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>> demo_Polynomial_Dictionary_Learning_Uber
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```
Starting to train the dictionary
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```
solving the quadratic problem with YALMIP...
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```
num. of constraints = 33
```

```
dim. of socp var = 34, num. of socp blk = 1
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```
dim. of linear var = 48
```

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*****
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```
SDPT3: Infeasible path-following algorithms
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```
version predcorr gam expon scale_data
```

```
HKM 1 0.000 1 0
```

```
it pstep dstep pinfeas dinfeas gap prim-obj dual-obj cputime
```

```
-----
0|0.000|0.000|1.0e+00|1.6e+02|8.5e+06|-6.585860e+02 0.000000e+00| 0:0:00| chol 1 1
1|0.983|0.944|1.7e-02|9.2e+00|4.8e+05|-1.625309e+01 8.455178e+02| 0:0:00| chol 2 2
2|1.000|0.966|4.6e-07|3.3e-01|1.8e+04| 7.556555e+00 -2.162983e+02| 0:0:00| chol 2 2
3|1.000|0.989|2.1e-07|8.0e-03|4.4e+02|-2.795292e+00 -9.880222e+00| 0:0:00| chol 2 2
4|0.912|0.927|1.3e-07|1.8e-03|7.2e+01|-9.536998e+00 -8.923701e+00| 0:0:00| chol 2 2
5|0.524|0.509|1.2e-07|1.1e-03|4.3e+01|-1.139023e+01 -1.009032e+01| 0:0:00| chol 2 2
6|0.272|0.416|8.9e-08|6.7e-04|2.9e+01|-1.214420e+01 -1.132766e+01| 0:0:00| chol 2 2
7|0.138|0.665|1.1e-07|2.5e-04|1.2e+01|-1.276183e+01 -1.270018e+01| 0:0:00| chol 2 2
8|0.182|0.368|8.5e-08|1.6e-04|8.6e+00|-1.313941e+01 -1.349940e+01| 0:0:00| chol 2 2
9|0.481|0.648|7.4e-08|5.8e-05|4.5e+00|-1.309943e+01 -1.469179e+01| 0:0:00| chol 2 2
10|0.740|0.823|1.7e-08|1.1e-05|1.5e+00|-1.394183e+01 -1.492675e+01| 0:0:00| chol 3 3
11|0.555|0.936|1.1e-08|9.8e-07|7.3e-01|-1.436317e+01 -1.505110e+01| 0:0:00| chol 3 4
12|1.000|1.000|1.0e-08|8.6e-08|1.9e-01|-1.484825e+01 -1.503935e+01| 0:0:00| chol 3 3
13|0.925|0.961|9.2e-09|3.0e-08|2.3e-02|-1.498197e+01 -1.500417e+01| 0:0:00| chol 3 4
14|0.953|0.954|1.5e-08|1.0e-08|3.5e-03|-1.499755e+01 -1.500070e+01| 0:0:00| chol 5 5
15|1.000|0.909|1.8e-08|4.4e-09|3.9e-04|-1.499982e+01 -1.500013e+01| 0:0:00| chol 7 7
16|1.000|0.986|1.0e-08|1.6e-10|2.7e-05|-1.500002e+01 -1.500007e+01| 0:0:00| chol
```

```
linsysolve: Schur complement matrix not positive definite
```

```
switch to LU factor. lu 11 ^14
```

```
17|1.000|0.811|3.8e-08|3.7e-11|2.0e-06|-1.500008e+01 -1.500006e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
```

```
-----
number of iterations = 17
```

```
primal objective value = -1.50000800e+01
```

```
dual objective value = -1.50000587e+01
```

```
gap := trace(XZ) = 2.00e-06
```

```
relative gap = 6.46e-08
```

```
actual relative gap = -6.87e-07
```

```
rel. primal infeas = 3.84e-08
```

```
