

# **DeepJSCC-I++: Robust and Bandwidth- Adaptive Wireless Image Transmission**

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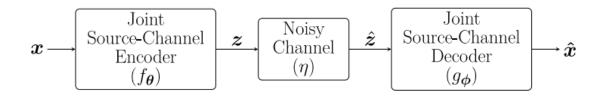
# DeepJSCC-I++

- Outline
  - Introduction & Motivation
  - System Model
  - Proposed Method
  - Experimental Results
  - Q & A

### **Introduction & Motivation**

#### DeepJSCC revisit

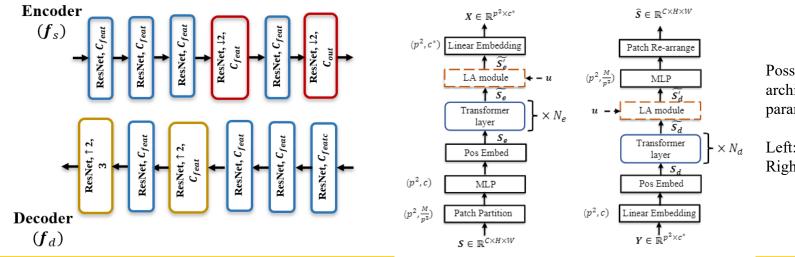
- An encoder  $f_{\theta}(\cdot)$  and decoder  $g_{\phi}(\cdot)$  parameterized by neural networks.
- $x \in \mathbb{R}^{C \times H \times W}$ ,  $z \in \mathbb{C}^k$ , with  $\rho = \frac{k}{N}$ ,  $N = C \times H \times W$ .
- Jointly optimize  $\{\theta, \phi\}$  to minimize reconstruction distortion, e.g.,  $||x \hat{x}||_2^2$ .



- Key merit:
  - · avoiding cliff and leveling effect
  - Achieving better reconstruction performance.
- Performance metrics:
  - $PSNR = 10 \log_{10} \frac{255^2}{\frac{1}{N} ||x \hat{x}||_F^2}$

#### **Introduction & Motivation**

- Motivation for DeepJSCC-I++
  - $\{\theta, \phi\}$  parameterized by CNNs/ViT, occupy 100+ Mb.
  - $\{\theta, \phi\}$  are optimized for a specific  $\{SNR, \rho\}$ .
  - 4 different SNR points and 4 bandwidth ratios → 16 models → 1.6 Gb space.
     -- Too large for a mobile device!
  - Is it possible to have a single  $\{\theta, \phi\}$  pair for all  $\{SNR, \rho\}$ ?

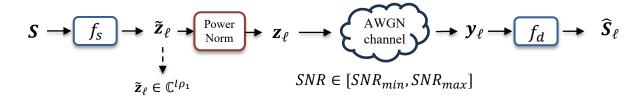


Possible neural network architectures to parameterize  $\{\theta, \phi\}$ :

Left: CNN, Right: ViT.

## **System Model**

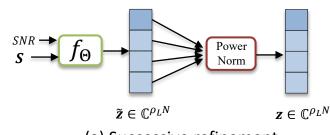
- System Model
  - Communication over an AWGN channel,
    - $\mathbf{y} = \mathbf{z} + \mathbf{n}$ ;  $\mathbf{z} \in \mathbb{C}^k$ ,  $n_i \sim \mathcal{CN}(0, \sigma^2)$ .
  - Assumptions of packets:
    - Possible supported bandwidth ratios  $[\rho_1, ..., \rho_L]$  with  $\rho_l = l\rho_1$ . (discrete)
    - Channel qualities:  $SNR \in [SNR_{min}, SNR_{max}]$  (continuous).
  - Channel model shown below:



