

Minimal Surface and Its Application to 3-manifolds II

Xiaolong Hans Han

Toronto Geometric Analysis Seminar

Some remark for last time

Stability operator and stable minimal surface

Assume $\Sigma^{n-1} \subset M^n$ is minimal. Let F be a normal variation, $F_t^T \equiv 0$.

The second variation of Σ is defined by

$$\left. \frac{d^2}{dt^2} \right|_{t=0} \text{Vol}(F(\Sigma, t)) = - \int_{\Sigma} \langle F_t, \mathcal{L}F_t \rangle, \quad (1)$$

where \mathcal{L} is called stability or Jacobi operator.

Assume Σ has trivial normal bundle, then for a normal vector field $X = \nu N$,

$$\mathcal{L}\nu := \Delta_{\Sigma}\nu + |A|^2\nu + \text{Ric}_M(N, N)\nu \quad (2)$$

A minimal surface Σ is called **stable** if

$$\left. \frac{d^2}{dt^2} \right|_{t=0} \text{Vol}(F(\Sigma, t)) = - \int_{\Sigma} \langle F_t, \mathcal{L}F_t \rangle \geq 0 \quad (3)$$

Morse index

We call λ an eigenvalue of \mathcal{L} if

$$\mathcal{L}X + \lambda X = 0 \quad (4)$$

The **Morse index** is defined to be the number of negative eigenvalues of \mathcal{L} .

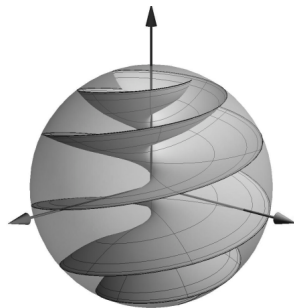
An index 1 minimal surface and an index 5 minimal surface:

Theorem, Urbano '90

Let S be a compact orientable nontotally geodesic minimal surface in S^3 . Then $\text{ind}(M) \geq 5$, and the equality holds iff M is a Clifford torus.

Examples of stable minimal surfaces

2-torus and hyperbolic helicoid (Biao Wang '19)



Area minimizing surfaces in a homotopy class or homology class are stable.

Complete stable surface in Euclidean space

Existence of minimal surface with boundary, non-compact minimal surface like helicoid and catenoid. Stable non-compact min surfaces in \mathbb{H}^3 .

Carmo-Peng '79, Schoen-Colbrie '80 (Bernstein 1917)

A stable complete minimal surface in \mathbb{R}^3 is a plane.

From ambient to submanifold and vice versa

Suppose $\Sigma^{n-1} \subset M^n$ is a closed stable minimal hypersurface with trivial normal bundle.

- ① Simons '68 : If $\text{Ric}_M \geq 0$, then Σ is totally geodesic and $\text{Ric}_M(N, N) = 0$ on Σ
- ② Schoen-Yau '79: If $\text{Scal}_M > 0$ and $n = 3$, then Σ is an S^2 or an \mathbb{RP}^2 and

$$\int_{\Sigma} \text{Scal}_M + |A|^2 \leq 8\pi \quad (5)$$

Proof:

Gao-Yau '86: Every closed M^3 admits a metric with negative Ricci.

Classical and geometric Dehn's Lemma

Dehn's lemma: If a Jordan curve on ∂M^3 compact is homotopically trivial, then it bounds an **embedded** disk.

Announced by Dehn 1910, a gap found Kneser '29, fixed by Papakyriakopoulos '57, simplified by Whitehead and Shapiro '57.

Classical and geometric Dehn's Lemma

Dehn's lemma: If a Jordan curve on ∂M^3 compact is homotopically trivial, then it bounds an **embedded** disk.

Announced by Dehn 1910, a gap found Kneser '29, fixed by Papakyriakopoulos '57, simplified by Whitehead and Shapiro '57.

Geometric Dehn's Lemma, GDL (Meeks-Yau, '82):

M^3 compact with ∂M convex. If Γ is a scc in ∂M homotopically trivial in M , then:

- 1 $\exists f : D \rightarrow M$ of least-energy such that $f|_{\partial D}$ parameterizes Γ .
- 2 f above is 1 – 1 and smooth immersion in D° .
- 3 f is as regular as Γ along ∂D . $\Gamma \in C^2 \implies f$ an immersion.
- 4 If f_1 and f_2 are two such solutions and $f_1(D^\circ) \cap f_2(D^\circ) \neq \emptyset$, then $f_2 = f_1$ up to conformal diffeomorphism reparameterization.

