

Analogue Electronics

Xiping Hu

<https://hxp.plus/>

June 20, 2020

Contents

1	Basics of Circuits	7
1.1	The direction of current and voltage	7
1.2	How to determine whether a component is consuming or providing energy	7
1.3	Electronic Components	7
1.3.1	Resistors	7
1.3.2	Power Sources	7
1.4	Kirchhoff's Laws	8
1.4.1	Kirchhoff's Current Law	8
1.4.2	Kirchhoff's Voltage Law	8
1.5	Gain of an Amplifier Circuit	8
2	Operational Amplifier	9
2.1	Operational Amplifier	9
2.2	Ideal Operational Amplifier	10
2.3	Closed-looped Amplifier	10
2.3.1	Non-inverting Operational Amplifier	10
2.3.2	Inverting Operational Amplifier	11
2.4	Applications of operational amplifiers	11
2.4.1	Subtraction Circuit	11
2.4.2	Sum Circuit	12
2.4.3	Instrumentation Amplifier	13
2.4.4	Integrating Circuit	13
2.4.5	Differential Circuit	14
3	Diodes	15
3.1	Semiconductors	15
3.1.1	Intrinsic Semiconductor	15
3.1.2	Extrinsic Semiconductor	15
3.2	P-N Junction and Diode	15
3.2.1	Breakdown of P-N Junction	16
3.3	Diode modeling	16
3.3.1	Real Diode Modeling	16
3.3.2	Mathematically idealized diode	16
3.3.3	Ideal diode in series with voltage source	17
3.3.4	Diode with voltage source and current-limiting resistor	17
3.3.5	Diode in Small Signal Circuits	18
3.4	Applications of Diodes	18
3.4.1	Rectifier Circuit	18
3.4.2	Limiting Circuit	19
3.4.3	Switching Circuit	19
3.5	Diodes for Special Usage	20
3.5.1	Zener diode	20
3.5.2	Photodiode	20
3.5.3	Light-emitting diode	20

3.5.4	Schottky diode	20
4	MOSFET and Amplifying Circuit	21
4.1	Classification of MOSFET	21
4.1.1	N-type Enhancement-mode MOSFET	21
4.1.2	N-type Depletion-mode MOSFET	22
4.1.3	P-type MOSFET	23
4.2	Static Working Point	24
4.3	Early Effect	24
4.4	Three types of Amplifier Circuit	25
4.4.1	Common Source Amplifier Circuit	25
4.4.2	Common Drain Amplifier Circuit	26
4.4.3	Common Gate Amplifier Circuit	26
4.5	Summary	27
4.5.1	Features of Three Types of MOSFET Amplifying Circuits	27
4.5.2	Small Signal Model of MOSFET	27
4.5.3	Saturation Mode of MOSFET	27
5	Bipolar Junction Transistor	29
5.1	Electronic Symbol	29
5.2	Control Principle	30
5.3	Three Types of Amplifier Circuit	30
5.4	Static Working Point	30
5.5	Determine the working state of BJT	31
5.6	Model of Small Signal	32
5.7	Compound Transistor	32
6	Frequency Response	33
6.1	Sketch of Gain vs Frequency of All Circuits	33
6.2	R-C Series Circuit	33
6.2.1	Low-Frequency Response of R-C High Pass Filter	33
6.2.2	Mid-Frequency	34
6.2.3	High-Frequency Response of R-C Low Pass Filter	34
6.3	Frequency Response of Amplifiers	34
6.3.1	Low-Frequency	34
6.3.2	High-Frequency	36
7	Analogue Integrated Circuits	39
7.1	Differential Amplifier Circuit	39
7.2	MOSFET Current Source	39
7.2.1	MOSFET Current Mirror	39
7.2.2	Cascade Current Mirror	40
7.2.3	Combined Current Mirror	40
7.2.4	JFET Current Mirror	41
7.3	BJT Current Source	41
7.3.1	BJT Current Mirror	41
7.3.2	Micro Current Source	42
7.3.3	Current Source with High Output Resistance	42
7.3.4	Combined Current Source	43
7.4	Differential Amplifier	43
7.4.1	MOSFET	43
7.4.2	BJT	44
8	Feedback	47
8.1	Basic Feedback Structure	47
8.2	Bandwidth and Gain	47
8.3	Stability Problem of Feedback	48

8.4	Four Basic Feedback Topologies	48
8.5	Positive or Negative	49
8.6	Virtual Short and Open Circuit of Amplifier in the State of Deep Negative Feedback	49
9	Power Amplifiers	51
9.1	Classification of Power Amplifiers	51
9.2	Some Example Circuits	52
9.3	Power Output	52
9.4	Crossover Distortion Avoiding	52
10	Filters and Signal Generators	53
10.1	Four Types of Filters	53
10.2	Filter with source	53
10.3	Sallen-Key Filtering Circuit	54
10.4	Voltage Comparator	54
10.5	Inverting Schmitt Trigger	54
10.6	RC Phase Shifting Network	54
10.7	Stability of RC Oscillator	55
10.8	RC Phase Selecting Network	55
10.9	Generation of Square Waveforms	56
10.10	Generation of Triangle Waveforms	56
11	Stability Problem of DC Source	57
11.1	The Bridge Rectifier	57
11.2	Single Phase Bridge Rectifier	57
11.3	Series Feedback Voltage Regulator	58
11.4	Integrated Voltage Regulator	58

Chapter 1

Basics of Circuits

1.1 The direction of current and voltage

In complex problems, we can not always know the direction of currents or voltage. The usual solution is to assume a direction, and use it to solve problems. If the solution of current or voltage, is positive, then the position is just what we assumed, and vice versa.

1.2 How to determine whether a component is consuming or providing energy

For resistors, resistors are always consuming energy.

For power sources, if the direction of current is from the positive electrode to the negative electrode, then the power source is consuming energy, and vice versa.

1.3 Eletronic Components

1.3.1 Resistors

$$U = -IR$$

1.3.2 Power Sources

(Controlled) Voltage Source

$$P = UI$$

The resistance of an ideal voltage source is : 0

Note that an ideal voltage source must not be short-circuited.

(Controlled) Current Source

The current through a current source is only decided by the source itself.

The resistance of an ideal current source is : ∞

Note that an ideal current source must not be open-circuited.

1.4 Kirchhoff's Laws

- branch
- node
- loop
- mesh

1.4.1 Kirchhoff's Current Law

For each node in the circuit, as the node can not accumulate charges, the sum of current is zero.

$$\sum I = 0$$

1.4.2 Kirchhoff's Voltage Law

For each loop in circuit, the sum of the voltage in of all branches is zero.

$$\sum U = 0$$

1.5 Gain of an Amplifier Circuit

	Voltage	Current	Transresistance	Transconductance	Power
Gain	$A_v = \frac{v_o}{v_i}$	$A_i = \frac{i_o}{i_i}$	$A_r = \frac{v_o}{i_i}$	$A_g = \frac{i_o}{v_i}$	$A_p = \frac{P_o}{P_i}$
Gain in dB	$20 \lg A_v $	$20 \lg A_i $	$20 \lg A_r $	$20 \lg A_g $	$10 \lg A_p$

Chapter 2

Operational Amplifier

2.1 Operational Amplifier

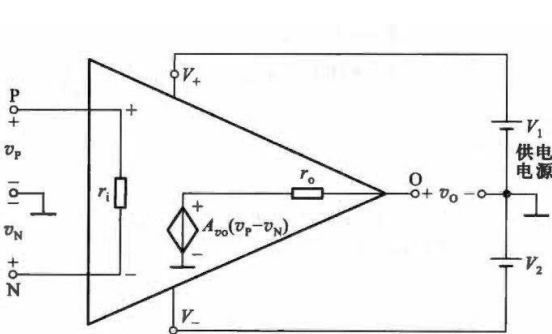
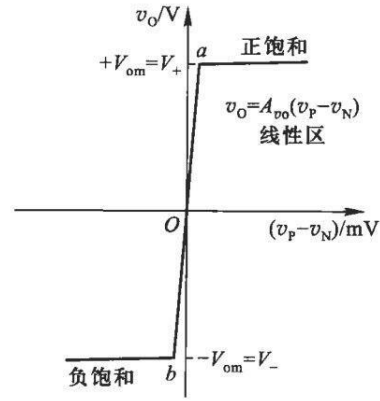


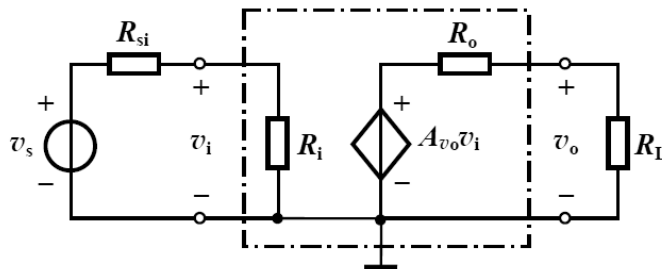
图 2.1.3 运算放大器的电路简化模型



We define r_i as the input impedance, r_o as the output impedance. v_p as the non-inverting input, v_n the inverting input.

Usually, we have $v_p \approx v_n$, $r_i \approx \infty$, $r_o \approx 0$.

Note that the output voltage of a operational amplifier has limits, called **Bandwidth**. When the input voltage exceeds the limits, it outputs the maximum or minimum value.



$$A_v = \frac{v_o}{v_i} = A_{vo} \cdot \frac{R_L}{R_o + R_L}$$

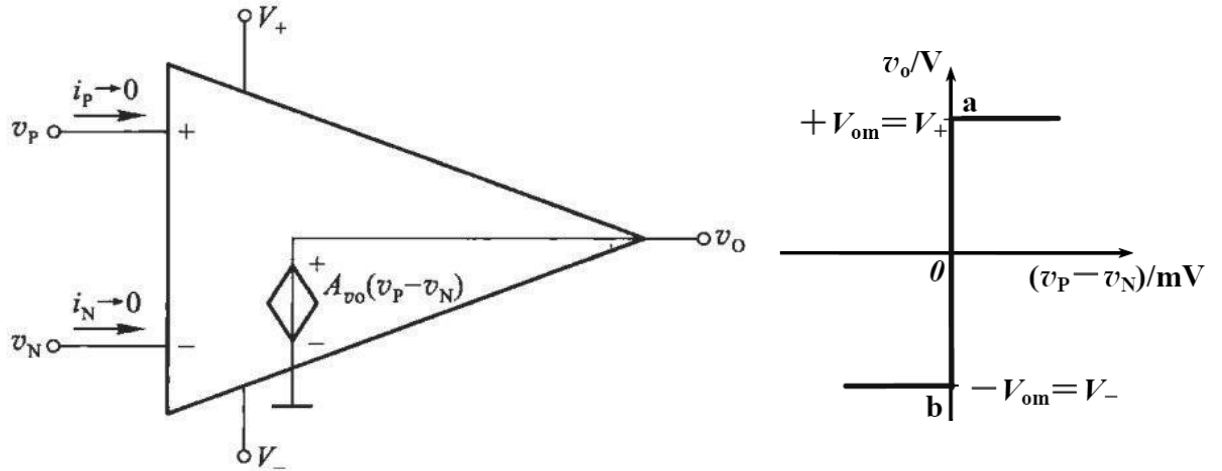
The output resistance may infect the gain of amplifier. The larger R_L is, the more A_v approaches A_{vo} , while the ideal case is when $R_o = 0$

2.2 Ideal Operational Amplifier

For ideal operational amplifier:

- $v_p = v_n$, $i_i = 0$, $r_i = \infty$
- $r_o = 0$, $v_o = A_{vo}(v_p - v_n)$
- $\text{bandwidth} = \infty$

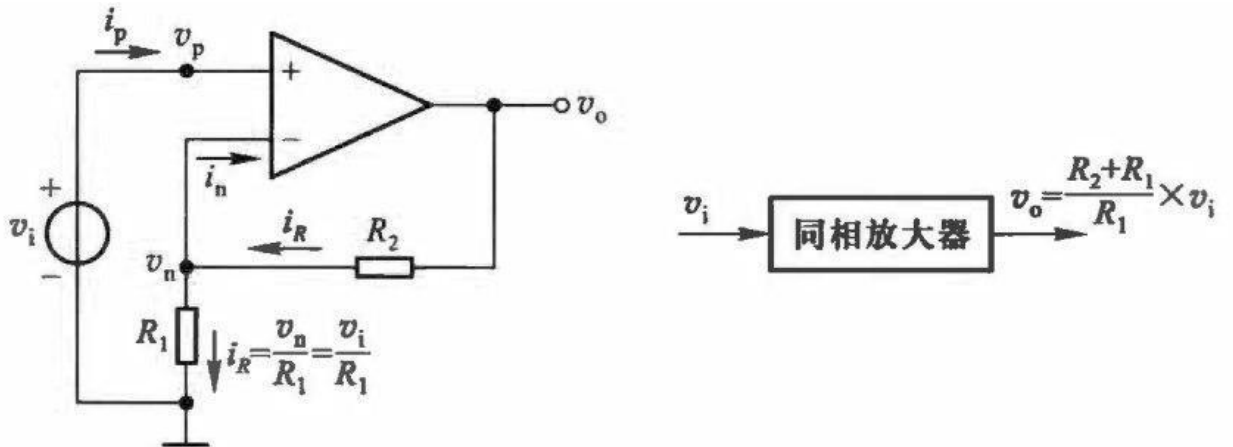
Here is a model which shows all the feature of an ideal operational comparator:



2.3 Closed-looped Amplifier

Usually operational amplifiers are used with vegetative feedback to ensure its stability. We apply a portion of output voltage to input, reducing the gain of a circuit.

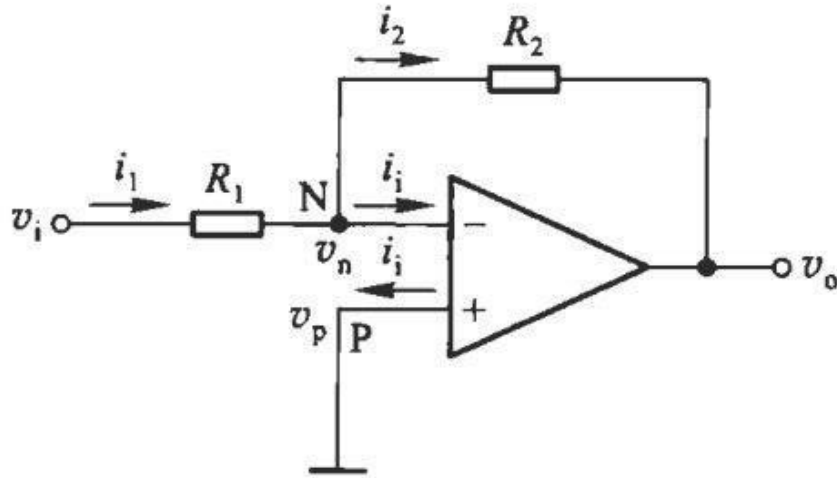
2.3.1 Non-inverting Operational Amplifier



$$A_{vo} = \frac{R_2 + R_1}{R_1} = 1 + \frac{R_2}{R_1}$$

Note that when $R_2 \ll R_1$, $A_{vo} = 1$, $v_i = v_o$.

2.3.2 Inverting Operational Amplifier

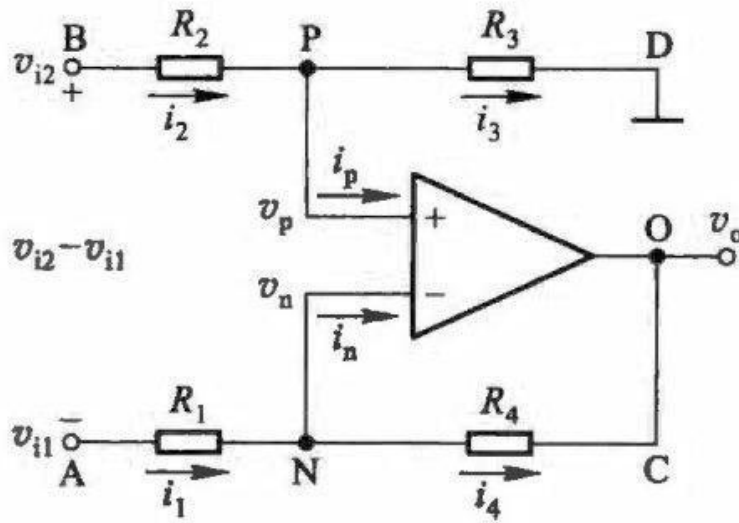


$$A_{vo} = -\frac{R_2}{R_1}$$

2.4 Applications of operational amplifiers

2.4.1 Subtraction Circuit

An subtraction circuit can calculate the difference of inverting input and non-inverting input.



$$\begin{cases} \frac{v_{i2} - v_p}{R_2} = \frac{v_p}{R_3} \\ \frac{v_{i1} - v_n}{R_1} = \frac{v_n - v_o}{R_4} \end{cases}$$

$$\begin{cases} R_3(v_{i2} - v_p) = R_2 v_p & \Rightarrow v_p = \frac{R_3}{R_2 + R_3} v_{i2} \\ R_4(v_{i1} - v_n) = R_1(v_n - v_o) & \Rightarrow v_n = \frac{R_4 v_{i1} + R_1 v_o}{R_4 + R_1} \end{cases}$$

$$\frac{R_3}{R_2 + R_3} v_{i2} = \frac{R_4 v_{i1} + R_1 v_o}{R_4 + R_1}$$

$$\frac{R_3 (R_4 + R_1)}{R_2 + R_3} v_{i2} = R_4 v_{i1} + R_1 v_o$$

\Rightarrow

$$v_o = \frac{\frac{R_4}{R_1} + 1}{\frac{R_2}{R_3} + 1} v_{i2} - \frac{R_4}{R_1} v_{i1} = \left(1 + \frac{R_4}{R_1}\right) \frac{\frac{R_3}{R_2}}{1 + \frac{R_3}{R_2}} v_{i2} - \frac{R_4}{R_1} v_{i1}$$

If $R_4/R_1 = R_3/R_2 = r$, then

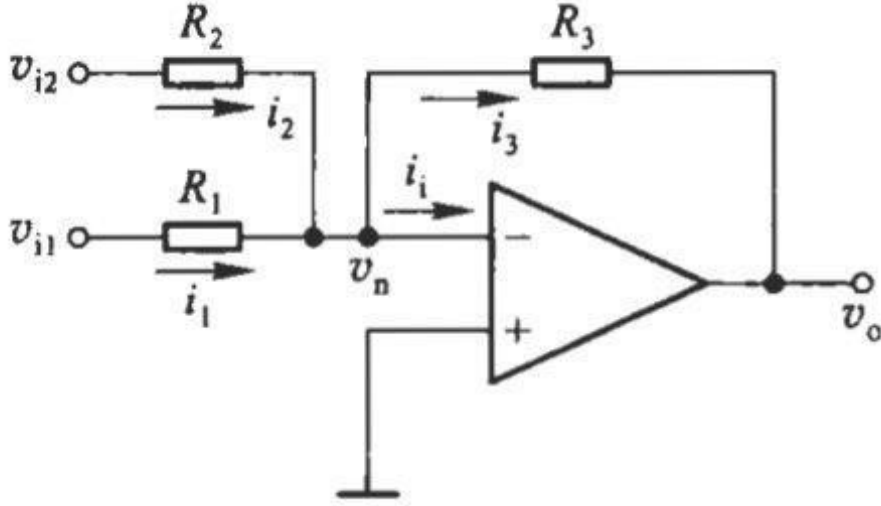
$$v_o = (1 + r) \frac{r}{1 + r} v_{i2} - r v_{i1} = r (v_{i2} - v_{i1})$$

$$A_v = r = \frac{R_4}{R_1} = \frac{R_3}{R_2}$$

Input Resistance $R_{id} = R_1 + R_2$, When $v_{i2} = 0$, $R_{i1} = R_1$, When $v_{i1} = 0$, $R_{i2} = R_2 + R_3$.

