

a) Consider two plane waves given as

$$\mathbf{E}_1(\mathbf{r}, t) = E_0 \cos(kz - \omega t + \delta_1) \hat{x} + E_0 \sin(kz - \omega t + \delta_1) \hat{y} \quad \text{and}$$

$$\mathbf{E}_2(\mathbf{r}, t) = E_0 \cos(kz - \omega t + \delta_2) \hat{x} - E_0 \sin(kz - \omega t + \delta_2) \hat{y}.$$

Derive and simplify the expression for the superposition of these waves. Describe in a couple of sentences which polarization have the initial plane waves $\mathbf{E}_1, \mathbf{E}_2$ and which polarization has the superimposed field.

b) Derive the expression for the magnetic field \mathbf{H} of the superimposed field.

c) Calculate the instantaneous Poynting vector and the time-averaged Poynting vector of the superimposed field.

$$\cos\left(\frac{\pi}{2} + \alpha\right)$$

$$\cos\left(\alpha - \frac{\pi}{2}\right)$$

$$(\text{a}) \quad \vec{E} = \vec{E}_1(\vec{r}, t) + \vec{E}_2(\vec{r}, t) = E_0 [\cos(kz - \omega t + \delta_1) + \cos(kz - \omega t + \delta_2)] \hat{x} + E_0 [\sin(kz - \omega t + \delta_1) - \sin(kz - \omega t + \delta_2)] \hat{y}$$

$$\cos\alpha = \cos\left(\frac{\alpha+\beta}{2} + \frac{\alpha-\beta}{2}\right) = \cos\frac{\alpha+\beta}{2} \cos\frac{\alpha-\beta}{2} - \sin\frac{\alpha+\beta}{2} \sin\frac{\alpha-\beta}{2}$$

$$\cos\beta = \cos\left(\frac{\alpha+\beta}{2} - \frac{\alpha-\beta}{2}\right) = \cos\frac{\alpha+\beta}{2} \cos\frac{\alpha-\beta}{2} + \sin\frac{\alpha+\beta}{2} \sin\frac{\alpha-\beta}{2} \quad \Rightarrow \cos\alpha + \cos\beta = 2 \cos\frac{\alpha+\beta}{2} \cos\frac{\alpha-\beta}{2}$$

$$\cos(kz - \omega t + \phi_1) + \cos(kz - \omega t + \phi_2) = 2 \cos(kz - \omega t + \frac{\delta_1 + \delta_2}{2}) \cos(\frac{\delta_1 - \delta_2}{2})$$

$$\sin\alpha = \sin\left(\frac{\alpha+\beta}{2} + \frac{\alpha-\beta}{2}\right) = \sin\frac{\alpha+\beta}{2} \cos\frac{\alpha-\beta}{2} + \cos\frac{\alpha+\beta}{2} \sin\frac{\alpha-\beta}{2}$$

$$\sin\beta = \sin\left(\frac{\alpha+\beta}{2} - \frac{\alpha-\beta}{2}\right) = \sin\frac{\alpha+\beta}{2} \cos\frac{\alpha-\beta}{2} - \cos\frac{\alpha+\beta}{2} \sin\frac{\alpha-\beta}{2} \quad \Rightarrow \sin\alpha - \sin\beta = 2 \cos\frac{\alpha+\beta}{2} \sin\frac{\alpha-\beta}{2}$$

$$\sin(kz - \omega t + \delta_1) - \sin(kz - \omega t + \delta_2) = 2 \cos(kz - \omega t + \frac{\delta_1 + \delta_2}{2}) \sin\frac{\delta_1 - \delta_2}{2}$$

$$\Rightarrow \vec{E}_r = 2E_0 \left[\cos\frac{\delta_1 - \delta_2}{2} \cos(kz - \omega t + \frac{\delta_1 + \delta_2}{2}) \hat{x} + \sin\frac{\delta_1 - \delta_2}{2} \cos(kz - \omega t + \frac{\delta_1 + \delta_2}{2}) \hat{y} \right]$$

