

CentraleSupélec
ST7 – Optimization
Part VII: Lagrange multipliers method

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Constrained optimization problem

Let \mathcal{H} be a Hilbert space. Let $f: \mathcal{H} \rightarrow]-\infty, +\infty]$.

Let $(m, q) \in \mathbb{N}^2$. For every $i \in \{1, \dots, m\}$, let $g_i: \mathcal{H} \rightarrow \mathbb{R}$ and for every $j \in \{1, \dots, q\}$, let $h_j: \mathcal{H} \rightarrow \mathbb{R}$.

Let

constrains.

$$C = \{x \in \mathcal{H} \mid (\forall i \in \{1, \dots, m\}) \ g_i(x) = 0 \\ (\forall j \in \{1, \dots, q\}) \ h_j(x) \leq 0\}.$$

We want to:

$$\text{Find } \hat{x} \in \underset{x \in C}{\text{Argmin}} \ f(x).$$

Remark: A vector $x \in \mathcal{H}$ is said to be **feasible** if $x \in \text{dom } f \cap C$.

Definitions

The **Lagrange function** (or Lagrangian) associated with the previous problem is defined as

$$(\forall x \in \mathcal{H})(\forall \nu = (\nu^{(i)})_{1 \leq i \leq m} \in \mathbb{R}^m)(\forall \lambda = (\lambda^{(j)})_{1 \leq j \leq q} \in [0, +\infty[^q)$$

$$\mathcal{L}(x, \nu, \lambda) = f(x) + \sum_{i=1}^m \nu^{(i)} g_i(x) + \sum_{j=1}^q \lambda^{(j)} h_j(x).$$

The vectors ν and λ are called **Lagrange multipliers**.

Remark:

► $\text{dom } \mathcal{L} = \text{dom } f \times \mathbb{R}^m \times [0, +\infty[^q.$

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Remark:

- ▶ When $q = 0$ (**only equality constraints**), the Lagrange function simplifies to

$$(\forall x \in \mathcal{H})(\forall \nu = (\nu^{(i)})_{1 \leq i \leq m} \in \mathbb{R}^m) \quad \mathcal{L}(x, \nu) = f(x) + \sum_{i=1}^m \nu^{(i)} g_i(x).$$

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Lagrange duality

Let $\bar{\mathcal{L}}$ be the **primal Lagrange function** defined as

$$(\forall x \in \mathcal{H}) \quad \bar{\mathcal{L}}(x) = \sup_{\nu \in \mathbb{R}^m, \lambda \in [0, +\infty[^q} \mathcal{L}(x, \nu, \lambda).$$

Then, for every $x \in C$, $\bar{\mathcal{L}}(x) = f(x)$.

Proof: For every $(x, \nu, \lambda) \in C \times \mathbb{R}^m \times [0, +\infty[^q$

$$\mathcal{L}(x, \nu, \lambda) = f(x) + \sum_{i=1}^m \underbrace{\nu^{(i)} g_i(x)}_{=0} + \sum_{j=1}^q \underbrace{\lambda^{(j)} h_j(x)}_{\leq 0} \leq f(x)$$

and $\bar{\mathcal{L}}(x) = \sup_{\nu \in \mathbb{R}^m, \lambda \in [0, +\infty[^q} \mathcal{L}(x, \nu, \lambda) = f(x)$.

Lagrange duality

Let $\bar{\mathcal{L}}$ be the primal Lagrange function defined as

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Then, for every $x \in C$, $\bar{\mathcal{L}}(x) = f(x)$.


Let $\underline{\mathcal{L}}$ be the dual Lagrange function defined as

$$(\forall (\nu, \lambda) \in \mathbb{R}^m \times [0, +\infty[^q) \quad \underline{\mathcal{L}}(\nu, \lambda) = \inf_{x \in \mathcal{H}} \mathcal{L}(x, \nu, \lambda)$$

Then, $-\underline{\mathcal{L}}$ is convex and s.c.i.

Lagrange duality

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Then, for every $x \in C$, $\bar{\mathcal{L}}(x) = f(x)$.

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Then, $-\underline{\mathcal{L}}$ is convex and s.c.i.

Proof: For every $(\nu, \lambda) \in \mathbb{R}^m \times [0, +\infty[^q$,

$$-\underline{\mathcal{L}}(\nu, \lambda) = \sup_{x \in \text{dom } f} (-\mathcal{L}(x, \nu, \lambda)).$$

$-\underline{\mathcal{L}}$ is thus the supremum of a set of affine functions.

Lagrange duality

For every $(x, \nu, \lambda) \in \mathcal{H} \times \mathbb{R}^m \times [0, +\infty[^q$,

$$\underline{\mathcal{L}}(\nu, \lambda) \leq \overline{\mathcal{L}}(x).$$

*weak
strong.*

In addition,

$$\sup_{\nu \in \mathbb{R}^m, \lambda \in [0, +\infty[^q} \underline{\mathcal{L}}(\nu, \lambda) \leq \mu = \inf_{x \in \mathcal{C}} f(x).$$

Lagrange duality

For every $(x, \nu, \lambda) \in \mathcal{H} \times \mathbb{R}^m \times [0, +\infty[^q$,

$$\underline{\mathcal{L}}(\nu, \lambda) \leq \overline{\mathcal{L}}(x).$$

In addition,

$$\sup_{\nu \in \mathbb{R}^m, \lambda \in [0, +\infty[^q} \underline{\mathcal{L}}(\nu, \lambda) \leq \mu = \inf_{x \in C} f(x).$$

Proof: We have, for every $(x, \nu, \lambda) \in \mathcal{H} \times \mathbb{R}^m \times [0, +\infty[^q$,

$$\inf_{x'} \mathcal{L}(x', \nu, \lambda) \leq \mathcal{L}(x, \nu, \lambda) \leq \sup_{\nu', \lambda'} \mathcal{L}(x, \nu', \lambda')$$

$$\Rightarrow \underline{\mathcal{L}}(\nu, \lambda) \leq \overline{\mathcal{L}}(x).$$

We deduce that, for every $x \in C$, $\underline{\mathcal{L}}(\nu, \lambda) \leq \overline{\mathcal{L}}(x) = f(x)$, which yields the last inequality.

Saddle points 鞍点.

$(\hat{x}, \hat{\nu}, \hat{\lambda}) \in \mathcal{H} \times \mathbb{R}^m \times [0, +\infty]^q$ is a saddle point of \mathcal{L} if

$$(\forall (x, \nu, \lambda) \in \mathcal{H} \times \mathbb{R}^m \times [0, +\infty]^q) \quad \mathcal{L}(\hat{x}, \nu, \lambda) \leq \mathcal{L}(\hat{x}, \hat{\nu}, \hat{\lambda}) \leq \mathcal{L}(x, \hat{\nu}, \hat{\lambda}).$$

Remark: If there exists a feasible point and $(\hat{x}, \hat{\nu}, \hat{\lambda})$ is a saddle point of \mathcal{L} , then it follows from the right inequality that $\hat{x} \in \text{dom } f$.