2.4.2 Sum Circuit

An sum circuit adds the inverting input and the non-inverting input.



Similarly, we have

$$\begin{cases} \frac{v_{i1} - v_n}{R_1} + \frac{v_{i2} - v_n}{R_2} = \frac{v_n - v_o}{R_3} \\ v_n = v_p = 0 \end{cases} \Rightarrow \frac{v_{i1}}{R_1} + \frac{v_{i2}}{R_2} = \frac{-v_o}{R_3}$$

$$v_o = - \left(\frac{R_3}{R_1} v_{i1} + \frac{R_3}{R_2} v_{i2} \right)$$

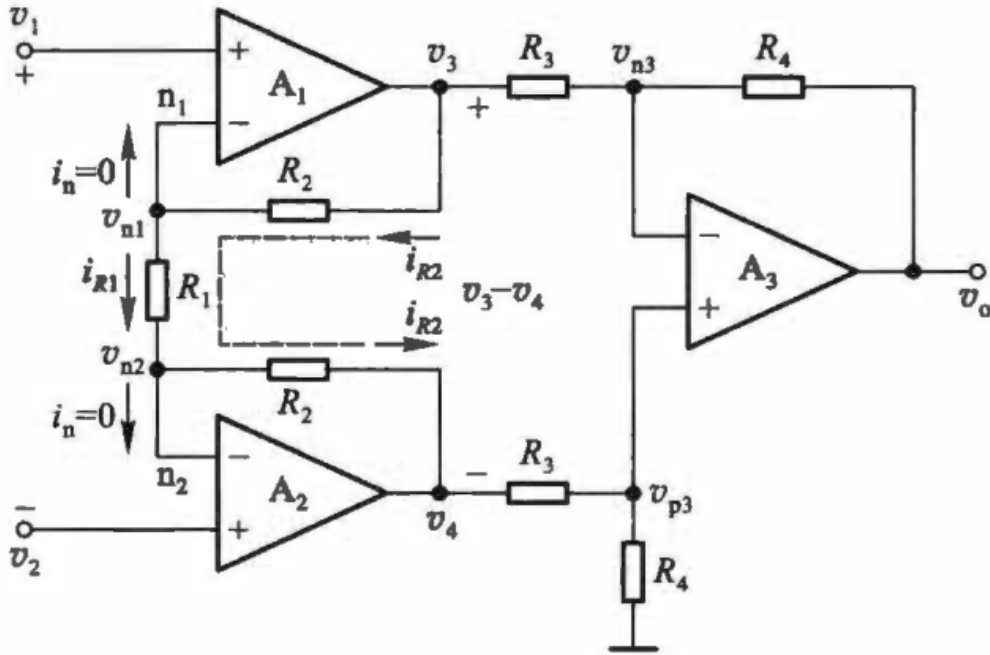
When we set

$$R_1 = R_2 = R_3$$

We have

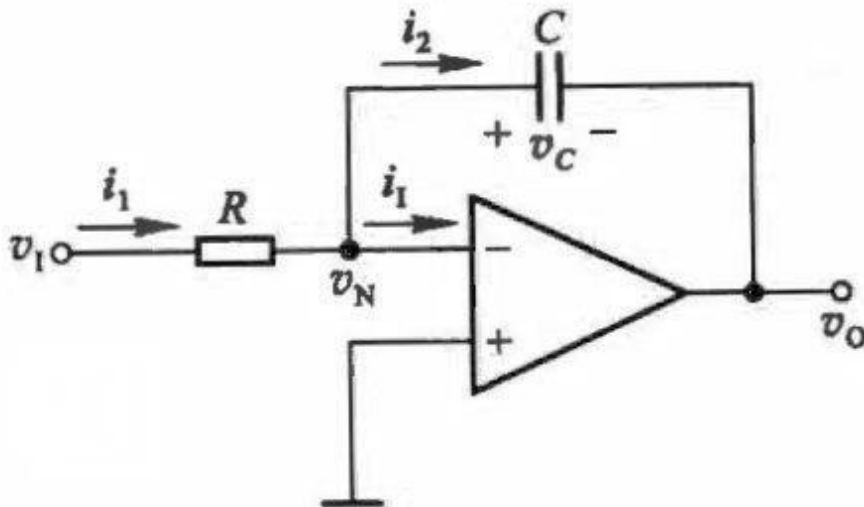
$$v_o = -(v_{i1} + v_{i2})$$

2.4.3 Instrumentation Amplifier



$$A_{vd} = -\frac{R_4}{R_3} \left(1 + \frac{2R_2}{R_1} \right) \quad v_o = A_{vd} (v_1 - v_2)$$

2.4.4 Integrating Circuit



Since

$$C = \frac{Q}{U}$$

\Rightarrow

$$U = \frac{Q}{C} = \frac{1}{C} \int I dt = \frac{1}{C} \int \frac{v_i}{R} dt = \frac{1}{RC} \int v_i dt$$

$$0 - v_o = U$$

\Rightarrow

$$v_o = -\frac{1}{RC} \int v_i dt$$

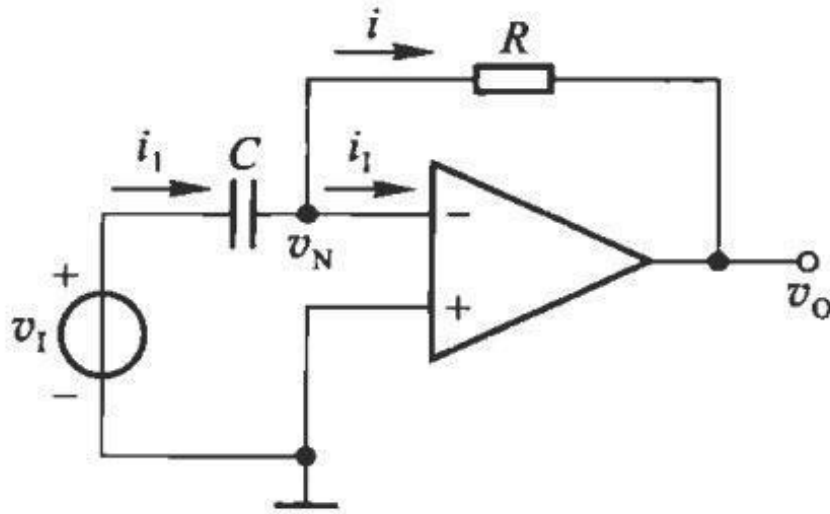
We define

$$\tau = RC$$

Then

$$-v_o = \frac{1}{\tau} \int v_i dt$$

2.4.5 Differential Circuit



$$\begin{cases} i_i = \frac{dQ}{dt} = C \frac{dv_i}{dt} \\ i = \frac{v_o}{R} \\ i_i = i \end{cases}$$

\Rightarrow

$$-v_o = RC \frac{dv_i}{dt} = \tau \frac{dv_i}{dt}$$

Chapter 3

Diodes

3.1 Semiconductors

3.1.1 Intrinsic Semiconductor

An intrinsic semiconductor, also called as undoped semiconductor, is a pure semiconductor without and significant dopant species present. Two factors are responsible to the current pass through it:

- Excited electrons
- Holes

However, we seldom use intrinsic semiconductors.

3.1.2 Extrinsic Semiconductor

An extrinsic semiconductor is a semiconductor that has been doped, which has more features and provides more charge carriers.

P-type semiconductor

P-type semiconductors are created by doping some electron acceptor elements during manufacture. It has more holes, holes are major carriers of the current.

N-type semiconductor

N-type semiconductors are created by doping some electron donor elements during manufacture. It has more electrons, electrons are major carriers of the current.

3.2 P-N Junction and Diode

When we combine the 2 types of extrinsic semiconductor together, we found some interesting features. As p-type semiconductors use holes to transmit currents, n-type semiconductors use electrons to transmit currents, and, to make life easier, we take holes as positive charges. When the two types of semiconductors are put together, at the contact surface, diffusion phenomenon occur.

Some holes traveled into the n-type semiconductor, some electrons traveled into the p-type semiconductor. And after that, an inner electric field formed, which hinders the p-n junction from carrying currents.

To ease the effect above, we need to add some positive voltage at p-type semiconductor, and also add some negative voltage at n-type semiconductor. And if we add negative voltage at n-type semiconductor, positive voltage at p-type semiconductor, the effect will be intensified.

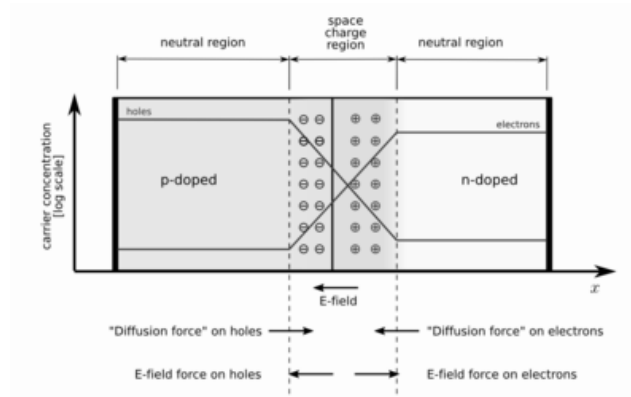


Figure 3.1: PN Junction at equilibrium state

In conclusion, if we add forward voltage (from p to n), the diode acts as a short circuit. If we add reversed voltage, the diode acts like an open circuit. And if the reversed voltage is big enough, it will cause the diode broken-through, and the current flow through it will increase tremendously.

3.2.1 Breakdown of P-N Junction

There are two types of breakdown

- electricity breakdown, which is invertible
- heat breakdown, which cause permanent damage

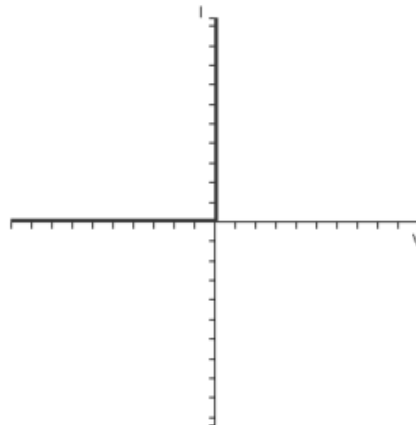
3.3 Diode modeling

3.3.1 Real Diode Modeling

$$i_d = I_S \left(e^{v_D / (nV_T)} - 1 \right)$$

3.3.2 Mathematically idealized diode

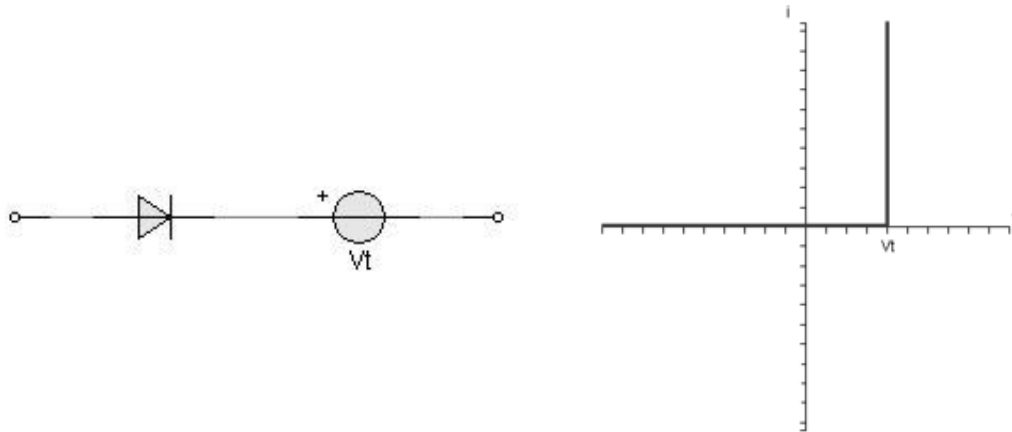
Firstly, consider a mathematically idealized diode. In such an ideal diode, if the diode is reverse biased, the current flowing through it is zero. This ideal diode starts conducting at 0 V and for any positive voltage an infinite current flows and the diode acts like a short circuit. The I-V characteristics of an ideal diode are shown below:



3.3.3 Ideal diode in series with voltage source

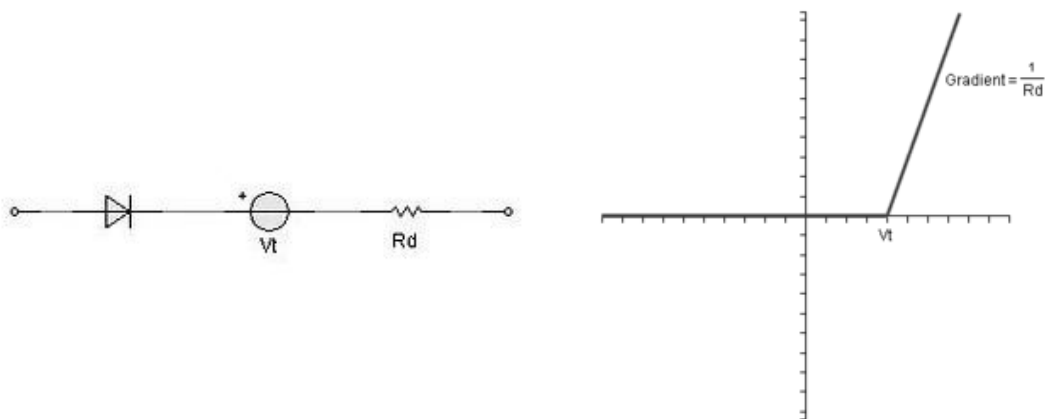
Now consider the case when we add a voltage source in series with the diode in the form shown below:

When forward biased, the ideal diode is simply a short circuit and when reverse biased, an open circuit.



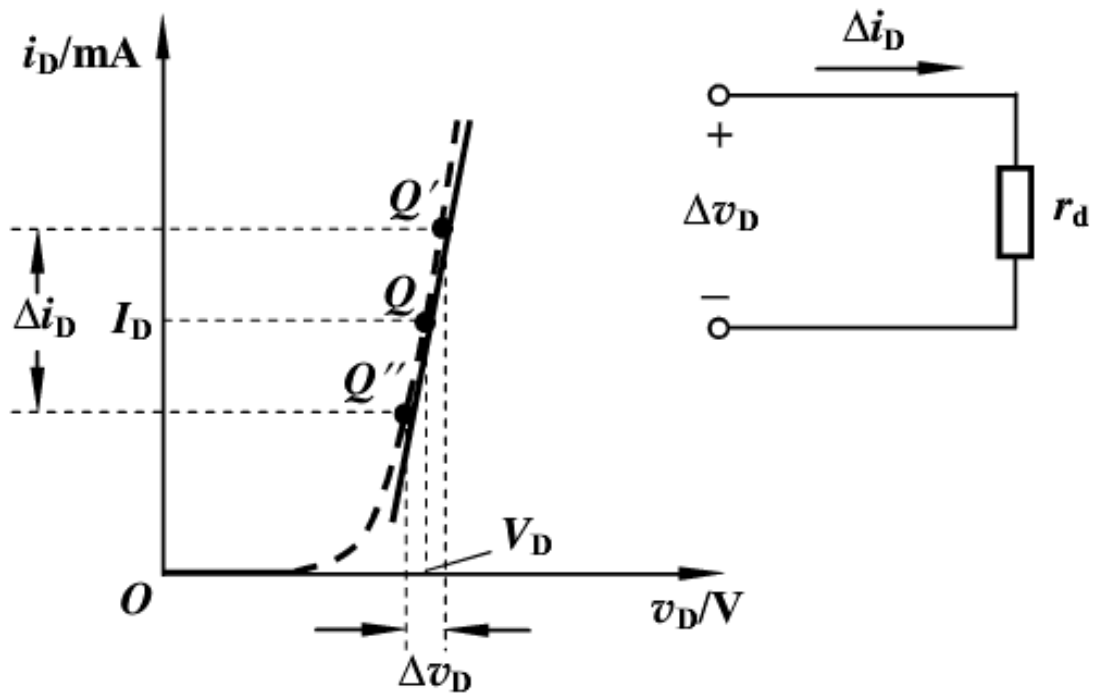
3.3.4 Diode with voltage source and current-limiting resistor

The last thing needed is a resistor to limit the current, as shown below:



The real diode now can be replaced with the combined ideal diode, voltage source and resistor and the circuit then is modelled using just linear elements. If the sloped-line segment is tangent to the real diode curve at the Q-point, this approximate circuit has the same small-signal circuit at the Q-point as the real diode.

3.3.5 Diode in Small Signal Circuits



$$r_d = \frac{1}{g_d} = \frac{V_T}{I_{DQ}}$$

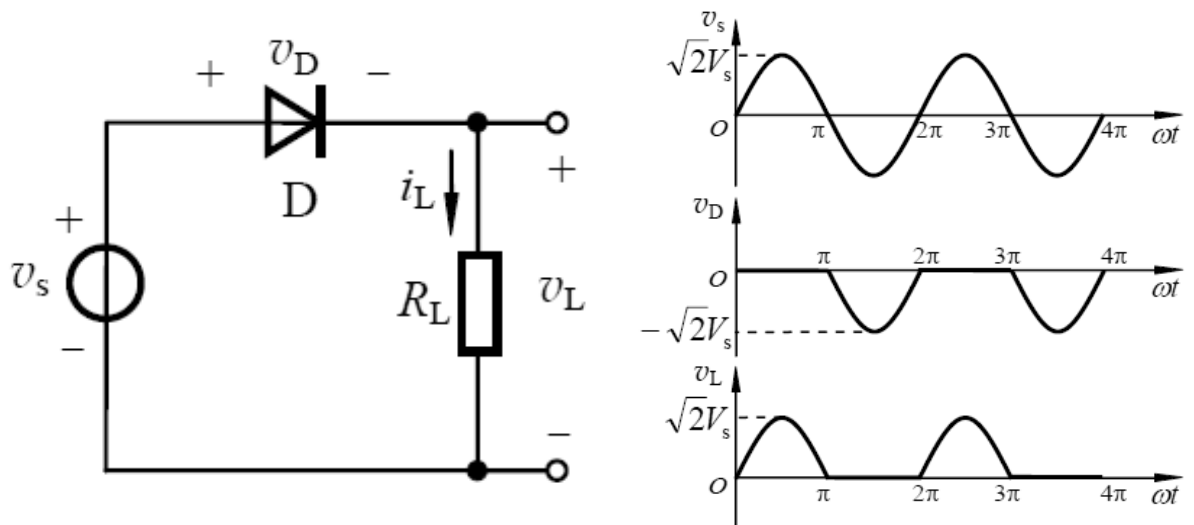
Where, in the condition of $T = 300$ K,

$$V_T = 26 \text{ mV}$$

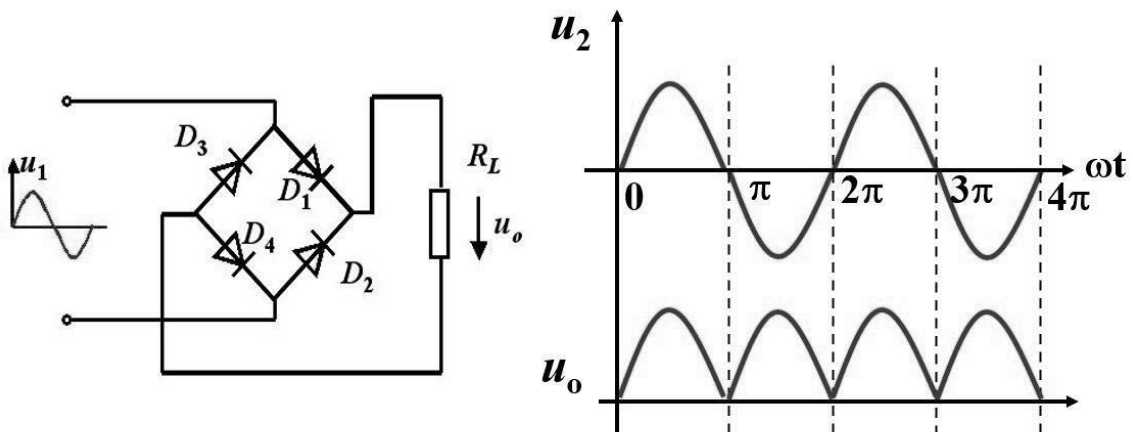
3.4 Applications of Diodes

3.4.1 Rectifier Circuit

The Half-wave Rectifier



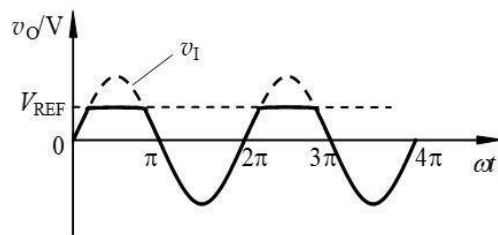
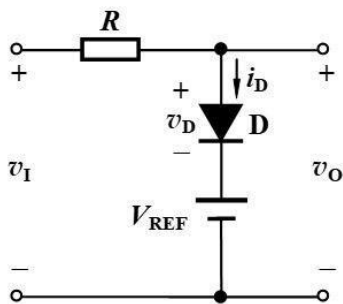
The Bridge Rectifier