$$\delta = (\phi_x - \phi_y) \quad \text{for } \mathbf{E}_1 \text{ and } \mathbf{E}_2 \quad \delta_1 = \frac{\pi}{2} \quad \delta_2 = -\frac{\pi}{2} \quad \text{thus Circular Polarization}$$

$$\text{for } \vec{E} \quad \delta = \frac{\delta_1 + \delta_2}{2} - \frac{\delta_1 - \delta_2}{2} = 0 \quad \text{thus also Linear Polarization}$$

$$(\text{b}) \quad \nabla \times \vec{E} = -\mu_0 \frac{\partial \vec{H}}{\partial t}$$

$$\nabla \times \vec{E} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ E_x & E_y & 0 \end{vmatrix} = -\frac{\partial}{\partial z} E_y \hat{x} + \frac{\partial}{\partial z} E_x \hat{y} + \left(\frac{\partial}{\partial y} E_z - \frac{\partial}{\partial z} E_y \right) \hat{z} = -\frac{\partial}{\partial z} E_y \hat{x} + \frac{\partial}{\partial z} E_x \hat{y}$$

$$\frac{\partial}{\partial z} E_y = 2k E_0 \sin\frac{\delta_1 - \delta_2}{2} \sin(kz - \omega t + \frac{\delta_1 + \delta_2}{2}) \quad \frac{\partial}{\partial z} E_x = -2k E_0 \cos\frac{\delta_1 - \delta_2}{2} \sin(kz - \omega t + \frac{\delta_1 + \delta_2}{2})$$

$$\Rightarrow -\mu_0 \frac{\partial \vec{H}}{\partial t} = 2k E_0 \left[\sin\frac{\delta_1 - \delta_2}{2} \sin(kz - \omega t + \frac{\delta_1 + \delta_2}{2}) \hat{x} - \cos\frac{\delta_1 - \delta_2}{2} \sin(kz - \omega t + \frac{\delta_1 + \delta_2}{2}) \hat{y} \right]$$

$$\Rightarrow \vec{H}_r(z, t) = \frac{2k E_0}{\mu_0 \omega} \left[\sin\frac{\delta_1 - \delta_2}{2} \cos(kz - \omega t + \frac{\delta_1 + \delta_2}{2}) \hat{x} + \cos\frac{\delta_1 - \delta_2}{2} \cos(kz - \omega t + \frac{\delta_1 + \delta_2}{2}) \hat{y} \right]$$

$$(\text{c}) \quad S(\vec{r}, t) = \vec{E}_r \times \vec{H}_r = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ E_x & E_y & 0 \\ H_x & H_y & 0 \end{vmatrix} = (E_x H_y - E_y H_x) \hat{z}$$

$$S(\vec{r}, t) = \frac{4E_0^2 k}{\mu_0 \omega} \left[\cos^2\frac{\delta_1 - \delta_2}{2} \cos^2(kz - \omega t + \frac{\delta_1 + \delta_2}{2}) + \sin^2\frac{\delta_1 - \delta_2}{2} \cos^2(kz - \omega t + \frac{\delta_1 + \delta_2}{2}) \right]$$

$$= \frac{4E_0^2 k}{\mu_0 \omega} \cos^2(kz - \omega t + \frac{\delta_1 + \delta_2}{2})$$

$$\langle S(\vec{r}, t) \rangle = \frac{1}{T} \operatorname{Re} \left[\vec{E}(\vec{r}, t) \times \vec{H}^*(\vec{r}, t) \right] = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T S(\vec{r}, t) dt$$

$$\int_{-T}^T S(\vec{r}, t) dt = \frac{(4E_0^2 k)}{\mu_0 \omega} \int_{-T}^T \cos^2(kz - \omega t + \frac{\delta_1 + \delta_2}{2}) dt = \frac{2E_0^2 k}{\mu_0 \omega} \int_{-T}^T [1 + \cos(2kz - 2\omega t + \delta_1 + \delta_2)] dt$$

