Problem 1

a) in timedomain

$$\nabla \cdot H = 0$$
 $\nabla X H = \hat{J} + \frac{\partial P}{\partial z}$
 $\nabla \cdot D = 0$ $\nabla X \Sigma = -M_n \frac{\partial H}{\partial z}$
in Freq Johnain
 $\nabla \cdot \hat{H} = \hat{J} - i \omega \hat{D}$

D.D=O DX = MOLWA

in time domain
$$D = Go \Sigma + Go \int R(V, t - t') \Sigma(V, t') dt'$$
in Frey Jamain $-\infty$

$$\bar{D} = Go \bar{\Sigma} + Go (K(W)) \bar{\Sigma} = Go G(W) \bar{\Sigma}$$

$$\Delta H + \frac{w^2}{C^2} \in Cw) = -ociwpo H$$

@ since
$$K^2 = \frac{\omega}{c} \mathcal{E}(\omega) => M = \frac{\omega}{c} \sqrt{\mathcal{E}(\omega)}$$

$$K = \frac{\omega}{c} \sqrt{\mathcal{E}' + i \mathcal{E}''} \quad \text{since } \mathcal{E}' >> \mathcal{E}''$$

$$K = \frac{\omega}{2} \sqrt{\varepsilon'} + \frac{i\varepsilon''}{2\sqrt{\varepsilon''}} = \gamma V' = \frac{\omega}{2} \sqrt{\varepsilon'}, \quad K'' = \frac{\varepsilon''}{2\sqrt{\varepsilon''}}$$

$$\Sigma_{Y}(\mathbf{r},t) = \Sigma_{0} e^{-\kappa''^{2}} \cos(\kappa'^{2} - \omega t + \phi) \hat{X}$$

$$\nabla X \Sigma_{Y} = [\hat{X} \hat{y} \hat{y} \hat{z}] \qquad -\kappa''^{2}$$

$$\Sigma_{Y}(x,t) = \Sigma_{0}e^{-K''^{2}}\cos\left(\frac{K'^{2}-\omega t}{A}+\phi\right)\hat{X}$$

$$\nabla X \Sigma_{Y} = \begin{bmatrix} \hat{X} & \hat{y} & \hat{z}^{2} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \end{bmatrix} = (\Sigma_{0}K''e^{-K''^{2}})(S_{0}A + \Sigma_{0}e^{-K''^{2}})(S_{0}A + \Sigma_{0}e^{-K''})(S_{0}A + \Sigma_{0}e^{-K''})(S_{0}$$

by takinging the average of both

$$\langle S_{1}(r_{1}t)\rangle = \frac{-\xi_{0}^{2} \kappa'}{2 \mu_{0} w} e^{-2\kappa''\xi}$$

$$Q(x) = A \left[1 + \cos \frac{2\pi x}{\sigma}\right] \quad call \frac{2\pi}{\sigma} = K$$

$$U_0(x) = \frac{A}{2\pi} \int (1 + \cos \kappa x) e^{i\kappa x} dx$$

$$U(\alpha;2) = A \left[S(\alpha) + \frac{1}{2} \left[S(\alpha - K) + S(\alpha + K) \right] e^{-i\alpha X} \right]$$

$$U(\alpha x; z) = A \int_{-i\alpha x} U(\alpha; z) e^{-i\alpha x} d\alpha$$

$$U(2X)^{2} = A \int U(x)^{2} E$$

$$= A \int e^{iX_{0}^{2}} + \frac{1}{2} \left[e + \frac{1}{2} \left[$$

$$=>A\left[e^{iK_0\frac{2}{2}}+e^{iV_{K_0^2}-K^2\frac{2}{2}}\cos x\right]$$

Since in talbot effect
$$U(X, 2=L_7) = U(X, 2=0)\theta$$

=> if we ignored the phase term that destray the perodicity

$$\frac{i\sqrt{\kappa_o^2 - \kappa^2}}{\ell} \frac{1}{2\tau} - i \kappa_o 2\tau - 2 \kappa ni}{\ell} = 1$$

$$= 5 \sqrt{\kappa_0^2 + \kappa^2} L_T - \kappa_0 L_T - 2\pi n = 0$$

$$L_{1} = \frac{2\pi n}{\sqrt{\kappa_{0}^{2} - \kappa_{2}^{2} - \frac{1}{12}\kappa_{0}^{2}}}, \text{ The shortest repetition } n = 1$$

$$L_{1} = \frac{2\pi n}{\sqrt{\kappa_{0}^{2} - \kappa_{2}^{2} - \frac{1}{12}\kappa_{0}^{2}}} - \frac{2\pi}{\sqrt{\frac{1}{12} - \frac{1}{6^{2}}}} - \frac{1}{\sqrt{\frac{1}{12} - \frac{1}{6^{2}}}}$$
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O under fersnel condition that $K_0^2 > 7 \propto^2$ which cause $H_5 = \frac{c K_0 2}{e 2K_0} - \frac{c x^2}{2K_0}$ where $x^2 = \left(\frac{26}{G}\right)^2$ Then $K_0 \left(1 - \frac{x^2}{2K_0^2}\right)$ $L_7 = \frac{27N}{2K_0} = \frac{27N(2K_0)}{2K_0}$

$$L_{7} = \frac{2\pi n}{\kappa / - \frac{\kappa^{2}}{2\kappa_{0}}} = \frac{2\pi n (2\kappa_{0})}{\kappa^{2}}$$

$$= \frac{4\pi \eta 2\pi}{\lambda \frac{4\pi^2}{G^2}} = \frac{2\eta G^2}{\lambda}$$

