Puhao Li

Education

2023-Present Tsinghua University (THU), Beijing, China

Ph.D. Student, Department of Automation

O Advisor: Prof. Song-Chun Zhu

2019–2023 Tsinghua University (THU), Beijing, China

Undergraduate, Department of Automation

Research Intersts

Computer Vision: 3D Scene Understanding & Human-Scene Interaction

Robotics: Dexterous Grasping & Manipulation & Planning

Long-term Goal: is to create an intelligent system that can naturally interact with a novel environment

via scene understanding, reasoning, planning and manipulation.

Research Experience

Sep 2021 Beijing Institution for General Artificial Intelligence (BIGAI), Beijing, China

-Present Research Intern, General Vision Lab

O Advisor: Dr. Tengyu Liu & Dr. Siyuan Huang

Publications

arXiv PhyRecon: Physically Plausible Neural Scene Reconstruction

Junfeng Ni*, Yixin Chen*, Bohan Jing, Nan Jiang, Bing Wang, Bo Dai, **Puhao Li**, Yixin Zhu, Song-

Chun Zhu, Siyuan Huang

Preprint, under review

IROS 2024 Ag2Manip: Learning Novel Manipulation Skills with Agent-Agnostic Visual and Action

Oral Pitch Representations

Puhao Li*, Tengyu Liu*, Muzhi Han, Haoran Geng, Shu Wang, Yixin Zhu, Song-Chun Zhu,

Siyuan Huang

IEEE/RSJ International Conference on Intelligent Robots and Systems, 2024

RA-L Grasp Multiple Objects with One Hand

Yuyang Li, Bo Liu, Yiran Geng, Puhao Li, Yaodong Yang, Yixin Zhu, Tengyu Liu, Siyuan Huang

IEEE Robotics and Automation Letters

Presented at IROS 2024 (Oral Presentation)

CVPR 2024 Move as You Say, Interact as You Can: Language-guided Human Motion Generation with Scene Affordance

Zan Wang, Yixin Chen, Baoxiong Jia, **Puhao Li**, Jinlu Zhang, Jingze Zhang, Tengyu Liu, Yixin Zhu,

Wei Liang, Siyuan Huang

IEEE Conference on Computer Vision and Pattern Recognition, 2024

ICML 2024 An Embodied Generalist Agent in 3D World

Jiangyong Huang*, Silong Yong*, Xiaojian Ma*, Xiongkun Linghu*, Puhao Li, Yan Wang, Qing Li,

Song-Chun Zhu, Baoxiong Jia, Siyuan Huang

International Conference on Machine Learning, 2024

CVPR 2023 Diffusion-based Generation, Optimization, and Planning in 3D Scenes

Siyuan Huang*, Zan Wang*, **Puhao Li**, Baoxiong Jia, Tengyu Liu, Yixin Zhu, Wei Liang, Song-Chun Zhu

IEEE Conference on Computer Vision and Pattern Recognition, 2023

ICRA 2023 GenDexGrasp: Generalizable Dexterous Grasping

Puhao Li*, Tengyu Liu*, Yuyang Li, Yiran Geng, Yixin Zhu, Yaodong Yang, Siyuan Huang *IEEE International Conference on Robotics and Automation*, 2023

ICRA 2023 DexGraspNet: A Large-Scale Robotic Dexterous Grasp Dataset for General Objects Based Oral on Simulation

Ruicheng Wang*, Jialiang Zhang*, Jiayi Chen, Yinzhen Xu, **Puhao Li**, Tengyu Liu, He Wang *IEEE International Conference on Robotics and Automation*, 2023

Outstanding Manipulation Paper Finalist

Professional Activities

Conference and Journal Reviewer

IEEE Robotics and Automation Letters (RA-L)

IEEE Conference on Computer Vision and Pattern Recognition (CVPR)

European Conference on Computer Vision (ECCV)

Open Source Contribution

Simulately (simulately.wiki), earned 200+ stars in Github

Awards and Scholarships

- 2023 Outstanding Graduation Thesis, Beijing, China
- 2023 Outstanding Graduation Thesis, Tsinghua University
- 2022 Scholarship of Excellent Academic Performance, Tsinghua University
- 2021 Scholarship of Social Work, Tsinghua University