

Sinusoidal Driving Forces

$$F = -kx - b \frac{dx}{dt} + F_0 \cos(\omega t)$$

$$m \frac{d^2x}{dt^2} + b \frac{dx}{dt} + kx = F_0 \cos(\omega t)$$

$$\frac{d^2x}{dt^2} + 2B \frac{dx}{dt} + \omega_0^2 x = A \cos(\omega t) \quad \text{where } A = \frac{F_0}{m}$$

The solution of its consists of two parts, a complementary function $X_h(t)$, and a particular solution $X_p(t)$

$$X_h(t) = e^{-Bt} (A_1 e^{\sqrt{B^2 - \omega_0^2} t} + A_2 e^{-\sqrt{B^2 - \omega_0^2} t})$$

for the $X_p(t)$, we try $X_p(t) = D \cos(\omega t - \delta)$

$$-\omega^2 D \cos(\omega t - \delta) - 2BD\omega \sin(\omega t - \delta) + \omega_0^2 D \cos(\omega t - \delta) = A \cos(\omega t)$$

$$-\omega^2 D (\cos(\omega t) \cos \delta + \sin(\omega t) \sin \delta) - 2BD\omega (\sin(\omega t) \cos \delta - \cos(\omega t) \sin \delta) + \omega_0^2 D (\cos(\omega t) \cos \delta + \sin(\omega t) \sin \delta) = A \cos(\omega t)$$

$$\Rightarrow \{A - D[(\omega_0^2 - \omega^2) \cos \delta + 2\omega B \sin \delta]\} \cos \omega t - \{D[(\omega_0^2 - \omega^2) \sin \delta - 2\omega B \cos \delta]\} \sin \omega t = 0$$

$$\tan \delta = \frac{2\omega B}{\omega_0^2 - \omega^2}, \quad \sin \delta = \frac{2\omega B}{\sqrt{(\omega_0^2 - \omega^2)^2 + 4\omega^2 B^2}}, \quad \cos \delta = \frac{\omega_0^2 - \omega^2}{\sqrt{(\omega_0^2 - \omega^2)^2 + 4\omega^2 B^2}}$$

$$D = \frac{A}{(\omega_0^2 - \omega^2) \cos \delta + 2\omega B \sin \delta} = \frac{A}{\sqrt{(\omega_0^2 - \omega^2)^2 + 4\omega^2 B^2}}$$

$$\Rightarrow X_p(t) = \frac{A}{\sqrt{(\omega_0^2 - \omega^2)^2 + 4\omega^2 B^2}} \cos(\omega t - \delta) \quad \delta = \tan^{-1} \frac{2\omega B}{\omega_0^2 - \omega^2}$$

$X_h(t)$ is transient effects, the terms contained in this solution damp out with time because of the factor e^{-Bt} , the $X_p(t)$ represents the steady-state effects

$$x(t \gg \frac{1}{B}) = X_p(t)$$

to find the angular frequency ω_R at which the amplitude D is a maximum (amplitude resonance frequency), we set

$$\frac{-2\omega(2B^2 + \omega^2 - \omega_0^2) \frac{dD}{d\omega}}{[(\omega_0^2 - \omega^2)^2 + 4\omega^2 B^2]^{\frac{3}{2}}} = 0 \quad , \quad \omega_R = \sqrt{\omega_0^2 - 2B^2}$$

$$2B^2 + \omega_0^2 - \omega_0^2 = 0 \\ \text{no resonance occurs if } B > \frac{\omega_0}{2}$$

free oscillations, no damping > free oscillations, damping > driven oscillations

$$\omega_0^2 = \frac{k}{m} > \omega^2 = \omega_0^2 - B^2 > \omega_R^2 = \omega_0^2 - 2B^2$$

describe the degree of damping in an oscillating system in terms of the "quality factor"

$$Q \equiv \frac{\omega_R}{2B}$$

for a lightly damped oscillator

$$D = \frac{A}{\sqrt{(\omega_0^2 - \omega^2)^2 + 4\omega^2 B^2}} \quad \text{at the } \omega = \omega_R = \sqrt{\omega_0^2 - 2B^2}$$

$$D_B = \frac{A}{2B\sqrt{\omega_0^2 - B^2}}$$

let us find the frequency, $\omega = \omega'$ at which the amplitude is $\frac{1}{\sqrt{2}} D_B$