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$$\frac{1}{\sqrt{2}} = \frac{3K}{3W} = \frac{1}{C_0} \left[n_{CW_0} + \frac{3W}{3W} \right]_{W_0}$$

$$= 7 \text{ Vg} = \frac{C_0}{2 + 3(10^{-32} \times 4 \times 10^{0})} = \frac{C_0}{2.12}$$

where
$$\frac{\partial h}{\partial w} = 2w^{C}$$

$$\frac{D}{7} q(0) = \frac{T_0^2 (C_0 + i)}{2D(1 + C_0^2)}$$
 Since $C_0 = 0$ (Flat Phase)

$$Q(0) = \frac{70^2 i}{2D}$$

* propagate distanc L

$$9(1) = \frac{T_0^2 i}{2D} + 2 = \frac{T_0^2 i + 22D}{2D}$$

$$\frac{1}{9(1)} = \frac{2D}{7_0^2 i + 2LD} = 3 - \frac{2DT_0^2 i + 4D^2 \lambda}{24\lambda^2 D^2 + T_0^4}$$

$$= \frac{4D^2 \lambda}{4D^2 + T_0 u} - \frac{i 2D T_0^2}{4D^2 + T_0^4}$$

$$\frac{1}{Q_{i}(\lambda)} = \frac{1}{2} \frac{U0^{2} \lambda_{i}}{U\lambda^{2} D^{2} + T_{0} g(T_{0}^{2})} - \frac{i}{2} \frac{2D T_{0}^{2}}{U\lambda^{2} D^{2} + T_{0}^{4}} \frac{(T_{0}^{2})}{U\lambda^{2} D^{2} + T_{0}^{4}} (T_{0}^{2})$$

$$= \frac{2D}{T_{0}^{2}} \left[\frac{2D \lambda_{i}}{U\lambda^{2} D^{2} + T_{0}^{4}} - \frac{i}{U\lambda^{2} D^{2} + T_{0}^{4}} \frac{T_{0}^{4}}{U\lambda^{2} D^{2} + T_{0}^{4}} \right]$$

$$C(2) \qquad \frac{T_{0}^{2}}{T^{2}(2)}$$
For the control of the

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$$= \frac{T_0^2 y}{4 \lambda^2 D^2 + T_0^4} = \frac{T_0^2}{T_0^2(2)} = \frac{T_0^2 (\lambda)}{T_0^2} = \frac{4 \lambda^2 D^2 + T_0^4}{T_0^2}$$

$$T(1) = \sqrt{\frac{41^2 v^2 + 70^4}{T_0^2}}$$

sinc
$$D = \frac{\partial^2 \kappa^2}{\partial \omega^2} = \frac{1}{-V_g^2} \frac{\partial V_g}{\partial \omega} = \frac{\partial}{\partial \omega} \left(\frac{1}{V_g} \right)$$

and
$$\frac{1}{V9} = \frac{1}{C_0} \left[N + 2\omega^2 C \right] = \frac{1}{C_0} \left[B + 3\omega^2 C \right]$$

Then
$$D = 6 \times 2 \times 10^{15} \times 10^{-32} = \frac{112 \times 10^{-16}}{112 \times 10^{-16}}$$

Then

$$T_{1}(L) = \sqrt{\frac{4 \times 400 \times (\frac{1}{2} \times 10^{-16})^{2} + (4 \times 10^{-12})^{4}}{(4 \times 10^{-12})^{2}}}$$

(C=0 => D=0

The diffunc = 1 Ti -Tz = !

$$\frac{1}{9(2)} = \frac{1}{R(2)} + \frac{i'}{20}$$
 Since we stat at the waist. Res

$$\frac{1}{q(a)} = +\frac{i}{2a} = 9 \quad q(a) = -i\frac{2}{2a}$$

$$= \frac{1}{9(2)^{2}} = \frac{1}{2 - i20} = \frac{2^{2}}{2^{2}} \sqrt{i20^{2}} + \frac{i20}{2^{2} + 20^{2}}$$

$$= \frac{1}{2(1+\frac{2^{2}}{2^{2}})} + \frac{1}{2^{2}(1+\frac{2^{3}}{20^{2}})}$$

$$\int \frac{\chi}{\chi^{2}(2)} = \frac{\chi}{\chi^{2}(2)} = \chi^{2}(2) = \chi^{2}(1 + \frac{z^{2}}{2^{2}})$$

$$= \chi^{2}(2) = \chi^{2}(2) = \chi^{2}(1 + \frac{z^{2}}{2^{2}})$$

$$Q_{+} = \frac{-i20(1-2/5) + 24}{-i20/5} = \frac{1-i20/5}{2'-i20(1-2/5)}$$

$$\frac{1}{4} = \frac{2' - i20(1 - 2/5) - \frac{i202'}{5} + 20/5(1 - 2/5)}{2'^2 + 20^2(1 - 2/5)^2}$$

$$\frac{1}{9} = \frac{2' - i20}{\frac{12}{15}} + \frac{i29}{15} - \frac{i29}{15} + \frac{20^{2}}{15} + \frac{20^{2}}{15} + \frac{20^{2}}{15} = \frac{2^{2}}{15} + \frac{20^{2}}{15} +$$

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