

## Lecture V : Finite Element Methods II

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### A) Aims of this class

After this class,

- I know how to get a mesh of a domain with a software in dimension 2.
- I can define the finite element method  $\mathbb{P}_1$  in dimension 2.
- I can assemble the stiffness matrix.
- I can program in FEniCS the solution of an elliptic problem in dimension 2.

**B) To become familiar with this class' concepts (to prepare before the examples class)**

Question V.1 must be done before the 7th lab. The solution is available online.

**Warning ! You must attend the class with your computer.**

**Question V.1**

Let  $\Omega$  be an open polyhedral bounded subset of  $\mathbb{R}^2$ . We want to solve approximately the Dirichlet problem over  $\Omega$ .

**Q. V.1.1** Recall the statement of the Dirichlet problem in dimension 2.

**Q. V.1.2** For a given triangular mesh  $\mathcal{T}$  of  $\Omega$ , describe the finite element method  $\mathbb{P}_1$ : type of problem, polynomials to use, and so on.

Consider a given triangle  $K$  and let  $a_1, a_2, a_3$  be its vertices. For  $j \in \{1, 2, 3\}$ , denote  $\lambda_j$  the barycentric coordinate associated with the vertex  $a_j$ . We already know that these 3 functions  $(\lambda_j)_{j \in \{1, 2, 3\}}$  is a basis of the polynomial space  $\mathbb{P}_1$ .

**Q. V.1.3** Let  $M \in K$  with coordinates  $(x, y)$ . For  $j \in \{a, b, c\}$ , give the expression of the barycentric coordinate  $\lambda_j$  depending on  $x$  and on  $y$ .

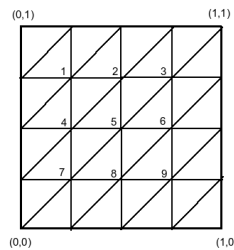
Define the elementary stiffness matrix  $\mathcal{A}$  associated with the triangle  $K$  as the symmetric 9-element matrix:

$$a_{ij} = \int_K \nabla \lambda_i \cdot \nabla \lambda_j dx dy.$$

**Q. V.1.4** Let  $h > 0$ . Compute  $\mathcal{A}$  for the triangle of vertices  $(0, 0), (0, -h), (h, 0)$ .

**Q. V.1.5** Let  $h > 0$ . Compute  $\mathcal{A}$  for the triangle of vertices  $(0, 0), (-h, -h), (0, -h)$ .

**Q. V.1.6** Compute the stiffness matrix for the Dirichlet problem in the square  $]0, 1[ \times ]0, 1[$  equipped with the following mesh.

**C) Exercises**

The exercises can be found on edunao as Jupyter notebooks.

## Chapter VII: Solutions

**Solution de Q. V.1.3** The barycentric coordinates  $(\lambda_j)_{j \in \{a,b,c\}}$  verify

$$\begin{pmatrix} x \\ y \\ 1 \end{pmatrix} = \lambda_a \begin{pmatrix} x_a \\ y_a \\ 1 \end{pmatrix} + \lambda_b \begin{pmatrix} x_b \\ y_b \\ 1 \end{pmatrix} + \lambda_c \begin{pmatrix} x_c \\ y_c \\ 1 \end{pmatrix}$$

which is the linear system

$$\begin{pmatrix} x_a & x_b & x_c \\ y_a & y_b & y_c \\ 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} \lambda_a \\ \lambda_b \\ \lambda_c \end{pmatrix} = \begin{pmatrix} x \\ y \\ 1 \end{pmatrix}.$$

On trouve alors

$$\begin{aligned} \lambda_a &= \frac{(x - x_c)(y_b - y_c) - (x_b - x_c)(y - y_c)}{(x_a - x_c)(y_b - y_c) - (x_b - x_c)(y_a - y_c)} \\ \lambda_b &= \frac{(x_a - x_c)(y - y_c) - (x - x_c)(y_a - y_c)}{(x_a - x_c)(y_b - y_c) - (x_b - x_c)(y_a - y_c)} \\ \lambda_c &= 1 - \lambda_a - \lambda_b. \end{aligned}$$