$$(\omega_0^2 - \omega'^2)^2 + (2B\omega')^2 = (\sqrt{2})^2 (2B\omega')^2, (\omega_0^2 - \omega'^2)(\omega_0^2 + \omega'^2) = 4\omega'^2 B^2$$

$$(\omega')^2 = \omega_0^2 - 2B^2 \pm 2B\omega_0\sqrt{1 - \frac{B^2}{\omega_0^2}} \cong \omega_0^2 \pm 2B\omega_0$$

$$\omega' \cong \omega_0 (1 \pm \frac{B}{\omega_0})$$

$$\Delta\omega = (\omega_0 + B) - (\omega_0 - B) = 2B$$

$$\omega_R = \sqrt{\omega_0^2 - 2B^2} \cong \omega_0$$

$$\Rightarrow Q \cong \frac{\omega_0}{\Delta\omega}$$

where $\Delta\omega$ represents the frequency interval between the points

on the amplitude resonance curve that are $\frac{1}{\sqrt{2}}$ of the maximum amplitude

$$\frac{dx}{dt} = \frac{-A\omega}{\sqrt{(\omega_0^2 - \omega^2)^2 + 4\omega^2 B^2}} \sin(\omega t - \delta)$$

$$E_k = \frac{1}{2} m \left(\frac{dx}{dt} \right)^2 = \frac{m A^2}{2} \frac{\omega^2}{(\omega_0^2 - \omega^2)^2 + 4\omega^2 B^2} \sin^2(\omega t - \delta)$$

to obtain a value of E_k independent of the time, we compute the average of E_k over one complete period of oscillation

$$\langle E_k \rangle = \frac{m A^2}{2} \frac{\omega^2}{(\omega_0^2 - \omega^2)^2 + 4\omega^2 B^2} \langle \sin^2(\omega t - \delta) \rangle$$

the average value of the square of the sine function taken over one period

$$\langle \sin^2(\omega t - \delta) \rangle = \frac{\omega}{2\pi} \int_0^{2\pi} \sin^2(\omega t - \delta) dt = \frac{1}{2}$$

$$\langle E_k \rangle = \frac{m A^2}{4} \frac{\omega^2}{(\omega_0^2 - \omega^2)^2 + 4\omega^2 B^2}$$

the value ω for $\langle E_k \rangle$ a maximum is labeled ω_E and is obtained from

