

Lecture 5: Image & Recognition (1)

Introduction to Recognition

- Pattern:
 - The **form of representation** of an objectively existed event or object.
 - A set of **measurements or observations**, represented in vector or matrix notation.
- Pattern distortion (扭曲)
- IR:
 - Intelligent Systems
 - Mapping from feature space to class space

IR System

Sensor -> Image & Signal Processing -> Pattern Recognition -> Decision Theory

Definitions

- **Classification**
 - Probabilistic or grammatical models
 - A classifier: decision regions
- **Recognition**
 - The ability to classify
 - One more class: unclassifiable

- **Pattern class**
 - A set of patterns
 - Keys:
 - Suitable attributes (features)
 - A good measure of similarity and an associating matching process
- **Preprocessing**
 - To aid **computational feasibility**
 - To aid **feature extraction**
 - Minimize **noise**
- **Description**
 - Resort(凭借) to **linguistic** or **structural** models.

Feature

Patterns -> Features with different numerical values.

1. Feature vector
2. Feature space.

Feature Selection

1. Computationally **feasible**
2. Lead to **good** PR system success
3. **Reduce** the problem data into a **manageable** amount of information

Simple classifiers

Template Matching

1. Get some versions of templates.
2. Compare with templates.
 - i. Max correlation.
 - ii. Min error.

Distance Function

A measure of similarity between pattern vectors (proximity).

Error-free linear separation

Consequence: equivalent to min-distance classifier.

Min-distance classifier

- The closest match between the pattern & the respective class prototypes.
(**correlation / cluster matching**)
- May contain single prototype (1 boundary) or multi-prototypes (**piecewise-linear** boundaries)
- Distance is calculated by **norm** $||x - m_k||$.

Linear Discriminants

- To find the m_k that minimizes $\|x - m_k\|$
- To minimize $g(x) = m'x - 0.5\|m\|^2$

Decision Function

For a line $d(X) = w_1x_1 + w_2x_2 + w_3 = 0$ separating 2 classes: $d(X) > 0$ and $d(X) < 0$

Multi-class: more lines.

Image Recognition Steps

- Image Formatting (capture/digitize)
- Conditioning (suppress noise; suppress uninteresting)
- Labeling (determine spatial events)
- Grouping (identifies events; maximum set of pixels in the event)
- Extracting (new spatial entities from groups)
- Matching (match entities to known objects)