Saddle points

$(\hat{x}, \hat{\nu}, \hat{\lambda}) \in \mathcal{H} \times \mathbb{R}^m \times [0, +\infty[^q$ is a **saddle point** of \mathcal{L} if

$$(\forall (x, \nu, \lambda) \in \mathcal{H} \times \mathbb{R}^m \times [0, +\infty[^q) \quad \mathcal{L}(\hat{x}, \nu, \lambda) \leq \mathcal{L}(\hat{x}, \hat{\nu}, \hat{\lambda}) \leq \mathcal{L}(x, \hat{\nu}, \hat{\lambda}).$$

Theorem

$(\hat{x}, \hat{\nu}, \hat{\lambda}) \in \mathcal{H} \times \mathbb{R}^m \times [0, +\infty[^q$ is a saddle point of \mathcal{L} if and only if

$$(\forall x \in \mathcal{H}) \quad \overline{\mathcal{L}}(\hat{x}) \leq \overline{\mathcal{L}}(x)$$

$$(\forall (\nu, \lambda) \in \mathbb{R}^m \times [0, +\infty[^q) \quad \underline{\mathcal{L}}(\nu, \lambda) \leq \underline{\mathcal{L}}(\hat{\nu}, \hat{\lambda})$$

$$\overline{\mathcal{L}}(\hat{x}) = \underline{\mathcal{L}}(\hat{\nu}, \hat{\lambda}).$$

Saddle points

Proof: If $(\hat{x}, \hat{\nu}, \hat{\lambda})$ is a saddle point of \mathcal{L} then, for every $(x', \nu', \lambda') \in \mathcal{H} \times \mathbb{R}^m \times [0, +\infty[^q$,

$$\begin{aligned}
 & \mathcal{L}(\hat{x}, \nu', \lambda') \leq \mathcal{L}(\hat{x}, \hat{\nu}, \hat{\lambda}) \leq \mathcal{L}(x', \hat{\nu}, \hat{\lambda}) \\
 \Rightarrow & \sup_{\nu', \lambda'} \mathcal{L}(\hat{x}, \nu', \lambda') \leq \inf_{x'} \mathcal{L}(x', \hat{\nu}, \hat{\lambda}) \\
 \Leftrightarrow & \overline{\mathcal{L}}(\hat{x}) \leq \underline{\mathcal{L}}(\hat{\nu}, \hat{\lambda}) \\
 \Rightarrow & \inf_x \overline{\mathcal{L}}(x) \leq \overline{\mathcal{L}}(\hat{x}) \leq \underline{\mathcal{L}}(\hat{\nu}, \hat{\lambda}) \leq \sup_{\nu, \lambda} \underline{\mathcal{L}}(\nu, \lambda).
 \end{aligned}$$

In addition

$$\sup_{\nu, \lambda} \underline{\mathcal{L}}(\nu, \lambda) \leq \inf_x \overline{\mathcal{L}}(x).$$

Therefore, $\inf_x \overline{\mathcal{L}}(x) = \sup_{\nu, \lambda} \underline{\mathcal{L}}(\nu, \lambda)$.

We deduce that $\overline{\mathcal{L}}(\hat{x}) = \inf_x \overline{\mathcal{L}}(x)$, $\underline{\mathcal{L}}(\hat{\nu}, \hat{\lambda}) = \sup_{\nu, \lambda} \underline{\mathcal{L}}(\nu, \lambda)$, and $\overline{\mathcal{L}}(\hat{x}) = \underline{\mathcal{L}}(\hat{\nu}, \hat{\lambda})$.

Saddle points

Proof: Conversely, if the last condition holds, then

$$\begin{aligned}\mathcal{L}(\hat{x}, \hat{\nu}, \hat{\lambda}) &\leq \sup_{\nu, \lambda} \mathcal{L}(\hat{x}, \nu, \lambda) = \overline{\mathcal{L}}(\hat{x}) \\ &= \underline{\mathcal{L}}(\hat{\nu}, \hat{\lambda}) = \inf_x \mathcal{L}(x, \hat{\nu}, \hat{\lambda}).\end{aligned}$$

Similarly,

$$\begin{aligned}\mathcal{L}(\hat{x}, \hat{\nu}, \hat{\lambda}) &\geq \inf_x \mathcal{L}(x, \hat{\nu}, \hat{\lambda}) = \underline{\mathcal{L}}(\hat{\nu}, \hat{\lambda}) \\ &= \overline{\mathcal{L}}(\hat{x}) = \sup_{\nu, \lambda} \mathcal{L}(\hat{x}, \nu, \lambda).\end{aligned}$$

In conclusion, for every $(x, \nu, \lambda) \in \mathcal{H} \times \mathbb{R}^m \times [0, +\infty[^q$,

$$\mathcal{L}(\hat{x}, \nu, \lambda) \leq \mathcal{L}(\hat{x}, \hat{\nu}, \hat{\lambda}) \leq \mathcal{L}(x, \hat{\nu}, \hat{\lambda}).$$

Sufficient condition for a constrained minimum

Assume that there exists a feasible point. 充分条件.

If $(\hat{x}, \hat{\nu}, \hat{\lambda}) \in \mathcal{H} \times \mathbb{R}^m \times [0, +\infty[^q$ is a saddle point of \mathcal{L} ,
then \hat{x} is a minimizer of f over C .

In addition, $\mu = f(\hat{x}) = \underline{\mathcal{L}}(\hat{\nu}, \hat{\lambda})$ and the complementary slackness condition holds:

$$(\forall j \in \{1, \dots, q\}) \quad \hat{\lambda}_j h_j(\hat{x}) = 0.$$

Sufficient condition for a constrained minimum

Assume that there exists a feasible point.

If $(\hat{x}, \hat{\nu}, \hat{\lambda}) \in \mathcal{H} \times \mathbb{R}^m \times [0, +\infty[^q$ is a saddle point of \mathcal{L} , then \hat{x} is a minimizer of f over C .

In addition, $\mu = f(\hat{x}) = \underline{\mathcal{L}}(\hat{\nu}, \hat{\lambda})$ and the complementary slackness condition holds:

$$(\forall j \in \{1, \dots, q\}) \quad \hat{\lambda}_j h_j(\hat{x}) = 0.$$

Proof: We know that $\hat{x} \in \text{dom } f$. We have, for every

$$(\nu, \lambda) \in \mathbb{R}^m \times [0, +\infty[^q, \quad \mathcal{L}(\hat{x}, \nu, \lambda) \leq \mathcal{L}(\hat{x}, \hat{\nu}, \hat{\lambda}).$$

For every $\nu' = (\nu'^{(i)})_{1 \leq i \leq m} \in \mathbb{R}^m$ by setting $\nu = \hat{\nu} + \nu'$ and $\lambda = \hat{\lambda}$,

$$\sum_{i=1}^m \nu'^{(i)} g_i(\hat{x}) \leq 0$$

and, for every $\lambda' = (\lambda'^{(j)})_{1 \leq j \leq q} \in [0, +\infty[^q$, by setting $\nu = \hat{\nu}$ and $\lambda = \hat{\lambda} + \lambda'$,

$$\sum_{j=1}^q \lambda'^{(j)} h_j(\hat{x}) \leq 0.$$

We deduce that $\begin{cases} (\forall i \in \{1, \dots, m\}) & g_i(\hat{x}) = 0 \\ (\forall j \in \{1, \dots, q\}) & h_j(\hat{x}) \leq 0, \end{cases} \quad \text{i.e. } \hat{x} \in C.$

Sufficient condition for a constrained minimum

Assume that there exists a feasible point.

If $(\hat{x}, \hat{\nu}, \hat{\lambda}) \in \mathcal{H} \times \mathbb{R}^m \times [0, +\infty[^q$ is a saddle point of \mathcal{L} , then \hat{x} is a minimizer of f over C .

