



CentraleSupélec

Statistics and Learning

Julien Bect

(julien.bect@centralesupelec.fr)

Teaching : CentraleSupélec / dept. of Statistics and Signal Processing

Research : Laboratory of Signals and Systems (L2S)

Lecture 3/9

Asymptotic distributions
and confidence regions intervals

In this lecture you will learn how to...

- ▶ Take the asymptotic approach one step further, introducing **asymptotic distributions**.
- ▶ Learn what **confidence intervals** are and show how to construct them (using, again, asymptotic arguments if needed)

Lecture outline

1 – Convergence rate and asymptotic distribution

1.1 – Definitions and examples

1.2 – Theoretical tools

1.3 – Asymptotic efficiency

2 – Confidence regions and confidence intervals

2.1 – Definition and example

2.2 – Exact confidence intervals

2.3 – Asymptotic confidence intervals

Mathematical framework

In this section :

- ▶ we consider a **statistical model**

$$\left(\underline{\mathcal{X}}, \underline{\mathcal{A}}, \left\{ \mathbb{P}_{\theta}^{\mathcal{X}}, \theta \in \Theta \right\} \right),$$

assumed (most of the time) to be **parametric** ($\Theta \subset \mathbb{R}^p$);

- ▶ $X_1, X_2, \dots \stackrel{\text{iid}}{\sim} P_{\theta}$, defined on a common $(\Omega, \mathcal{F}, \mathbb{P}_{\theta})$
- ▶ we want to estimate a « **quantity of interest** » :
 - ▶ either θ itself (we assume in this case that $\Theta \subset \mathbb{R}^p$),
 - ▶ or, more generally, $\eta = g(\theta) \in \mathbb{R}^q$.

Lecture outline

1 – Convergence rate and asymptotic distribution

1.1 – Definitions and examples

1.2 – Theoretical tools

1.3 – Asymptotic efficiency

2 – Confidence regions and confidence intervals

2.1 – Definition and example

2.2 – Exact confidence intervals

2.3 – Asymptotic confidence intervals

Lecture outline

1 – Convergence rate and asymptotic distribution

1.1 – Definitions and examples

1.2 – Theoretical tools

1.3 – Asymptotic efficiency

2 – Confidence regions and confidence intervals

2.1 – Definition and example

2.2 – Exact confidence intervals

2.3 – Asymptotic confidence intervals

Convergence rate

Let $\hat{\eta}_n = \hat{\eta}_n(X_1, \dots, X_n)$ be a consistent estimator of $\eta = g(\theta)$.

Definition

If there exists a sequence $(a_n)_{n \in \mathbb{N}^*}$ of positive numbers such that :

- ▶ $\lim_{n \rightarrow \infty} a_n = \infty$,
 - ▶ $a_n (\hat{\eta}_n - \eta) \xrightarrow[n \rightarrow \infty]{d} Z$,
 - ▶ where Z is a **non-degenerate*** random variable (or vector),
- then $\hat{\eta}_n$ converges to η at the rate $\frac{1}{a_n}$.

* We say that Z is **degenerate** if :

- ▶ scalar case : $\exists c \in \mathbb{R}, Z = c$ a.s. ;
- ▶ vector case : $\exists a_1, \dots, a_q, c \in \mathbb{R}, \sum_{j=1}^q a_j Z^{(j)} = c$ a.s. ;

Exercise. Let Z be a random vector with finite second order moments.

▮ Prove that Z is non-degenerate iff its covariance matrix is invertible.

Asymptotic normality

Let $\hat{\eta}_n = \hat{\eta}_n(X_1, \dots, X_n)$ be a **consistent** estimator of $\eta = g(\theta)$.

Definition

If there exists

- ▶ a sequence $(a_n)_{n \in \mathbb{N}^*}$ of positive numbers s.t. $\lim_{n \rightarrow \infty} a_n = \infty$,
- ▶ a symmetric positive-definite matrix $\Sigma(\theta)$,

such that

$$a_n (\hat{\eta}_n - \eta) \xrightarrow[n \rightarrow \infty]{d} \mathcal{N}(0, \Sigma(\theta)), \quad (1)$$

then we say that $\hat{\eta}_n$ is **asymptotically normal**.

Vocabulary. $\Sigma(\theta)$ is called the **asymptotic covariance matrix** (asymptotic variance, in the scalar case).

Note : it can be proved that (1) with $a_n \rightarrow +\infty$ implies consistency.

Relation between convergence in distribution and in proba.

We already know that convergence in probability implies convergence in distribution. Let $(Y_n)_{n \in \mathbb{N}^*}$ be a sequence of RV with values in \mathbb{R}^d .

Proposition

If $Y_n \xrightarrow{d} c$, with $c \in \mathbb{R}^d$ a constant, then $Y_n \xrightarrow{\mathbb{P}} c$.

Corollary

If there exists $c \in \mathbb{R}^d$,

- ▶ a RV Z with values in \mathbb{R}^d ,
- ▶ a sequence $(a_n)_{n \in \mathbb{N}^*}$ of rel numbers such that $\lim_{n \rightarrow \infty} a_n = \infty$,

such that

$$a_n (Y_n - c) \xrightarrow[n \rightarrow \infty]{d} Z$$

then

$$Y_n \xrightarrow[n \rightarrow \infty]{\mathbb{P}} c.$$

Proof (exercise) : use above proposition and Slutsky's theorem (see below).



Probability refresher : the Central Limit Theorem (CLT)

The CLT gives us the convergence rate of the empirical mean.

Theorem

Let

- ▶ a sequence $(X_n)_{n \in \mathbb{N}^*}$ of IID RV taking values in \mathbb{R}^d , with finite second order moments.
- ▶ $\mu = \mathbb{E}(X_1)$ and $\Sigma = \mathbb{V}(X_1) \in \mathbb{R}^{d \times d}$.

