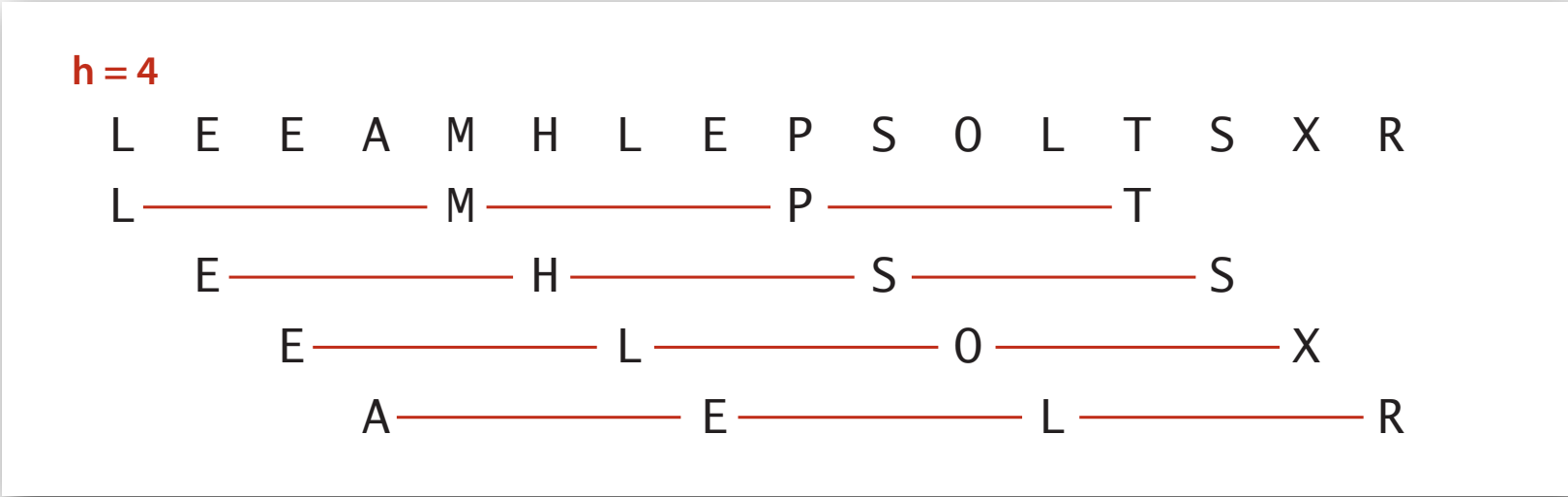


- ▶ **shellsort**
- ▶ shuffling
- ▶ convex hull

Shellsort overview

Idea. Move entries more than one position at a time by *h-sorting* the array.

an *h*-sorted array is *h* interleaved sorted subsequences



Shellsort. [Shell 1959] *h-sort* the array for decreasing sequence of values of *h*.

input	S	H	E	L	L	S	O	R	T	E	X	A	M	P	L	E
13-sort	P	H	E	L	L	S	O	R	T	E	X	A	M	S	L	E
4-sort	L	E	E	A	M	H	L	E	P	S	O	L	T	S	X	R
1-sort	A	E	E	E	H	L	L	L	M	O	P	R	S	S	T	X

How to *h*-sort an array? Insertion sort, with stride length *h*.

3-sorting an array

M	O	L	E	E	X	A	S	P	R	T
E	O	L	M	E	X	A	S	P	R	T
E	E	L	M	O	X	A	S	P	R	T
E	E	L	M	O	X	A	S	P	R	T
A	E	L	E	O	X	M	S	P	R	T
A	E	L	E	O	X	M	S	P	R	T
A	E	L	E	O	P	M	S	X	R	T
A	E	L	E	O	P	M	S	X	R	T
A	E	L	E	O	P	M	S	X	R	T
A	E	L	E	O	P	M	S	X	R	T

Why insertion sort?

- Big increments \Rightarrow small subarray.
- Small increments \Rightarrow nearly in order. [stay tuned]

Shellsort example: increments 7, 3, 1

input

S	O	R	T	E	X	A	M	P	L	E
---	---	---	---	---	---	---	---	---	---	---

7-sort

S	O	R	T	E	X	A	M	P	L	E
M	O	R	T	E	X	A	S	P	L	E
M	O	R	T	E	X	A	S	P	L	E
M	O	L	T	E	X	A	S	P	R	E
M	O	L	E	E	X	A	S	P	R	T

3-sort

M	O	L	E	E	X	A	S	P	R	T
E	O	L	M	E	X	A	S	P	R	T
E	E	L	M	O	X	A	S	P	R	T
E	E	L	M	O	X	A	S	P	R	T
A	E	L	E	O	X	M	S	P	R	T
A	E	L	E	O	X	M	S	P	R	T
A	E	L	E	O	P	M	S	X	R	T
A	E	L	E	O	P	M	S	X	R	T
A	E	L	E	O	P	M	S	X	R	T

1-sort

A	E	L	E	O	P	M	S	X	R	T
A	E	L	E	O	P	M	S	X	R	T
A	E	L	E	O	P	M	S	X	R	T
A	E	E	L	O	P	M	S	X	R	T
A	E	E	L	O	P	M	S	X	R	T
A	E	E	L	M	O	P	S	X	R	T
A	E	E	L	M	O	P	S	X	R	T
A	E	E	L	M	O	P	R	S	X	T
A	E	E	L	M	O	P	R	S	T	X

result

A	E	E	L	M	O	P	R	S	T	X
---	---	---	---	---	---	---	---	---	---	---

Shellsort: intuition

Proposition. A g -sorted array remains g -sorted after h -sorting it.

7-sort

M	O	R	T	E	X	A	S	P	L	E
M	O	R	T	E	X	A	S	P	L	E
M	O	L	T	E	X	A	S	P	R	E
M	O	L	E	E	X	A	S	P	R	T
M	O	L	E	E	X	A	S	P	R	T

3-sort

M	O	L	E	E	X	A	S	P	R	T
E	O	L	M	E	X	A	S	P	R	T
E	E	L	M	O	X	A	S	P	R	T
E	E	L	M	O	X	A	S	P	R	T
A	E	L	E	O	X	M	S	P	R	T
A	E	L	E	O	X	M	S	P	R	T
A	E	L	E	O	P	M	S	X	R	T
A	E	L	E	O	P	M	S	X	R	T
A	E	L	E	O	P	M	S	X	R	T
A	E	L	E	O	P	M	S	X	R	T

still 7-sorted

Challenge. Prove this fact—it's more subtle than you'd think!

Shellsort: which increment sequence to use?

Powers of two. 1, 2, 4, 8, 16, 32, ...

No.

Powers of two minus one. 1, 3, 7, 15, 31, 63, ...

Maybe.

→ $3x + 1$. 1, 4, 13, 40, 121, 364, ...

OK. Easy to compute.

merging of $(9 \times 4^i) - (9 \times 2^i) + 1$ and $4^i - (3 \times 2^i) + 1$

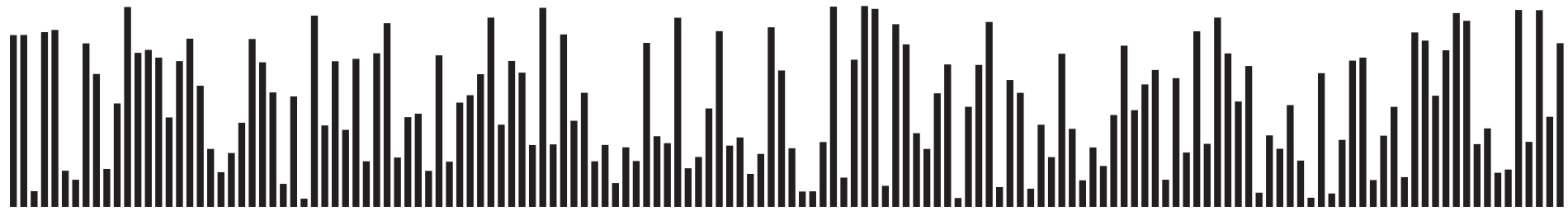


Sedgewick. 1, 5, 19, 41, 109, 209, 505, 929, 2161, 3905, ...

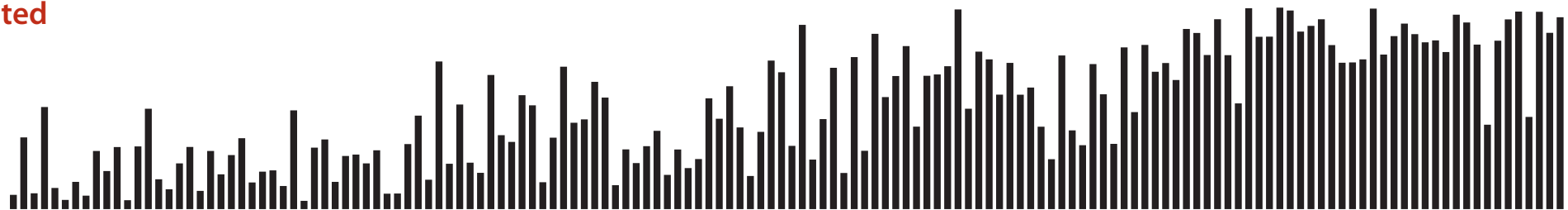
Good. Tough to beat in empirical studies.