In addition, $\mu = f(\hat{x}) = \underline{\mathcal{L}}(\hat{\nu}, \hat{\lambda})$ and the **complementary slackness** condition holds:

$$(\forall j \in \{1, \dots, q\}) \quad \hat{\lambda}_j h_j(\hat{x}) = 0.$$

Proof: We have shown that $(\forall i \in \{1, \dots, m\}) \ g_i(\hat{x}) = 0$ and $(\forall j \in \{1, \dots, q\}) \ h_j(\hat{x}) \leq 0 \Rightarrow \hat{\lambda}_j h_j(\hat{x}) \leq 0$.

Then, since

$$\mathcal{L}(\hat{x}, \hat{\nu}, 0) \leq \mathcal{L}(\hat{x}, \hat{\nu}, \hat{\lambda}),$$

we have

$$\sum_{j=1}^m \hat{\lambda}_j h_j(\hat{x}) \geq 0,$$

which implies that the complementary slackness condition holds.

Sufficient condition for a constrained minimum

Assume that there exists a feasible point.

If $(\hat{x}, \hat{\nu}, \hat{\lambda}) \in \mathcal{H} \times \mathbb{R}^m \times [0, +\infty[^q$ is a saddle point of \mathcal{L} , then \hat{x} is a minimizer of f over C .

In addition, $\mu = f(\hat{x}) = \underline{\mathcal{L}}(\hat{\nu}, \hat{\lambda})$ and the complementary slackness condition holds:

$$(\forall j \in \{1, \dots, q\}) \quad \hat{\lambda}_j h_j(\hat{x}) = 0.$$

Proof: As $\hat{x} \in C$ and the complementary slackness condition holds, $\mathcal{L}(\hat{x}, \hat{\nu}, \hat{\lambda}) = f(\hat{x})$. Furthermore,

$$\begin{aligned} (\forall x \in C) \quad \mathcal{L}(\hat{x}, \hat{\nu}, \hat{\lambda}) &\leq \mathcal{L}(x, \hat{\nu}, \hat{\lambda}) \\ \Leftrightarrow f(\hat{x}) &\leq f(x) + \sum_{i=1}^m \hat{\nu}_i g_i(x) + \sum_{j=1}^q \hat{\lambda}_j h_j(x) \leq f(x). \end{aligned}$$

Finally, as a consequence of previous results, $f(\hat{x}) = \bar{\mathcal{L}}(\hat{x}) = \underline{\mathcal{L}}(\hat{\nu}, \hat{\lambda})$.

Convex case

Assume that f is a convex function, $(g_i)_{1 \leq i \leq m}$ are affine functions and $(h_j)_{1 \leq j \leq q}$ are convex functions. Assume that the **Slater condition** holds, i.e. there exists $\bar{x} \in \text{int}(\text{dom } f)$ such that

$$\begin{aligned} (\forall i \in \{1, \dots, m\}) \quad & g_i(\bar{x}) = 0 \\ (\forall j \in \{1, \dots, q\}) \quad & h_j(\bar{x}) < 0. \end{aligned}$$

If \hat{x} is a minimizer of f over C , then there exists $\hat{\nu} \in \mathbb{R}^m$ and $\hat{\lambda} \in [0, +\infty[^q$ such that $(\hat{x}, \hat{\nu}, \hat{\lambda})$ is a saddle point of the Lagrangian.

Convex case

Assume that f is a convex function, $(g_i)_{1 \leq i \leq m}$ are affine functions and $(h_j)_{1 \leq j \leq q}$ are convex functions. Assume that the Slater condition holds, i.e. there exists $\bar{x} \in \text{int}(\text{dom } f)$ such that

$$\begin{aligned} (\forall i \in \{1, \dots, m\}) \quad & g_i(\bar{x}) = 0 \\ (\forall j \in \{1, \dots, q\}) \quad & h_j(\bar{x}) < 0. \end{aligned}$$

\hat{x} is a minimizer of f over C if and only if there exists $\hat{\nu} \in \mathbb{R}^m$ and $\hat{\lambda} \in [0, +\infty[^q$ such that $(\hat{x}, \hat{\nu}, \hat{\lambda})$ is a saddle point of the Lagrangian.

Proof: Combine the two previous results.

Convex case

Assume that f is a convex function, $(g_i)_{1 \leq i \leq m}$ are affine functions and $(h_j)_{1 \leq j \leq q}$ are convex functions. Assume that the Slater condition holds, i.e. there exists $\bar{x} \in \text{int}(\text{dom } f)$ such that

$$\begin{aligned} (\forall i \in \{1, \dots, m\}) \quad & g_i(\bar{x}) = 0 \\ (\forall j \in \{1, \dots, q\}) \quad & h_j(\bar{x}) < 0. \end{aligned}$$

\hat{x} is a minimizer of f over C if and only if there exists $\hat{\nu} \in \mathbb{R}^m$ and $\hat{\lambda} \in [0, +\infty[^q$ such that $(\hat{x}, \hat{\nu}, \hat{\lambda})$ is a saddle point of the Lagrangian.

Remark: Under the assumptions of the above theorem, if \hat{x} is a minimizer of f over C then $\mathcal{L}(\cdot, \hat{\nu}, \hat{\lambda})$ is a convex function which is minimum at \hat{x} . This optimality condition is often used to calculate \hat{x} , in conjunction with the equality constraints and the complementary slackness condition.

Convex case

Only equality constraints:

Assume that f is a convex function and $(g_i)_{1 \leq i \leq m}$ are affine functions. Assume that the Slater condition holds, i.e. there exists $\bar{x} \in \text{int}(\text{dom } f)$ such that

$$(\forall i \in \{1, \dots, m\}) \quad g_i(\bar{x}) = 0.$$

\hat{x} is a minimizer of f over C if and only if there exists $\hat{\nu} \in \mathbb{R}^m$ such that $(\hat{x}, \hat{\nu})$ is a saddle point of the Lagrangian.

Convex case

Only inequality constraints:

Assume that f is a convex function, and $(h_j)_{1 \leq j \leq q}$ are convex functions. Assume that the Slater condition holds, i.e. there exists $\bar{x} \in \text{dom } f$ such that

$$(\forall j \in \{1, \dots, q\}) \quad h_j(\bar{x}) < 0.$$

\hat{x} is a minimizer of f over C if and only if there exists $\hat{\lambda} \in [0, +\infty[^q$ such that $(\hat{x}, \hat{\lambda})$ is a saddle point of the Lagrangian.

Exercise 1

One wants to minimize the production cost of a factory.

The factory produces cars in quantity x_1 and trucks in quantity x_2 . The production of cars and trucks require $\psi_1(x_1)$ and $\psi_2(x_2)$ machine tools, respectively. The overall number of used machine tools is equal to c . The production costs of cars and trucks are equal to $\varphi_1(x_1)$ and $\varphi_2(x_2)$, respectively.

Solve this problem by the Lagrange multiplier method, when

$$\varphi_1(x_1) = (x_1 - 100)^2$$

$$\varphi_2(x_2) = 2(x_2 - 50)^2$$

$$\psi_1(x_1) = x_1$$

$$\psi_2(x_2) = x_2$$

$$c = 90.$$

Exercise 2

Let f be defined as

$$(\forall x \in \mathbb{R}^N) \quad f(x) = \frac{1}{2}x^\top Qx + c^\top x.$$

where $Q \in \mathbb{R}^{N \times N}$ is a definite positive matrix and $c \in \mathbb{R}^N$.

We are interested in finding a minimizer of f subject to the constraint:

$$Ax = b$$

where $A \in \mathbb{R}^{m \times N}$ is a matrix of rank m and $b \in \mathbb{R}^m$.

1. Show that the problem has a unique solution.
2. By using the Lagrange multipliers method, find the expression of the solution.

