

**CentraleSupélec**  
**ST7 – Optimization**  
**Part VII: Lagrange multipliers method**

jean-christophe@pesquet.eu

# Constrained optimization problem

Let  $\mathcal{H}$  be a Hilbert space. Let  $f: \mathcal{H} \rightarrow ]-\infty, +\infty]$ .

Let  $(m, q) \in \mathbb{N}^2$ . For every  $i \in \{1, \dots, m\}$ , let  $g_i: \mathcal{H} \rightarrow \mathbb{R}$  and for every  $j \in \{1, \dots, q\}$ , let  $h_j: \mathcal{H} \rightarrow \mathbb{R}$ .

Let

*constrains.*

$$C = \{x \in \mathcal{H} \mid (\forall i \in \{1, \dots, m\}) \ g_i(x) = 0 \\ (\forall j \in \{1, \dots, q\}) \ h_j(x) \leq 0\}.$$

We want to:

$$\text{Find } \hat{x} \in \underset{x \in C}{\text{Argmin}} \ f(x).$$

Remark: A vector  $x \in \mathcal{H}$  is said to be **feasible** if  $x \in \text{dom } f \cap C$ .

# Definitions

The **Lagrange function** (or Lagrangian) associated with the previous problem is defined as

$$(\forall x \in \mathcal{H})(\forall \nu = (\nu^{(i)})_{1 \leq i \leq m} \in \mathbb{R}^m)(\forall \lambda = (\lambda^{(j)})_{1 \leq j \leq q} \in [0, +\infty[^q)$$

$$\mathcal{L}(x, \nu, \lambda) = f(x) + \sum_{i=1}^m \nu^{(i)} g_i(x) + \sum_{j=1}^q \lambda^{(j)} h_j(x).$$

The vectors  $\nu$  and  $\lambda$  are called **Lagrange multipliers**.

Remark:

►  $\text{dom } \mathcal{L} = \text{dom } f \times \mathbb{R}^m \times [0, +\infty[^q.$

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Remark:

- ▶ When  $q = 0$  (**only equality constraints**), the Lagrange function simplifies to

$$(\forall x \in \mathcal{H})(\forall \nu = (\nu^{(i)})_{1 \leq i \leq m} \in \mathbb{R}^m) \quad \mathcal{L}(x, \nu) = f(x) + \sum_{i=1}^m \nu^{(i)} g_i(x).$$

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# Lagrange duality

Let  $\bar{\mathcal{L}}$  be the **primal Lagrange function** defined as

$$(\forall x \in \mathcal{H}) \quad \bar{\mathcal{L}}(x) = \sup_{\nu \in \mathbb{R}^m, \lambda \in [0, +\infty[^q} \mathcal{L}(x, \nu, \lambda).$$

Then, for every  $x \in C$ ,  $\bar{\mathcal{L}}(x) = f(x)$ .

Proof: For every  $(x, \nu, \lambda) \in C \times \mathbb{R}^m \times [0, +\infty[^q$

$$\mathcal{L}(x, \nu, \lambda) = f(x) + \sum_{i=1}^m \underbrace{\nu^{(i)} g_i(x)}_{=0} + \sum_{j=1}^q \underbrace{\lambda^{(j)} h_j(x)}_{\leq 0} \leq f(x)$$

and  $\bar{\mathcal{L}}(x) = \sup_{\nu \in \mathbb{R}^m, \lambda \in [0, +\infty[^q} \mathcal{L}(x, \nu, \lambda) = f(x)$ .

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Then, for every  $x \in C$ ,  $\bar{\mathcal{L}}(x) = f(x)$ .


Let  $\underline{\mathcal{L}}$  be the dual Lagrange function defined as

$$(\forall (\nu, \lambda) \in \mathbb{R}^m \times [0, +\infty[^q) \quad \underline{\mathcal{L}}(\nu, \lambda) = \inf_{x \in \mathcal{H}} \mathcal{L}(x, \nu, \lambda)$$

Then,  $-\underline{\mathcal{L}}$  is convex and s.c.i.

# Lagrange duality

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Then,  $-\underline{\mathcal{L}}$  is convex and s.c.i.

Proof: For every  $(\nu, \lambda) \in \mathbb{R}^m \times [0, +\infty[^q$ ,

$$-\underline{\mathcal{L}}(\nu, \lambda) = \sup_{x \in \text{dom } f} (-\mathcal{L}(x, \nu, \lambda)).$$

$-\underline{\mathcal{L}}$  is thus the supremum of a set of affine functions.



# Lagrange duality

For every  $(x, \nu, \lambda) \in \mathcal{H} \times \mathbb{R}^m \times [0, +\infty[^q$ ,

$$\underline{\mathcal{L}}(\nu, \lambda) \leq \overline{\mathcal{L}}(x).$$

*weak  
strong.*

In addition,

$$\sup_{\nu \in \mathbb{R}^m, \lambda \in [0, +\infty[^q} \underline{\mathcal{L}}(\nu, \lambda) \leq \mu = \inf_{x \in \mathcal{C}} f(x).$$

# Lagrange duality

For every  $(x, \nu, \lambda) \in \mathcal{H} \times \mathbb{R}^m \times [0, +\infty[^q$ ,

$$\underline{\mathcal{L}}(\nu, \lambda) \leq \overline{\mathcal{L}}(x).$$

In addition,

$$\sup_{\nu \in \mathbb{R}^m, \lambda \in [0, +\infty[^q} \underline{\mathcal{L}}(\nu, \lambda) \leq \mu = \inf_{x \in C} f(x).$$

Proof: We have, for every  $(x, \nu, \lambda) \in \mathcal{H} \times \mathbb{R}^m \times [0, +\infty[^q$ ,

$$\inf_{x'} \mathcal{L}(x', \nu, \lambda) \leq \mathcal{L}(x, \nu, \lambda) \leq \sup_{\nu', \lambda'} \mathcal{L}(x, \nu', \lambda')$$

$$\Rightarrow \underline{\mathcal{L}}(\nu, \lambda) \leq \overline{\mathcal{L}}(x).$$

We deduce that, for every  $x \in C$ ,  $\underline{\mathcal{L}}(\nu, \lambda) \leq \overline{\mathcal{L}}(x) = f(x)$ , which yields the last inequality.

## Saddle points 鞍点.

$(\hat{x}, \hat{\nu}, \hat{\lambda}) \in \mathcal{H} \times \mathbb{R}^m \times [0, +\infty]^q$  is a saddle point of  $\mathcal{L}$  if

$$(\forall (x, \nu, \lambda) \in \mathcal{H} \times \mathbb{R}^m \times [0, +\infty]^q) \quad \mathcal{L}(\hat{x}, \nu, \lambda) \leq \mathcal{L}(\hat{x}, \hat{\nu}, \hat{\lambda}) \leq \mathcal{L}(x, \hat{\nu}, \hat{\lambda}).$$

Remark: If there exists a feasible point and  $(\hat{x}, \hat{\nu}, \hat{\lambda})$  is a saddle point of  $\mathcal{L}$ , then it follows from the right inequality that  $\hat{x} \in \text{dom } f$ .