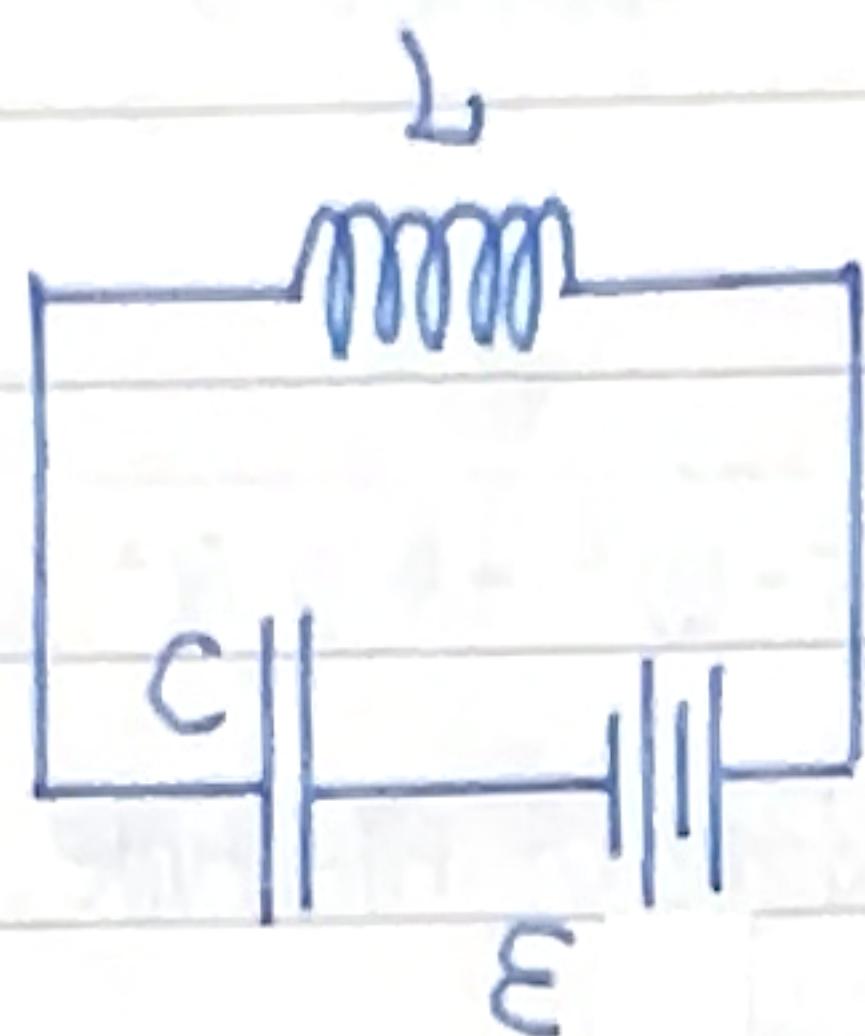
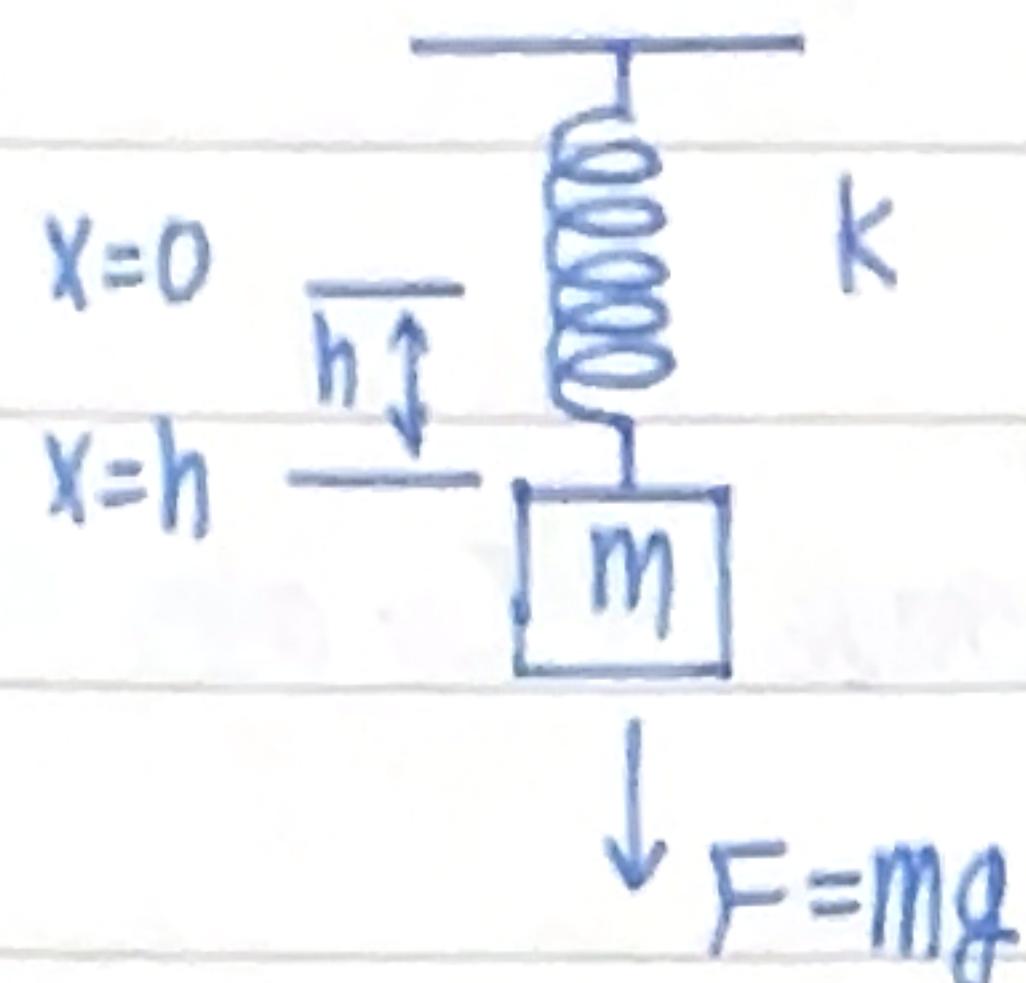
$$\frac{d\langle E_k \rangle}{d\omega} \Big|_{\omega=\omega_E} = 0, \quad \omega_E = \omega_0$$