Then :

$$\sqrt{n} (\bar{X}_n - \mu) \xrightarrow[n \rightarrow \infty]{d} \mathcal{N}(0, \Sigma),$$

with $\bar{X}_n = \frac{1}{n} \sum_{i=1}^n X_i$ the sample mean.

Convergence rate of the sample mean.

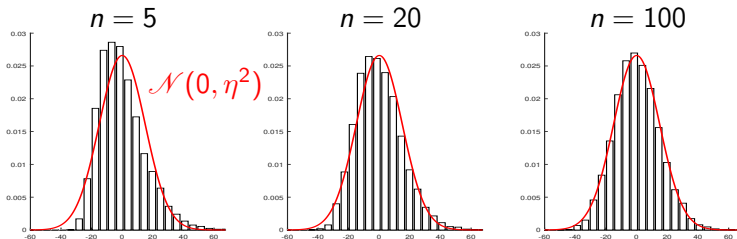
\bar{X}_n converges to $\mathbb{E}(X_1)$ at the rate $\frac{1}{\sqrt{n}}$.

Example : component reliability

Recall that

- ▶ $X_i \stackrel{\text{iid}}{\sim} \mathcal{E}(\theta)$, $\theta > 0$, and $\eta = \mathbb{E}_\theta(X_1) = \frac{1}{\theta}$.
- ▶ $\hat{\eta}_n = \bar{X}_n$ is obtained by ML and the method of moments.

➡ Direct application of the CLT : $\sqrt{n} (\bar{X}_n - \eta) \xrightarrow[n \rightarrow \infty]{d} \mathcal{N}(0, \eta^2)$.



Histograms of $\sqrt{n} (\bar{X}_n - \eta)$ obtained from 10000 realizations of \underline{X}_n

Another exemple : indicator function

Let $(X_n)_{n \geq 1}$ be a sequence of IID RV with values in $(\mathcal{X}, \mathcal{A})$.

For a given $A \in \mathcal{A}$, we estimate $\eta = \mathbb{P}(X_1 \in A)$ by

$$\hat{\eta}_n = \frac{1}{n} \sum_{i=1}^n \mathbb{1}_{X_i \in A}.$$

Direct application of the CLT :

$$\Rightarrow Y_i = \mathbb{1}_{X_i \in A} \stackrel{\text{iid}}{\sim} \text{Ber}(\eta)$$

$$\sqrt{n}(\hat{\eta}_n - \eta) \xrightarrow[n \rightarrow \infty]{d} \mathcal{N}(0, \eta(1 - \eta)).$$

Concl. : if $0 < \eta < 1$, then $\hat{\eta}_n$ is **asymptotically Gaussian**, with

- ▶ convergence rate : $\frac{1}{\sqrt{n}}$,
- ▶ asymptotic variance : $\eta(1 - \eta)$.

Lecture outline

1 – Convergence rate and asymptotic distribution

1.1 – Definitions and examples

1.2 – Theoretical tools

1.3 – Asymptotic efficiency

2 – Confidence regions and confidence intervals

2.1 – Definition and example

2.2 – Exact confidence intervals

2.3 – Asymptotic confidence intervals

Slutsky's theorem

Theorem

Let

- ▶ $(X_n)_{n \in \mathbb{N}^*}$ a sequence of random variables that converges in distribution to a RV X :

$$X_n \xrightarrow[n \rightarrow \infty]{d} X,$$

- ▶ $(Y_n)_{n \in \mathbb{N}^*}$ a sequence of random variables that converges in distribution (therefore in probability) to a **constant** c :

$$Y_n \xrightarrow[n \rightarrow \infty]{d} c,$$

Then

$$(X_n, Y_n) \xrightarrow[n \rightarrow \infty]{d} (X, c).$$

Remark : $Y_n \xrightarrow[n \rightarrow \infty]{d} c$ implies $Y_n \xrightarrow[n \rightarrow \infty]{\mathbb{P}} c$ (constant limit).

The continuous mapping theorem

Theorem (Mann-Wald)

Let

- ▶ $h : \mathbb{R}^d \rightarrow \mathbb{R}^q$ a continuous function
- ▶ Y a random vector, taking values in \mathbb{R}^d ,

such that

h is continuous at the point Y , almost surely.

Then, for any sequence $(Y_n)_{n \in \mathbb{N}^*}$ of RV with values in \mathbb{R}^d ,

- (i) $Y_n \xrightarrow{\text{as}} Y \quad \Rightarrow \quad h(Y_n) \xrightarrow{\text{as}} h(Y),$
- (ii) $Y_n \xrightarrow{\mathbb{P}} Y \quad \Rightarrow \quad h(Y_n) \xrightarrow{\mathbb{P}} h(Y),$
- (iii) $Y_n \xrightarrow{d} Y \quad \Rightarrow \quad h(Y_n) \xrightarrow{d} h(Y).$

Example : component reliability (cont'd)

Recall that

- ▶ $X_i \stackrel{\text{iid}}{\sim} \mathcal{E}(\theta)$, $\theta > 0$, and $\eta = \mathbb{E}_\theta(X_1) = \frac{1}{\theta}$.
- ▶ $\hat{\eta}_n = \bar{X}_n$ is obtained by ML and the method of moments.

Law of large numbers (strong and in L^2) :

$$\hat{\eta}_n = \bar{X}_n \xrightarrow{\text{as}, L^2} \eta.$$

By the continuous mapping theorem :

$$\hat{\theta}_n = \frac{1}{\hat{\eta}_n} \xrightarrow{\text{as}} \frac{1}{\eta} = \theta,$$

therefore $\hat{\theta}_n$ is **strongly consistent**.

Exercise : prove that $\hat{\theta}_n$ is also consistent the L^2 sense.

Example : component reliability (cont'd)

Recall that (CLT) $\sqrt{n} (\bar{X}_n - \eta) \xrightarrow[n \rightarrow \infty]{d} \mathcal{N}(0, \eta^2)$.