Shellsort: visual trace

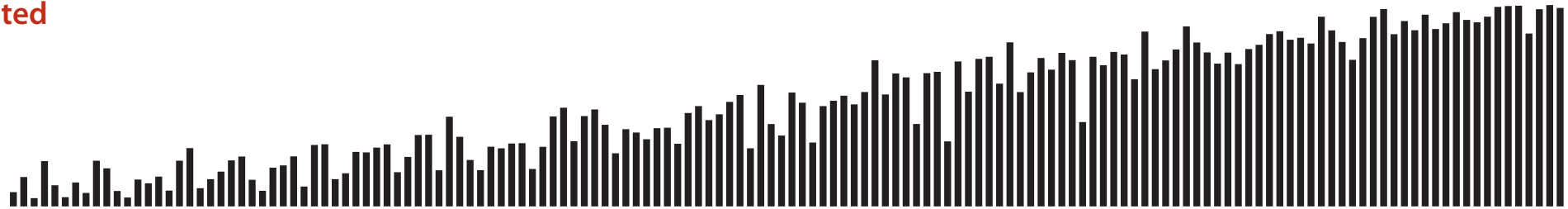
input



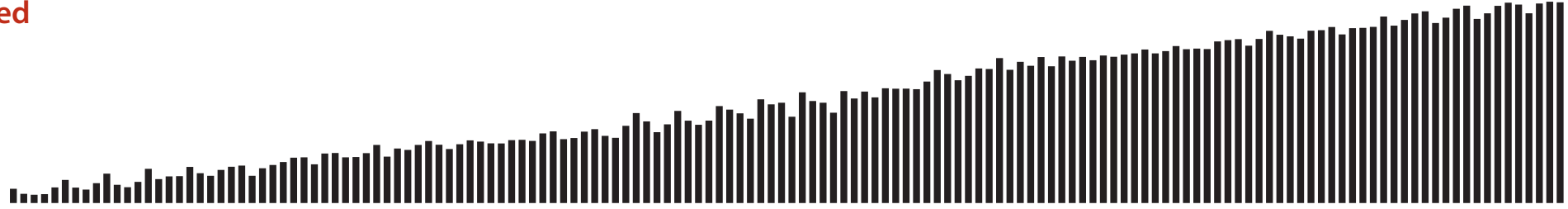
40-sorted



13-sorted



4-sorted

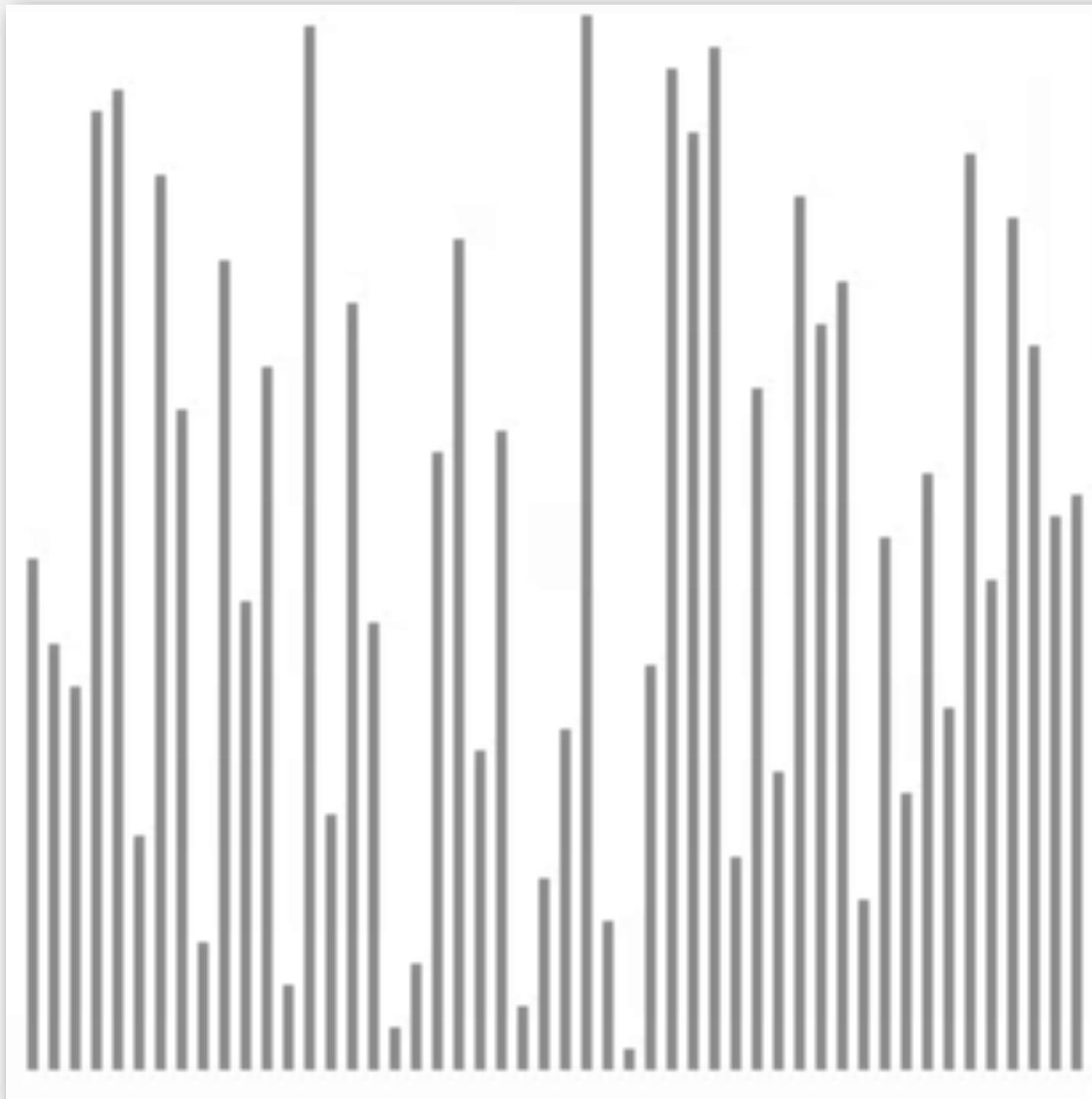


result



Shellsort: animation

50 random items

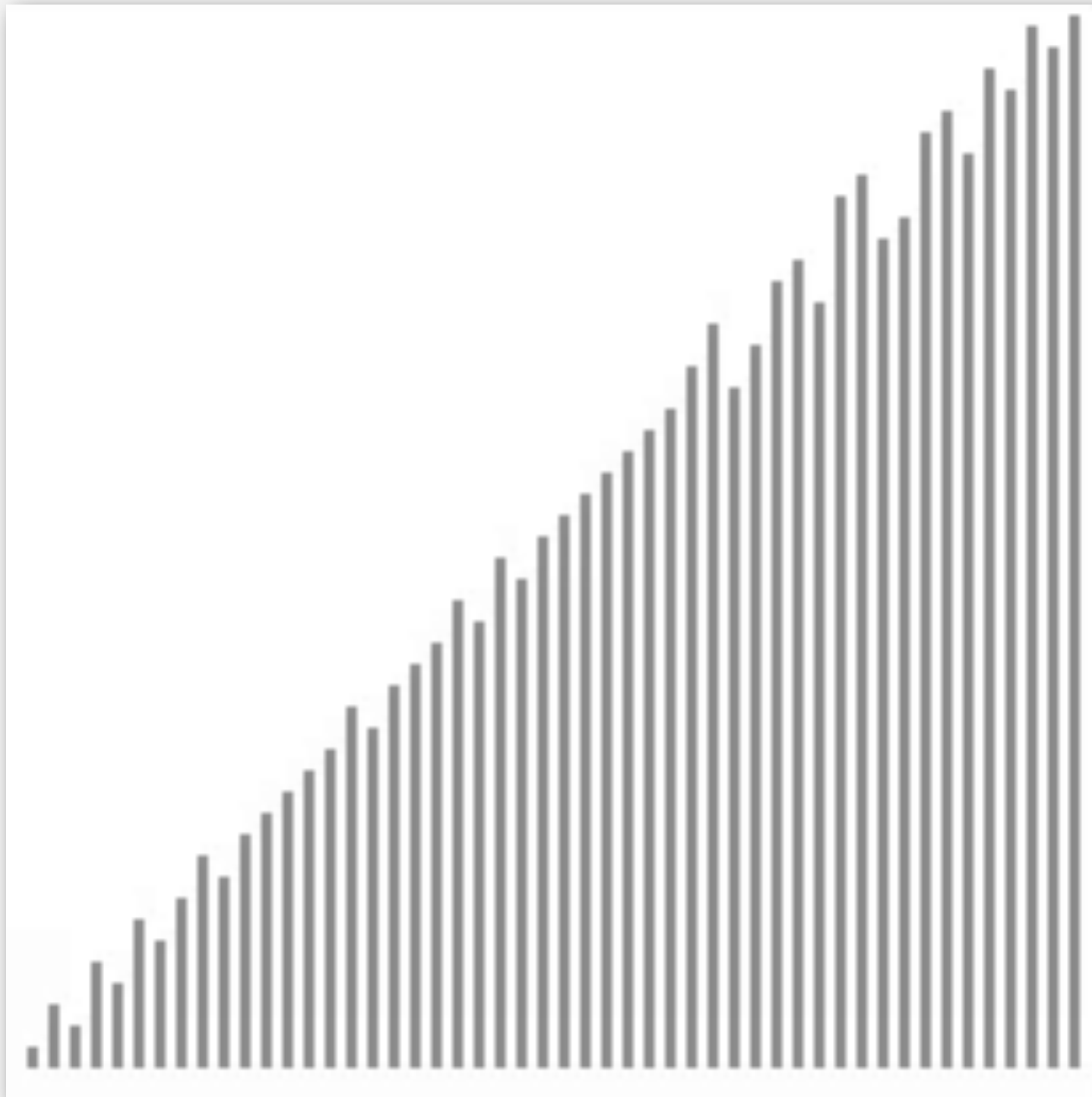


<http://www.sorting-algorithms.com/shell-sort>

- ▲ algorithm position
- h-sorted
- current subsequence
- other elements

Shellsort: animation

50 partially-sorted items



<http://www.sorting-algorithms.com/shell-sort>

- ▲ algorithm position
- h-sorted
- current subsequence
- other elements

Shellsort: analysis

Proposition. The worst-case number of compares used by shellsort with the $3x+1$ increments is $O(N^{3/2})$.

Property. The number of compares used by shellsort with the $3x+1$ increments is at most by a small multiple of N times the # of increments used.

N	compares	N	$2.5 N \lg N$
5,000	93	58	106
10,000	209	143	230
20,000	467	349	495
40,000	1022	855	1059
80,000	2266	2089	2257

measured in thousands

Remark. Accurate model has not yet been discovered (!)

Why are we interested in shellsort?

Example of simple idea leading to substantial performance gains.

Useful in practice.

- Fast unless array size is huge.
- Tiny, fixed footprint for code (used in embedded systems).
- Hardware sort prototype.
- Shellsort: Tradeoff between size and partial order in the subseq
 - beginning: shorter;
 - later in the sort subsequence are partially ordered

Simple algorithm, nontrivial performance, interesting questions.

- Asymptotic growth rate?
- Best sequence of increments?
- Average-case performance?

MERGESORT

- ▶ mergesort
- ▶ bottom-up mergesort
- ▶ sorting complexity
- ▶ stability

Two classic sorting algorithms

Critical components in the world's computational infrastructure.

- Full scientific understanding of their properties has enabled us to develop them into practical system sorts.
- Quicksort honored as one of top 10 algorithms of 20th century in science and engineering.

Mergesort.

- Java sort for objects.
- Perl, C++ stable sort, Python stable sort, Firefox JavaScript, ...

Quicksort.

- Java sort for primitive types.
- C qsort, Unix, Visual C++, Python, Matlab, Chrome JavaScript, ...

- ▶ **mergesort**
- ▶ bottom-up mergesort
- ▶ sorting complexity
- ▶ stability

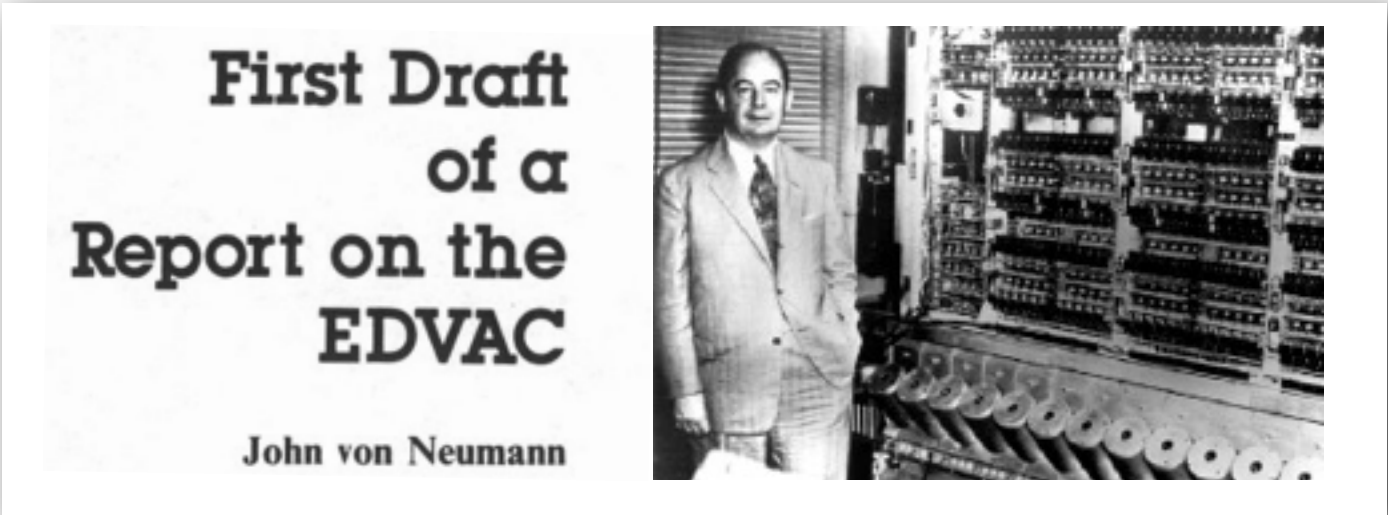
Mergesort

Basic plan.

- Divide array into two halves.
- **Recursively** sort each half.
- Merge two halves.

input	M	E	R	G	E	S	O	R	T	E	X	A	M	P	L	E
sort left half	E	E	G	M	O	R	R	S	T	E	X	A	M	P	L	E
sort right half	E	E	G	M	O	R	R	S	A	E	E	L	M	P	T	X
merge results	A	E	E	E	E	G	L	M	M	O	P	R	R	S	T	X

Mergesort overview



Merging

Q. How to combine two sorted subarrays into a sorted whole.

A. Use an auxiliary array.

a[]											aux[]												
	k	0	1	2	3	4	5	6	7	8	9	i	j	0	1	2	3	4	5	6	7	8	9
input		E	E	G	M	R	A	C	E	R	T			-	-	-	-	-	-	-	-	-	-
copy		E	E	G	M	R	A	C	E	R	T			E	E	G	M	R	A	C	E	R	T
												0	5										
	0	A										0	6	E	E	G	M	R	A	C	E	R	T
	1	A	C									0	7	E	E	G	M	R		C	E	R	T
	2	A	C	E								1	7	E	E	G	M	R			E	R	T
	3	A	C	E	E							2	7		E	G	M	R			E	R	T
	4	A	C	E	E	E						2	8			G	M	R		E	R	T	
	5	A	C	E	E	E	G					3	8			G	M	R				R	T
	6	A	C	E	E	E	G	M				4	8				M	R				R	T
	7	A	C	E	E	E	G	M	R			5	8					R				R	T
	8	A	C	E	E	E	G	M	R	R		5	9								R	T	
	9	A	C	E	E	E	G	M	R	R	T	6	10										T
merged result		A	C	E	E	E	G	M	R	R	T												

Abstract in-place merge trace

Mergesort: trace

	lo	hi	a[]															
			0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
			M	E	R	G	E	S	O	R	T	E	X	A	M	P	L	E
merge(a,	0	0, 1)	E	M	R	G	E	S	O	R	T	E	X	A	M	P	L	E
merge(a,	2	2, 3)	E	M	G	R	E	S	O	R	T	E	X	A	M	P	L	E
merge(a,	0	1, 3)	E	G	M	R	E	S	O	R	T	E	X	A	M	P	L	E
merge(a,	4	4, 5)	E	G	M	R	E	S	O	R	T	E	X	A	M	P	L	E
merge(a,	6	6, 7)	E	G	M	R	E	S	O	R	T	E	X	A	M	P	L	E
merge(a,	4	5, 7)	E	G	M	R	E	O	R	S	T	E	X	A	M	P	L	E
merge(a,	0	3, 7)	E	E	G	M	O	R	R	S	T	E	X	A	M	P	L	E
merge(a,	8	8, 9)	E	E	G	M	O	R	R	S	E	T	X	A	M	P	L	E
merge(a,	10	10, 11)	E	E	G	M	O	R	R	S	E	T	A	X	M	P	L	E
merge(a,	8	9, 11)	E	E	G	M	O	R	R	S	A	E	T	X	M	P	L	E
merge(a,	12	12, 13)	E	E	G	M	O	R	R	S	A	E	T	X	M	P	L	E
merge(a,	14	14, 15)	E	E	G	M	O	R	R	S	A	E	T	X	M	P	E	L
merge(a,	12	13, 15)	E	E	G	M	O	R	R	S	A	E	T	X	E	L	M	P
merge(a,	8	11, 15)	E	E	G	M	O	R	R	S	A	E	E	L	M	P	T	X
merge(a,	0	7, 15)	A	E	E	E	E	G	L	M	M	O	P	R	R	S	T	X

Trace of merge results for top-down mergesort

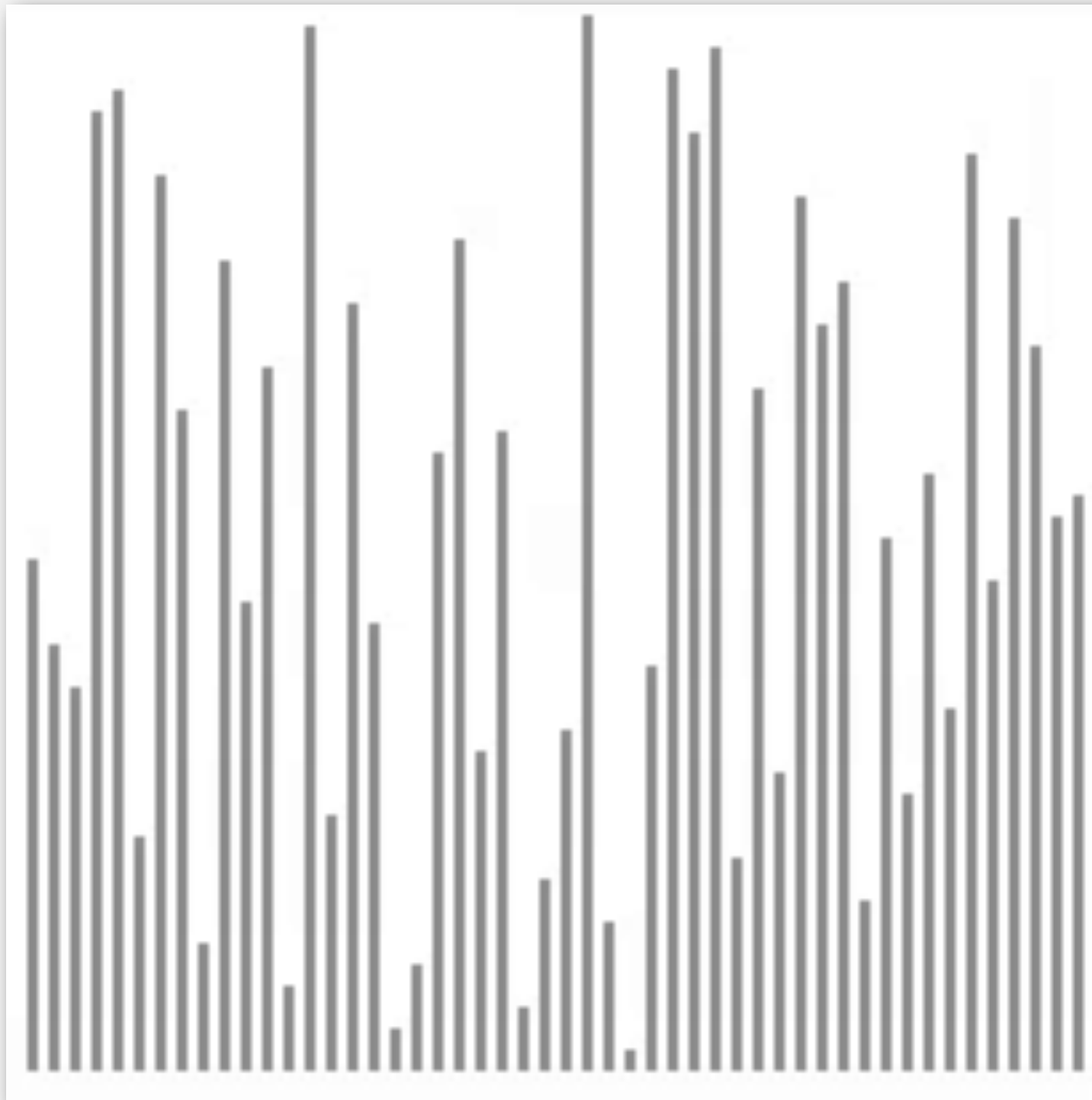
A. n log n

n → merge

result after recursive call

Mergesort: animation

50 random items

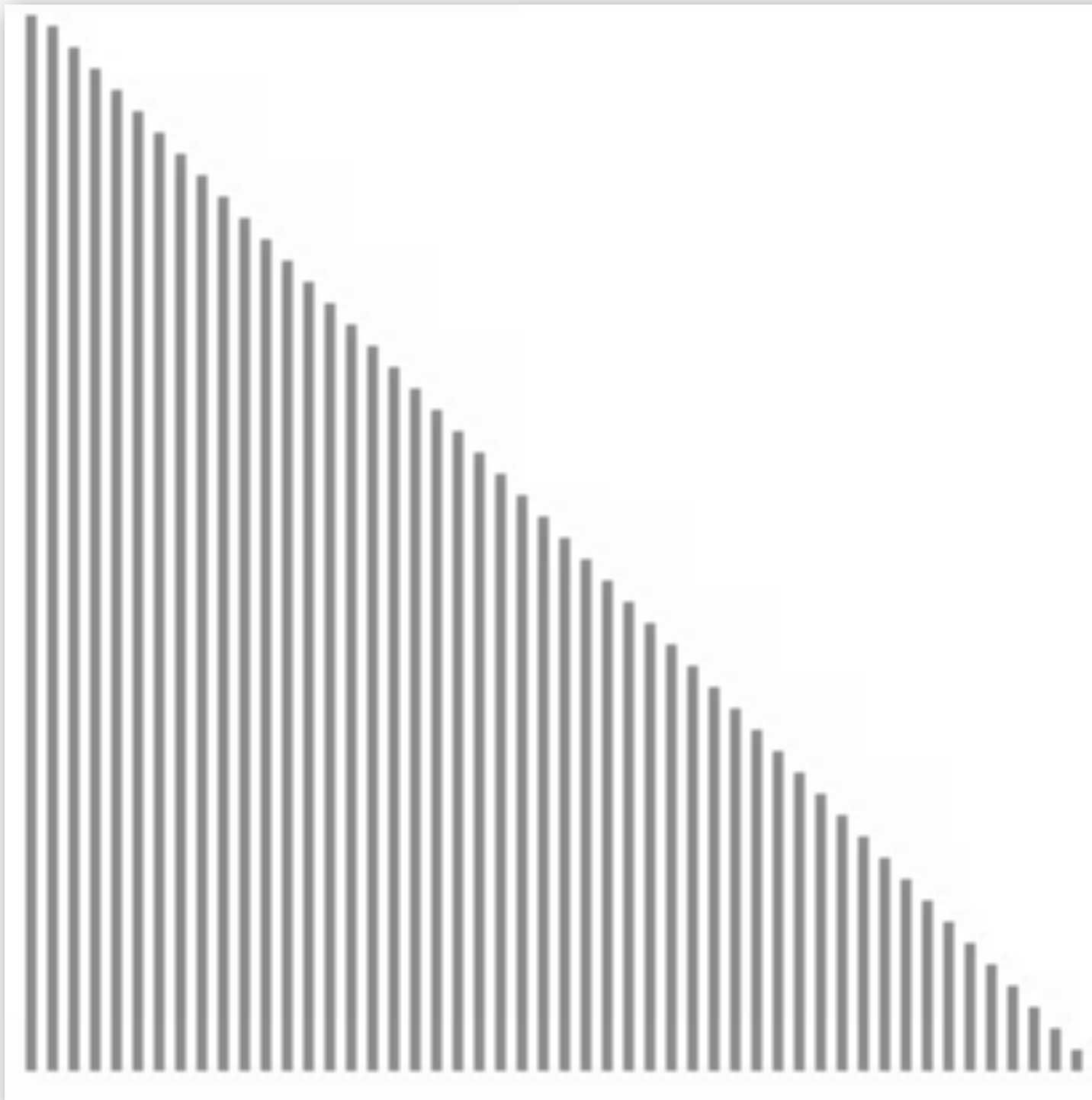


<http://www.sorting-algorithms.com/merge-sort>

- ▲ algorithm position
- in order
- current subarray
- not in order

Mergesort: animation

50 reverse-sorted items



<http://www.sorting-algorithms.com/merge-sort>

W n Legn

- ▲ algorithm position
- ▬ in order
- ▬ current subarray
- ▬ not in order

Mergesort: empirical analysis

Running time estimates:

- Laptop executes 10^8 compares/second.
- Supercomputer executes 10^{12} compares/second.

	insertion sort (N)			mergesort (N log N)		
computer	thousand	million	billion	thousand	million	billion
home	instant	2.8 hours	317 years	instant	1 second	18 min
super	instant	1 second	1 week	instant	instant	instant

Bottom line. Good algorithms are better than supercomputers.