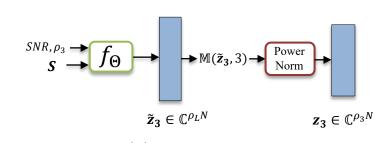
#### Solutions

- Solution A: Successive Refinement
- SNR-adaptive solution is given in [2], first focus on the varying bandwidth setting.
- Shown in figure (a):
  - $\tilde{z} = f_{\Theta}(S, SNR)$
  - Partition  $\tilde{z}$  to L blocks, denote it as  $\tilde{z}[l], l \in [1, L]$ .
  - <u>Block-wise</u> Power normalize:  $z[l] = \frac{\tilde{z}[l]}{\|\tilde{z}[l]\|_2}$
  - The first  $k \in [1, L]$  blocks should be able to reconstruct the image,  $\hat{S}_l$  to some level.
  - Loss function:

$$- \mathcal{L} = \sum_{l=1}^{L} ||S - \hat{S}_{l}||_{F}^{2}$$



(a) Successive refinement



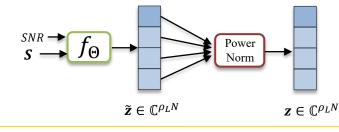
(b) Bandwidth adaptive

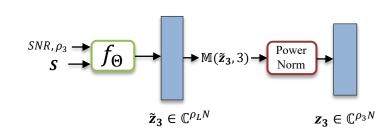
A concrete example

of L = 4,  $\ell = 3$ 

[2] J. Xu, etc, "Wireless image transmission using deep source channel coding with attention modules," IEEE Trans. Circuits Syst. Video Technol. 2021

- Solution B: Bandwidth Adaptive; in figure (b)
  - Obtain target bandwidth, ℓ, from the user.
  - $\tilde{\mathbf{z}}_{\ell} = f_{\Theta}(S, SNR, \ell)$
  - Masking instead of partitioning:
    - $z_{\ell} = M(\tilde{z}_{\ell}, \ell)$
  - Train the model as:
    - $\mathcal{L} = \mathbb{E}_{\ell \sim \mathcal{U}(1,L)} || \mathbf{S} \widehat{\mathbf{S}}_{\ell} ||_F^2$
  - Compare with Solution A:
    - Additional information from the user is required.
    - The reconstruction can be performed when all the  $z_\ell$  is received.
    - Since different users have different requirements, ℓ, in general, it only fits the point-to-point channel, instead of broadcast channel (where solution A can be easily applied).





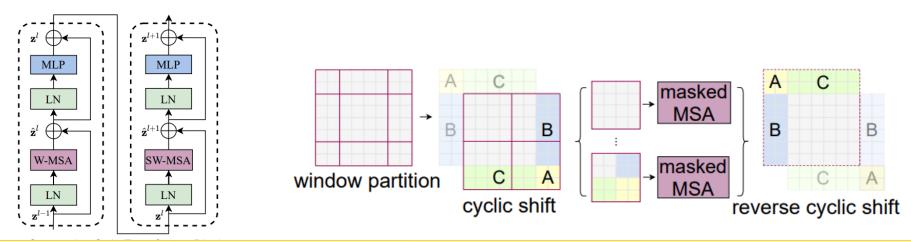
A concrete example

of L = 4,  $\ell = 3$ 

(b) Bandwidth adaptive

(a) Successive refinement

- A good backbone Swin Transformer
  - A good neural network backbone makes a difference an improvement from ViT to CNN is observed [3]
  - Make it even better by adopting the state-of-the-art Swin transformer.
  - A brief introduction below:
    - The key idea for Swin is to perform self attention within a (small, e.g., 7x7) window instead of the whole image.
    - Shifting window operations enable communication between different windows.
    - Swin Transformer Block (Left) Illustration of SW-MSA module (Right).

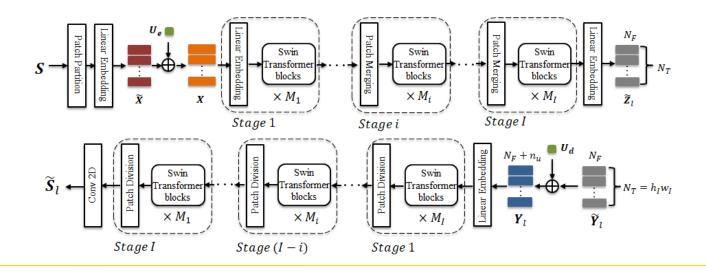


[3] H. Wu, etc, "Vision transformer for adaptive image transmission over MIMO channels," in IEEE International Conference on Communications (ICC), 2023.