Since $\bar{X}_n \xrightarrow[n \rightarrow \infty]{as} \eta$ (constant), we have by Slutsky's theorem :

$$(\sqrt{n} (\bar{X}_n - \eta), \bar{X}_n) \xrightarrow[n \rightarrow \infty]{d} (Z, \eta) \quad \text{with } Z \sim \mathcal{N}(0, \eta^2).$$

Therefore, by the continuous mapping theorem,

$$\sqrt{n} \frac{(\bar{X}_n - \eta)}{\bar{X}_n} \xrightarrow[n \rightarrow \infty]{d} \frac{Z}{\eta} \sim \mathcal{N}(0, 1),$$

since $(z, y) \mapsto \frac{z}{y}$ is continuous at any point where $y \neq 0$.

Linearization method (“delta method”)

Theorem (“delta theorem”)

Let $(Y_n)_{n \in \mathbb{N}^*}$ be a sequence of RV with values in \mathbb{R}^d , s.t.

$$\sqrt{n}(Y_n - m) \xrightarrow[n \rightarrow \infty]{d} Z,$$

Y a random vector, taking values in \mathbb{R}^d and $m \in \mathbb{R}^d$.

Then, for any $h : \mathbb{R}^d \rightarrow \mathbb{R}^q$ that is differentiable at m ,

$$\sqrt{n}(h(Y_n) - h(m)) \xrightarrow[n \rightarrow \infty]{d} (Dh)(m) Z,$$

where $(Dh)(m)$ is the Jacobian matrix of h at m :

$$(Dh)(m) = \left((\partial_j h_i)(m) \right)_{1 \leq i \leq q, 1 \leq j \leq d}.$$

Intuition : $h(y) - h(m) \approx (Dh)(m)(y - m)$.

Special cases

Gaussian case

If $\sqrt{n}(Y_n - m) \xrightarrow[n \rightarrow \infty]{d} \mathcal{N}(0, \Sigma)$, then

$$\sqrt{n}(h(Y_n) - h(m)) \xrightarrow[n \rightarrow \infty]{d} \mathcal{N}\left(0, (Dh)(m) \Sigma (Dh)(m)^\top\right).$$

Scalar case

If $d = q = 1$ and $\sqrt{n}(Y_n - m) \xrightarrow[n \rightarrow \infty]{d} Z$, then

$$\sqrt{n}(h(Y_n) - h(m)) \xrightarrow[n \rightarrow \infty]{d} h'(m) Z.$$

Exercise. If $h'(m) = 0$, and if h is twice differentiable at m , show that

$$n(h(Y_n) - h(m)) \xrightarrow[n \rightarrow \infty]{d} \frac{1}{2} h''(m) Z^2.$$

Proof (scalar case)

Consider the function ψ defined by :

$$\psi(y) = \begin{cases} \frac{h(y) - h(m)}{y - m} & \text{si } y \neq m, \\ h'(m) & \text{si } y = m; \end{cases}$$

ψ is continuous at m because h est differentiable at m . Since $Y_n \xrightarrow[n \rightarrow \infty]{d} m$,

$$\psi(Y_n) \xrightarrow[n \rightarrow \infty]{d} \psi(m) = h'(m),$$

and thus (Slutsky)

$$(\sqrt{n}(Y_n - m), \psi(Y_n)) \xrightarrow[n \rightarrow \infty]{d} (Z, h'(m)).$$

Finally, we have

$$\sqrt{n}(h(Y_n) - h(m)) = \sqrt{n}(Y_n - m) \psi(Y_n) \xrightarrow[n \rightarrow \infty]{d} h'(m) Z. \quad \square$$

Example : component reliability (cont'd)

Application : comparing estimators of $\eta = \mathbb{E}_\theta(X_1)$.

1) For $\hat{\eta}^{(1)} = \bar{X}_n$, we have (CLT) : $\sqrt{n}(\hat{\eta}^{(1)} - \eta) \xrightarrow[n \rightarrow \infty]{d} \mathcal{N}(0, \eta^2)$.

2) For $\hat{\eta}^{(2)} = \sqrt{\frac{1}{2n} \sum_{i=1}^n X_i^2}$ (see lecture #1) ?

► Since $\mathbb{E}(X_1^2) = 2\eta^2$ et $\mathbb{E}(X_1^4) = 24\eta^4$, we have (CLT) :

$$\sqrt{n} \left(\frac{1}{n} \sum_{i=1}^n X_i^2 - 2\eta^2 \right) \xrightarrow[n \rightarrow \infty]{d} \mathcal{N}(0, 20\eta^4).$$

► Hence, using the delta method with $h(z) = \sqrt{\frac{1}{2}z}$,

$$\sqrt{n}(\hat{\eta}^{(2)} - \eta) \xrightarrow[n \rightarrow \infty]{d} \mathcal{N}\left(0, \frac{5}{4}\eta^2\right).$$

Conclusion : $\hat{\eta}^{(1)}$ is “asymptotically preferable” to $\hat{\eta}^{(2)}$.

(Actually, it can be proved that $\hat{\eta}^{(1)}$ is efficient ; see comput. of the FIM below).

Asymptotic comparison of (scalar) estimators

Let $\hat{\eta}_n$ and $\tilde{\eta}_n$ be two estimators of $\eta = g(\theta) \in \mathbb{R}$,

- ▶ **asymptotically Gaussian**.
- ▶ with asymptotic variances $\sigma^2(\theta)$ and $\tilde{\sigma}^2(\theta)$.

Definition : asymptotically preferable

If

- ▶ the two estimators have the **same convergence rate**,
- ▶ $\sigma^2(\theta) \leq \tilde{\sigma}^2(\theta) \quad \forall \theta \in \Theta$,

then we say that

$\hat{\eta}_n$ is **asymptotically preferable** to $\tilde{\eta}_n$

(“strictly” if $\exists \theta \in \Theta$ such that $\sigma^2(\theta) < \tilde{\sigma}^2(\theta)$).

