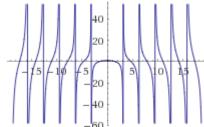
$$(a)\triangle y = sin(x+h) - sin(x) \approx sin'(x) \times h = h \cdot cos(x)$$

- $(b)\Delta y/y = h \cdot cos(x)/sin(x) = h \cdot cot(x), x \neq \pm n\pi, n = 0, 1, 2, 3...$  When  $x = \pm n\pi, n = 0, 1, 2, 3...$ , there is no real relative error.
- (c)  $cond = \frac{\triangle y/y}{\triangle x/x} = \frac{h \cdot cot(x)}{h/x} = x \cdot cot(x), x \neq \pm n\pi, n = 0, 1, 2, 3....$  When  $x = \pm n\pi, n = 0, 1, 2, 3...$ , there is no recondition number.
- (d) The curve of cond is like below with  $x \in (-15, 15)$ . When  $x = \pm n\pi$ , n =0, 1, 2, 3..., the absolute value of cond is extremely large. So the estimation will be highly sensitive.



(a) $x^2 - y^2$ has a higher accuracy in floating-point arithmetic.

 $fl(x^2 - y^2) = [(\bar{x}^2)(1 + \delta_1) - (y^2)(1 + \bar{\delta}_2)](1 + \delta_3) = x^2 + x^2\delta_1 - y^2 - \bar{\delta}_1$  $y^{2}\delta_{2} + x^{2}\delta_{3} + x^{2}\delta_{1}\delta_{3} - y^{2}\delta_{3} - y^{2}\delta_{2}\delta_{3}$ 

 $\approx x^2(1+\delta_1+\delta_3) - y^2(1+\delta_2+\delta_3) = (x^2-y^2)(1+2\epsilon_{mach})$   $fl((x-y)(x+y)) = [(x-y)(1+\delta_1)][(x+y)(1+\delta_2)](1+\delta_3) = (x^2-y^2)(1+\delta_3)$  $2\epsilon_{mach}$ )(1 +  $\epsilon_{mach}$ )

(b) When x and y are one big with the other very small, (x - y)(x + y) is substantially more accurate.

When x and y are very different. For an example, x is  $10^{10}$  bigger than y,  $x^2$  will be  $10^{20}$  bigger than  $y^2$ , which makes  $x^2$  cease to change as  $y^2$  is relatively negligible.

Programming part

1.4

As k goes from 1 to 8, the estimation continues to increase at a slowing-down speed. So the error continues to approach 0.

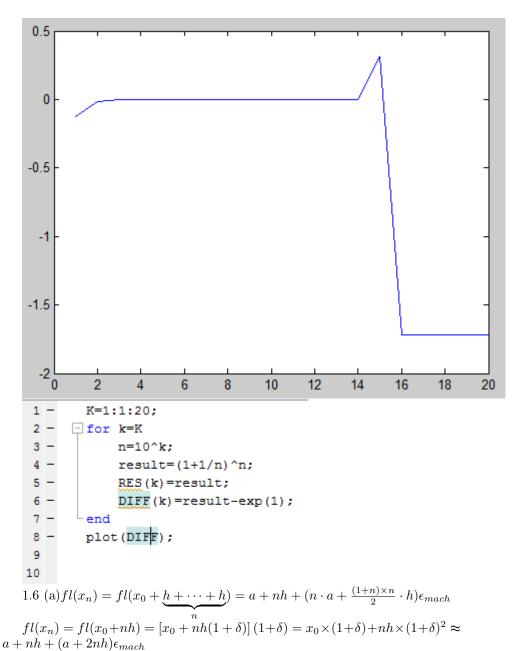
From 9 to 12, the value of  $fl(1+1/n)^n$  is greater than e. Because the rounding error introduced by multiplying a value close to  $e \times (1 + 1/10^k), k =$ [9, 10, 11, 12]

is influentially relatively big.

From 13 to 14, the rounding error by multiplying the (1+1/n)take away the value in the estimation function influentially.

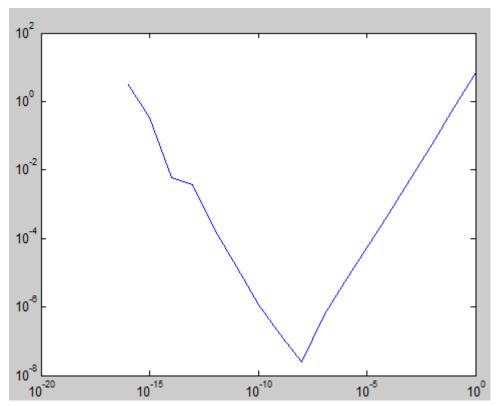
At k=15, 1/n is the last position in mantissa, which means rounding error becomes relatively even bigger. And the rounding error makes the value bigger

From 16 to 20, 1/n is smaller than  $\epsilon$ , so 1+1/n=1 and the error becomes 1-e.



The second one has a smaller rounding error. So the second one is better.

```
format long;
       a=0:
       b=1;
       n=13^8;
       xk=a;
     □ for k=1:1:10^7
             xk=xk+1/n;
       end
       xk2=a+10^7*1/n;
   The first formula is bigger than the second by 4.456487262549658e-13.
   1.7(a) There is a minimum value for the magnitude of error. h=10<sup>-8</sup>. \epsilon_{mach} =
\frac{1}{2}\beta^{1-p} = \frac{1}{2}10^{1-17} = 0.5 \times 10^{-16}. \sqrt{\epsilon_{mach}} = \sqrt{0.5 \times 10^{-16}} \approx 7.1 \times 10^{-9} = 0.5 \times 10^{-16}.
0.71 \times 10^{-8}. It matches well.
          function[Derivative] = Appr(x,h,F)
   1
   2
            %x, h, F
   3 -
            f=inline(F); %repalce the funciton to be test in the parentheses;
           Derivative=(f(x+h)-f(x))/h;
   1 -
            format long;
   2 -
            x=1; K=0:1:16; F='tan(x)';
          for k=K,
   3 -
                  h(k+1)=10^{-(-k)};
   4 -
   5 -
                  APPR(k+1) = Appr(x, h(k+1), F);
    6 -
                  ERR(k+1) = APPR(k+1) - sec(x)^2;
   7 -
           ∟end
   8 -
            loglog(h,abs(ERR));
            min(abs(ERR))
```



(b) There is a minimum value for error. The corresponding value for h is  $10^{-7}$ . It is 10 times of  $\sqrt{\epsilon_{mach}}$ . Because this estimation method reduces the truncation error (as you see, the minimum error from the estimation is much smaller than the one from the previous).

```
1
     function[Derivative] = Appr2(x,h,F)
2
       %x, h, F
3 -
       f=inline(F); %repalce the funciton to be test in the parentheses;
      Derivative=(f(x+h)-f(x-h))/2/h;
1 -
       format long;
2
       x=1; K=0:1:16; F='tan(x)';
     for k=K,
3 -
           h(k+1)=10^{-k};
4
           APPR(k+1) = Appr2(x, h(k+1), F);
5 -
6
           ERR(k+1) = APPR(k+1) - sec(x)^2;
      ∟end
8 -
       loglog(h,abs(ERR));
9 -
       min(abs(ERR))
```

