XIHANG YU (JIMMY)

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EDUCATION

University of Michigan, College of Literature, Science, and the Arts

ANN ARBOR, MI

B.S. in Computer Science with Honors, B.S. in Mathematics, GPA: 4.0 /4.0

Jan 2022 - May 2024(Expected)

COLUMBIA UNIVERSALITY, COLUMBIA COLLEGE

NEW YORK, NY

Visiting Student Program in Computer Science track, GPA: 4.0/4.0

Sep 2021 - Dec 2021

CHINESE UNIVERSITY OF HONG KONG, DEPT. OF COMPUTER SCIENCE

Hong Kong

Major in Artificial Intelligence: Systems and Technologies, GPA: 3.869/4.0

SELECTED COURSES:

Sep 2019 - May 2021

Graduate Level: Hybrid Control, Continuous Optimization Methods, Mobile Robotics, Nonlinear Dynamics and Geometric Mechanics, Robot Perception, Principles of Machine Learning.

Undergraduate Level: Analysis and Optimization, Combinatorics and Graph Theory, Linear Programming,

Autonomous Robotics, Natural Language Processing, Computer Vision, Computational Aspects of Robotics, Computer Systems, Computer Science Theory, Cryptography.

RESEARCH INTERESTS

Optimization, Robot Perception, Vision-based Control

PUBLICATION

[1] Fully Proprioceptive Slip-Velocity-Aware State Estimation for Mobile Robots via Invariant Kalman Filtering and Disturbance Observer

X. Yu, S. Teng, T. Chakhachiro, W. Tong, T. Li, TY. Lin, S. Koehler, M. Ahumada, JM. Walls, M. Ghaffari 2023 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS) (acceptance rate: 43.3%)[arXiv]

[2] LaDyBot: Learning Language-Guided Collaborative Dynamics

X. Yu, E. A. Olson, and O. C. Jenkins

Computer Science Honors Thesis, University of Michigan.

[3] SIM-Sync: From Certifiably Optimal Synchronization over the 3D Similarity Group to Scene Reconstruction with Learned Depth

X. Yu, H. Yang

Under Review at RA-L. [arXiv]

[4] APISR: Anime Production Inspired Real-World Anime Super-Resolution

B. Wang, F. Yang, X. Yu, C. Zhang, H. Zhao

Under Review at CVPR

RESEARCH AND INTERNSHIP

MANIPULATION AND ROBOT PERCEPTION | ROBOTICS INSTITUTE, UNIVERSITY OF MICHIGAN

Research Assistant Supervised by Dr. Chad Jenkins (Lab for Progress)

Jan 2023-April 2023, Sep 2023 - Present

Conducted Computer Science Honors Thesis: Learning Language-Guided Collaborative Dynamics in Robotics

CERTIFIABLE ALGORITHM AND SEMIDEFINITE PROGRAMMING | HARVARD UNIVERSITY

Visiting Scholar Supervised by Dr. Heng Yang (Computational Robotics Lab)

May 2023 - Aug 2023

Developed certifiably correct camera trajectory estimation algorithm using semidefinite programming (SDP)

MOBILE ROBOT | ROBOTICS INSTITUTE, UNIVERSITY OF MICHIGAN

Research Assistant Supervised by Dr. Maani Ghaffari (Curly Lab)

April 2022 - Dec 2022

• Conducted research on state estimation using Invariant Extended Kalman Filter

REHABILITATION ROBOT | MECHANICAL ENGINEERING DEPT., COLUMBIA UNIVERSITY

Research Assistant Supervised by Dr. Sunil K Agrawal (ROAR Lab)

Dec 2021 - April 2022

• Contributed kinematics and dynamic libraries to wheelchair robot for active postural support using rospy [website]

AV SIMULATION | CIVIL ENGINEERING AND ENGINEERING MECHANICS DEPT., COLUMBIA UNIVERSITY

Research Assistant Supervised by Dr. Sharon Di (DitecT Lab)

