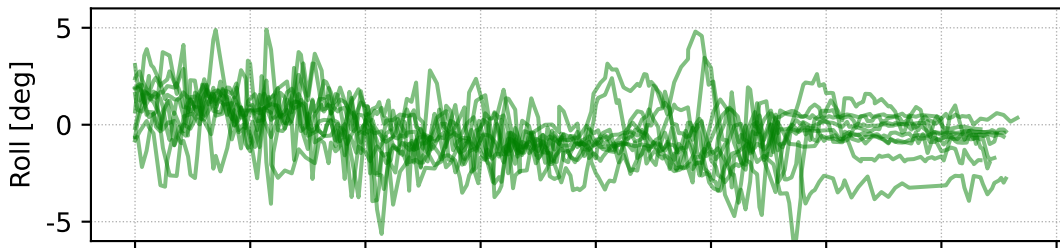


Actual trajectory

Roll (deg)



Roll (With compensation)

