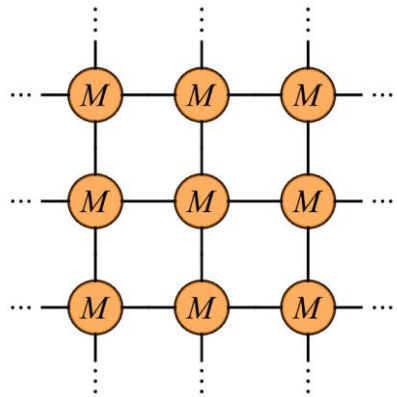


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# nonlocal MPO and SLM optimization

Xingyu Zhang  
2024.6.28

# AFIsing resident entropy



$$\begin{aligned}
 +[2,2,1,1] &= 1.0 \\
 +[1,1,2,2] &= 1.0 \\
 +[1,1,1,1] &= 1.0 \\
 +[1,2,1,1] &= 1.0 \\
 +[2,2,2,2] &= 1.0 \\
 +[2,1,2,2] &= 1.0
 \end{aligned}$$

Non-Hermitian and non-normal

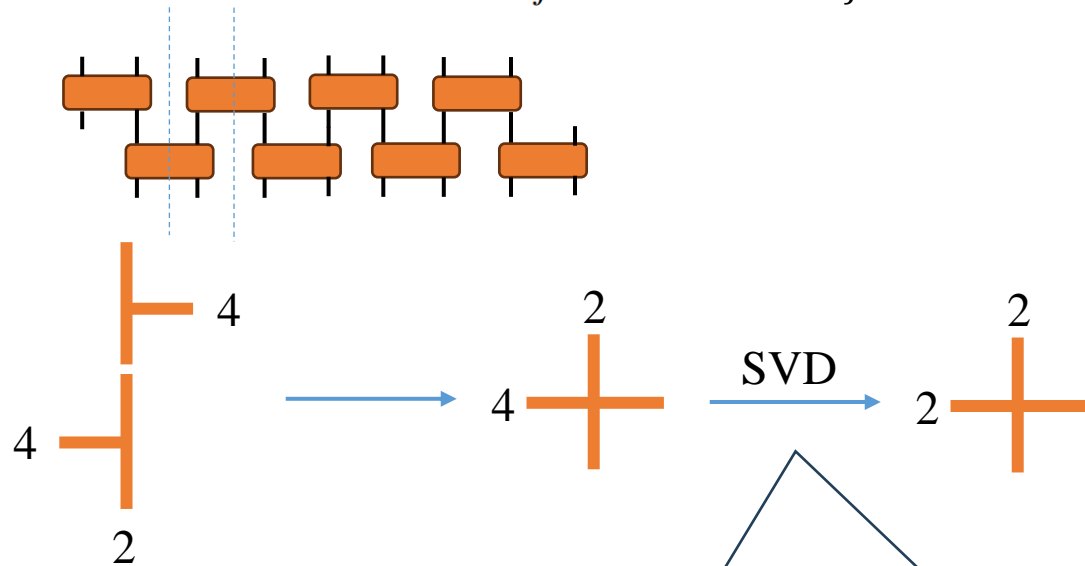
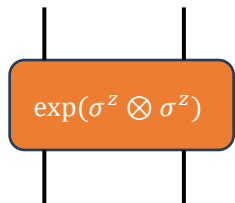
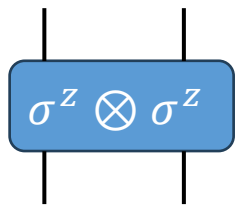
$$+ ' \leftarrow P + P^{-1}$$

$$\mathcal{P} = \exp(\tau Q) = \exp\left(-\tau \sum_j \sigma_j^z \sigma_{j+1}^z\right)$$

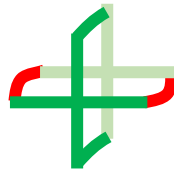
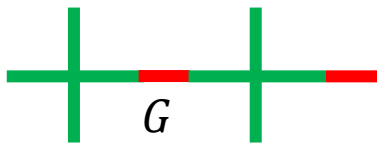
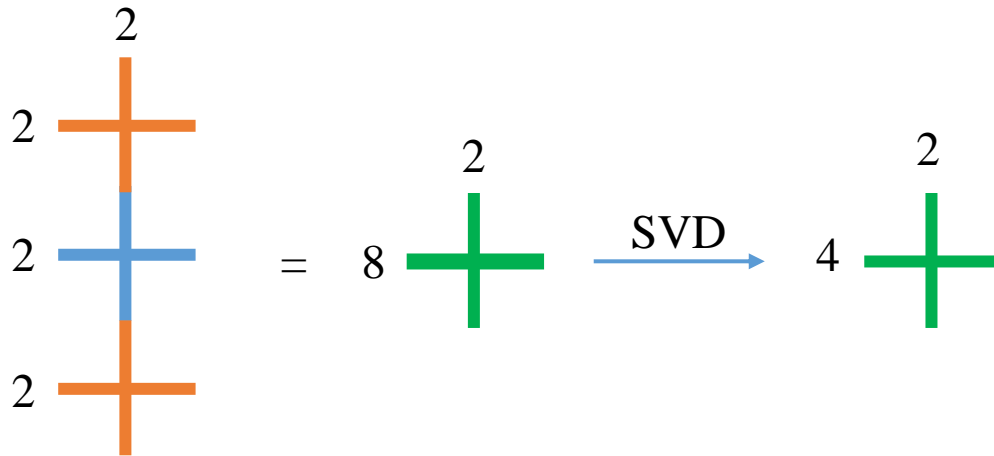
$$\begin{array}{c} 2 \\ \text{+} \\ 8 \end{array} = \begin{array}{c} 2 \\ \text{+} \\ 2 \\ \text{+} \\ 2 \end{array}$$

# vertical nonlocal gauge P

$$\mathcal{P} = \exp(\tau Q) = \exp(-\tau \sum_j \sigma_j^z \sigma_{j+1}^z) = \prod_j \exp(-\tau \sigma_j^z \sigma_{j+1}^z)$$

