

# Energy Storage Based Adaptive Demand Response in Smart Commercial Buildings

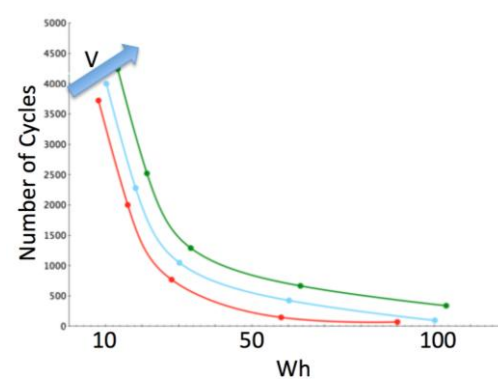
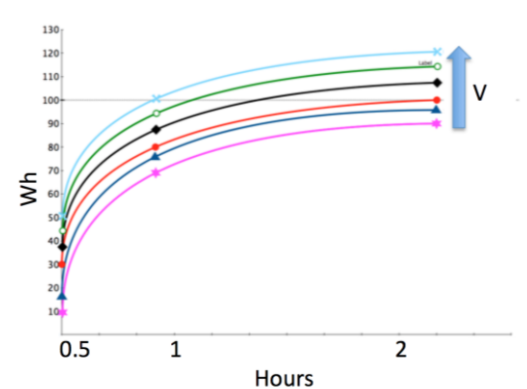
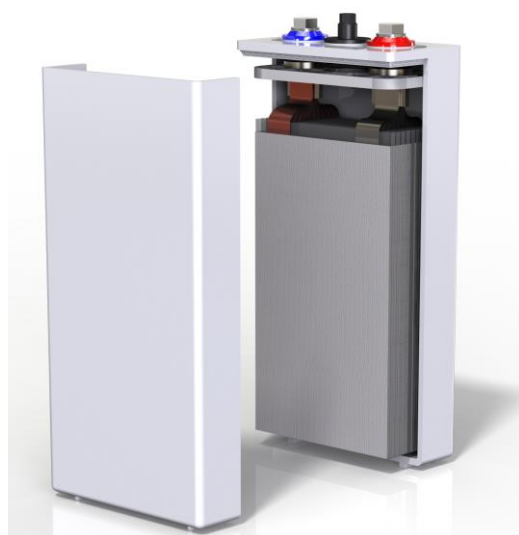
## Motivation

- High peak demand and more **intermittent renewable energy** requires energy storage to ensure reliability, stability and resilience of the power grid.
- Novel **ultra low-cost, compact, and scalable Zn-MnO<sub>2</sub> batteries** as distributed solution in concert with building automation systems.
- Lower net ownership cost and grid stress via **adaptive demand response** algorithm that supports **different tariff structures**.
- Battery size and control **optimized for cost and occupant comfort**.



