

Introduction to Optimization

Yangyang Xu

Mathematical Sciences, RPI

Ubiquitousness of optimization

- Optimization in everyday life: shortest path, least time, most efficient ...
- Optimization problems in many areas including operations research, management, engineering, finance, and so on.
- In recent years, optimization becomes particularly popular in machine learning, statistics, signal processing, and various data sciences.

Basic formulation

In general, an optimization problem can be formulated as

$$\underset{\mathbf{x}}{\text{minimize}} f(\mathbf{x}), \quad \text{subject to } \mathbf{x} \in \mathcal{X}.$$

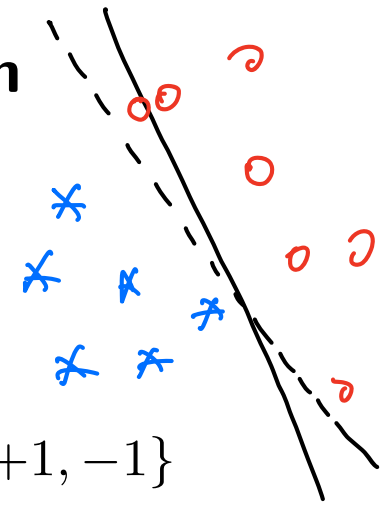
- f is called the objective function
- \mathbf{x} is called the variable
- \mathcal{X} is called a feasible set. In this course, we assume

$$\mathcal{X} = \left\{ \mathbf{x} \in \mathcal{X}_{\text{smpI}} : g_i(\mathbf{x}) \leq 0, \forall i \in [m], h_i(\mathbf{x}) = 0, \forall i \in [\ell] \right\},$$

where $\mathcal{X}_{\text{smpI}}$ is a simple set such as a box constraint set.

- $\min_{\mathbf{x}} f(\mathbf{x})$ is equivalent to $\max_{\mathbf{x}} -f(\mathbf{x})$

Example I: Logistic regression



Problem setting:

- given a set of training data $\{(\mathbf{x}_i, y_i)\}_{i=1}^N$ with $y_i \in \{+1, -1\}$
- Assume the conditional probability of the label y_i based on sample \mathbf{x}_i takes the form of

$$\text{Prob}(y_i | \mathbf{x}_i, \mathbf{w}, b) = \frac{\exp[y_i(\mathbf{w}^\top \mathbf{x}_i + b)]}{1 + \exp[y_i(\mathbf{w}^\top \mathbf{x}_i + b)]}, \forall i \in [N].$$

Goal:

- to learn a hyperplane $\{\mathbf{x} : \mathbf{w}^\top \mathbf{x} + b = 0\}$ to separate the dataset.
- for a new data point \mathbf{x}^{new} , it can be classified based on the margin $\mathbf{w}^\top \mathbf{x}^{\text{new}} + b$.

Example I: Logistic regression

Optimization model:

- Assume independent identical distribution
- The likelihood function is

$$\mathcal{L} = \prod_{i=1}^N \frac{\exp[y_i(\mathbf{w}^\top \mathbf{x}_i + b)]}{1 + \exp[y_i(\mathbf{w}^\top \mathbf{x}_i + b)]},$$

- Maximizing likelihood is equivalent to

$$\underset{\mathbf{w}, b}{\text{minimize}} \frac{1}{N} \sum_{i=1}^N \log \left(1 + \exp[-y_i(\mathbf{w}^\top \mathbf{x}_i + b)] \right). \quad (\text{LogReg})$$

$$\max_{w, b} \frac{1}{N} \sum_{i=1}^N \frac{\exp[y_i(w^T x_i + b)]}{1 + \exp[y_i(w^T x_i + b)]}$$

$$\Leftrightarrow \max_{w, b} \log \left(\frac{1}{N} \sum_{i=1}^N \frac{\exp[y_i(w^T x_i + b)]}{1 + \exp[y_i(w^T x_i + b)]} \right)$$

$$\log \left(\frac{1}{N} \sum_{i=1}^N \frac{\exp[y_i(w^T x_i + b)]}{1 + \exp[y_i(w^T x_i + b)]} \right)$$

$$= \sum_{i=1}^N \log \frac{\exp[y_i(w^T x_i + b)]}{1 + \exp[y_i(w^T x_i + b)]}$$