Mergesort: number of compares and array accesses

Proposition. Mergesort uses at most $N \lg N$ compares and $6 N \lg N$ array accesses to sort any array of size N .

Pf sketch. The number of compares $C(N)$ and array accesses $A(N)$ to mergesort an array of size N satisfy the recurrences:

$$C(N) \leq C(\lceil N/2 \rceil) + C(\lfloor N/2 \rfloor) + N \quad \text{for } N > 1, \text{ with } C(1) = 0.$$

↑
left half

↑
right half

↑
merge

$$A(N) \leq A(\lceil N/2 \rceil) + A(\lfloor N/2 \rfloor) + 6N \quad \text{for } N > 1, \text{ with } A(1) = 0.$$

We solve the simpler divide-and-conquer recurrence when N is a power of 2.

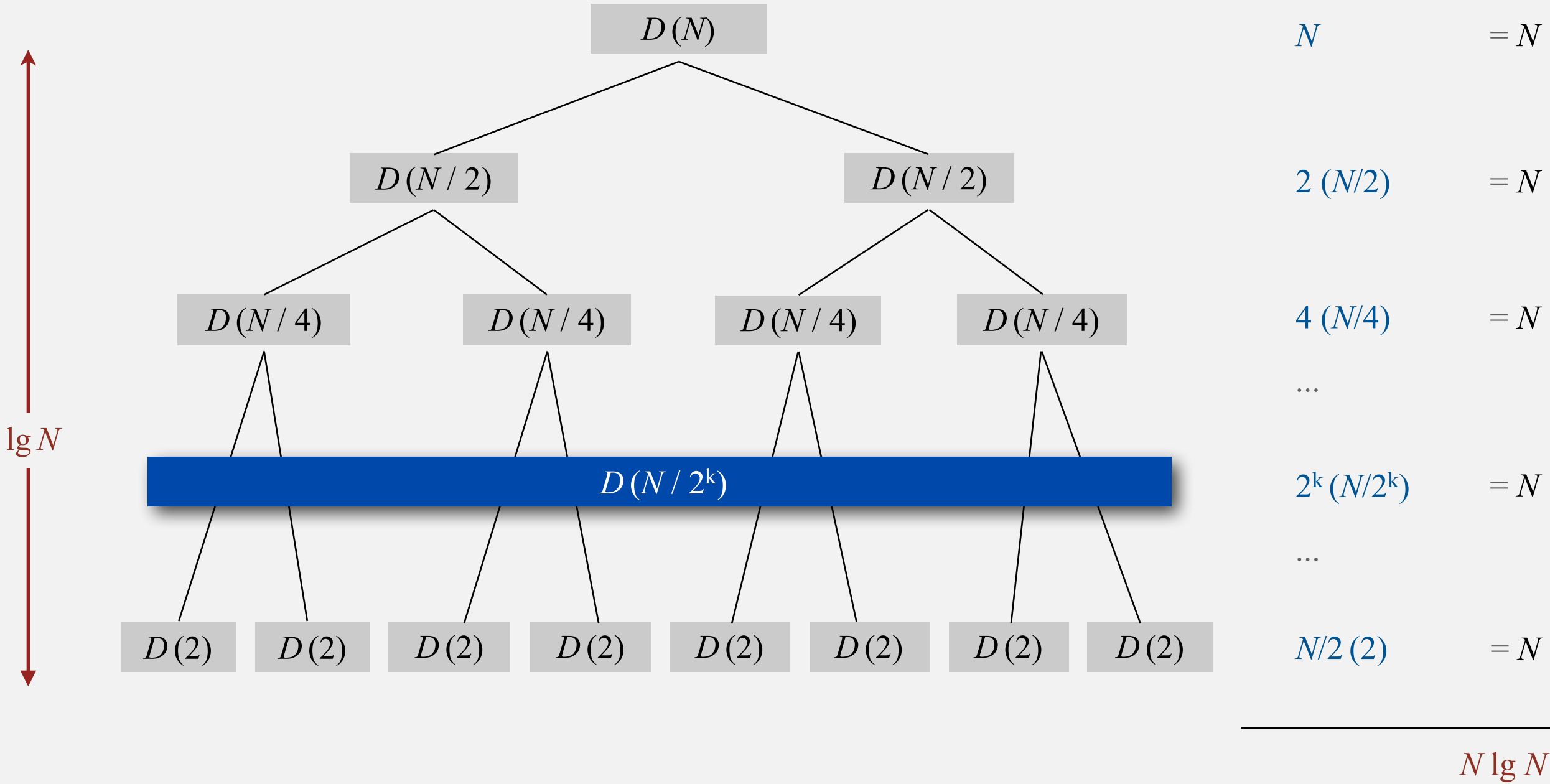
$$D(N) = 2 D(N/2) + N, \text{ for } N > 1, \text{ with } D(1) = 0.$$

↑
result holds for all N

Divide-and-conquer recurrence: proof by picture

Proposition. If $D(N)$ satisfies $D(N) = 2 D(N/2) + N$ for $N > 1$, with $D(1) = 0$, then $D(N) = N \lg N$.

Pf 1. [assuming N is a power of 2]



Divide-and-conquer recurrence: proof by expansion

Proposition. If $D(N)$ satisfies $D(N) = 2 D(N/2) + N$ for $N > 1$, with $D(1) = 0$, then $D(N) = N \lg N$.

Pf 2. [assuming N is a power of 2]

$$D(N) = 2 D(N/2) + N$$

given

$$D(N) / N = 2 D(N/2) / N + 1$$

divide both sides by N

$$= D(N/2) / (N/2) + 1$$

algebra

$$= D(N/4) / (N/4) + 1 + 1$$

apply to first term

$$= D(N/8) / (N/8) + 1 + 1 + 1$$

apply to first term again

...

$$= D(N/N) / (N/N) + 1 + 1 + \dots + 1$$

$$= \lg N$$

stop applying, $D(1) = 0$

Divide-and-conquer recurrence: proof by induction

Proposition. If $D(N)$ satisfies $D(N) = 2 D(N/2) + N$ for $N > 1$, with $D(1) = 0$, then $D(N) = N \lg N$.

Pf 3. [assuming N is a power of 2]

- Base case: $N = 1$.
- Inductive hypothesis: $D(N) = N \lg N$.
- Goal: show that $D(2N) = (2N) \lg (2N)$.

$$D(2N) = 2 D(N) + 2N$$

given

$$= 2 N \lg N + 2N$$

inductive hypothesis

$$= 2 N (\lg (2N) - 1) + 2N$$

algebra

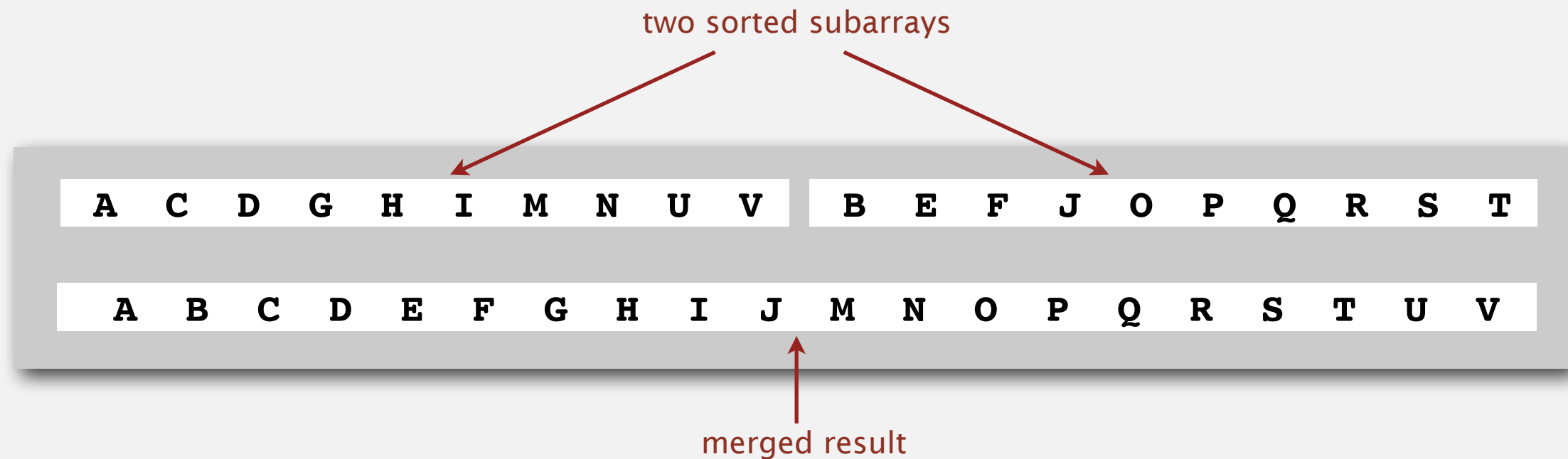
$$= 2 N \lg (2N)$$

QED

Mergesort analysis: memory

Proposition. Mergesort uses extra space proportional to N .

Pf. The array `aux[]` needs to be of size N for the last merge.



Def. A sorting algorithm is **in-place** if it uses $O(\log N)$ extra memory.

Ex. Insertion sort, selection sort, shellsort.

Mergesort: practical improvements

Use insertion sort for small subarrays.

- Mergesort has too much overhead for tiny subarrays.
- Cutoff to insertion sort for ≈ 7 items.

```
private static void sort(Comparable[] a, Comparable[] aux, int lo, int hi)
{
    if (hi <= lo + CUTOFF - 1) Insertion.sort(a, lo, hi);
    int mid = lo + (hi - lo) / 2;
    sort(a, aux, lo, mid);
    sort(a, aux, mid+1, hi);
    merge(a, aux, lo, mid, hi);
}
```

Mergesort: practical improvements

Stop if already sorted.

- Is biggest item in first half \leq smallest item in second half?
- Helps for partially-ordered arrays.

A B C D E F G H I J

M N O P Q R S T U V

A B C D E F G H I J M N O P Q R S T U V

```
private static void sort(Comparable[] a, Comparable[] aux, int lo, int hi)
{
    if (hi <= lo) return;
    int mid = lo + (hi - lo) / 2;
    sort(a, aux, lo, mid);
    sort(a, aux, mid+1, hi);
    if (!less(a[mid+1], a[mid])) return;
    merge(a, aux, lo, mid, hi);
}
```

Mergesort: practical improvements

Eliminate the copy to the auxiliary array. Save time (but not space) by switching the role of the input and auxiliary array in each recursive call.

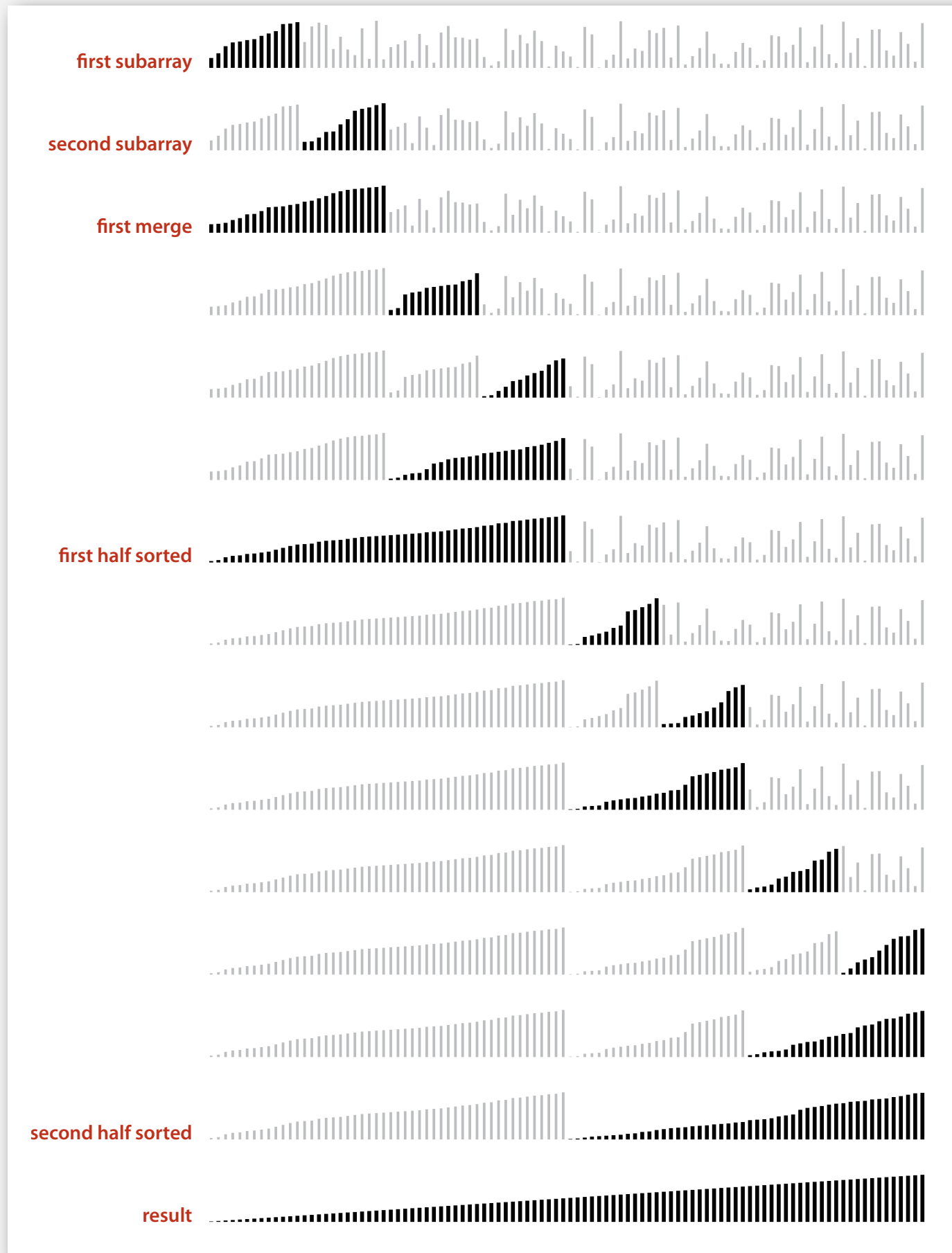
```
private static void merge(Comparable[] a, Comparable[] aux, int lo, int mid, int hi)
{
    int i = lo, j = mid+1;
    for (int k = lo; k <= hi; k++)
    {
        if (i > mid)          aux[k] = a[j++];
        else if (j > hi)      aux[k] = a[i++];
        else if (less(a[j], a[i])) aux[k] = a[j++];
        else                  aux[k] = a[i++];
    }
}

private static void sort(Comparable[] a, Comparable[] aux, int lo, int hi)
{
    if (hi <= lo) return;
    int mid = lo + (hi - lo) / 2;
    sort (aux, a, lo, mid);
    sort (aux, a, mid+1, hi);
    merge(aux, a, lo, mid, hi);
}
```

← merge from a[] to aux[]

↑ switch roles of aux[] and a[]

