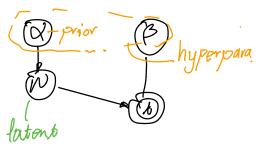
Q1.1.

Difference. SBLR BLR

latent variable, of W or, B deterministic para a,b,c,d W prion a,B,

the Bayesian network of the model in the home work



41.2. the Bayesian network of SBLR.

de terministic hyperparameter B

 $P(\overline{\mathcal{X}}, \overline{\mathcal{W}}, \overline{\mathcal{Q}}, \beta) = \mathcal{N}(\overline{\mathcal{X}}; \underline{\mathcal{T}} \overline{\mathcal{W}}, \beta^{-1} 1) \mathcal{N}(\overline{\mathcal{W}}; 0, diag(\overline{\mathcal{Q}})^{-1}).$  $(\prod_{i=1}^{n}G(\alpha_{i}; a,b)G(\beta_{i}; c,d)$  $= \left(\prod_{i=1}^{n} \mathcal{N}(t_i) \vec{w}^{\intercal} \vec{\sigma}(x_i), \beta^{-1}\right) \left(\prod_{i=1}^{n} \mathcal{N}(w_i), 0, \alpha_i^{-1}\right) \left(\prod_{i=1}^{n} \mathcal{N}(w_i), \alpha_i^{-1}\right) \left(\prod_{i$ 

$$A = 1. \quad Q^{*}(\vec{w}) = N(\vec{w}) \vec{\mu}, \vec{\Sigma}_{N}$$

$$= E_{q(\vec{x})}q_{(\vec{p})} \left[ \ln P(\vec{k}, \vec{w}, \vec{x}, \vec{p}) \right] + coh$$

$$= E_{q(\vec{x})}q_{(\vec{p})} \left[ \sum_{i=1}^{N} \ln N(d_{i}; \vec{w}^{T}\vec{b}(x_{i}), \vec{p}^{T}) + \ln N(\vec{w}; \vec{p}, d_{i}) \right] + coh$$

$$= E_{q(\vec{x})}q_{(\vec{p})} \left[ \sum_{i=1}^{N} (-\frac{p}{2}) \left( d_{i} - \vec{w}^{T}\vec{b}(x_{i}) \right)^{2} - \frac{1}{2} \operatorname{diag}(\vec{x}) \vec{w}^{2} \right] + coh$$

$$= -\frac{1}{2} \left( \sum_{i=1}^{N} E_{q(\vec{p})} \beta \left[ d_{i}^{2} - 2\vec{w}^{T}\vec{b}(x_{i}) d_{i} + \vec{w}^{T}\vec{b}(x_{i}) \vec{b}^{T}(x_{i}) \vec{w} \right] + E_{q(\vec{x})} \left[ \operatorname{diag}(\vec{x}) \vec{w}^{2} \right] + coh$$

$$= -\frac{1}{2} \left( E_{q(\vec{p})} \left[ \beta \right] \sum_{i=1}^{N} \left( -2\vec{w}^{T}\vec{b}(x_{i}) \vec{w} \right) + \left[ E_{q(\vec{p})} \beta \right] \sum_{i=1}^{N} \vec{b}^{T}(x_{i}) \vec{v} \right] + E_{q(\vec{x})} \left[ \operatorname{diag}(\vec{x}) \right] \vec{k} \right]$$

$$= -\frac{1}{2} \left( E_{q(\vec{p})} \left[ \beta \right] \sum_{i=1}^{N} \left( -2d_{i} \vec{b}^{T}(x_{i}) \vec{w} \right) + \left[ E_{q(\vec{p})} \beta \right] \sum_{i=1}^{N} \vec{b}^{T}(x_{i}) \vec{v} \right] + E_{q(\vec{p})} \left[ \operatorname{diag}(\vec{x}) \right] \vec{k} \right]$$