$$\begin{aligned}
 &= \frac{2E_0^2 k}{\mu_0 w} \left(2T + \int_{-T}^T \cos(2kz - 2wt + \delta_1 + \delta_2) dt \right) \\
 &= \frac{2E_0^2 k}{\mu_0 w} \left[2T - \frac{1}{2w} \sin(2kz - 2wt + \delta_1 + \delta_2) \Big|_{-T}^T \right] \\
 &= \frac{2E_0^2 k}{\mu_0 w} \left[2T + \frac{1}{w} \cos(2kz + \delta_1 + \delta_2) \sin(2wT) \right]
 \end{aligned}$$

$$\lim_{T \rightarrow \infty} \frac{2E_0^2 k}{\mu_0 w} \left[T + \frac{\cos(2kz + \delta_1 + \delta_2) \sin(2wT)}{2w} \right] = \frac{2E_0^2 k}{\mu_0 w}$$

$$\vec{H}(z) = -\frac{2kE_0}{w\mu_0} \sin \frac{\delta_1 - \delta_2}{2} e^{i(kz + \frac{\delta_1 + \delta_2}{2})} \hat{x} + \frac{2kE_0}{w\mu_0} \cos \frac{\delta_1 - \delta_2}{2} e^{i(kz + \frac{\delta_1 + \delta_2}{2})} \hat{y}$$

$$\vec{E}(z) = 2E_0 \cos \frac{\delta_1 - \delta_2}{2} e^{i(kz + \frac{\delta_1 + \delta_2}{2})} \hat{x} + 2E_0 \sin \frac{\delta_1 - \delta_2}{2} e^{i(kz + \frac{\delta_1 + \delta_2}{2})} \hat{y}$$

$$\begin{aligned}
 \vec{E}(\vec{r}) \times \vec{H}^*(\vec{r}) &= \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ E_x & E_y & 0 \\ H_x & H_y & 0 \end{vmatrix} = E_0 H_y - E_y H_x \\
 &= \frac{(4E_0^2 k) \cos \frac{\delta_1 - \delta_2}{2}}{w\mu_0} + \frac{(4E_0^2 k) \sin \frac{\delta_1 - \delta_2}{2}}{w\mu_0} = \frac{4E_0^2 k}{w\mu_0}
 \end{aligned}$$

$$S(\vec{r}, t) = \frac{1}{2} \operatorname{Re} [\vec{E}(\vec{r}) \times \vec{H}^*(\vec{r})] = \frac{2E_0^2 k}{w\mu_0}$$

The Jones formalism is a powerful technique for the treatment of polarized light. To take a look at it, let's consider a monochromatic plane wave in vacuum of the form $\mathbf{E}(r, t) = \mathbf{E}_0 e^{i(kz - \omega t)}$, where the electric field is polarized in the (x, y) -plane, so $\mathbf{E}_0 = (E_x, E_y, 0)$. We can write it in a form of so-called "Jones vector":

$$\mathbf{J}_{\text{in}} = \begin{pmatrix} E_x e^{i\varphi_x} \\ E_y e^{i\varphi_y} \end{pmatrix}.$$

Then light propagation through a polarizing optical element can be written as a linear transformation:

$$\mathbf{J}_{\text{out}} = \hat{\mathbf{T}} \cdot \mathbf{J}_{\text{in}}$$

where $\hat{\mathbf{T}}$ denotes a "Jones matrix" of that element.

Recommendation: For more information about the Jones formalism we strongly recommend to read B.E.A. Saleh, M.C. Teich "Fundamentals of Photonics", Chapter 6, pp.197-205.

- a) Elements of the Jones vectors and Jones matrices depend on the choice of the coordinate system. Consider, the Jones matrix of an x -polarizer is given by $\hat{\mathbf{T}} = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$. Now we rotate the polarizer around z by an angle 2θ . Using matrix methods, define the Jones matrix in the new coordinate system.
Hint: Make use of the rotation matrix.
- b) Is it possible to rotate the polarization direction of linearly polarized light by 90° using two linear polarizers? If yes, estimate in terms of intensity (excluding absorption), how large would be the total loss of such a system. How large would be the loss if one could use infinitely many linear polarizers? Explain your answers.
- c) Given is an optical element characterized by Jones matrix $\hat{\mathbf{T}} = \frac{1}{2} \begin{pmatrix} 1 & i \\ -i & 1 \end{pmatrix}$. Which polarization state should the light have to pass the element without change?

