

## Second derivatives

divergence of gradient  $\nabla \cdot (\nabla T)$  divergence of curl  $\nabla \cdot (\nabla \times \vec{V})$

curl of gradient  $\nabla \times (\nabla T)$  curl of curl  $\nabla \times (\nabla \times \vec{V})$

gradient of divergent  $\nabla \cdot (\nabla \cdot \vec{V})$

$\nabla \cdot (\nabla T)$

$$\begin{aligned} &= \nabla \left( \frac{\partial T}{\partial x} \hat{i} + \frac{\partial T}{\partial y} \hat{j} + \frac{\partial T}{\partial z} \hat{k} \right) = \left( \frac{\partial}{\partial x} \hat{i} + \frac{\partial}{\partial y} \hat{j} + \frac{\partial}{\partial z} \hat{k} \right) \cdot \left( \frac{\partial T}{\partial x} \hat{i} + \frac{\partial T}{\partial y} \hat{j} + \frac{\partial T}{\partial z} \hat{k} \right) \\ &= \frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} + \frac{\partial^2 T}{\partial z^2} = \nabla^2 T \quad \text{Laplacian of } T \end{aligned}$$

$(\nabla \cdot \nabla) \vec{V}$

$$\begin{aligned} &= \left[ \left( \frac{\partial}{\partial x} \hat{i} + \frac{\partial}{\partial y} \hat{j} + \frac{\partial}{\partial z} \hat{k} \right) \cdot \left( \frac{\partial}{\partial x} \hat{i} + \frac{\partial}{\partial y} \hat{j} + \frac{\partial}{\partial z} \hat{k} \right) \right] \vec{V} \\ &= \left( \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right) (\hat{i} V_x + \hat{j} V_y + \hat{k} V_z) \\ &= \nabla^2 V_x \hat{i} + \nabla^2 V_y \hat{j} + \nabla^2 V_z \hat{k} \quad \nabla^2 \vec{V} = (\nabla \cdot \nabla) \vec{V} \approx \nabla (\nabla \cdot \vec{V}) \end{aligned}$$

$\nabla \cdot (\nabla \times \vec{V})$

$$\because \vec{A} \cdot (\vec{B} \times \vec{C}) = (\vec{A} \times \vec{B}) \cdot \vec{C}$$

$$\Rightarrow (\nabla \times \nabla) \cdot \vec{V} = 0 \cdot \vec{V} = \begin{vmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ V_x & V_y & V_z \end{vmatrix} = 0$$

means if  $\nabla \cdot \vec{A} = 0$ , then  $\vec{A} = \nabla \times \vec{B}$

EX:  $\nabla \cdot \vec{B} = 0$   $\vec{B} = \nabla \times \vec{A}$  vector potential

$\nabla \times (\nabla T)$

$$= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{\partial T}{\partial x} & \frac{\partial T}{\partial y} & \frac{\partial T}{\partial z} \end{vmatrix} = \left( \frac{\partial^2 T}{\partial y \partial z} - \frac{\partial^2 T}{\partial z \partial y} \right) \hat{i} + \left( \frac{\partial^2 T}{\partial z \partial x} - \frac{\partial^2 T}{\partial x \partial z} \right) \hat{j} + \left( \frac{\partial^2 T}{\partial x \partial y} - \frac{\partial^2 T}{\partial y \partial x} \right) \hat{k} = 0$$

means if  $\nabla \times \vec{A} = 0$  then  $\vec{A} = \pm \nabla V$

EX:  $\nabla \times \vec{E} = 0$  for static  $E$ , then  $\vec{E} = -\nabla V$

$\nabla \times (\nabla \times \vec{V})$

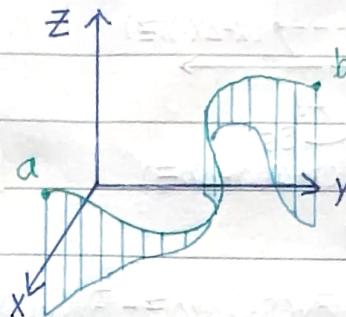
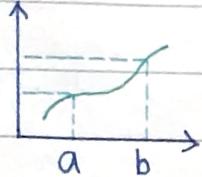
$$\because \vec{A} \times \vec{B} \times \vec{C} = (\vec{A} \cdot \vec{C}) \vec{B} - (\vec{A} \cdot \vec{B}) \vec{C}$$

$$\Rightarrow \nabla(\nabla \cdot \vec{V}) - (\nabla \cdot \nabla) \cdot \vec{V}$$

## Integral Calculus

$$\int_a^b \frac{dF(x)}{dx} = - \int_b^a \frac{dF(x)}{dx} = \int_a^b f(x) = F(b) - F(a)$$

$$\int_a^b (\nabla g) \cdot d\vec{l} = \int \frac{\partial g}{\partial x} dx + \int \frac{\partial g}{\partial y} dy + \int \frac{\partial g}{\partial z} dz = g(b_x, b_y, b_z) - g(a_x, a_y, a_z)$$



$$\text{corollary 1: } \int_a^b (\nabla g) \cdot d\vec{l} = g(\vec{b}) - g(\vec{a})$$

$$\text{corollary 2: } \oint (\nabla g) \cdot d\vec{l} = 0 = \int_a^a (\nabla g) \cdot d\vec{l}$$

Gauss theorem, Green's theorem, divergence theorem

$$\int \text{fluxes within the volume} = \int \text{flow out through the surface} \quad \int_V (\nabla \cdot \vec{B}) dV = \oint_S \vec{B} \cdot d\vec{a}$$