amplitude resonance at $\sqrt{\omega_0^2 - 2B^2}$ ← potential energy resonance

kinetic energy resonance occurs at ω_0

⇒ damped oscillator is not a conservative system

Physical Systems

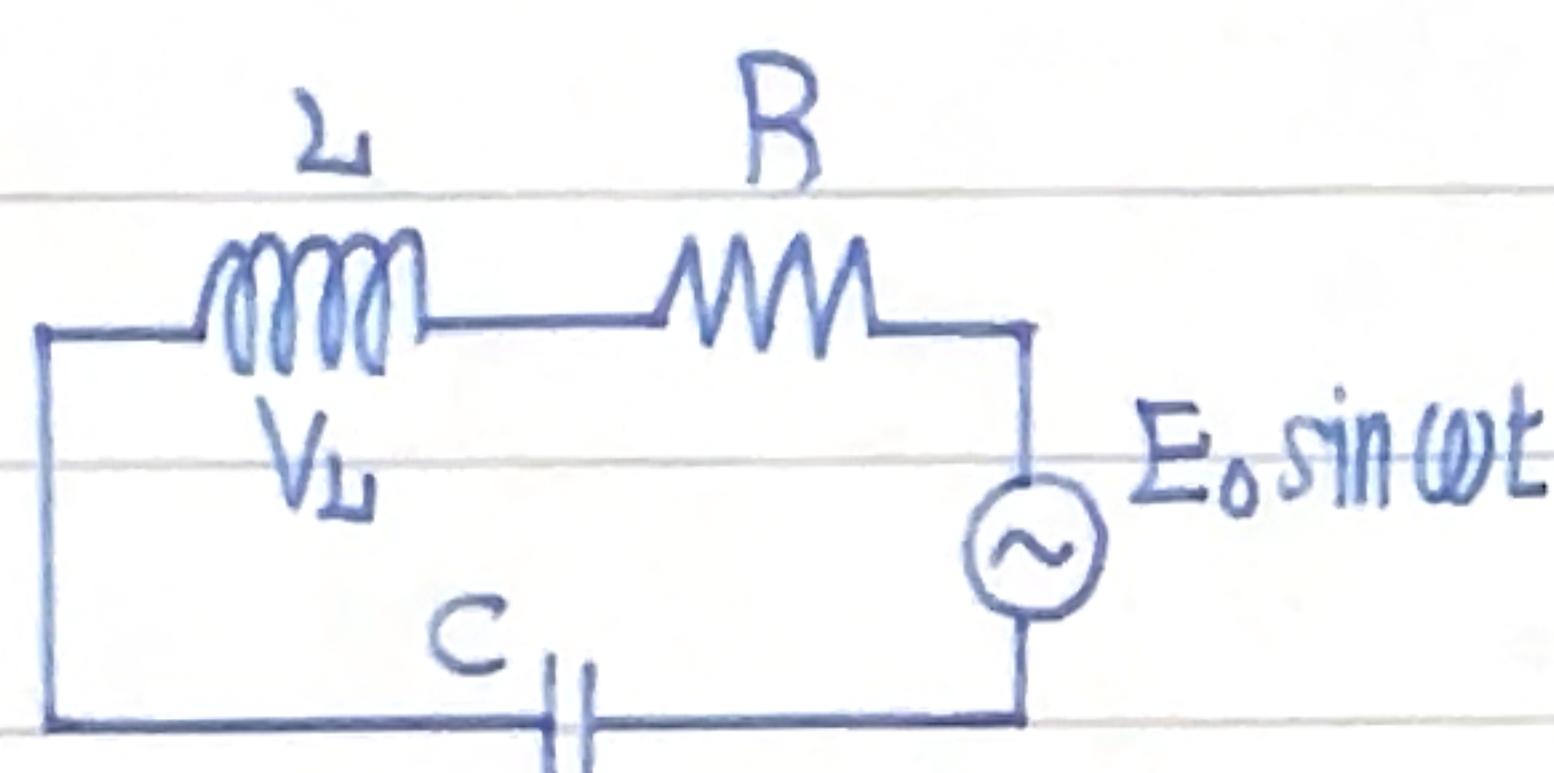


$$m \frac{d^2x}{dt^2} + k(x-h) = 0 \Leftrightarrow L \frac{dI}{dt} + \frac{1}{C} \int I dt = E = \frac{q_1}{C}$$