Exercise 3

Let f be defined as

$$(\forall x = (x^{(i)})_{1 \leq i \leq N} \in [0, +\infty[^N) \quad f(x) = \sum_{i=1}^N x^{(i)} \ln(x^{(i)}),$$

with $N > 1$. Find a minimizer of f on $[0, +\infty[^N$ subject to the constraints

$$\sum_{i=1}^N x^{(i)} = 1$$

$$\sum_{i=1}^P x^{(i)} = q,$$

where $P \in \{1, \dots, N-1\}$ and $q \in]0, 1[$.

Differentiable case 可微.

Assume that f , $(g_i)_{1 \leq i \leq m}$, and $(h_j)_{1 \leq j \leq q}$ are continuously differentiable on $\mathcal{H} = \mathbb{R}^N$.

If \hat{x} is a local minimum of f over C then the **Fritz-John conditions** hold, i.e. there exists a nonzero vector $(\alpha_0, \alpha_1, \dots, \alpha_m, \alpha_{m+1}, \dots, \alpha_{m+q}) \in [0, +\infty[\times \mathbb{R}^m \times [0, +\infty[^q$ such that

$$\alpha_0 \nabla f(\hat{x}) + \sum_{i=1}^m \alpha_i \nabla g_i(\hat{x}) + \sum_{j=1}^q \alpha_{m+j} \nabla h_j(\hat{x}) = 0$$

$$(\forall j \in \{1, \dots, q\}) \quad \alpha_{m+j} h_j(\hat{x}) = 0.$$

Differentiable case

Karush-Kuhn-Tucker (KKT) theorem

Assume that f , $(g_i)_{1 \leq i \leq m}$, and $(h_j)_{1 \leq j \leq q}$ are continuously differentiable on $\mathcal{H} = \mathbb{R}^N$.

Assume that \hat{x} is a local minimizer of f over C satisfying the following Mangasarian-Fromovitz **constraint qualification conditions** :

- (i) $\{\nabla g_i(\hat{x}) \mid i \in \{1, \dots, m\}\}$ is a family of linearly independent vectors;
- (ii) there exists $z \in \mathbb{R}^N$ such that

$$\begin{aligned} (\forall i \in \{1, \dots, m\}) \quad & \langle \nabla g_i(\hat{x}) \mid z \rangle = 0 \\ (\forall j \in J(\hat{x})) \quad & \langle \nabla h_j(\hat{x}) \mid z \rangle < 0 \end{aligned}$$

where $J(\hat{x}) = \{j \in \{1, \dots, q\} \mid h_j(\hat{x}) = 0\}$ is the set of **active inequality constraints** at \hat{x} .

Then, there exists $\hat{\nu} \in \mathbb{R}^N$ and $\hat{\lambda} \in [0, +\infty[^q$ such that \hat{x} is a critical point of $\mathcal{L}(\cdot, \hat{\nu}, \hat{\lambda})$ and the complementary slackness condition holds.

Differentiable case

Proof: We know that there exists a nonzero vector

$(\alpha_0, \alpha_1, \dots, \alpha_m, \alpha_{m+1}, \dots, \alpha_{m+q}) \in [0, +\infty[\times \mathbb{R}^m \times [0, +\infty[^q$ such that

$$\alpha_0 \nabla f(\hat{x}) + \sum_{i=1}^m \alpha_i \nabla g_i(\hat{x}) + \sum_{j=1}^q \alpha_{m+j} \nabla h_j(\hat{x}) = 0$$

$$(\forall j \in \{1, \dots, q\}) \quad \alpha_{m+j} h_j(\hat{x}) = 0.$$

The complementary slackness condition implies that $(\forall j \notin J(\hat{x})) \alpha_{m+j} = 0$ and the first equality reduces to

$$\alpha_0 \nabla f(\hat{x}) + \sum_{i=1}^m \alpha_i \nabla g_i(\hat{x}) + \sum_{j \in J(\hat{x})} \alpha_{m+j} \nabla h_j(\hat{x}) = 0$$

which yields

$$\alpha_0 \langle \nabla f(\hat{x}) \mid z \rangle + \sum_{i=1}^m \alpha_i \langle \nabla g_i(\hat{x}) \mid z \rangle + \sum_{j \in J(\hat{x})} \alpha_{m+j} \langle \nabla h_j(\hat{x}) \mid z \rangle = 0$$

$$\Leftrightarrow \alpha_0 \langle \nabla f(\hat{x}) \mid z \rangle + \sum_{j \in J(\hat{x})} \alpha_{m+j} \langle \nabla h_j(\hat{x}) \mid z \rangle = 0.$$

Differentiable case

Proof: We have proved that there exists a nonzero vector

$(\alpha_0, \alpha_1, \dots, \alpha_m, \alpha_{m+1}, \dots, \alpha_{m+q}) \in [0, +\infty[\times \mathbb{R}^m \times [0, +\infty[^q$ such that

$$\alpha_0 \nabla f(\hat{x}) + \sum_{i=1}^m \alpha_i \nabla g_i(\hat{x}) + \sum_{j \in J(\hat{x})} \alpha_{m+j} \nabla h_j(\hat{x}) = 0$$

$$\alpha_0 \langle \nabla f(\hat{x}) \mid z \rangle + \sum_{j \in J(\hat{x})} \alpha_{m+j} \langle \nabla h_j(\hat{x}) \mid z \rangle = 0.$$

Let us suppose that $\alpha_0 = 0$.

Since, for every $j \in J(\hat{x})$, $\langle \nabla h_j(\hat{x}) \mid z \rangle < 0$, in the latter equality, we would have, $\alpha_{m+j} = 0$ which, in the first equality, would lead to

$$\sum_{i=1}^m \alpha_i \nabla g_i(\hat{x}) = 0.$$

Since the vectors $(\nabla g_i(\hat{x}))_{1 \leq i \leq m}$ are linearly independent, $(\forall i \in \{1, \dots, m\}) \alpha_i = 0$.

In conclusion, the vector $(\alpha_i)_{1 \leq i \leq q}$ would be zero, which is impossible.

This shows that $\alpha_0 > 0$.

Differentiable case

By defining $(\forall i \in \{1, \dots, m\}) \hat{\nu}_i = \alpha_i / \alpha_0$, $(\forall j \in \{1, \dots, q\}) \hat{\lambda}_j = \alpha_{m+j} / \alpha_0 \geq 0$, we have then

$$\nabla f(\hat{x}) + \sum_{i=1}^m \hat{\nu}_i \nabla g_i(\hat{x}) + \sum_{j=1}^q \hat{\lambda}_j \nabla h_j(\hat{x}) = 0$$

$$(\forall j \in \{1, \dots, q\}) \quad \hat{\lambda}_j h_j(\hat{x}) = 0.$$

By setting $\hat{\nu} = (\hat{\nu}_i)_{1 \leq i \leq m} \in \mathbb{R}^m$ and $\hat{\lambda} = (\hat{\lambda}_j)_{1 \leq j \leq q} \in [0, +\infty[^q$, the first equality also reads

$$\nabla_x \mathcal{L}(\hat{x}, \hat{\nu}, \hat{\lambda}) = 0.$$

Differentiable case

Karush-Kuhn-Tucker (KKT) theorem

Assume that f , $(g_i)_{1 \leq i \leq m}$, and $(h_j)_{1 \leq j \leq q}$ are continuously differentiable on $\mathcal{H} = \mathbb{R}^N$.

