
PROJECT REPORT: FRACTURE FIXATION FEA SIMULATION

TECHNICAL REPORT

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ABSTRACT

This report details the implementation and evaluation of a finite element analysis simulation for fracture fixation. We present a comprehensive study examining the mechanical behavior of bone-implant systems under various loading conditions. Our methodology incorporates detailed geometric modeling, material property characterization, and boundary condition specifications to accurately simulate the biomechanical environment.

Keywords FEA · Fracture Fixation

1 Introduction

In fracture repair processes, as splints or internal fixators gradually reduce load-bearing, the fracture region begins to regain stress-bearing capacity. This project simulates how decreasing splint stiffness (or increasing fracture surface bonding strength) in a "bone+splint" system affects stress redistribution during healing, helping to understand the biomechanical phenomenon of "stress transfer".

2 FEA Modeling Stress Redistribution During Fracture Healing

2.1 Problem Definition

- **Type:** Non-homogeneous elastic body under load with time-varying material properties (elastic modulus)
- **Model:** 2D "bone+splint" system with either:
 - Gradually recovering fracture surface stiffness, or
 - Progressively decreasing splint stiffness
- **Features:** Simulation of stress transfer from splint to bone tissue

2.2 Mathematical Model

2.2.1 Mechanical Framework

Linear elasticity theory with time-dependent parameters:

$$\sigma^{(t)} = \mathbf{D}^{(t)} \epsilon$$

where $\mathbf{D}^{(t)}$ evolves with healing progression.

2.2.2 Material Evolution

Bone tissue : $E_{bone} \approx 17$ GPa (constant)

Splint : $E_{splint}^{(t)}$ (may decrease)

Callus : $E_{callus}^{(t)}$ (increases with healing)

2.2.3 Fracture Interface

Bonding coefficient $\beta(t)$ represents healing progress:

$$\beta(t) \in [0, 1] \quad (0 = \text{unhealed}, 1 = \text{fully bonded})$$

2.3 Finite Element Implementation

2.3.1 CST Element Formulation

Displacement field for triangular elements:

$$\mathbf{u} = \begin{bmatrix} u(x, y) \\ v(x, y) \end{bmatrix} = \mathbf{N} \mathbf{d}^e$$

Strain-displacement relationship:

$$\boldsymbol{\varepsilon} = \mathbf{B} \mathbf{d}^e$$

where \mathbf{B} is the strain-displacement matrix.

2.3.2 Time-Stepping Algorithm

1. Initialize material properties $E_{callus}(t_0), E_{splint}(t_0)$
2. Compute element stiffness matrices:

$$\mathbf{K}^{e(t)} = t \mathbf{A} \mathbf{B}^T \mathbf{D}^{(t)} \mathbf{B}$$

3. Assemble global system:

$$\mathbf{K}^{(t)} \mathbf{d}^{(t)} = \mathbf{F}^{(t)}$$

4. Update material properties for next time step

2.4 Expected Outcomes

- Quantification of stress shielding effects
- Optimal load transfer protocols
- Time-dependent stress distribution visualizations
- Correlation between mechanical environment and healing rates

2.5 Results

2.6 Discussion

3 Conclusion

[Kour and Saabne, 2014]

References

George Kour and Raid Saabne. Real-time segmentation of on-line handwritten arabic script. In *Frontiers in Handwriting Recognition (ICFHR), 2014 14th International Conference on*, pages 417–422. IEEE, 2014.