rel. dual infeas = 3.70e-11
```

```
norm(X), norm(y), norm(Z) = 1.7e+03, 4.6e+01, 2.2e+01
```

```
norm(A), norm(b), norm(C) = 3.1e+03, 1.6e+03, 4.4e+01
```

```
Total CPU time (secs) = 0.12
```

```
CPU time per iteration = 0.01
```

```
termination code = 0
```

```
DIMACS errors: 8.3e-08 0.0e+00 5.0e-11 0.0e+00 -6.9e-07 6.5e-08
```

```
ans =
```

```
15.0001
```

```

num. of constraints = 33
dim. of socp var = 34, num. of socp blk = 1
dim. of linear var = 48
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|2.0e+02|7.1e+06|-6.009084e+02  0.000000e+00| 0:0:00| chol 1 1
1|0.980|0.938|2.0e-02|1.2e+01|4.4e+05|-1.895277e+01  3.040602e+03| 0:0:00| chol 2 2
2|1.000|0.943|3.9e-07|7.2e-01|2.8e+04| 9.609427e-01 -1.681182e+02| 0:0:00| chol 2 2
3|1.000|0.992|1.4e-07|1.0e-02|4.4e+02|-9.692374e-01 -1.045163e+01| 0:0:00| chol 2 2
4|0.925|0.984|2.5e-08|1.4e-03|5.0e+01|-8.614237e+00 -8.838937e+00| 0:0:00| chol 2 2
5|0.464|0.410|2.9e-08|9.9e-04|3.3e+01|-9.885847e+00 -9.269360e+00| 0:0:00| chol 2 2
6|0.253|0.417|2.8e-08|6.3e-04|2.2e+01|-1.039541e+01 -1.009009e+01| 0:0:00| chol 2 2
7|0.191|0.643|2.6e-08|2.5e-04|9.3e+00|-1.109626e+01 -1.089936e+01| 0:0:00| chol 3 2
8|0.688|0.535|3.9e-08|1.2e-04|5.4e+00|-1.166773e+01 -1.195133e+01| 0:0:00| chol 3 3
9|0.793|0.669|1.5e-08|4.2e-05|2.5e+00|-1.202385e+01 -1.269224e+01| 0:0:00| chol 2 3
10|0.675|0.750|4.2e-09|1.1e-05|1.0e+00|-1.241895e+01 -1.298211e+01| 0:0:00| chol 3 3
11|0.380|0.559|2.8e-09|5.1e-06|7.0e-01|-1.258648e+01 -1.305988e+01| 0:0:00| chol 3 3
12|0.299|0.575|8.3e-09|2.2e-06|5.1e-01|-1.268557e+01 -1.309523e+01| 0:0:00| chol 3 3
13|0.392|1.000|8.0e-09|2.6e-08|3.1e-01|-1.280269e+01 -1.311356e+01| 0:0:00| chol 4 5
14|1.000|1.000|1.9e-08|8.8e-09|9.7e-02|-1.301550e+01 -1.311168e+01| 0:0:00| chol 4 4
15|0.999|1.000|2.0e-08|4.1e-09|1.2e-02|-1.307920e+01 -1.309104e+01| 0:0:00| chol 6 6
16|0.949|0.966|3.2e-08|3.6e-09|1.2e-03|-1.308697e+01 -1.308797e+01| 0:0:00| chol
linsysolve: Schur complement matrix not positive definite
switch to LU factor. lu 23 2
17|0.936|0.900|2.9e-08|7.4e-10|1.5e-04|-1.308768e+01 -1.308778e+01| 0:0:00| lu 30 ^ 3
18|1.000|1.000|4.7e-08|5.4e-11|2.1e-05|-1.308776e+01 -1.308775e+01| 0:0:00| lu 28 ^19
19|0.988|0.794|6.0e-08|1.5e-11|1.7e-06|-1.308771e+01 -1.308774e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
-----
number of iterations = 19
primal objective value = -1.30877141e+01
dual objective value = -1.30877444e+01
gap := trace(XZ) = 1.73e-06
relative gap = 6.38e-08
actual relative gap = 1.12e-06
rel. primal infeas = 6.03e-08
rel. dual infeas = 1.54e-11
norm(X), norm(y), norm(Z) = 2.1e+03, 4.7e+01, 2.4e+01
norm(A), norm(b), norm(C) = 7.4e+03, 2.7e+03, 4.4e+01
Total CPU time (secs) = 0.12
CPU time per iteration = 0.01
termination code = 0
DIMACS errors: 9.7e-08 0.0e+00 2.1e-11 0.0e+00 1.1e-06 6.4e-08
-----

ans =

13.0877