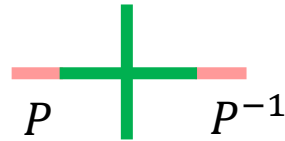


# Horizontal local gauge



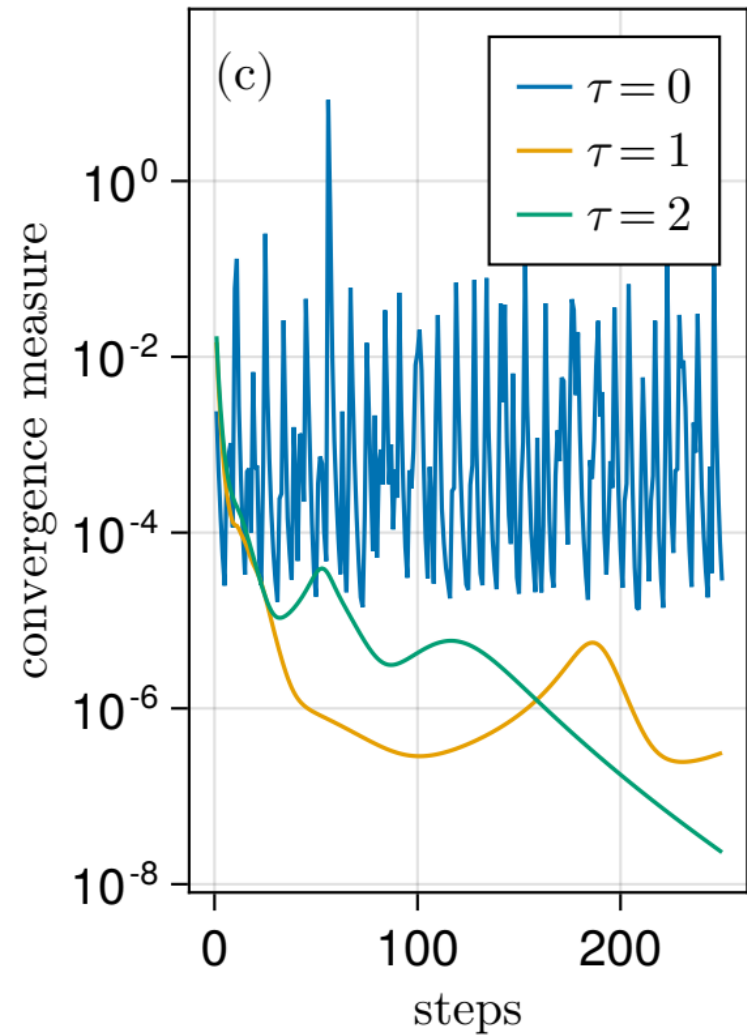
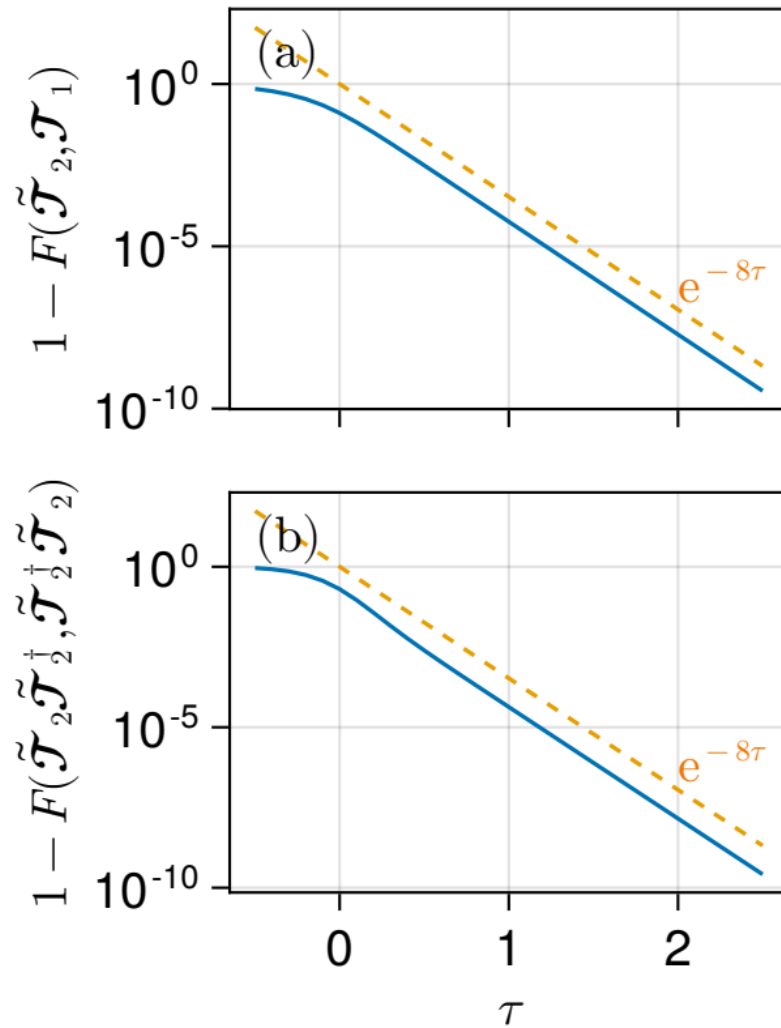
$$G = e^p = U\Lambda U' \quad P = \sqrt{\Lambda}U'$$

$$p \leftarrow p + p' \quad P^{-1} = U\sqrt{\Lambda^{-1}}$$

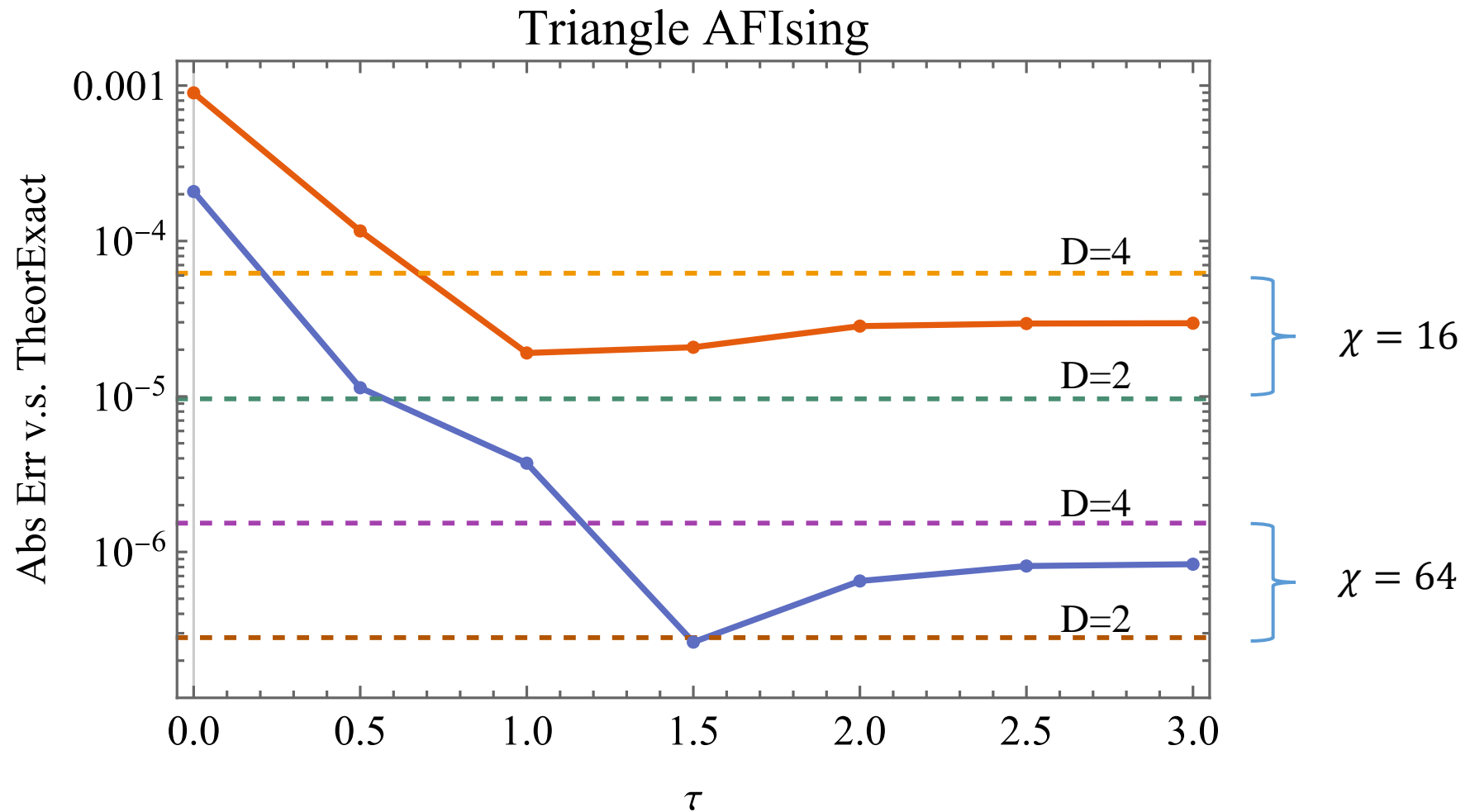


Precondition is important!

