow \mathbb{S}^1$  be the covering map given by  $p(t) = e^{2\pi i t}$ .

$$\begin{array}{ccc} & & \mathbb{R} \\ & \nearrow \tilde{f} & \downarrow p \\ \mathbb{R} & \xrightarrow{p} & \mathbb{S}^1 \xrightarrow{f} \mathbb{S}^1 \end{array}$$

Since  $\mathbb{R}$  is simply connected, the map  $f \circ p: \mathbb{R} \rightarrow \mathbb{S}^1$  lifts to a continuous map  $\tilde{f}: \mathbb{R} \rightarrow \mathbb{R}$ . Any two such lifts differ by an integer. The **degree** of  $f$  is defined to be the integer  $\deg(f) = \tilde{f}(1) - \tilde{f}(0)$ .

- (1) If  $f \in C(\mathbb{S}^1, \mathbb{S}^1)$  is not surjective, then  $\deg(f) = 0$ .
- (2) If  $f, g \in C(\mathbb{S}^1, \mathbb{S}^1)$ , then  $\deg(f \circ g) = \deg(f) \deg(g)$ .
- (3) Two maps  $f, g \in C(\mathbb{S}^1, \mathbb{S}^1)$  are homotopic if and only if  $\deg(f) = \deg(g)$ .

**Proof** (1) If  $f \in C(\mathbb{S}^1, \mathbb{S}^1)$  is not surjective, then  $|\tilde{f}(1) - \tilde{f}(0)| < 1$  by the intermediate value theorem, so  $\deg(f) = 0$ .

- (2) Using the commutative diagram above, we have

$$p(\tilde{f}(\tilde{g}(t))) = f(p(\tilde{g}(t))) = f(g(p(t))) = (f \circ g)(p(t)), \quad \forall t \in \mathbb{R}.$$

Thus,  $\tilde{f} \circ \tilde{g}$  is a lift of  $f \circ g$ . Note that the map  $\tilde{f}(t+1) - \tilde{f}(t)$  is a continuous map from  $\mathbb{R}$  to  $\mathbb{Z}$ , so it must be the constant map with value  $\deg(f)$ . Therefore,  $\tilde{f}(t+k) - \tilde{f}(t) = k \deg(f)$  for  $k \in \mathbb{Z}$ , and

$$\begin{aligned} \deg(f \circ g) &= \tilde{f} \circ \tilde{g}(1) - \tilde{f} \circ \tilde{g}(0) = \tilde{f}(\tilde{g}(0) + \deg(g)) - \tilde{f}(\tilde{g}(0)) \\ &= \tilde{f}(\tilde{g}(0)) + \deg(g) \deg(f) - \tilde{f}(\tilde{g}(0)) = \deg(f) \deg(g). \end{aligned}$$

- (3) Fix  $x_0 = 1 \in \mathbb{S}^1$ . Let  $T_\theta(t) = t + \theta$  be the translation map on  $\mathbb{R}$  by  $\theta \in \mathbb{R}$ , and let  $R_\theta: \mathbb{S}^1 \rightarrow \mathbb{S}^1$  be the rotation map given by  $R_\theta(e^{2\pi i t}) = e^{2\pi i (t+\theta)}$ . It is clear that  $T_\theta$  is a lift of  $R_\theta$ . Given  $f: \mathbb{S}^1 \rightarrow \mathbb{S}^1$ , let  $\theta$  be such that  $R_\theta \circ f(x_0) = x_0$ . Since  $R_\theta$  is homotopic to the identity map, it follows that  $f$  is homotopic to  $R_\theta \circ f$ . Now,  $T_\theta \circ \tilde{f}$  is a lift of  $R_\theta \circ f$  satisfying

$$T_\theta \circ \tilde{f}(1) - T_\theta \circ \tilde{f}(0) = \tilde{f}(1) - \tilde{f}(0),$$

so  $\deg(R_\theta \circ f) = \deg(f)$ . Similarly, any map  $g: \mathbb{S}^1 \rightarrow \mathbb{S}^1$  is homotopic to a map  $R_\phi \circ g$  with  $R_\phi \circ g(x_0) = x_0$  and  $\deg(R_\phi \circ g) = \deg(g)$ . Thus, it suffices to show that two maps  $f, g \in C(\mathbb{S}^1, \mathbb{S}^1)$  with  $f(x_0) = g(x_0) = x_0$  are homotopic if and only if  $\deg(f) = \deg(g)$ .