Mergesort: visualization



- ▶ mergesort
- ▶ **bottom-up mergesort**
- ▶ sorting complexity
- ▶ stability

Bottom-up mergesort

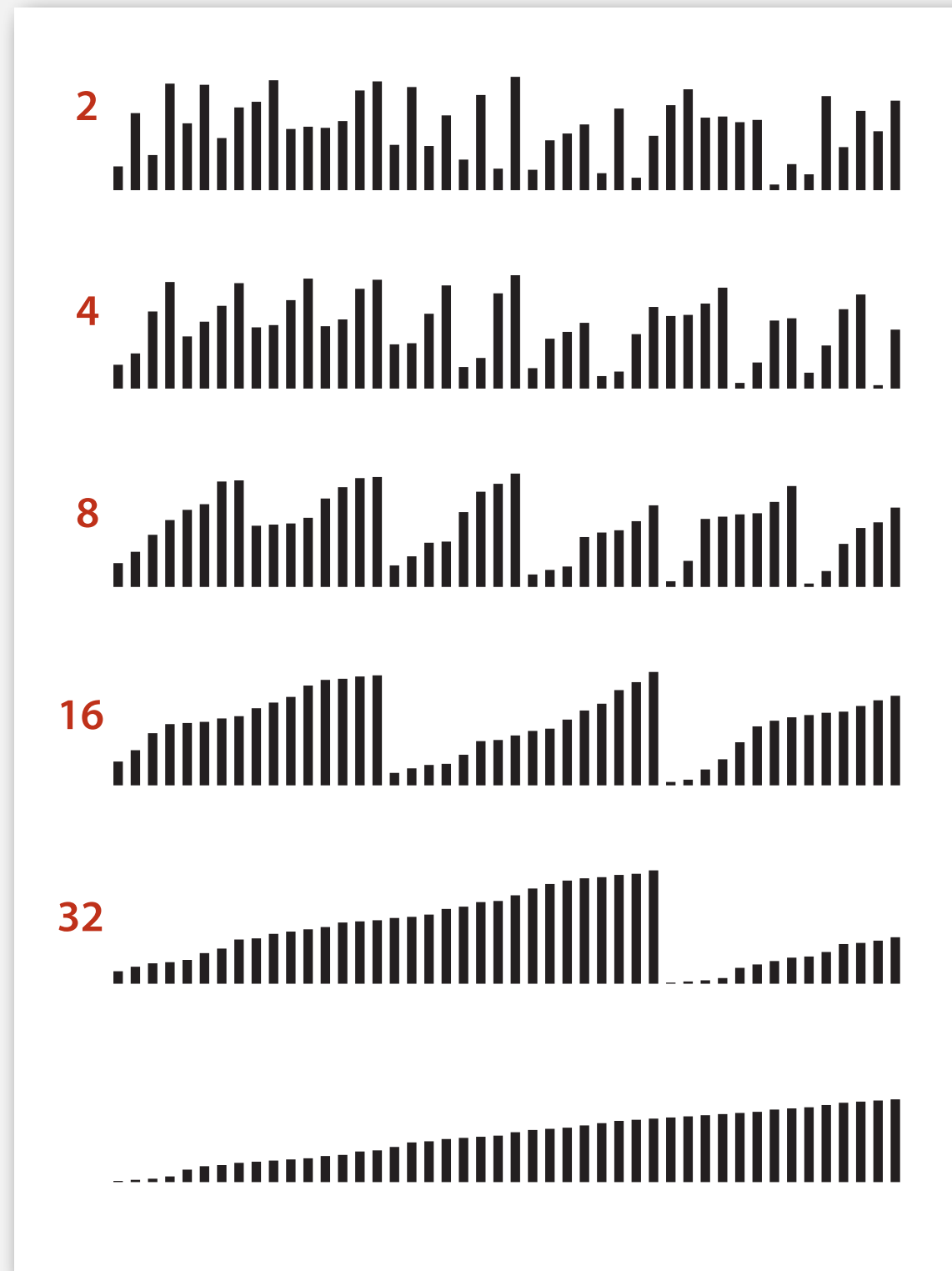
Basic plan.

- Pass through array, merging subarrays of size 1.
- Repeat for subarrays of size 2, 4, 8, 16,

	a[i]															
	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
sz = 1																
merge(a, 0, 0, 1)	E	M	R	G	E	S	O	R	T	E	X	A	M	P	L	E
merge(a, 2, 2, 3)	E	M	G	R	E	S	O	R	T	E	X	A	M	P	L	E
merge(a, 4, 4, 5)	E	M	G	R	E	S	O	R	T	E	X	A	M	P	L	E
merge(a, 6, 6, 7)	E	M	G	R	E	S	O	R	T	E	X	A	M	P	L	E
merge(a, 8, 8, 9)	E	M	G	R	E	S	O	R	E	T	X	A	M	P	L	E
merge(a, 10, 10, 11)	E	M	G	R	E	S	O	R	E	T	A	X	M	P	L	E
merge(a, 12, 12, 13)	E	M	G	R	E	S	O	R	E	T	A	X	M	P	L	E
merge(a, 14, 14, 15)	E	M	G	R	E	S	O	R	E	T	A	X	M	P	E	L
sz = 2																
merge(a, 0, 1, 3)	E	G	M	R	E	S	O	R	E	T	A	X	M	P	E	L
merge(a, 4, 5, 7)	E	G	M	R	E	O	R	S	E	T	A	X	M	P	E	L
merge(a, 8, 9, 11)	E	G	M	R	E	O	R	S	A	E	T	X	M	P	E	L
merge(a, 12, 13, 15)	E	G	M	R	E	O	R	S	A	E	T	X	E	L	M	P
sz = 4																
merge(a, 0, 3, 7)	E	E	G	M	O	R	R	S	A	E	T	X	E	L	M	P
merge(a, 8, 11, 15)	E	E	G	M	O	R	R	S	A	E	E	L	M	P	T	X
sz = 8																
merge(a, 0, 7, 15)	A	E	E	E	E	G	L	M	M	O	P	R	R	S	T	X

Bottom line. No recursion needed!

Bottom-up mergesort: visual trace



- ▶ mergesort
- ▶ bottom-up mergesort
- ▶ **sorting complexity**
- ▶ stability

Complexity of sorting

Computational complexity. Framework to study efficiency of algorithms for solving a particular problem X .

Model of computation. Allowable operations.

Cost model. Operation count(s).

Upper bound. Cost guarantee provided by **some** algorithm for X .

Lower bound. Proven limit on cost guarantee of **all** algorithms for X .

Optimal algorithm. Algorithm with best possible cost guarantee for X .


lower bound ~ upper bound



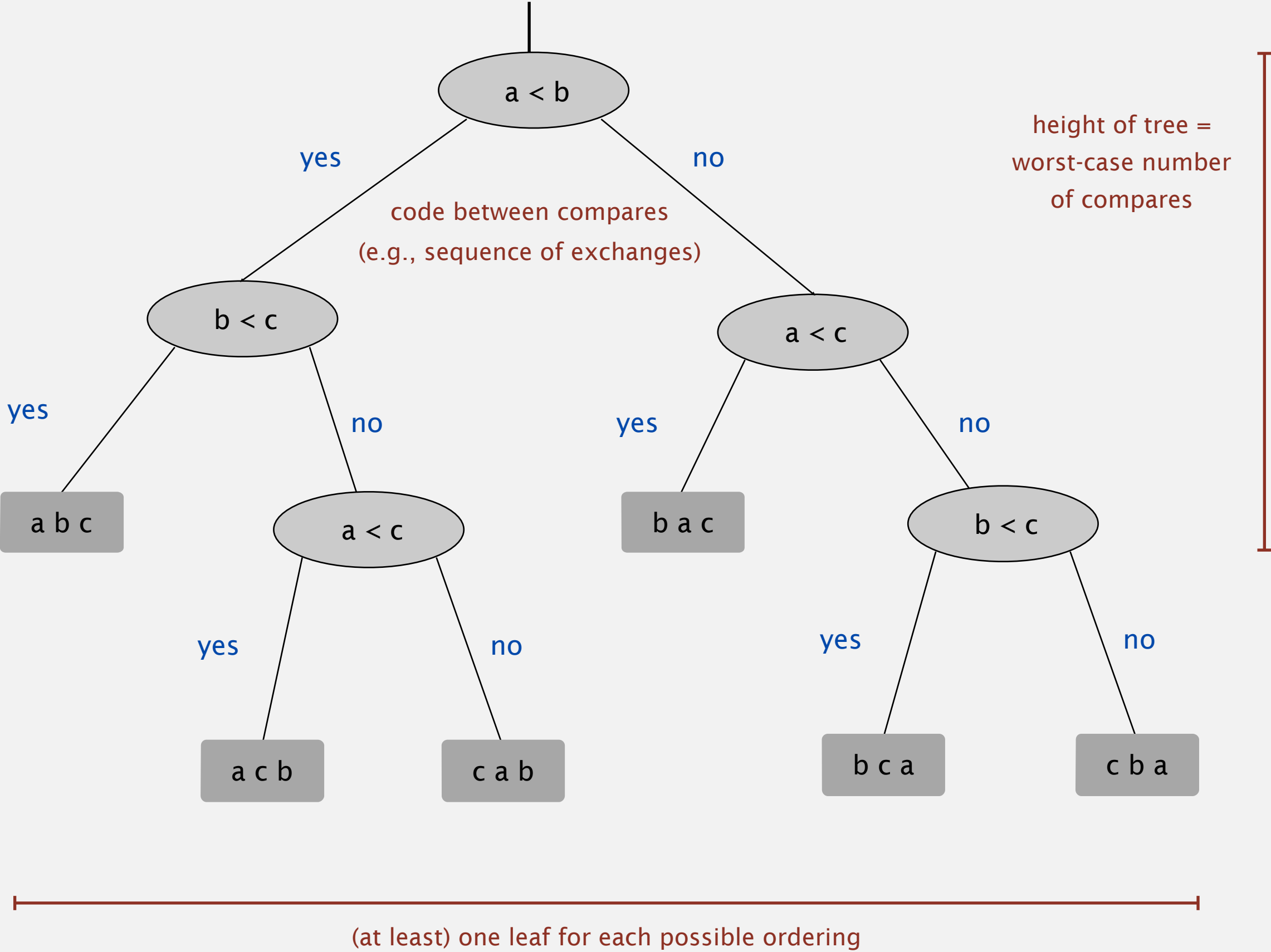
Example: sorting.

- Model of computation: decision tree.
- Cost model: # compares.
- Upper bound: $\sim N \lg N$ from mergesort.
- Lower bound: ?
- Optimal algorithm: ?

can access information
only through compares



Decision tree (for 3 distinct items a, b, and c)

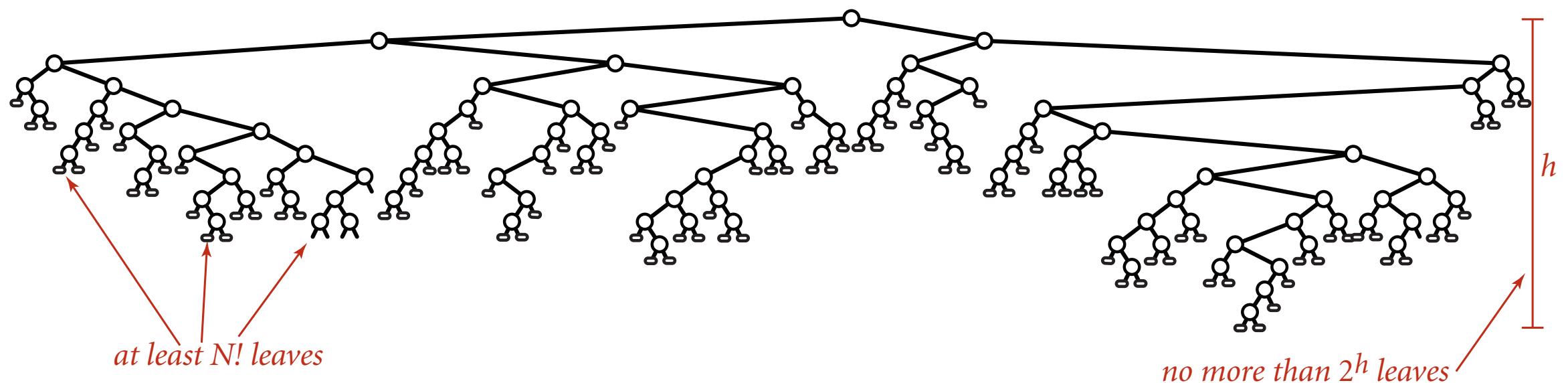


Compare-based lower bound for sorting

Proposition. Any compare-based sorting algorithm must use at least $\lg(N!) \sim N \lg N$ compares in the worst-case.

Pf.

- Assume array consists of N distinct values a_1 through a_N .
- Worst case dictated by **height** h of decision tree.
- Binary tree of height h has at most 2^h leaves.
- $N!$ different orderings \Rightarrow at least $N!$ leaves.



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- Worst case dictated by **height** h of decision tree.
- Binary tree of height h has at most 2^h leaves.
- $N!$ different orderings \Rightarrow at least $N!$ leaves.

$$2^h \geq \# \text{ leaves} \geq N!$$

$$\Rightarrow h \geq \lg(N!) \sim N \lg N$$

↑
Stirling's formula

Complexity of sorting

Model of computation. Allowable operations.

Cost model. Operation count(s).

Upper bound. Cost guarantee provided by some algorithm for X .

Lower bound. Proven limit on cost guarantee of all algorithms for X .

Optimal algorithm. Algorithm with best possible cost guarantee for X .

Example: sorting.

- Model of computation: decision tree.
- Cost model: # compares.
- Upper bound: $\sim N \lg N$ from mergesort.
- Lower bound: $\sim N \lg N$.
- **Optimal algorithm = mergesort.**

First goal of algorithm design: optimal algorithms.

Complexity results in context

Other operations? Mergesort is optimal with respect to number of compares (e.g., but not with respect to number of array accesses).

Space?

- Mergesort is **not optimal** with respect to space usage.
- Insertion sort, selection sort, and shellsort are space-optimal.

Challenge. Find an algorithm that is both time- and space-optimal.

Lessons. Use theory as a guide.

Ex. Don't try to design sorting algorithm that guarantees $\frac{1}{2} N \lg N$ compares.

Complexity results in context (continued)

Lower bound may not hold if the algorithm has information about:

- The initial order of the input.
- The distribution of key values.
- The representation of the keys.

Partially-ordered arrays. Depending on the initial order of the input, we may not need $N \lg N$ compares.

↖ insertion sort requires only $N-1$ compares if input array is sorted

Duplicate keys. Depending on the input distribution of duplicates, we may not need $N \lg N$ compares.

↖ stay tuned for 3-way quicksort

Digital properties of keys. We can use digit/character compares instead of key compares for numbers and strings.

↖ radix sorts..

- ▶ mergesort
- ▶ bottom-up mergesort
- ▶ sorting complexity
- ▶ **stability**

A typical application. First, sort by name; **then** sort by section.

```
Selection.sort(a, Student.BY_NAME);
```

Andrews	3	A	664-480-0023	097 Little
Battle	4	C	874-088-1212	121 Whitman
Chen	3	A	991-878-4944	308 Blair
Fox	3	A	884-232-5341	11 Dickinson
Furia	1	A	766-093-9873	101 Brown
Gazsi	4	B	766-093-9873	101 Brown
Kanaga	3	B	898-122-9643	22 Brown
Rohde	2	A	232-343-5555	343 Forbes

```
Selection.sort(a, Student.BY_SECTION);
```

Furia	1	A	766-093-9873	101 Brown
Rohde	2	A	232-343-5555	343 Forbes
Chen	3	A	991-878-4944	308 Blair
Fox	3	A	884-232-5341	11 Dickinson
Andrews	3	A	664-480-0023	097 Little
Kanaga	3	B	898-122-9643	22 Brown
Gazsi	4	B	766-093-9873	101 Brown
Battle	4	C	874-088-1212	121 Whitman

@#%&@! Students in section 3 no longer sorted by name.

A **stable** sort preserves the relative order of items with equal keys.

- Q. Which sorts are stable?
- A. Insertion sort and mergesort (but not selection sort or shellsort).

sorted by time	sorted by location (not stable)	sorted by location (stable)
Chicago 09:00:00	Chicago 09:25:52	Chicago 09:00:00
Phoenix 09:00:03	Chicago 09:03:13	Chicago 09:00:59
Houston 09:00:13	Chicago 09:21:05	Chicago 09:03:13
Chicago 09:00:59	Chicago 09:19:46	Chicago 09:19:32
Houston 09:01:10	Chicago 09:19:32	Chicago 09:19:46
Chicago 09:03:13	Chicago 09:00:00	Chicago 09:21:05
Seattle 09:10:11	Chicago 09:35:21	Chicago 09:25:52
Seattle 09:10:25	Chicago 09:00:59	Chicago 09:35:21
Phoenix 09:14:25	Houston 09:01:10	Houston 09:00:13
Chicago 09:19:32	Houston 09:00:13	Houston 09:01:10
Chicago 09:19:46	Phoenix 09:37:44	Phoenix 09:00:03
Chicago 09:21:05	Phoenix 09:00:03	Phoenix 09:14:25
Seattle 09:22:43	Phoenix 09:14:25	Phoenix 09:37:44
Seattle 09:22:54	Seattle 09:10:25	Seattle 09:10:11
Chicago 09:25:52	Seattle 09:36:14	Seattle 09:10:25
Chicago 09:35:21	Seattle 09:22:43	Seattle 09:22:43
Seattle 09:36:14	Seattle 09:10:11	Seattle 09:22:54
Phoenix 09:37:44	Seattle 09:22:54	Seattle 09:36:14

no longer sorted by time

still sorted by time

Note. Need to carefully check code ("less than" vs "less than or equal to").

