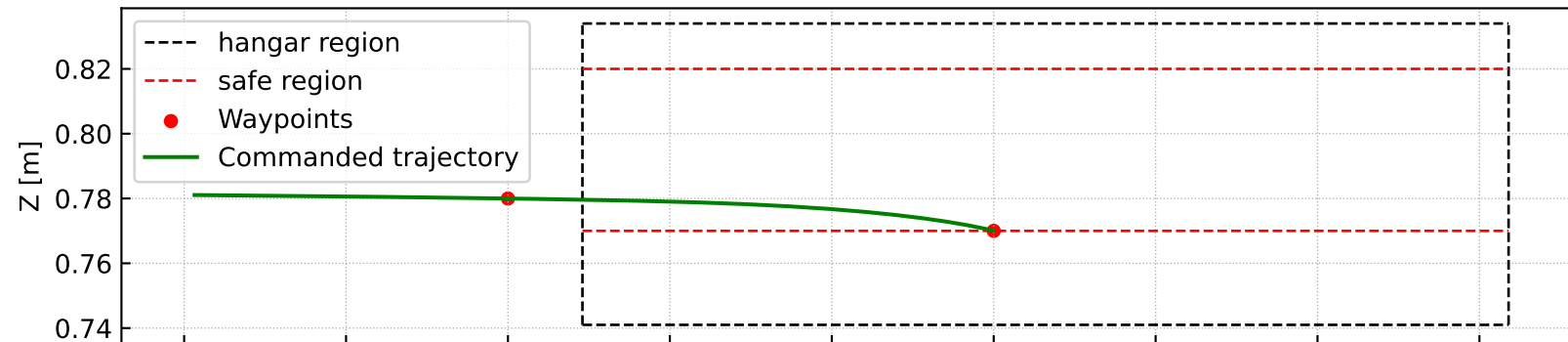


Baseline Trajectory



Optimized Trajectory