```

Iteration 2 Total error is: 0.074008

num. of constraints = 33
 dim. of socp var = 34, num. of socp blk = 1
 dim. of linear var = 48

SDPT3: Infeasible path-following algorithms

version predcorr gam expon scale_data

HKM 1 0.000 1 0

it pstep dstep pinfeas dinfeas gap prim-obj dual-obj cputime

0	0.000	0.000	1.0e+00	2.0e+02	7.3e+06	-6.205988e+02	0.000000e+00	0:0:00	chol	1	1
1	0.982	0.940	1.8e-02	1.2e+01	4.3e+05	-1.775192e+01	3.123831e+03	0:0:00	chol	2	2
2	1.000	0.944	3.1e-07	6.9e-01	2.7e+04	1.051253e+00	-1.396162e+02	0:0:00	chol	2	2
3	1.000	0.992	1.2e-07	9.6e-03	4.2e+02	-8.568468e-01	-9.980188e+00	0:0:00	chol	2	2
4	0.923	0.987	2.6e-08	1.4e-03	4.9e+01	-8.491015e+00	-8.694762e+00	0:0:00	chol	2	2
5	0.470	0.389	1.6e-08	1.0e-03	3.3e+01	-9.766241e+00	-9.099710e+00	0:0:00	chol	2	2
6	0.247	0.410	6.1e-08	6.4e-04	2.2e+01	-1.026163e+01	-9.923038e+00	0:0:00	chol	2	2
7	0.193	0.633	5.1e-08	2.6e-04	9.5e+00	-1.097806e+01	-1.074085e+01	0:0:00	chol	3	2
8	0.704	0.542	7.8e-08	1.2e-04	5.4e+00	-1.153141e+01	-1.180274e+01	0:0:00	chol	2	3
9	0.806	0.665	2.6e-08	4.3e-05	2.6e+00	-1.188449e+01	-1.254752e+01	0:0:00	chol	2	2
10	0.670	0.749	8.8e-09	1.2e-05	1.1e+00	-1.227828e+01	-1.284725e+01	0:0:00	chol	2	3
11	0.376	0.587	5.6e-09	4.9e-06	7.0e-01	-1.244742e+01	-1.293390e+01	0:0:00	chol	3	3
12	0.278	0.534	4.7e-09	2.3e-06	5.3e-01	-1.254217e+01	-1.296539e+01	0:0:00	chol	3	3
13	0.360	1.000	4.8e-09	2.6e-08	3.4e-01	-1.265064e+01	-1.298947e+01	0:0:00	chol	4	4
14	0.863	1.000	1.1e-08	8.5e-09	1.6e-01	-1.282924e+01	-1.299078e+01	0:0:00	chol	4	5
15	1.000	1.000	1.9e-08	3.7e-09	5.8e-02	-1.291673e+01	-1.297467e+01	0:0:00	chol	5	5
16	0.923	0.929	6.3e-08	3.1e-09	5.8e-03	-1.295543e+01	-1.296094e+01	0:0:00	chol	9	10
17	0.954	0.940	3.4e-08	1.6e-09	4.6e-04	-1.295926e+01	-1.295962e+01	0:0:00	chol		

linsysolve: Schur complement matrix not positive definite

switch to LU factor. lu 22 ^10

18	0.808	0.789	2.0e-07	6.5e-10	1.3e-04	-1.295847e+01	-1.295954e+01	0:0:00	lu	19	^10
19	1.000	1.000	7.0e-07	1.9e-10	7.6e-05	-1.295537e+01	-1.295954e+01	0:0:00	lu	22	30
20	1.000	0.819	9.3e-07	8.8e-11	2.1e-05	-1.295775e+01	-1.295952e+01	0:0:00	lu	11	^7
21	0.084	0.083	1.0e-06	1.3e-10	2.1e-05	-1.295774e+01	-1.295952e+01	0:0:00	lu	11	^18
22	0.041	0.076	1.0e-06	1.8e-10	2.2e-05	-1.295778e+01	-1.295952e+01	0:0:00			

stop: progress is too slow

stop: progress is bad

number of iterations = 22
 primal objective value = -1.29577453e+01
 dual objective value = -1.29595196e+01
 gap := trace(XZ) = 2.09e-05
 relative gap = 7.75e-07
 actual relative gap = 6.59e-05
 rel. primal infeas = 9.32e-07
 rel. dual infeas = 8.81e-11
 norm(X), norm(y), norm(Z) = 2.2e+03, 4.7e+01, 2.4e+01
 norm(A), norm(b), norm(C) = 7.9e+03, 2.6e+03, 4.4e+01
 Total CPU time (secs) = 0.14
 CPU time per iteration = 0.01
 termination code = -5
 DIMACS errors: 1.6e-06 0.0e+00 1.2e-10 0.0e+00 6.6e-05 7.8e-07

ans =

12.9595

Iteration 3 Total error is: 0.073688

num. of constraints = 33
 dim. of socp var = 34, num. of socp blk = 1
 dim. of linear var = 48