# normality



# Free energy

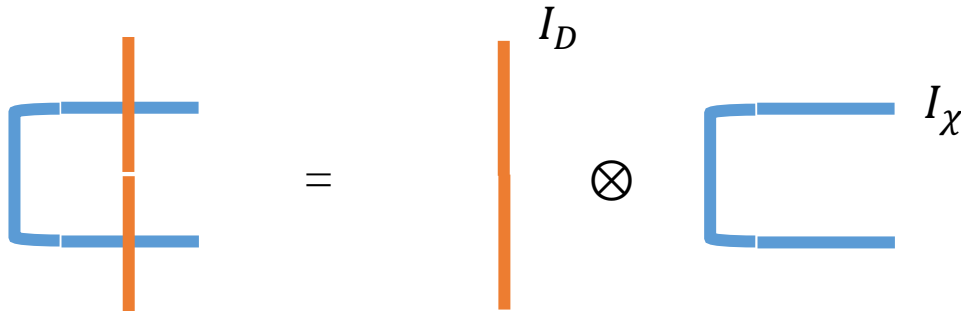


# More discuss

- Hard to generalize

- Qi Yang's ansatz

- 



The diagram shows an equation between two expressions. On the left is a blue square loop with a vertical orange line passing through its center. This is followed by an equals sign. On the right is a vertical orange line labeled  $I_D$  above it, followed by a tensor product symbol  $\otimes$ , and then another blue square loop labeled  $I_X$  above its right side.

- Good normality but wrong free energy
- Quasi-fixed point?

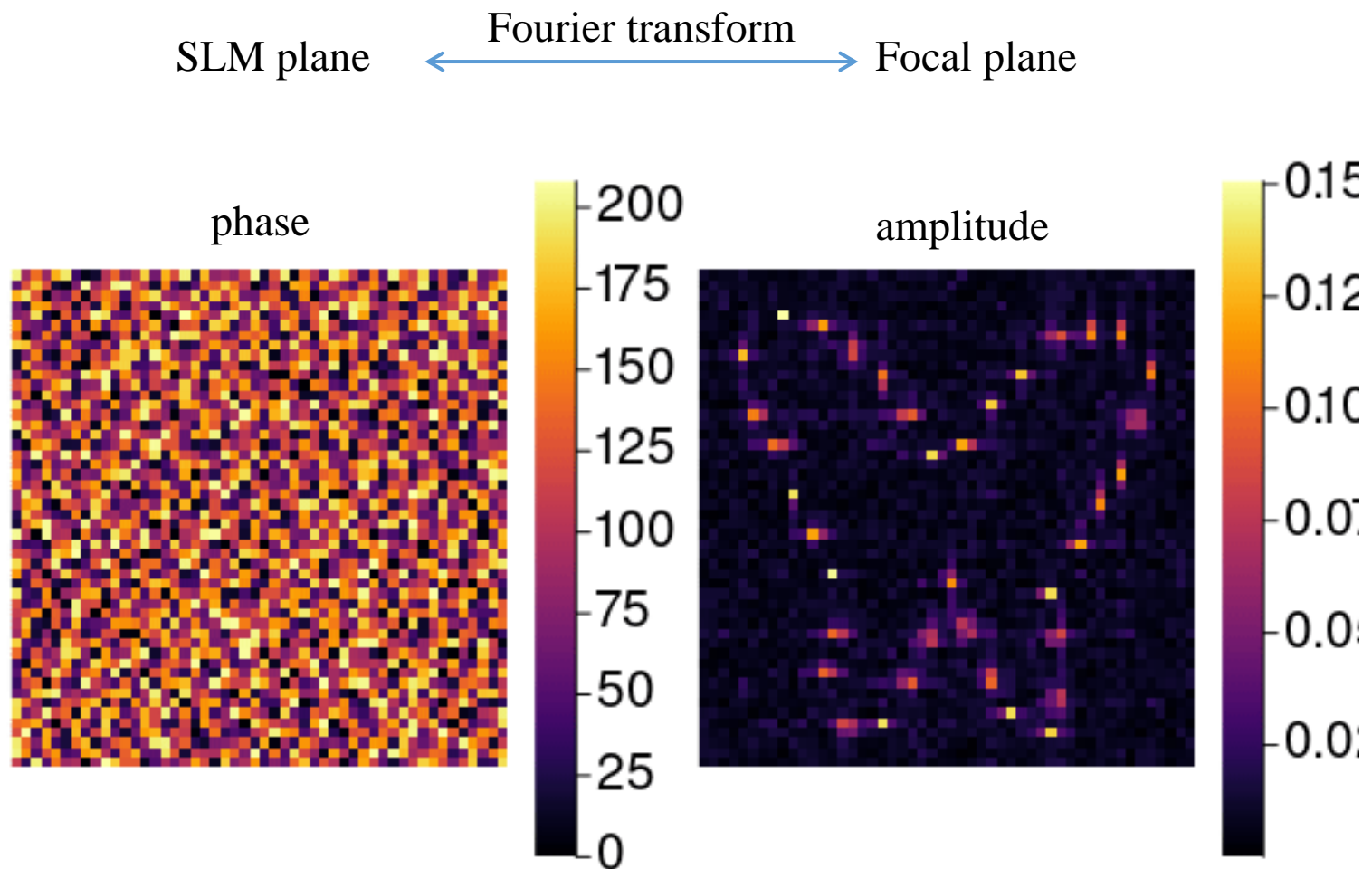
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# SLM flow



# Uniform optical focus arrays

- spatial light modulators (SLM)



