

# ENSC 2113

## Engineering Mechanics: Statics

Lecture 23  
Section 6.6



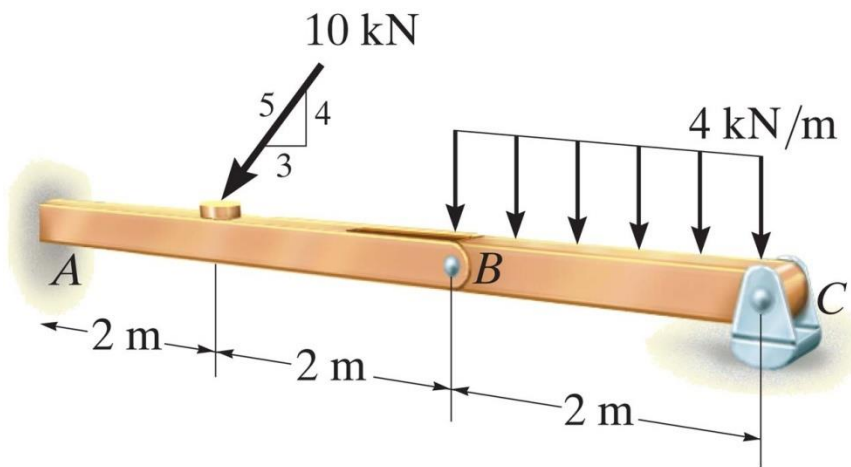
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## 6.6: Frames and Machines

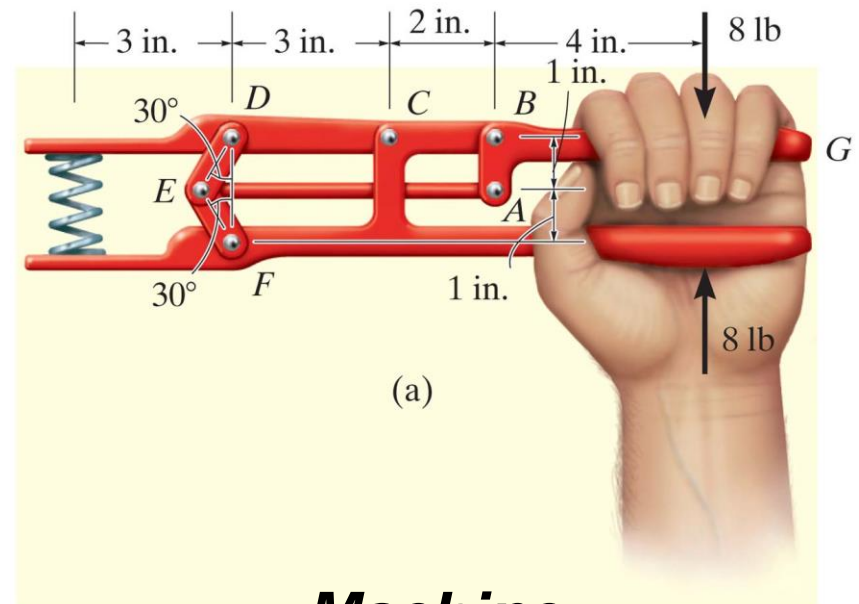
**Frames** and **Machines** are composed of pin-connected, multi-force members.