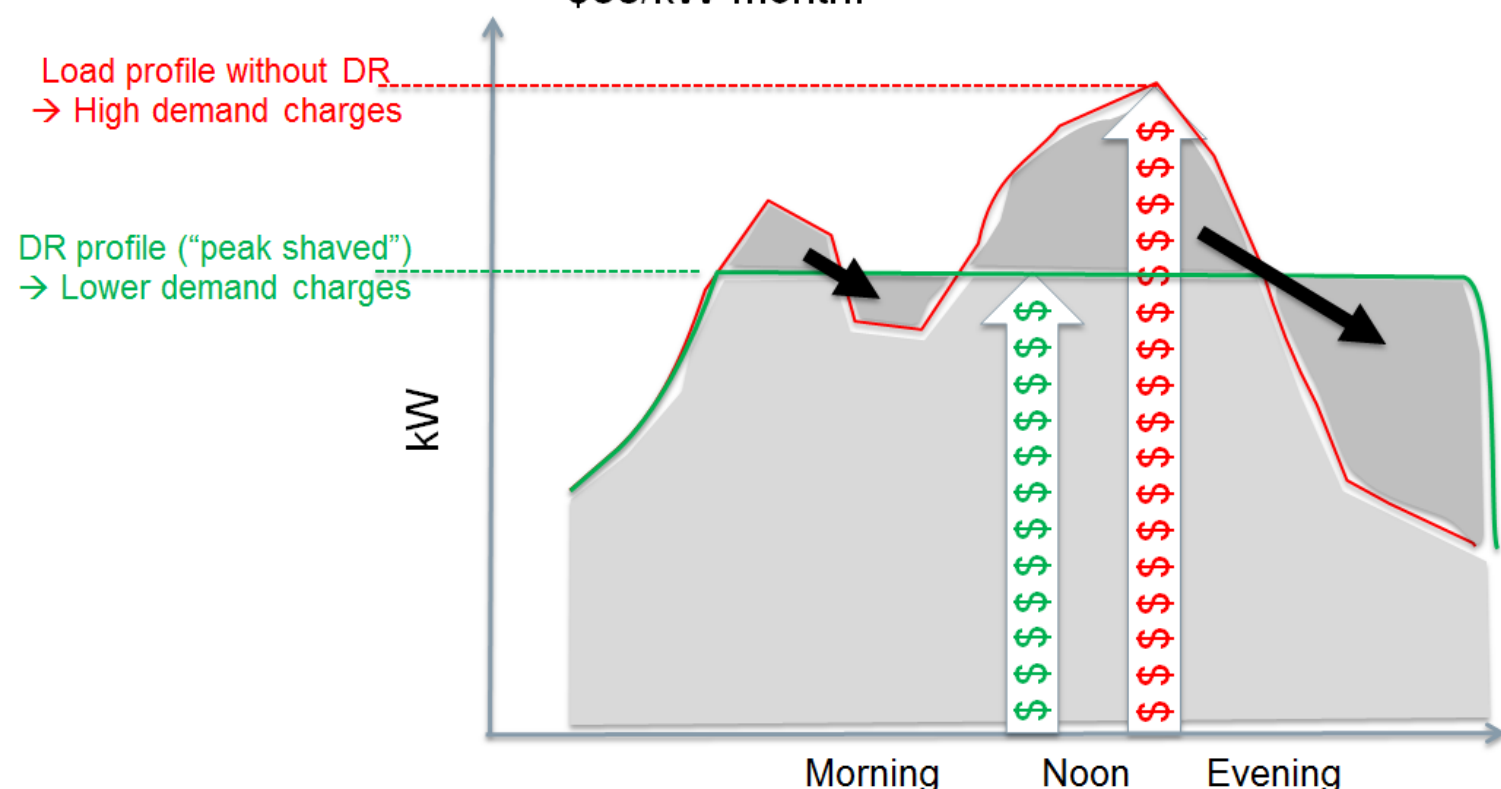
## Key Battery Features

- Half** the price of Li-ion (\$80/kWh).
- Twice** the cycle number (3,000 cycles)
- Completely safe and stable.
- Same components as used in Duracell.

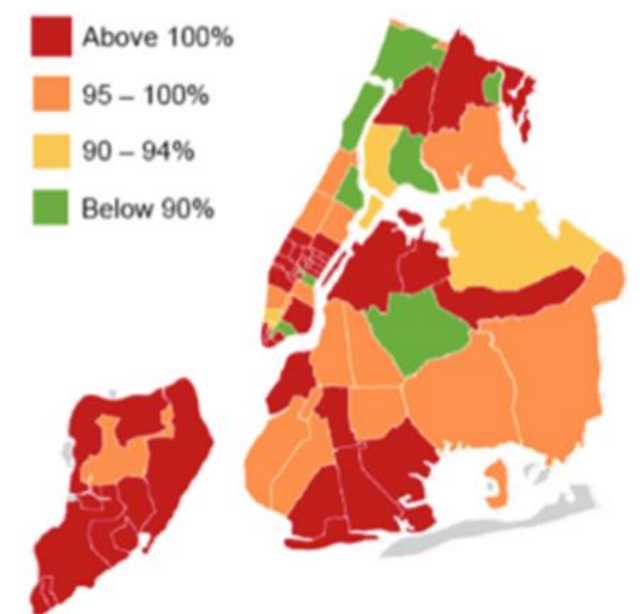


## Building Owners Face High Demand Charges

Electricity tariff for peak demand is as high as \$50/kW-month.



## Testing Site



## Optimal Control and Design Optimization

**Innerloop Optimal Controller:** when and how to charge and discharge the batteries.

**Objective Function**  
 $J_1[n] = \min f_1(X[n]; \theta)$

**Subject to**

$$g_1(X[n]; \theta) = 0$$

$$g_2(X[n]; \theta) \leq 0$$

$f_1$  is aggregated objective function based on performance and energy costs.

$g_1$  is for schedule, set points and air quality requirements.

$g_2$  is for comfort, tariff.

$X$  is the control variables.

$\theta$  is configuration parameter, including battery size and inverter types.

**Outerloop Design Optimizer:** what is the most economical system setup, including battery size and inverter type, etc.

**Objective Function**  
 $J_2 = \min f_2(\theta)$

**Subject to**

$$f_1[n] = \min f_1(X[n]; \theta)$$

$$g_1(X[n]; \theta) = 0$$

$$g_2(X[n]; \theta) \leq 0$$

$f_2$  is building and battery life cycle costs.

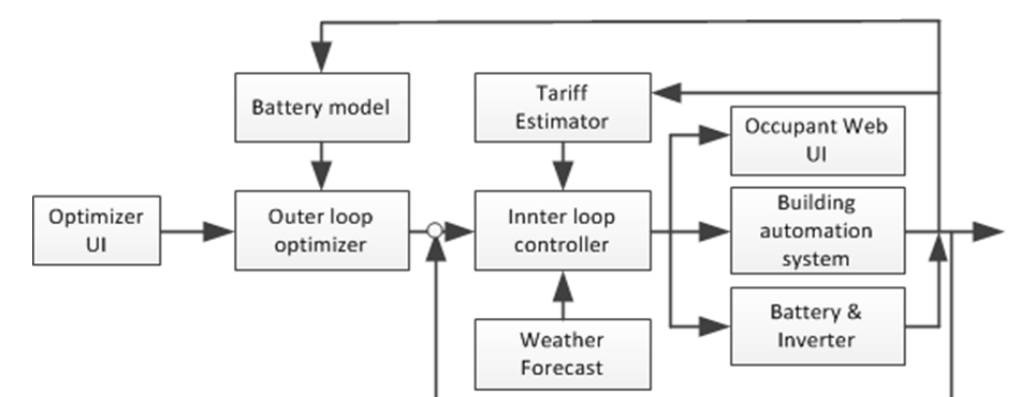
**Tariff Model**

$$C_1 = W_1 \int_{T_1}^{T_2} p(t) dt + W_2 \max(p(t))$$

**Battery Model**

$$SOC = \int_{T_1}^{T_2} kI(t) dt$$

$$SOH = f_3(I(t), R(t))$$



## System Architecture and Simulation Engine