Cut and paste for Statement 4

Suppose that D_1, D_2 are two least-area embedded disks in M with $\partial D_1 = \partial D_2 = \Gamma$, which intersect transversely at some interior point of the disks.

Outline for Statement 1 and 3

- 1 Extend M to a homogeneously regular \tilde{M} without boundary.
- 2 Use Morrey '48 to get a least-energy map f .
- 3 Use Osserman '70 and Gulliver '73 to conclude $f|_{\text{int}(D)}$ is an immersion. Use Lewy '51 and Hildebrandt '69 to conclude the boundary regularity.

Proof of Statement 2

Let M^3 be compact analytic. Suppose D is the closed unit disk in the plane and γ is an analytic curve on ∂M and $f : D \rightarrow M$ is a least-area (energy) map with $f(\partial D) = f(D) \cap \partial M = \gamma$. Then f is 1-1.

- ① f is an analytic immersion (Last slide + Morrey '48 for analyticity)
- ② f is simplicial w.r.t. fixed triangulations of D and M (by Lojasiewicz '64).
- ③ two distinct analytic embedded disks (least-area w.r.t. boundary) have no interior intersections.
- ④ by barycentric subdivision, can assume the simplicial nbhd of $f(D)$ is a regular nbhd.



Refined tower construction using minimal surface

Construction of a tower for $f : D \rightarrow M$ to simplify the self-intersection for f :

N_1 a simplicial regular nbhd of $f(D)$. Restrict the range to get $f_1 : D \rightarrow N_1$. If N_1 is not simply connected, take universal cover and lift to get f_2 .

A combinatorial upper bound on complexity

T is the collection of open simplices and vertices. Let $c = \#T \times T$.
Terminates $\leq c$ steps.

Lemma

If $S(f_i) = \{(\sigma, \tau) \in T \times T \mid \sigma \neq \tau, f(\sigma) = f(\tau)\}$, then $S(f_{i+1})$ is a proper subset of $S(f_i)$. Hence the tower construction terminates at finite steps.

Background and Motivation

Mostow Rigidity and Effective Geometrization

When M is finite-volume hyperbolic manifold with $\dim \geq 3$, its geometry is determined by its topology.

Norms on the Cohomology

Measuring $H^1(M) \cong H_2(M)$

Thurston norm, L^2 -norm, least area norm, L^1 -norm, L^∞ -norm.

Thurston Norm

For a compact irreducible 3-manifold M , the Thurston norm of $\phi \in H^1(M; \mathbb{Z}) \cong H_2(M; \mathbb{Z})$ is defined by

$$\chi_-(S) = \max\{0, -\chi(S)\}$$
$$\|\phi\|_{Th} = \min\{\chi_-(S) \mid S \text{ is a properly embedded surface dual to } \phi\}$$

When M is closed hyperbolic, it is non-degenerate and a genuine norm.

L^2 and L^1 Norm

$$|\alpha|_{L^2}^2 := \int_M |\alpha(x)|^2 d\text{vol}_g(x) = \int_M \alpha \wedge *\alpha$$

For $\phi \in H^1$, we have $\|\phi\|_{L^2} = \inf\{|\alpha|_{L^2} \mid \alpha \text{ represents } \phi\}$

$$|\alpha|_{L^1} := \int_M |\alpha(x)| d\text{vol}_g(x)$$

Least Area Norm

For $\phi \in H^1$, let \mathcal{F}_ϕ be the collection of smooth maps $f : S \rightarrow M$ where S is a closed oriented surface with $f_*([S])$ dual to ϕ . The least area norm of ϕ is

$$\|\phi\|_{LA} = \inf \{ \text{Area}(f(S)) \mid f \in \mathcal{F}_\phi \}$$

Theorem (Bergeron-Sengün-Venkatesh 2015)

If M is a finite of a fixed closed orientable hyperbolic 3-manifold M_0 , then we have

$$\frac{C_1}{\text{vol}(M)} \|\cdot\|_{Th} \leq \|\cdot\|_{L^2} \leq C_2 \|\cdot\|_{Th} \text{ on } H^1(M; \mathbb{R})$$

where C_1 and C_2 depend only on M_0 . It generalizes Kronheimer-Mrowka.