( $\Rightarrow$ ) Let  $H: [0, 1] \times \mathbb{S}^1 \rightarrow \mathbb{S}^1$  be a homotopy from  $f$  to  $g$ .

$$\begin{array}{ccc} & & \mathbb{R} \\ & \nearrow \tilde{H} & \downarrow p \\ [0, 1] \times \mathbb{R} & \xrightarrow{\text{Id} \times p} & [0, 1] \times \mathbb{S}^1 \xrightarrow{H} \mathbb{S}^1 \end{array}$$

Since  $[0, 1] \times \mathbb{R}$  is simply connected, the map  $H \circ (\text{Id} \times p)$  lifts to a continuous map  $\tilde{H}: [0, 1] \times$

$\mathbb{R} \rightarrow \mathbb{R}$ . Note that the map  $\tilde{H}(s, t+1) - \tilde{H}(s, t)$  is a continuous map from  $[0, 1] \times \mathbb{R}$  to  $\mathbb{Z}$ , so it must be the constant map with value  $\deg(f)$  when  $s = 0$  and  $\deg(g)$  when  $s = 1$ . Since  $[0, 1] \times \mathbb{R}$  is connected, we have  $\deg(f) = \deg(g)$ .

( $\Leftarrow$ ) If  $\deg(f) = \deg(g)$ , then we can choose lifts  $\tilde{f}$  and  $\tilde{g}$  such that  $\tilde{f}(0) = \tilde{g}(0)$  and  $\tilde{f}(1) = \tilde{g}(1)$ .

Define the homotopy

$$\tilde{H}: [0, 1] \times \mathbb{R} \rightarrow \mathbb{R}, \quad (s, t) \mapsto (1-s)\tilde{f}(t) + s\tilde{g}(t).$$

Since  $\tilde{H}$  satisfies  $\tilde{H}(s, t+1) - \tilde{H}(s, t) = \deg(f) = \deg(g) \in \mathbb{Z}$  for all  $(s, t) \in [0, 1] \times \mathbb{R}$ , it descends to a continuous homotopy  $H: [0, 1] \times \mathbb{S}^1 \rightarrow \mathbb{S}^1$  between  $f$  and  $g$ .  $\square$

Returning to the context of Problem 15, part (2) of that problem implies that there is a well-defined map  $C(X \times Z, Y) \rightarrow C(Z, C(X, Y))$  sending  $f$  to  $\hat{f}$ . This is injective, and part (3) implies that it is surjective if  $X$  is locally compact.

**Problem 20** The map  $C(X \times Z, Y) \rightarrow C(Z, C(X, Y))$ ,  $f \mapsto \hat{f}$ , is a homeomorphism if  $X$  is locally compact Hausdorff and  $Z$  is Hausdorff.

**Proof** First we show that a subbasis for  $C(X \times Z, Y)$  is formed by the sets  $M(A \times B, U)$  as  $A$  and  $B$  range over compact sets in  $X$  and  $Z$  respectively, and  $U$  ranges over open sets in  $Y$ . Given a compact  $K \subset X \times Z$  and a continuous map  $f \in M(K, U)$ , let  $K_X$  and  $K_Z$  be the projections of  $K$  onto  $X$  and  $Z$ . Then  $K_X \times K_Z$  is compact Hausdorff and hence normal. A normal space has the property that for each closed set  $C$  and each open set  $O$  containing  $C$  there is another open set  $O'$  containing  $C$  whose closure is contained in  $O$ . To see this, apply the normality property to the two closed sets  $C$  and the complement  $C'$  of  $O$ , taking  $O'$  to be the resulting open set containing  $C$  and disjoint from an open set containing  $C'$ , so the closure of  $O'$  is contained in  $O$ . Applying this observation to the normal space  $K_X \times K_Z$  with  $C$  a point  $k \in K$  and  $O = (K_X \times K_Z) \cap f^{-1}(U)$ , the result is an open neighborhood of  $k$  in  $K_X \times K_Z$  whose closure is contained in  $f^{-1}(U)$ . We can take this open neighborhood to be a product  $V_k \times W_k \subset K_X \times K_Z$ , so its closure is a compact neighborhood  $A_k \times B_k \subset f^{-1}(U)$  of  $k$  in  $K_X \times K_Z$ . The sets  $V_k \times W_k$  for varying  $k \in K$  form an open cover of the compact set  $K$ , so a finite number of the products  $A_k \times B_k$  cover  $K$ . After discarding the others we then have

$$f \in \bigcap_k M(A_k \times B_k, U) \subset M(K, U),$$

which shows that the sets  $M(A \times B, U)$  form a subbasis for  $C(X \times Z, Y)$  as claimed.

Under the bijection  $C(X \times Z, Y) \rightarrow C(Z, C(X, Y))$ , the sets  $M(A \times B, U)$  correspond to the sets  $M(B, M(A, U))$ , so it will suffice to show that the latter sets form a subbasis for  $C(Z, C(X, Y))$ . We will show more generally that for any space  $Q$  a subbasis for  $C(Z, Q)$  is formed by the sets  $M(K, V)$  as  $V$  ranges over a subbasis for  $Q$  and  $K$  ranges over compact sets in  $Z$ , assuming that  $Z$  is Hausdorff. Then we let  $Q = C(X, Y)$  with subbasis the sets  $M(A, U)$ .