Assume that \hat{x} is a local minimizer of f over C satisfying the following Mangasarian-Fromovitz **constraint qualification conditions** :

- (i) $\{\nabla g_i(\hat{x}) \mid i \in \{1, \dots, m\}\}$ is a family of linearly independent vectors;
- (ii) there exists $z \in \mathbb{R}^N$ such that

$$\begin{aligned} (\forall i \in \{1, \dots, m\}) \quad & \langle \nabla g_i(\hat{x}) \mid z \rangle = 0 \\ (\forall j \in J(\hat{x})) \quad & \langle \nabla h_j(\hat{x}) \mid z \rangle < 0 \end{aligned}$$

where $J(\hat{x}) = \{j \in \{1, \dots, q\} \mid h_j(\hat{x}) = 0\}$ is the set of **active inequality constraints** at \hat{x} .

Then, there exists $\hat{\nu} \in \mathbb{R}^N$ and $\hat{\lambda} \in [0, +\infty[^q$ such that \hat{x} is a critical point of $\mathcal{L}(\cdot, \hat{\nu}, \hat{\lambda})$ and the complementary slackness condition holds.

Remark: A sufficient condition for Mangasarian-Fromovitz conditions to be satisfied is that $\{\nabla g_i(\hat{x}) \mid i \in \{1, \dots, m\}\} \cup \{\nabla h_j(\hat{x}) \mid j \in J(\hat{x})\}$ is a family of linearly independent vectors.

Differentiable case

Karush-Kuhn-Tucker (KKT) theorem

Assume that f , $(g_i)_{1 \leq i \leq m}$, and $(h_j)_{1 \leq j \leq q}$ are continuously differentiable on $\mathcal{H} = \mathbb{R}^N$.

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- (i) $\{\nabla g_i(\hat{x}) \mid i \in \{1, \dots, m\}\}$ is a family of linearly independent vectors;
- (ii) there exists $z \in \mathbb{R}^N$ such that

$$\begin{aligned} (\forall i \in \{1, \dots, m\}) \quad & \langle \nabla g_i(\hat{x}) \mid z \rangle = 0 \\ (\forall j \in J(\hat{x})) \quad & \langle \nabla h_j(\hat{x}) \mid z \rangle < 0. \end{aligned}$$

Then, there exists $\hat{\nu} \in \mathbb{R}^m$ and $\hat{\lambda} \in [0, +\infty[^q$ such that \hat{x} is a critical point of $\mathcal{L}(\cdot, \hat{\nu}, \hat{\lambda})$ and the complementary slackness condition holds.

Remark: A sufficient condition for Mangasarian-Fromovitz conditions to be satisfied is that $\{\nabla g_i(\hat{x}) \mid i \in \{1, \dots, m\}\} \cup \{\nabla h_j(\hat{x}) \mid j \in J(\hat{x})\}$ is a family of linearly independent vectors.

Proof: If this condition holds, then the matrix

$$A = \begin{bmatrix} ((\nabla g_i(\hat{x}))^\top)_{1 \leq i \leq m} \\ ((\nabla h_j(\hat{x}))^\top)_{j \in J(\hat{x})} \end{bmatrix} \in \mathbb{R}^{(m+|J(\hat{x})|) \times N}$$

has rank $m + |J(\hat{x})|$. Let $\mathbf{1}$ be the unit vector of $\mathbb{R}^{|J(\hat{x})|}$. Hence, the equation

$$Az = \begin{bmatrix} 0 \\ -\mathbf{1} \end{bmatrix}, \quad z \in \mathbb{R}^N,$$

admits a solution. Such a solution satisfies (ii).

Differentiable case

Only equality constraints:

Assume that f and $(g_i)_{1 \leq i \leq m}$ are continuously differentiable on $\mathcal{H} = \mathbb{R}^N$.
Assume that \hat{x} is a local minimizer of f over C and
 $\{\nabla g_i(\hat{x}) \mid i \in \{1, \dots, m\}\}$ is a family of linearly independent vectors.
Then, there exists $\hat{\nu} \in \mathbb{R}^N$ such that \hat{x} is a critical point of $\mathcal{L}(\cdot, \hat{\nu})$.

Differentiable case

Only inequality constraints:

Assume that f and $(h_j)_{1 \leq j \leq q}$ are continuously differentiable on $\mathcal{H} = \mathbb{R}^N$.
 Assume that \hat{x} is a local minimizer of f over C and
 there exists $z \in \mathbb{R}^N$ such that

$$(\forall j \in J(\hat{x})) \quad \langle \nabla h_j(\hat{x}) \mid z \rangle < 0$$

where $J(\hat{x}) = \{j \in \{1, \dots, q\} \mid h_j(\hat{x}) = 0\}$ is the set of active inequality constraints at \hat{x} .

Then, there exists $\hat{\lambda} \in [0, +\infty[^q$ such that \hat{x} is a critical point of $\mathcal{L}(\cdot, \hat{\lambda})$ and the complementary slackness condition holds.

Differentiable case

Only inequality constraints:

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 Assume that \hat{x} is a local minimizer of f over C and
 there exists $z \in \mathbb{R}^N$ such that

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Then, there exists $\hat{\lambda} \in [0, +\infty[^q$ such that \hat{x} is a critical point of $\mathcal{L}(\cdot, \hat{\lambda})$ and the complementary slackness condition holds.

Remark: A sufficient condition for the qualification conditions to be satisfied is that $\{\nabla h_j(\hat{x}) \mid j \in J(\hat{x})\}$ is a family of linearly independent vectors.

Exercise 4

By using the Lagrange multipliers method, solve the following problem

$$\underset{x=(x^{(i)})_{1 \leq i \leq N} \in B}{\text{maximize}} \quad (x^{(N)})^3 - \frac{1}{2}(x^{(N)})^2$$

where B is the unit sphere, centered at 0, of \mathbb{R}^N .

Appendix

Preliminary result

Lemma

Let $\hat{x} \in C \cap \text{dom } f$, let $\hat{\nu} \in \mathbb{R}^m$, and let $\hat{\lambda} \in [0, +\infty[^q$ be such that

$$\underline{\mathcal{L}}(\hat{\nu}, \hat{\lambda}) = f(\hat{x}).$$

Then $(\hat{x}, \hat{\nu}, \hat{\lambda})$ is a saddle point of the Lagrange function.

Preliminary result

Lemma

Let $\hat{x} \in C \cap \text{dom } f$, let $\hat{\nu} \in \mathbb{R}^m$, and let $\hat{\lambda} \in [0, +\infty[^q$ be such that

$$\underline{\mathcal{L}}(\hat{\nu}, \hat{\lambda}) = f(\hat{x}).$$

Then $(\hat{x}, \hat{\nu}, \hat{\lambda})$ is a saddle point of the Lagrange function.

Proof: By looking more carefully at the proof of the theorem we provided for characterizing a saddle point, it appears that a sufficient condition for $(\hat{x}, \hat{\nu}, \hat{\lambda})$ to a saddle point of \mathcal{L} is

$$\underline{\mathcal{L}}(\hat{\nu}, \hat{\lambda}) = \overline{\mathcal{L}}(\hat{x}).$$

In addition, we know that $(\forall x \in C) \overline{\mathcal{L}}(x) = f(x)$.

Therefore the sufficient condition reduces the one stated.