# WGS algorithm

weighted-Gerchberg–Saxton

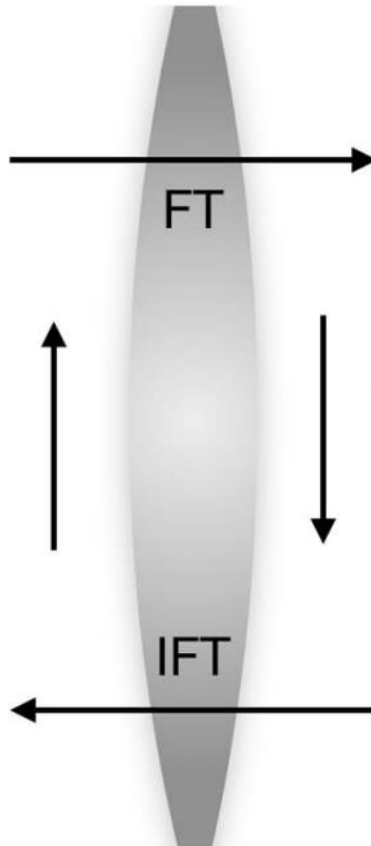
(a)

$$\sqrt{I(\mathbf{x})}, \phi_i(\mathbf{x})$$

$$i \leftarrow i + 1$$

$$A_{i+1}(\mathbf{x}), \phi_{i+1}(\mathbf{x})$$

[SLM plane]



$$B_i(\mathbf{u}), \psi_i(\mathbf{u})$$

$$g_i(\mathbf{u}_m) = \frac{\langle B_i(\mathbf{u}) \rangle_M}{B_i(\mathbf{u}_m)} g_{i-1}(\mathbf{u}_m)$$

If  $i \geq N, \psi_i(\mathbf{u}) = \psi_N(\mathbf{u})$

$$B'(\mathbf{u})$$

$$g_i(\mathbf{u})\mathcal{T}(\mathbf{u}), \psi_i(\mathbf{u})$$

[Focal plane]

Donggyu Kim, Opt. Lett. 44, 3178-3181 (2019)

How to get  $\frac{d\phi}{dt}$  from  $\frac{du}{dt}$ ?

implicit function theorem

# Continuous fourier transformation

$$F(u, v) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x, y) e^{-2\pi i(ux+vy)}$$

$\downarrow$   
*trap*  $N_u \times N_v$

≤

$\downarrow$   
*SLM*  $N_x \times N_y$

$$F_{uv} = \sum_y \left( \sum_x X_{ux} f_{xy} \right) Y_{vy}$$

$$F_j = \sum_y \left( \sum_x X_{jx} f_{xy} \right) Y_{jy}$$

$$f_{xy} = \sum_v \left( \sum_u X_{ux}^* F_{uv} \right) Y_{vy}^*$$

$$f_{xy} = \sum_j (X_{jx}^* F_j) Y_{jy}^*$$

$$X_{ux} = e^{-2\pi i u x}$$

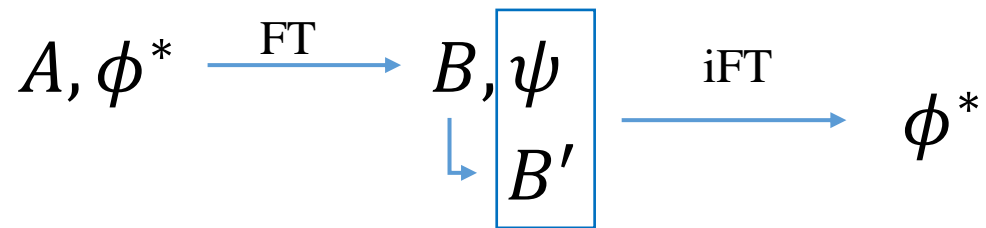
$$X_{jx} = e^{-2\pi i u_i x}$$

$$Y_{vy} = e^{-2\pi i v y}.$$


$$Y_{jy} = e^{-2\pi i v_i y},$$

# Fixed point

- $\phi^* = f(\phi^*, B', u)$



$$\frac{d\phi^*}{dt} = \frac{\partial f}{\partial \phi^*} \frac{d\phi^*}{dt} + \frac{\partial f}{\partial B'} \frac{dB'}{dt} + \frac{\partial f}{\partial u} \frac{du}{dt}$$


$$\left(1 - \frac{\partial f}{\partial \phi^*}\right) \frac{d\phi^*}{dt} = \frac{\partial f}{\partial B'} \frac{dB'}{dt} + \frac{\partial f}{\partial u} \frac{du}{dt}$$

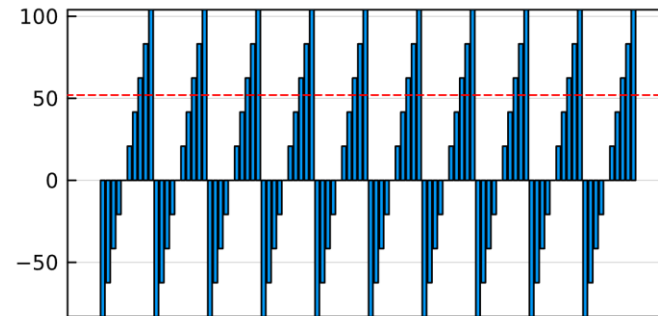
Forward AD + Linear solve

# Test: move one point (0.1)

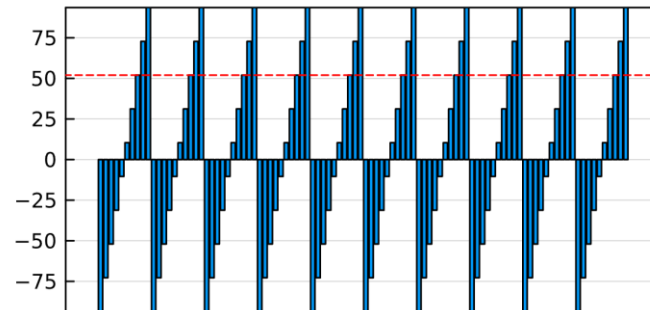
Up: Discrete



$\Delta\phi$

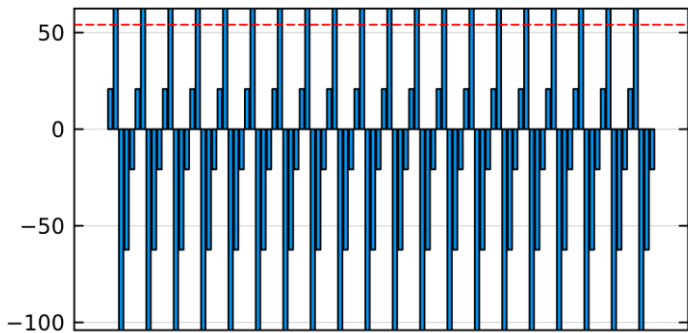
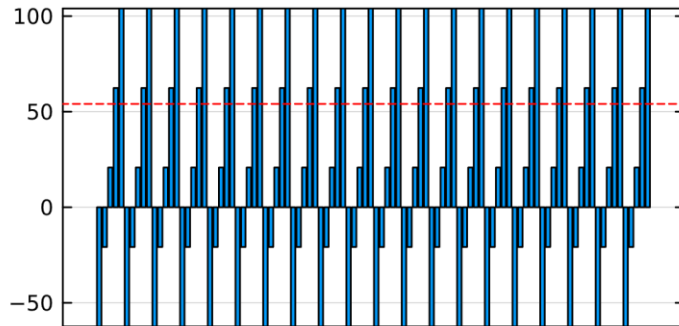


