# XIHANG YU (JIMMY)

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### **EDUCATION**

UNIVERSITY OF MICHIGAN, COLLEGE OF LITERATURE, SCIENCE, AND THE ARTS

B.S. in Computer Science with Honors, B.S. in Mathematics, GPA: 4.0 / 4.0

COLUMBIA UNIVERSALITY, COLUMBIA COLLEGE

Visiting Student Program in Computer Science track, GPA: 4.0 / 4.0

CHINESE UNIVERSITY OF HONG KONG, DEPT. OF COMPUTER SCIENCE

Major in Artificial Intelligence: Systems and Technologies, GPA: 3.869 / 4.0

ANN ARBOR, MI

Jan 2022 - May 2024 (Expected)

NEW YORK, NY

Sep 2021 - Dec 2021

HONG KONG

Major in Artificial Intelligence: Systems and Technologies, GPA: 3.869 / 4.0

#### **SELECTED COURSES:**

Graduate Level: Hybrid Control, Continuous Optimization Methods, Mobile Robotics, Nonlinear Dynamics and Geometric Mechanics, Deep Learning for Robot Perception, Principles of Machine Learning Undergraduate Level: Analysis and Optimization, Combinatorics and Graph Theory, Linear Programming, Introduction to Autonomous Robotics, Natural Language Processing, Computer Vision, Computational Aspects of Robotics, Introduction to Computer Systems, Computer Science Theory, Introduction to Cryptography

#### **RESEARCH INTERESTS**

Optimization, Robot Perception, Vision-based Control

#### **PUBLICATION**

X. Yu, S. Teng, T. Chakhachiro, W. Tong, T. Li, TY. Lin, S. Koehler, M. Ahumada, JM. Walls, M. Ghaffari, "Fully Proprioceptive Slip-Velocity-Aware State Estimation for Mobile Robots via Invariant Kalman Filtering and Disturbance Observer", 2023 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS) (acceptance rate: 43.3%)[arXiv]

**X. Yu**, E. A. Olson, and O. C. Jenkins. LaDyBot: Learning Language-Guided Collaborative Dynamics, 2023. Computer Science Honors Thesis, University of Michigan.

**X. Yu**, H. Yang, "SIM-Sync: From Certifiably Optimal Synchronization over the 3D Similarity Group to Scene Reconstruction with Learned Depth". Under Review at RA-L. [arXiv]

B. Wang, F. Yang, X. Yu, C. Zhang, H. Zhao, "APISR: Anime Production Inspired Real-World Anime Super-Resolution". Under Review at CVPR.

#### RESEARCH AND INTERNSHIP

MANIPULATION AND ROBOT PERCEPTION | ROBOTICS INSTITUTE, UNIVERSITY OF MICHIGAN

Research Assistant Supervised by Dr. Chad Jenkins (Lab for Progress)

Jan 2023-April 2023, Sep 2023 - Present

Conducted Computer Science Honors Thesis: Learning Language-Guided Collaborative Dynamics in Robotics

CERTIFIABLE ALGORITHM AND SEMIDEFINITE PROGRAMMING | HARVARD UNIVERSITY

Visiting Scholar Supervised by Dr. Heng Yang (Computational Robotics Lab)

May 2023 - Aug 2023

Developed certifiably correct camera trajectory estimation algorithm using semidefinite programming

MOBILE ROBOT | ROBOTICS INSTITUTE, UNIVERSITY OF MICHIGAN

Research Assistant Supervised by Dr. Maani Ghaffari (Curly Lab)

April 2022 - Dec 2022

Conducted research on state estimation using Invariant Extended Kalman Filter

REHABILITATION ROBOT | MECHANICAL ENGINEERING DEPT., COLUMBIA UNIVERSITY

Research Assistant Supervised by Dr. Sunil K Agrawal (ROAR Lab)

Dec 2021 - April 2022

• Contributed kinematics and dynamic libraries to wheelchair robot for active postural support using rospy. [website]

AV SIMULATION | CIVIL ENGINEERING AND ENGINEERING MECHANICS DEPT., COLUMBIA UNIVERSITY

Research Assistant Supervised by Dr. Sharon Di (DitecT Lab)

Sep 2021 - Dec 2021

Developed MmWave communication in TraCI framework for NS3 and SUMO Coupling in the COSMOS project

Software Engineer Internship | Huawei Technologies Co., Ltd

June 2021 - Aug 2021

• Contributed to code auto-generation frame on HUAWEI OptiX OSN1800 OTN communication platform

Lyapunov Stability and Finite-Time Control | CUHK Summer Research Internship

Research Assistant Supervised by Dr. Dongkun Han

May 2020 - Aug 2020

Designed Control Barrier Function-based multiagent coordination controller with Matlab simulation [video]

## EXTRACURRICULAR ACTIVITIES AND SERVICE

**REVIEWER | TRANSACTION ON MECHATRONICS (TMECH)** 

TEACHING ASSISTANT | ROB 530 MOBILE ROBOTICS, UNIVERSITY OF MICHIGAN

Instructor: Dr. Maani Ghaffari

Jan 2023 - Apr 2023

■ Developed homework and quizzes and organized office hour sessions in the graduate course with 158 students

GRADER, MATH 465 COMBINATORICS AND GRAPH

Oct 2022 - Dec 2022

AUTONOMOUS VEHICLES DEVELOPMENT | COLUMBIA UNIVERSITY ROBOTICS CLUB

Motion Planning Subteam Leader

Sep 2021 - Dec 2021

## HONORS AND AWARDS

LEUNG SIU KOI SCHOLARSHIP, CUHK Academic Merit	Dec 2021
ELITE STREAM SCHOLARSHIP, CUHK Academic Merit	Oct 2021
DEAN'S LIST, CUHK Top 10% in the department	Aug 2021, Aug 2020
CHUNG CHI COLLEGE CLASS SCHOLARSHIP, CUHK Best student in the class of a department	Nov 2020
TALENT DEVELOPMENT SCHOLARSHIP, HONG KONG GOVERNMENT EDUCATION BUREAU	May 2020
NATIONAL CREATIVE COMPOSITION COMPETITION Grand Prize (10 awards in total, National level)	Aug 2018

## **SKILLS**

- Programming Tool: C/C++, Python, MATLAB
- Robotics Tool: ROS, CUDA, NVIDIA Issac Gym, PyBullet
- Optimization Tool: MOSEK, Gurobi