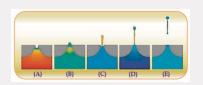




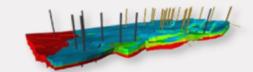
Introduction

- What is control?
- Why do we need control?
- How does control essentially work?
- How are control systems implemented?
- Control Objectives









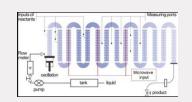


Control is Everywhere

Intelligent Decision Making



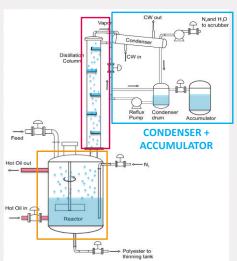








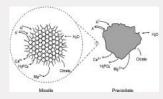
Specialty chemicals



Reactive Distilllation Column

Quality Control

Milk acidification



pH control

Hotel Groningen



Energy reduction in buildings

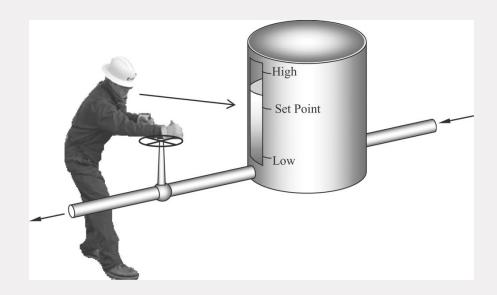


Fermentation Process

Optimal productivity



Example 1: A primitive 'level control' system (1)



Control objective : Keep the level at the desired level

(1) Kravaris & Kookos

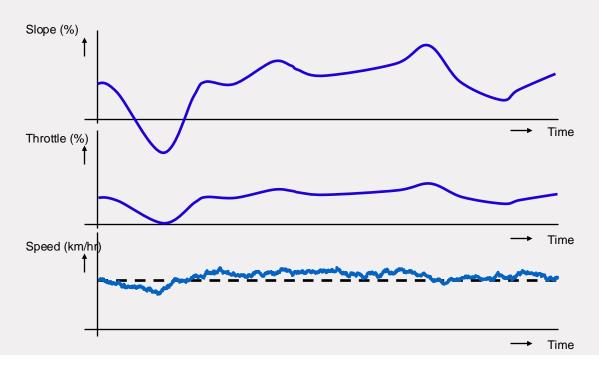


Example 2: Cruise control system in a car (Volvo's Adaptive Cruise Control)





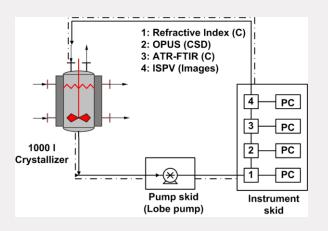
Example 2: Cruise control system in a car





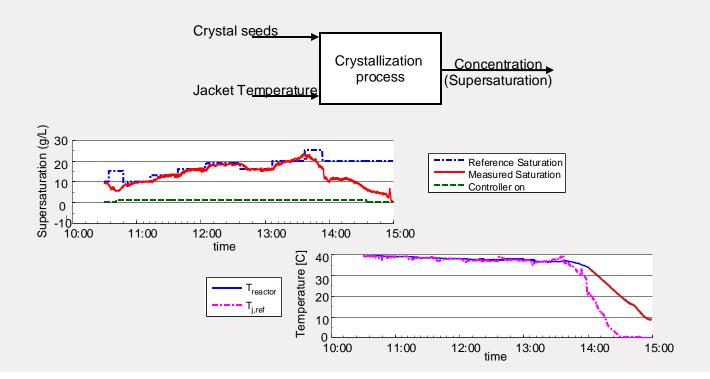
Control of an industrial scale batch crystallization process *)