Stability: insertion sort

Proposition. Insertion sort is **stable**.

```
public class Insertion
{
    public static void sort(Comparable[] a)
    {
        int N = a.length;
        for (int i = 0; i < N; i++)
            for (int j = i; j > 0 && less(a[j], a[j-1]); j--)
                exch(a, j, j-1);
    }
}
```

i	j	0	1	2	3	4
0	0	B	A	A	A	B
1	0	A	B	A	A	B
2	1	A	A	B	A	B
3	2	A	A	A	B	B
4	4	A	A	A	B	B
		A	A	A	B	B

Pf. Equal items never move past each other.

Stability: selection sort

Proposition. Selection sort is **not** stable.

```
public class Selection
{
    public static void sort(Comparable[] a)
    {
        int N = a.length;
        for (int i = 0; i < N; i++)
        {
            int min = i;
            for (int j = i+1; j < N; j++)
                if (less(a[j], a[min]))
                    min = j;
            exch(a, i, min);
        }
    }
}
```

i	min	0	1	2
0	2	B	B	A
1	1	A	B	B
2	2	A	B	B
		A	B	B

Pf by counterexample. Long-distance exchange might move an item past some equal item.

Stability: shellsort

Proposition. Shellsort sort is **not** stable.

```
public class Shell
{
    public static void sort(Comparable[] a)
    {
        int N = a.length;
        int h = 1;
        while (h < N/3) h = 3*h + 1;
        while (h >= 1)
        {
            for (int i = h; i < N; i++)
            {
                for (int j = i; j > h && less(a[j], a[j-h]); j -= h)
                    exch(a, j, j-h);
            }
            h = h/3;
        }
    }
}
```

h	0	1	2	3	4
	B	B	B	B	A
4	A	B	B	B	B
1	A	B	B	B	B
	A	B	B	B	B

Pf by counterexample. Long-distance exchanges.

Proposition. Mergesort is **stable**.

```
public class Merge
{
    private static Comparable[] aux;
    private static void merge(Comparable[] a, int lo, int mid, int hi)
    { /* as before */ }

    private static void sort(Comparable[] a, int lo, int hi)
    {
        if (hi <= lo) return;
        int mid = lo + (hi - lo) / 2;
        sort(a, lo, mid);
        sort(a, mid+1, hi);
        merge(a, lo, mid, hi);
    }

    public static void sort(Comparable[] a)
    { /* as before */ }
}
```

Pf. Suffices to verify that merge operation is stable.

Proposition. Merge operation is stable.

```
private static void merge(Comparable[] a, int lo, int mid, int hi)
{
    for (int k = lo; k <= hi; k++)
        aux[k] = a[k];

    int i = lo, j = mid+1;
    for (int k = lo; k <= hi; k++)
    {
        if (i > mid)                a[k] = aux[j++];
        else if (j > hi)            a[k] = aux[i++];
        else if (less(aux[j], aux[i])) a[k] = aux[j++];
        else                        a[k] = aux[i++];
    }
}
```

0	1	2	3	4	5	6	7	8	9	10
A	A	A	B	D	A	A	C	E	F	G

Pf. Takes from left subarray if equal keys.

QUICKSORT



- quicksort
- selection
- duplicate keys
- system sorts

Two classic sorting algorithms

Critical components in the world's computational infrastructure.

- Full scientific understanding of their properties has enabled us to develop them into practical system sorts.
- Quicksort honored as one of top 10 algorithms of 20th century in science and engineering.

Mergesort.

- Java sort for objects.
- Perl, C++ stable sort, Python stable sort, Firefox JavaScript, ...

Quicksort.

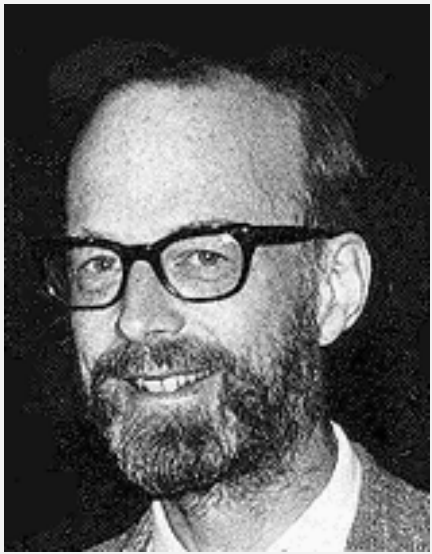
- Java sort for primitive types.
- C qsort, Unix, Visual C++, Python, Matlab, Chrome JavaScript, ...

- ▶ quicksort
- ▶ selection
- ▶ duplicate keys
- ▶ system sorts

Quicksort

Basic plan.

- **Shuffle** the array.
- **Partition** so that, for some j
 - entry $a[j]$ is in place
 - no larger entry to the left of j
 - no smaller entry to the right of j
- **Sort** each piece recursively.



Sir Charles Antony Richard Hoare
1980 Turing Award

input	Q	U	I	C	K	S	O	R	T	E	X	A	M	P	L	E
shuffle	K	R	A	T	E	L	E	P	U	I	M	Q	C	X	O	S
partition	E	C	A	I	E	K	L	P	U	T	M	Q	R	X	O	S
sort left	A	C	E	E	I	K	L	P	U	T	M	Q	R	X	O	S
sort right	A	C	E	E	I	K	L	M	O	P	Q	R	S	T	U	X
result	A	C	E	E	I	K	L	M	O	P	Q	R	S	T	U	X

Quicksort partitioning

Basic plan.

- Scan i from left for an item that belongs on the right.
- Scan j from right for an item that belongs on the left.
- Exchange $a[i]$ and $a[j]$.
- Repeat until pointers cross.

	i	j	$a[i]$															
			0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
initial values	0	16	K	R	A	T	E	L	E	P	U	I	M	Q	C	X	O	S
scan left, scan right	1	12	K	R	A	T	E	L	E	P	U	I	M	Q	C	X	O	S
exchange	1	12	K	C	A	T	E	L	E	P	U	I	M	Q	R	X	O	S
scan left, scan right	3	9	K	C	A	T	E	L	E	P	U	I	M	Q	R	X	O	S
exchange	3	9	K	C	A	I	E	L	E	P	U	T	M	Q	R	X	O	S
scan left, scan right	5	6	K	C	A	I	E	L	E	P	U	T	M	Q	R	X	O	S
exchange	5	6	K	C	A	I	E	E	L	P	U	T	M	Q	R	X	O	S
scan left, scan right	6	5	K	C	A	I	E	E	L	P	U	T	M	Q	R	X	O	S
final exchange	6	5	E	C	A	I	E	K	L	P	U	T	M	Q	R	X	O	S
result	6	5	E	C	A	I	E	K	L	P	U	T	M	Q	R	X	O	S

Partitioning trace (array contents before and after each exchange)

Quicksort partitioning demo

Quicksort: Java code for partitioning

```
private static int partition(Comparable[] a, int lo, int hi)
{
    int i = lo, j = hi+1;
    while (true)
    {
        while (less(a[++i], a[lo]))           find item on left to swap
            if (i == hi) break;

        while (less(a[lo], a[--j]))           find item on right to swap
            if (j == lo) break;

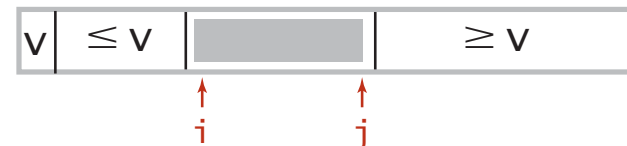
        if (i >= j) break;                     check if pointers cross
        exch(a, i, j);                         swap

        exch(a, lo, j);                       swap with partitioning item
        return j;                             return index of item now known to be in place
    }
}
```

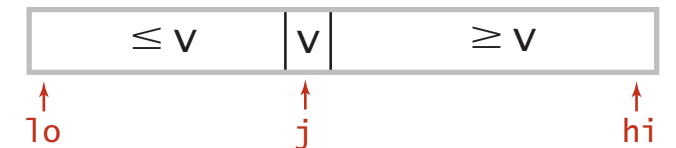
before



during



after



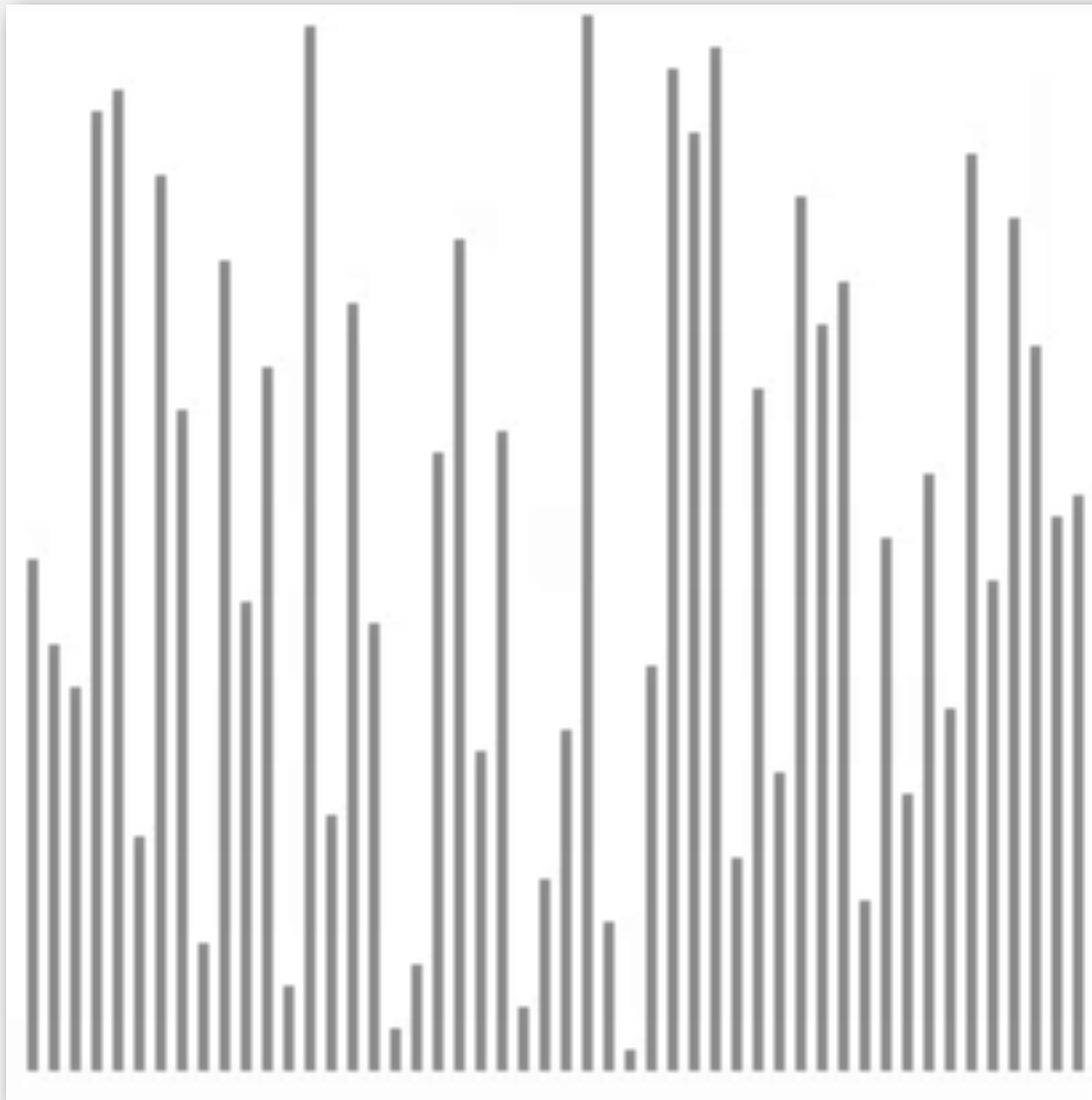
Quicksort trace

			0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
initial values	lo	j	hi	Q	U	I	C	K	S	O	R	T	E	X	A	M	P	L	E
	random shuffle			K	R	A	T	E	L	E	P	U	I	M	Q	C	X	O	S
<div>no partition for subarrays of size 1</div>	0	5	15	E	C	A	I	E	K	L	P	U	T	M	Q	R	X	O	S
	0	3	4	E	C	A	E	I	K	L	P	U	T	M	Q	R	X	O	S
	0	2	2	A	C	E	E	I	K	L	P	U	T	M	Q	R	X	O	S
	0	0	1	A	C	E	E	I	K	L	P	U	T	M	Q	R	X	O	S
	1		1	A	C	E	E	I	K	L	P	U	T	M	Q	R	X	O	S
	4		4	A	C	E	E	I	K	L	P	U	T	M	Q	R	X	O	S
	6	6	15	A	C	E	E	I	K	L	P	U	T	M	Q	R	X	O	S
	7	9	15	A	C	E	E	I	K	L	M	O	P	T	Q	R	X	U	S
	7	7	8	A	C	E	E	I	K	L	M	O	P	T	Q	R	X	U	S
	8		8	A	C	E	E	I	K	L	M	O	P	T	Q	R	X	U	S
	10	13	15	A	C	E	E	I	K	L	M	O	P	S	Q	R	T	U	X
	10	12	12	A	C	E	E	I	K	L	M	O	P	R	Q	S	T	U	X
	10	11	11	A	C	E	E	I	K	L	M	O	P	Q	R	S	T	U	X
	10		10	A	C	E	E	I	K	L	M	O	P	Q	R	S	T	U	X
	14	14	15	A	C	E	E	I	K	L	M	O	P	Q	R	S	T	U	X
15		15	A	C	E	E	I	K	L	M	O	P	Q	R	S	T	U	X	
result			A	C	E	E	I	K	L	M	O	P	Q	R	S	T	U	X	

Quicksort trace (array contents after each partition)

Quicksort animation

50 random items



<http://www.sorting-algorithms.com/quick-sort>

- ▲ algorithm position
- █ in order
- █ current subarray
- █ not in order

Quicksort: implementation details

Partitioning in-place. Using an extra array makes partitioning easier (and stable), but is not worth the cost.

Terminating the loop. Testing whether the pointers cross is a bit trickier than it might seem.

Staying in bounds. The $(j == lo)$ test is redundant (why?), but the $(i == hi)$ test is not.

Preserving randomness. Shuffling is needed for performance guarantee.

Equal keys. When duplicates are present, it is (counter-intuitively) better to stop on keys equal to the partitioning item's key.

Quicksort: empirical analysis

Running time estimates:

- Home PC executes 10^8 compares/second.
- Supercomputer executes 10^{12} compares/second.

	insertion sort (N)			mergesort (N log N)			quicksort (N log N)		
computer	thousand	million	billion	thousand	million	billion	thousand	million	billion
home	instant	2.8 hours	317 years	instant	1 second	18 min	instant	0.6 sec	12 min
super	instant	1 second	1 week	instant	instant	instant	instant	instant	instant

Lesson 1. Good algorithms are better than supercomputers.

Lesson 2. Great algorithms are better than good ones.

Quicksort: best-case analysis

Best case. Number of compares is $\sim N \lg N$.

			a[]															
lo	j	hi	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	
initial values			H	A	C	B	F	E	G	D	L	I	K	J	N	M	O	
random shuffle			H	A	C	B	F	E	G	D	L	I	K	J	N	M	O	
0	7	14	D	A	C	B	F	E	G	H	L	I	K	J	N	M	O	
0	3	6	B	A	C	D	F	E	G	H	L	I	K	J	N	M	O	
0	1	2	A	B	C	D	F	E	G	H	L	I	K	J	N	M	O	
0		0	A	B	C	D	F	E	G	H	L	I	K	J	N	M	O	
2		2	A	B	C	D	F	E	G	H	L	I	K	J	N	M	O	
4	5	6	A	B	C	D	E	F	G	H	L	I	K	J	N	M	O	
4		4	A	B	C	D	E	F	G	H	L	I	K	J	N	M	O	
6		6	A	B	C	D	E	F	G	H	L	I	K	J	N	M	O	
8	11	14	A	B	C	D	E	F	G	H	J	I	K	L	N	M	O	
8	9	10	A	B	C	D	E	F	G	H	I	J	K	L	N	M	O	
8		8	A	B	C	D	E	F	G	H	I	J	K	L	N	M	O	
10		10	A	B	C	D	E	F	G	H	I	J	K	L	N	M	O	
12	13	14	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O	
12		12	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O	
14		14	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O	
			A	B	C	D	E	F	G	H	I	J	K	L	M	N	O	

Quicksort: worst-case analysis

Worst case. Number of compares is $\sim \frac{1}{2} N^2$.