SDPT3: Infeasible path-following algorithms

version predcorr gam expon scale_data

HKM 1 0.000 1 0

it	pstep	dstep	pinfeas	dinfeas	gap	prim-obj	dual-obj	cputime
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0	0.000	0.000	1.0e+00	2.1e+02	8.0e+06	-6.309153e+02	0.000000e+00	0:0:00 chol 1 1
1	0.983	0.941	1.7e-02	1.2e+01	4.7e+05	-1.696211e+01	3.257957e+03	0:0:00 chol 2 2
2	1.000	0.945	3.0e-07	6.8e-01	2.8e+04	1.411313e+00	-1.438446e+02	0:0:00 chol 2 2
3	1.000	0.992	1.3e-07	9.2e-03	4.4e+02	-4.794849e-01	-9.898190e+00	0:0:00 chol 2 2
4	0.924	0.990	1.8e-08	1.4e-03	5.2e+01	-8.300236e+00	-8.566354e+00	0:0:00 chol 2 2
5	0.469	0.371	2.0e-08	9.9e-04	3.5e+01	-9.570396e+00	-8.951039e+00	0:0:00 chol 2 2
6	0.232	0.430	4.7e-08	6.2e-04	2.3e+01	-1.009243e+01	-9.823648e+00	0:0:00 chol 2 2
7	0.194	0.634	4.0e-08	2.5e-04	9.9e+00	-1.082907e+01	-1.067725e+01	0:0:00 chol 3 3
8	0.728	0.564	5.3e-08	1.1e-04	5.5e+00	-1.138676e+01	-1.178184e+01	0:0:00 chol 3 3
9	0.827	0.690	1.7e-08	3.7e-05	2.4e+00	-1.177880e+01	-1.250383e+01	0:0:00 chol 3 3
10	0.623	0.677	6.3e-09	1.3e-05	1.2e+00	-1.217067e+01	-1.275347e+01	0:0:00 chol 3 3
11	0.418	0.625	3.9e-09	4.9e-06	7.2e-01	-1.235705e+01	-1.285010e+01	0:0:00 chol 3 3
12	0.285	0.673	3.8e-09	1.7e-06	5.1e-01	-1.245434e+01	-1.288743e+01	0:0:00 chol 3 4
13	0.395	1.000	4.5e-09	2.6e-08	3.3e-01	-1.257815e+01	-1.290307e+01	0:0:00 chol 5 4
14	1.000	1.000	9.9e-09	8.5e-09	1.0e-01	-1.279715e+01	-1.290108e+01	0:0:00 chol 4 4
15	0.936	0.998	3.1e-08	3.6e-09	1.3e-02	-1.286576e+01	-1.287834e+01	0:0:00 chol 8 7
16	0.976	0.971	2.5e-08	2.2e-09	5.9e-04	-1.287550e+01	-1.287602e+01	0:0:00 chol

linsysolve: Schur complement matrix not positive definite

switch to LU factor. lu 11 ^25

17	0.947	0.790	8.9e-08	5.6e-10	3.7e-05	-1.287598e+01	-1.287591e+01	0:0:00 lu 30 ^29
18	0.500	0.551	6.4e-07	3.1e-10	2.3e-05	-1.287604e+01	-1.287592e+01	0:0:00 lu 13 ^ 7
19	0.098	0.094	6.2e-07	3.4e-10	2.4e-05	-1.287646e+01	-1.287592e+01	0:0:00 lu 30 ^12
20	0.203	0.409	5.1e-07	2.5e-10	2.1e-05	-1.287603e+01	-1.287592e+01	0:0:00 lu 30 30
21	0.065	0.108	3.7e-07	2.8e-10	2.2e-05	-1.287602e+01	-1.287592e+01	0:0:00

lack of progress in infeas

number of iterations = 21
 primal objective value = -1.28760448e+01
 dual objective value = -1.28759178e+01
 gap := trace(XZ) = 2.26e-05
 relative gap = 8.44e-07
 actual relative gap = -4.75e-06
 rel. primal infeas = 6.39e-07
 rel. dual infeas = 3.07e-10
 norm(X), norm(y), norm(Z) = 2.3e+03, 4.7e+01, 2.4e+01
 norm(A), norm(b), norm(C) = 8.4e+03, 2.8e+03, 4.4e+01
 Total CPU time (secs) = 0.16

```

CPU time per iteration = 0.01
termination code       = 0
DIMACS errors: 1.1e-06  0.0e+00  4.2e-10  0.0e+00  -4.7e-06  8.4e-07
-----