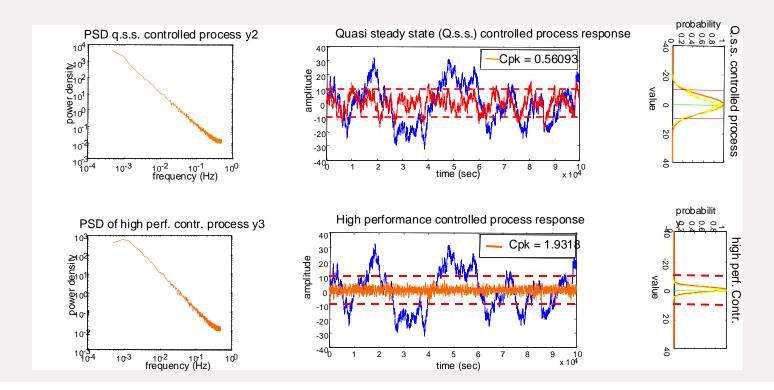


*) Courtesy of former MSD Apeldoorn











By nature every process, also any chemical process is dynamic, i.e. ever changing operating conditions:

- Composition of processed materials
- •Temperature
- Pressure
- •residence time



Control systems enable us to keep critical process variables within permitted operating conditions

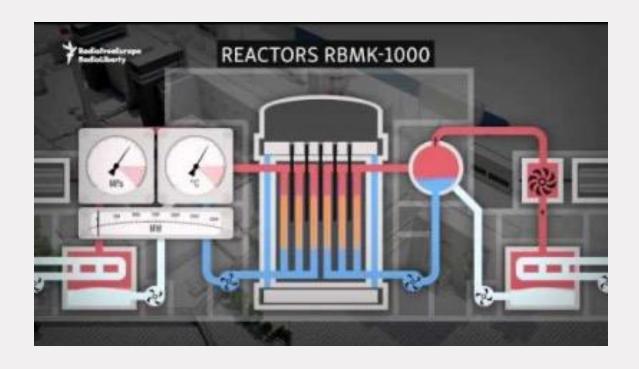
Example 1: Polymer reactor

- Reaction initiation requires heat
- Once initiated the reaction starts producing sufficient heat to initiate new reactions → runaway, unless the system is properly cooled
- Polymer properties are strongly influenced by time-temperature history of the polymer particles

Example 2: Cracker

- Cracking conversion and selectivity are strongly temperature dependent
- Large energy demand to perform cracking of heavy components







Ideal process operation involves making the process insensitive for disturbances by compensation. It requires tight control of applied operating conditions.

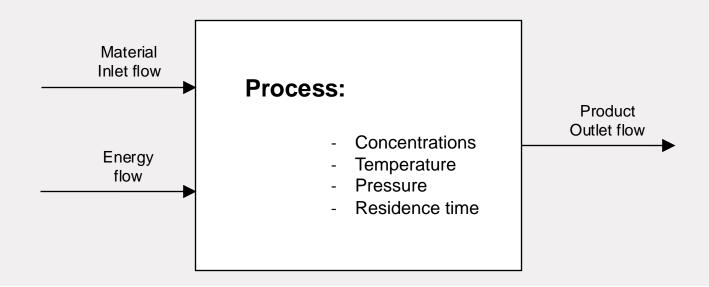
Compensation of disturbances (e.g. chemical reaction)

- Feed compositions
- Pressure
- Temperature
- Residence time

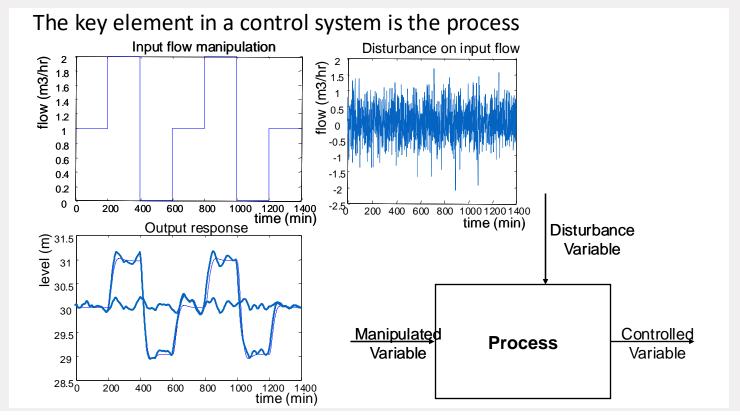
Drive the process to desired conditions

- Avoid dangerous operating conditions
- Follow preferred path for optimum production