$$V_L \approx 0.9V_S$$

$$I_{D1} = I_{D2} = I_{D3} = I_{D4} = \frac{0.45V_S}{R_L}$$

3.4.2 Limiting Circuit



3.4.3 Switching Circuit

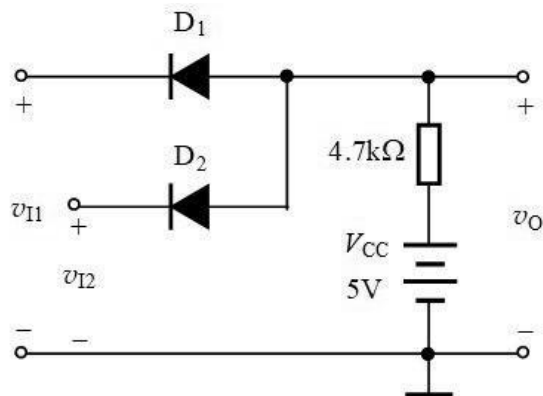
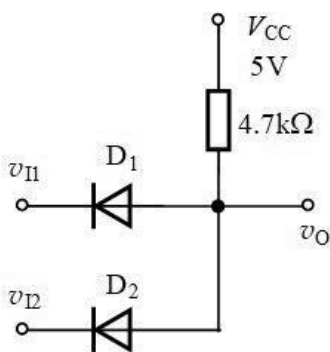
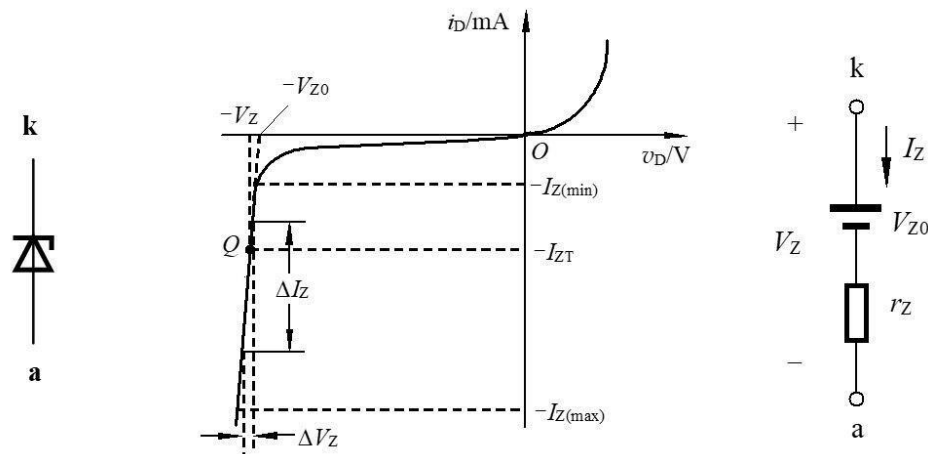


Figure 3.5: A Switching Circuit, $v_o = 5\text{ V}$ holds only if all the input voltage is 5 V

3.5 Diodes for Special Usage

3.5.1 Zener diode

A Zener diode is manufactured to be broken-through. It is used to stabilize voltages. As we can know from the I-V characteristic of an diode, when the diode is broken-through, change in current only cause little change in voltage.



3.5.2 Photodiode

A photodiode is a semiconductor device that converts light into an electrical current. The current is generated when photons are absorbed in the photodiode.

3.5.3 Light-emitting diode

A light-emitting diode (LED) is a semiconductor light source that emits light when current flows through it.

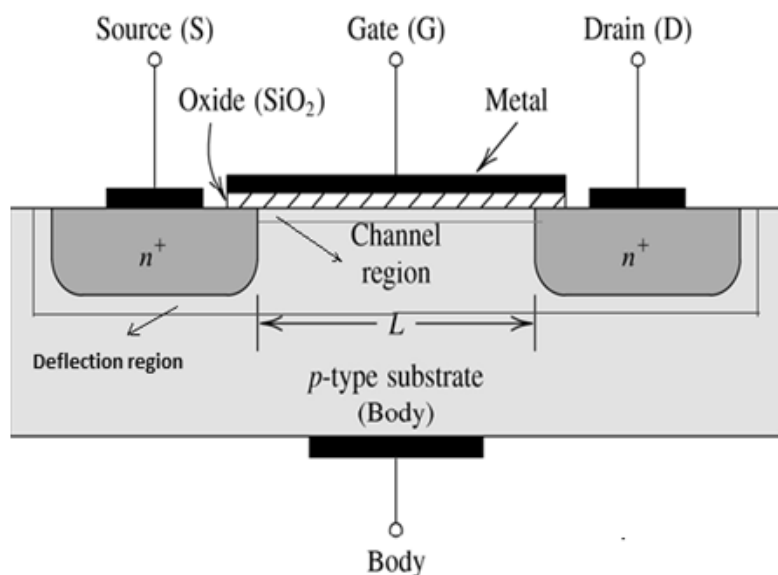
3.5.4 Schottky diode

The Schottky diode (named after the German physicist Walter H. Schottky), also known as Schottky barrier diode or hot-carrier diode, is a semiconductor diode formed by the junction of a semiconductor with a metal. It has a low forward voltage drop and a very fast switching action.

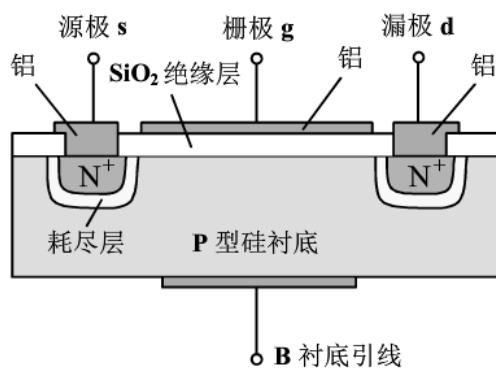
Chapter 4

MOSFET and Amplifying Circuit

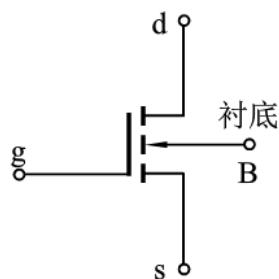
4.1 Classification of MOSFET



4.1.1 N-type Enhancement-mode MOSFET

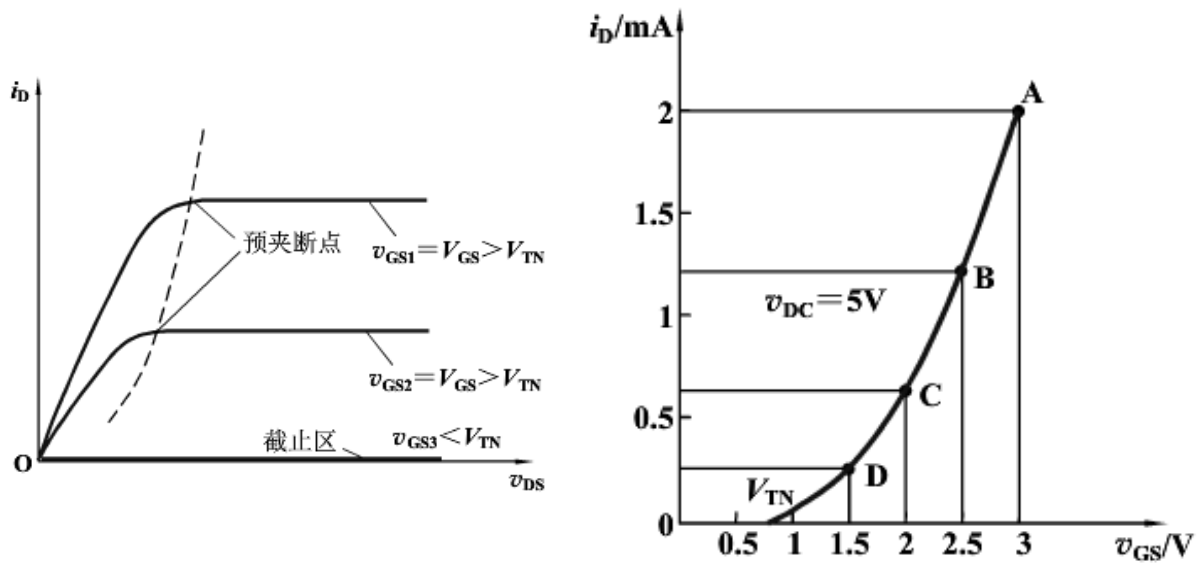
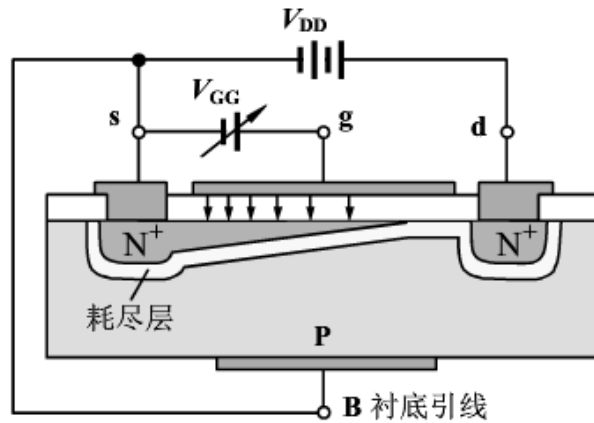


剖面图



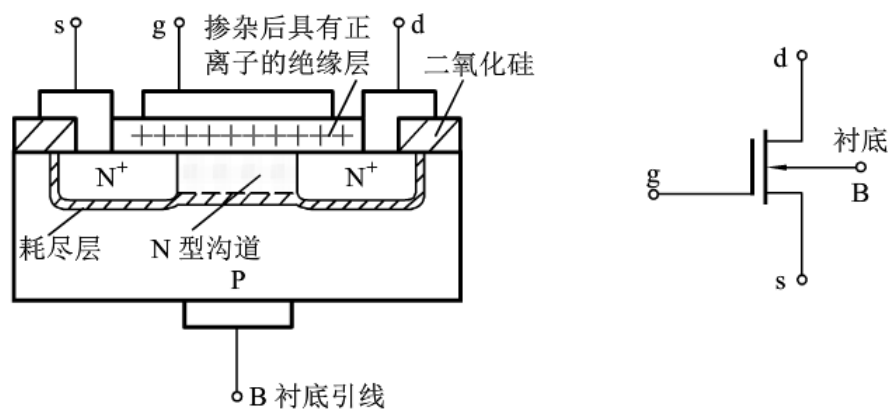
符号

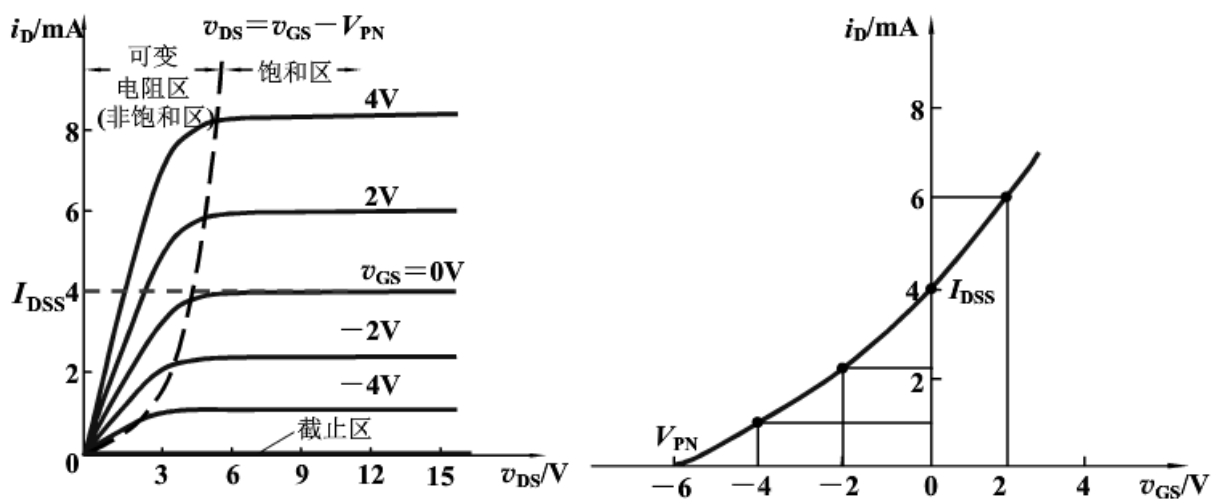
Only when $V_{GS} > V_{TN} > 0$, N-Channel will be formed, MOSFET is conductive. V_{TN} is called the Threshold Voltage.



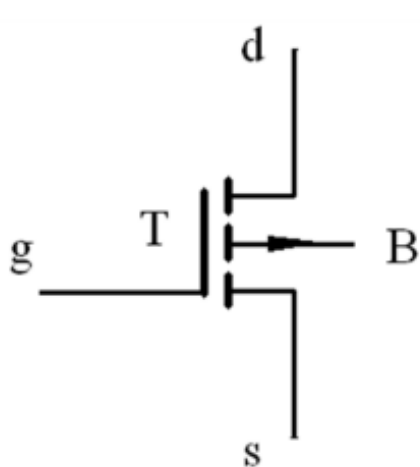
4.1.2 N-type Depletion-mode MOSFET

The only difference between Enhancement-mode and Depletion-mode is the charges in oxide, which made $V_{TN} < 0$

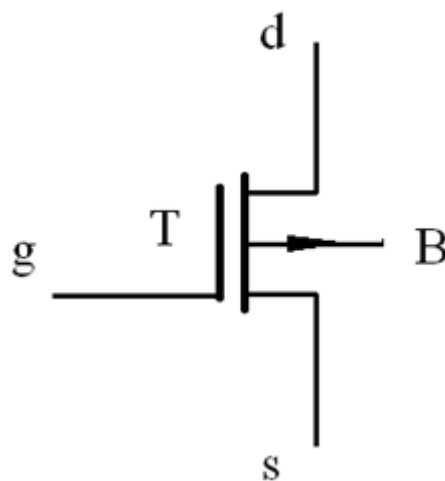




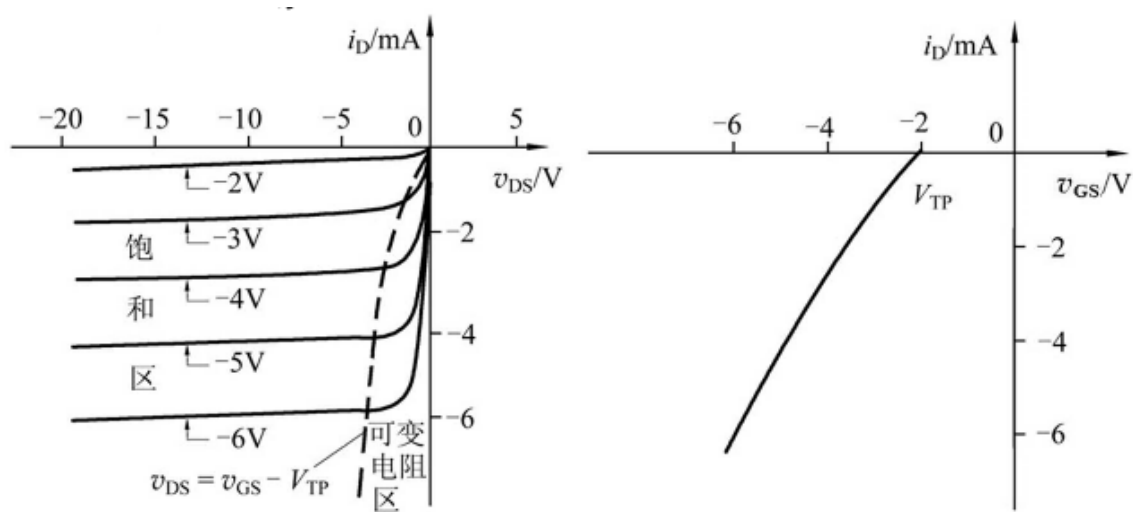
4.1.3 P-type MOSFET



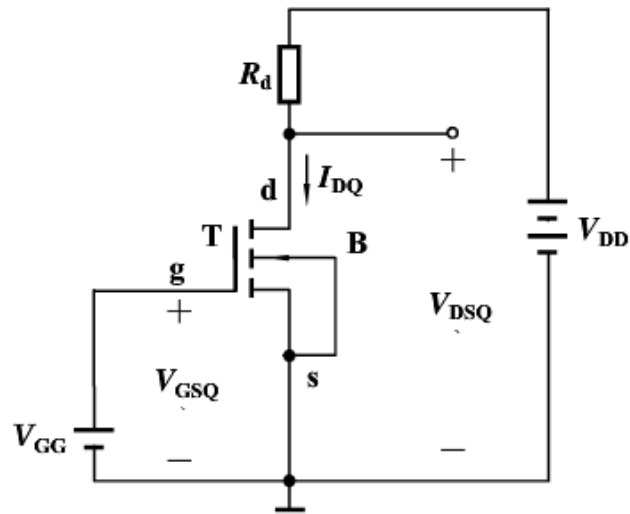
(a) Enhancement-mode



(b) Depletion-mode



4.2 Static Working Point



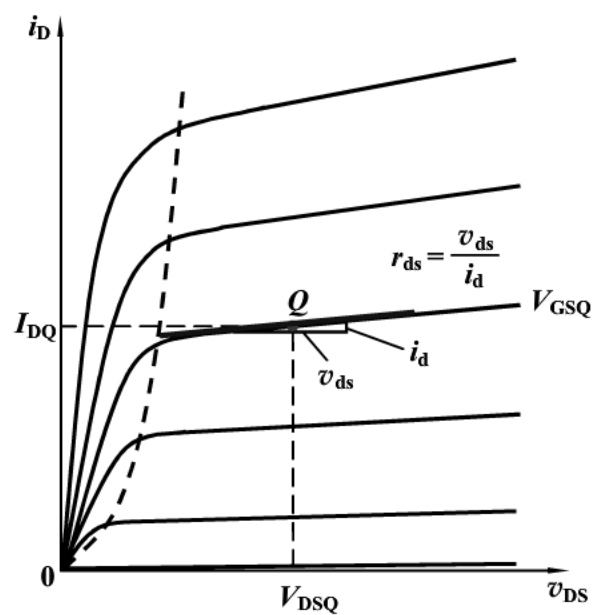
To calculate the DC bias point of a MOSFET

$$\begin{cases} V_{GSQ} = V_{GG} \\ I_{DQ} = K_n (V_{GSQ} - V_{TN})^2 \\ V_{DSQ} = V_{DD} - I_{DQ} R_d \end{cases}$$

