

10.1: Moment of Inertia

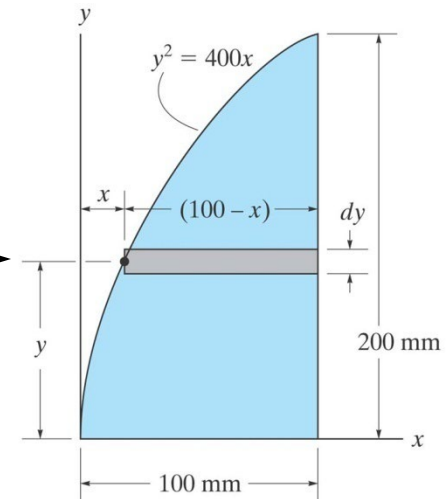
Finding the *moment of inertia* of a shape depends on the orientation of the differential slice used.

For *Moment of Inertia* about x-axis:

When slice is taken parallel to the x-axis:

Use the basic equation:

$$I_x = \int_A y^2 dA$$



where,

I_x = *Moment of Inertia* of shape about the x axis

y = Distance from x axis to centroid of slice

dA = Area of differential slice

For *Moment of Inertia* about x-axis:

When slice is taken perpendicular to the x-axis:

Use the Parallel-Axis Theorem eqn:

$$I_x = \int dI_x$$

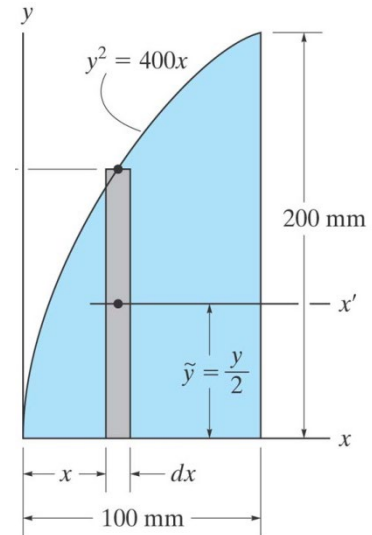
where,

$$dI_x = d\bar{I}_{x'} + dA y^2$$

$$\begin{aligned} d\bar{I}_{x'} &= \text{moment of inertia of differential slice about its centroid} \\ &= \frac{dx y^3}{12} \end{aligned}$$

$$dA = \text{area of differential slice}$$

$$y = \text{distance from x-axis to centroid of slice}$$



Procedures for determining *Moment of Inertia*:

1. Choose a differential slice to use - Horiz. or Vert.:
 - a) If differential slice is taken parallel to the axis, use the basic eqn.
 - b) If slice is taken perpendicular to the axis, use the *Parallel-Axis* eqn.
2. Define slice size & moment arm to use.
Draw these on the sketch for reference.
3. Apply eqns previously derived and perform integration.
Integrate in the direction perpendicular to the slice.
4. Does the answer make sense?