Note : comparing vector-valued estimators \Rightarrow compare matrices. . .

Example : component reliability (cont'd)

We already saw that

- ▶ $\hat{\theta}_n = 1/\bar{X}_n$ is a consistent estimator of θ ,
- ▶ $\sqrt{n}(\bar{X}_n - \eta) \xrightarrow[n \rightarrow \infty]{d} \mathcal{N}(0, \eta^2)$, where $\eta = \frac{1}{\theta}$.

Using the delta method with $h(\eta) = \frac{1}{\eta}$, we get :

$$\sqrt{n} \left(\frac{1}{\bar{X}_n} - \theta \right) \xrightarrow[n \rightarrow \infty]{d} \mathcal{N} \left(0, \eta^2 (h'(\eta))^2 \right),$$

hence, since $h'(\eta) = -\frac{1}{\eta^2}$,

$$\sqrt{n}(\hat{\theta}_n - \theta) \xrightarrow[n \rightarrow \infty]{d} \mathcal{N}(0, \theta^2).$$

⇒ the estimator $\hat{\theta}_n$ is **asymptotically Gaussian**.

Lecture outline

1 – Convergence rate and asymptotic distribution

1.1 – Definitions and examples

1.2 – Theoretical tools

1.3 – Asymptotic efficiency

2 – Confidence regions and confidence intervals

2.1 – Definition and example

2.2 – Exact confidence intervals

2.3 – Asymptotic confidence intervals

Asymptotic efficiency

Recall the Cramér-Rao lower bound (scalar parameter)

$\forall \hat{\theta}$ regular UE of θ , $\forall \theta \in \Theta$,

$$R_{\theta}(\hat{\theta}) = \mathbb{V}_{\theta}(\hat{\theta}) \geq \frac{1}{n} I_1^{-1}(\theta),$$

with $I_1(\theta) = \mathbb{V}_{\theta}(S_{\theta}(X_1))$.

⇒ When equality holds for all θ , the estimator is called **efficient**.

Asymptotic efficiency

Definition. An estimator is called **asymptotically efficient** :

- ▶ if it is asymptotically normal with rate $\frac{1}{\sqrt{n}}$,
- ▶ is its asymptotic variance is such that $\Sigma(\theta) = I_1^{-1}(\theta)$.

Remark : this definition is valid for the vector-valued case as well.

Asymptotic efficiency of the MLE

Context : $X_1, X_2, \dots \stackrel{\text{iid}}{\sim} P_\theta$ and, $\forall \theta \in \Theta$, P_θ admits a pdf f_θ .

Definition : regular model

The statistical model is called **regular** if

- ▶ **conditions C_1 – C_4 hold**, (C₃ and C₄ defined below)
- ▶ $\forall \theta \in \Theta$, the Fisher information matrix **$I_1(\theta)$ is positive definite**.


Theorem

If the statistical model is **regular** and if the MLE $\hat{\theta}_n$ is **consistent**, then it is **asymptotically efficient** :

$$\sqrt{n} \left(\hat{\theta}_n - \theta \right) \xrightarrow[n \rightarrow \infty]{d} \mathcal{N} \left(0, I_1^{-1}(\theta) \right).$$

Counter-example in a non-regular model

Let $X_1, \dots, X_n \stackrel{\text{iid}}{\sim} \mathcal{U}_{[0, \theta]}$, with $\theta > 0$ unknown.

 This model is not regular (why?).

It can be proved that (cf. TD1, exercise 1.3)

- ▶ $\hat{\theta}_n = \max_{i \leq n} X_i$ is the MLE of θ , and
- ▶ $n \left(\hat{\theta}_n - \theta \right) \xrightarrow[n \rightarrow \infty]{d} -Z$ with $Z \sim \mathcal{E} \left(\lambda = \frac{1}{\theta} \right)$.

In this particular case

- ▣ the MLE is **not asymptotically Gaussian**;
- ▣ the **convergence rate** is $\frac{1}{n}$: faster than $\frac{1}{\sqrt{n}}$.

Partial solution of exercise 1.3 (TD 1)

By maximization of the likelihood, we get (see TD1) :

$$\hat{\theta}_n = \max_{i=1 \dots n} X_i.$$

We have, for $0 \leq t \leq \theta$:

$$\mathbb{P}_\theta \left(\hat{\theta}_n \leq t \right) = \left(\frac{t}{\theta} \right)^n,$$

thus, for all $u \leq 0$:

$$\mathbb{P}_\theta \left(n \left(\hat{\theta}_n - \theta \right) \leq u \right) = \begin{cases} \left(1 + \frac{u}{n\theta} \right)^n & \text{if } u \geq -n\theta, \\ 0 & \text{otherwise.} \end{cases}$$

Finally, for all $u \leq 0$,

$$\mathbb{P}_\theta \left(n \left(\hat{\theta}_n - \theta \right) \leq u \right) \xrightarrow{n \rightarrow \infty} \exp \left(\frac{u}{\theta} \right).$$



Regularity conditions : C_3 and C_4

We assume that C_1 and C_2 hold.

Regularity condition C_3

$\theta \mapsto f_\theta(\underline{x})$ is twice continuously differentiable for ν -almost all \underline{x} .

Regularity condition C_4

At any point $\theta \in \Theta$, we have

$$\int_S \nabla_\theta \nabla_\theta^\top f_\theta(\underline{x}) \nu(d\underline{x}) = \nabla_\theta \int_S \nabla_\theta^\top f_\theta(\underline{x}) \nu(d\underline{x}).$$

In other words, : $\forall \theta \in \Theta, \forall k \leq p, \forall j \leq p,$

$$\int_S \frac{\partial^2 f_\theta(\underline{x})}{\partial \theta_k \partial \theta_j} \nu(d\underline{x}) = \frac{\partial}{\partial \theta_k} \int_S \frac{\partial f_\theta(\underline{x})}{\partial \theta_j} \nu(d\underline{x}).$$

Consequence of $C_3 + C_4$: Fisher information matrix

We assume that C_1 and C_2 hold.