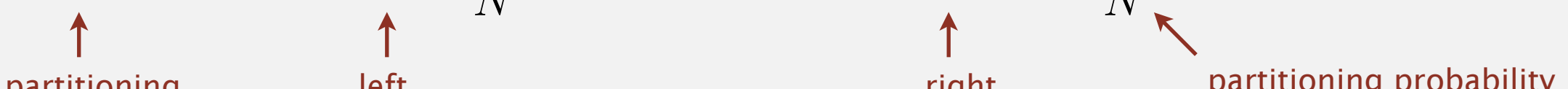
			a[]														
lo	j	hi	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14
initial values			A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
random shuffle			A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
0	0	14	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
1	1	14	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
2	2	14	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
3	3	14	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
4	4	14	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
5	5	14	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
6	6	14	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
7	7	14	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
8	8	14	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
9	9	14	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
10	10	14	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
11	11	14	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
12	12	14	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
13	13	14	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
14		14	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
			A	B	C	D	E	F	G	H	I	J	K	L	M	N	O

Quicksort: average-case analysis

Proposition. The average number of compares C_N to quicksort an array of N distinct keys is $\sim 2N \ln N$ (and the number of exchanges is $\sim \frac{1}{3} N \ln N$).

Pf 1. C_N satisfies the recurrence $C_0 = C_1 = 0$ and for $N \geq 2$:

$$C_N = (N+1) + \frac{C_0 + C_1 + \dots + C_{N-1}}{N} + \frac{C_{N-1} + C_{N-2} + \dots + C_0}{N}$$



- Multiply both sides by N and collect terms:

$$NC_N = N(N+1) + 2(C_0 + C_1 + \dots + C_{N-1})$$

- Subtract this from the same equation for $N-1$:

$$NC_N - (N-1)C_{N-1} = 2N + 2C_{N-1}$$

- Rearrange terms and divide by $N(N+1)$:

$$\frac{C_N}{N+1} = \frac{C_{N-1}}{N} + \frac{2}{N+1}$$

Quicksort: average-case analysis

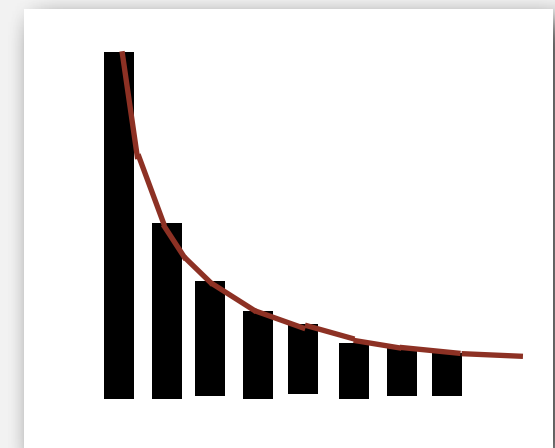
- Repeatedly apply above equation:

$$\begin{aligned}\frac{C_N}{N+1} &= \frac{C_{N-1}}{N} + \frac{2}{N+1} \\ &= \frac{C_{N-2}}{N-1} + \frac{2}{N} + \frac{2}{N+1} \quad \leftarrow \text{substitute previous equation} \\ &= \frac{C_{N-3}}{N-2} + \frac{2}{N-1} + \frac{2}{N} + \frac{2}{N+1} \\ &= \frac{2}{3} + \frac{2}{4} + \frac{2}{5} + \dots + \frac{2}{N+1}\end{aligned}$$

previous equation

- Approximate sum by an integral:

$$\begin{aligned}C_N &= 2(N+1) \left(\frac{1}{3} + \frac{1}{4} + \frac{1}{5} + \dots + \frac{1}{N+1} \right) \\ &\sim 2(N+1) \int_3^{N+1} \frac{1}{x} dx\end{aligned}$$



- Finally, the desired result:

$$C_N \sim 2(N+1) \ln N \approx 1.39N \lg N$$

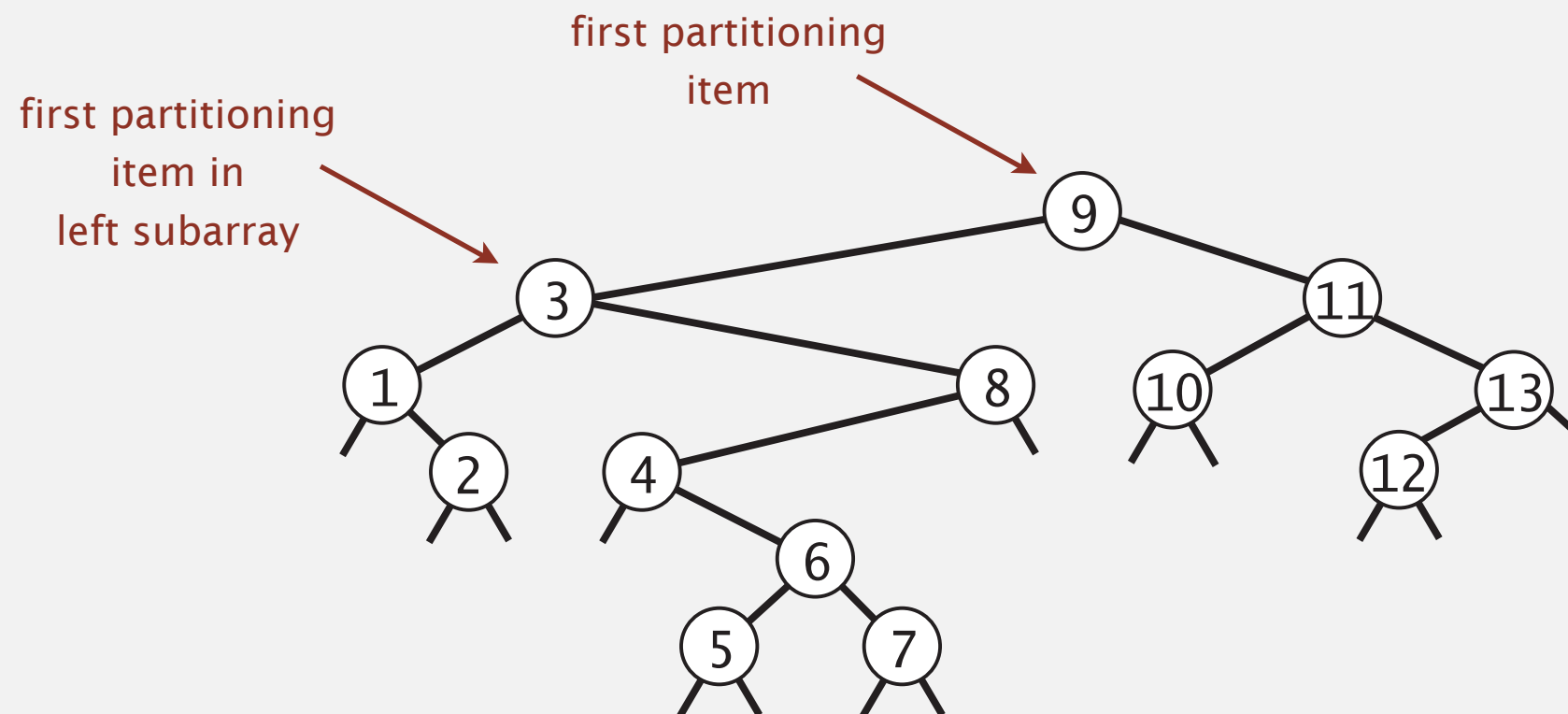
Quicksort: average-case analysis

Proposition. The average number of compares C_N to quicksort an array of N distinct keys is $\sim 2N \ln N$ (and the number of exchanges is $\sim \frac{1}{3} N \ln N$).

Pf 2. Consider BST representation of keys 1 to N .

shuffle

9	10	2	5	8	7	6	1	11	12	13	3	4
---	----	---	---	---	---	---	---	----	----	----	---	---



Quicksort: average-case analysis

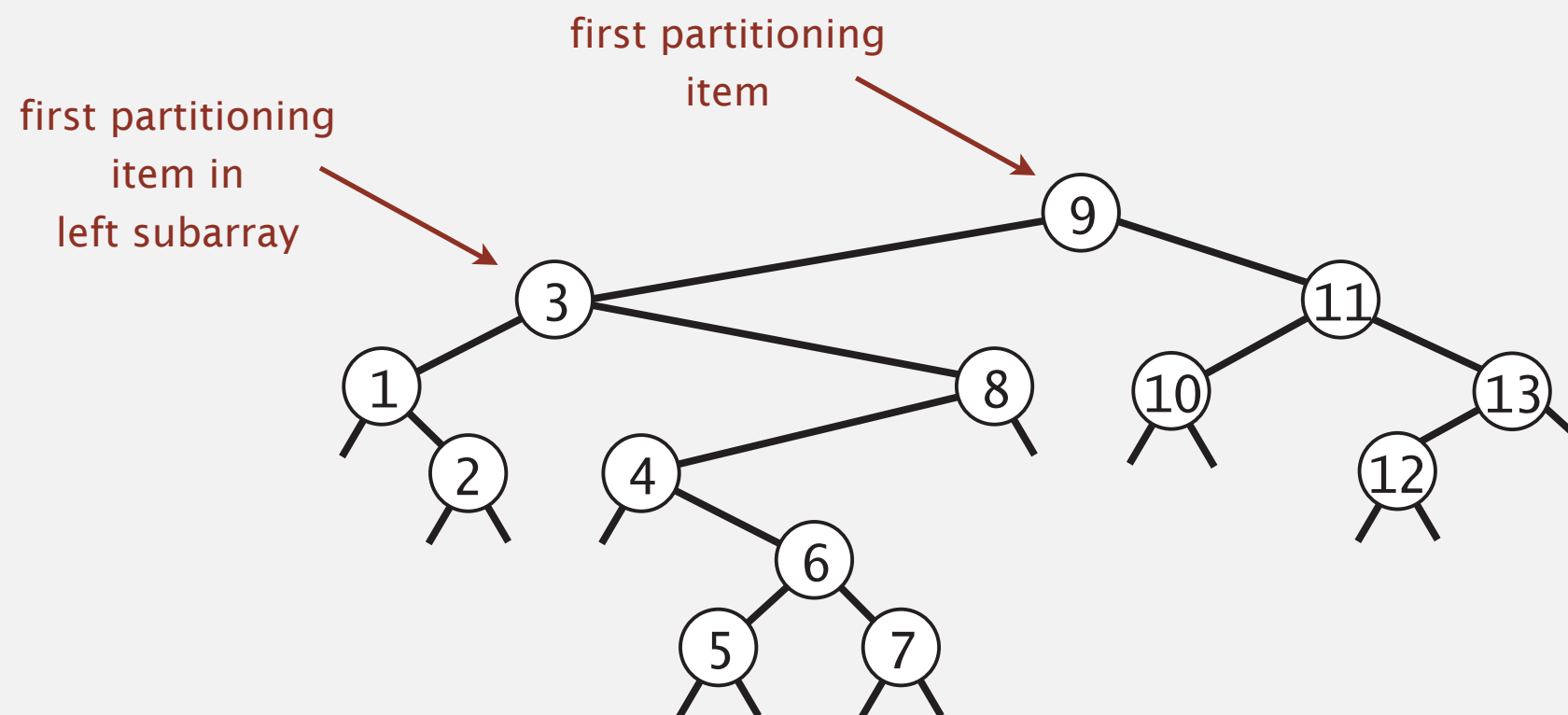
Proposition. The average number of compares C_N to quicksort an array of N distinct keys is $\sim 2N \ln N$ (and the number of exchanges is $\sim \frac{1}{3} N \ln N$).

Pf 2. Consider BST representation of keys 1 to N .

- A key is compared only with its ancestors and descendants.
- Probability i and j are compared equals $2 / |j - i + 1|$.

3 and 6 are compared
(when 3 is partition)

1 and 6 are not compared
(because 3 is partition)




Proposition. The average number of compares C_N to quicksort an array of N distinct keys is $\sim 2N \ln N$ (and the number of exchanges is $\sim \frac{1}{3} N \ln N$).

Pf 2. Consider BST representation of keys 1 to N .

- A key is compared only with its ancestors and descendants.
- Probability i and j are compared equals $2 / |j - i + 1|$.

- Expected number of compares =
$$\sum_{i=1}^N \sum_{j=i+1}^N \frac{2}{j - i + 1} = 2 \sum_{i=1}^N \sum_{j=2}^{N-i+1} \frac{1}{j}$$


all pairs i and j

$$\leq 2N \sum_{j=1}^N \frac{1}{j}$$
$$\sim 2N \int_{x=1}^N \frac{1}{x} dx$$
$$= 2N \ln N$$

Quicksort: summary of performance characteristics

Worst case. Number of compares is quadratic.

- $N + (N - 1) + (N - 2) + \dots + 1 \sim \frac{1}{2} N^2$.
- More likely that your computer is struck by lightning bolt.

Average case. Number of compares is $\sim 1.39 N \lg N$.

- 39% more compares than mergesort.
- **But** faster than mergesort in practice because of less data movement.

Random shuffle.

- Probabilistic guarantee against worst case.
- Basis for math model that can be validated with experiments.

Caveat emptor. Many textbook implementations go **quadratic** if array

- Is sorted or reverse sorted.
- Has many duplicates (even if randomized!)

Quicksort properties

Proposition. Quicksort is an **in-place** sorting algorithm.

Pf.

- Partitioning: constant extra space.
- Depth of recursion: logarithmic extra space (with high probability).

can guarantee logarithmic depth by
recurring on smaller subarray
before larger subarray

Proposition. Quicksort is **not stable**.

Pf.

i	j	0	1	2	3
		B	C	C	A
1	3	B	C	C	A
1	3	B	A	C	C
0	1	A	B	C	C

Quicksort: practical improvements

Insertion sort small subarrays.

- Even quicksort has too much overhead for tiny subarrays.
- Cutoff to insertion sort for ≈ 10 items.
- Note: could delay insertion sort until one pass at end.

```
private static void sort(Comparable[] a, int lo, int hi)
{
    if (hi <= lo + CUTOFF - 1)
    {
        Insertion.sort(a, lo, hi);
        return;
    }
    int j = partition(a, lo, hi);
    sort(a, lo, j-1);
    sort(a, j+1, hi);
}
```

Quicksort: practical improvements

Median of sample.

- Best choice of pivot item = median.
- Estimate true median by taking median of sample.
- Median-of-3 (random) items.