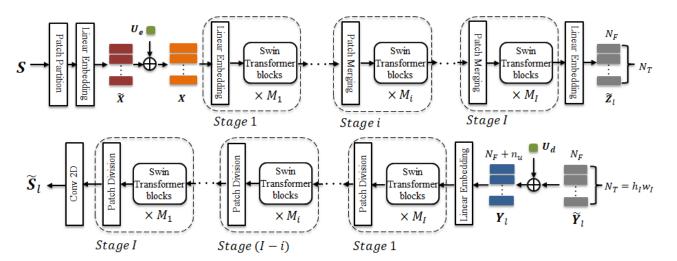
[4] Z. Liu, etc., "Swin transformer: Hierarchical vision transformer using shifted windows," in ICCV, October 2021

#### The overall framework

- Explaining details of the framework:
  - Patch partitioning:  $S(C, H, W) \to X'\left(Cp^2, h = \frac{H}{p}, w = \frac{W}{p}\right)$  -- dividing the image evenly.
  - Patch Merging:  $X(d, h', w') \to X'\left(d', \frac{h'}{2}, \frac{w'}{2}\right)$  -- can be understood as stacking the patches and transform.
  - Patch Division:  $X(d, h', w') \rightarrow X'(d', 2h', 2w')$  -- can be achieved via 2d transpose convolution.



- The overall framework
  - Side information generation:
    - $U = MLP([\rho_{\ell}, SNR])$ , Note, if successive refinement, we use only SNR values.
    - Concatenate U to each token of  $\tilde{X}$  (d, h, w) to generate X ( $d + n_{emb}$ , h, w).
  - We show by experiments, we can achieve both SNR and bandwidth adaptive objective by feeding  $MLP([\rho_{\ell}, SNR])$  to the framework.
  - Contrary to [2], we don't need to add the SA block to achieve SNR-adaptive! The Swin transformer performs it automatically.



# Varying features vs varying tokens:

- The output of the encoder is a matrix with  $N_T \times N_F$ .
- For different ρ, we can either transmit less amount of N<sub>t</sub> or less amount of N<sub>f</sub>.
   Simulations show different strategies yield similar reconstruction performance.

### Training methodology

- Naïve training strategy for Solution A (successive refinement):
  - Recall: total bandwidth budget,  $\rho_L$ , is fixed, number of layers, L, is fixed, the first l layers should recover the original image to some level...
  - $\mathcal{L} = \sum_{l=1}^{L} ||\mathbf{S} \hat{\mathbf{S}}_l||_F^2$  if noise power is fixed, if not:
  - $\mathcal{L} = \mathbb{E}_{\gamma \sim \mathcal{U}(\gamma_1, \gamma_2)} \sum_{l=1}^L ||\mathbf{S} \hat{\mathbf{S}}_{l, \gamma}||_F^2$ , where  $\gamma_1, \gamma_2$  denote the min and max SNR value.
- Naïve training strategy for Solution B (bandwidth adaptive):
  - Recall: user specific bandwidth ratio  $\rho_{\ell}$  is known to the transmitter,  $\ell$  is a random variable.
  - $\mathcal{L} = \mathbb{E}_{\ell \sim \mathcal{U}(1,L)} ||S \hat{S}_{\ell}||_F^2$  if noise power is fixed, if not:
  - $\mathcal{L} = \mathbb{E}_{\gamma \sim \mathcal{U}(\gamma_1, \gamma_2), \ell \sim \mathcal{U}(1, L)} ||S \hat{S}_{\ell, \gamma}||_F^2$
  - This is achieved by randomly sample  $\gamma$ ,  $\ell$  from the uniform distributions and then calculate the end-to-end loss.
  - All the equations assume a same weight  $w_{\ell} = 1$  for all the bandwidth ratios.