# Saddle points

$(\hat{x}, \hat{\nu}, \hat{\lambda}) \in \mathcal{H} \times \mathbb{R}^m \times [0, +\infty[^q$  is a **saddle point** of  $\mathcal{L}$  if

$$(\forall (x, \nu, \lambda) \in \mathcal{H} \times \mathbb{R}^m \times [0, +\infty[^q) \quad \mathcal{L}(\hat{x}, \nu, \lambda) \leq \mathcal{L}(\hat{x}, \hat{\nu}, \hat{\lambda}) \leq \mathcal{L}(x, \hat{\nu}, \hat{\lambda}).$$

## Theorem

$(\hat{x}, \hat{\nu}, \hat{\lambda}) \in \mathcal{H} \times \mathbb{R}^m \times [0, +\infty[^q$  is a saddle point of  $\mathcal{L}$  if and only if

$$(\forall x \in \mathcal{H}) \quad \overline{\mathcal{L}}(\hat{x}) \leq \overline{\mathcal{L}}(x)$$

$$(\forall (\nu, \lambda) \in \mathbb{R}^m \times [0, +\infty[^q) \quad \underline{\mathcal{L}}(\nu, \lambda) \leq \underline{\mathcal{L}}(\hat{\nu}, \hat{\lambda})$$

$$\overline{\mathcal{L}}(\hat{x}) = \underline{\mathcal{L}}(\hat{\nu}, \hat{\lambda}).$$

## Saddle points

Proof: If  $(\hat{x}, \hat{\nu}, \hat{\lambda})$  is a saddle point of  $\mathcal{L}$  then, for every  $(x', \nu', \lambda') \in \mathcal{H} \times \mathbb{R}^m \times [0, +\infty[^q$ ,

$$\begin{aligned} \mathcal{L}(\hat{x}, \nu', \lambda') &\leq \mathcal{L}(\hat{x}, \hat{\nu}, \hat{\lambda}) \leq \mathcal{L}(x', \hat{\nu}, \hat{\lambda}) \\ \Rightarrow \sup_{\nu', \lambda'} \mathcal{L}(\hat{x}, \nu', \lambda') &\leq \inf_{x'} \mathcal{L}(x', \hat{\nu}, \hat{\lambda}) \\ \Leftrightarrow \overline{\mathcal{L}}(\hat{x}) &\leq \underline{\mathcal{L}}(\hat{\nu}, \hat{\lambda}) \\ \Rightarrow \inf_x \overline{\mathcal{L}}(x) &\leq \overline{\mathcal{L}}(\hat{x}) \leq \underline{\mathcal{L}}(\hat{\nu}, \hat{\lambda}) \leq \sup_{\nu, \lambda} \underline{\mathcal{L}}(\nu, \lambda). \end{aligned}$$

In addition

$$\sup_{\nu, \lambda} \underline{\mathcal{L}}(\nu, \lambda) \leq \inf_x \overline{\mathcal{L}}(x).$$

Therefore,  $\inf_x \overline{\mathcal{L}}(x) = \sup_{\nu, \lambda} \underline{\mathcal{L}}(\nu, \lambda)$ .

We deduce that  $\overline{\mathcal{L}}(\hat{x}) = \inf_x \overline{\mathcal{L}}(x)$ ,  $\underline{\mathcal{L}}(\hat{\nu}, \hat{\lambda}) = \sup_{\nu, \lambda} \underline{\mathcal{L}}(\nu, \lambda)$ , and  $\overline{\mathcal{L}}(\hat{x}) = \underline{\mathcal{L}}(\hat{\nu}, \hat{\lambda})$ .

## Saddle points

Proof: Conversely, if the last condition holds, then

$$\begin{aligned}\mathcal{L}(\hat{x}, \hat{\nu}, \hat{\lambda}) &\leq \sup_{\nu, \lambda} \mathcal{L}(\hat{x}, \nu, \lambda) = \overline{\mathcal{L}}(\hat{x}) \\ &= \underline{\mathcal{L}}(\hat{\nu}, \hat{\lambda}) = \inf_x \mathcal{L}(x, \hat{\nu}, \hat{\lambda}).\end{aligned}$$

Similarly,

$$\begin{aligned}\mathcal{L}(\hat{x}, \hat{\nu}, \hat{\lambda}) &\geq \inf_x \mathcal{L}(x, \hat{\nu}, \hat{\lambda}) = \underline{\mathcal{L}}(\hat{\nu}, \hat{\lambda}) \\ &= \overline{\mathcal{L}}(\hat{x}) = \sup_{\nu, \lambda} \mathcal{L}(\hat{x}, \nu, \lambda).\end{aligned}$$

In conclusion, for every  $(x, \nu, \lambda) \in \mathcal{H} \times \mathbb{R}^m \times [0, +\infty[^q$ ,

$$\mathcal{L}(\hat{x}, \nu, \lambda) \leq \mathcal{L}(\hat{x}, \hat{\nu}, \hat{\lambda}) \leq \mathcal{L}(x, \hat{\nu}, \hat{\lambda}).$$

## Sufficient condition for a constrained minimum

Assume that there exists a feasible point. 充分条件.

If  $(\hat{x}, \hat{\nu}, \hat{\lambda}) \in \mathcal{H} \times \mathbb{R}^m \times [0, +\infty[^q$  is a saddle point of  $\mathcal{L}$ ,  
then  $\hat{x}$  is a minimizer of  $f$  over  $C$ .

In addition,  $\mu = f(\hat{x}) = \underline{\mathcal{L}}(\hat{\nu}, \hat{\lambda})$  and the complementary slackness condition holds:

$$(\forall j \in \{1, \dots, q\}) \quad \hat{\lambda}_j h_j(\hat{x}) = 0.$$

# Sufficient condition for a constrained minimum

Assume that there exists a feasible point.

If  $(\hat{x}, \hat{\nu}, \hat{\lambda}) \in \mathcal{H} \times \mathbb{R}^m \times [0, +\infty[^q$  is a saddle point of  $\mathcal{L}$ , then  $\hat{x}$  is a minimizer of  $f$  over  $C$ .

In addition,  $\mu = f(\hat{x}) = \underline{\mathcal{L}}(\hat{\nu}, \hat{\lambda})$  and the complementary slackness condition holds:

$$(\forall j \in \{1, \dots, q\}) \quad \hat{\lambda}_j h_j(\hat{x}) = 0.$$

Proof: We know that  $\hat{x} \in \text{dom } f$ . We have, for every

$$(\nu, \lambda) \in \mathbb{R}^m \times [0, +\infty[^q, \quad \mathcal{L}(\hat{x}, \nu, \lambda) \leq \mathcal{L}(\hat{x}, \hat{\nu}, \hat{\lambda}).$$

For every  $\nu' = (\nu'^{(i)})_{1 \leq i \leq m} \in \mathbb{R}^m$  by setting  $\nu = \hat{\nu} + \nu'$  and  $\lambda = \hat{\lambda}$ ,

$$\sum_{i=1}^m \nu'^{(i)} g_i(\hat{x}) \leq 0$$

and, for every  $\lambda' = (\lambda'^{(j)})_{1 \leq j \leq q} \in [0, +\infty[^q$ , by setting  $\nu = \hat{\nu}$  and  $\lambda = \hat{\lambda} + \lambda'$ ,

$$\sum_{j=1}^q \lambda'^{(j)} h_j(\hat{x}) \leq 0.$$

We deduce that  $\begin{cases} (\forall i \in \{1, \dots, m\}) & g_i(\hat{x}) = 0 \\ (\forall j \in \{1, \dots, q\}) & h_j(\hat{x}) \leq 0, \end{cases}$  i.e.  $\hat{x} \in C$ .



## Sufficient condition for a constrained minimum

Assume that there exists a feasible point.

If  $(\hat{x}, \hat{\nu}, \hat{\lambda}) \in \mathcal{H} \times \mathbb{R}^m \times [0, +\infty[^q$  is a saddle point of  $\mathcal{L}$ , then  $\hat{x}$  is a minimizer of  $f$  over  $C$ .

In addition,  $\mu = f(\hat{x}) = \underline{\mathcal{L}}(\hat{\nu}, \hat{\lambda})$  and the **complementary slackness** condition holds:

$$(\forall j \in \{1, \dots, q\}) \quad \hat{\lambda}_j h_j(\hat{x}) = 0.$$

Proof: We have shown that  $(\forall i \in \{1, \dots, m\}) \ g_i(\hat{x}) = 0$  and  $(\forall j \in \{1, \dots, q\}) \ h_j(\hat{x}) \leq 0 \Rightarrow \hat{\lambda}_j h_j(\hat{x}) \leq 0$ .