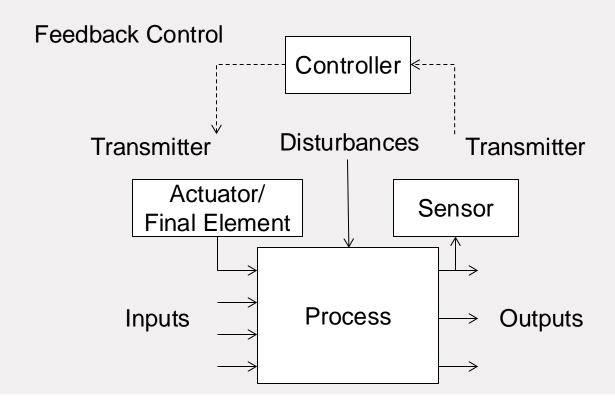




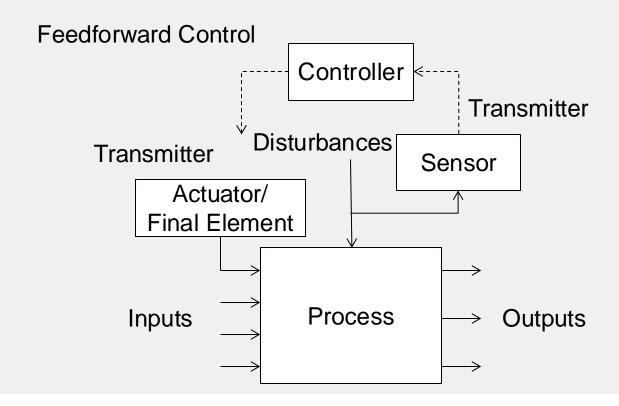




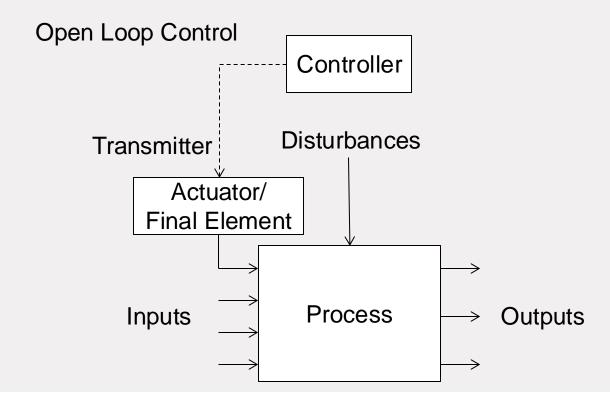














Process Variables:

INPUTS:

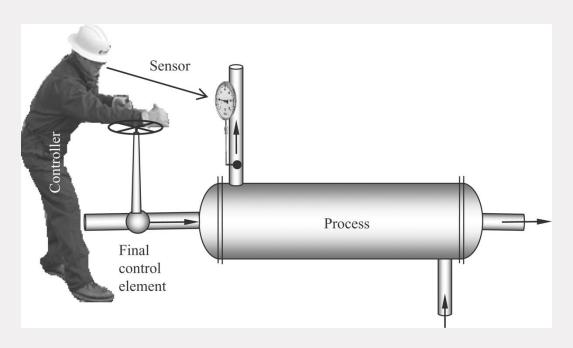
- Variables, which independently stimulate the system and can induce change in the internal conditions of the process
- Manipulated Variables
- Disturbances

OUTPUTS (MEASURED VARIABLES):

Variables from which we can obtain information about the internal state of the process.
 The variables selected as output variables in general are directly relevant for process operation or are (related to) critical properties of products or intermediates



Process variables of a cooling system in a heat exchanger.