Note that $V_{DSQ} > V_{GSQ} - V_{TN}$ must be verified to ensure that MOSFET is working in active mode. Then for small AC signal, the current at drain is

$$i_D = 2K_n (V_{GSQ} - V_{TN}) v_{GS} = g_m v_{GS}$$

4.3 Early Effect



$$i_D = K_n (v_{GS} - V_{TN})^2 (1 + \lambda v_{DS})$$

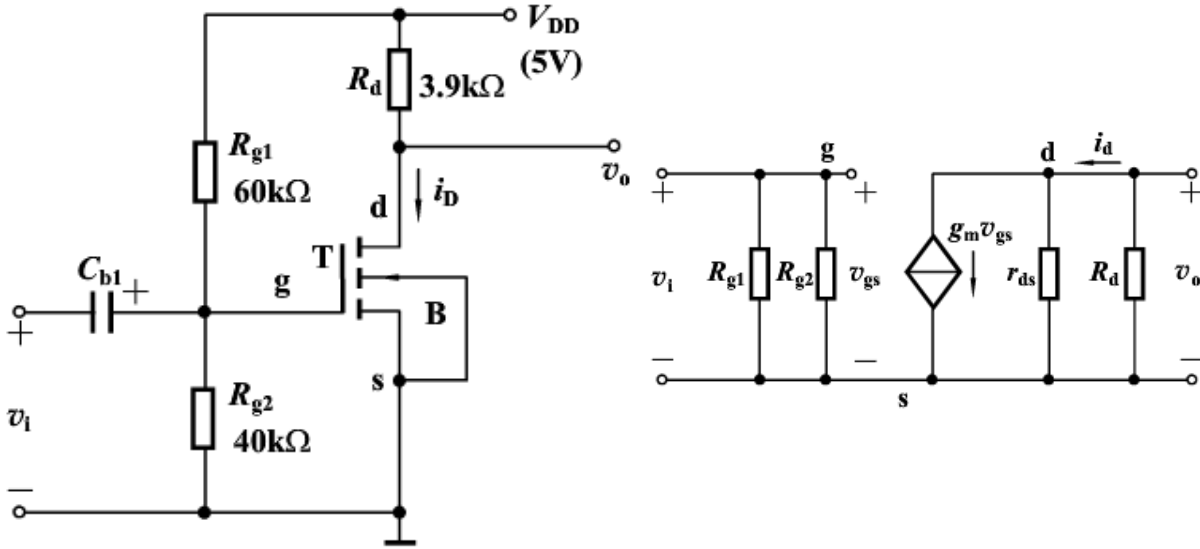
$$r_{ds} = \left. \frac{\partial v_{DS}}{\partial i_D} \right|_{V_{GSQ}} = \frac{1}{\lambda K_n (V_{GSQ} - V_{TN})^2} \approx \frac{1}{\lambda I_{DQ}} = \frac{V_A}{I_{DQ}}$$

Where V_A is called the Early Voltage

$$V_A = \frac{1}{\lambda}$$

4.4 Three types of Amplifier Circuit

4.4.1 Common Source Amplifier Circuit



DC bias point:

$$\begin{cases} V_{GSQ} = \left(\frac{R_{g2}}{R_{g1} + R_{g2}} \right) V_{DD} \\ I_{DQ} = K_n (V_{GSQ} - V_{TN})^2 \\ V_{DSQ} = V_{DD} - I_{DQ} R_d \end{cases}$$

Transconductance:

$$g_m = 2K_n (V_{GSQ} - V_{TN})$$

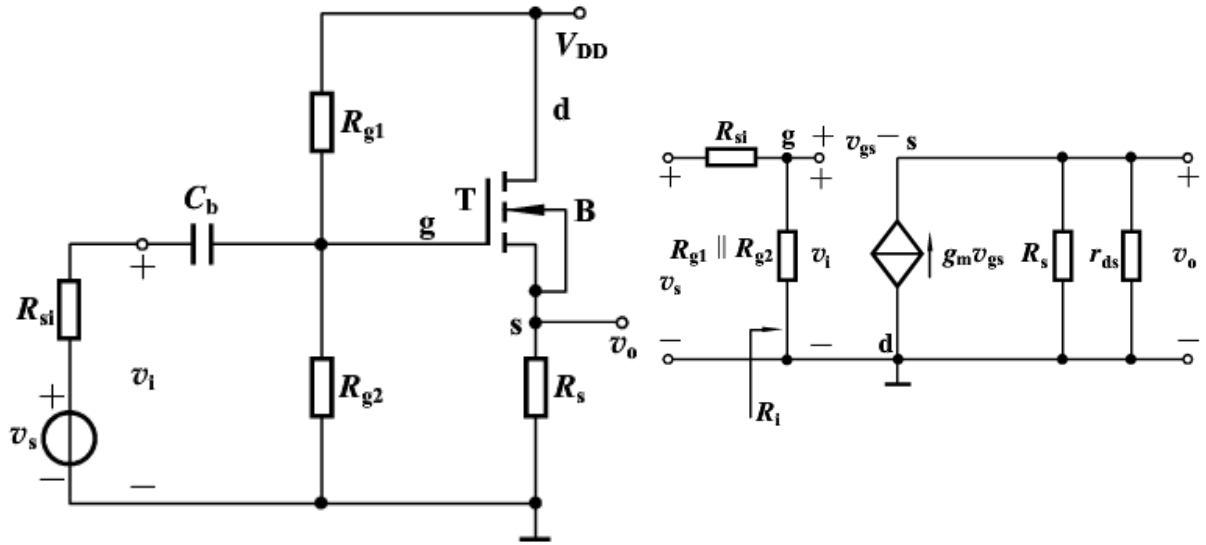
Gain:

$$A_v = -g_m (r_{ds} \parallel R_d) \quad A_{vs} = \frac{v_o}{v_s} = \frac{v_o}{v_i} \cdot \frac{v_i}{v_s} = \frac{v_i}{v_s} A_v$$

Resistance:

$$R_i = R_{g1} \parallel R_{g2} \quad R_o = r_{ds} \parallel R_d \approx R_d$$

4.4.2 Common Drain Amplifier Circuit



DC bias point:

$$\begin{cases} V_{GSQ} = \frac{R_{g2}}{R_{g1} + R_{g2}} \cdot V_{DD} - I_{DQ} R_s \\ I_{DQ} = K_n (V_{GSQ} - V_{TN})^2 \\ V_{DSQ} = V_{DD} - I_{DQ} R_s \end{cases}$$

Transconductance:

$$g_m = 2K_n (V_{GSQ} - V_{TN})$$

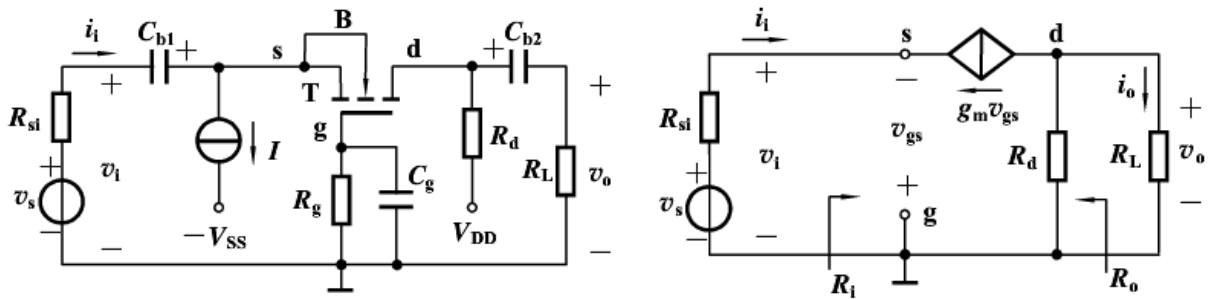
Gain:

$$A_v = \frac{R_s \parallel r_{ds} \parallel R_L}{\frac{1}{g_m} + R_s \parallel r_{ds} \parallel R_L} \approx 1 \quad A_{vs} = \frac{v_o}{v_s} = \frac{v_o}{v_i} \cdot \frac{v_i}{v_s} = \frac{v_i}{v_s} A_v$$

Resistance:

$$R_i = R_{g1} \parallel R_{g2} \quad R_o = R_s \parallel r_{ds} \parallel \frac{1}{g_m}$$

4.4.3 Common Gate Amplifier Circuit



DC bias point:

$$\begin{cases} I = I_{DQ} = K_n (V_{GSQ} - V_{TN})^2 \\ V_{DSQ} = V_{DD} - I_{DQ}R_d + V_{GSQ} \end{cases}$$

Transconductance:

$$g_m = 2K_n (V_{GSQ} - V_{TN})$$

Gain:

$$A_v = g_m (R_d \parallel R_L) \quad A_{vs} = \frac{g_m (R_d \parallel R_L)}{1 + g_m R_{si}} \quad A_{is} = \left(\frac{R_d}{R_d + R_L} \right) \left(\frac{g_m R_{si}}{1 + g_m R_{si}} \right)$$

Resistance:

$$R_i = \frac{1}{g_m} \quad R_o \approx R_d$$

4.5 Summary

4.5.1 Features of Three Types of MOSFET Amplifying Circuits

Type	A_v	A_i	R_i	R_o
Common Source	high, inverse	-	high	-
Common Drain	1	-	high	low
Common Gate	high, non-inverse	1	low	-

4.5.2 Small Signal Model of MOSFET

$$I_{DQ} = K_n (V_{GSQ} - V_{TN})^2 \quad g_m = 2K_n (V_{GSQ} - V_{TN}) \quad r_{ds} = \frac{1}{\lambda K_n (V_{GSQ} - V_{TN})^2}$$

4.5.3 Saturation Mode of MOSFET

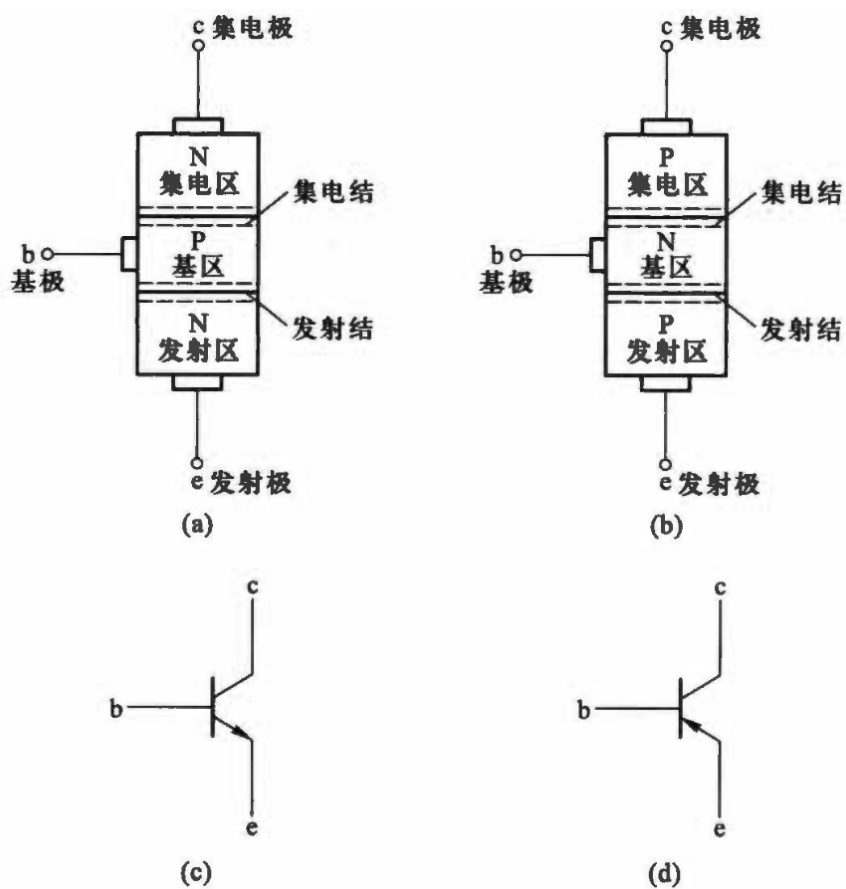
MOSFET Type	V_{GS}	V_{DS}
N-type enhancement	$V_{GS} > V_{TN}$	$V_{DS} > V_{GS} - V_{TN}$
N-type depletion	$V_{GS} > V_{PN}$	$V_{DS} > V_{GS} - V_{PN}$
P-type enhancement	$V_{GS} < V_{TP}$	$V_{DS} < V_{GS} - V_{TP}$
P-type depletion	$V_{GS} < V_{PP}$	$V_{DS} < V_{GS} - V_{PP}$

Chapter 5

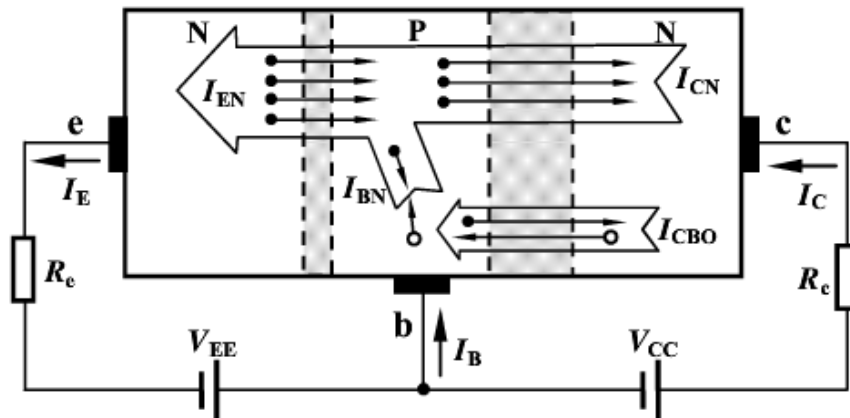
Bipolar Junction Transistor

5.1 Electronic Symbol

The arrow represents the direction of current.



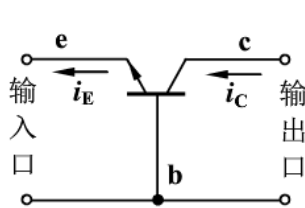
5.2 Control Principle



$$\alpha = \frac{I_c}{I_e} \quad \beta = \frac{I_c}{I_b} \quad \alpha = \frac{\beta}{1 + \beta} \quad I_e = (1 + \beta) I_b$$

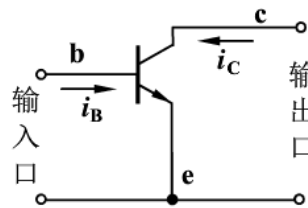
$$I_E = I_{ES} \exp(V_{BE}/V_T) \quad V_T = 26 \text{ mV}$$

5.3 Three Types of Amplifier Circuit



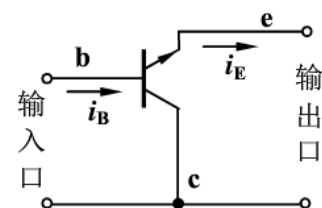
(a) 共基极

$$i_C = \alpha i_E$$



(b) 共发射极

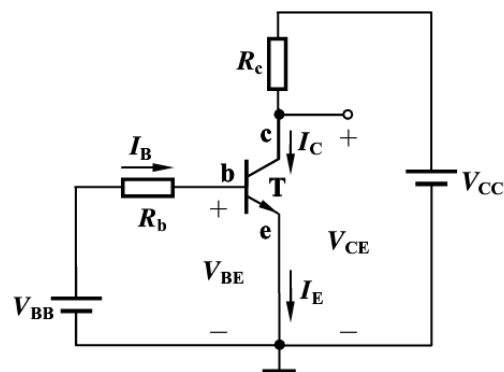
$$i_C = \beta i_B$$



(c) 共集电极

$$i_E = (1 + \beta) i_B$$

5.4 Static Working Point



$$I_{BQ} = \frac{V_{BB} - V_{BEQ}}{R_b}$$

$$V_{BEQ} = 0.7 \text{ V}$$

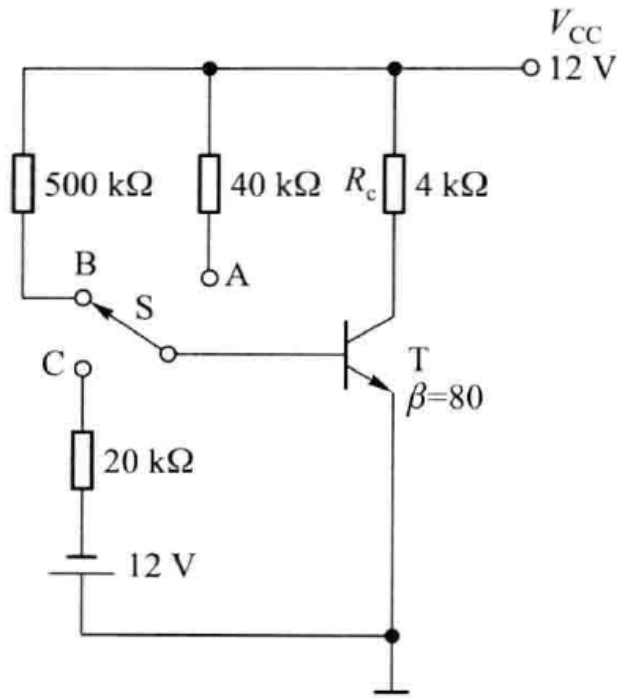
$$I_{CQ} = \beta I_{BQ}$$

$$V_{CEQ} = V_{CC} - I_{CQ} R_C$$

Note that the static working point is not associated with small signals discussed below.

5.5 Determine the working state of BJT

$\beta = 80$, $V_{BE} = 0.6 \text{ V}$ (Note that if the problem asks you to estimate, $V_{BE} = 0 \text{ V}$)



$S \rightarrow A$

$$I_B = \frac{(12 - 0.6 \text{ V})}{40 \text{ k}\Omega} = 0.3 \text{ mA} \quad I_{CS} = \frac{V_{CC}}{R_C} = 0.038 \text{ mA} \quad I_{BS} = \frac{I_{CS}}{\beta} = 3 \text{ mA}$$

Since

$$I_B > I_{BS}$$

BJT works in **saturation** mode.

$S \rightarrow B$

$$I_B = \frac{(12 - 0.6 \text{ V})}{500 \text{ k}\Omega} = 0.023 \text{ mA} \quad I_{CS} = \frac{V_{CC}}{R_C} = 0.038 \text{ mA} \quad I_{BS} = \frac{I_{CS}}{\beta} = 3 \text{ mA}$$

Since

$$I_B < I_{BS}$$

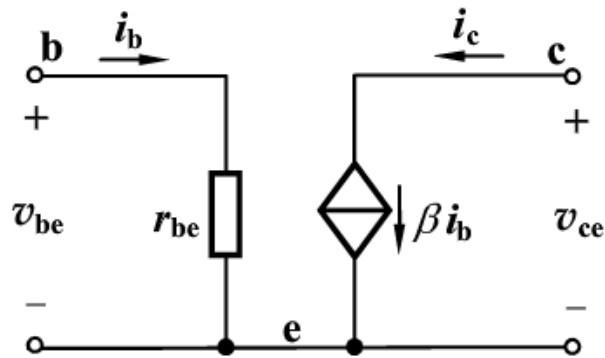
BJT works in **active** mode.

$S \rightarrow C$, since

$$V_B < V_E$$

The Emitter-Base Junction is reverse biased, BJT works in **cutoff** mode.