Then, since

$$\mathcal{L}(\hat{x}, \hat{\nu}, 0) \leq \mathcal{L}(\hat{x}, \hat{\nu}, \hat{\lambda}),$$

we have

$$\sum_{j=1}^m \hat{\lambda}_j h_j(\hat{x}) \geq 0,$$

which implies that the complementary slackness condition holds.

## Sufficient condition for a constrained minimum

Assume that there exists a feasible point.

If  $(\hat{x}, \hat{\nu}, \hat{\lambda}) \in \mathcal{H} \times \mathbb{R}^m \times [0, +\infty[^q$  is a saddle point of  $\mathcal{L}$ , then  $\hat{x}$  is a minimizer of  $f$  over  $C$ .

In addition,  $\mu = f(\hat{x}) = \underline{\mathcal{L}}(\hat{\nu}, \hat{\lambda})$  and the complementary slackness condition holds:

$$(\forall j \in \{1, \dots, q\}) \quad \hat{\lambda}_j h_j(\hat{x}) = 0.$$

Proof: As  $\hat{x} \in C$  and the complementary slackness condition holds,  $\mathcal{L}(\hat{x}, \hat{\nu}, \hat{\lambda}) = f(\hat{x})$ . Furthermore,

$$\begin{aligned} (\forall x \in C) \quad \mathcal{L}(\hat{x}, \hat{\nu}, \hat{\lambda}) &\leq \mathcal{L}(x, \hat{\nu}, \hat{\lambda}) \\ \Leftrightarrow f(\hat{x}) &\leq f(x) + \sum_{i=1}^m \hat{\nu}_i g_i(x) + \sum_{j=1}^q \hat{\lambda}_j h_j(x) \leq f(x). \end{aligned}$$

Finally, as a consequence of previous results,  $f(\hat{x}) = \bar{\mathcal{L}}(\hat{x}) = \underline{\mathcal{L}}(\hat{\nu}, \hat{\lambda})$ .

## Convex case

Assume that  $f$  is a convex function,  $(g_i)_{1 \leq i \leq m}$  are affine functions and  $(h_j)_{1 \leq j \leq q}$  are convex functions. Assume that the **Slater condition** holds, i.e. there exists  $\bar{x} \in \text{int}(\text{dom } f)$  such that

$$\begin{aligned} (\forall i \in \{1, \dots, m\}) \quad & g_i(\bar{x}) = 0 \\ (\forall j \in \{1, \dots, q\}) \quad & h_j(\bar{x}) < 0. \end{aligned}$$

If  $\hat{x}$  is a minimizer of  $f$  over  $C$ , then there exists  $\hat{\nu} \in \mathbb{R}^m$  and  $\hat{\lambda} \in [0, +\infty[^q$  such that  $(\hat{x}, \hat{\nu}, \hat{\lambda})$  is a saddle point of the Lagrangian.

## Convex case

Assume that  $f$  is a convex function,  $(g_i)_{1 \leq i \leq m}$  are affine functions and  $(h_j)_{1 \leq j \leq q}$  are convex functions. Assume that the Slater condition holds, i.e. there exists  $\bar{x} \in \text{int}(\text{dom } f)$  such that

$$\begin{aligned} (\forall i \in \{1, \dots, m\}) \quad & g_i(\bar{x}) = 0 \\ (\forall j \in \{1, \dots, q\}) \quad & h_j(\bar{x}) < 0. \end{aligned}$$

$\hat{x}$  is a minimizer of  $f$  over  $C$  if and only if there exists  $\hat{\nu} \in \mathbb{R}^m$  and  $\hat{\lambda} \in [0, +\infty[^q$  such that  $(\hat{x}, \hat{\nu}, \hat{\lambda})$  is a saddle point of the Lagrangian.

Proof: Combine the two previous results.

## Convex case

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$\hat{x}$  is a minimizer of  $f$  over  $C$  if and only if there exists  $\hat{\nu} \in \mathbb{R}^m$  and  $\hat{\lambda} \in [0, +\infty[^q$  such that  $(\hat{x}, \hat{\nu}, \hat{\lambda})$  is a saddle point of the Lagrangian.

Remark: Under the assumptions of the above theorem, if  $\hat{x}$  is a minimizer of  $f$  over  $C$  then  $\mathcal{L}(\cdot, \hat{\nu}, \hat{\lambda})$  is a convex function which is minimum at  $\hat{x}$ . This optimality condition is often used to calculate  $\hat{x}$ , in conjunction with the equality constraints and the complementary slackness condition.

## Convex case

Only equality constraints:

Assume that  $f$  is a convex function and  $(g_i)_{1 \leq i \leq m}$  are affine functions. Assume that the Slater condition holds, i.e. there exists  $\bar{x} \in \text{int}(\text{dom } f)$  such that

$$(\forall i \in \{1, \dots, m\}) \quad g_i(\bar{x}) = 0.$$

$\hat{x}$  is a minimizer of  $f$  over  $C$  if and only if there exists  $\hat{\nu} \in \mathbb{R}^m$  such that  $(\hat{x}, \hat{\nu})$  is a saddle point of the Lagrangian.

## Convex case

Only inequality constraints:

Assume that  $f$  is a convex function, and  $(h_j)_{1 \leq j \leq q}$  are convex functions. Assume that the Slater condition holds, i.e. there exists  $\bar{x} \in \text{dom } f$  such that

$$(\forall j \in \{1, \dots, q\}) \quad h_j(\bar{x}) < 0.$$

$\hat{x}$  is a minimizer of  $f$  over  $C$  if and only if there exists  $\hat{\lambda} \in [0, +\infty[^q$  such that  $(\hat{x}, \hat{\lambda})$  is a saddle point of the Lagrangian.

## Exercise 1

One wants to minimize the production cost of a factory.

The factory produces cars in quantity  $x_1$  and trucks in quantity  $x_2$ . The production of cars and trucks require  $\psi_1(x_1)$  and  $\psi_2(x_2)$  machine tools, respectively. The overall number of used machine tools is equal to  $c$ . The production costs of cars and trucks are equal to  $\varphi_1(x_1)$  and  $\varphi_2(x_2)$ , respectively.

Solve this problem by the Lagrange multiplier method, when

$$\varphi_1(x_1) = (x_1 - 100)^2$$

$$\varphi_2(x_2) = 2(x_2 - 50)^2$$

$$\psi_1(x_1) = x_1$$

$$\psi_2(x_2) = x_2$$

$$c = 90.$$



## Exercise 2

Let  $f$  be defined as

$$(\forall x \in \mathbb{R}^N) \quad f(x) = \frac{1}{2}x^\top Qx + c^\top x.$$

where  $Q \in \mathbb{R}^{N \times N}$  is a definite positive matrix and  $c \in \mathbb{R}^N$ .

We are interested in finding a minimizer of  $f$  subject to the constraint:

$$Ax = b$$

where  $A \in \mathbb{R}^{m \times N}$  is a matrix of rank  $m$  and  $b \in \mathbb{R}^m$ .

1. Show that the problem has a unique solution.
2. By using the Lagrange multipliers method, find the expression of the solution.

## Exercise 3

Let  $f$  be defined as

$$(\forall x = (x^{(i)})_{1 \leq i \leq N} \in [0, +\infty[^N) \quad f(x) = \sum_{i=1}^N x^{(i)} \ln(x^{(i)}),$$

with  $N > 1$ . Find a minimizer of  $f$  on  $[0, +\infty[^N$  subject to the constraints

$$\begin{aligned} \sum_{i=1}^N x^{(i)} &= 1 \\ \sum_{i=1}^P x^{(i)} &= q, \end{aligned}$$

where  $P \in \{1, \dots, N-1\}$  and  $q \in ]0, 1[$ .