Stoke's theorem

corollary 1:  $\int (\nabla \times \vec{V}) \cdot d\vec{a}$  depends only on the boundary line, not on the particular surface used

corollary 2:  $\oint (\nabla \times \vec{V}) \cdot d\vec{a} = 0$  for any closed surface

$$\int_S (\nabla \times \vec{V}) \cdot d\vec{a} = \oint_{\text{boundary}} \vec{V} \cdot d\vec{l}$$

let  $\vec{V} = \nabla T$  and  $a=b$ , [ gradient theorem  $\int_a^b \vec{V} \cdot d\vec{l} = \oint \vec{V} \cdot d\vec{l} = 0$   
Stoke's theorem  $\oint \vec{V} \cdot d\vec{l} = \int_S (\nabla \times \vec{V}) \cdot d\vec{a} = \int_S \nabla \times (\nabla T) \cdot d\vec{a} = 0$  means  $\nabla \times (\nabla T) = 0$

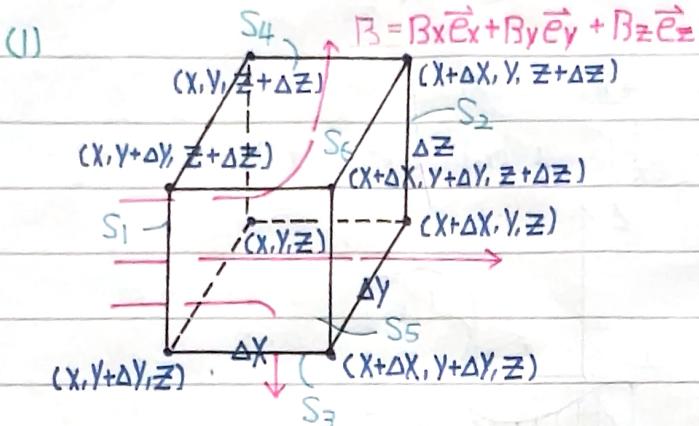
$$\text{let } \oint_S (\nabla \times \vec{V}) \cdot d\vec{a} = 0$$

$$\oint_S (\nabla \times \vec{V}) \cdot d\vec{a} = \int_V \nabla \cdot (\nabla \times \vec{V}) dV = 0 \text{ means } \nabla \cdot (\nabla \times \vec{V}) = 0$$

$$\int \nabla \cdot (\vec{f} \vec{A}) dV = \int \vec{f} \cdot (\nabla \cdot \vec{A}) dV + \int \vec{A} \cdot (\nabla \cdot \vec{f}) dV = \oint_S \vec{f} \vec{A} \cdot d\vec{a}$$

$$\Rightarrow \int_V \vec{f} \cdot (\nabla \cdot \vec{A}) dV = - \int_V \vec{A} \cdot (\nabla \cdot \vec{f}) dV + \oint_S \vec{f} \vec{A} \cdot d\vec{a}$$

Green's theorem  $\int_V (\nabla \cdot \vec{B}) dV = \oint_S \vec{B} \cdot d\vec{a}$



flux of  $S_1$  and  $S_2$ :  $B_x(S_2) \Delta y \Delta z - B_x(S_1) \Delta y \Delta z$  and  $B_x(S_2) = B_x(S_1) + \frac{\partial B_x}{\partial x} \Delta x$

$$\Rightarrow [B_x(S_1) + \frac{\partial B_x}{\partial x} \Delta x] \Delta y \Delta z - B_x(S_1) \Delta y \Delta z = \frac{\partial B_x}{\partial x} \Delta x \Delta y \Delta z$$

similarly, flux( $S_3, S_4$ ) =  $\frac{\partial B_z}{\partial z} \Delta x \Delta y \Delta z$ , flux( $S_5, S_6$ ) =  $\frac{\partial B_y}{\partial y} \Delta x \Delta z \Delta y$

$$\Rightarrow \oint \vec{B} \cdot d\vec{a} = (\frac{\partial B_x}{\partial x} + \frac{\partial B_y}{\partial y} + \frac{\partial B_z}{\partial z}) \Delta x \Delta y \Delta z = (\nabla \cdot \vec{B}) \Delta V$$

$$\Rightarrow \lim_{\Delta x \Delta y \Delta z \rightarrow 0} \frac{\oint \vec{B} \cdot d\vec{a}}{\Delta x \Delta y \Delta z} = \frac{\partial B_x}{\partial x} + \frac{\partial B_y}{\partial y} + \frac{\partial B_z}{\partial z} = \nabla \cdot \vec{B}$$

(2)

$$\begin{aligned} \int_V (\nabla \cdot \vec{B}) dV &= \int_V \frac{\partial B_x}{\partial x} dx dy dz + \int_V \frac{\partial B_y}{\partial y} dx dy dz + \int_V \frac{\partial B_z}{\partial z} dx dy dz \\ &= \iint dy dz \int_{x_1}^{x_2} \frac{\partial B_x}{\partial x} dx = \iint [B_x(x_2, y, z) - B_x(x_1, y, z)] dy dz \\ &= B_x(P_2) da_{xy} - B_x(P_1) (-da_{xy}) = B_{x_2} da_{xy} + B_{x_1} da_{xy} = \oint_S B_x da_x \\ &= \oint_S (B_x da_x + B_y da_y + B_z da_z) = \oint_S \vec{B} \cdot d\vec{a} \end{aligned}$$

consider a point P at the center of a small volume  $\Delta V$ , if  $\Delta V$  is very small

$$\int_{\Delta V} \nabla \cdot \vec{B} dV = \langle \nabla \cdot \vec{B} \rangle_p \Delta V, \quad \langle \nabla \cdot \vec{B} \rangle_p = \frac{1}{\Delta V} \oint_S \vec{B} \cdot d\vec{a}$$

$$\nabla \cdot \vec{B} = \lim_{\Delta V \rightarrow 0} \frac{1}{\Delta V} \oint_S \vec{B} \cdot d\vec{a}$$