**Frames** are typically stationary ...

***Machines*** typically contain moving parts and transmit or alter the effects of forces and moments ...



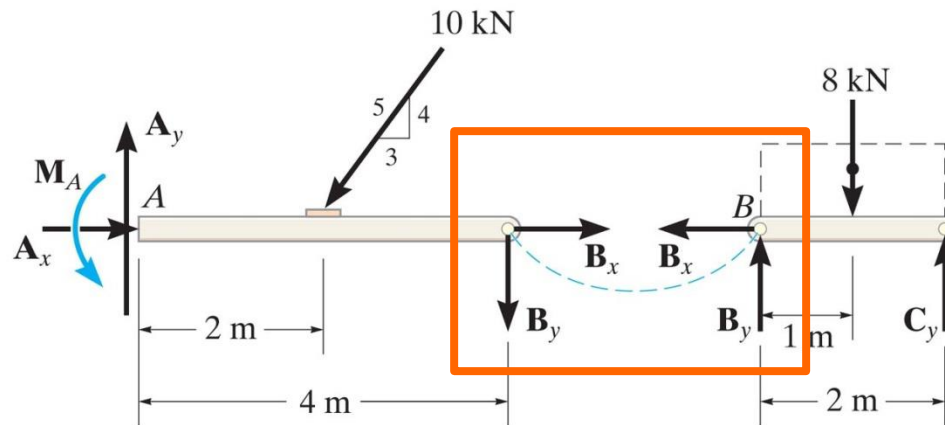
## Frame



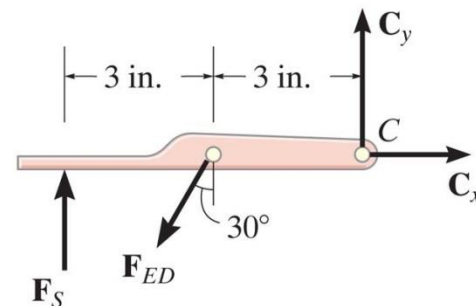
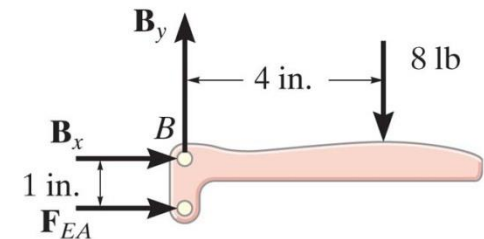
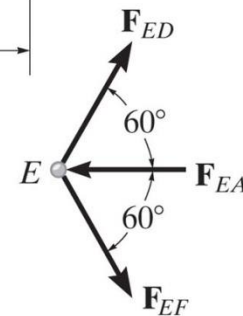
## Machine

For a coplanar system, remember that we only have 3 equilibrium eqns to use ...

For **Frames & Machines**, this often requires that we break the system into individual mbrs ...

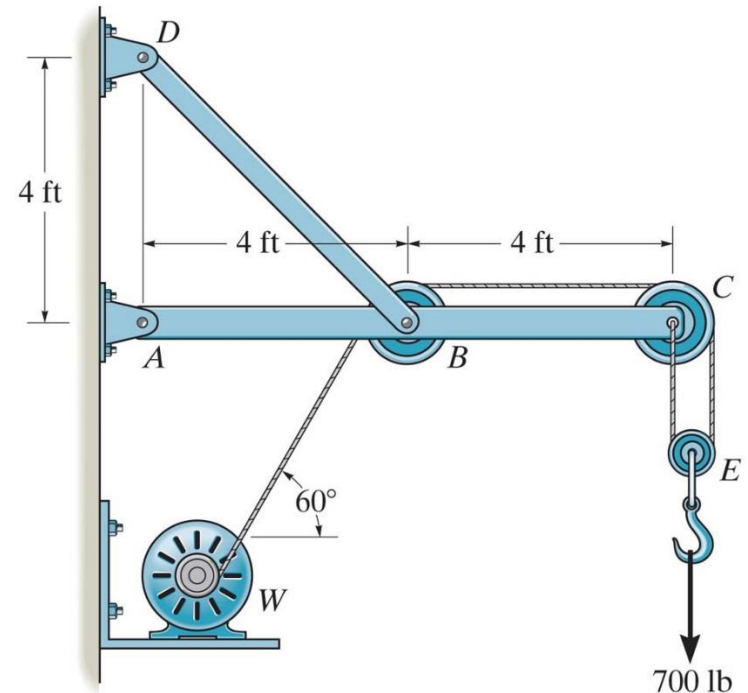
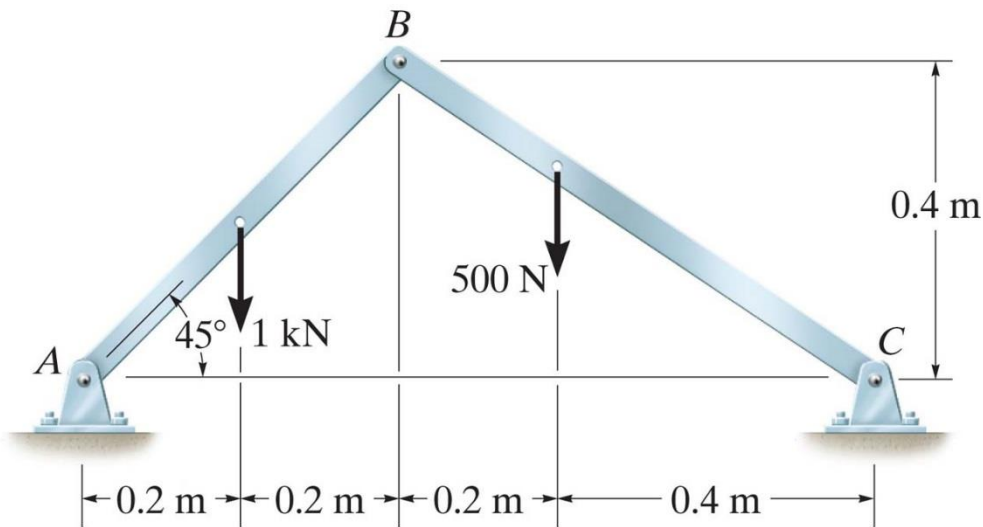


Internal forces at joints  
become equal magnitude  
acting in opposite directions ...



## Procedures for Analysis:

- 1) Draw **FBD** for frame or machine.
- 2) Identify all 2-force members.
- 3) Forces at connecting joints btwn mbrs will have equal & opposite forces applied to each mbr of the joint.
- 4) Apply equilibrium eqns to solve for unknown values.



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