Down: Current flow

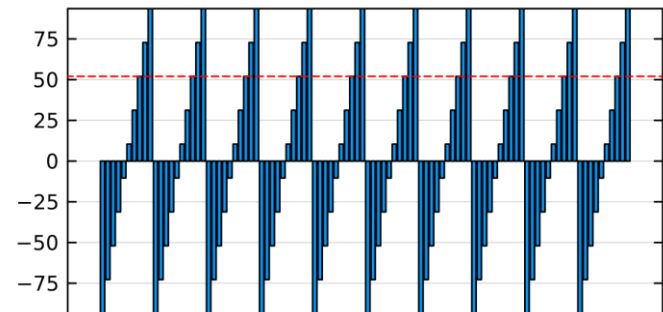


# Test: move one point (0.2)

Up: Discrete v.s. Down: Current flow

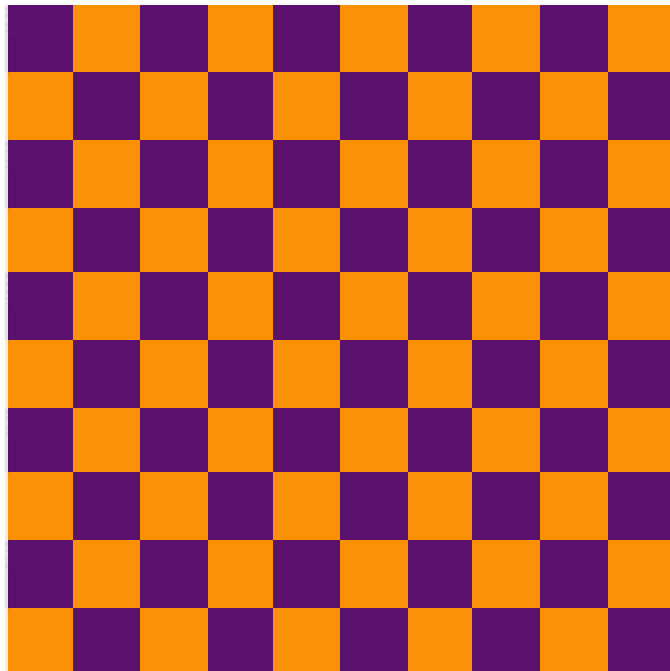


$\approx 2\times$

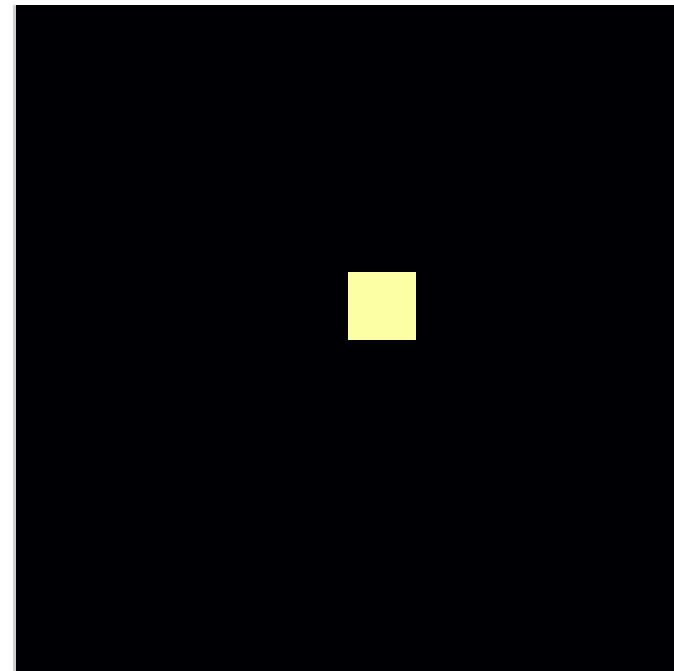


# Test: move one point (0.2)

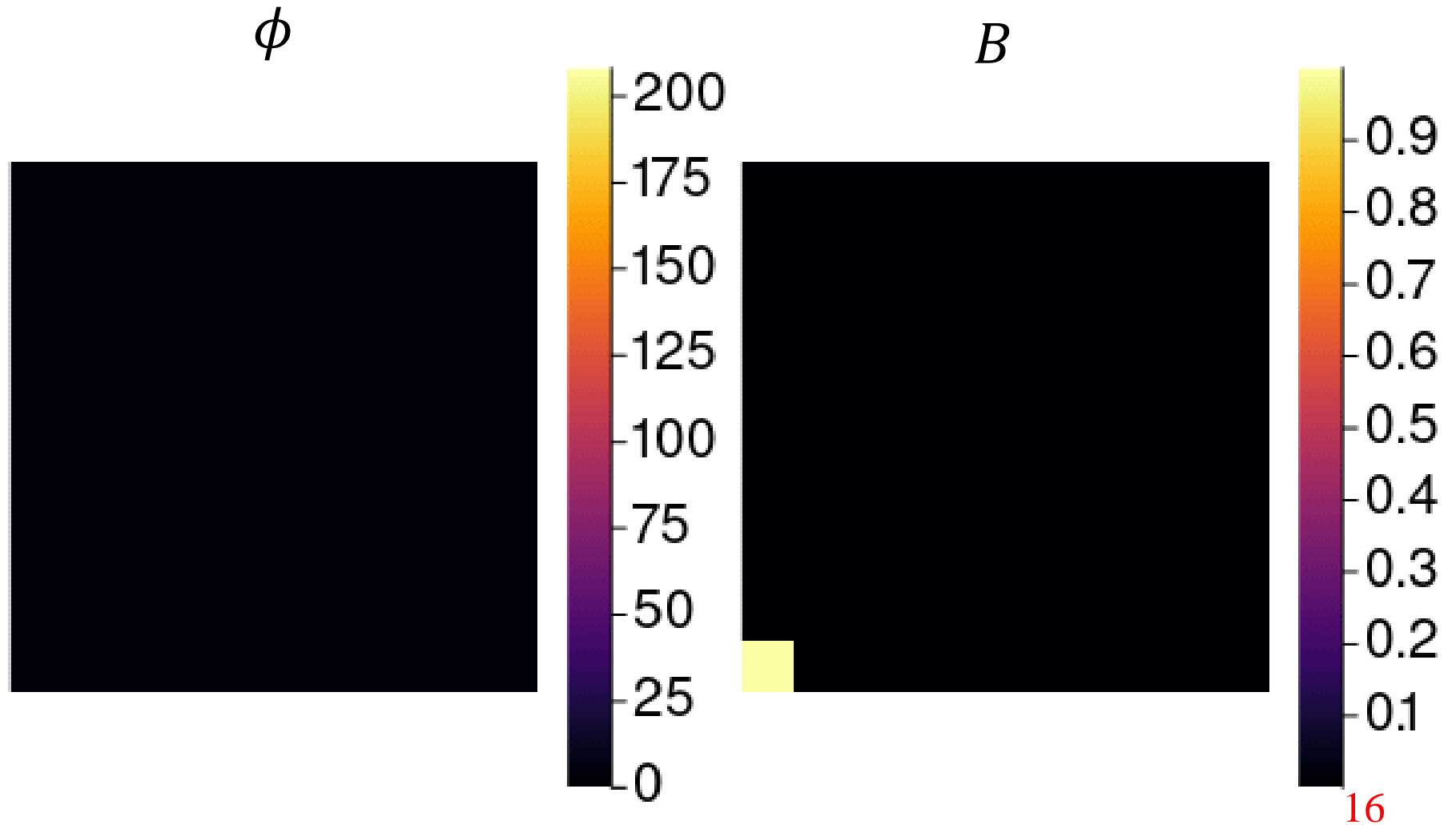
