0. Import Dependencies

```
In [1]:
```

```
from __future__ import print_function
import torch
import torch.nn as nn
import torch.nn.functional as F
import torch.optim as optim
from torchvision import datasets, transforms
import matplotlib.pyplot as plt

import pandas as pd
import numpy as np
import scipy
import matplotlib.pyplot as plt

import torchvision.models as models
from ptflops import get_model_complexity_info
```

1. MNIST classification

main references:

```
https://juejin.im/entry/5a6463a86fb9a01ca5609228
https://github.com/Sylar257/My-data-science-tool-
kit/blob/458a96239a11145377710b90b455e8a81a365e7e/145_PyTorch_Tricks.ipynb
https://github.com/sovrasov/flops-counter.pytorch
```

e) Download file YourEmail_in.csv from the course drive. File contains 5x5 array of integers X. Manualy compute valid convolution

of w and X and submit output in file named YourEmail_out.csv (note the difference between convolution and cross-correlation, see https://en.wikipedia.org/wiki/Convolution).

In [2]:

```
csv1=pd.read_csv('XZHANG6@TCD.IE_in.csv')
csv1.head(5)
```

Out[2]:

```
    214
    54
    89
    143
    169

    0
    4
    38
    72
    87
    74

    1
    66
    90
    88
    104
    242

    2
    103
    210
    51
    141
    145

    3
    76
    179
    19
    211
    80
```

In [3]:

```
In [4]:
```

```
weights_data1=weights_data[::-1]
print(weights_data1)
```

```
[[-1, 0, -1], [0, 0, 0], [1, 0, 1]]
```

In [5]:

```
def compute conv(fm, kernel):
    h, w=fm.shape
   k, k=kernel.shape
   r=int(k/2)
   #define the map after no padding
   padding fm=np.zeros([h,w],np.int)
    #Remain the calculating output
    rs=np.zeros([h-2,w-2],np.float32)
    #Assign the input result to the specified area, that is, the remaining area except 4 boundarie
   padding_fm[0:h,0:w]=fm
    #Traversing the area centered on each point
    for i in range (1, h-1):
        for j in range(1,w-1):
            #Take out the k*k area centered on the current point
            roi=padding fm[i-r:i+r+1,j-r:j+r+1]
            \#Calculate the convolution of the current point, multiply after k*k points
            rs[i-1][j-1]=np.sum(roi*kernel)
    return rs
```

In [6]:

```
def my_conv2d(input,weights):
    #shape=[h,w]
    h,w=input.shape
    #shape=[k,k]
    k,k=weights.shape
    outputs=np.zeros([h-2,w-2],np.int)
    f_map=input
    w=weights
    rs =compute_conv(f_map,w)
    outputs=outputs+rs

return outputs
```

In [7]:

[-59. 196. -231.]]

- f) Download file YourEmail_network.csv from the course drive. File contains network definiton in the following format:
 - i) Convolution, N, K convolution layer with N feature maps and KxK filters
 - ii) Maxpool, K max pooling layer KxK pooling window
 - iii) Fully-connected, N fully connected layer with N neurons

All convolutions use same padding that preserves input feature size. All convolutional and fully-connected layers use bias. The network is applied on 32x32 RGB images (3 input channels). Calculate the number of parameters and the number of FLOPS of this network and submit them in YourEmail params.csv each of the 2 values in separate row (number of parameters in the first row).

In [8]:

```
csv2=pd.read_csv('XZHANG6@TCD.IE_network.csv')
csv2.head(10)
```

Out[8]:

	convolution	24	5
0	convolution	60	3.0
1	maxpool	2	NaN
2	convolution	72	3.0
3	maxpool	4	NaN
4	fully-connected	160	NaN
5	fully-connected	10	NaN

In [9]:

```
class CNN4 (nn.Module):
   def init (self):
       super(CNN4, self).__init__()
       self.conv1 = nn.Conv2d(in channels=3, out channels=24,
                               kernel_size=5, stride=1, padding=2)
       self.conv2 = nn.Conv2d(in_channels=24, out_channels=60,
                               kernel size=3, stride=1, padding=1)
       self.pool1 = nn.MaxPool2d(2)
       self.conv3 = nn.Conv2d(in channels=60, out channels=72,
                               kernel_size=3, stride=1, padding=1)
       self.pool2 = nn.MaxPool2d(4)
       self.fc1 = nn.Linear(in features=1152, out features=160)
       self.fc2 = nn.Linear(in_features=160, out_features=10)
       nn.init.kaiming normal (self.conv1.weight, nonlinearity='relu')
       nn.init.kaiming_normal_(self.conv2.weight, nonlinearity='relu')
       nn.init.kaiming_normal_(self.conv3.weight, nonlinearity='relu')
       nn.init.kaiming normal (self.fcl.weight, nonlinearity='relu')
       nn.init.kaiming normal (self.fc2.weight, nonlinearity='linear')
   def forward(self, x):
       x = self.conv1(x)
       x = F.relu(x)
       x = self.conv2(x)
       x = F.relu(x)
       x = self.pool1(x)
       x = self.conv3(x)
       x = F.relu(x)
       x = self.pool2(x)
       x = x.view(-1, 1152)
       x = self.fcl(x)
       x = F.relu(x)
       x = self.fc2(x)
       return F.log_softmax(x, dim=1)
```

In [10]:

```
use_cuda = torch.cuda.is_available()
device = torch.device("cuda" if use_cuda else "cpu")
model = CNN4().to(device)
flop,params=get_model_complexity_info(model, (3,32,32))
print(f'Params: {params}')
print(f'Flop: {flop}')
```

```
CNN4 (
 0.025 GMac, 100.000% MACs,
  (conv1): Conv2d(0.002 GMac, 7.343% MACs, 3, 24, kernel_size=(5, 5), stride=(1, 1), padding=(2, 2
))
  (conv2): Conv2d(0.013 GMac, 52.412% MACs, 24, 60, kernel size=(3, 3), stride=(1, 1), padding=(1,
1))
  (pool1): MaxPool2d(0.0 GMac, 0.242% MACs, kernel_size=2, stride=2, padding=0, dilation=1,
ceil mode=False)
  (conv3): Conv2d(0.01 GMac, 39.200% MACs, 60, 72, kernel_size=(3, 3), stride=(1, 1), padding=(1,
1))
  (pool2): MaxPool2d(0.0 GMac, 0.072% MACs, kernel size=4, stride=4, padding=0, dilation=1,
ceil mode=False)
  (fcl): Linear(0.0 GMac, 0.725% MACs, in features=1152, out features=160, bias=True)
  (fc2): Linear(0.0 GMac, 0.006% MACs, in features=160, out features=10, bias=True)
Params: 239.89 k
Flop: 0.03 GMac
In [11]:
final2=pd.DataFrame(data={
        'parameters':'239.89k','FLOPS':'0.03GMac',},index=[0])
final2.to_csv('XZHANG6@TCD.IE_params.csv',index=None)
```