- Dynamic weight assignment (DWA)
  - Problem of Naïve training for Solution A&B:
    - Having  $w_{\ell} = 1$  for all bandwidth ratios results in:
      - the model only focus on optimizing the lower  $\rho_l$  with much larger loss  $\mathcal{L}_{\ell}$ .
      - $PSNR_{\ell}$  of the higher bandwidth ratios are much worse than  $PSNR_{\ell}^*$  of the separately trained models.
    - · This will be verified in the experiments.

#### – Solution:

- Consider unequal  $w_{\ell}$  to different  $\rho_{\ell}$ 's.
- However, it is hard to figure out a good configuration of *w* to achieve a good overall performance.
- Instead of pre-assigned values, we have:
  - Dynamic weight assignment: assigning larger  $w_l^t$  to  $\mathcal{L}_l^t$  with larger  $\rho_l$  dynamically during the training epochs t.

- Dynamic weight assignment (DWA)
  - The weights  $w_t^t$  are updated according to the reconstruction performance evaluated over the validation dataset:
    - The separately trained models with  $[\rho_1, ..., \rho_L]$  yields  $[PSNR_1^*, ..., PSNR_L^*]$
    - Use it as a criterion to guide the training process of DeepJSCC-l++
  - we first determine the gap from the optimal results, then calculate the weight for each bandwidth ratio.

$$\Delta_l^t = \text{PSNR}_l^* - \text{PNSR}_l^t,$$

$$w_l^t = \text{clip}(2^{\alpha(\Delta_l^t - \beta)} - 1, 0, \Gamma),$$
(5)

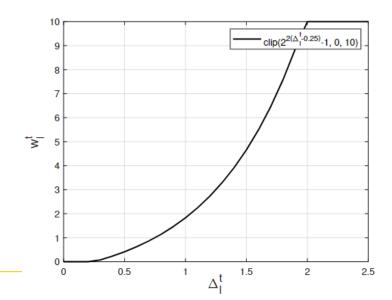
- Explanation of the Parameters
  - $\alpha$ : how sensitive the weight w.r.t to the gap.
  - $\beta$ : allowable gap from the optimal PSNR value.
  - Γ: designed for stable training, should not be too large.
  - The function in (5) is continuous from [0, Γ].

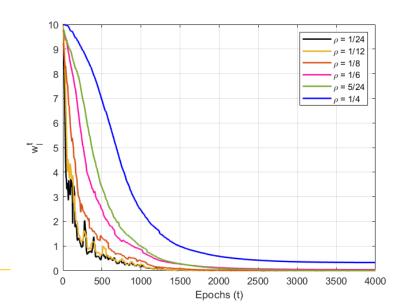
A summary of the DeepJSCC-I++ framework

```
Algorithm 1 Overall Training Process for DeepJSCC-l++
Model with DWA.
 1: Initialize w_l^1 = 1, \forall l \in [L]
 2: for t = 1, ..., T do
          Training Phase:
 3:
          for each batch do
 4:
               Sample l \in [L], SNR \in [SNR<sub>min</sub>, SNR<sub>max</sub>]
 5:
              Encoder: z_l = f_{\Theta}(S, SNR, l)
 6:
              Decoder: S_l = g_{\Psi}(\boldsymbol{y}, \text{SNR}, l)
               Weighted Loss: \mathcal{L}_{l}^{t} = w_{l}^{t} ||S - \tilde{S}_{l}||_{2}^{2}.
 8:
              Optimize \{\Theta, \Psi\} using \mathcal{L}_{t}^{t}.
 9:
          Validation Phase:
10:
          for l \in [L] do
11:
               Calculate PSNR<sub>I</sub><sup>t</sup>, \Delta_I^t over validation set.
12:
               Update w_I^t according to (5).
13:
```

#### Analysis of DWA

- Given parameters:  $(\alpha, \beta, \Gamma) = (2, 0.25, 10)$ .
- Left figure  $\rightarrow$  the  $w_l^t$  v.s.  $\Delta_l^t$ .
- Right figure → We train a bandwidth adaptive DeepJSCC-l++ (solution B) with L = 6 and 4000 epochs.
  - · Larger bandwidth ratio needs larger weight.
  - The gap for  $\rho_L = 1/4$  is larger than  $\beta = 0.25$  dB even when the training ends.