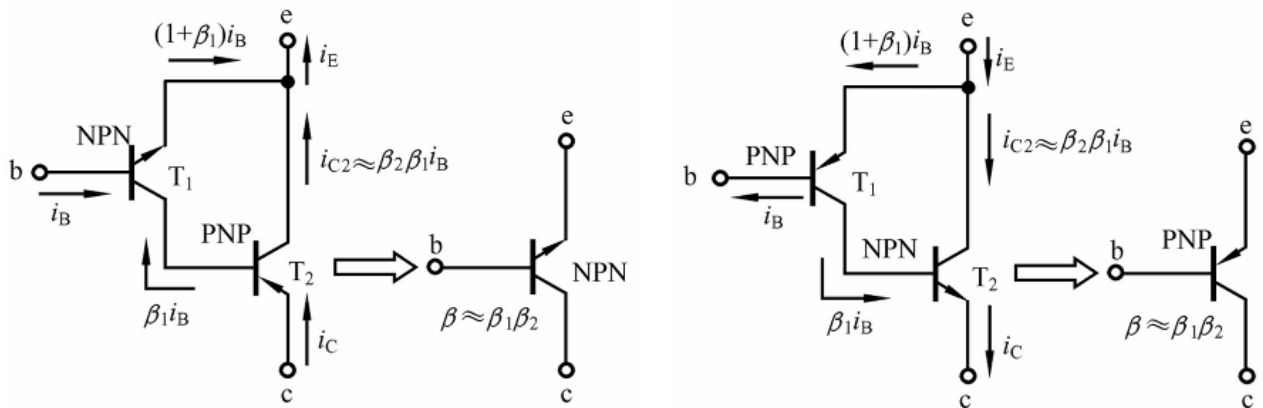
5.6 Model of Small Signal



When $T = 300$ K

$$r_{be} = 200 \, \Omega + (1 + \beta) \frac{26 \, \text{mV}}{I_{EQ} \, (\text{mA})}$$

5.7 Compound Transistor

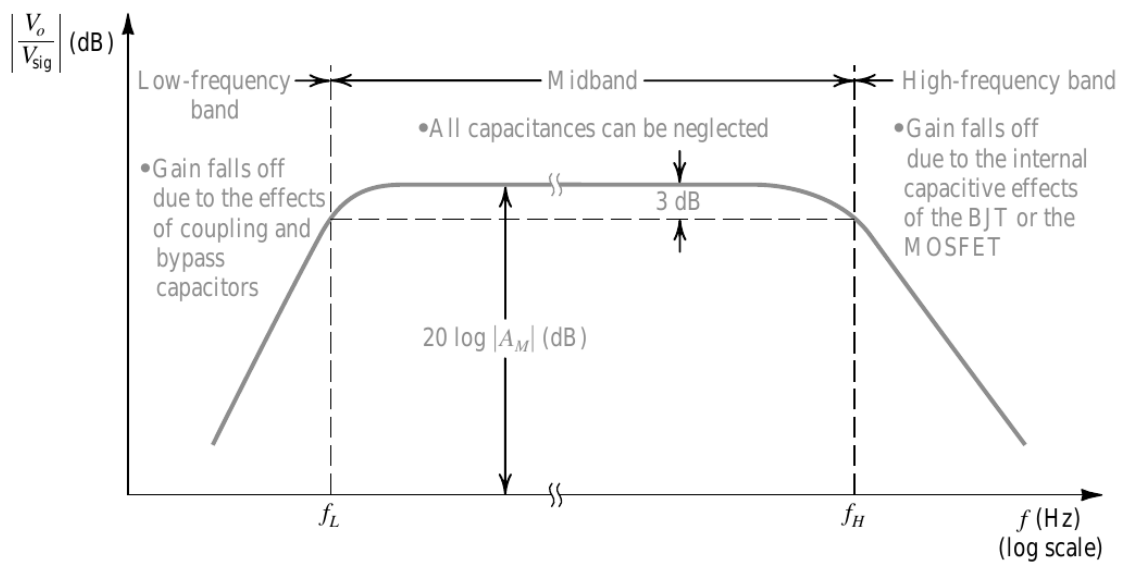


Noted that the emitter and base of compound transistor is exactly the same as the first transistor's.

Chapter 6

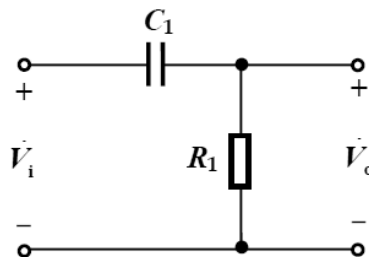
Frequency Response

6.1 Sketch of Gain vs Frequency of All Circuits



6.2 R-C Series Circuit

6.2.1 Low-Frequency Response of R-C High Pass Filter



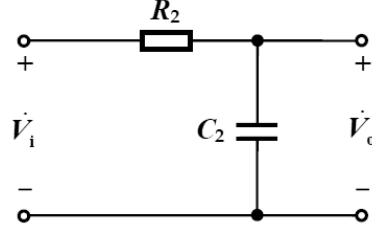
$$f_L = \frac{1}{2\pi R_1 C_1} \quad |A_{vL}| = \frac{1}{\sqrt{1 + (f_L/f)^2}} \quad \varphi_L = \arctan(f_L/f)$$

6.2.2 Mid-Frequency

In mid-frequency, capacitors are equal to open circuit while only resistors remain in the circuit. Where

$$A_{vM} = 1 \quad \varphi = 0$$

6.2.3 High-Frequency Response of R-C Low Pass Filter

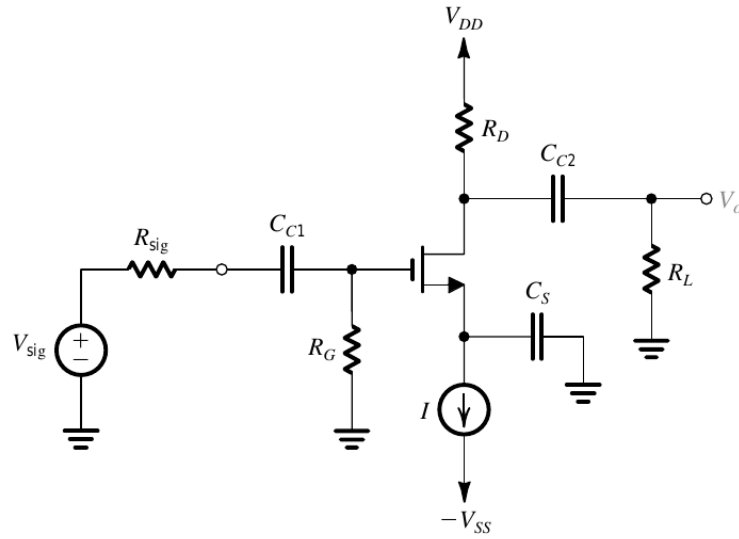


$$f_H = \frac{1}{2\pi R_1 C_1} \quad |A_{vH}| = \frac{1}{\sqrt{1 + (f_H/f)^2}} \quad \varphi_H = -\arctan(f_H/f)$$

6.3 Frequency Response of Amplifiers

6.3.1 Low-Frequency

Common-Source Amplifier



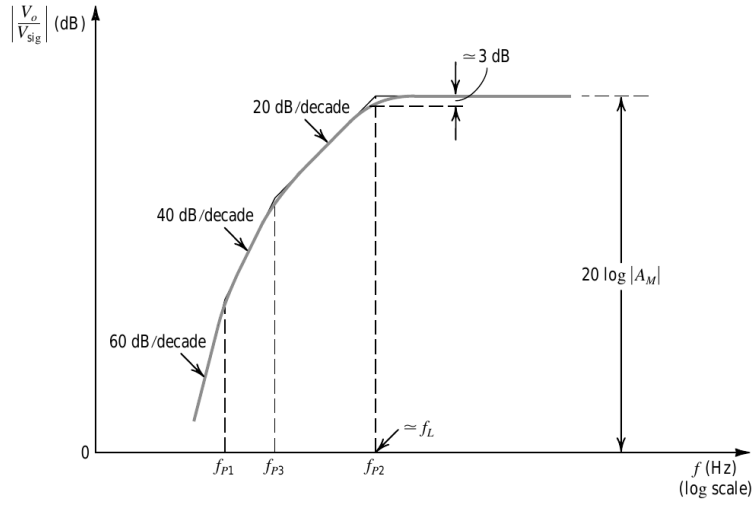
$$A_M = -\frac{R_G}{R_G + R_{sig}} [g_m (R_D \parallel R_L)]$$

$$\omega_{p1} = \frac{1}{C_{C1} (R_G + R_{sig})}$$

$$\omega_{p2} = \frac{g_m}{C_S}$$

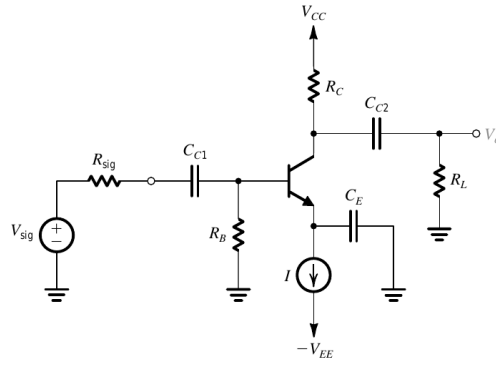
$$\omega_{p3} = \frac{1}{C_{C2} (R_D + R_L)}$$

$$\frac{V_o}{V_{sig}} = A_M \left(\frac{s}{s + \omega_{p1}} \right) \left(\frac{s}{s + \omega_{p2}} \right) \left(\frac{s}{s + \omega_{p3}} \right)$$



$$f_L \approx f_{p2} = \frac{\omega_{p2}}{2\pi} = \frac{1}{2\pi (C_S/g_m)}$$

Common-Emitter Amplifier

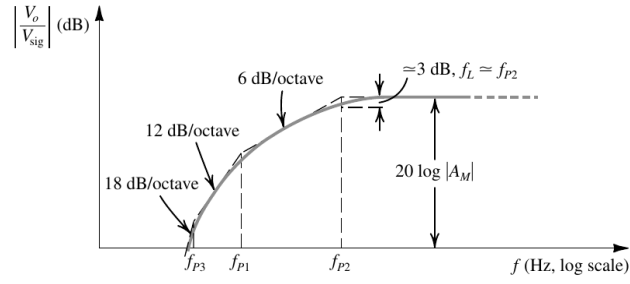


$$A_M = - \frac{(R_B \parallel r_\pi)}{(R_B \parallel r_\pi) R_{sig}} g_m (R_C \parallel R_L)$$

$$\omega_{p1} = \frac{1}{C_{C1} [(R_B \parallel r_\pi) + R_{sig}]}$$

$$\omega_{p2} = \frac{1}{C_E \left[r_e + \frac{R_B \parallel R_{sig}}{\beta + 1} \right]}$$

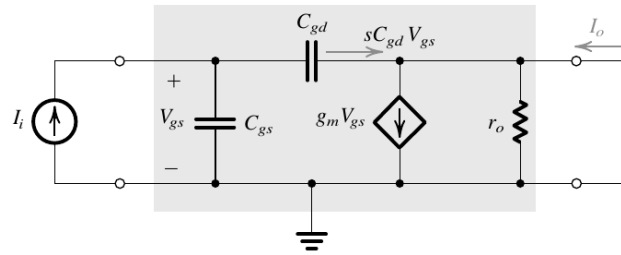
$$\omega_{p3} = \frac{1}{C_{C2} (R_C + R_L)}$$



$$f_L \approx f_{p2}$$

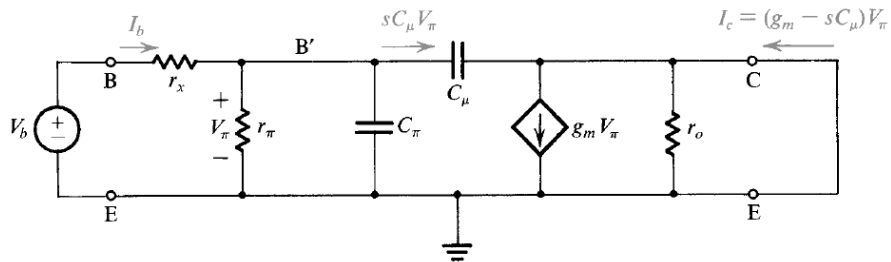
6.3.2 High-Frequency

Unity-Gain Frequency



MOSFET

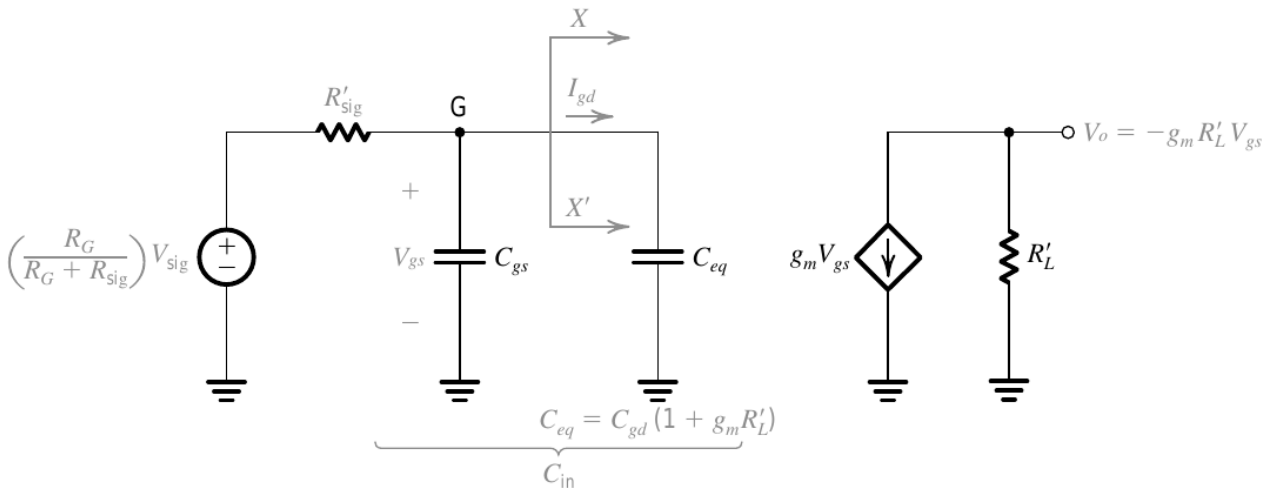
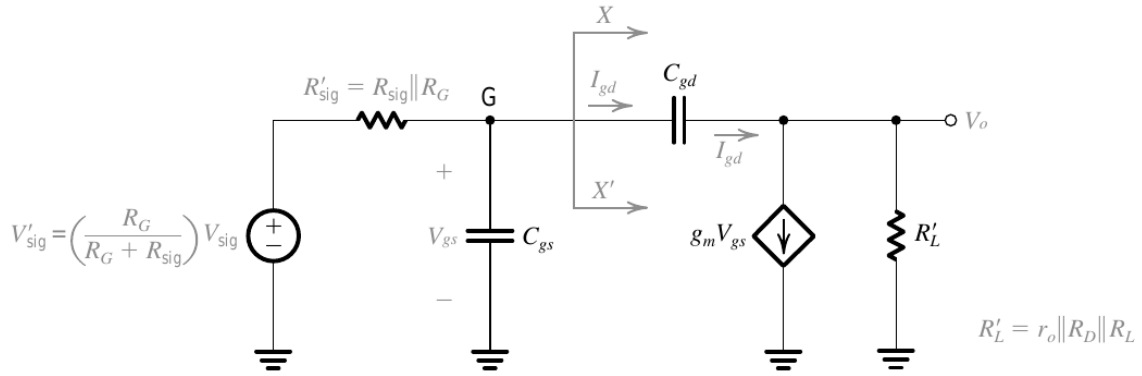
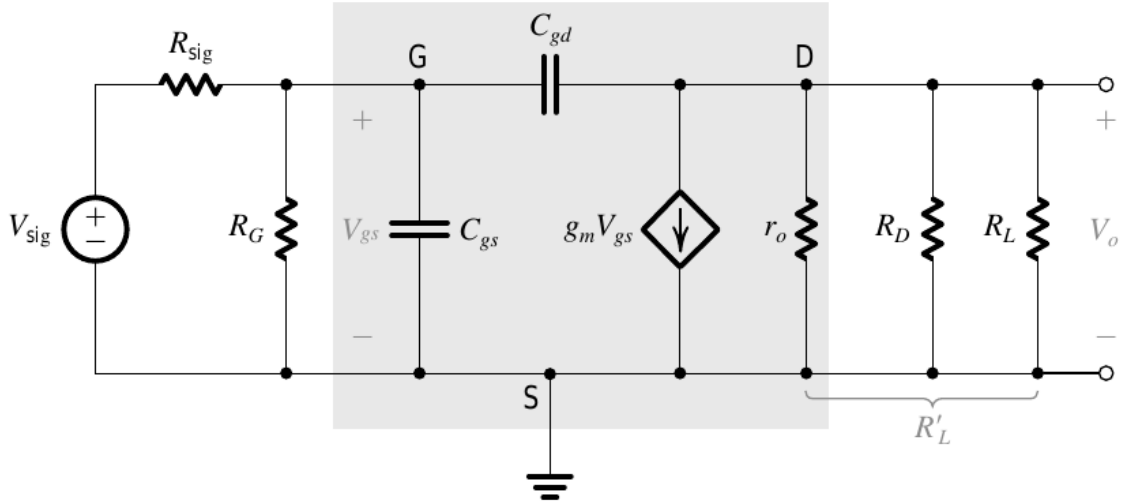
$$\frac{I_o}{I_i} = \frac{g_m}{s(C_{gs} + C_{gd})} \quad \omega_T = \frac{g_m}{(C_{gs} + C_{gd})} \quad f_T = \frac{g_m}{2\pi(C_{gs} + C_{gd})}$$



BJT

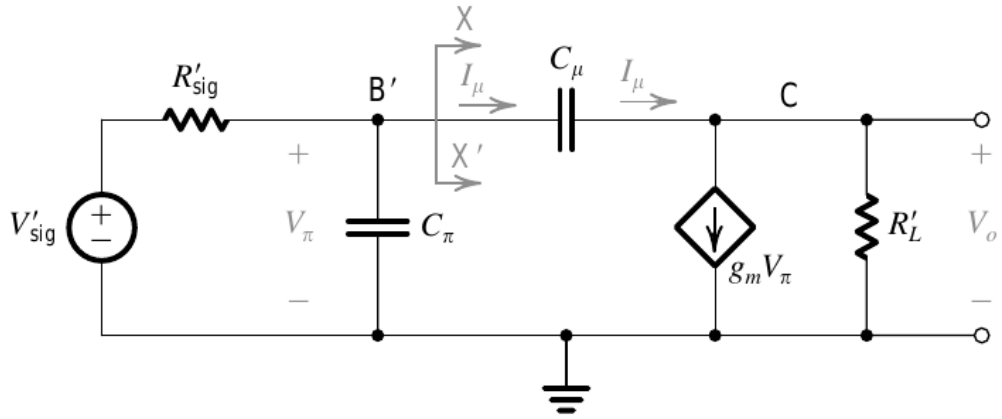
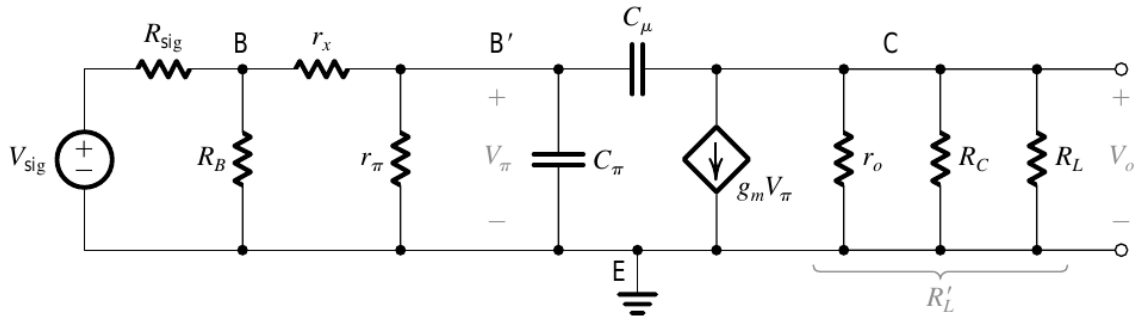
$$\frac{I_c}{I_b} = \frac{g_m r_\pi}{1 + s(C_\pi + C_\mu) r_\pi} = \frac{\beta_0}{1 + s(C_\pi + C_\mu) r_\pi} \quad \omega_\beta = \frac{1}{(C_\pi + C_\mu) r_\pi} \quad \omega_T = \beta_0 \omega_\beta = \frac{g_m}{C_\pi + C_\mu}$$