## Differentiable case 可微.

Assume that  $f$ ,  $(g_i)_{1 \leq i \leq m}$ , and  $(h_j)_{1 \leq j \leq q}$  are continuously differentiable on  $\mathcal{H} = \mathbb{R}^N$ .

If  $\hat{x}$  is a local minimum of  $f$  over  $C$  then the **Fritz-John conditions** hold, i.e. there exists a nonzero vector  $(\alpha_0, \alpha_1, \dots, \alpha_m, \alpha_{m+1}, \dots, \alpha_{m+q}) \in [0, +\infty[ \times \mathbb{R}^m \times [0, +\infty[^q$  such that

$$\alpha_0 \nabla f(\hat{x}) + \sum_{i=1}^m \alpha_i \nabla g_i(\hat{x}) + \sum_{j=1}^q \alpha_{m+j} \nabla h_j(\hat{x}) = 0$$

$$(\forall j \in \{1, \dots, q\}) \quad \alpha_{m+j} h_j(\hat{x}) = 0.$$

# Differentiable case

## Karush-Kuhn-Tucker (KKT) theorem

Assume that  $f$ ,  $(g_i)_{1 \leq i \leq m}$ , and  $(h_j)_{1 \leq j \leq q}$  are continuously differentiable on  $\mathcal{H} = \mathbb{R}^N$ .

Assume that  $\hat{x}$  is a local minimizer of  $f$  over  $C$  satisfying the following Mangasarian-Fromovitz **constraint qualification conditions** :

- (i)  $\{\nabla g_i(\hat{x}) \mid i \in \{1, \dots, m\}\}$  is a family of linearly independent vectors;
- (ii) there exists  $z \in \mathbb{R}^N$  such that

$$\begin{aligned} (\forall i \in \{1, \dots, m\}) \quad & \langle \nabla g_i(\hat{x}) \mid z \rangle = 0 \\ (\forall j \in J(\hat{x})) \quad & \langle \nabla h_j(\hat{x}) \mid z \rangle < 0 \end{aligned}$$

where  $J(\hat{x}) = \{j \in \{1, \dots, q\} \mid h_j(\hat{x}) = 0\}$  is the set of **active inequality constraints** at  $\hat{x}$ .

Then, there exists  $\hat{\nu} \in \mathbb{R}^N$  and  $\hat{\lambda} \in [0, +\infty[^q$  such that  $\hat{x}$  is a critical point of  $\mathcal{L}(\cdot, \hat{\nu}, \hat{\lambda})$  and the complementary slackness condition holds.

## Differentiable case

Proof: We know that there exists a nonzero vector

$(\alpha_0, \alpha_1, \dots, \alpha_m, \alpha_{m+1}, \dots, \alpha_{m+q}) \in [0, +\infty[ \times \mathbb{R}^m \times [0, +\infty[^q$  such that

$$\alpha_0 \nabla f(\hat{x}) + \sum_{i=1}^m \alpha_i \nabla g_i(\hat{x}) + \sum_{j=1}^q \alpha_{m+j} \nabla h_j(\hat{x}) = 0$$

$$(\forall j \in \{1, \dots, q\}) \quad \alpha_{m+j} h_j(\hat{x}) = 0.$$

The complementary slackness condition implies that  $(\forall j \notin J(\hat{x})) \alpha_{m+j} = 0$  and the first equality reduces to

$$\alpha_0 \nabla f(\hat{x}) + \sum_{i=1}^m \alpha_i \nabla g_i(\hat{x}) + \sum_{j \in J(\hat{x})} \alpha_{m+j} \nabla h_j(\hat{x}) = 0$$

which yields

$$\alpha_0 \langle \nabla f(\hat{x}) \mid z \rangle + \sum_{i=1}^m \alpha_i \langle \nabla g_i(\hat{x}) \mid z \rangle + \sum_{j \in J(\hat{x})} \alpha_{m+j} \langle \nabla h_j(\hat{x}) \mid z \rangle = 0$$

$$\Leftrightarrow \alpha_0 \langle \nabla f(\hat{x}) \mid z \rangle + \sum_{j \in J(\hat{x})} \alpha_{m+j} \langle \nabla h_j(\hat{x}) \mid z \rangle = 0.$$

## Differentiable case

Proof: We have proved that there exists a nonzero vector

$(\alpha_0, \alpha_1, \dots, \alpha_m, \alpha_{m+1}, \dots, \alpha_{m+q}) \in [0, +\infty[ \times \mathbb{R}^m \times [0, +\infty[^q$  such that

$$\alpha_0 \nabla f(\hat{x}) + \sum_{i=1}^m \alpha_i \nabla g_i(\hat{x}) + \sum_{j \in J(\hat{x})} \alpha_{m+j} \nabla h_j(\hat{x}) = 0$$

$$\alpha_0 \langle \nabla f(\hat{x}) \mid z \rangle + \sum_{j \in J(\hat{x})} \alpha_{m+j} \langle \nabla h_j(\hat{x}) \mid z \rangle = 0.$$

Let us suppose that  $\alpha_0 = 0$ .

Since, for every  $j \in J(\hat{x})$ ,  $\langle \nabla h_j(\hat{x}) \mid z \rangle < 0$ , in the latter equality, we would have,  $\alpha_{m+j} = 0$  which, in the first equality, would lead to

$$\sum_{i=1}^m \alpha_i \nabla g_i(\hat{x}) = 0.$$

Since the vectors  $(\nabla g_i(\hat{x}))_{1 \leq i \leq m}$  are linearly independent,  $(\forall i \in \{1, \dots, m\}) \alpha_i = 0$ .

In conclusion, the vector  $(\alpha_i)_{1 \leq i \leq q}$  would be zero, which is impossible.

This shows that  $\alpha_0 > 0$ .

## Differentiable case

By defining  $(\forall i \in \{1, \dots, m\}) \hat{\nu}_i = \alpha_i / \alpha_0$ ,  $(\forall j \in \{1, \dots, q\}) \hat{\lambda}_j = \alpha_{m+j} / \alpha_0 \geq 0$ , we have then

$$\nabla f(\hat{x}) + \sum_{i=1}^m \hat{\nu}_i \nabla g_i(\hat{x}) + \sum_{j=1}^q \hat{\lambda}_j \nabla h_j(\hat{x}) = 0$$

$$(\forall j \in \{1, \dots, q\}) \quad \hat{\lambda}_j h_j(\hat{x}) = 0.$$

By setting  $\hat{\nu} = (\hat{\nu}_i)_{1 \leq i \leq m} \in \mathbb{R}^m$  and  $\hat{\lambda} = (\hat{\lambda}_j)_{1 \leq j \leq q} \in [0, +\infty[^q$ , the first equality also reads

$$\nabla_x \mathcal{L}(\hat{x}, \hat{\nu}, \hat{\lambda}) = 0.$$

## Differentiable case

### Karush-Kuhn-Tucker (KKT) theorem

Assume that  $f$ ,  $(g_i)_{1 \leq i \leq m}$ , and  $(h_j)_{1 \leq j \leq q}$  are continuously differentiable on  $\mathcal{H} = \mathbb{R}^N$ .