$$= \sum_{i=1}^N \left(\log \exp[y_i(w^T x_i + b)] - \log (1 + \exp[y_i(w^T x_i + b)]) \right)$$

$$= \sum_{i=1}^N \left(y_i(w^T x_i + b) - \log (1 + \exp[y_i(w^T x_i + b)]) \right)$$

$$\Leftrightarrow \min_{w, b} \frac{\sum_{i=1}^N \log (1 + \exp[y_i(w^T x_i + b)])}{N} - \frac{\sum_{i=1}^N y_i(w^T x_i + b)}{N}$$

$$\log \left(\frac{1}{N} \sum_{i=1}^N \frac{\exp[y_i(w^T x_i + b)]}{1 + \exp[y_i(w^T x_i + b)]} \right)$$

$$= \sum_{i=1}^N \log \frac{\exp[y_i(w^T x_i + b)]}{1 + \exp[y_i(w^T x_i + b)]} = \sum_{i=1}^N \log \frac{1}{1 + \exp[-y_i(w^T x_i + b)]}$$

Example II: Portfolio optimization

Problem setting:

- We have a unit of capital to invest on m assets
- Let x_i be the fraction of capital invested on the i -th asset and ξ_i be the (stochastic) return rate of the i -th asset
- The risk measured by variance of total return

$$\mathbb{E}[x^T \xi] = x^T \mathbb{E}[\xi]$$

$$\begin{aligned} \text{Var}(x^T \xi) &= \mathbb{E}[(x^T \xi - \mathbb{E}[x^T \xi])^2] = \mathbb{E}[(x^T (\xi - \mathbb{E}[\xi]))^2] \\ &= x^T \mathbb{E}[(\xi - \mathbb{E}[\xi])(\xi - \mathbb{E}[\xi])^T] x = x^T \Sigma x \end{aligned}$$

Handwritten notes: $(x^T(\xi - \mathbb{E}[\xi]))^2$ and $= x^T(\xi - \mathbb{E}[\xi])(\xi - \mathbb{E}[\xi])^T x$ with arrows pointing to the corresponding terms in the derivation.

where $\mathbf{x} = (x_1; \dots; x_m)$ and Σ is the covariance matrix

Goal:

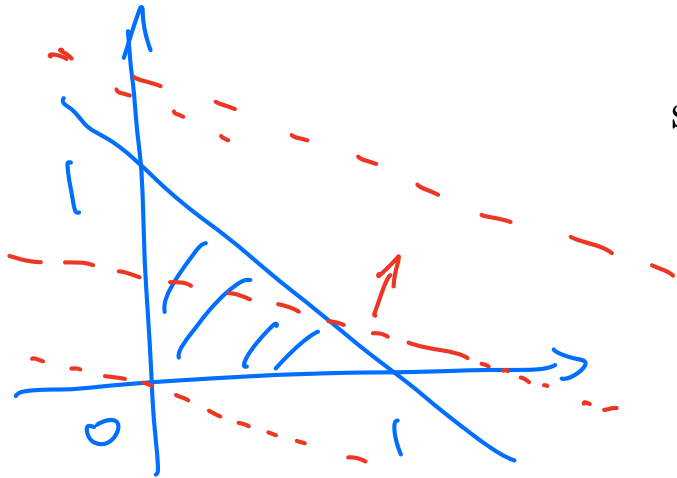
- To minimize risk subject to total unit capital and minimum expected return c

Example II: Portfolio optimization

Optimization model:

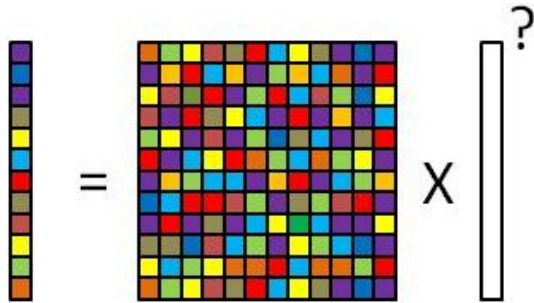
- variable: fraction vector of capital $\mathbf{x} = (x_1; \dots; x_m)$
- risk function: $\frac{1}{2} \mathbf{x}^\top \Sigma \mathbf{x}$
- constraint: total unit capital and minimum expected return c
- formulation:

$$\begin{aligned} & \underset{\mathbf{x}}{\text{minimize}} && \frac{1}{2} \mathbf{x}^\top \Sigma \mathbf{x} \\ & \text{subject to} && \sum_{i=1}^m x_i \leq 1, \\ & && \mathbb{E}[\boldsymbol{\xi}^\top \mathbf{x}] \geq c, \\ & && x_i \geq 0, \forall i \in [m]. \end{aligned} \quad (\text{Portfolio})$$