$$(a) \quad \hat{\mathbf{T}} = R(\theta) \hat{\mathbf{T}} R(-\theta) \Rightarrow \hat{\mathbf{T}}' = R(\theta) \hat{\mathbf{T}} R(-2\theta) = \begin{bmatrix} \cos 2\theta & -\sin 2\theta \\ \sin 2\theta & \cos 2\theta \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} \cos 2\theta & \sin 2\theta \\ -\sin 2\theta & \cos 2\theta \end{bmatrix}$$

$$= \begin{bmatrix} \cos 2\theta & 0 \\ \sin 2\theta & 0 \end{bmatrix} \begin{bmatrix} \cos 2\theta & \sin 2\theta \\ -\sin 2\theta & \cos 2\theta \end{bmatrix} = \begin{bmatrix} \cos^2 2\theta & \sin 2\theta \cos 2\theta \\ \sin 2\theta \cos 2\theta & \sin^2 2\theta \end{bmatrix}$$

$$b. \quad x\text{-polarized light} \quad \mathbf{J}_x = \hat{\mathbf{T}} \mathbf{J}_{\text{in}} = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} E_x e^{i\varphi_x} \\ E_y e^{i\varphi_y} \end{bmatrix} = \begin{bmatrix} E_x e^{i\varphi_x} \\ 0 \end{bmatrix}$$

Firstly rotating the polarized light at an angle of θ .

$$\Rightarrow \mathbf{J}_\theta = R(\theta) \hat{\mathbf{T}} R(-\theta) \quad \mathbf{J}_\theta = \begin{bmatrix} \cos^2 \theta & \sin \theta \cos \theta \\ \sin \theta \cos \theta & \sin^2 \theta \end{bmatrix} \begin{bmatrix} E_x e^{i\varphi_x} \\ 0 \end{bmatrix} = \begin{bmatrix} E_x \cos^2 \theta e^{i\varphi_x} \\ E_x \sin \theta \cos \theta e^{i\varphi_x} \end{bmatrix}$$

Then rotating the rotated light at an angle of $\theta_0 - \theta$: i.e. $\frac{\lambda}{2}$ from the start.

$$J_2 = R(\frac{\pi}{2}) T(R(\frac{\pi}{2})) J_0 = \begin{bmatrix} \cos^2 \frac{\pi}{2} & \sin^2 \frac{\pi}{2} \\ \sin^2 \frac{\pi}{2} & \cos^2 \frac{\pi}{2} \end{bmatrix} \begin{bmatrix} E_x \cos \theta e^{i\phi_x} \\ E_y \sin \theta e^{i\phi_y} \end{bmatrix}$$

$$= \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} E_x \cos^2 \theta e^{i\phi_x} \\ E_y \sin^2 \theta e^{i\phi_y} \end{bmatrix} = \begin{bmatrix} 0 \\ E_y \sin^2 \theta e^{i\phi_y} \end{bmatrix}$$

$$I = E_x^2 \quad I_{2z} = E_x^2 \sin^2 \theta \cos^2 \theta \quad I_{\text{loss}} = I - I_{2z} = E_x^2 (1 - \sin^2 \theta \cos^2 \theta) = E_x^2 (1 - \frac{1}{4} \sin^2 2\theta)$$

$$\Rightarrow \sin^2 2\theta = 0 \rightarrow \text{Maximum of Loss} \quad I_{\text{max}} = E_x^2$$

$$\sin^2 2\theta = 1 \rightarrow \text{Minimum of Loss} \quad I_{\text{min}} = \frac{3}{4} E_x^2$$

$$\text{Rotating at an angle of } \theta \Rightarrow J_0 = \begin{bmatrix} E_x \cos \theta e^{i\phi_x} \\ E_y \sin \theta e^{i\phi_y} \end{bmatrix} \Rightarrow I = E_x^2 (\cos^2 \theta + \sin^2 \theta) = E_x^2 \cos^2 \theta = I_0 \cos^2 \theta$$