**Solution de Q. V.1.4** Let us number the vertices  $S_1 = (0,0)$ ,  $S_4 = (0,-h)$ ,  $S_2 = (h,0)$  and let us note  $T^I = (S_1, S_4, S_2)$ ,

$$\begin{aligned} \lambda_1^I &= 1 - (x - y)/h, & \nabla \lambda_1^I &= (1/h)(-1, 1)^T \\ \lambda_4^I &= -y/h, & \nabla \lambda_4^I &= (1/h)(0, -1)^T \\ \lambda_2^I &= x/h, & \nabla \lambda_2^I &= (1/h)(1, 0)^T \end{aligned}$$

The matrix can be written

$$\mathcal{A}^I = \frac{1}{h^2} \frac{h^2}{2} \begin{pmatrix} 2 & -1 & -1 \\ -1 & 1 & 0 \\ -1 & 0 & 1 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 2 & -1 & -1 \\ -1 & 1 & 0 \\ -1 & 0 & 1 \end{pmatrix}.$$

**Solution de Q. V.1.5** Let us number the vertices  $S_2 = (0,0)$ ,  $S_4 = (-h,-h)$ ,  $S_5 = (0,-h)$  and note  $T^{II} = (S_2, S_4, S_5)$ ,

$$\begin{aligned} \lambda_2^{II} &= 1 + y/h, & \nabla \lambda_2^{II} &= (1/h)(0, 1)^T \\ \lambda_4^{II} &= -x/h, & \nabla \lambda_4^{II} &= (1/h)(-1, 0)^T \\ \lambda_5^{II} &= (x - y)/h, & \nabla \lambda_5^{II} &= (1/h)(1, -1)^T \end{aligned}$$

The matrix can be written

$$\mathcal{A}^{II} = \frac{1}{h^2} \frac{h^2}{2} \begin{pmatrix} 1 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 1 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 1 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 1 \end{pmatrix}$$

**Solution de Q. V.1.6** Let us characterize the basis functions at the interior vertices:

$$\begin{aligned} \Phi_1 &= \lambda_1^{(142)}, \nabla \Phi_1 = (1/h)(-1, 1)^T \mathbf{1}_{(142)} \\ \Phi_2 &= \lambda_2^{(142)} \mathbf{1}_{(142)} + \lambda_2^{(245)} \mathbf{1}_{(245)} + \lambda_2^{(253)} \mathbf{1}_{(253)}, \nabla \Phi_2 = (1/h)((1, 0)^T \mathbf{1}_{(142)} + (0, 1)^T \mathbf{1}_{(245)} + (-1, 1)^T \mathbf{1}_{(253)}) \\ &\text{etc.} \end{aligned}$$

We work a triangle at a time, then we tally up. Eventually, the stiffness matrix is

$$\mathcal{A} = \begin{pmatrix} 4 & -1 & 0 & -1 & 0 & 0 & 0 & 0 & 0 \\ -1 & 4 & -1 & 0 & -1 & 0 & 0 & 0 & 0 \\ 0 & -1 & 4 & 0 & 0 & -1 & 0 & 0 & 0 \\ -1 & 0 & 0 & 4 & -1 & 0 & -1 & 0 & 0 \\ 0 & -1 & 0 & -1 & 4 & -1 & 0 & -1 & 0 \\ 0 & 0 & -1 & 0 & -1 & 4 & 0 & 0 & -1 \\ 0 & 0 & 0 & -1 & 0 & 0 & 4 & -1 & 0 \\ 0 & 0 & 0 & 0 & -1 & 0 & -1 & 4 & -1 \\ 0 & 0 & 0 & 0 & 0 & -1 & 0 & -1 & 4 \end{pmatrix}$$