Validity of Slater condition

Assume that Slater condition holds and that \hat{x} is a minimizer of f . Let us show that there exists $\hat{\nu} \in \mathbb{R}^m$ and $\hat{\lambda} \in [0, +\infty[^q$ such that $f(\hat{x}) = \underline{\mathcal{L}}(\hat{\nu}, \hat{\lambda})$. For every $i \in \{1, \dots, m\}$, since g_i is an affine function, there exists $v_i \in \mathcal{H}$ such that

$$(\forall x \in \mathcal{H}) \quad g_i(x) = g_i(\bar{x}) + \langle v_i \mid x - \bar{x} \rangle = \langle v_i \mid x - \bar{x} \rangle.$$

Assume first that the vectors $(v_i)_{1 \leq i \leq m}$ are independent.

Validity of Slater condition

Assume that Slater condition holds and that \hat{x} is a minimizer of f . Let us show that there exists $\hat{\nu} \in \mathbb{R}^m$ and $\hat{\lambda} \in [0, +\infty[^q$ such that $f(\hat{x}) = \underline{\mathcal{L}}(\hat{\nu}, \hat{\lambda})$. For every $i \in \{1, \dots, m\}$, since g_i is an affine function, there exists $v_i \in \mathcal{H}$ such that

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Assume first that the vectors $(v_i)_{1 \leq i \leq m}$ are independent.

Let

$$C_1 = \left\{ (u^{(0)}, u^{(1)}, \dots, u^{(m)}, u^{(m+1)}, \dots, u^{(m+q)}) \in \mathbb{R}^{m+q+1} \right. \\ \left. \begin{array}{l} f(x) \leq u^{(0)} \\ (\exists x \in \mathcal{H}) \quad \begin{array}{l} (\forall i \in \{1, \dots, m\}) \quad g_i(x) = u^{(i)} \\ (\forall j \in \{1, \dots, q\}) \quad h_j(x) \leq u^{(m+j)} \end{array} \end{array} \right\}$$

$$C_2 = \left\{ (u^{(0)}, u^{(1)}, \dots, u^{(m)}, u^{(m+1)}, \dots, u^{(m+q)}) \in \mathbb{R}^{m+q+1} \right. \\ \left. \begin{array}{l} u^{(0)} < f(\hat{x}) \\ (\forall i \in \{1, \dots, m\}) \quad u^{(i)} = 0 \\ (\forall j \in \{1, \dots, q\}) \quad u^{(m+j)} \leq 0 \end{array} \right\}.$$

Since f and $(h_j)_{1 \leq j \leq q}$ are convex and $(g_i)_{1 \leq i \leq m}$ are affine, C_1 is convex. As a consequence of Slater condition, it is nonempty.

C_2 is convex and nonempty. In addition, $C_1 \cap C_2 = \emptyset$ since there does not exist $x \in C$ such that $f(x) < f(\hat{x})$.

Validity of Slater condition

Let

$$C_1 = \left\{ (u^{(0)}, u^{(1)}, \dots, u^{(m)}, u^{(m+1)}, \dots, u^{(m+q)}) \in \mathbb{R}^{m+q+1} \right.$$

$$\left. \begin{array}{l} f(x) \leq u^{(0)} \\ (\exists x \in \mathcal{H}) \quad (\forall i \in \{1, \dots, m\}) \quad g_i(x) = u^{(i)} \\ (\forall j \in \{1, \dots, q\}) \quad h_j(x) \leq u^{(m+j)} \end{array} \right\}$$

$$C_2 = \left\{ (u^{(0)}, u^{(1)}, \dots, u^{(m)}, u^{(m+1)}, \dots, u^{(m+q)}) \in \mathbb{R}^{m+q+1} \right.$$

$$\left. \begin{array}{l} u^{(0)} < f(\hat{x}) \\ (\forall i \in \{1, \dots, m\}) \quad u^{(i)} = 0 \\ (\forall j \in \{1, \dots, q\}) \quad u^{(m+j)} \leq 0 \end{array} \right\}.$$

According to separation theorem in \mathbb{R}^{m+q+1} , there exists $a = (a^{(0)}, a^{(1)}, \dots, a^{(m)}, a^{(m+1)}, \dots, a^{(m+q)}) \in \mathbb{R}^{m+q+1} \setminus \{0\}$ such that

$$\inf_{u \in C_1} \langle a \mid u \rangle \geq \sup_{u \in C_2} \langle a \mid u \rangle = \sup_{u=(u^j)_{0 \leq j \leq m+q} \in C_2} \left(a^{(0)} u^{(0)} + \sum_{j=1}^q a^{(j+m)} u^{(j+m)} \right).$$

If one of the components $a^{(0)}$ or $(a^{(j+m)})_{1 \leq j \leq q}$ would be negative, the right-hand side term would be $+\infty$, which is prohibited.

Since these components belong to $[0, +\infty]^q$, $\sup_{u \in C_2} \langle a \mid u \rangle = a^{(0)} f(\hat{x})$.

Validity of Slater condition

Let

$$C_1 = \left\{ (u^{(0)}, u^{(1)}, \dots, u^{(m)}, u^{(m+1)}, \dots, u^{(m+q)}) \in \mathbb{R}^{m+q+1} \right. \\ \left. \begin{array}{l} f(x) \leq u^{(0)} \\ (\exists x \in \mathcal{H}) \quad (\forall i \in \{1, \dots, m\}) \quad g_i(x) = u^{(i)} \\ (\forall j \in \{1, \dots, q\}) \quad h_j(x) \leq u^{(m+j)} \end{array} \right\}.$$

In addition,

$$(\forall x \in \text{dom } f) \quad (f(x), g_1(x), \dots, g_m(x), h_1(x), \dots, h_q(x)) \in C_1.$$

Hence,

$$\inf_{x \in \mathcal{H}} a^{(0)} f(x) + \sum_{i=1}^m a^{(i)} g_i(x) + \sum_{j=1}^q a^{(m+j)} h_j(x) \\ = \inf_{x \in \text{dom } f} a^{(0)} f(x) + \sum_{i=1}^m a^{(i)} g_i(x) + \sum_{j=1}^q a^{(m+j)} h_j(x) \geq \sup_{u \in C_2} \langle a \mid u \rangle = a^{(0)} f(\hat{x}).$$

Validity of Slater condition

$$\begin{aligned}
 & \inf_{x \in \mathcal{H}} a^{(0)} f(x) + \sum_{i=1}^m a^{(i)} g_i(x) + \sum_{j=1}^q a^{(m+j)} h_j(x) \\
 &= \inf_{x \in \text{dom } f} a^{(0)} f(x) + \sum_{i=1}^m a^{(i)} g_i(x) + \sum_{j=1}^q a^{(m+j)} h_j(x) \geq \sup_{u \in \mathcal{C}_2} \langle a \mid u \rangle = a^{(0)} f(\hat{x}).
 \end{aligned}$$

If $a^{(0)} = 0$, then

$$\inf_{x \in \text{dom } f} \sum_{i=1}^m a^{(i)} g_i(x) + \sum_{j=1}^q a^{(m+j)} h_j(x) \geq 0.$$

This implies that $\sum_{j=1}^q a^{(m+j)} h_j(\bar{x}) \geq 0$.

Since $(\forall j \in \{1, \dots, q\}) a^{(m+j)} \geq 0$ and $h_j(\bar{x}) < 0$, then $(\forall j \in \{1, \dots, q\}) a^{(m+j)} = 0$.

We deduce that

$$(\forall x \in \text{dom } f) \quad \sum_{i=1}^m a^{(i)} g_i(x) = \sum_{i=1}^m a^{(i)} \langle v_i \mid x - \bar{x} \rangle = \left\langle \sum_{i=1}^m a^{(i)} v_i \mid x - \bar{x} \right\rangle \geq 0.$$

Since $\bar{x} \in \text{int}(\text{dom } f)$, $\sum_{i=1}^m a^{(i)} v_i = 0$ and, since $(v_i)_{1 \leq i \leq m}$ are independent vectors, $(\forall i \in \{1, \dots, m\}) a^{(i)} = 0$, which is impossible since $a \neq 0$.