Theorem (Bergeron-Sengün-Venkatesh 2015)

If M is a finite of a fixed closed orientable hyperbolic 3-manifold M_0 , then we have

$$\frac{C_1}{\text{vol}(M)} \|\cdot\|_{Th} \leq \|\cdot\|_{L^2} \leq C_2 \|\cdot\|_{Th} \text{ on } H^1(M; \mathbb{R})$$

where C_1 and C_2 depend only on M_0 . It generalizes Kronheimer-Mrowka.

Theorem (Brock-Dunfield 2017), (Lin 2017)

For all closed orientable hyperbolic 3-manifolds M one has :

$$\frac{\pi}{\sqrt{\text{vol}(M)}} \|\cdot\|_{Th} \leq \|\cdot\|_{L^2} \leq \frac{10\pi}{\sqrt{\text{inj}}} \|\cdot\|_{Th}, \text{ on } H^1(M; \mathbb{R})$$

(Lin 2017) uses the technique of Kronheimer-Mrowka to prove the LHS.

Theorem (Stern 2019, Bray-Stern 2019)

Generalize the LHS to 3-manifolds with boundary and reducible cases.

A Glance at the Noncompact Case

Finite-volume case also shares the rigidity and it is natural to wonder.

$\text{inj} = 0$

One immediate challenge: injectivity radius of M is zero. We have to modify the inequality so that it can produce useful bounds on the 1-form.

Thurston norm degenerate $H_2(M)$

The boundary-parallel torus has Thurston norm 0 and area goes to 0.

Solution is Surprisingly Simple!

Only need to ask for L^2

The L^2 condition works extraordinarily well with Thurston norm and minimal surface theory. Denote \mathcal{H}^1 the space of L^2 harmonic 1-form. [Zucker, 1982 and Mazzeo-Phillips 1990] showed that $\mathcal{H}^1 \cong \text{Im}(H_0^1(M) \rightarrow H^1(M)) \cong \text{Im}(H_2(M) \rightarrow H_2(M, \partial M))$.

Lemma (H. '20):

- 1 The Thurston norm is a genuine norm on \mathcal{H}^1 .
- 2 The following estimates hold on \mathcal{H}^1 :

$$\pi \| \cdot \|_{Th} \leq \| \cdot \|_{LA} \leq 2\pi \| \cdot \|_{Th}$$

Existence of LA surface established by Huang-Wang, Collin-Hauswirth-Mazet-Rosenberg is crucial. Apply arguments in Hass or Collin-Hauswirth-Mazet-Rosenberg for the estimates.

Compact Subdomain Suffices for the Inequality

Theorem (H. '20):

For all finite-volume orientable hyperbolic 3-manifolds M one has

$$\frac{\pi}{\sqrt{\text{vol}(M)}} \|\cdot\|_{Th} \leq \|\cdot\|_{L^2} \leq \max\left\{\frac{10\pi}{\sqrt{\text{inj}(M_\tau)}}, \frac{8\pi}{\text{inj}(M_\tau)}\right\} \|\cdot\|_{Th} \text{ on } \mathcal{H}^1 \quad (6)$$

τ is a constant explicitly computable from M .

Proof of Upper Bound

Counting duplicates when M is lifted:

Poincaré duality in closed vs. non-compact

Proof of Upper Bound

For the closed case: Fix a surface S dual to α , and α is the harmonic representative of ϕ . Thus we have

$$\begin{aligned}\|\alpha\|_{L^2}^2 &= \int_M *\alpha \wedge \alpha = \int_S *\alpha \\ &\leq \int_S |*\alpha| dA \leq \int_S \|\alpha\|_{L^\infty} dA \\ &\leq \|\alpha\|_{L^\infty} \text{Area}(S) \leq 2\pi \|\alpha\|_{L^\infty} \|\alpha\|_{Th}\end{aligned}$$