Given  $f \in M(K, U)$  with  $K$  compact in  $Z$  and  $U$  open in  $Q$ , write  $U$  as a union of basic sets  $U_\alpha$  with each  $U_\alpha$  an intersection of finitely many sets  $V_{\alpha,j}$  of the given subbasis for  $Q$ . The cover of  $K$  by the open sets  $f^{-1}(U_\alpha)$  has a finite subcover, say by the open sets  $f^{-1}(U_i)$ . Since  $K$  is compact Hausdorff, hence normal, we can write  $K$  as a union of compact subsets  $K_i$  with  $K_i \subset f^{-1}(U_i)$ , namely, each  $k \in K$  has a compact neighborhood  $K_k$  contained in some  $f^{-1}(U_i)$  with  $k \in f^{-1}(U_i)$ , so compactness of  $K$  implies that finitely many of these sets  $K_k$  cover  $K$  and we let  $K_i$  be the union of those contained in  $f^{-1}(U_i)$ .

Now  $f$  lies in  $M(K_i, U_i) = M(K_i, \cap_j V_{ij}) = \cap_j M(K_i, V_{ij})$  for each  $i$ . Hence,

$$f \in \cap_{i,j} M(K_i, V_{ij}) = \cap_i M(K_i, U_i) \subset M(K, U).$$

Since  $\cap_{i,j} M(K_i, V_{ij})$  is a finite intersection, this shows that the sets  $M(K, V)$  form a subbasis for  $C(Z, Q)$  as claimed.  $\square$

Let  $M$  be a topological manifold and  $\text{Homeo}(M)$  be the group of homeomorphisms of  $M$  endowed with the compact-open topology (as in Problem 15). The path-component of the identity map  $\text{Id}_M$  for this topology is denoted as  $\text{Homeo}_0(M)$ . Since manifolds are always locally compact Hausdorff, and  $[0, 1]$  is Hausdorff, Problem 20 gives a homeomorphism

$$C(M \times [0, 1], M) \simeq C([0, 1], C(M, M)).$$

Thus,  $\text{Homeo}_0(M)$  is a normal subgroup of  $\text{Homeo}(M)$ , consisting of all homeomorphisms of  $M$  that are *isotopic* to the identity.

The **mapping class group** of  $M$  is defined as the quotient group

$$\text{MCG}(M) := \text{Homeo}(M)/\text{Homeo}_0(M).$$

In other words,  $\text{MCG}(M)$  is the group of homeomorphism of  $M$  onto itself, modulo **isotopy**.

**Problem 21** Show that  $\text{MCG}(\mathbb{S}^1) \simeq \mathbb{Z}_2$ .

**Proof** By Problem 19 (2), for any  $f \in \text{Homeo}(\mathbb{S}^1)$ , we have

$$1 = \deg(\text{Id}_{\mathbb{S}^1}) = \deg(f \circ f^{-1}) = \deg(f) \deg(f^{-1}).$$

This implies  $\deg(f) = \pm 1$ . Using Problem 19 (2) again, we see that there is a group epimorphism

$$\deg: \text{Homeo}(\mathbb{S}^1) \rightarrow \{\pm 1\}, \quad f \mapsto \deg(f).$$

By Problem 19 (3),  $\text{Homeo}_0(\mathbb{S}^1) \subset \ker(\deg)$ . Conversely, if  $f \in \ker(\deg)$ , then it admits a lift  $\tilde{f}: \mathbb{R} \rightarrow \mathbb{R}$  satisfying  $\tilde{f}(x+1) = \tilde{f}(x) + 1$  for all  $x \in \mathbb{R}$ . Since  $f \in \text{Homeo}(\mathbb{S}^1)$ ,  $\tilde{f}$  is a strictly increasing homeomorphism of  $\mathbb{R}$ . For each  $t \in [0, 1]$ , define  $\tilde{f}_t(x) = (1-t)x + t\tilde{f}(x)$  where  $x \in \mathbb{R}$ . Then each  $\tilde{f}_t$  is strictly increasing, and

$$\begin{aligned} \tilde{f}_t(x+1) &= (1-t)(x+1) + t\tilde{f}(x+1) \\ &= (1-t)(x+1) + t[\tilde{f}(x) + 1] \\ &= \tilde{f}_t(x) + 1. \end{aligned}$$

Thus, each  $\tilde{f}_t$  is a homeomorphism of  $\mathbb{R}$  and descends to a continuous bijection  $f_t: \mathbb{S}^1 \rightarrow \mathbb{S}^1$ . Since  $\mathbb{S}^1$  is compact Hausdorff, each  $f_t$  is a homeomorphism. This shows that  $f$  is isotopic to the identity map, so  $f \in \text{Homeo}_0(\mathbb{S}^1)$ . Therefore, by the first isomorphism theorem,

$$\text{MCG}(\mathbb{S}^1) = \text{Homeo}(\mathbb{S}^1)/\text{Homeo}_0(\mathbb{S}^1) \simeq \{\pm 1\} \simeq \mathbb{Z}_2.$$

$\square$