Sep 2021 - Dec 2021

• Developed MmWave communication in TraCI framework for NS3 and SUMO Coupling in the COSMOS project

SOFTWARE ENGINEER INTERNSHIP | HUAWEI TECHNOLOGIES CO., LTD

June 2021 - Aug 2021

Contributed to code auto-generation frame on HUAWEI OptiX OSN1800 OTN communication platform
LYAPUNOV STABILITY AND FINITE-TIME CONTROL | CUHK SUMMER RESEARCH INTERNSHIP

Research Assistant Supervised by Dr. Dongkun Han

May 2020 - Aug 2020

Designed Control Barrier Function-based multiagent coordination controller with Matlab simulation [video]

SELECTED COURSE PROJECTS

3D SEMANTIC SCENE UNDERSTANDING | EECS487 INTRODUCTION TO NLP, UNIVERSITY OF MICHIGAN

• Fine-tuned feed-forward network with GPT-J that achieves state-of-the-art scene classification performance

VISION AND LANGUAGE MANIPULATION | EECS498 PRINCIPLE OF ML, UNIVERSITY OF MICHIGAN

Conducted transfer learning experiments of the PerceiverActor model on the VLMbench dataset

PARALLEL COMPUTING | EECS475 INTRODUCTION TO CRYPTOGRAPHY, UNIVERSITY OF MICHIGAN

Developed from scratch parallelized versions of cryptographic algorithms, encompassing Counter Mode (CTR),
Electronic Code Book (ECB), Cipher Block Chaining (CBC), and Hash Tree algorithms

HYBRID MODEL PREDICTIVE CONTROL | EECS563 HYBRID CONTROL, UNIVERSITY OF MICHIGAN

 Proposed and implemented Moment Relaxation-based solver for Multi-Contact Consensus Complementarity Control via ADMM

3D VISION | EECS442 COMPUTER VISION, UNIVERSITY OF MICHIGAN

Proposed and implemented SDP-based formulation for joint camera trajectory estimation and depth finetuning

LEADERSHIP AND SERVICES

TEACHING ASSISTANT | ROB 530 MOBILE ROBOTICS, UNIVERSITY OF MICHIGAN

Instructor: Dr. Maani Ghaffari

Jan 2023 - Apr 2023

• Helped to develop homework and quizzes, organized office hour sessions in the graduate course with 158 students

REVIEWER | TRANSACTION ON MECHATRONICS (TMECH)

GRADER | MATH 465 COMBINATORICS AND GRAPH

Oct 2022 - Dec 2022

MOTION PLAN SUBTEAM LEADER | COLUMBIA UNIVERSITY ROBOTICS CLUB

Sep 2021 - Dec 2021

Led 10+ Columbia students to develop autonomous vehicles, organized motion planning workshops

HONORS AND AWARDS

UNIVERSITY HONORS, UMICH Academic Merit	Dec 2022
LEUNG SIU KOI SCHOLARSHIP, CUHK Academic Merit	Dec 2021
ELITE STREAM SCHOLARSHIP, CUHK Academic Merit	Oct 2021
DEAN'S LIST, CUHK Top 10% in the department	Aug 2021, Aug 2020
CHUNG CHI COLLEGE CLASS SCHOLARSHIP, CUHK Best student in the class of a department	Nov 2020
TALENT DEVELOPMENT SCHOLARSHIP, HONG KONG GOVERNMENT EDUCATION BUREAU	May 2020
NATIONAL CREATIVE COMPOSITION COMPETITION Grand Prize (10 awards in total, National level)	Aug 2018

SKILLS

- Programming Tool: Experienced with C/C++ (system-level and high-performance code), Python (including PyTorch, Pandas, and Numpy), MATLAB (fast-implemented simulation code)
- Robotics Tool: ROS, CUDA, NVIDIA Issac Gym, PyBullet
- Optimization Tool: MOSEK, Gurobi

EXTRACURRICULAR ACTIVITIES

University of Michigan Chinese Soccer Club