Common-Source Amplifier



$$\omega_H = \frac{1}{C_{in} R'_{sig}} \quad A_M = -\frac{R_G}{R_G + R_{sig}} g_m R'_L \quad f_H = \frac{\omega_H}{2\pi} = \frac{1}{2\pi C_{in} R'_{sig}}$$

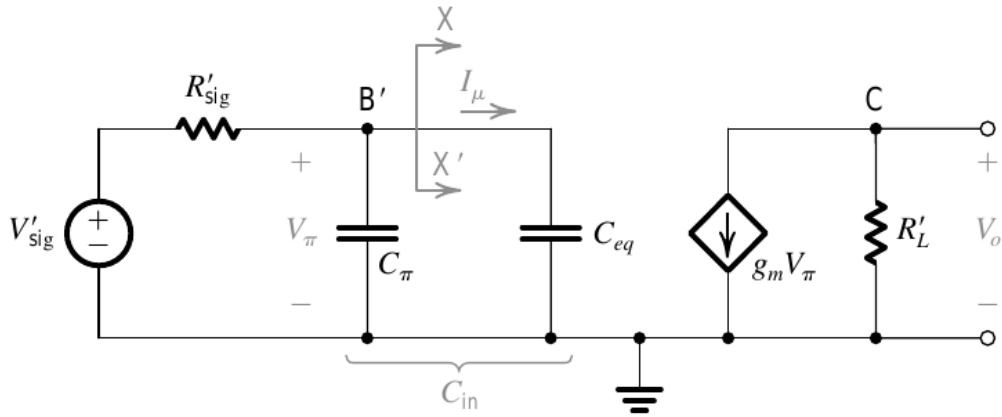
Common-Emitter Amplifier



$$V'_{\text{sig}} = V_{\text{sig}} \frac{R_B}{R_B + R_{\text{sig}}} \frac{r_{\pi}}{r_{\pi} + r_x + (R_{\text{sig}} \parallel R_B)}$$

$$R'_L = r_o \parallel R_C \parallel R_L$$

$$R'_{\text{sig}} = r_{\pi} \parallel [r_x + (R_B \parallel R_{\text{sig}})]$$



$$C_{\text{in}} = C_{\pi} + C_{eq} \\ = C_{\pi} + C_{\mu}(1 + g_m R'_L)$$

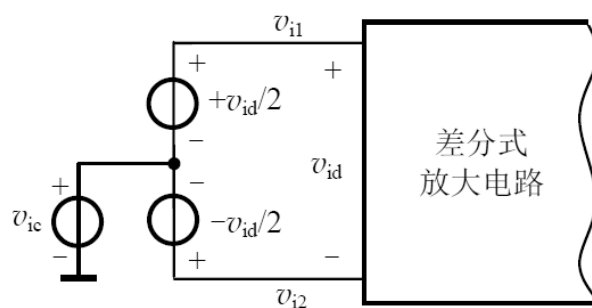
$$V_o = -g_m R'_L V_{\pi}$$

$$A_M = -\frac{R_B}{R_B + R_{\text{sig}}} \frac{r_{\pi}}{r_{\pi} + r_x + (R_{\text{sig}} \parallel R_B)} (g_m R'_L) \quad f_H = \frac{\omega_H}{2\pi} = \frac{1}{2\pi C_{\text{in}} R'_{\text{sig}}}$$

Chapter 7

Analogue Integrated Circuits

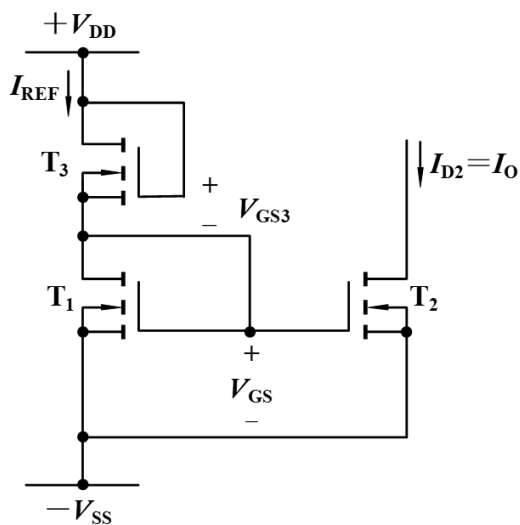
7.1 Differential Amplifier Circuit



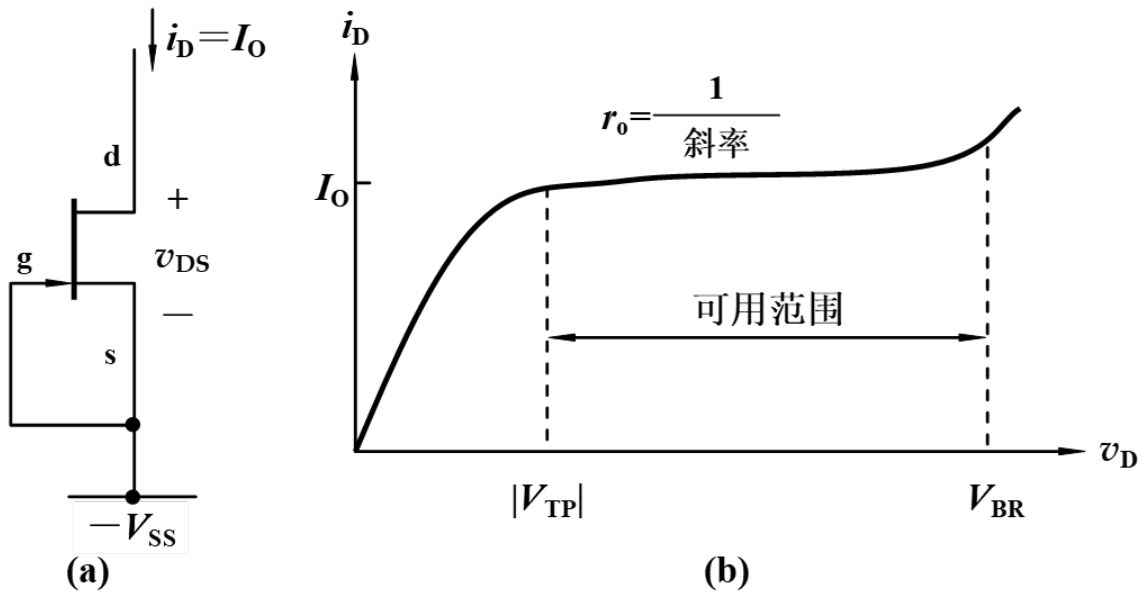
$$v_{i1} = v_{ic} + \frac{v_{id}}{2} \quad v_{i2} = v_{ic} - \frac{v_{id}}{2}$$

7.2 MOSFET Current Source

7.2.1 MOSFET Current Mirror



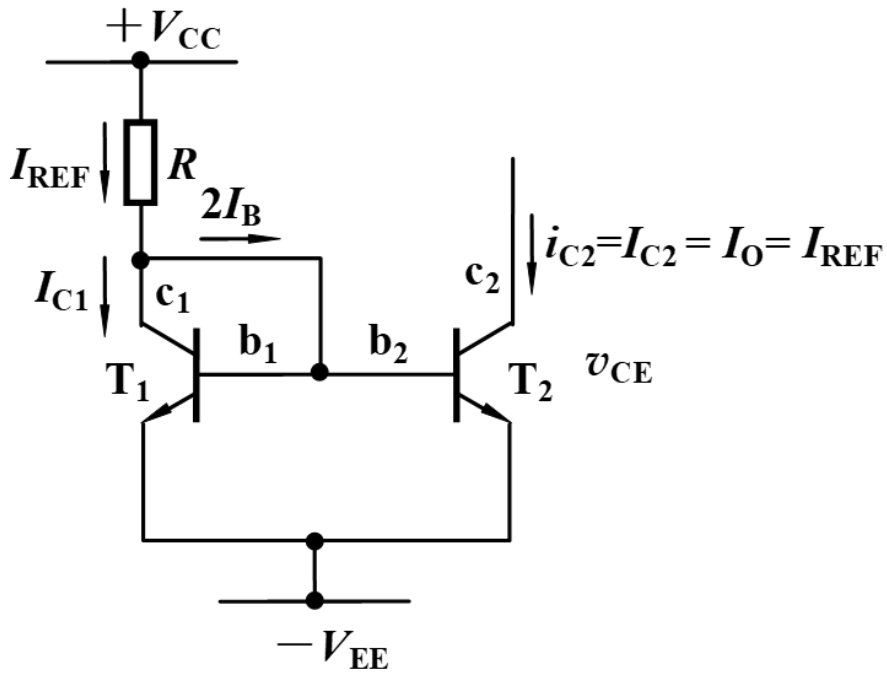
7.2.4 JFET Current Mirror



$$i_D = I_o = I_{DSS} (1 + \lambda v_{DS}) \quad r_o = \frac{1}{\lambda I_{DSS}}$$

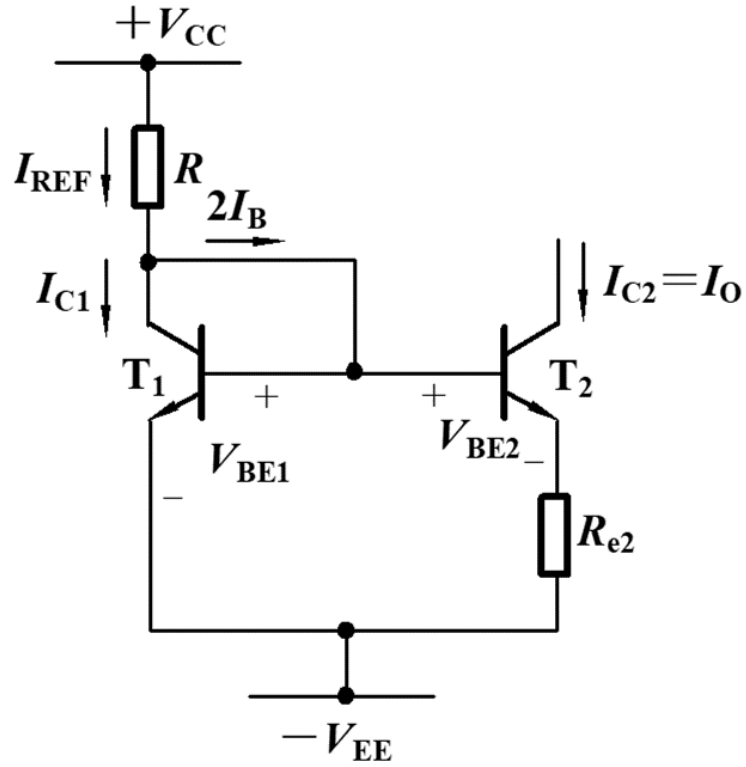
7.3 BJT Current Source

7.3.1 BJT Current Mirror



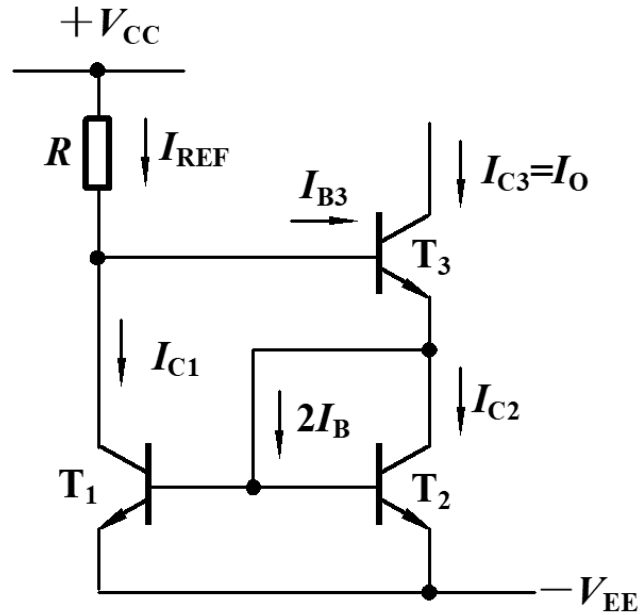
$$I_{C2} = I_{C1} \approx I_{REF} \approx \frac{V_{CC}}{R} \quad r_o = r_{ce}$$

7.3.2 Micro Current Source



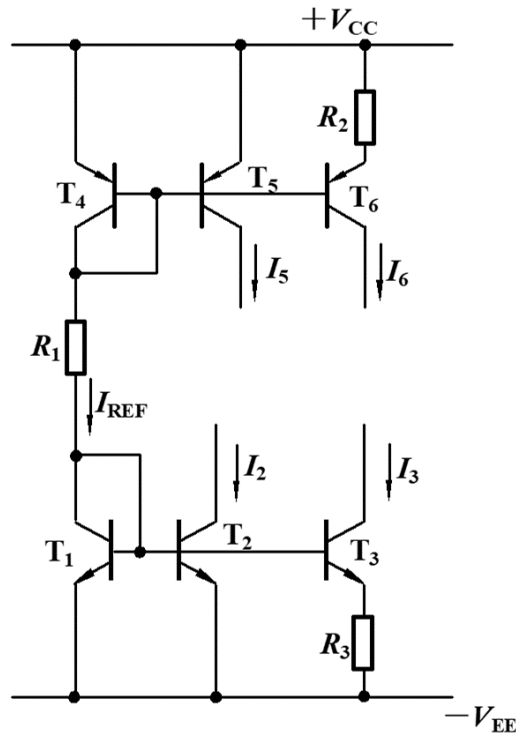
$$I_o = \frac{\Delta V_{BE}}{R_{e2}} \quad r_o \approx r_{ce2} + \left(1 + \frac{\beta R_{e2}}{r_{be2} + R_{e2}}\right)$$

7.3.3 Current Source with High Output Resistance



$$I_{REF} = \frac{V_{CC} - V_{BE3} - V_{BE2} + V_{EE}}{R} \quad I_o \approx I_{C2} = \frac{A_3}{A_1} \cdot I_{REF}$$

7.3.4 Combined Current Source

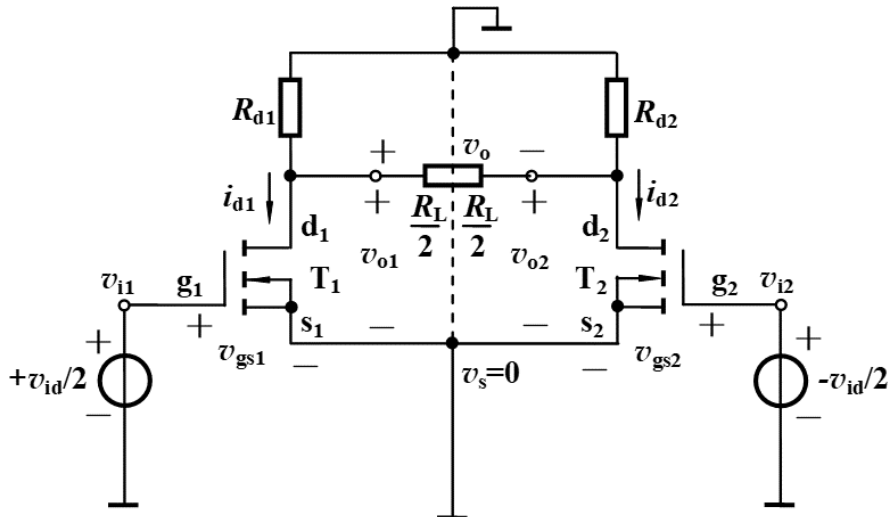


$$I_{REF} = \frac{V_{CC} + V_{EE} - V_{BE1} + V_{EB4}}{R_1}$$

7.4 Differential Amplifier

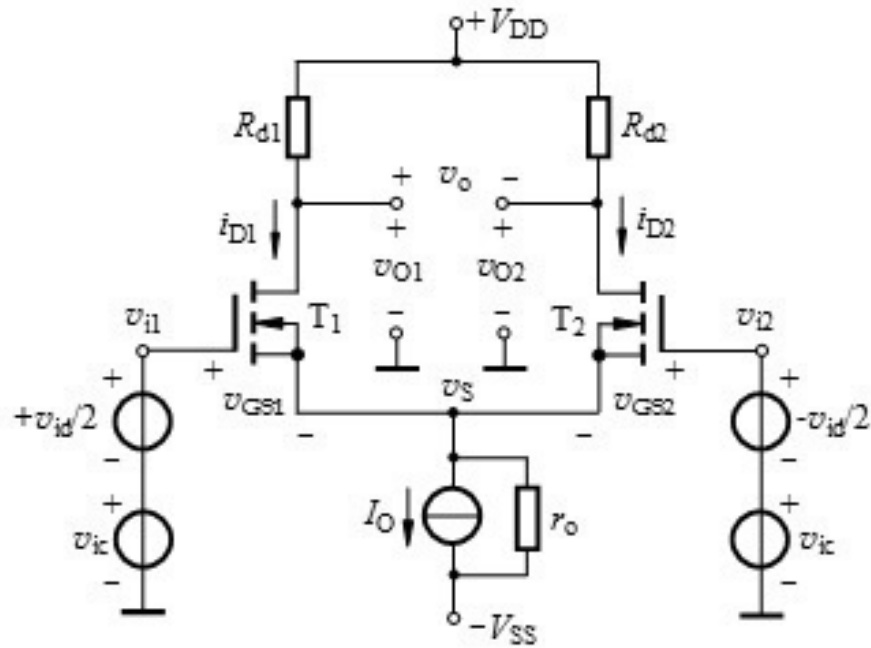
7.4.1 MOSFET

Two Output Terminals



$$i_{d1} = i_{d2} = I_D = \frac{1}{2}I_o \quad g_m = \sqrt{2K_n I_o} \quad A_{vd} = -g_m \left(r_{ds} \parallel R_d \parallel \frac{R_L}{2} \right) \quad K_{CMR} = \infty \quad R_o = 2R_d$$

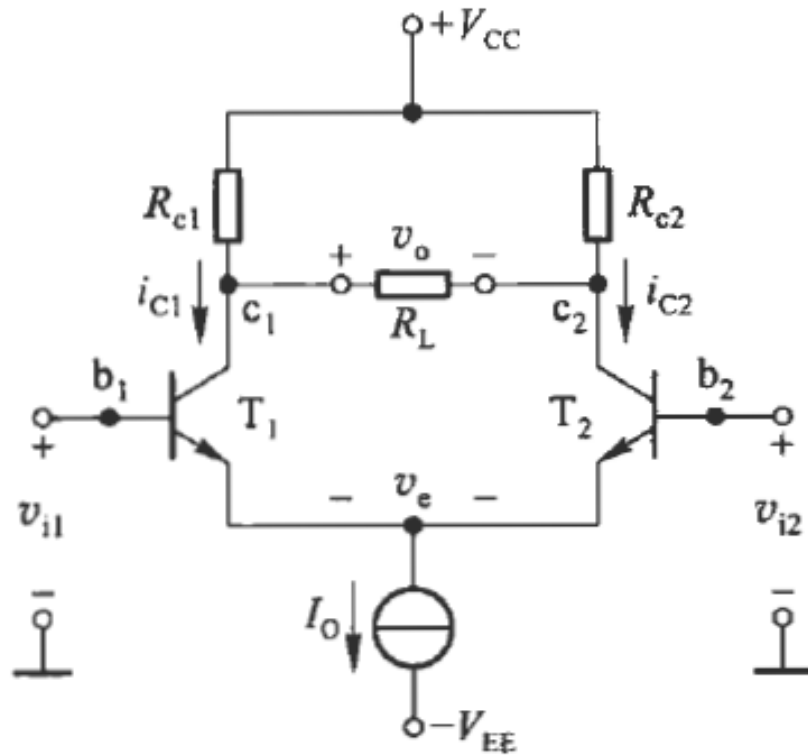
One Output Terminal



$$g_m = \sqrt{2K_n I_o} \quad A_{vd1} = -A_{vd2} = -\frac{g_m (r_{ds} \parallel R_d \parallel R_L)}{2} \quad K_{CMR} \approx g_m r_o \quad R_o = R_d$$