$\phi$



$B$



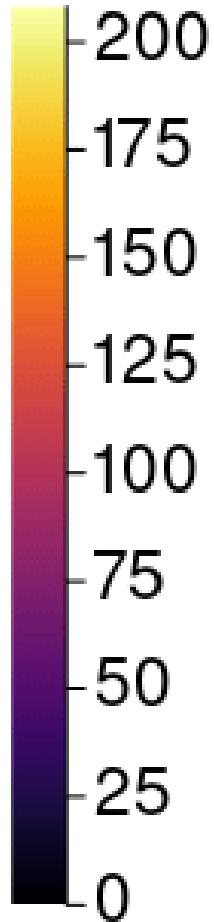
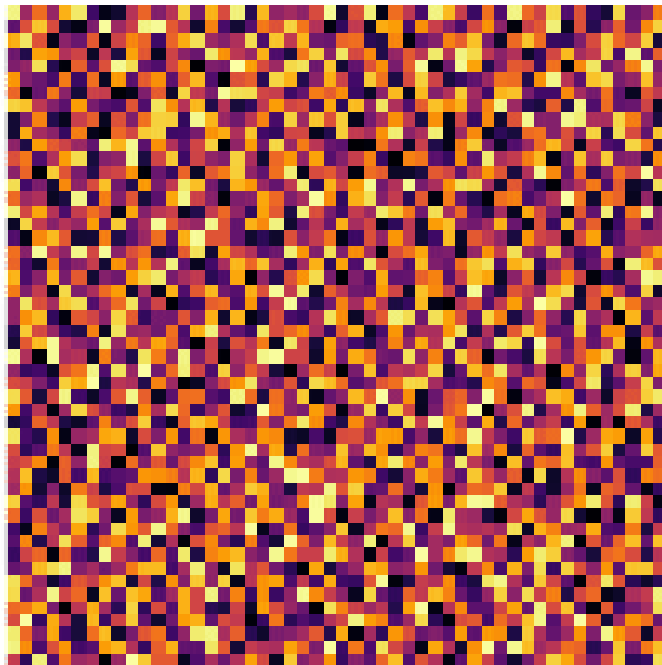
# Diagonally move



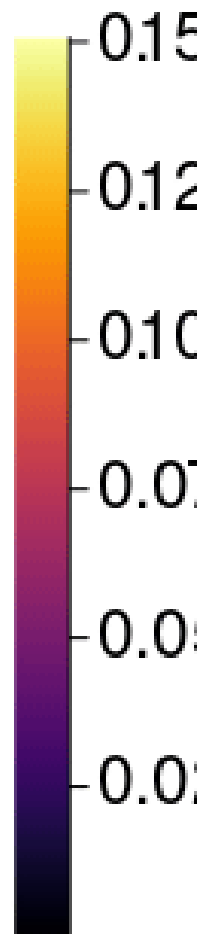
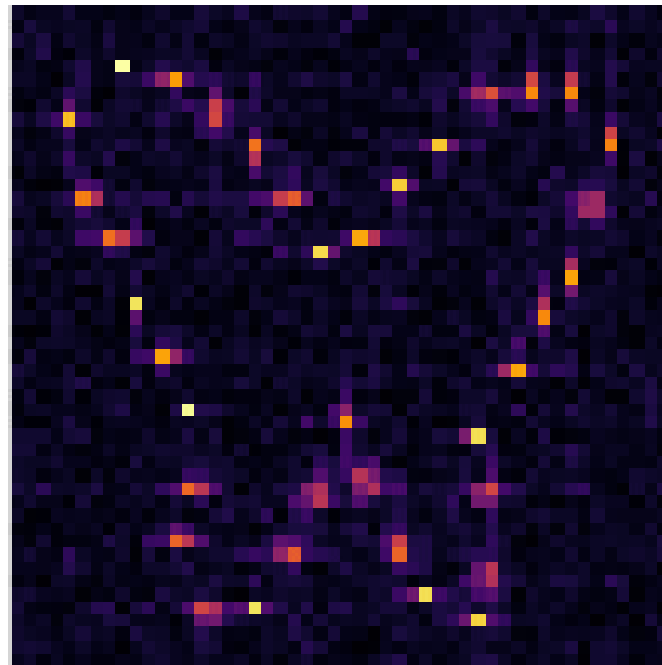


# butterfly

$\phi$

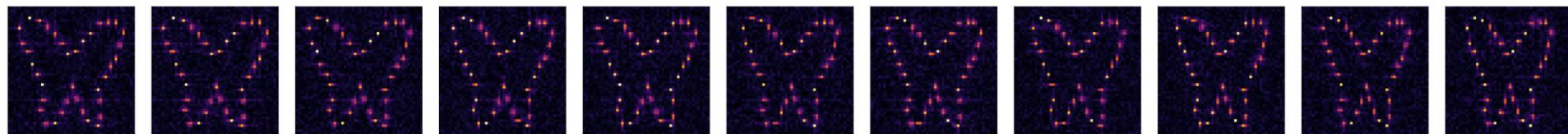
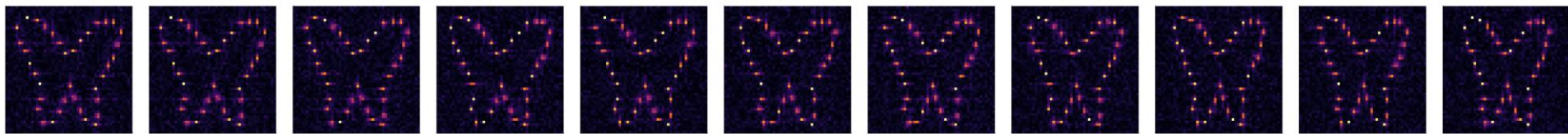