Validity of Slater condition

$$\begin{aligned}
 & \inf_{x \in \mathcal{H}} a^{(0)} f(x) + \sum_{i=1}^m a^{(i)} g_i(x) + \sum_{j=1}^q a^{(m+j)} h_j(x) \\
 &= \inf_{x \in \text{dom } f} a^{(0)} f(x) + \sum_{i=1}^m a^{(i)} g_i(x) + \sum_{j=1}^q a^{(m+j)} h_j(x) \geq \sup_{u \in \mathcal{C}_2} \langle a \mid u \rangle = a^{(0)} f(\hat{x}).
 \end{aligned}$$

Hence $a^{(0)} > 0$ and, by setting

$$\begin{aligned}
 (\forall i \in \{1, \dots, m\}) \quad \hat{\nu}^{(i)} &= \frac{a^{(i)}}{a^{(0)}} \\
 (\forall j \in \{1, \dots, q\}) \quad \hat{\lambda}^{(j)} &= \frac{a^{(m+j)}}{a^{(0)}} \geq 0,
 \end{aligned}$$

$$\text{we get } \underline{\mathcal{L}}(\hat{\nu}, \hat{\lambda}) = \inf_{x \in \text{dom } f} f(x) + \sum_{i=1}^m \hat{\nu}^{(i)} g_i(x) + \sum_{j=1}^q \hat{\lambda}^{(j)} h_j(x) \geq f(\hat{x}).$$

Validity of Slater condition

Hence $a^{(0)} > 0$ and, by setting

$$\begin{aligned} (\forall i \in \{1, \dots, m\}) \quad \hat{\nu}^{(i)} &= \frac{a^{(i)}}{a^{(0)}} \\ (\forall j \in \{1, \dots, q\}) \quad \hat{\lambda}^{(j)} &= \frac{a^{(m+j)}}{a^{(0)}} \geq 0, \end{aligned}$$

we get $\underline{\mathcal{L}}(\hat{\nu}, \hat{\lambda}) = \inf_{x \in \text{dom } f} f(x) + \sum_{i=1}^m \hat{\nu}^{(i)} g_i(x) + \sum_{j=1}^q \hat{\lambda}^{(j)} h_j(x) \geq f(\hat{x})$.

Since $\sup_{\nu \in \mathbb{R}^m, \lambda \in [0, +\infty[^q} \underline{\mathcal{L}}(\nu, \lambda) \leq f(\hat{x})$, $\underline{\mathcal{L}}(\hat{\nu}, \hat{\lambda}) = f(\hat{x})$.

If $(v_i)_{1 \leq i \leq m}$ are linearly dependent, let $(v_i)_{i \in \mathbb{I} \subset \{1, \dots, m\}}$ be a maximum size subfamily of linearly independent vectors. Then the same equality holds by setting $(\forall i \in \{1, \dots, m\} \setminus \mathbb{I}) \hat{\nu}_i = 0$.

The final result follows from the previous lemma.

Validity of Fritz-John conditions

Let $J(\hat{x}) = \{j \in \{1, \dots, q\} \mid h_j(\hat{x}) = 0\}$ be the set of active inequality constraints and let $\bar{J}(\hat{x}) = \{1, \dots, q\} \setminus J(\hat{x})$.

For every $j \in \bar{J}(\hat{x})$, $h_j(\hat{x}) < 0$. Since functions $(h_j)_{1 \leq j \leq q}$ are continuous, there exists $\rho \in]0, +\infty[$ such that \hat{x} is a global minimizer of f on $B(\hat{x}, \rho)$, the open ball centered at \hat{x} and with radius ρ , and $(\forall x \in B(\hat{x}, \rho))$
 $(\forall j \in \bar{J}(\hat{x})) \ h_j(x) < 0$.

For every $\eta \in]0, +\infty[$, define

$$(\forall x \in \mathbb{R}^N) \quad f_\eta(x) = f(x) + \|x - \hat{x}\|^2 + \frac{\eta}{2} \left(\sum_{i=1}^m (g_i(x))^2 + \sum_{j \in J(\hat{x})} \max\{0, h_j(x)\}^2 \right).$$

Let $\epsilon \in]0, \rho[$. Let us first show that

$$(\exists \eta_\epsilon \in]0, +\infty[)(\forall x \in \mathbb{R}^N) \quad \|x - \hat{x}\| = \epsilon \Rightarrow f_{\eta_\epsilon}(x) > f(\hat{x}). \quad (1)$$

Validity of Fritz-John conditions

For every $\eta \in]0, +\infty[$, define

$$(\forall x \in \mathbb{R}^N) \quad f_\eta(x) = f(x) + \|x - \hat{x}\|^2 + \frac{\eta}{2} \left(\sum_{i=1}^m (g_i(x))^2 + \sum_{j \in J(\hat{x})} \max\{0, h_j(x)\}^2 \right).$$

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$$(\exists \eta_\epsilon \in]0, +\infty[)(\forall x \in \mathbb{R}^N) \quad \|x - \hat{x}\| = \epsilon \Rightarrow f_{\eta_\epsilon}(x) > f(\hat{x}). \quad (1)$$

Otherwise, we could build a sequence $(\eta_n)_{n \in \mathbb{N}}$ converging to $+\infty$ and a sequence $(x_n)_{n \in \mathbb{N}}$ such that $(\forall n \in \mathbb{N}) \quad \|x_n - \hat{x}\| = \epsilon$ and $f_{\eta_n}(x_n) \leq f(\hat{x})$, i.e.

$$f(x_n) + \epsilon^2 + \frac{\eta_n}{2} \left(\sum_{i=1}^m (g_i(x_n))^2 + \sum_{j \in J(\hat{x})} \max\{0, h_j(x_n)\}^2 \right) \leq f(\hat{x})$$

Since $(x_n)_{n \in \mathbb{N}}$ is bounded, it has a cluster point \tilde{x} . Since f , $(g_i)_{1 \leq i \leq m}$, and $(h_j)_{1 \leq j \leq q}$ are continuous and $\eta_n \rightarrow +\infty$, we deduce that

$$\sum_{i=1}^m (g_i(\tilde{x}))^2 + \sum_{j \in J(\tilde{x})} \max\{0, h_j(\tilde{x})\}^2 = 0 \quad \Rightarrow \quad \begin{cases} (\forall i \in \{1, \dots, m\}) \quad g_i(\tilde{x}) = 0 \\ (\forall j \in J(\tilde{x})) \quad h_j(\tilde{x}) \leq 0. \end{cases}$$

Since $\tilde{x} \in B(\hat{x}, \rho) \Rightarrow (\forall j \in \bar{J}(\hat{x})) \quad h_j(\tilde{x}) < 0$, this shows that $\tilde{x} \in C$.