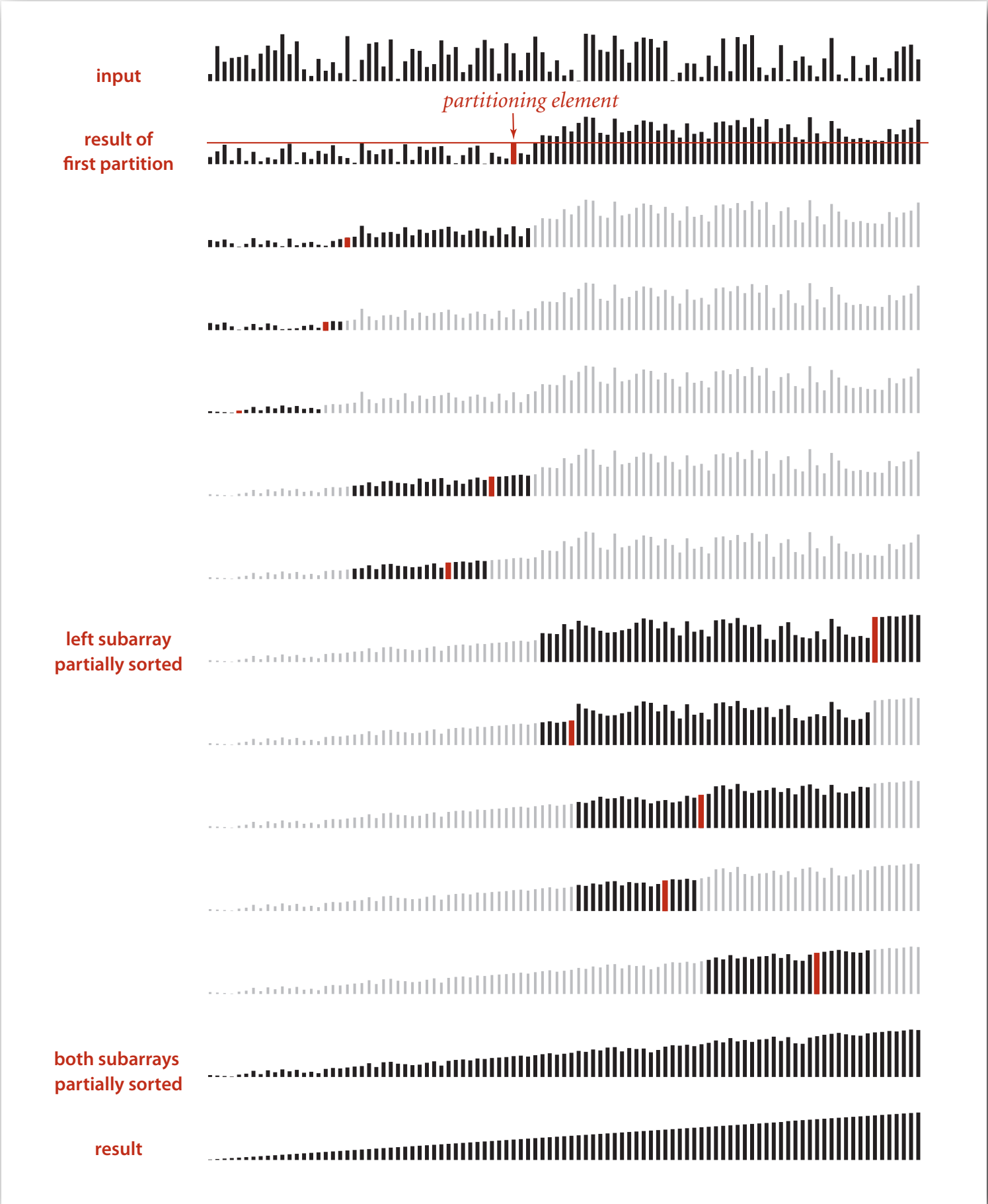
~ 12/7 $N \ln N$ compares (slightly fewer)
~ 12/35 $N \ln N$ exchanges (slightly more)

```
private static void sort(Comparable[] a, int lo, int hi)
{
    if (hi <= lo) return;

    int m = medianOf3(a, lo, lo + (hi - lo)/2, hi);
    swap(a, lo, m);

    int j = partition(a, lo, hi);
    sort(a, lo, j-1);
    sort(a, j+1, hi);
}
```

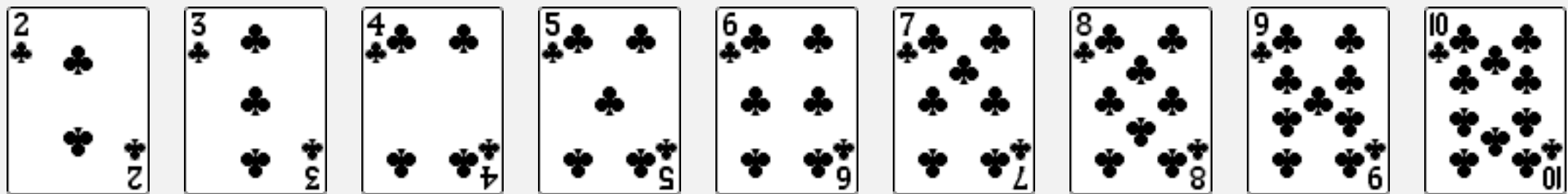
Quicksort with median-of-3 and cutoff to insertion sort: visualization



- ▶ rules of the game
- ▶ selection sort
- ▶ insertion sort
- ▶ shellsort
- ▶ **shuffling**
- ▶ convex hull

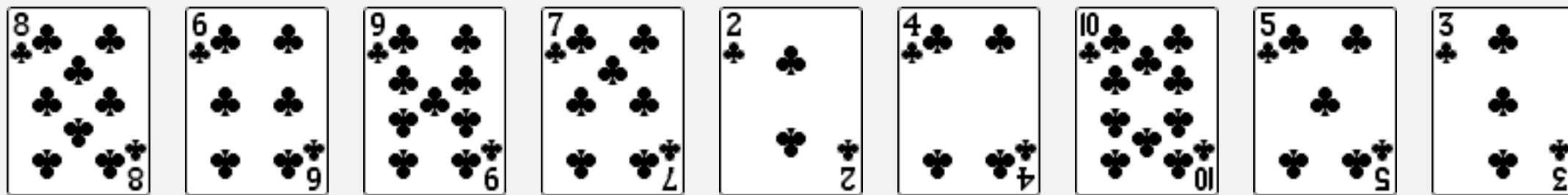
How to shuffle an array

Shuffling. Rearrange an array so that result is a uniformly random permutation.



How to shuffle an array

Shuffling. Rearrange an array so that result is a uniformly random permutation.

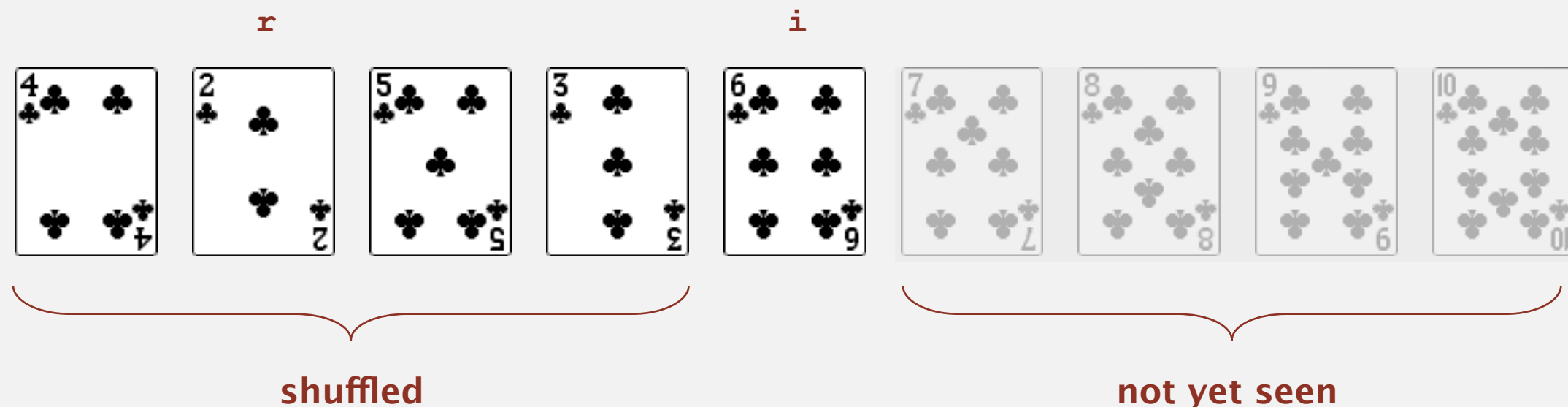


Knuth shuffle demo

Knuth shuffle

Knuth shuffle. [Fisher-Yates 1938]

- In iteration i , pick integer r between 0 and i uniformly at random.
- Swap $a[i]$ and $a[r]$.



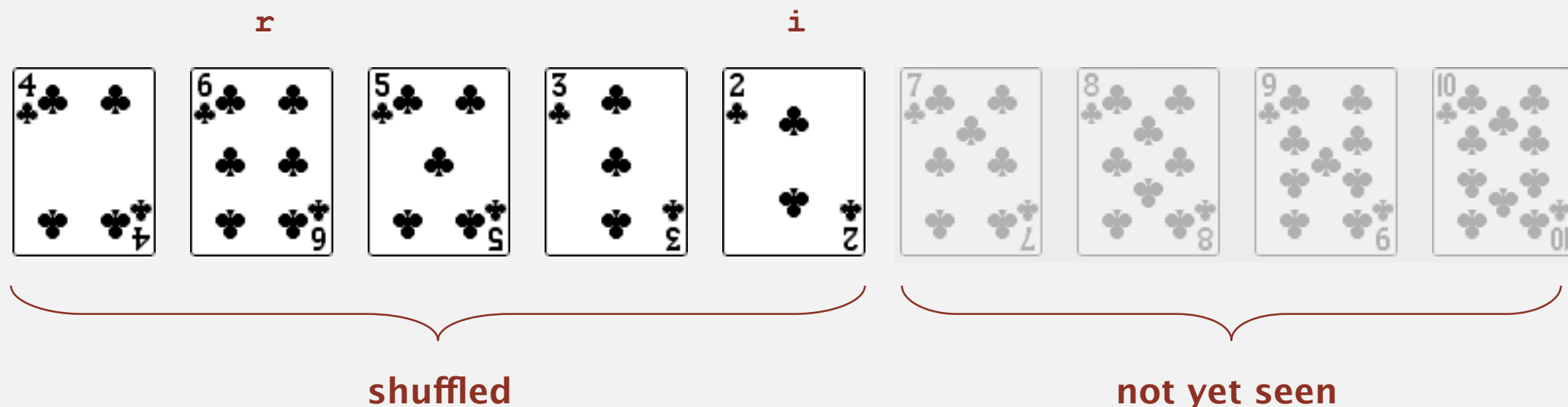
Proposition. Knuth shuffling algorithm produces a uniformly random permutation of the input array in linear time.

↖ assuming integers
uniformly at random

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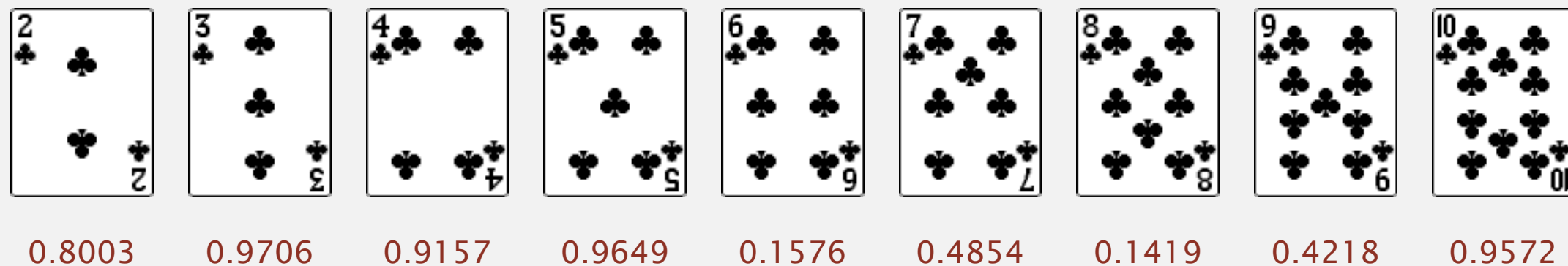
↖ assuming integers
uniformly at random

Shuffle sort

Shuffle sort.

- Generate a random real number for each array entry.
- Sort the array.

useful for shuffling
columns in a spreadsheet



Proposition. Shuffle sort produces a uniformly random permutation of the input array, provided no duplicate values.

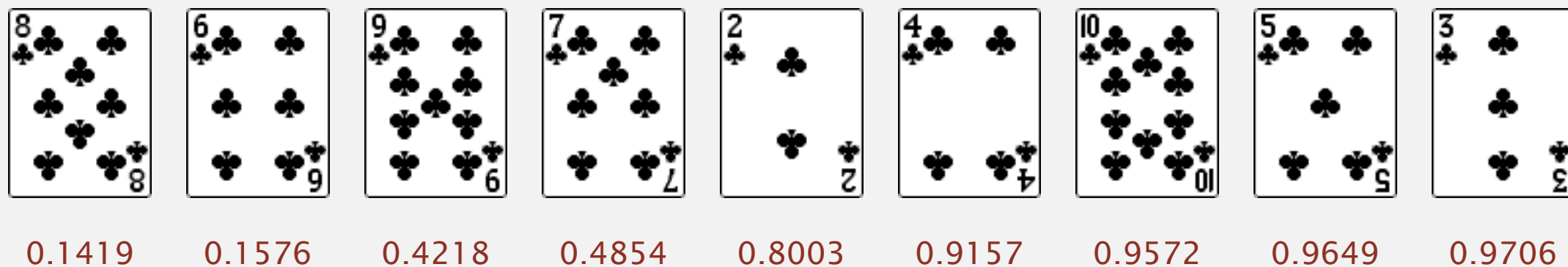
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assuming real numbers
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- ▶ quicksort
- ▶ **selection**
- ▶ duplicate keys
- ▶ system sorts

Selection

Goal. Given an array of N items, find the k^{th} largest.

Ex. Min ($k = 0$), max ($k = N - 1$), median ($k = N / 2$).

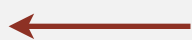
Applications.

- Order statistics.
- Find the "top k ."

Use theory as a guide.

- Easy $N \log N$ upper bound. How?
- Easy N upper bound for $k = 1, 2, 3$. How?
- Easy N lower bound. Why?

Which is true?

- $N \log N$ lower bound?  is selection as hard as sorting?
- N upper bound?  is there a linear-time algorithm for each k ?

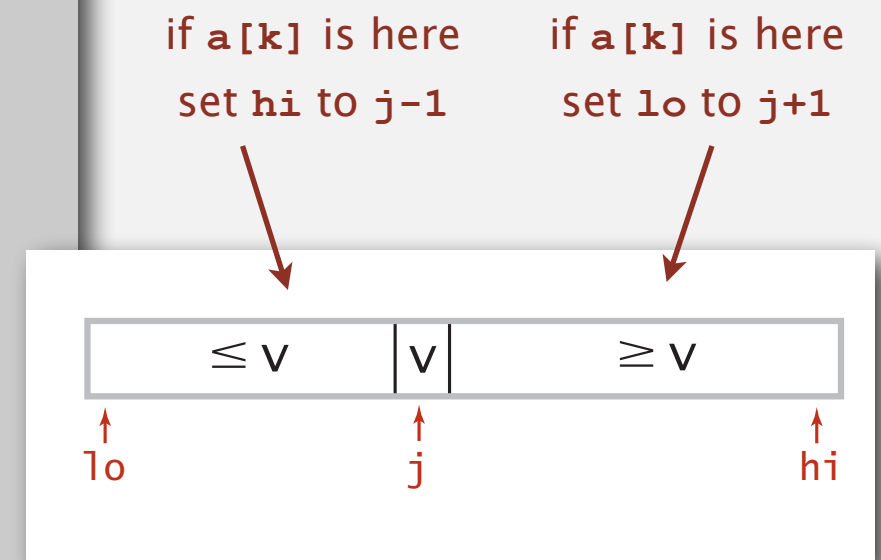
Quick-select

Partition array so that:

- Entry $a[j]$ is in place.
- No larger entry to the left of j .
- No smaller entry to the right of j .

Repeat in **one** subarray, depending on j ; finished when j equals k .

```
public static Comparable select(Comparable[] a, int k)
{
    StdRandom.shuffle(a);
    int lo = 0, hi = a.length - 1;
    while (hi > lo)
    {
        int j = partition(a, lo, hi);
        if (j < k) lo = j + 1;
        else if (j > k) hi = j - 1;
        else
            return a[k];
    }
    return a[k];
}
```



Quick-select: mathematical analysis

Proposition. Quick-select takes **linear** time on average.

Pf sketch.

- Intuitively, each partitioning step splits array approximately in half:
 $N + N/2 + N/4 + \dots + 1 \sim 2N$ compares.
- Formal analysis similar to quicksort analysis yields:

$$C_N = 2N + k \ln(N/k) + (N-k) \ln(N/(N-k))$$

 $(2 + 2 \ln 2) N$ to find the median

Remark. Quick-select uses $\sim \frac{1}{2} N^2$ compares in the worst case, but (as with quicksort) the random shuffle provides a probabilistic guarantee.

- ▶ quicksort
- ▶ selection
- ▶ **duplicate keys**
- ▶ system sorts

Duplicate keys

Often, purpose of sort is to bring items with equal keys together.

- Sort population by age.
- Find collinear points.
- Remove duplicates from mailing list.
- Sort job applicants by college attended.

Typical characteristics of such applications.

- Huge array.
- Small number of key values.

```
Chicago 09:25:52
Chicago 09:03:13
Chicago 09:21:05
Chicago 09:19:46
Chicago 09:19:32
Chicago 09:00:00
Chicago 09:35:21
Chicago 09:00:59
Houston 09:01:10
Houston 09:00:13
Phoenix 09:37:44
Phoenix 09:00:03
Phoenix 09:14:25
Seattle 09:10:25
Seattle 09:36:14
Seattle 09:22:43
Seattle 09:10:11
Seattle 09:22:54
```

↑
key

Duplicate keys

Mergesort with duplicate keys. Always between $\frac{1}{2} N \lg N$ and $N \lg N$ compares.

Quicksort with duplicate keys.

- Algorithm goes **quadratic** unless partitioning stops on equal keys!
- 1990s C user found this defect in `qsort()`.

several textbook and system
implementation also have this defect

S T O P O N E Q U A L K **E** Y **S**

↑ swap

↑ if we don't stop on equal keys

↑ if we stop on equal keys

Duplicate keys: the problem

Mistake. Put all items equal to the partitioning item on one side.

Consequence. $\sim \frac{1}{2} N^2$ compares when all keys equal.