Reminder. The **Fisher information** brought by \underline{X} is the matrix

$$I_{\underline{X}}(\theta) = \mathbb{V}_{\theta}(S_{\theta}(\underline{X})) = \mathbb{E}_{\theta} \left(S_{\theta}(\underline{X}) S_{\theta}(\underline{X})^{\top} \right).$$

Proposition : another expression for the FIM

If conditions C_1 – C_4 hold, then

$$I_{\underline{X}}(\theta) = - \mathbb{E}_{\theta} \left(\nabla_{\theta} \left(S_{\theta}(\underline{X})^{\top} \right) \right), \quad (\star)$$

In other words, : $\forall \theta \in \Theta, \forall j \leq p, \forall k \leq p,$

$$(I_{\underline{X}}(\theta))_{j,k} = - \mathbb{E}_{\theta} \left(\frac{\partial}{\partial \theta_j} S_{\theta}^{(k)}(\underline{X}) \right) = - \mathbb{E}_{\theta} \left(\frac{\partial^2}{\partial \theta_j \partial \theta_k} \ln f_{\theta}(\underline{X}) \right).$$

Remark : actually, if C_1 – C_3 hold, then C_4 and (\star) are equivalent.

Example : component reliability (cont'd)

Question : is $\hat{\theta}_n = 1/\bar{X}_n$ asymptotically efficient ?

We have already computed the score : $S_\theta(X_1) = \frac{1}{\theta} - X_1$.

Computation of Fisher's information (two approaches) :

Comput. of $\mathbb{E}_\theta (S_\theta(X_1)^2)$

$$I_1(\theta) = \mathbb{V}_\theta(X_1) = \eta^2 = \frac{1}{\theta^2}$$

Comput. of $-\mathbb{E}_\theta \left(\frac{\partial S_\theta}{\partial \theta}(X_1) \right)$

$$I_1(\theta) = -\mathbb{E}_\theta \left(-\frac{1}{\theta^2} \right) = \frac{1}{\theta^2}$$

Conclusion : since $\sqrt{n} \left(\frac{1}{\bar{X}_n} - \theta \right) \xrightarrow[n \rightarrow \infty]{d} \mathcal{N}(0, \theta^2)$,

$\hat{\theta}_n = \frac{1}{\bar{X}_n}$ is asymptotically efficient.

⇒ We recover the conclusions of the theorem (C_1 – C_4 hold indeed).

Lecture outline

1 – Convergence rate and asymptotic distribution

1.1 – Definitions and examples

1.2 – Theoretical tools

1.3 – Asymptotic efficiency

2 – Confidence regions and confidence intervals

2.1 – Definition and example

2.2 – Exact confidence intervals

2.3 – Asymptotic confidence intervals

Lecture outline

1 – Convergence rate and asymptotic distribution

1.1 – Definitions and examples

1.2 – Theoretical tools

1.3 – Asymptotic efficiency

2 – Confidence regions and confidence intervals

2.1 – Definition and example

2.2 – Exact confidence intervals

2.3 – Asymptotic confidence intervals

Motivation

Problem

A point estimator necessarily makes some **estimation error**.
How can we “report” this error?

Two approaches :

- ▶ provide, in addition to the estimated value,
 - ▶ the **distribution of the estimator** $\hat{\eta}$, exact or approximate,
 - ▶ or at least some « measure of dispersion » (e.g., its standard deviation);
- ▶ give, instead of a point estimation $\hat{\eta}$,

a **confidence interval** for η .

Confidence regions and confidence intervals

Recall that $\eta = g(\theta)$. We denote by $\mathcal{P}(N)$ the subsets of $N = g(\Theta)$.

Definition : confidence region

Let $\alpha \in]0, 1[$. A **confidence region with level (at least) $1 - \alpha$** for η is a statistics $I_\alpha(\underline{X})$ taking values in $\mathcal{P}(N)$, such that :

$$\forall \theta \in \Theta, \quad \mathbb{P}_\theta(g(\theta) \in I_\alpha(\underline{X})) \geq 1 - \alpha.$$

We say that $I_\alpha(\underline{X})$ is a confidence region with level **exactly** $1 - \alpha$ if

$$\forall \theta \in \Theta, \quad \mathbb{P}_\theta(g(\theta) \in I_\alpha(\underline{X})) = 1 - \alpha.$$

(Some authors also write : of “size” $1 - \alpha$.)

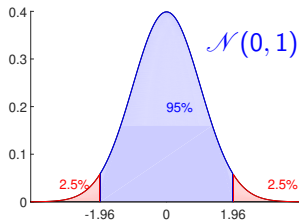
Scalar case : if $I_\alpha(\underline{X})$ is an interval, it is called a **confidence interval**.

Example : $\mathcal{N}(\mu, 1)$ n -sample, with known σ_0^2

Since $\bar{X} \sim \mathcal{N}\left(\mu, \frac{\sigma_0^2}{n}\right)$, $T = \sqrt{n} \frac{\bar{X} - \mu}{\sigma_0} \sim \mathcal{N}(0, 1)$, therefore

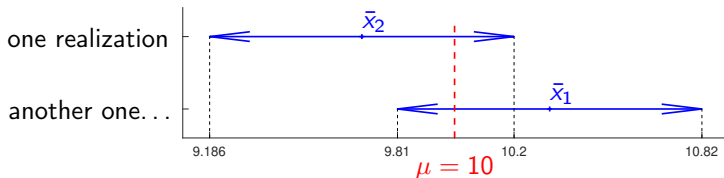
$$\mathbb{P}_\mu \left(\sqrt{n} \frac{\bar{X} - \mu}{\sigma_0} \in [q_{\frac{\alpha}{2}}, q_{1-\frac{\alpha}{2}}] \right) = 1 - \alpha,$$

with q_r the quantile of order r of the $\mathcal{N}(0, 1)$ distribution.