$$= -\frac{1}{2} \left( E_{q(\vec{p})} \left[ \beta \right] \sum_{i=1}^{N} \left( -2d_{i} \vec{b}^{T}(x_{i}) \vec{w} \right) + \left[ E_{q(\vec{p})} \beta \right] \sum_{i=1}^{N} \vec{b}^{T}(x_{i}) \right] + E_{q(\vec{p})} \left[ \operatorname{diag}(\vec{x}) \right] \vec{k} \right]$$

$$= -\frac{1}{2} \left( E_{q(\vec{p})} \left[ \beta \right] \sum_{i=1}^{N} \left( -2d_{i} \vec{b}^{T}(x_{i}) \vec{v} \right) + \left[ E_{q(\vec{p})} \beta \right] \left[ \operatorname{diag}(\vec{x}) \right] \right)$$

$$= -\frac{1}{2} \left( E_{q(\vec{p})} \left[ \beta \right] \sum_{i=1}^{N} \left( -2d_{i} \vec{b}^{T}(x_{i}) \vec{v} \right) + \left[ E_{q(\vec{p})} \beta \right] \left[ \operatorname{diag}(\vec{x}) \right] \right)$$

$$= -\frac{1}{2} \left( E_{q(\vec{p})} \left[ \beta \right] \sum_{i=1}^{N} \left( -2d_{i} \vec{b}^{T}(x_{i}) \vec{v} \right) + \left[ E_{q(\vec{p})} \beta \right] \left[ \operatorname{diag}(\vec{x}) \right] \right)$$

$$= -\frac{1}{2} \left( E_{q(\vec{p})} \left[ \beta \right] \sum_{i=1}^{N} \left[ -2d_{i} \vec{b}^{T}(x_{i}) \vec{v} \right] + \left[ E_{q(\vec{p})} \beta \right] \left[ \operatorname{diag}(\vec{x}) \vec{v} \right] \right)$$

$$= -\frac{1}{2} \left( E_{q(\vec{p})} \left[ \beta \right] \sum_{i=1}^{N} \left[ -2d_{i} \vec{b}^{T}(x_{i}) \vec{v} \right] + \left[ E_{q(\vec{p})} \beta \right] \left[ \operatorname{diag}(\vec{x}) \vec{v} \right] \right)$$

$$= -\frac{1}{2} \left( E_{q(\vec{p})} \left[ \beta \right] \sum_{i=1}^{N} \left[ -2d_{i} \vec{b}^{T}(x_{i}) \vec{v} \right] + \left[ E_{q(\vec{p})} \beta \right] \left[ \operatorname{diag}(\vec{x}) \vec{v} \right] \right)$$

$$= -\frac{1}{2} \left( E_{q(\vec{p})} \left[ \beta \right] \sum_{i=1}^{N} \left[ -2d_{i} \vec{b}^{T}(x_{i}) \vec{v} \right] + \left[ E_{q(\vec{p})} \beta \right] \left[ E_{q(\vec{p})} \beta \right] \right]$$

$$= -\frac{1}{2} \left( E_{q(\vec{p})} \left[ E_{q(\vec{p})} \beta \right] \left$$

$$\Rightarrow \overrightarrow{M}_{N} = E_{q(\overrightarrow{\alpha})}[diag(\overrightarrow{\alpha})] + E_{q(\overrightarrow{\alpha})}[\overrightarrow{\alpha}] = I_{\overline{j}=1}^{-1} G(\alpha_{j} | \overrightarrow{\alpha}, \overrightarrow{b}_{j})] + I_{2}(\alpha_{j} | \overrightarrow{\alpha}, \overrightarrow{b}_{j}) .$$

$$A_{1} \cdot 2 \cdot Q^{*}(\overrightarrow{\alpha}) = I_{\overline{j}=1}^{M} G(\alpha_{j} | \overrightarrow{\alpha}, \overrightarrow{b}_{j}) .$$