$B$

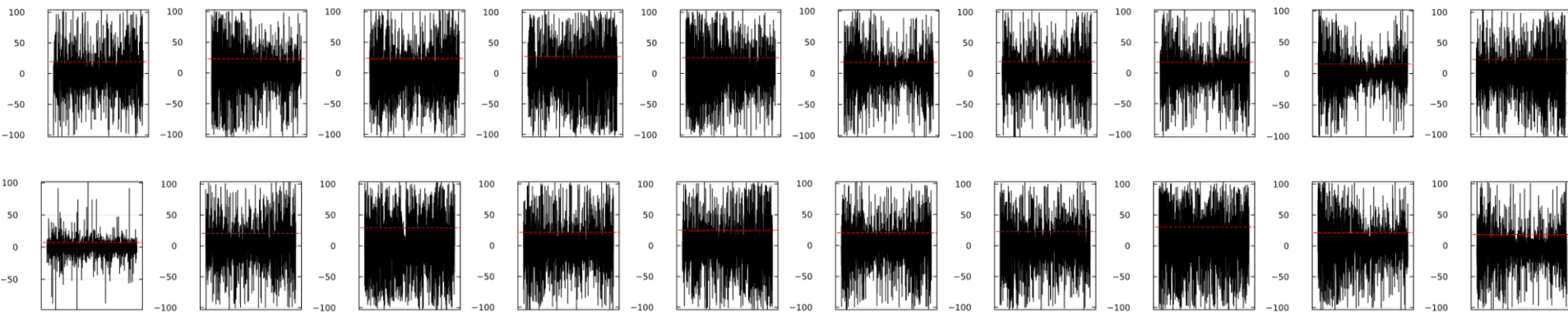


# results

Up: Discrete v.s. Down: Current flow

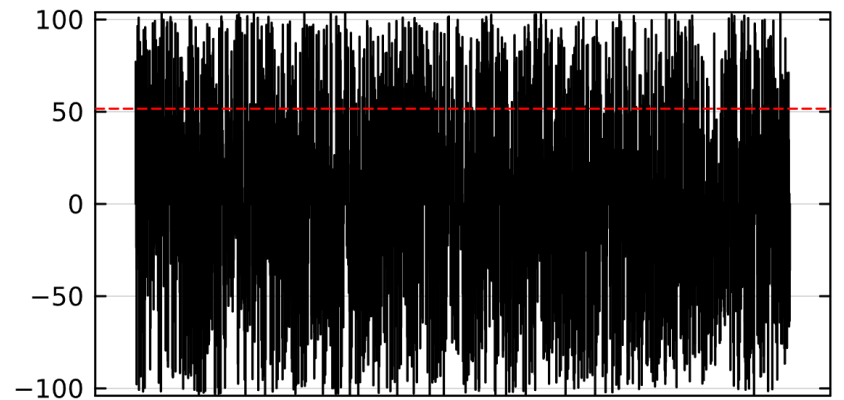
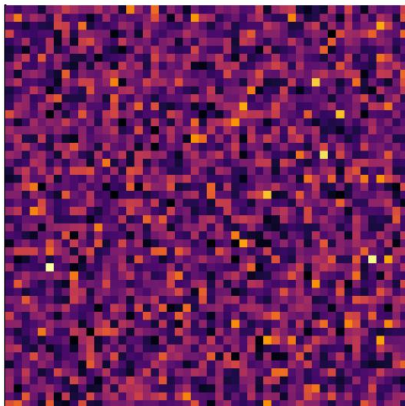
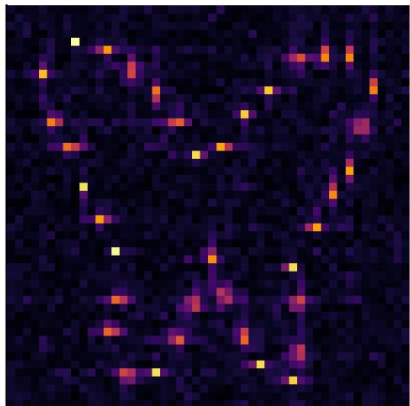
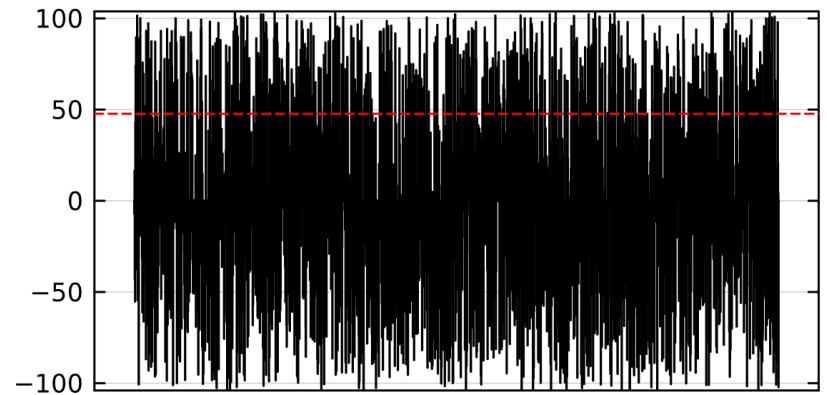
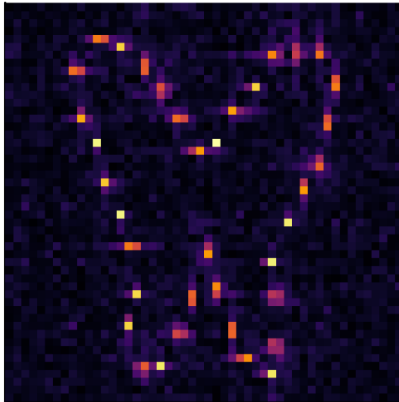
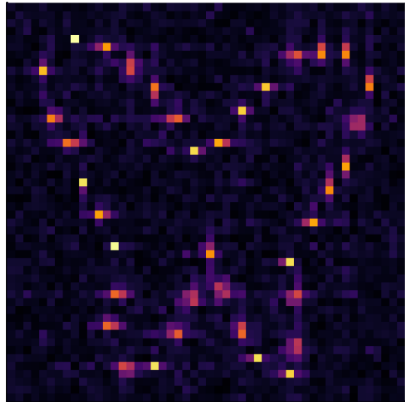