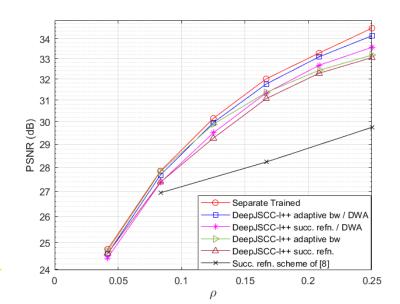


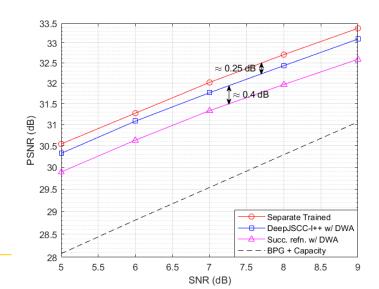


#### Bandwidth & SNR adaptive

- Experiment setup
  - CIFAR-10 dataset, 32 x 32 resolution
  - Swin encoder/decoder employ I = 2 stages with the numbers of Swin transformer blocks in each stage is set to  $M_1 = 4$ ,  $M_2 = 2$ , the number of features c is set to 256, the window size to w = 8,.
  - The dimension of the embedding is set to 2.
  - Train for 4000 epochs, varying learning rate initialized at 10–4, which is reduced by a factor of 0.95 if the validation loss does not drop for 20 epochs.
  - DeepJSCC-I++ models for Solution A & B are trained under the conditions:
    - $SNR \in [4, 10] dB$
    - $\rho_l \in \left[\frac{1}{24}, \frac{1}{12}, \frac{1}{8}, \frac{1}{6}, \frac{5}{24}, \frac{1}{4}\right]$
- Benchmark:
  - 1. Separately trained models -- upper bound for the proposed DeepJSCC-I++
  - 2. BPG compression algorithm delivered at the (AWGN) channel capacity.

- Bandwidth & SNR adaptive
  - Left: PSNR under (fixed) SNR = 7 dB, with varying bandwidth ratios.
    - DWA improves the reconstruction performance a lot at larger  $\rho_l$  yet only sacrifice very little PSNR at small  $\rho_l$ .
    - Solution B can outperform Solution A as its encoding phase is more flexible (known the target  $\rho_l$ )
  - Right: PSNR under (fixed)  $\rho_l = \frac{1}{6}$ , with varying channel qualities.
    - The proposed schemes can significantly outperform the digital baseline while avoiding cliff-effect.
    - Adapting to SNR does not sacrifice the performance at all, the gap between the optimal is from the bandwidth adaptive part.





- Supplementary materials
  - Left → Compare the Swin transformer with ViT.
    - Configuration: SNR = 7 dB, separately trained.
  - Right → varying patches/tokens v.s. varying features.
    - Swin Transformer, with architecture shown in Slide 10.

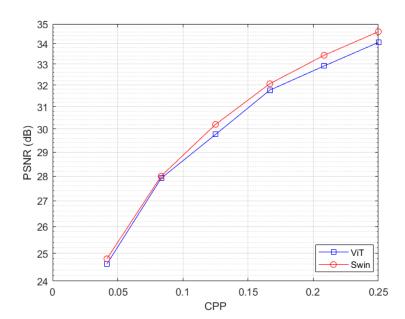


Table I: Evaluation for the varying patches and varying features DeepJSCC-l++ schemes at SNR = 7 dB in terms of PSNR (dB).

ρ	1/16	1/8	3/16	1/4
varying patches	26.12	30.01	32.53	34.32
varying features	26.14	30.01	32.53	34.31
separate training	26.36	30.23	32.70	34.55

## **Thanks for Listening!**

Any questions are welcomed! ©