

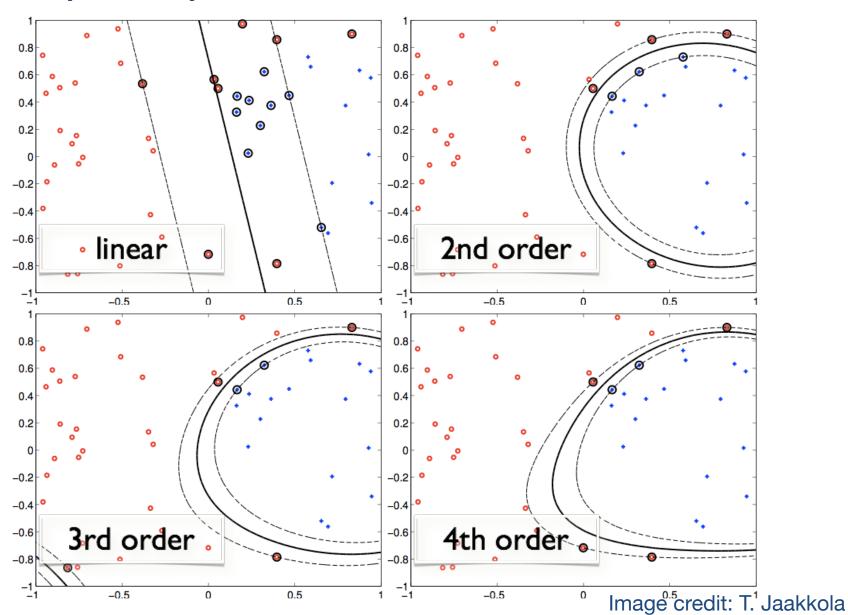
CSCI 5622 Fall 2020

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Today

- Intro. to Learning Theory
 - Complexity of classifiers
 - VC dimension
 - Margin
 - Sauer's lemma (if time)

Complexity of classifiers



We have seen various different hypothesis classes, e.g. linear separators, polynomial separators, decision trees, nearest-neighbor classifiers, etc.

How do we compare them? One way is to define a notion of the level of complexity of a hypothesis class H.

Complexity can be defined in various ways.

Complexity and the ability to generalize to future data are inversely related (as we have mentioned repeatedly!)

→ i.e. as complexity of the classifier increases, it can lead to overfitting.

Definition: Vapnik-Chervonenkis (VC) dimension.

The VC-dimension of a hypothesis class H is the maximum number of points that a classifier can shatter.

This is a measure of the complexity of H.

To prove that the VC dimension of a class H is V, you must prove both of the following:

- H can shatter V points.
- H cannot shatter V+1 points.

Shattering

Definition: A hypothesis class H can shatter n points if there exists a set of n points such that for every possible labeling of the points, there exists some h in H that can attain that labeling.

To prove that a hypothesis class H can shatter n points, you must:

- \exists give a point set S of size n
 - orall and show that for all possible labelings of S
 - ∃ there exists some h in H which achieves that labeling.

Shattering

To prove that a hypothesis class H cannot shatter n points you need to you need to show that:

- \forall for any set of n points
 - ∃ there exists some labeling of that configuration
 - y such that no h in H can achieve that labeling of that configuration (i.e. for all h in H, h cannot)

• Example: what is the VC dimension of decision stumps in R¹?

• Example: what is the VC dimension of decision stumps in R²?

Example: what is the VC dimension of 1-nearest-neighbor classifiers?

• Example: What is the VC dimension of linear classifiers in the plane (R²)?

Example: What is the VC dimension of linear classifiers in R^d?

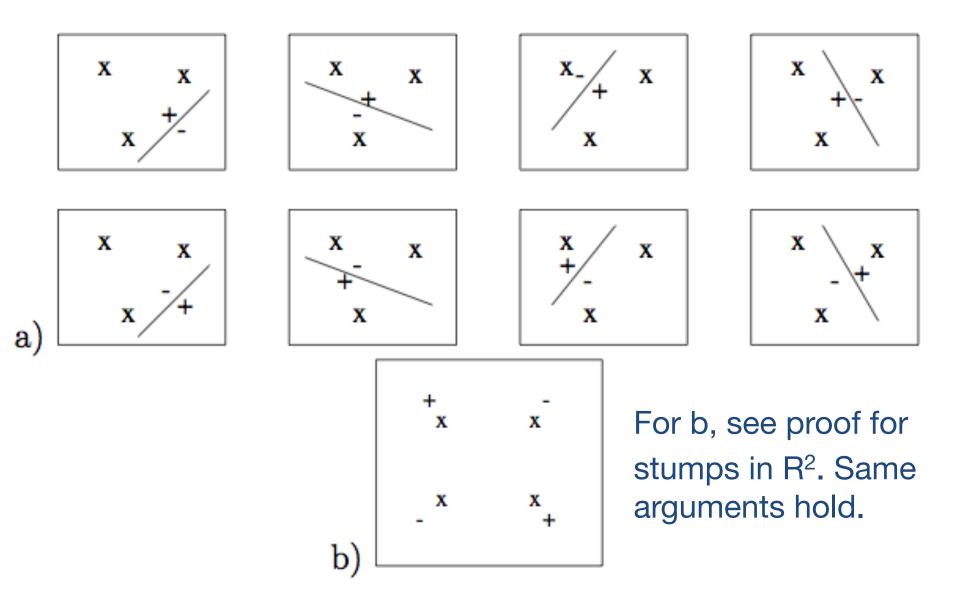


Image credit: T. Jaakkola

- The VC dimension of Linear Classifiers in R^d is: d+1
- If the data has margin r, and B upper bounds the norm of all points, then the VC dimension of Linear Classifiers in R^d is
 V ≤ (B/r)² [like perceptron mistake bound!]
- This means even if $d = \infty$ we can use linear separators and not suffer from high complexity, if there's a margin!
- Margin is therefore another measure of complexity.

Sauer's Lemma

Suppose you are given m (unlabeled) points.

Before we introduce Sauer's lemma, what's an upper bound on the number of possible (binary) labelings of the m points?

If we know that the VC dimension, V, of a class H is finite, then we can apply Sauer's lemma which says that the number of possible labelings of the m points that can be achieved by classifiers in H is $O(m^{V})$.

As long as we have more points than the VC dimension (i.e. m > V), this is a much tighter bound, i.e. $O(m^{V}) \le O(2^{m})$

Sauer's Lemma

Formally, given a hypothesis class H define H(m) as the maximum number of ways to label any set of m points using hypotheses in H. Let V = VC-dimension(H) $< \infty$.

Sauer's Lemma:

$$H(m) \le \sum_{i=1}^{V} {m \choose i} = O(m^V)$$

Effective size of H

Given a hypothesis class H, the size of H, |H|, is the number of classifiers in H.

This can be infinite, for example if H = {Linear Classifiers in R^d}

However, as soon as we fix a set of m (unlabeled) data points, M, the "effective" size of H becomes finite.

Group the hypotheses into equivalence classes, where each class contains all hypotheses in H that output the same labeling on M.

A (potentially loose) upper bound on the effective size of H is:

If H has finite VC dimension, V, what's a tighter upper bound on the effective size of H?