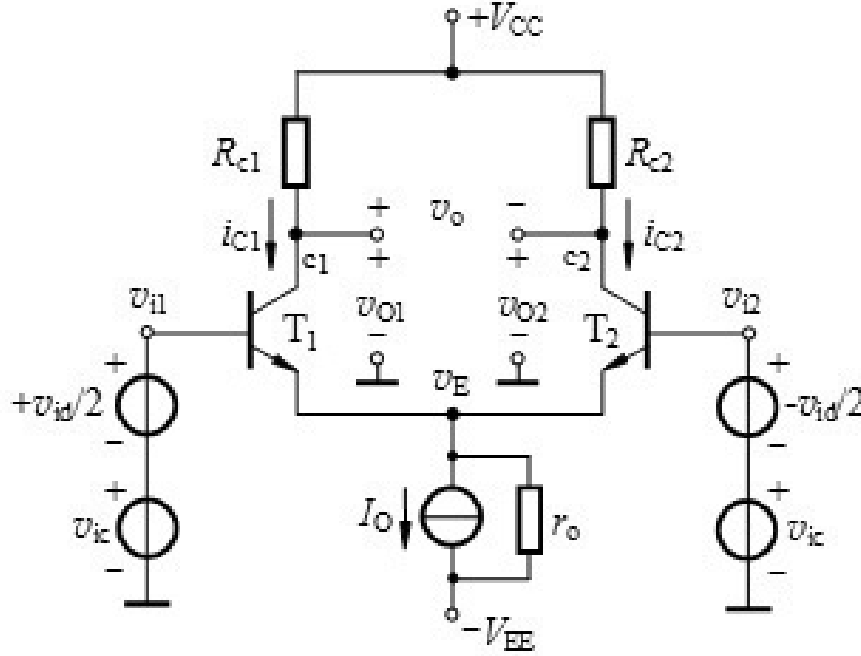
7.4.2 BJT

Two Output Terminals



$$A_{vd} = -\frac{\beta \left(R_c \parallel \frac{R_L}{2} \right)}{r_{be}} \quad K_{CMR} = \infty \quad R_{id} = 2r_{be} \quad R_{ic} = \frac{1}{2} [r_{be} + (1 + \beta) 2r_o] \quad R_o = 2R_c$$

One Output Terminal

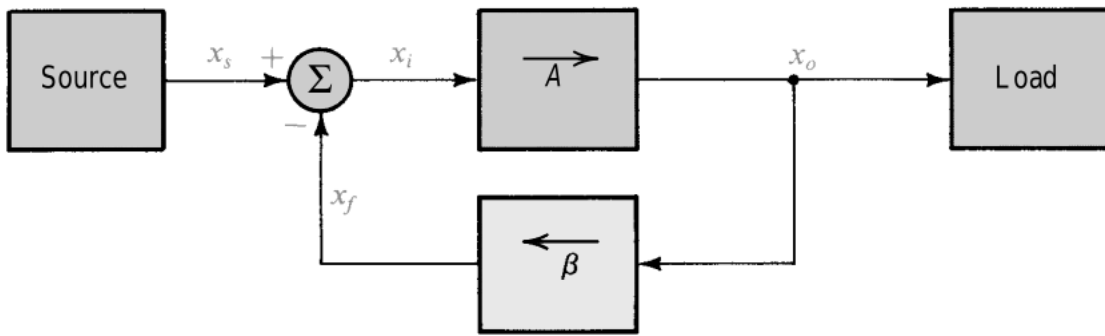


$$A_{vd1} = -A_{vd2} = -\frac{\beta (R_c \parallel R_L)}{2r_{be}} \quad K_{CMR} \approx \frac{\beta r_o}{r_{be}} \quad R_{id} = 2r_{be} \quad R_{ic} = \frac{1}{2} [r_{be} + (1 + \beta) 2r_o] \quad R_o = R_c$$

Chapter 8

Feedback

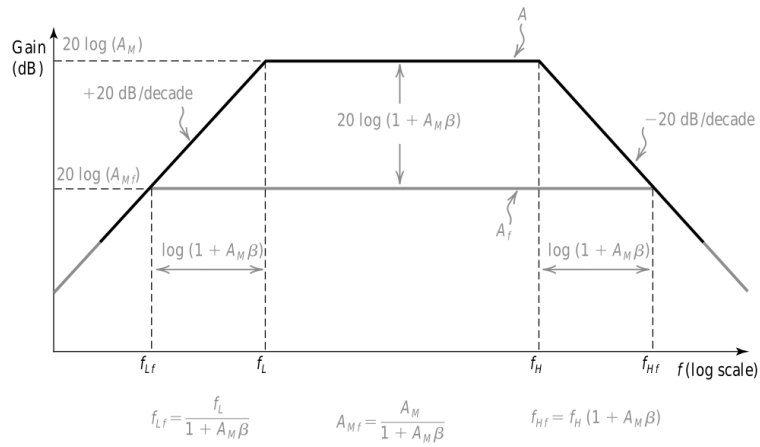
8.1 Basic Feedback Structure



$$x_o = Ax_i \quad x_f = \beta x_o \quad x_i = x_s - x_f$$

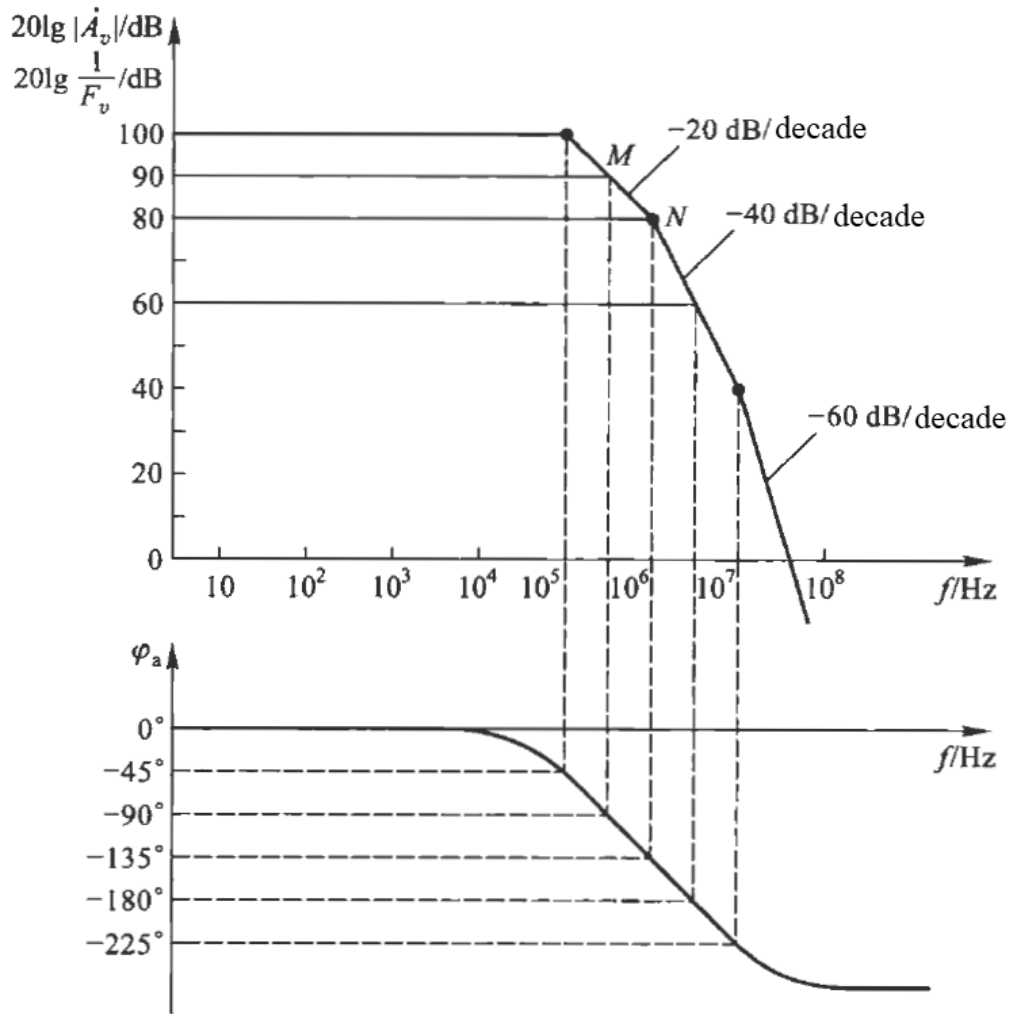
$$A_f = \frac{x_o}{x_s} = \frac{Ax_i}{x_i + \beta Ax_i} = \frac{A}{1 + A\beta} \approx \frac{1}{\beta} \quad (A\beta \gg 1)$$

8.2 Bandwidth and Gain



$$\omega_{Hf} = \omega_H \cdot (1 + A_M\beta) \quad \omega_{Lf} = \omega_L / (1 + A_M\beta)$$

8.3 Stability Problem of Feedback



$$\varphi_a = -135^\circ \quad AF < 1$$

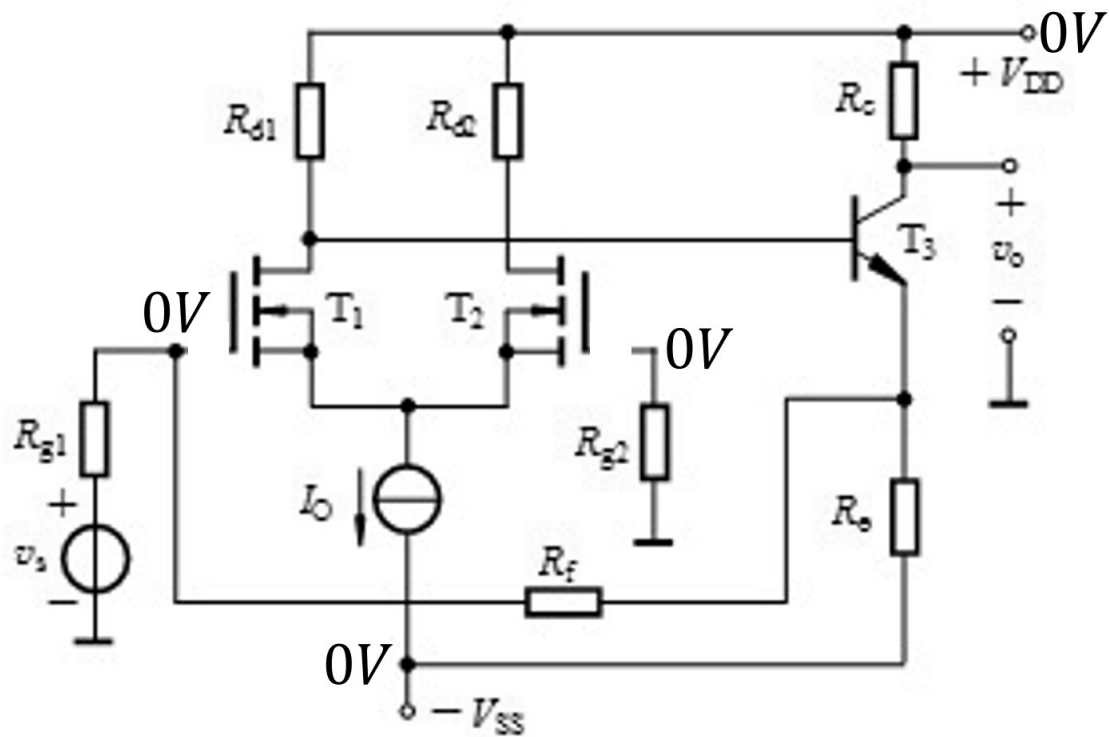
8.4 Four Basic Feedback Topologies

Feedback Type	Usage	Gain	Input Resistance	Output Resistance
Series-Shunt	Voltage \rightarrow Voltage	$A_f = \frac{A}{1 + A\beta}$	$R_{if} = (1 + A\beta) R_i$	$R_{of} = \frac{R_o}{1 + A\beta}$
Shunt-Series	Current \rightarrow Current	$A_f = \frac{A}{1 + A\beta}$	$R_{if} = \frac{R_i}{1 + A\beta}$	$R_{of} = (1 + A\beta) R_o$
Series-Series	Voltage \rightarrow Current	$A_f = \frac{A}{1 + A\beta}$	$R_{if} = (1 + A\beta) R_i$	$R_{of} = (1 + A\beta) R_o$
Shunt-Shunt	Current \rightarrow Voltage	$A_f = \frac{A}{1 + A\beta}$	$R_{if} = \frac{R_i}{1 + A\beta} R_i$	$R_{of} = \frac{R_o}{1 + A\beta}$

8.5 Positive or Negative

Amplifier Type	Common S	Common G	Common D	Common E	Common B	Common C
Sign of A_v	–	+	+	–	+	–

8.6 Virtual Short and Open Circuit of Amplifier in the State of Deep Negative Feedback

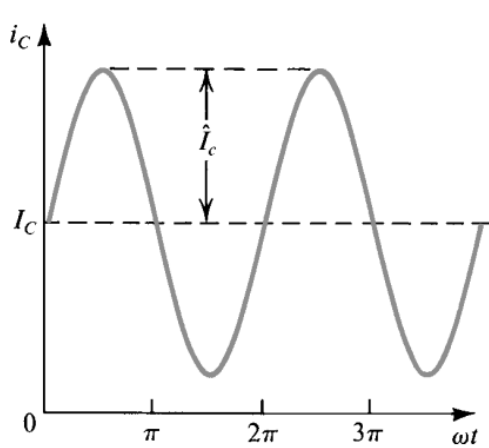


Chapter 9

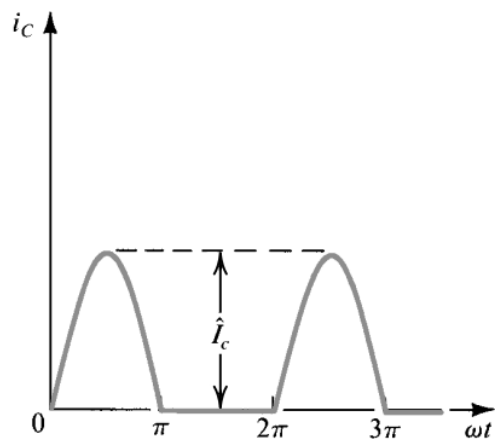
Power Amplifiers

9.1 Classification of Power Amplifiers

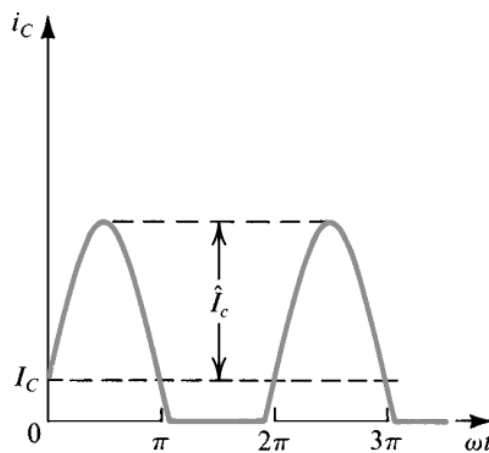
Output stages are classified according to the collector current waveform that results when an input signal is applied.



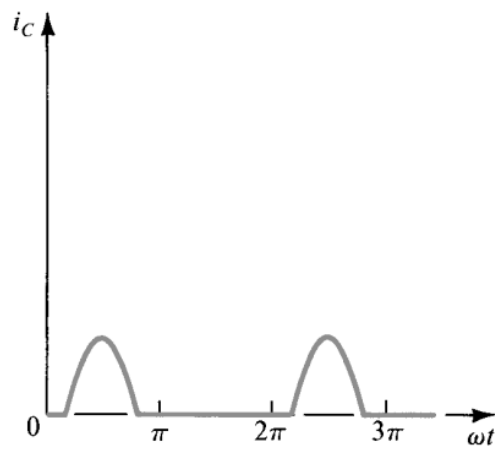
(a) Class A



(b) Class B

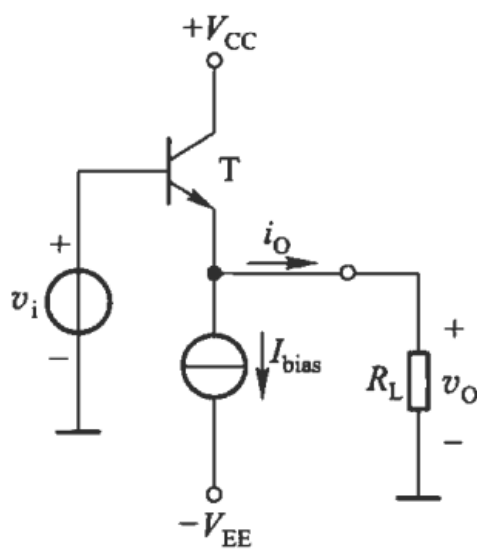


(a) Class AB

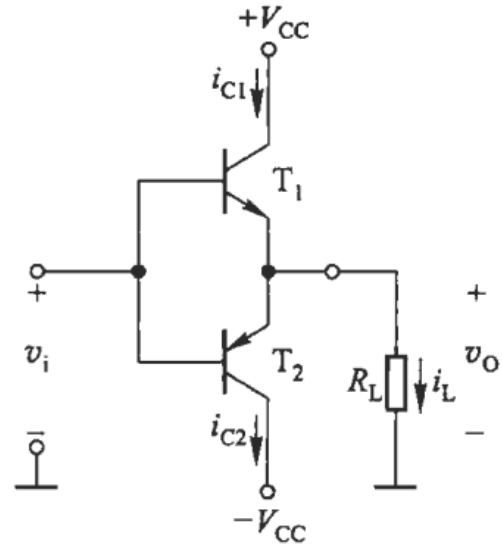


(b) Class C

9.2 Some Example Circuits



(a) Class A Output Stage



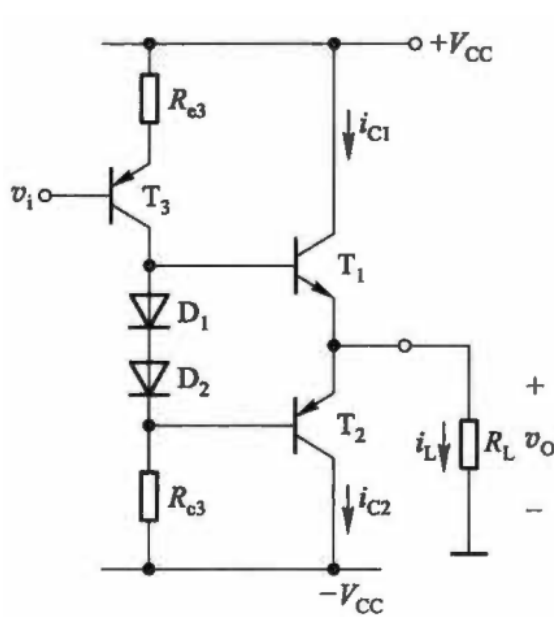
(b) Class B Output Stage

9.3 Power Output

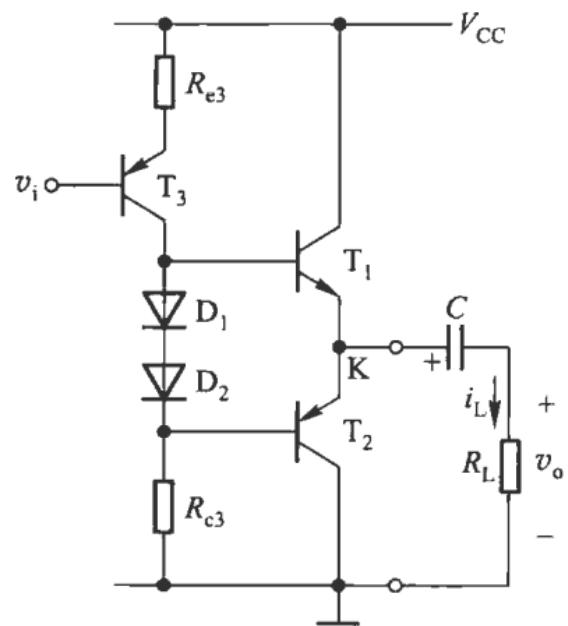
$$V_{om} = \frac{V_{om+} + V_{om-}}{2}$$

$$P_{om} = \left(\frac{V_{om}}{\sqrt{2}} \right)^2 \cdot \frac{1}{R_L}$$

9.4 Crossover Distortion Avoiding



(a) Class AB Output Stage with Double Source

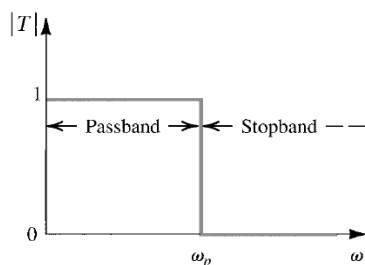


(b) Class AB Output Stage with Single Source

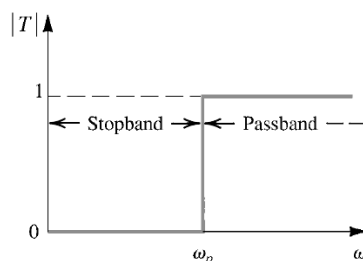
Chapter 10

Filters and Signal Generators

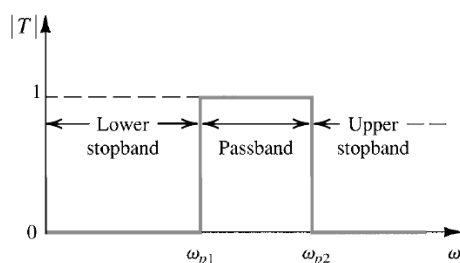
10.1 Four Types of Filters



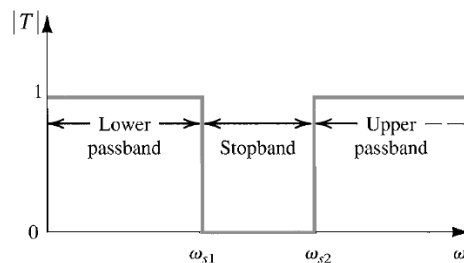
(a) Low-pass (LP)