Assume that we rotate the linear polarizers at $\frac{\pi}{2n}$ every time, totally n times

$$\Rightarrow I = I_0 \cos^{2n} \left(\frac{\pi}{2n} \right) \quad I_{\text{loss}} = I_0 - I = I_0 [1 - \cos^{2n} \left(\frac{\pi}{2n} \right)]$$

$$n=1 \rightarrow \text{maximum of Loss} : I_{\text{max}} = I_0$$

$$n \rightarrow \infty \rightarrow \text{minimum of Loss} : I_{\text{loss}} = I_0 \lim_{n \rightarrow \infty} [1 - \cos^{2n} \left(\frac{\pi}{2n} \right)] = 0.$$

$$(c) J_{\text{out}} = \frac{1}{2} J_{\text{in}} = \frac{1}{2} \begin{bmatrix} 1 & i \\ -i & 1 \end{bmatrix} \begin{bmatrix} E_x e^{i\phi_x} \\ E_y e^{i\phi_y} \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 & i \\ -i & 1 \end{bmatrix} \begin{bmatrix} J_x \\ J_y \end{bmatrix} = \lambda \begin{bmatrix} J_x \\ J_y \end{bmatrix}$$

$$\det \left(\frac{1}{2} - \lambda \right) = \begin{vmatrix} \frac{1}{2} - \lambda & \frac{i}{2} \\ -\frac{i}{2} & \frac{1}{2} - \lambda \end{vmatrix} = \left(\frac{1}{2} - \lambda \right)^2 - \frac{1}{4} = 0 \Rightarrow \lambda = 0 \quad \text{and} \quad \lambda = 1$$

$$\lambda = 0 \Rightarrow \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \begin{bmatrix} J_x \\ J_y \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Rightarrow \begin{cases} J_x + iJ_y = 0 \\ -iJ_x + J_y = 0 \end{cases} \Rightarrow \begin{cases} J_x = 1 \\ J_y = i \end{cases} \Rightarrow J_1 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ i \end{bmatrix}$$

$$\lambda = 1 \Rightarrow \begin{bmatrix} \frac{1}{2} & \frac{i}{2} \\ -\frac{i}{2} & \frac{1}{2} \end{bmatrix} \begin{bmatrix} J_x \\ J_y \end{bmatrix} = \begin{bmatrix} J_x \\ J_y \end{bmatrix} \Rightarrow \begin{cases} J_x + iJ_y = 2J_x \\ -iJ_x + J_y = 2J_y \end{cases} \Rightarrow \begin{cases} J_x = 1 \\ J_y = -i \end{cases} \Rightarrow J_2 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ -i \end{bmatrix}$$

$$\text{For } J_1 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ i \end{bmatrix} = \frac{1}{\sqrt{2}} \begin{bmatrix} e^{i0} \\ e^{i\frac{\pi}{2}} \end{bmatrix} \quad \delta = \phi_x - \phi_y = -\frac{\pi}{2} \quad E_x = E_y \Rightarrow \text{circular polarization}$$

$$\text{For } J_2 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ -i \end{bmatrix} = \frac{1}{\sqrt{2}} \begin{bmatrix} e^{i0} \\ e^{-i\frac{\pi}{2}} \end{bmatrix} \quad \delta = \phi_x - \phi_y = \frac{\pi}{2} \quad E_x = E_y \Rightarrow \text{circular polarization}$$

Thus, the light should have circular polarization

Normal modes of a polarization system are the waves which polarization states remain unchanged after transmission through the polarization system. These modes are characterized by the Jones vectors satisfying the eigenproblem

$$\hat{T}J = aJ,$$

where a is a constant, meaning that the normal modes a the eigenvectors of the Jones matrix.

a) Show that the normal modes of the linear polarizer with

$$\hat{T} = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$$

are linearly polarized waves.