Validity of Fritz-John conditions

For every $\eta \in]0, +\infty[$, define

$$(\forall x \in \mathbb{R}^N) \quad f_\eta(x) = f(x) + \|x - \hat{x}\|^2 + \frac{\eta}{2} \left(\sum_{i=1}^m (g_i(x))^2 + \sum_{j \in J(\hat{x})} \max\{0, h_j(x)\}^2 \right).$$

Let $\epsilon \in]0, \rho[$. Let us first show that

$$(\exists \eta_\epsilon \in]0, +\infty[)(\forall x \in \mathbb{R}^N) \quad \|x - \hat{x}\| = \epsilon \Rightarrow f_{\eta_\epsilon}(x) > f(\hat{x}). \quad (1)$$

Otherwise, we could build a sequence $(\eta_n)_{n \in \mathbb{N}}$ converging to $+\infty$ and a sequence $(x_n)_{n \in \mathbb{N}}$ such that $(\forall n \in \mathbb{N}) \quad \|x_n - \hat{x}\| = \epsilon$ and $f_{\eta_n}(x_n) \leq f(\hat{x})$, i.e.

$$f(x_n) + \epsilon^2 + \frac{\eta_n}{2} \left(\sum_{i=1}^m (g_i(x_n))^2 + \sum_{j \in J(\hat{x})} \max\{0, h_j(x_n)\}^2 \right) \leq f(\hat{x})$$

Since $(x_n)_{n \in \mathbb{N}}$ is bounded, it has a cluster point \tilde{x} . Since f , $(g_i)_{1 \leq i \leq m}$, and $(h_j)_{1 \leq j \leq q}$ are continuous and $\eta_n \rightarrow +\infty$, we deduce that $\tilde{x} \in C$ and

$$f(\tilde{x}) \leq f(\hat{x}) - \epsilon^2,$$

which contradicts the fact that \hat{x} minimizes f over $B(\hat{x}, \rho)$.

Validity of Fritz-John conditions

For every $\eta \in]0, +\infty[$, define

$$(\forall x \in \mathbb{R}^N) \quad f_\eta(x) = f(x) + \|x - \hat{x}\|^2 + \frac{\eta}{2} \left(\sum_{i=1}^m (g_i(x))^2 + \sum_{j \in J(\hat{x})} \max\{0, h_j(x)\}^2 \right).$$

Let $\epsilon \in]0, \rho[$. We have shown that

$$(\exists \eta_\epsilon \in]0, +\infty[)(\forall x \in \mathbb{R}^N) \quad \|x - \hat{x}\| = \epsilon \Rightarrow f_{\eta_\epsilon}(x) > f(\hat{x}). \quad (1)$$

Since $\overline{B}(\hat{x}, \epsilon)$ is a compact set and f_{η_ϵ} is continuous, f_{η_ϵ} admits a minimizer \hat{x}_ϵ on $\overline{B}(\hat{x}, \epsilon)$.

We have thus $f(\hat{x}_\epsilon) \leq f(\hat{x})$ and we deduce from (1) that $\hat{x}_\epsilon \in B(\hat{x}, \epsilon)$.

Since f , $(g_i)_{1 \leq i \leq m}$ and $(h_j)_{1 \leq j \leq q}$ are differentiable, a necessary first-order condition is

$$\nabla f_{\eta_\epsilon}(\hat{x}_\epsilon) = 0.$$

Validity of Fritz-John conditions

For every $\eta \in]0, +\infty[$, define

$$(\forall x \in \mathbb{R}^N) \quad f_\eta(x) = f(x) + \|x - \hat{x}\|^2 + \frac{\eta}{2} \left(\sum_{i=1}^m (g_i(x))^2 + \sum_{j \in J(\hat{x})} \max\{0, h_j(x)\}^2 \right).$$

We have

$$\nabla f_{\eta_\epsilon}(\hat{x}_\epsilon) = 0$$

$$\Leftrightarrow \nabla f(\hat{x}_\epsilon) + 2(\hat{x}_\epsilon - \hat{x}) + \eta_\epsilon \left(\sum_{i=1}^m g_i(\hat{x}_\epsilon) \nabla g_i(\hat{x}_\epsilon) + \sum_{j \in J(\hat{x})} \max\{0, h_j(\hat{x}_\epsilon)\} \nabla h_j(\hat{x}_\epsilon) \right) = 0.$$

Let $a_\epsilon = (1, a_\epsilon^{(1)}, \dots, a_\epsilon^{(m)}, a_\epsilon^{(m+1)}, \dots, a_\epsilon^{(m+q)}) \in \mathbb{R}^{m+q+1}$ with

$$(\forall i \in \{1, \dots, m\}) \quad a_\epsilon^{(i)} = \eta_\epsilon g_i(\hat{x}_\epsilon)$$

$$(\forall j \in \{1, \dots, q\}) \quad a_\epsilon^{(j+m)} = \begin{cases} \eta_\epsilon \max\{0, h_j(\hat{x}_\epsilon)\} & \text{if } j \in J(\hat{x}) \\ 0 & \text{otherwise.} \end{cases}$$

We get

$$\nabla f(\hat{x}_\epsilon) + 2(\hat{x}_\epsilon - \hat{x}) + \sum_{i=1}^m a_\epsilon^{(i)} \nabla g_i(\hat{x}_\epsilon) + \sum_{j=1}^q a_\epsilon^{(j+m)} \nabla h_j(\hat{x}_\epsilon) = 0.$$

Validity of Fritz-John conditions

Let $a_\epsilon = (1, a_\epsilon^{(1)}, \dots, a_\epsilon^{(m)}, a_\epsilon^{(m+1)}, \dots, a_\epsilon^{(m+q)}) \in \mathbb{R}^{m+q+1}$ with

$$\begin{aligned} (\forall i \in \{1, \dots, m\}) \quad a_\epsilon^{(i)} &= \eta_\epsilon g_i(\hat{x}_\epsilon) \\ (\forall j \in \{1, \dots, q\}) \quad a_\epsilon^{(j+m)} &= \begin{cases} \eta_\epsilon \max\{0, h_j(\hat{x}_\epsilon)\} & \text{if } j \in J(\hat{x}) \\ 0 & \text{otherwise.} \end{cases} \end{aligned}$$

We get

$$\nabla f(\hat{x}_\epsilon) + 2(\hat{x}_\epsilon - \hat{x}) + \sum_{i=1}^m a_\epsilon^{(i)} \nabla g_i(\hat{x}_\epsilon) + \sum_{j=1}^q a_\epsilon^{(j+m)} \nabla h_j(\hat{x}_\epsilon) = 0.$$

Let $\alpha_\epsilon = a_\epsilon / \|a_\epsilon\|$.

Consider now a sequence $(\epsilon_n)_{n \in \mathbb{N}}$ of $]0, \rho[$ converging to 0.

Then $\hat{x}_{\epsilon_n} \rightarrow \hat{x}$, which implies that $(\hat{x}_{\epsilon_n} - \hat{x}) / \|a_{\epsilon_n}\| \rightarrow 0$ (since $\|a_{\epsilon_n}\| \geq 1$).

In addition, $(\alpha_{\epsilon_n})_{n \in \mathbb{N}}$ being bounded, there exists a subsequence $(\alpha_{\epsilon_{n_k}})_{k \in \mathbb{N}}$ converging to some $\alpha = (\alpha^{(i)})_{0 \leq i \leq m+q}$. It follows from the continuity of ∇f , $(\nabla g_i)_{1 \leq i \leq m}$, and $(\nabla h_j)_{1 \leq j \leq q}$ that

$$\alpha^{(0)} \nabla f(\hat{x}) + \sum_{i=1}^m \alpha^{(i)} \nabla g_i(\hat{x}) + \sum_{j=1}^q \alpha^{(m+j)} \nabla h_j(\hat{x}) = 0.$$

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It can be finally observed that, for every $j \in \bar{J}(\hat{x})$, $\alpha^{(j+m)} = 0$, which means that the complementarity condition is satisfied.