B A A B A B B **B** C C C

A A A A A A A A A A **A**

Recommended. Stop scans on items equal to the partitioning item.

Consequence. $\sim N \lg N$ compares when all keys equal.

B A A B A **B** C C B C B

A A A A A **A** A A A A A

Desirable. Put all items equal to the partitioning item in place.

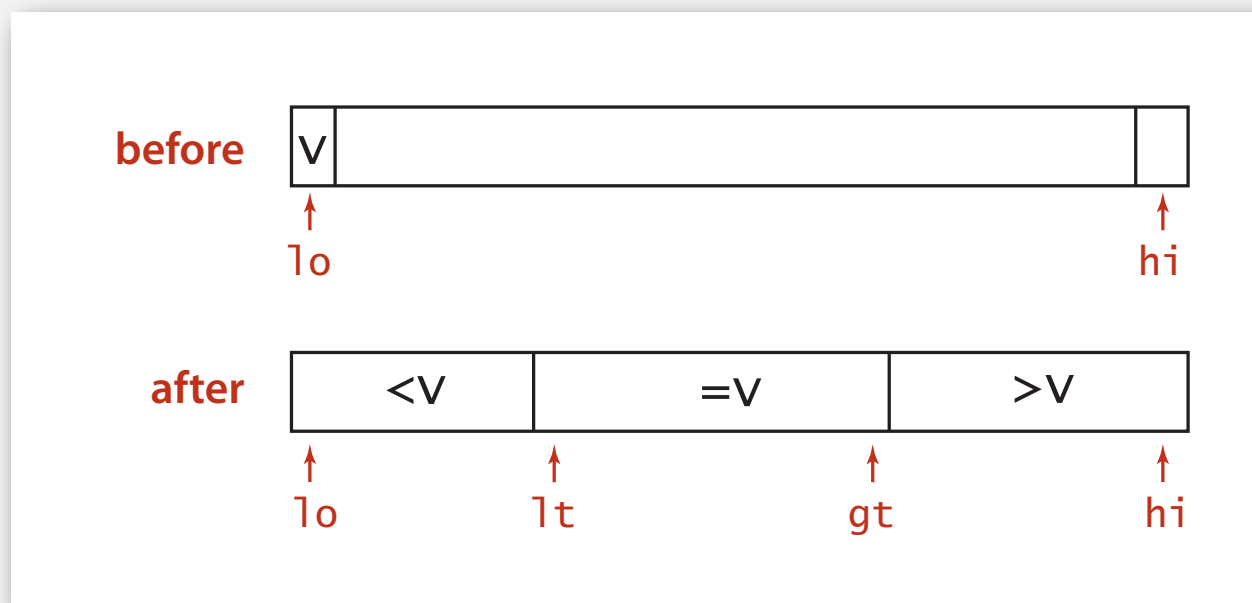
A A A **B B B B B** C C C

A A A A A A A A A A A

3-way partitioning

Goal. Partition array into 3 parts so that:

- Entries between lt and gt equal to partition item v .
- No larger entries to left of lt .
- No smaller entries to right of gt .



Dutch national flag problem. [Edsger Dijkstra]

- Conventional wisdom until mid 1990s: not worth doing.
- New approach discovered when fixing mistake in C library `qsort()`.
- Now incorporated into `qsort()` and Java `system sort`.

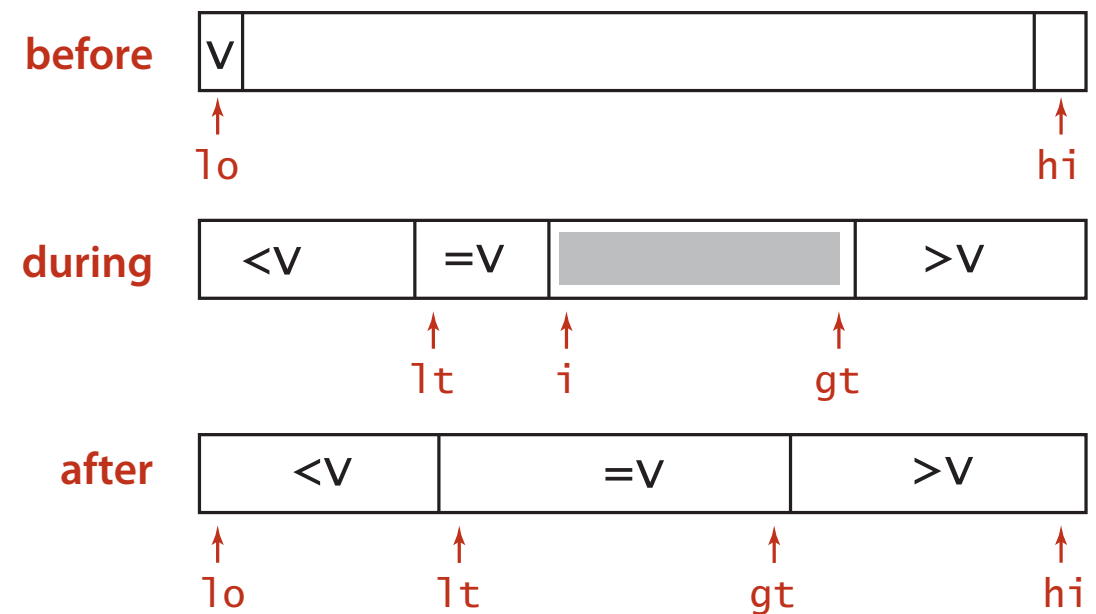
Dijkstra 3-way partitioning algorithm

3-way partitioning.

- Let v be partitioning item $a[l_0]$.
- Scan i from left to right.
 - $a[i]$ less than v : exchange $a[l_t]$ with $a[i]$ and increment both l_t and i
 - $a[i]$ greater than v : exchange $a[gt]$ with $a[i]$ and decrement gt
 - $a[i]$ equal to v : increment i

Most of the right properties.

- In-place.
- Not much code.
- Linear time if keys are all equal.



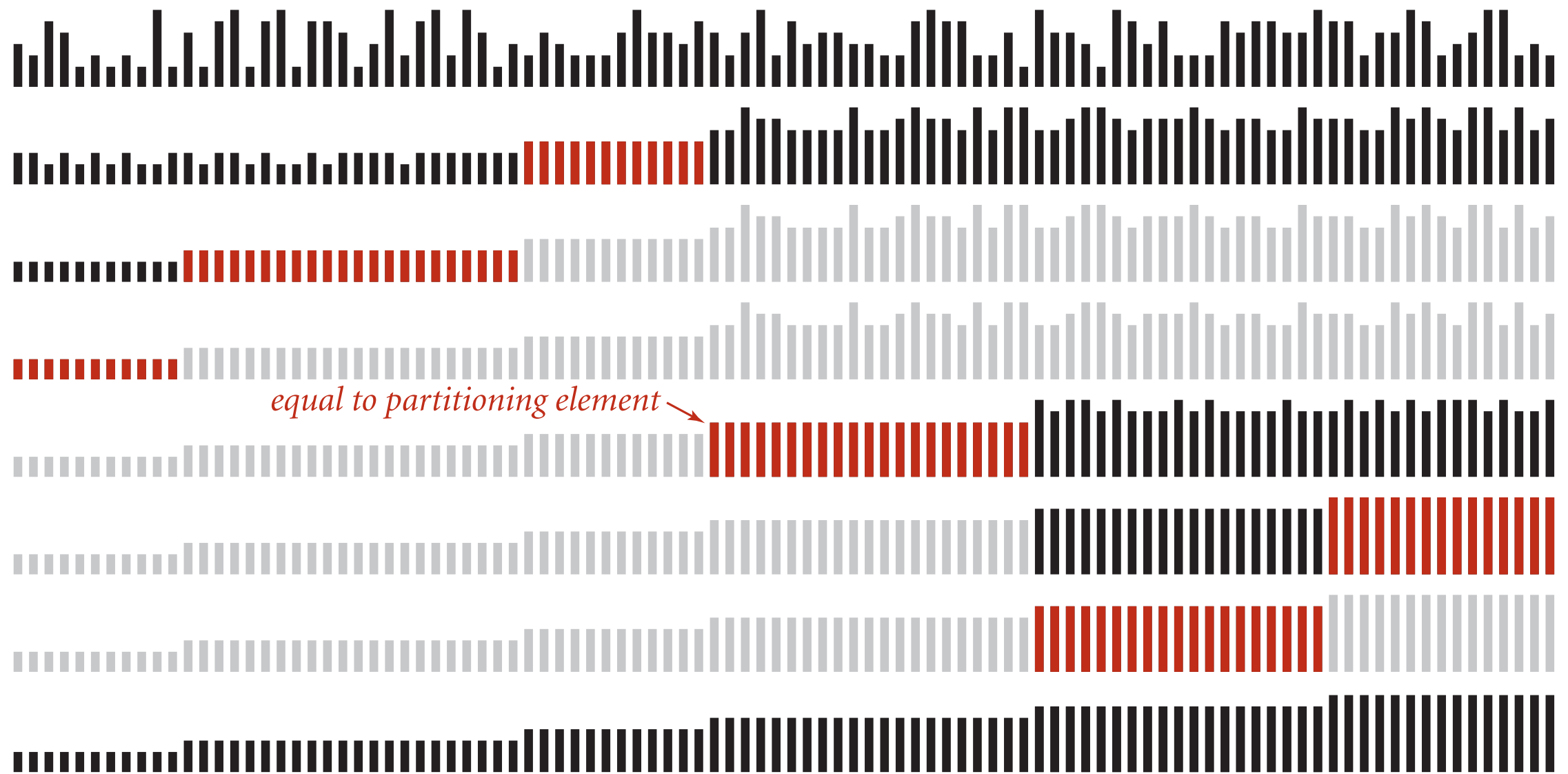
Dijkstra's 3-way partitioning: demo

Dijkstra's 3-way partitioning: trace

			a[]												
l	t	i	gt	0	1	2	3	4	5	6	7	8	9	10	11
0		0	11	R	B	W	W	R	W	B	R	R	W	B	R
0		1	11	R	B	W	W	R	W	B	R	R	W	B	R
1		2	11	B	R	W	W	R	W	B	R	R	W	B	R
1		2	10	B	R	R	W	R	W	B	R	R	W	B	W
1		3	10	B	R	R	W	R	W	B	R	R	W	B	W
1		3	9	B	R	R	B	R	W	B	R	R	W	W	W
2		4	9	B	B	R	R	R	W	B	R	R	W	W	W
2		5	9	B	B	R	R	R	W	B	R	R	W	W	W
2		5	8	B	B	R	R	R	W	B	R	R	W	W	W
2		5	7	B	B	R	R	R	R	B	R	W	W	W	W
2		6	7	B	B	R	R	R	R	B	R	W	W	W	W
3		7	7	B	B	B	R	R	R	R	R	W	W	W	W
3		8	7	B	B	B	R	R	R	R	R	W	W	W	W
3		8	7	B	B	B	R	R	R	R	R	W	W	W	W

3-way partitioning trace (array contents after each loop iteration)

3-way quicksort: visual trace



Duplicate keys: lower bound

Sorting lower bound. If there are n distinct keys and the i^{th} one occurs x_i times, any compare-based sorting algorithm must use at least

$$\lg \left(\frac{N!}{x_1! x_2! \cdots x_n!} \right) \sim - \sum_{i=1}^n x_i \lg \frac{x_i}{N}$$

compares in the worst case.

$N \lg N$ when all distinct;
linear when only a constant number of distinct keys

Proposition. [Sedgewick-Bentley, 1997]

Quicksort with 3-way partitioning is **entropy-optimal**.

Pf. [beyond scope of course]

proportional to lower bound

Bottom line. Randomized quicksort with 3-way partitioning reduces running time from linearithmic to linear in broad class of applications.

- ▶ selection
- ▶ duplicate keys
- ▶ comparators
- ▶ **Perspective of sorts...**

Sorting applications

Sorting algorithms are essential in a broad variety of applications:

- Sort a list of names.
- Organize an MP3 library.
- Display Google PageRank results.
- List RSS feed in reverse chronological order.

obvious applications

- Find the median.
- Find the closest pair.
- Binary search in a database.
- Identify statistical outliers.
- Find duplicates in a mailing list.

problems become easy once items
are in sorted order

- Data compression.
- Computer graphics.
- Computational biology.
- Supply chain management.
- Load balancing on a parallel computer.

non-obvious applications

...

Every system needs (and has) a system sort!

System sort: Which algorithm to use?

Many sorting algorithms to choose from:

Internal sorts.

- Insertion sort, selection sort, bubblesort, shaker sort.
- Quicksort, mergesort, heapsort, samplesort, shellsort.
- Solitaire sort, red-black sort, splay sort, Dobosiewicz sort, psort, ...

External sorts. Poly-phase mergesort, cascade-merge, oscillating sort.

String/radix sorts. Distribution, MSD, LSD, 3-way string quicksort.

Parallel sorts.

- Bitonic sort, Batcher even-odd sort.
- Smooth sort, cube sort, column sort.
- GPU sort.

System sort: Which algorithm to use?

Applications have diverse attributes.

- Stable?
- Parallel?
- Deterministic?
- Keys all distinct?
- Multiple key types?
- Linked list or arrays?
- Large or small items?
- Is your array randomly ordered?
- Need guaranteed performance?

		attributes								
		1	2	3	4	M
algorithm	A	•			•					
	B			•		•				•
	C		•		•					
	D						•			
	E			•						
	F		•			•			•	
	G	•								•
	.			•		•			•	
	.		•	•					•	
	.						•			
	K	•				•				•

many more combinations of
attributes than algorithms

Elementary sort may be method of choice for some combination.

Cannot cover **all** combinations of attributes.

Q. Is the system sort good enough?

A. Usually.

Sorting summary

	inplace?	stable?	worst	average	best	remarks
selection	x		N	N	N	N exchanges
insertion	x	x	N	N	N	use for small N or partially ordered
shell	x		?	?	N	tight code, subquadratic
merge		x	$N \lg N$	$N \lg N$	$N \lg N$	$N \log N$ guarantee, stable
quick	x		N	$2 N \ln N$	$N \lg N$	$N \log N$ probabilistic guarantee fastest in practice
3-way quick	x		N	$2 N \ln N$	N	improves quicksort in presence of duplicate keys
???	x	x	$N \lg N$	$N \lg N$	$N \lg N$	holy sorting grail

Which sorting algorithm?

lifo	find	data	data	data	data	hash	data
fifo	fifo	fifo	fifo	exch	fifo	fifo	exch
data	data	find	find	fifo	lifo	data	fifo
type	exch	hash	hash	find	type	link	find
hash	hash	heap	heap	hash	hash	leaf	hash
heap	heap	lifo	lifo	heap	heap	heap	heap
sort	less	link	link	leaf	link	exch	leaf
link	left	list	list	left	sort	node	left
list	leaf	push	push	less	find	lifo	less
push	lifo	root	root	lifo	list	left	lifo
find	push	sort	sort	link	push	find	link
root	root	type	type	list	root	path	list
leaf	list	leaf	leaf	sort	leaf	list	next
tree	tree	left	tree	tree	null	next	node
null	null	node	null	null	path	less	null
path	path	null	path	path	tree	root	path
node	node	path	node	node	exch	sink	push
left	link	tree	left	type	left	swim	root
less	sort	exch	less	root	less	null	sink
exch	type	less	exch	push	node	sort	sort
sink	sink	next	sink	sink	next	type	swap
swim	swim	sink	swim	swim	sink	tree	swim
next	next	swap	next	next	swap	push	tree
swap	swap	swim	swap	swap	swim	swap	type
original	?	?	?	?	?	?	sorted

Which sorting algorithm?

lifo	find	data	data	data	data	hash	data
fifo	fifo	fifo	fifo	exch	fifo	fifo	exch
data	data	find	find	fifo	lifo	data	fifo
type	exch	hash	hash	find	type	link	find
hash	hash	heap	heap	hash	hash	leaf	hash
heap	heap	lifo	lifo	heap	heap	heap	heap
sort	less	link	link	leaf	link	exch	leaf
link	left	list	list	left	sort	node	left
list	leaf	push	push	less	find	lifo	less
push	lifo	root	root	lifo	list	left	lifo
find	push	sort	sort	link	push	find	link
root	root	type	type	list	root	path	list
leaf	list	leaf	leaf	sort	leaf	list	next
tree	tree	left	tree	tree	null	next	node
null	null	node	null	null	path	less	null
path	path	null	path	path	tree	root	path
node	node	path	node	node	exch	sink	push
left	link	tree	left	type	left	swim	root
less	sort	exch	less	root	less	null	sink
exch	type	less	exch	push	node	sort	sort
sink	sink	next	sink	sink	next	type	swap
swim	swim	sink	swim	swim	sink	tree	swim
next	next	swap	next	next	swap	push	tree
swap	swap	swim	swap	swap	swim	swap	type
original	quicksort	mergesort	insertion	selection	merge BU	shellsort	sorted