b) Show that the normal modes of the wave retarder with

$$\hat{T} = \begin{pmatrix} 1 & 0 \\ 0 & e^{-i\Gamma} \end{pmatrix}$$

are linearly polarized waves. As can be seen from the Jones matrix, the wave retarder delays the y -component by a phase Γ , while the x -component remains unchanged, which is why this element is called "retarder".

c) Show that the normal modes of the polarization rotator with

$$\hat{T} = \begin{pmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{pmatrix}$$

are right and left circularly polarized waves.

$$(a) \det(\hat{T} - aI) = \begin{vmatrix} -a & 0 \\ 0 & -a \end{vmatrix} = 0 \Rightarrow a(-a) = 0 \Rightarrow a_1 = 1 \quad a_2 = 0$$

$$\text{for } a_2 = 0 \Rightarrow \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} J_x \\ J_y \end{bmatrix} = 0 \begin{bmatrix} J_x \\ J_y \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} J_y \\ J_y \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Rightarrow J_1 = \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0^{i0} \end{bmatrix}$$

$$\text{for } a_1 = 1 \Rightarrow \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} J_x \\ J_y \end{bmatrix} = \begin{bmatrix} J_x \\ J_y \end{bmatrix} \Rightarrow J_2 = \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} e^{i0} \\ 0 \end{bmatrix}$$

Thus the normal modes are linear waves

$$(b) \det(\hat{T} - aI) = \begin{vmatrix} -a & 0 \\ 0 & e^{-i\Gamma} - a \end{vmatrix} = (-a)(e^{-i\Gamma} - a) = 0 \Rightarrow \begin{array}{l} a_1 = 1 \\ a_2 = e^{-i\Gamma} \end{array}$$

$$\text{for } a_1 = 1 \quad \begin{bmatrix} 1 & 0 \\ 0 & e^{-i\Gamma} \end{bmatrix} \begin{bmatrix} J_x \\ J_y \end{bmatrix} = \begin{bmatrix} J_x \\ J_y \end{bmatrix} \Rightarrow J_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\text{for } a_2 = e^{-i\Gamma} \quad \begin{bmatrix} 1 & 0 \\ 0 & e^{-i\Gamma} \end{bmatrix} \begin{bmatrix} J_x \\ J_y \end{bmatrix} = \begin{bmatrix} e^{-i\Gamma} J_x \\ e^{-i\Gamma} J_y \end{bmatrix} = J_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

Thus they are linear polarized waves

$$(c) \det(\hat{T} - aI) = \begin{vmatrix} \cos\theta - a & -\sin\theta \\ \sin\theta & \cos\theta - a \end{vmatrix} = (\cos\theta - a)^2 + \sin^2\theta = 0 \Rightarrow a^2 - 2a\cos\theta + 1 = 0$$

$$a_1 = \frac{\cos\theta + \sqrt{\cos^2\theta - 1}}{2} = \cos\theta + i\sin\theta = e^{i\theta} \quad a_2 = e^{-i\theta}$$

$$\text{for } a_1 = e^{i\theta} \quad \begin{bmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{bmatrix} \begin{bmatrix} J_x \\ J_y \end{bmatrix} = \begin{bmatrix} e^{i\theta} J_x \\ e^{i\theta} J_y \end{bmatrix} \Rightarrow \begin{cases} \cos\theta J_x - \sin\theta J_y = e^{i\theta} J_x \\ \sin\theta J_x + \cos\theta J_y = e^{i\theta} J_y \end{cases} \Rightarrow T_1 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ -i \end{bmatrix}$$

$$\text{for } a_2 = e^{-i\theta} \quad \begin{bmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{bmatrix} \begin{bmatrix} J_x \\ J_y \end{bmatrix} = \begin{bmatrix} e^{-i\theta} J_x \\ e^{-i\theta} J_y \end{bmatrix} \Rightarrow \begin{cases} J_x \cos\theta - J_y \sin\theta = e^{-i\theta} J_x \\ J_x \sin\theta + J_y \cos\theta = e^{-i\theta} J_y \end{cases} \Rightarrow T_2 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ i \end{bmatrix}$$

Thus they are right and left circular polarized waves.