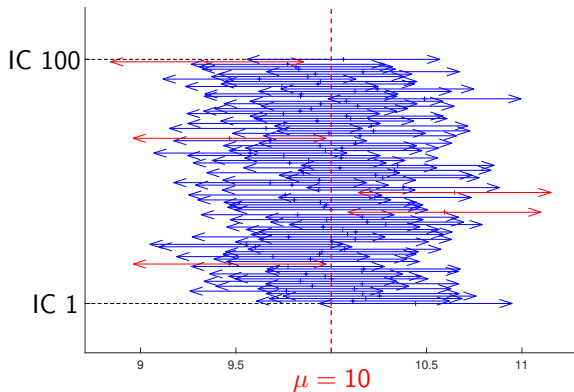
CI with level exactly $1 - \alpha$:

$$\left[\bar{X} - 1.96 \frac{\sigma_0}{\sqrt{n}}, \bar{X} + 1.96 \frac{\sigma_0}{\sqrt{n}} \right]$$



Interpretation : simulations

We simulate 100 realizations with $\mu = 10$ and $\sigma_n = 1$.



In red : realizations where the IC does not contain $\mu = 10$.

➡ The proportion of cases where the CI does not contain μ is (approx.) α .

Lecture outline

1 – Convergence rate and asymptotic distribution

1.1 – Definitions and examples

1.2 – Theoretical tools

1.3 – Asymptotic efficiency

2 – Confidence regions and confidence intervals

2.1 – Definition and example

2.2 – Exact confidence intervals

2.3 – Asymptotic confidence intervals

Pivotal functions

The method can be formalized using **pivotal functions**.

Definitions

A function

$$T : \underline{\mathcal{X}} \times N \rightarrow \mathbb{R}$$

is called **pivotal** if the distribution of the RV $T = T(\underline{X}, \eta)$ **does not depend on θ** . We say that the distribution of $T(\underline{X}, \eta)$ is **free** from the parameter.

Back to the **example** : $X_1, \dots, X_n \stackrel{\text{iid}}{\sim} \mathcal{N}(\mu, \sigma_0^2)$ with known σ_0 .

Then $T = \sqrt{n} \frac{\bar{X}_n - \mu}{\sigma_0}$ is pivotal since

$$\sqrt{n} \frac{\bar{X}_n - \mu}{\sigma_0} \sim \mathcal{N}(0, 1).$$

Remark : we can also choose $T = \sqrt{n} (\bar{X}_n - \mu) \sim \mathcal{N}(0, \sigma_0^2)$.

Probability refresher : quantiles

Definition : quantile of order r

Let $F(x)$ be the cdf of a probability distribution on \mathbb{R} .

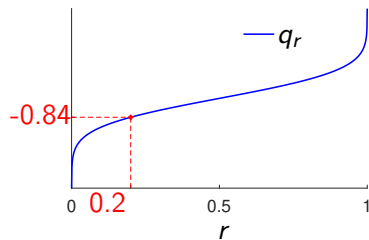
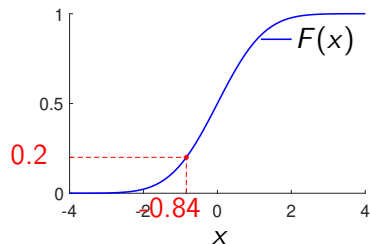
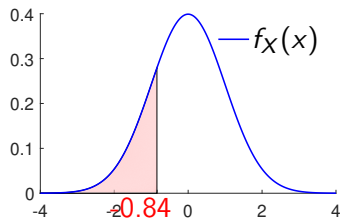
For $0 < r < 1$, the **quantile of order r** of the distribution is defined as :

$$q_r = \inf \{x \in \mathbb{R}, F(x) \geq r\}.$$

Properties :

- ▶ If F is continuous, then $F(q_r) = r$.
- ▶ If, in addition, F is strictly increasing, then $q_r = F^{-1}(r)$.

Quantile function of the $\mathcal{N}(0, 1)$ distribution



How to use pivotal functions

Let $T(\underline{X}, \eta)$ be a pivotal function and $\alpha \in]0, 1[$.

Proposition

Assume that the cdf F of $T(\underline{X}, \eta)$ is continuous, denote by $q_r = F^{-1}(r)$ the quantile of order r .

Then, for all $\gamma \in [0, \alpha]$:

$$\begin{aligned} I_{\alpha}^{\gamma}(\underline{X}) &= \{\eta \in N \text{ such that } q_{\gamma} \leq T(\underline{X}, \eta) \leq q_{\gamma+1-\alpha}\} \\ &= S^{-1}(\underline{X}, [q_{\gamma}, q_{\gamma+1-\alpha}]) \end{aligned}$$

is a confidence interval for η with level exactly $1 - \alpha$.