Assume that  $\hat{x}$  is a local minimizer of  $f$  over  $C$  satisfying the following Mangasarian-Fromovitz **constraint qualification conditions** :

- (i)  $\{\nabla g_i(\hat{x}) \mid i \in \{1, \dots, m\}\}$  is a family of linearly independent vectors;
- (ii) there exists  $z \in \mathbb{R}^N$  such that

$$\begin{aligned} (\forall i \in \{1, \dots, m\}) \quad & \langle \nabla g_i(\hat{x}) \mid z \rangle = 0 \\ (\forall j \in J(\hat{x})) \quad & \langle \nabla h_j(\hat{x}) \mid z \rangle < 0 \end{aligned}$$

where  $J(\hat{x}) = \{j \in \{1, \dots, q\} \mid h_j(\hat{x}) = 0\}$  is the set of **active inequality constraints** at  $\hat{x}$ .

Then, there exists  $\hat{\nu} \in \mathbb{R}^N$  and  $\hat{\lambda} \in [0, +\infty[^q$  such that  $\hat{x}$  is a critical point of  $\mathcal{L}(\cdot, \hat{\nu}, \hat{\lambda})$  and the complementary slackness condition holds.

Remark: A sufficient condition for Mangasarian-Fromovitz conditions to be satisfied is that  $\{\nabla g_i(\hat{x}) \mid i \in \{1, \dots, m\}\} \cup \{\nabla h_j(\hat{x}) \mid j \in J(\hat{x})\}$  is a family of linearly independent vectors.



# Differentiable case

## Karush-Kuhn-Tucker (KKT) theorem

Assume that  $f$ ,  $(g_i)_{1 \leq i \leq m}$ , and  $(h_j)_{1 \leq j \leq q}$  are continuously differentiable on  $\mathcal{H} = \mathbb{R}^N$ .

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- (i)  $\{\nabla g_i(\hat{x}) \mid i \in \{1, \dots, m\}\}$  is a family of linearly independent vectors;
- (ii) there exists  $z \in \mathbb{R}^N$  such that

$$\begin{aligned} (\forall i \in \{1, \dots, m\}) \quad & \langle \nabla g_i(\hat{x}) \mid z \rangle = 0 \\ (\forall j \in J(\hat{x})) \quad & \langle \nabla h_j(\hat{x}) \mid z \rangle < 0. \end{aligned}$$

Then, there exists  $\hat{\nu} \in \mathbb{R}^m$  and  $\hat{\lambda} \in [0, +\infty[^q$  such that  $\hat{x}$  is a critical point of  $\mathcal{L}(\cdot, \hat{\nu}, \hat{\lambda})$  and the complementary slackness condition holds.

Remark: A sufficient condition for Mangasarian-Fromovitz conditions to be satisfied is that  $\{\nabla g_i(\hat{x}) \mid i \in \{1, \dots, m\}\} \cup \{\nabla h_j(\hat{x}) \mid j \in J(\hat{x})\}$  is a family of linearly independent vectors.

Proof: If this condition holds, then the matrix

$$A = \begin{bmatrix} ((\nabla g_i(\hat{x}))^\top)_{1 \leq i \leq m} \\ ((\nabla h_j(\hat{x}))^\top)_{j \in J(\hat{x})} \end{bmatrix} \in \mathbb{R}^{(m+|J(\hat{x})|) \times N}$$

has rank  $m + |J(\hat{x})|$ . Let  $\mathbf{1}$  be the unit vector of  $\mathbb{R}^{|J(\hat{x})|}$ . Hence, the equation

$$Az = \begin{bmatrix} 0 \\ -\mathbf{1} \end{bmatrix}, \quad z \in \mathbb{R}^N,$$

admits a solution. Such a solution satisfies (ii).

## Differentiable case

Only equality constraints:

Assume that  $f$  and  $(g_i)_{1 \leq i \leq m}$  are continuously differentiable on  $\mathcal{H} = \mathbb{R}^N$ .  
Assume that  $\hat{x}$  is a local minimizer of  $f$  over  $C$  and  
 $\{\nabla g_i(\hat{x}) \mid i \in \{1, \dots, m\}\}$  is a family of linearly independent vectors.  
Then, there exists  $\hat{\nu} \in \mathbb{R}^N$  such that  $\hat{x}$  is a critical point of  $\mathcal{L}(\cdot, \hat{\nu})$ .

## Differentiable case

Only inequality constraints:

Assume that  $f$  and  $(h_j)_{1 \leq j \leq q}$  are continuously differentiable on  $\mathcal{H} = \mathbb{R}^N$ .  
Assume that  $\hat{x}$  is a local minimizer of  $f$  over  $C$  and  
there exists  $z \in \mathbb{R}^N$  such that

$$(\forall j \in J(\hat{x})) \quad \langle \nabla h_j(\hat{x}) \mid z \rangle < 0$$

where  $J(\hat{x}) = \{j \in \{1, \dots, q\} \mid h_j(\hat{x}) = 0\}$  is the set of active inequality constraints at  $\hat{x}$ .

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Only inequality constraints:

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Then, there exists  $\hat{\lambda} \in [0, +\infty[^q$  such that  $\hat{x}$  is a critical point of  $\mathcal{L}(\cdot, \hat{\lambda})$  and the complementary slackness condition holds.

Remark: A sufficient condition for the qualification conditions to be satisfied is that  $\{\nabla h_j(\hat{x}) \mid j \in J(\hat{x})\}$  is a family of linearly independent vectors.

## Exercise 4

By using the Lagrange multipliers method, solve the following problem

$$\underset{x=(x^{(i)})_{1 \leq i \leq N} \in B}{\text{maximize}} \quad (x^{(N)})^3 - \frac{1}{2}(x^{(N)})^2$$

where  $B$  is the unit sphere, centered at 0, of  $\mathbb{R}^N$ .

# Appendix

## Preliminary result

### Lemma

Let  $\hat{x} \in C \cap \text{dom } f$ , let  $\hat{\nu} \in \mathbb{R}^m$ , and let  $\hat{\lambda} \in [0, +\infty[^q$  be such that

$$\underline{\mathcal{L}}(\hat{\nu}, \hat{\lambda}) = f(\hat{x}).$$

Then  $(\hat{x}, \hat{\nu}, \hat{\lambda})$  is a saddle point of the Lagrange function.

## Preliminary result

### Lemma

Let  $\hat{x} \in C \cap \text{dom } f$ , let  $\hat{v} \in \mathbb{R}^m$ , and let  $\hat{\lambda} \in [0, +\infty[^q$  be such that

$$\underline{\mathcal{L}}(\hat{v}, \hat{\lambda}) = f(\hat{x}).$$

Then  $(\hat{x}, \hat{v}, \hat{\lambda})$  is a saddle point of the Lagrange function.

Proof: By looking more carefully at the proof of the theorem we provided for characterizing a saddle point, it appears that a sufficient condition for  $(\hat{x}, \hat{v}, \hat{\lambda})$  to a saddle point of  $\mathcal{L}$  is

$$\underline{\mathcal{L}}(\hat{v}, \hat{\lambda}) = \overline{\mathcal{L}}(\hat{x}).$$

In addition, we know that  $(\forall x \in C) \overline{\mathcal{L}}(x) = f(x)$ .

Therefore the sufficient condition reduces the one stated.



## Validity of Slater condition

Assume that Slater condition holds and that  $\hat{x}$  is a minimizer of  $f$ . Let us show that there exists  $\hat{\nu} \in \mathbb{R}^m$  and  $\hat{\lambda} \in [0, +\infty[^q$  such that  $f(\hat{x}) = \underline{\mathcal{L}}(\hat{\nu}, \hat{\lambda})$ . For every  $i \in \{1, \dots, m\}$ , since  $g_i$  is an affine function, there exists  $v_i \in \mathcal{H}$  such that

$$(\forall x \in \mathcal{H}) \quad g_i(x) = g_i(\bar{x}) + \langle v_i \mid x - \bar{x} \rangle = \langle v_i \mid x - \bar{x} \rangle.$$

Assume first that the vectors  $(v_i)_{1 \leq i \leq m}$  are independent.