(b) High-pass (HP)

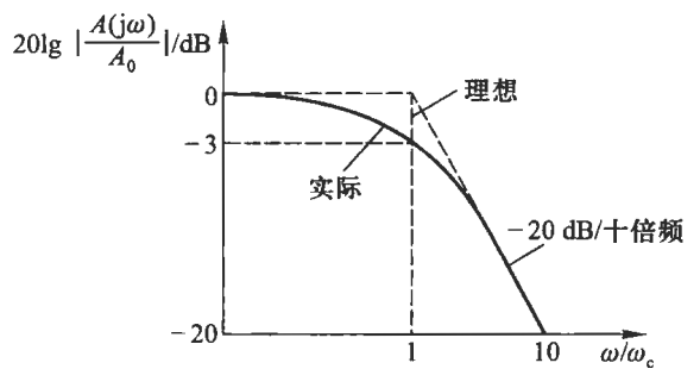
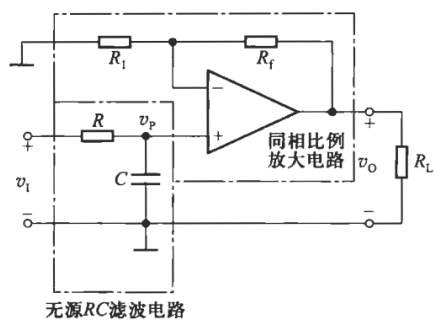


(c) Bandpass (BP)

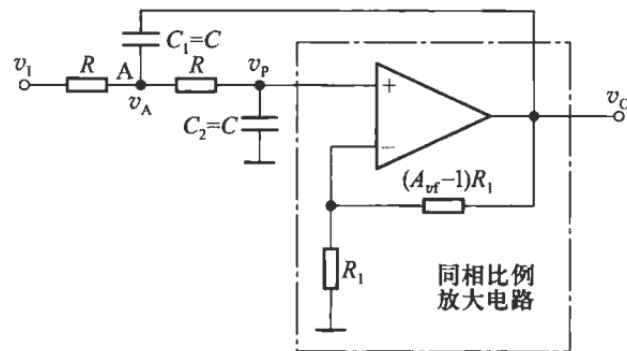


(d) Bandstop (BS)

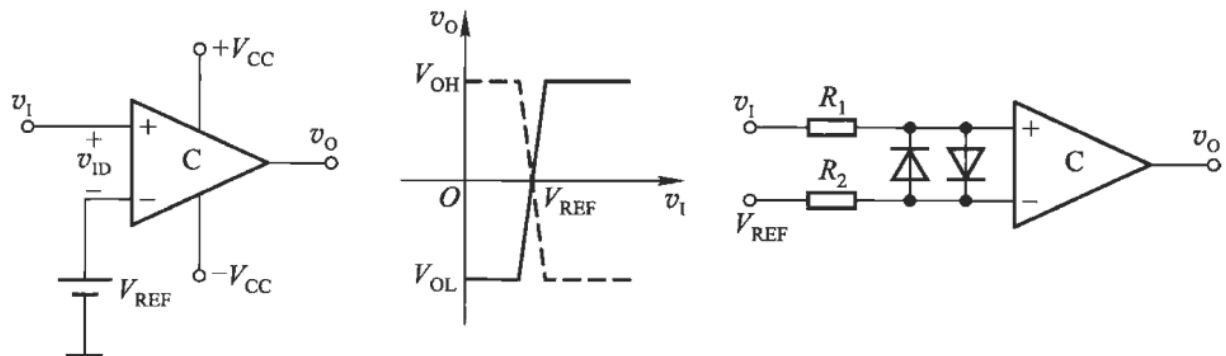
10.2 Filter with source



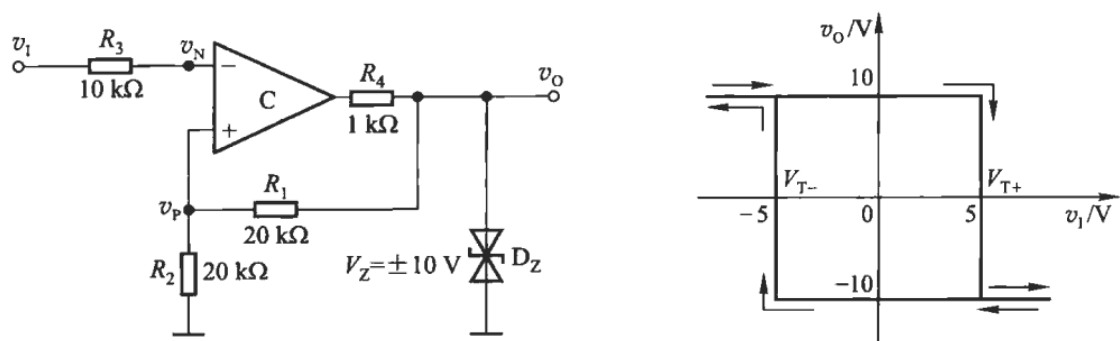
10.3 Sallen-Key Filtering Circuit



10.4 Voltage Comparator

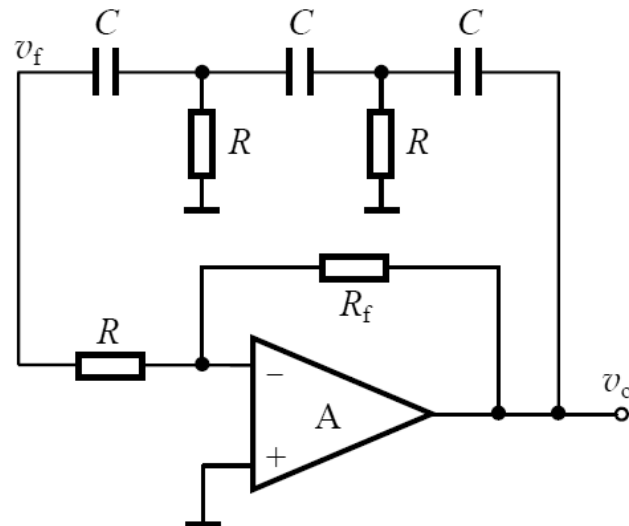


10.5 Inverting Schmitt Trigger

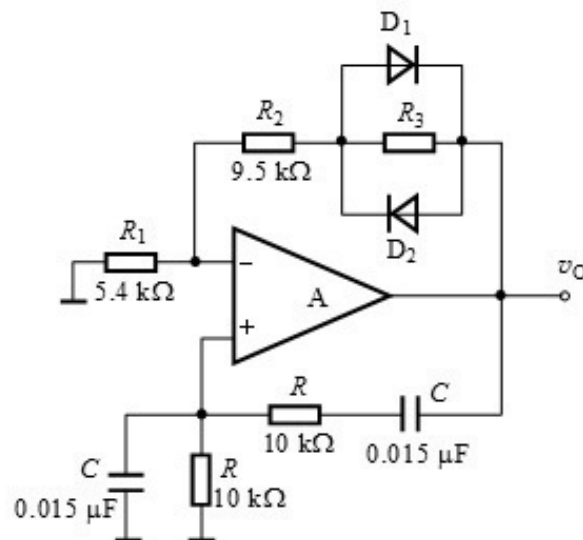


10.6 RC Phase Shifting Network

There are 3 this kind of network below, each may generate up to 90° phase shift.

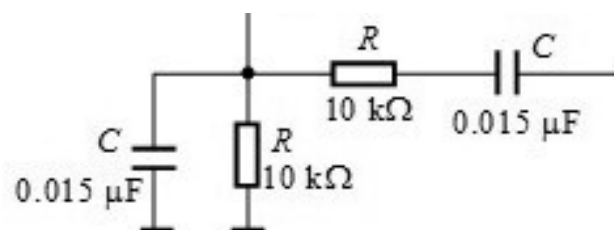


10.7 Stability of RC Oscillator



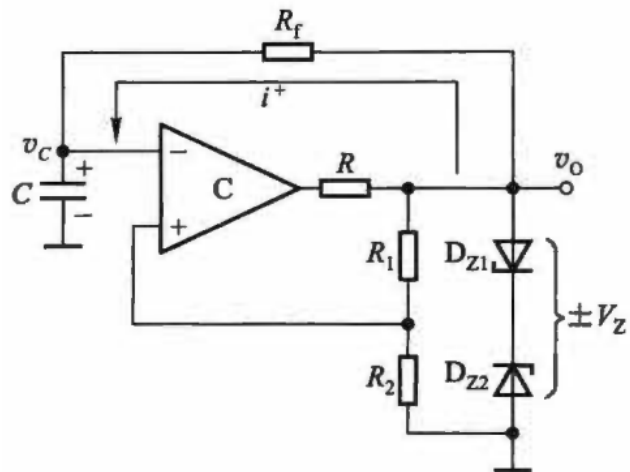
$$A_V = 1 + \frac{R_2 + R_3}{R_1} > 3$$

10.8 RC Phase Selecting Network

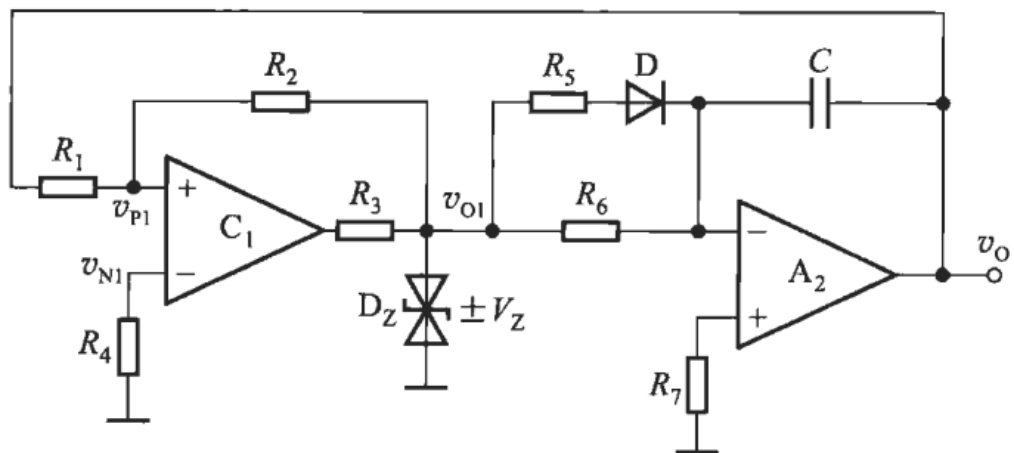


$$f = \frac{1}{2\pi RC}$$

10.9 Generation of Square Waveforms



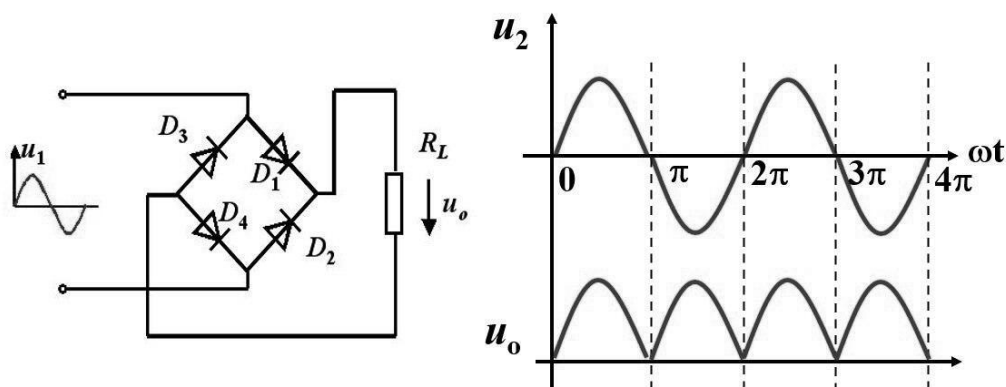
10.10 Generation of Triangle Waveforms



Chapter 11

Stability Problem of DC Source

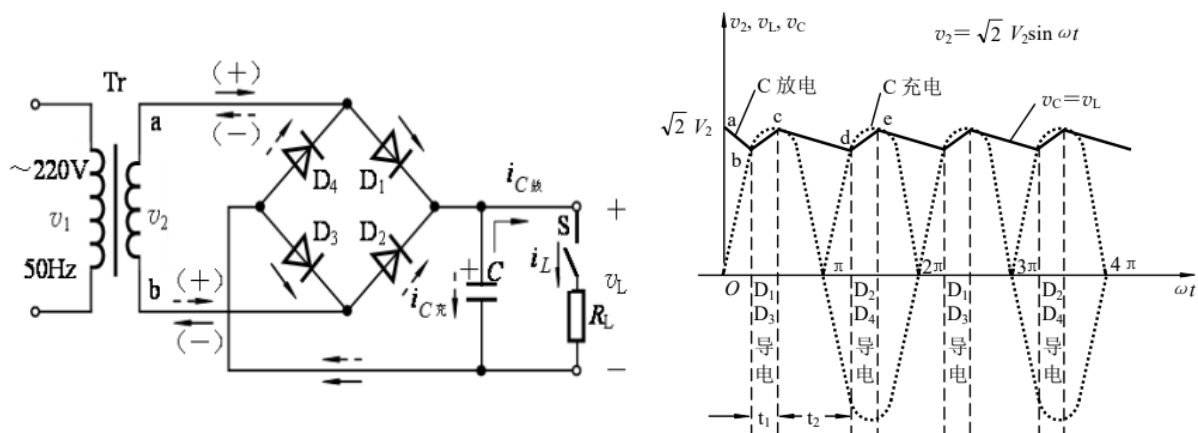
11.1 The Bridge Rectifier



$$V_L \approx 0.9V_S$$

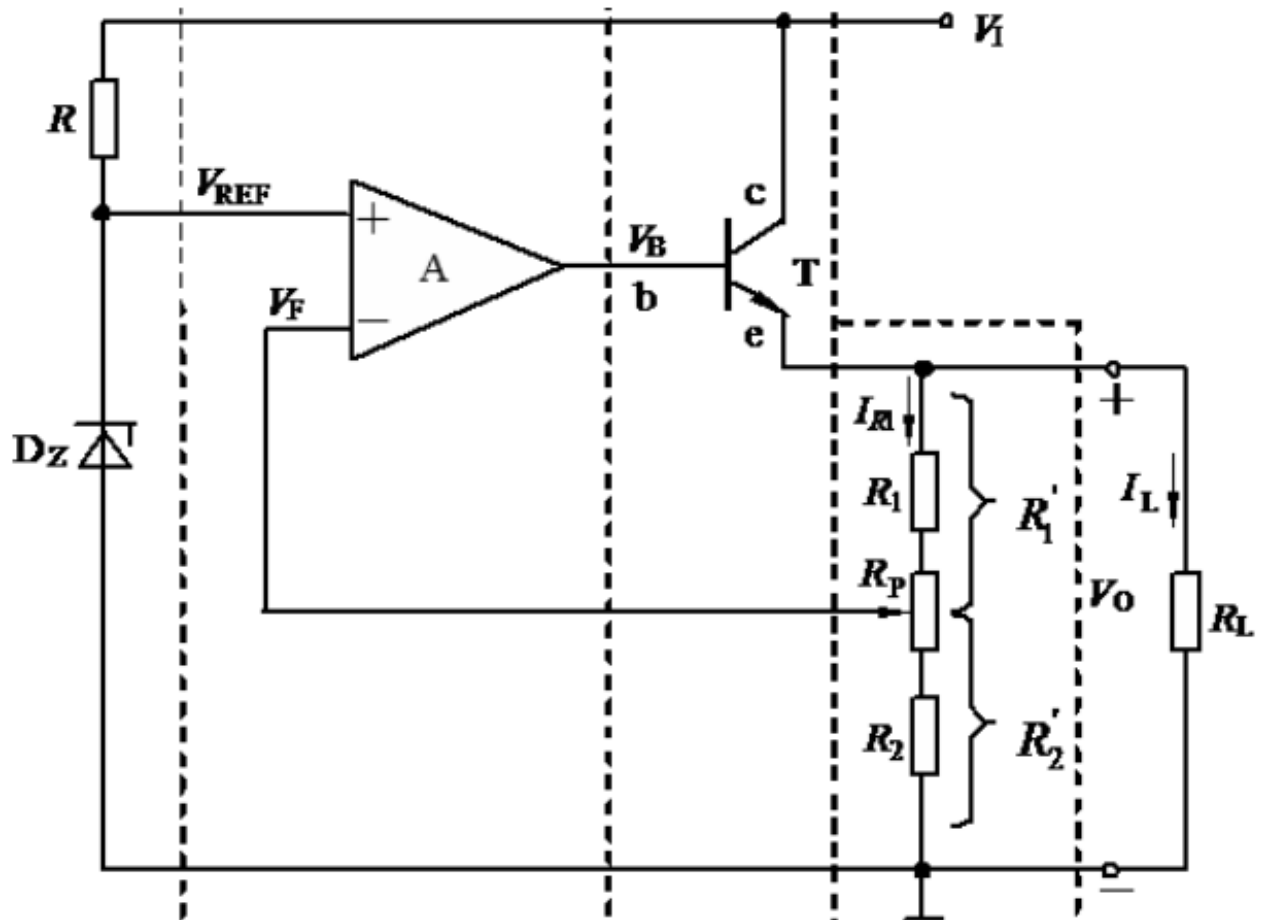
$$I_{D1} = I_{D2} = I_{D3} = I_{D4} = \frac{0.45V_S}{R_L}$$

11.2 Single Phase Bridge Rectifier



$$v_L = 1.2v_2$$

11.3 Series Feedback Voltage Regulator



$$V_O = V_{REF} \left(1 + \frac{R_1}{R_2} \right)$$

11.4 Integrated Voltage Regulator