$\Delta\phi$



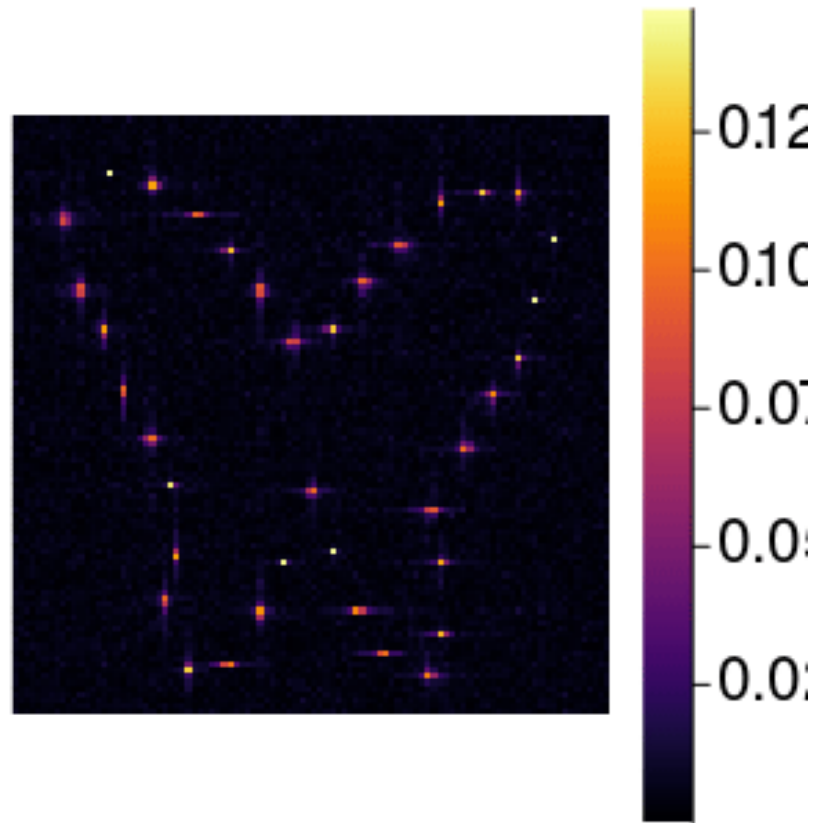
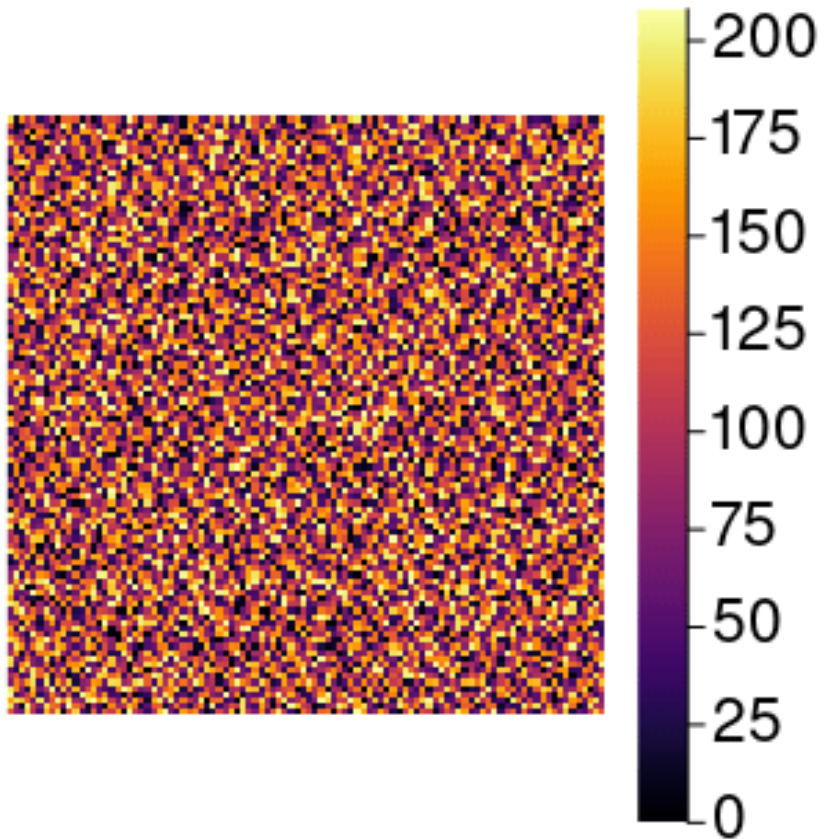
# butterfly

Up: Discrete v.s. Down: Current flow

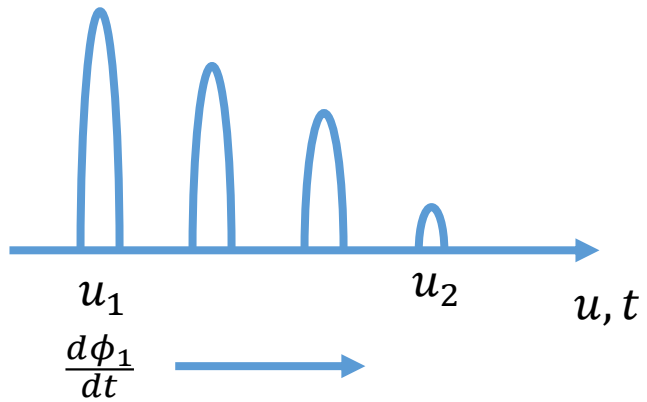


# Continuous flow

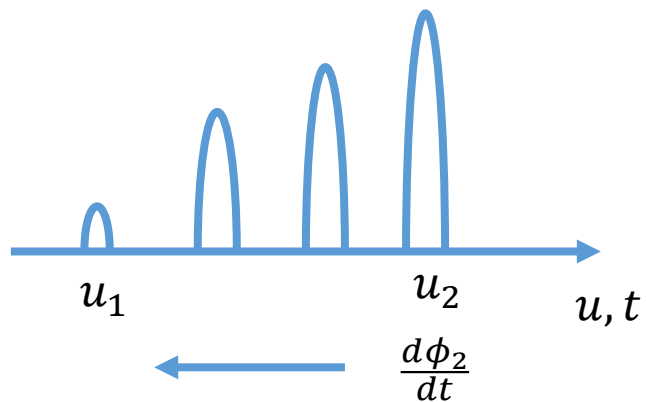
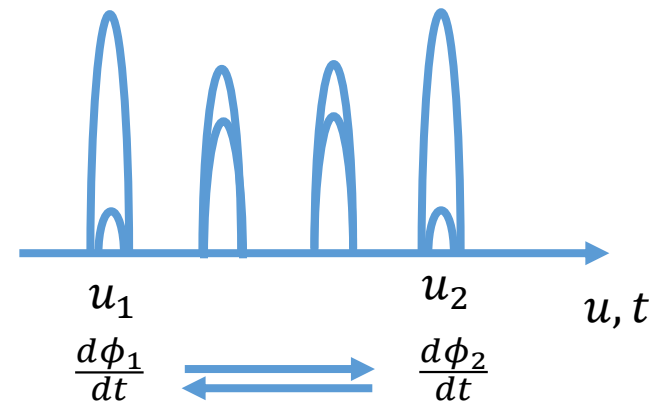
Gradually disappear



# Interpolation between two steps

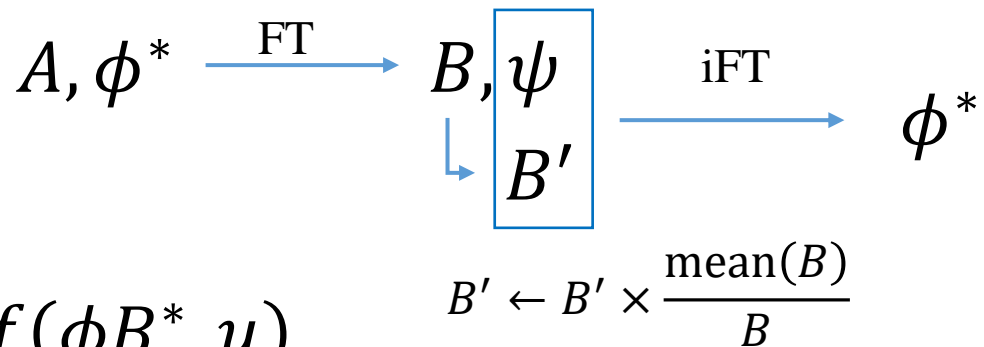


Combine?



# Ignore B!

- $\phi^*, B' = f(\phi^*, B', u)$



- $\phi B^* = f(\phi B^*, u)$

$$\frac{d\phi B^*}{dt} = \frac{\partial f}{\partial \phi B^*} \frac{d\phi B^*}{dt} + \frac{\partial f}{\partial u} \frac{du}{dt}$$

$\phi, B'$  need to include both configuration

$$\left(1 - \frac{\partial f}{\partial \phi B^*}\right) \frac{d\phi B^*}{dt} = \frac{\partial f}{\partial u} \frac{du}{dt}$$

# Discussion

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- There are only disappears without moving for multi-points for short time
- Convergence of the linear solve
- Estimate the moving quality

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Thank you for listening!