# Validity of Slater condition

Assume that Slater condition holds and that  $\hat{x}$  is a minimizer of  $f$ . Let us show that there exists  $\hat{\nu} \in \mathbb{R}^m$  and  $\hat{\lambda} \in [0, +\infty[^q$  such that  $f(\hat{x}) = \underline{\mathcal{L}}(\hat{\nu}, \hat{\lambda})$ . For every  $i \in \{1, \dots, m\}$ , since  $g_i$  is an affine function, there exists  $v_i \in \mathcal{H}$  such that

$$(\forall x \in \mathcal{H}) \quad g_i(x) = g_i(\bar{x}) + \langle v_i \mid x - \bar{x} \rangle = \langle v_i \mid x - \bar{x} \rangle.$$

Assume first that the vectors  $(v_i)_{1 \leq i \leq m}$  are independent.

Let

$$C_1 = \left\{ (u^{(0)}, u^{(1)}, \dots, u^{(m)}, u^{(m+1)}, \dots, u^{(m+q)}) \in \mathbb{R}^{m+q+1} \right. \\ \left. \begin{array}{l} f(x) \leq u^{(0)} \\ (\exists x \in \mathcal{H}) \quad \begin{array}{l} (\forall i \in \{1, \dots, m\}) \quad g_i(x) = u^{(i)} \\ (\forall j \in \{1, \dots, q\}) \quad h_j(x) \leq u^{(m+j)} \end{array} \end{array} \right\}$$

$$C_2 = \left\{ (u^{(0)}, u^{(1)}, \dots, u^{(m)}, u^{(m+1)}, \dots, u^{(m+q)}) \in \mathbb{R}^{m+q+1} \right. \\ \left. \begin{array}{l} u^{(0)} < f(\hat{x}) \\ (\forall i \in \{1, \dots, m\}) \quad u^{(i)} = 0 \\ (\forall j \in \{1, \dots, q\}) \quad u^{(m+j)} \leq 0 \end{array} \right\}.$$

Since  $f$  and  $(h_j)_{1 \leq j \leq q}$  are convex and  $(g_i)_{1 \leq i \leq m}$  are affine,  $C_1$  is convex. As a consequence of Slater condition, it is nonempty.

$C_2$  is convex and nonempty. In addition,  $C_1 \cap C_2 = \emptyset$  since there does not exist  $x \in C$  such that  $f(x) < f(\hat{x})$ .

# Validity of Slater condition

Let

$$C_1 = \left\{ (u^{(0)}, u^{(1)}, \dots, u^{(m)}, u^{(m+1)}, \dots, u^{(m+q)}) \in \mathbb{R}^{m+q+1} \right.$$

$$\left. \begin{array}{l} f(x) \leq u^{(0)} \\ (\exists x \in \mathcal{H}) \quad (\forall i \in \{1, \dots, m\}) \quad g_i(x) = u^{(i)} \\ (\forall j \in \{1, \dots, q\}) \quad h_j(x) \leq u^{(m+j)} \end{array} \right\}$$

$$C_2 = \left\{ (u^{(0)}, u^{(1)}, \dots, u^{(m)}, u^{(m+1)}, \dots, u^{(m+q)}) \in \mathbb{R}^{m+q+1} \right.$$

$$\left. \begin{array}{l} u^{(0)} < f(\hat{x}) \\ (\forall i \in \{1, \dots, m\}) \quad u^{(i)} = 0 \\ (\forall j \in \{1, \dots, q\}) \quad u^{(m+j)} \leq 0 \end{array} \right\}.$$

According to separation theorem in  $\mathbb{R}^{m+q+1}$ , there exists  $a = (a^{(0)}, a^{(1)}, \dots, a^{(m)}, a^{(m+1)}, \dots, a^{(m+q)}) \in \mathbb{R}^{m+q+1} \setminus \{0\}$  such that

$$\inf_{u \in C_1} \langle a \mid u \rangle \geq \sup_{u \in C_2} \langle a \mid u \rangle = \sup_{u=(u^j)_{0 \leq j \leq m+q} \in C_2} \left( a^{(0)} u^{(0)} + \sum_{j=1}^q a^{(j+m)} u^{(j+m)} \right).$$

If one of the components  $a^{(0)}$  or  $(a^{(j+m)})_{1 \leq j \leq q}$  would be negative, the right-hand side term would be  $+\infty$ , which is prohibited.

Since these components belong to  $[0, +\infty]^q$ ,  $\sup_{u \in C_2} \langle a \mid u \rangle = a^{(0)} f(\hat{x})$ .

# Validity of Slater condition

Let

$$C_1 = \left\{ (u^{(0)}, u^{(1)}, \dots, u^{(m)}, u^{(m+1)}, \dots, u^{(m+q)}) \in \mathbb{R}^{m+q+1} \right. \\ \left. \begin{array}{l} f(x) \leq u^{(0)} \\ (\exists x \in \mathcal{H}) \quad (\forall i \in \{1, \dots, m\}) \quad g_i(x) = u^{(i)} \\ (\forall j \in \{1, \dots, q\}) \quad h_j(x) \leq u^{(m+j)} \end{array} \right\}.$$

In addition,

$$(\forall x \in \text{dom } f) \quad (f(x), g_1(x), \dots, g_m(x), h_1(x), \dots, h_q(x)) \in C_1.$$

Hence,

$$\inf_{x \in \mathcal{H}} a^{(0)} f(x) + \sum_{i=1}^m a^{(i)} g_i(x) + \sum_{j=1}^q a^{(m+j)} h_j(x) \\ = \inf_{x \in \text{dom } f} a^{(0)} f(x) + \sum_{i=1}^m a^{(i)} g_i(x) + \sum_{j=1}^q a^{(m+j)} h_j(x) \geq \sup_{u \in C_2} \langle a \mid u \rangle = a^{(0)} f(\hat{x}).$$

# Validity of Slater condition

$$\begin{aligned} & \inf_{x \in \mathcal{H}} a^{(0)} f(x) + \sum_{i=1}^m a^{(i)} g_i(x) + \sum_{j=1}^q a^{(m+j)} h_j(x) \\ &= \inf_{x \in \text{dom } f} a^{(0)} f(x) + \sum_{i=1}^m a^{(i)} g_i(x) + \sum_{j=1}^q a^{(m+j)} h_j(x) \geq \sup_{u \in \mathcal{C}_2} \langle a \mid u \rangle = a^{(0)} f(\hat{x}). \end{aligned}$$

If  $a^{(0)} = 0$ , then

$$\inf_{x \in \text{dom } f} \sum_{i=1}^m a^{(i)} g_i(x) + \sum_{j=1}^q a^{(m+j)} h_j(x) \geq 0.$$

This implies that  $\sum_{j=1}^q a^{(m+j)} h_j(\bar{x}) \geq 0$ .

Since  $(\forall j \in \{1, \dots, q\}) a^{(m+j)} \geq 0$  and  $h_j(\bar{x}) < 0$ , then  $(\forall j \in \{1, \dots, q\}) a^{(m+j)} = 0$ .

We deduce that

$$(\forall x \in \text{dom } f) \quad \sum_{i=1}^m a^{(i)} g_i(x) = \sum_{i=1}^m a^{(i)} \langle v_i \mid x - \bar{x} \rangle = \left\langle \sum_{i=1}^m a^{(i)} v_i \mid x - \bar{x} \right\rangle \geq 0.$$

Since  $\bar{x} \in \text{int}(\text{dom } f)$ ,  $\sum_{i=1}^m a^{(i)} v_i = 0$  and, since  $(v_i)_{1 \leq i \leq m}$  are independent vectors,  $(\forall i \in \{1, \dots, m\}) a^{(i)} = 0$ , which is impossible since  $a \neq 0$ .