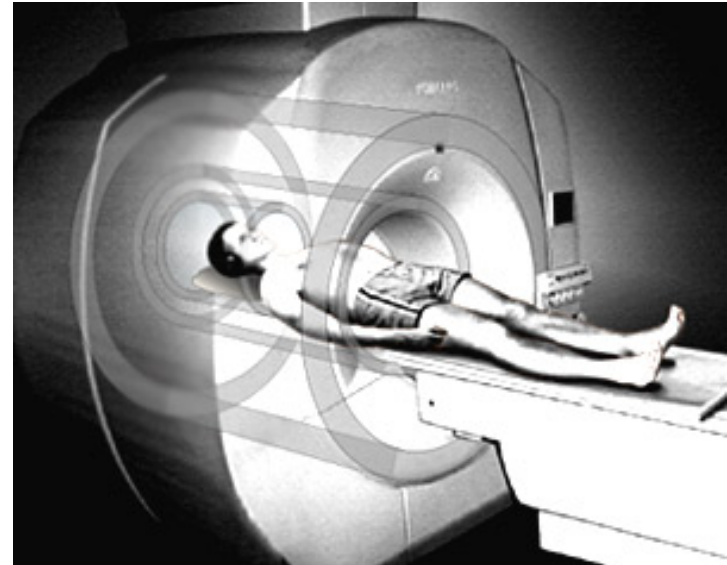
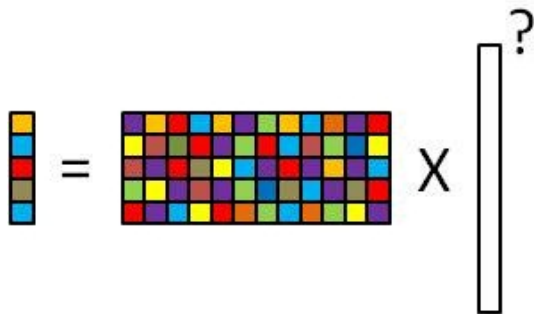


Example III: compressed sensing MRI¹

- Classic technique



- Compressed sensing



- Classic technique: about 8 minutes
- Compressed sensing: about 80 seconds

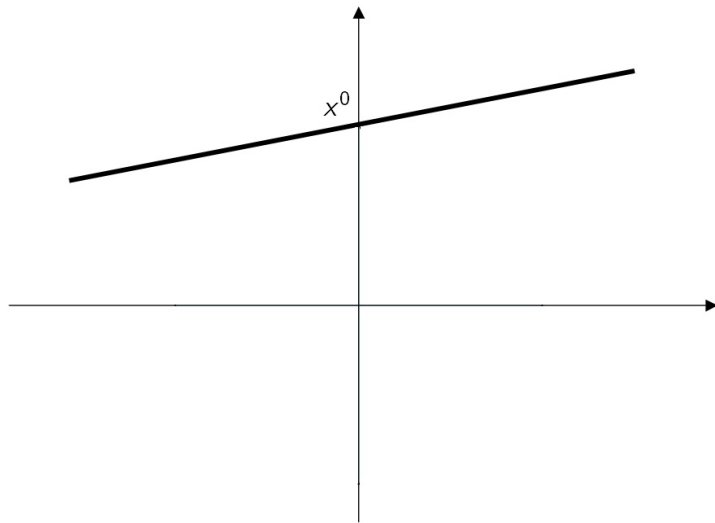
¹Donoho'06, Candès et al.'06

How to recover the signal

- find the sparsest solution

$$\begin{cases} \min_{\mathbf{x} \in \mathbb{R}^n} \|\mathbf{x}\|_0 \\ \text{s.t. } \mathbf{Ax} = \mathbf{b} \end{cases}$$