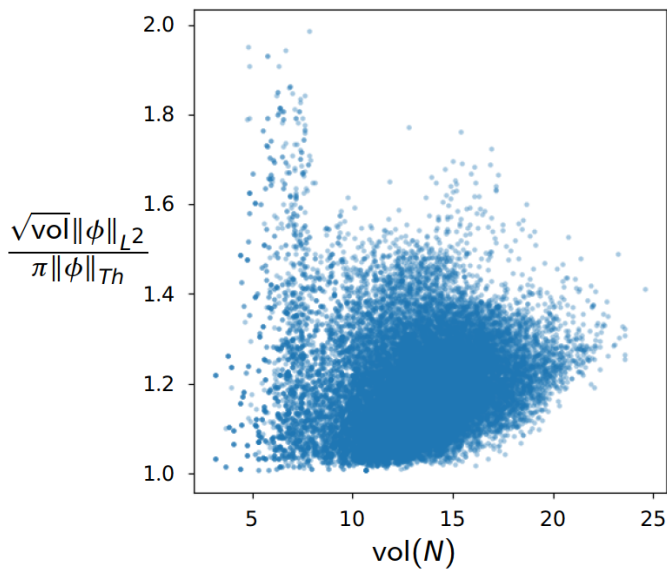


Figure 1: Data from Dunfield-Hirani

Sharpness for M closed

Can it achieve 1?

Proposition (H. '20):

The LHS of the inequality in Brock-Dunfield will never be realized:

$$\frac{\pi}{\sqrt{\text{vol}(M)}} \|\cdot\|_{Th} < \|\cdot\|_{L^2} \quad (7)$$

Proof of non-sharpness for Brock-Dunfield

First Proof by Bochner technique (Inspired by Stern)

Let α be a harmonic 1-form with constant length c , By Bochner formula,

$$|\nabla \alpha|^2 = 2|\alpha|^2 = 2c^2$$

The second fundamental form on S is

$$\sigma_S = \frac{\nabla \alpha}{|\alpha|} \Big|_S$$

which implies that

$$|\sigma_S|^2 = 2$$

Contradicts the property of holomorphic quadratic differential.

Second proof based on Wolf-Wu

Wolf-Wu: Geometric foliation

Locally geometric 1-parameter family of closed minimal surface: if \exists a closed surface S , $\epsilon > 0$, an embedding:

$$h : (-\epsilon, \epsilon) \times S \rightarrow M \quad (8)$$

$\forall p \in S$, $f(t, p) := \langle (h_t)_*(\partial_t), \nu \rangle|_{t=0}$ only depends on the principal curvature of S at p .

Geometric foliation and harmonic forms of constant length

- ① Harmonic form with constant length gives a foliation by minimal surface (fibered over S^1) with orthogonal geodesic flow. Particular case of Wolf-Wu.
- ② Theorem (Zeghib, '83): There is no smooth vector fields on a closed hyperbolic 3-manifold where all flow lines are geodesic.

Non-sharpness in the non-compact case is easier to prove, thanks to Mazzeo-Phillips, on asymptotic of harmonic forms near infinity.

A conjecture from Brock-Dunfield

Let M_j be a sequence of orientable closed hyperbolic 3-manifolds, converging geometrically to M . Then the

$$\sup_{H^1(M_j)} \frac{\|\cdot\|_{L^2}}{\|\cdot\|_{Th}} \sim \mathcal{O}\left(\sqrt{-\log(\text{inj}(M_j))}\right) \quad (9)$$

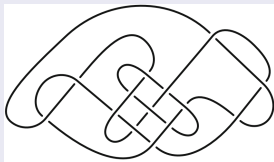


Figure 2: L14n21792

M_j is obtained from M by particular Dehn fillings.

Natural questions: one cusp? More than two cusps?

Theorem, H' 21

Let M_j be a sequence of orientable closed hyperbolic 3-manifolds, converging geometrically to M with one cusp. Then for j large enough,

$$\sup_{H^1(M_j)} \frac{\|\cdot\|_{L^2}}{\|\cdot\|_{Th}} < C \quad (10)$$

where C depends on M .

For n cusps, this is generic. Geometric convergence vs. Dehn fillings:

Outline of proof (for large j)

- 1 Use Hatcher '82 to conclude $H_2(M_j)$ all come from the closed non-peripheral surfaces from M , Im . Use Agol '01 to control the topological complexity;
- 2 Use barrier surface arguments to argue no deep disk, as in Wang '12, Huang-Wang '18, Hass '15, Mazet-Rosenberg '20. Use k -bi-Lipshitz diffeomorphism between thick part of M_j and M to argue no deep annulus, by the work of Futer-Purcell-Schleimer '19 (based on Bromberg-Brock 04, Hodgson-Kerckhoff '02) and Huang-Wang '17;
- 3 Modify Brock-Dunfield, replace $\text{inj}(M_j)$ by $\epsilon(M)$.

Thanks to the organizers and the audiences!