$$ln Q^{*}(\overrightarrow{\alpha}) = E_{q(\overrightarrow{\alpha})} q(a) \left( ln P(\overrightarrow{\lambda}, \overrightarrow{N}, \overrightarrow{\alpha}, \beta) \right) + ln \overrightarrow{L} G(\alpha_{j} | \alpha_{j}, b) \right) + ln \overrightarrow{L} G(\alpha_{j} | \alpha_{j}, b) + ln \overrightarrow{L} G(\alpha_{j} | \alpha_{j}, b)) + ln \overrightarrow{L} G(\alpha_{j} | \alpha_{j}, b) + ln \overrightarrow{L} G(\alpha_{j} | \alpha_{j}, b)) + ln \overrightarrow{L} G(\alpha_{j} | \alpha_{j}, b) + ln \overrightarrow{L} G(\alpha_{j} | \alpha_{j}, b)) + ln \overrightarrow{L} G(\alpha_{j} | \alpha_{j}, b) + ln \overrightarrow{L} G(\alpha_{j} | \alpha_{j}, b)) + ln \overrightarrow{L} G(\alpha_{j} | \alpha_{j}, b) + ln \overrightarrow{L} G(\alpha_{j} | \alpha_{j}, b)) + ln$$

A1.3. 
$$Q^*(\rho) = G(\beta; \hat{c}, \hat{d})$$
.

 $\begin{cases} \ln Q^*(\beta) = E_{q(\vec{\omega})q(\vec{\omega})}[\ln P(\vec{x}, \vec{w}, \vec{\alpha}, \rho)] + c_{q}\hat{d} \\ = E_{q(\vec{\omega})q(\vec{\omega})}[\frac{\beta}{2}][\ln N(t_{i}; \vec{w} \vec{\sigma}(x_{i}), \rho^{-1})] + \ln G(\beta; c_{q}\hat{d}) \end{cases}$ 
 $= E_{q(\vec{\omega})}[\frac{\beta}{2}][\ln N(t_{i}; \vec{w} \vec{\sigma}(x_{i}), \rho^{-1})] + \ln G(\beta; c_{q}\hat{d}) \end{cases}$ 
 $= E_{q(\vec{\omega})}[\frac{\beta}{2}][\frac{1}{2}\ln \beta - \frac{\beta}{2}(t_{i} - \vec{w} \vec{\sigma}(x_{i}))^{2}] + (c_{q}\hat{d}) + c_{q}\hat{d}$ 
 $= \frac{\beta}{2} \frac{1}{2}\ln \beta - \frac{\beta}{2}E_{q(\vec{\omega})}[\frac{\beta}{2}][t_{i} - \vec{w}\vec{\sigma}(x_{i})]^{2}] + (c_{q}\hat{d}) + c_{q}\hat{d}$ 
 $= \frac{\beta}{2} E_{q(\vec{\omega})}[||\vec{t} - \vec{u}\vec{w}||_{2}^{2}] + (c_{q}\hat{d}) + c_{q}\hat{d}$ 
 $= -(d + \frac{1}{2}E_{q(\vec{\omega})}[||\vec{t} - \vec{u}\vec{w}||_{2}^{2}])\beta + (c_{q}\hat{d}) + c_{q}\hat{d}$ 
 $= -(d + \frac{1}{2}E_{q(\vec{\omega})}[||\vec{t} - \vec{u}\vec{w}||_{2}^{2}])\beta + (c_{q}\hat{d}) + c_{q}\hat{d}$ 
 $= -(d + \frac{1}{2}E_{q(\vec{\omega})}[||\vec{t} - \vec{u}\vec{w}||_{2}^{2}])\beta + (c_{q}\hat{d}) + c_{q}\hat{d}$ 
 $= -(d + \frac{1}{2}E_{q(\vec{\omega})}[||\vec{t} - \vec{u}\vec{w}||_{2}^{2}])\beta + (c_{q}\hat{d}) + c_{q}\hat{d}$ 
 $= -(d + \frac{1}{2}E_{q(\vec{\omega})}[||\vec{t} - \vec{u}\vec{w}||_{2}^{2}])\beta + (c_{q}\hat{d}) + c_{q}\hat{d} +$