$$x(t) = h + A \cos(\omega_0 t)$$

$$L \frac{d^2q}{dt^2} + \frac{1}{C} q = \frac{q_1}{C}$$

$$q(t) = q_1 + (q_0 - q_1) \cos(\omega_0 t)$$



$$V_L = L \frac{dI}{dt} = L \frac{d^2q}{dt^2}$$

$$L \frac{d^2q}{dt^2} + R \frac{dq}{dt} + \frac{q}{C} = E_0 \sin(\omega t)$$

$$V_R = L I = L \frac{dq}{dt}$$

$$R = \frac{V_R}{I} \quad \omega_0 = \frac{1}{\sqrt{LC}} \quad A = \frac{E_0}{L}$$

$$V_C = \frac{q}{C}$$

$$I = \frac{-E_0}{\sqrt{R^2 + \left(\frac{1}{\omega C} - \omega L\right)^2}} \sin(\omega t - \delta)$$

$$V_L = \frac{-\omega L E_0}{\sqrt{R^2 + \left(\frac{1}{\omega C} - \omega L\right)^2}} \cos(\omega t - \delta) = V(\omega) \cos(\omega t - \delta)$$

$$\frac{dV(\omega)}{d\omega} = \frac{L E_0 \left(R^2 - \frac{2L}{C} + \frac{2}{\omega^2 C^2} \right)}{\left[R^2 + \left(\frac{1}{\omega C} - \omega L \right)^2 \right]^{\frac{3}{2}}}$$

$$\omega_{max} = \frac{1}{\sqrt{L C - \frac{R^2 C^2}{2}}}$$

$$\omega_B = \sqrt{\frac{1}{2C} - \frac{2R^2}{L^2}}$$

Principle of Superposition - Fourier Series

$$\left(\frac{d^2}{dt^2} + a \frac{d}{dt} + b \right) x(t) = A \cos(\omega t)$$

$$\Rightarrow \mathcal{L} x(t) = F(t)$$

linear operator

linear operator obey the principle of superposition

$$\mathcal{L}(x_1 + x_2) = \mathcal{L}(x_1) + \mathcal{L}(x_2)$$

$$\mathcal{L}x_1 = F_1(t) \quad \mathcal{L}x_2 = F_2(t)$$

$$\Rightarrow \mathcal{L}(a_1 x_1 + a_2 x_2) = a_1 F_1(t) + a_2 F_2(t)$$

$$\Rightarrow \mathcal{L}\left(\sum_{n=1}^N a_n x_n(t)\right) = \sum_{n=1}^N a_n F_n(t)$$

$$x(t) = \sum_{n=1}^N a_n x_n(t) \quad F(t) = \sum_{n=1}^N a_n F_n(t) = \sum_{n=1}^N a_n \cos(\omega_n t - \phi_n)$$

$$\text{the steady-state solution is } x(t) = \frac{1}{m} \sum_n \frac{a_n}{\sqrt{(\omega_0^2 - \omega_n^2)^2 + 4\omega_n^2 B^2}} \cos(\omega_n t - \phi_n - \delta_n)$$

$$\delta_n = \tan^{-1} \left(\frac{2\omega_n B}{(\omega_0^2 - \omega_n^2)} \right)$$

$$F(t) = \frac{1}{2} a_0 + \sum_{n=1}^{\infty} (a_n \cos n\omega t + b_n \sin n\omega t)$$

$$a_n = \frac{2}{T} \int_0^T F(t') \cos n\omega t' dt' = \frac{\omega}{\pi} \int_{-\frac{\pi}{\omega}}^{\frac{\pi}{\omega}} F(t') \cos n\omega t' dt'$$

$$b_n = \frac{2}{T} \int_0^T F(t') \sin n\omega t' dt' = \frac{\omega}{\pi} \int_{-\frac{\pi}{\omega}}^{\frac{\pi}{\omega}} F(t') \sin n\omega t' dt'$$