# Validity of Slater condition

$$\begin{aligned}
 & \inf_{x \in \mathcal{H}} a^{(0)} f(x) + \sum_{i=1}^m a^{(i)} g_i(x) + \sum_{j=1}^q a^{(m+j)} h_j(x) \\
 &= \inf_{x \in \text{dom } f} a^{(0)} f(x) + \sum_{i=1}^m a^{(i)} g_i(x) + \sum_{j=1}^q a^{(m+j)} h_j(x) \geq \sup_{u \in \mathcal{C}_2} \langle a \mid u \rangle = a^{(0)} f(\hat{x}).
 \end{aligned}$$

Hence  $a^{(0)} > 0$  and, by setting

$$\begin{aligned}
 (\forall i \in \{1, \dots, m\}) \quad \hat{\nu}^{(i)} &= \frac{a^{(i)}}{a^{(0)}} \\
 (\forall j \in \{1, \dots, q\}) \quad \hat{\lambda}^{(j)} &= \frac{a^{(m+j)}}{a^{(0)}} \geq 0,
 \end{aligned}$$

$$\text{we get } \underline{\mathcal{L}}(\hat{\nu}, \hat{\lambda}) = \inf_{x \in \text{dom } f} f(x) + \sum_{i=1}^m \hat{\nu}^{(i)} g_i(x) + \sum_{j=1}^q \hat{\lambda}^{(j)} h_j(x) \geq f(\hat{x}).$$

## Validity of Slater condition

Hence  $a^{(0)} > 0$  and, by setting

$$\begin{aligned} (\forall i \in \{1, \dots, m\}) \quad \hat{\nu}^{(i)} &= \frac{a^{(i)}}{a^{(0)}} \\ (\forall j \in \{1, \dots, q\}) \quad \hat{\lambda}^{(j)} &= \frac{a^{(m+j)}}{a^{(0)}} \geq 0, \end{aligned}$$

we get  $\underline{\mathcal{L}}(\hat{\nu}, \hat{\lambda}) = \inf_{x \in \text{dom } f} f(x) + \sum_{i=1}^m \hat{\nu}^{(i)} g_i(x) + \sum_{j=1}^q \hat{\lambda}^{(j)} h_j(x) \geq f(\hat{x})$ .

Since  $\sup_{\nu \in \mathbb{R}^m, \lambda \in [0, +\infty[^q} \underline{\mathcal{L}}(\nu, \lambda) \leq f(\hat{x})$ ,  $\underline{\mathcal{L}}(\hat{\nu}, \hat{\lambda}) = f(\hat{x})$ .

If  $(v_i)_{1 \leq i \leq m}$  are linearly dependent, let  $(v_i)_{i \in \mathbb{I} \subset \{1, \dots, m\}}$  be a maximum size subfamily of linearly independent vectors. Then the same equality holds by setting  $(\forall i \in \{1, \dots, m\} \setminus \mathbb{I}) \hat{\nu}_i = 0$ .

The final result follows from the previous lemma.

## Validity of Fritz-John conditions

Let  $J(\hat{x}) = \{j \in \{1, \dots, q\} \mid h_j(\hat{x}) = 0\}$  be the set of active inequality constraints and let  $\bar{J}(\hat{x}) = \{1, \dots, q\} \setminus J(\hat{x})$ .

For every  $j \in \bar{J}(\hat{x})$ ,  $h_j(\hat{x}) < 0$ . Since functions  $(h_j)_{1 \leq j \leq q}$  are continuous, there exists  $\rho \in ]0, +\infty[$  such that  $\hat{x}$  is a global minimizer of  $f$  on  $B(\hat{x}, \rho)$ , the open ball centered at  $\hat{x}$  and with radius  $\rho$ , and  $(\forall x \in B(\hat{x}, \rho))$   
 $(\forall j \in \bar{J}(\hat{x})) \ h_j(x) < 0$ .

For every  $\eta \in ]0, +\infty[$ , define

$$(\forall x \in \mathbb{R}^N) \quad f_\eta(x) = f(x) + \|x - \hat{x}\|^2 + \frac{\eta}{2} \left( \sum_{i=1}^m (g_i(x))^2 + \sum_{j \in J(\hat{x})} \max\{0, h_j(x)\}^2 \right).$$

Let  $\epsilon \in ]0, \rho[$ . Let us first show that

$$(\exists \eta_\epsilon \in ]0, +\infty[)(\forall x \in \mathbb{R}^N) \quad \|x - \hat{x}\| = \epsilon \Rightarrow f_{\eta_\epsilon}(x) > f(\hat{x}). \quad (1)$$



# Validity of Fritz-John conditions

For every  $\eta \in ]0, +\infty[$ , define

$$(\forall x \in \mathbb{R}^N) \quad f_\eta(x) = f(x) + \|x - \hat{x}\|^2 + \frac{\eta}{2} \left( \sum_{i=1}^m (g_i(x))^2 + \sum_{j \in J(\hat{x})} \max\{0, h_j(x)\}^2 \right).$$

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$$(\exists \eta_\epsilon \in ]0, +\infty[)(\forall x \in \mathbb{R}^N) \quad \|x - \hat{x}\| = \epsilon \Rightarrow f_{\eta_\epsilon}(x) > f(\hat{x}). \quad (1)$$

Otherwise, we could build a sequence  $(\eta_n)_{n \in \mathbb{N}}$  converging to  $+\infty$  and a sequence  $(x_n)_{n \in \mathbb{N}}$  such that  $(\forall n \in \mathbb{N}) \quad \|x_n - \hat{x}\| = \epsilon$  and  $f_{\eta_n}(x_n) \leq f(\hat{x})$ , i.e.

$$f(x_n) + \epsilon^2 + \frac{\eta_n}{2} \left( \sum_{i=1}^m (g_i(x_n))^2 + \sum_{j \in J(\hat{x})} \max\{0, h_j(x_n)\}^2 \right) \leq f(\hat{x})$$

Since  $(x_n)_{n \in \mathbb{N}}$  is bounded, it has a cluster point  $\tilde{x}$ . Since  $f$ ,  $(g_i)_{1 \leq i \leq m}$ , and  $(h_j)_{1 \leq j \leq q}$  are continuous and  $\eta_n \rightarrow +\infty$ , we deduce that

$$\sum_{i=1}^m (g_i(\tilde{x}))^2 + \sum_{j \in J(\tilde{x})} \max\{0, h_j(\tilde{x})\}^2 = 0 \quad \Rightarrow \quad \begin{cases} (\forall i \in \{1, \dots, m\}) \quad g_i(\tilde{x}) = 0 \\ (\forall j \in J(\tilde{x})) \quad h_j(\tilde{x}) \leq 0. \end{cases}$$

Since  $\tilde{x} \in B(\hat{x}, \rho) \Rightarrow (\forall j \in \bar{J}(\hat{x})) \quad h_j(\tilde{x}) < 0$ , this shows that  $\tilde{x} \in C$ .