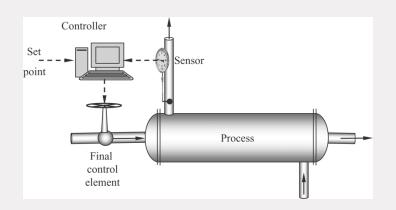


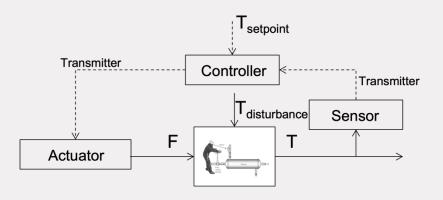
Input Variables: F_{seawater}

Output Variable: T_{out}

Disturbance Variable: ?

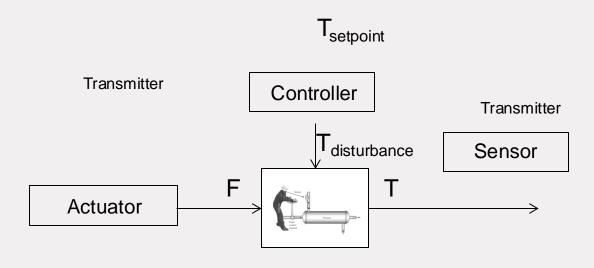








Feedforward Control of a Cooling system of a Heat Exchanger?





How are control systems implemented?

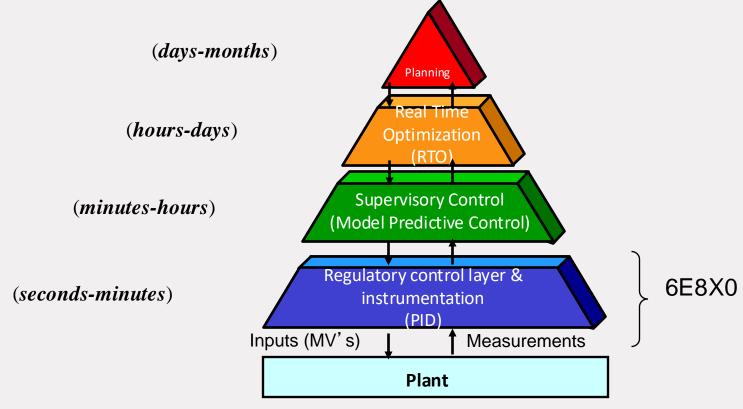
Control system evolution

•	<1945	Only manual operator control
•	1945 – 1960	Pneumatic analog PID control
•	1960 – 1970	Analog electronic PID control systems
•	1970 – 1980	Digital PID control systems
•	1980 – today	Distributed digital control systems
•	1985 – today	Supervisory multivariable optimizing control
		(Model Predictive Control)
•	1990 – today	Steady state model based plant wide
		optimization
•	Future	Dynamic/flexible model based plant wide

optimization



Process Control Hierarchy



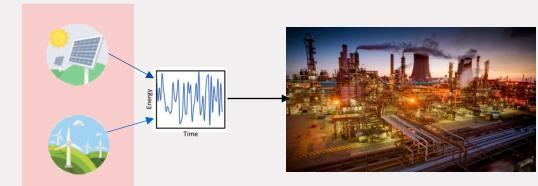


Future is Promising

Electrification of the Process Industry



Smart Grid



Renewable energy

Production +Utilities

Transient Plant Operation



Coming lectures

- Topic 2: Introduction to frequency domain and Laplace transformation
- Topic 3: Dynamic Behavior of Linear Systems
- Topic 4: Frequency Response Analysis and Bode plots
- Topic 5: Mathematical Description of Chemical Systems
- Topic 6: Nonlinear ODE's, Linearity, Linearization Feedback, Stability, Root Locus
- Topic 7: Feedback Controller Design and Bode stability
- Topic 8: Advanced (Enhanced)Process Control