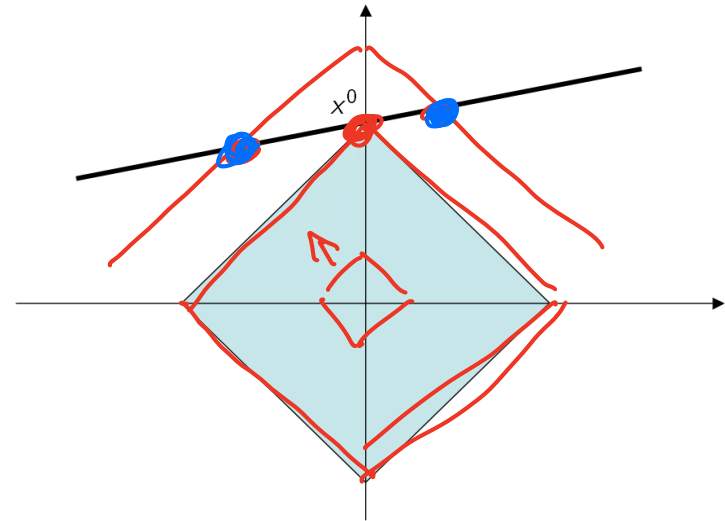
where $\|\mathbf{x}\|_0$ denotes #non-zeros in \mathbf{x} .



- ℓ_1 relaxation

$$\begin{cases} \min_{\mathbf{x} \in \mathbb{R}^n} \|\mathbf{x}\|_1 \\ \text{s.t. } \mathbf{Ax} = \mathbf{b} \end{cases}$$

where $\|\mathbf{x}\|_1 \triangleq \sum_{i=1}^n |x_i|$.

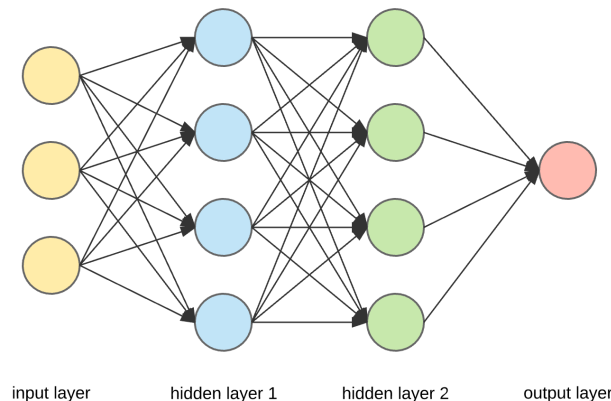


Example IV: Logistic regression with neural network approximation

Instead of hand pre-processing and directly applying LogReg on $\{\mathbf{x}_i\}$, auto-process the data first through a system (that is to be learned)

$$\underset{\mathbf{w}, b, \theta}{\text{minimize}} \frac{1}{N} \sum_{i=1}^N \log (1 + \exp[-y_i(\mathbf{w}^\top f_{\theta}(\mathbf{x}_i) + b)])$$

- f_{θ} a nonlinear transformation: extract features (maybe in other domain)
- currently popular: deep neural network $f_{\theta}(\mathbf{x}) = f_{\theta_d} \circ f_{\theta_{d-1}} \circ \cdots \circ f_{\theta_1}(\mathbf{x})$



$\max(\theta, x, o)$

Key questions

- Whether the minimization problem has a feasible and/or optimal solution
 - feasibility often assumed. But note checking feasibility can be hard
 - existence of optimal solution can be shown under mild conditions
- How to determine a candidate solution is optimal
 - by checking sufficient optimality conditions
- How to find an optimal solution (numerically and/or analytically)
 - analytically by formulating necessary optimality conditions and solving linear or nonlinear systems, e.g., $\min_{x,y} (x-1)^2 + y^2$, s.t. $x + y = 2$
 - **Focus of this course:** numerically by moving iterate along feasible and descent directions

Outline of the rest

1. Concepts of numerical algorithm and convergence
2. Fundamentals of unconstrained optimization
3. Gradient type methods: steepest gradient descent, projected gradient, conjugate gradient, proximal gradient, and Nesterov's accelerated proximal gradient
4. Newton type methods: Newton's method, quasi-Newton method, and Gauss-Newton method
5. Derivative free methods: coordinate descent method
6. Theory of functional constrained optimization: Karush-Kuhn-Tucker (KKT) conditions and Lagrangian duality
7. Simplex method and Interior-point methods for linear programming
8. Ellipsoid method and cutting-plane methods
9. Penalty methods, barrier function methods, and augmented Lagrangian method
10. Alternating direction method of multipliers and applications