# Validity of Fritz-John conditions

For every  $\eta \in ]0, +\infty[$ , define

$$(\forall x \in \mathbb{R}^N) \quad f_\eta(x) = f(x) + \|x - \hat{x}\|^2 + \frac{\eta}{2} \left( \sum_{i=1}^m (g_i(x))^2 + \sum_{j \in J(\hat{x})} \max\{0, h_j(x)\}^2 \right).$$

Let  $\epsilon \in ]0, \rho[$ . Let us first show that

$$(\exists \eta_\epsilon \in ]0, +\infty[)(\forall x \in \mathbb{R}^N) \quad \|x - \hat{x}\| = \epsilon \Rightarrow f_{\eta_\epsilon}(x) > f(\hat{x}). \quad (1)$$

Otherwise, we could build a sequence  $(\eta_n)_{n \in \mathbb{N}}$  converging to  $+\infty$  and a sequence  $(x_n)_{n \in \mathbb{N}}$  such that  $(\forall n \in \mathbb{N}) \quad \|x_n - \hat{x}\| = \epsilon$  and  $f_{\eta_n}(x_n) \leq f(\hat{x})$ , i.e.

$$f(x_n) + \epsilon^2 + \frac{\eta_n}{2} \left( \sum_{i=1}^m (g_i(x_n))^2 + \sum_{j \in J(\hat{x})} \max\{0, h_j(x_n)\}^2 \right) \leq f(\hat{x})$$

Since  $(x_n)_{n \in \mathbb{N}}$  is bounded, it has a cluster point  $\tilde{x}$ . Since  $f$ ,  $(g_i)_{1 \leq i \leq m}$ , and  $(h_j)_{1 \leq j \leq q}$  are continuous and  $\eta_n \rightarrow +\infty$ , we deduce that  $\tilde{x} \in C$  and

$$f(\tilde{x}) \leq f(\hat{x}) - \epsilon^2,$$

which contradicts the fact that  $\hat{x}$  minimizes  $f$  over  $B(\hat{x}, \rho)$ .

## Validity of Fritz-John conditions

For every  $\eta \in ]0, +\infty[$ , define

$$(\forall x \in \mathbb{R}^N) \quad f_\eta(x) = f(x) + \|x - \hat{x}\|^2 + \frac{\eta}{2} \left( \sum_{i=1}^m (g_i(x))^2 + \sum_{j \in J(\hat{x})} \max\{0, h_j(x)\}^2 \right).$$

Let  $\epsilon \in ]0, \rho[$ . We have shown that

$$(\exists \eta_\epsilon \in ]0, +\infty[)(\forall x \in \mathbb{R}^N) \quad \|x - \hat{x}\| = \epsilon \Rightarrow f_{\eta_\epsilon}(x) > f(\hat{x}). \quad (1)$$

Since  $\overline{B}(\hat{x}, \epsilon)$  is a compact set and  $f_{\eta_\epsilon}$  is continuous,  $f_{\eta_\epsilon}$  admits a minimizer  $\hat{x}_\epsilon$  on  $\overline{B}(\hat{x}, \epsilon)$ .

We have thus  $f(\hat{x}_\epsilon) \leq f(\hat{x})$  and we deduce from (1) that  $\hat{x}_\epsilon \in B(\hat{x}, \epsilon)$ .

Since  $f$ ,  $(g_i)_{1 \leq i \leq m}$  and  $(h_j)_{1 \leq j \leq q}$  are differentiable, a necessary first-order condition is

$$\nabla f_{\eta_\epsilon}(\hat{x}_\epsilon) = 0.$$

# Validity of Fritz-John conditions

For every  $\eta \in ]0, +\infty[$ , define

$$(\forall x \in \mathbb{R}^N) \quad f_\eta(x) = f(x) + \|x - \hat{x}\|^2 + \frac{\eta}{2} \left( \sum_{i=1}^m (g_i(x))^2 + \sum_{j \in J(\hat{x})} \max\{0, h_j(x)\}^2 \right).$$

We have

$$\nabla f_{\eta_\epsilon}(\hat{x}_\epsilon) = 0$$

$$\Leftrightarrow \nabla f(\hat{x}_\epsilon) + 2(\hat{x}_\epsilon - \hat{x}) + \eta_\epsilon \left( \sum_{i=1}^m g_i(\hat{x}_\epsilon) \nabla g_i(\hat{x}_\epsilon) + \sum_{j \in J(\hat{x})} \max\{0, h_j(\hat{x}_\epsilon)\} \nabla h_j(\hat{x}_\epsilon) \right) = 0.$$

Let  $a_\epsilon = (1, a_\epsilon^{(1)}, \dots, a_\epsilon^{(m)}, a_\epsilon^{(m+1)}, \dots, a_\epsilon^{(m+q)}) \in \mathbb{R}^{m+q+1}$  with

$$(\forall i \in \{1, \dots, m\}) \quad a_\epsilon^{(i)} = \eta_\epsilon g_i(\hat{x}_\epsilon)$$

$$(\forall j \in \{1, \dots, q\}) \quad a_\epsilon^{(j+m)} = \begin{cases} \eta_\epsilon \max\{0, h_j(\hat{x}_\epsilon)\} & \text{if } j \in J(\hat{x}) \\ 0 & \text{otherwise.} \end{cases}$$

We get

$$\nabla f(\hat{x}_\epsilon) + 2(\hat{x}_\epsilon - \hat{x}) + \sum_{i=1}^m a_\epsilon^{(i)} \nabla g_i(\hat{x}_\epsilon) + \sum_{j=1}^q a_\epsilon^{(j+m)} \nabla h_j(\hat{x}_\epsilon) = 0.$$

# Validity of Fritz-John conditions

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Let  $\alpha_\epsilon = a_\epsilon / \|a_\epsilon\|$ .

Consider now a sequence  $(\epsilon_n)_{n \in \mathbb{N}}$  of  $]0, \rho[$  converging to 0.

Then  $\hat{x}_{\epsilon_n} \rightarrow \hat{x}$ , which implies that  $(\hat{x}_{\epsilon_n} - \hat{x}) / \|a_{\epsilon_n}\| \rightarrow 0$  (since  $\|a_{\epsilon_n}\| \geq 1$ ).

In addition,  $(\alpha_{\epsilon_n})_{n \in \mathbb{N}}$  being bounded, there exists a subsequence  $(\alpha_{\epsilon_{n_k}})_{k \in \mathbb{N}}$  converging to some  $\alpha = (\alpha^{(i)})_{0 \leq i \leq m+q}$ . It follows from the continuity of  $\nabla f$ ,  $(\nabla g_i)_{1 \leq i \leq m}$ , and  $(\nabla h_j)_{1 \leq j \leq q}$  that

$$\alpha^{(0)} \nabla f(\hat{x}) + \sum_{i=1}^m \alpha^{(i)} \nabla g_i(\hat{x}) + \sum_{j=1}^q \alpha^{(m+j)} \nabla h_j(\hat{x}) = 0.$$

## Validity of Fritz-John conditions

Let  $a_\epsilon = (1, a_\epsilon^{(1)}, \dots, a_\epsilon^{(m)}, a_\epsilon^{(m+1)}, \dots, a_\epsilon^{(m+q)}) \in \mathbb{R}^{m+q+1}$  with

$$\begin{aligned} (\forall i \in \{1, \dots, m\}) \quad a_\epsilon^{(i)} &= \eta_\epsilon g_i(\hat{x}_\epsilon) \\ (\forall j \in \{1, \dots, q\}) \quad a_\epsilon^{(j+m)} &= \begin{cases} \eta_\epsilon \max\{0, h_j(\hat{x}_\epsilon)\} & \text{if } j \in J(\hat{x}) \\ 0 & \text{otherwise.} \end{cases} \end{aligned}$$

We get

$$\nabla f(\hat{x}_\epsilon) + 2(\hat{x}_\epsilon - \hat{x}) + \sum_{i=1}^m a_\epsilon^{(i)} \nabla g_i(\hat{x}_\epsilon) + \sum_{j=1}^q a_\epsilon^{(j+m)} \nabla h_j(\hat{x}_\epsilon) = 0.$$

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In addition,  $(\alpha_{\epsilon_n})_{n \in \mathbb{N}}$  being bounded, there exists a subsequence  $(\alpha_{\epsilon_{n_k}})_{k \in \mathbb{N}}$  converging to some  $\alpha = (\alpha^{(i)})_{0 \leq i \leq m+q}$ .

It can be finally observed that, for every  $j \in \bar{J}(\hat{x})$ ,  $\alpha^{(j+m)} = 0$ , which means that the complementarity condition is satisfied.