view_frames Result Recorded at time: 893.412 world Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (893.412 sec old) Most recent transform: 0.000 (893.412 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec right_base_link left_base_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 50.298 Hz Average rate: 10000.000 Hz Average rate: 50.298 Hz Most recent transform: 0.000 (893.412 sec old) Most recent transform: 0.000 (893.412 sec old) Most recent transform: 893.377 (0.035 sec old) Most recent transform: 893.377 (0.035 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 3.360 sec Buffer length: 3.360 sec right_base left_shoulder_link right_shoulder_link left_base Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.298 Hz Average rate: 50.298 Hz Most recent transform: 893.377 (0.035 sec old) Most recent transform: 893.377 (0.035 sec old) Buffer length: 3.360 sec Buffer length: 3.360 sec left_upper_arm_link right_upper_arm_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.298 Hz Average rate: 50.298 Hz Most recent transform: 893.377 (0.035 sec old) Most recent transform: 893.377 (0.035 sec old) Buffer length: 3.360 sec Buffer length: 3.360 sec left_forearm_link right_forearm_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.298 Hz Average rate: 50.298 Hz Most recent transform: 893.377 (0.035 sec old) Most recent transform: 893.377 (0.035 sec old) Buffer length: 3.360 sec Buffer length: 3.360 sec right_wrist_1_link left_wrist_1_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.298 Hz Average rate: 50.298 Hz Most recent transform: 893.377 (0.035 sec old) Most recent transform: 893.377 (0.035 sec old) Buffer length: 3.360 sec Buffer length: 3.360 sec right_wrist_2_link left_wrist_2_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.298 Hz Average rate: 50.298 Hz Most recent transform: 893.377 (0.035 sec old) Most recent transform: 893.377 (0.035 sec old) Buffer length: 3.360 sec Buffer length: 3.360 sec left_wrist_3_link right_wrist_3_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (893.412 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec right_ee_link right_tool0 left_ee_link left_tool0