Proof.
$$\begin{aligned} \mathbb{P}_{\theta}(I_{\alpha}^{\gamma}(\underline{X})) &= \mathbb{P}_{\theta}(q_{\gamma} \leq T(\underline{X}, \eta) \leq q_{\gamma+1-\alpha}) \\ &= F(q_{\gamma+1-\alpha}) - F(q_{\gamma}) = 1 - \alpha \end{aligned}$$



Example : $\mathcal{N}(\mu, 1)$ n -sample, with known σ_0^2

Consider once more the pivotal function

$$T(\underline{X}, \mu) = \sqrt{n} \frac{(\bar{X} - \mu)}{\sigma_0} \sim \mathcal{N}(0, 1).$$

For all $\gamma \leq \alpha$, we obtain a CI with level (exactly) $1 - \alpha$:

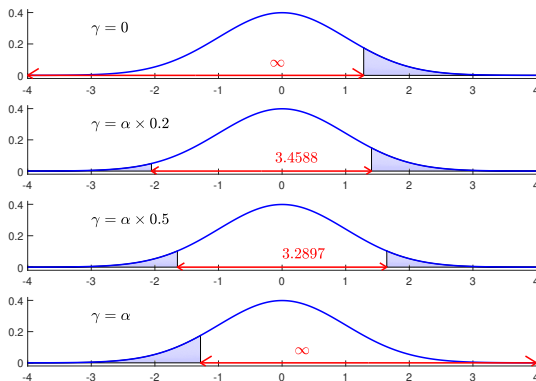
$$I_\alpha^\gamma = \left[\bar{X} + \frac{\sigma_0}{\sqrt{n}} q_\gamma, \quad \bar{X} + \frac{\sigma_0}{\sqrt{n}} q_{1-\alpha+\gamma} \right],$$

with q_r the quantile of order r of the $\mathcal{N}(0, 1)$ distribution.

For instance, with $\gamma = \frac{\alpha}{2}$ and $\alpha = 0.05$:

$$q_\gamma \approx -1.96 \quad \text{and} \quad q_{1-\alpha+\gamma} \approx 1.96.$$

How to choose γ ?



Density of the $\mathcal{N}(0, 1)$ distribution and corresponding quantiles for $\alpha = 0.1$ and several values of γ (in red : $q_{\gamma+1-\alpha} - q_{\gamma}$).

Usual criterion : value s.t. the CI has minimal length (here $\gamma = \frac{\alpha}{2}$).

Example : component reliability (cont'd)

It can be proved that :

$$T(\underline{X}, \eta) = \frac{\bar{X}}{\eta} \sim \Gamma(n, n).$$

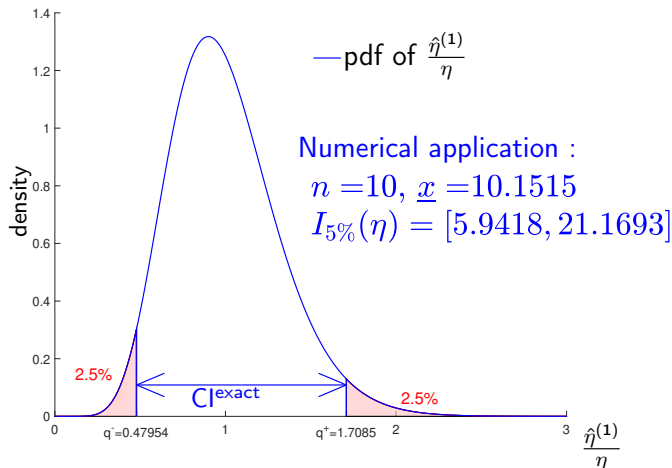
Thus, a CI with level exactly $1 - \alpha$ is :

$$I_{\alpha}^{\gamma} = \left[\frac{\bar{X}}{q_{\gamma+1-\alpha}}, \frac{\bar{X}}{q_{\gamma}} \right],$$

with q_r the quantile of order r of the $\Gamma(n, n)$ distribution.

Choic of γ : we can take $\gamma = \frac{\alpha}{2}$ for simplicity, or search numerically for the value γ such that the length $q_{1+\gamma-\alpha} - q_{\gamma}$ is minimal.

Example : component reliability (cont'd)



Probability density function of the pivotal distribution $\Gamma(n, n)$ and corresponding quantiles for $\alpha = 0.05$ and $\gamma = \frac{\alpha}{2}$.

Another exemple : the Rayleigh distribution

Definition : Rayleigh distribution with parameter σ^2

$$X \sim \mathcal{R}(\sigma^2) \quad \text{if (déf.)} \quad f(x) = \frac{x}{\sigma^2} \exp\left(-\frac{x^2}{2\sigma^2}\right), \quad x \geq 0.$$

Pivotal function. Finding a pivotal function in this case requires the knowledge of some “fine” properties of the Rayleigh distribution. . .

It can be proved that : if $X \sim \mathcal{R}(\sigma^2)$ then $Y = X^2 \sim \mathcal{E}\left(\frac{1}{2\sigma^2}\right)$;

⇒ thus $T(\underline{X}, \sigma^2) = \frac{1}{n\sigma^2} \sum_{i=1}^n X_i^2 \sim \Gamma\left(n, \frac{1}{2}\right)$ is pivotal for σ^2 .

Hence a CI with level exactly $1 - \alpha$:

$$I_{\alpha}^{\gamma = \frac{\alpha}{2}} = \left[\frac{1}{nq_{1-\frac{\alpha}{2}}} \sum_{i=1}^n X_i^2, \frac{1}{nq_{\frac{\alpha}{2}}} \sum_{i=1}^n X_i^2 \right].$$

Lecture outline

1 – Convergence rate and asymptotic distribution

1.1 – Definitions and examples

1.2 – Theoretical tools

1.3 – Asymptotic efficiency

2 – Confidence regions and confidence intervals

2.1 – Definition and example

2.2 – Exact confidence intervals

2.3 – Asymptotic confidence intervals

Motivation and goal

Problem

It is sometimes (often) **difficult to find a pivotal function**.

Solution : use once again an **asymptotic approach**.

- ▶ Intervals with “approximate guarantees” will be obtained.
- ▶ Comput. become easier with the tools that we already have (CLT, Slutsky, delta method. . .).



Any analysis carried out in an asymptotic setting is

approximate when n is finite.

▮▶ The results can be bad for small n . . .

Asymptotic confidence regions (intervals)

We set $\underline{X}_n = (X_1, \dots, X_n)$. Recall that $\eta = g(\theta)$ and $N = g(\Theta)$.

Definition : asymptotic confidence region

An **asymptotic confidence region with level (at least) $1 - \alpha$** is a statistic $I_{n,\alpha}(\underline{X}_n)$, with values in $\mathcal{P}(N)$, such that

$$\forall \theta \in \Theta, \quad \lim_{n \rightarrow \infty} \mathbb{P}_{\theta}(g(\theta) \in I_{n,\alpha}(\underline{X}_n)) \geq 1 - \alpha.$$

(variant : « exactly » if equality holds for all θ .)

Recall that for an “exact” CR with level (at least) $1 - \alpha$,

$$\forall \theta \in \Theta, \quad \mathbb{P}_{\theta}(g(\theta) \in I_{\alpha}(\underline{X}_n)) \geq 1 - \alpha$$

(here, « exact » means « non asymptotic »).

Asymptotic pivotal function

Definition

A (sequence of) function(s)

$$T_n : \mathcal{X}^n \times N \rightarrow \mathbb{R}$$

is an **asymptotic pivotal function** if the **limit** distribution of $T_n(\underline{X}_n, \eta)$ does not depend on θ :

$$T_n(\underline{X}_n, \eta) \xrightarrow[n \rightarrow \infty]{d} T_\infty.$$

where T_∞ is a RV whose distribution is free of θ .

How to use asymptotic pivotal functions :

⇒ exactly as we used the non-asymptotic ones !

Example : component reliability (cont'd)

We already saw that (Slutsky + continuity theorem)

$$\sqrt{n} \frac{(\bar{X}_n - \eta)}{\bar{X}_n} \xrightarrow[n \rightarrow \infty]{d} \mathcal{N}(0, 1).$$

⇒ Asymptotic pivotal function :

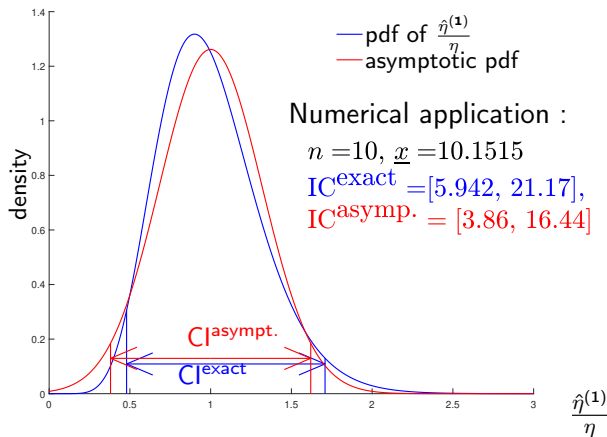
$$T_n(\underline{X}_n, \eta) = \sqrt{n} \frac{\bar{X} - \eta}{\bar{X}}.$$

⇒ Asymptotic CI with level (exactly) $1 - \alpha$ for η :

$$I_\alpha = \left[\left(1 - \frac{1}{\sqrt{n}} q_{1-\frac{\alpha}{2}} \right) \bar{X}, \left(1 + \frac{1}{\sqrt{n}} q_{1-\frac{\alpha}{2}} \right) \bar{X} \right]$$

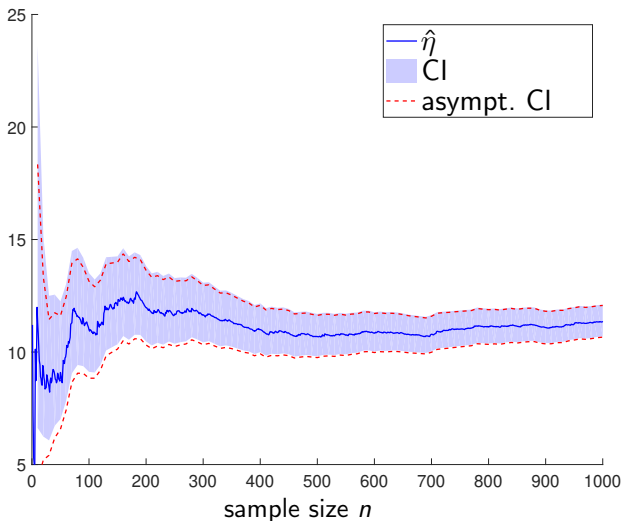
with q_r the quantile of order r of the $\mathcal{N}(0, 1)$ distribution.

Example : component reliability (cont'd)



Comparison of the pdfs of pivotal functions
(exact and asymptotic)

Example : component reliability (cont'd)



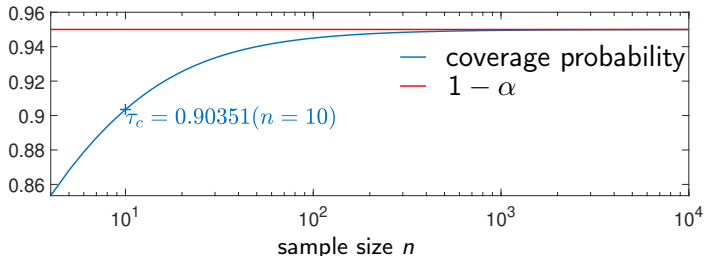
Comparison of exact and asymptotic CIs, as a function of n

Coverage probability of a confidence interval

Definition

For $\theta \in \Theta$, the **coverage probability** of $I_\alpha(\underline{X}_n)$ is defined by

$$\tau_{n,\theta}^c(I_\alpha(\underline{X}_n)) = \mathbb{P}_\theta(\eta \in I_\alpha(\underline{X}_n))$$



Ex. « component reliability » : $\tau_{n,\theta}^c$ for the asympt. CI with level 95%

Remark. If $I_\alpha(\underline{X}_n)$ is an asympt. CI with level $1 - \alpha$, then :

$$\forall \theta, \lim_{n \rightarrow \infty} \tau_\theta^c(I_\alpha(\underline{X}_n)) \geq 1 - \alpha.$$