```

```
ans =
```

```
12.8759
```

```
Iteration 4 Total error is: 0.073492
```

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 48

```

```
*****
```

```
SDPT3: Infeasible path-following algorithms
```

```
*****
```

```

version predcorr gam expon scale_data
HKM      1      0.000 1      0

```

it	pstep	dstep	pinfeas	dinfeas	gap	prim-obj	dual-obj	cputime			
0	0.000	0.000	1.0e+00	2.1e+02	8.5e+06	-6.357477e+02	0.000000e+00	0:0:00	chol	1	1
1	0.983	0.942	1.7e-02	1.2e+01	4.9e+05	-1.657204e+01	3.431747e+03	0:0:00	chol	2	2
2	1.000	0.946	2.9e-07	6.9e-01	3.0e+04	1.644553e+00	-1.477665e+02	0:0:00	chol	2	2
3	1.000	0.992	1.6e-07	9.3e-03	4.7e+02	-1.793680e-01	-9.903993e+00	0:0:00	chol	2	2
4	0.926	0.992	1.8e-08	1.3e-03	5.4e+01	-8.113742e+00	-8.476839e+00	0:0:00	chol	2	2
5	0.459	0.371	1.7e-08	9.9e-04	3.7e+01	-9.367998e+00	-8.854721e+00	0:0:00	chol	2	2
6	0.228	0.449	1.0e-08	6.0e-04	2.3e+01	-9.922688e+00	-9.747179e+00	0:0:00	chol	2	2
7	0.192	0.638	8.6e-09	2.4e-04	1.0e+01	-1.065480e+01	-1.062524e+01	0:0:00	chol	3	2
8	0.733	0.577	2.1e-08	1.1e-04	5.5e+00	-1.122120e+01	-1.172934e+01	0:0:00	chol	3	2
9	0.820	0.702	1.3e-08	3.4e-05	2.4e+00	-1.163746e+01	-1.242013e+01	0:0:00	chol	3	3
10	0.622	0.658	6.2e-09	1.2e-05	1.2e+00	-1.204317e+01	-1.264883e+01	0:0:00	chol	3	3
11	0.478	0.700	2.9e-09	3.9e-06	6.6e-01	-1.225942e+01	-1.274965e+01	0:0:00	chol	3	3
12	0.351	0.889	5.8e-09	5.1e-07	4.2e-01	-1.237957e+01	-1.277915e+01	0:0:00	chol	4	4
13	0.397	1.000	1.1e-08	2.6e-08	3.0e-01	-1.248387e+01	-1.278529e+01	0:0:00	chol	4	4
14	1.000	1.000	1.1e-08	8.9e-09	1.1e-01	-1.267293e+01	-1.278173e+01	0:0:00	chol	4	4
15	0.961	1.000	4.3e-08	4.2e-09	1.3e-02	-1.274536e+01	-1.275889e+01	0:0:00	chol	5	6
16	0.977	0.969	4.3e-08	2.4e-09	6.2e-04	-1.275563e+01	-1.275609e+01	0:0:00	chol		
linsysolve: Schur complement matrix not positive definite											
switch to LU factor. lu 30 13											
17	0.987	0.987	4.5e-08	5.4e-11	8.8e-06	-1.275579e+01	-1.275597e+01	0:0:00	lu	11	^14
18	0.363	0.358	2.0e-07	5.0e-11	5.9e-06	-1.275587e+01	-1.275597e+01	0:0:00	lu	30	^ 4
19	0.025	0.027	1.6e-07	6.5e-11	6.4e-06	-1.275579e+01	-1.275597e+01	0:0:00	lu	13	30
20	0.499	0.215	1.1e-07	6.7e-11	6.1e-06	-1.275569e+01	-1.275597e+01	0:0:00	lu	30	^10
21	0.183	0.999	1.2e-07	9.9e-12	3.8e-06	-1.275566e+01	-1.275597e+01	0:0:00	lu	30	^ 5
22	0.030	0.033	2.6e-07	2.0e-11	4.1e-06	-1.275552e+01	-1.275597e+01	0:0:00	lu	30	^19
23	0.353	0.379	1.8e-07	2.1e-11	3.2e-06	-1.275557e+01	-1.275597e+01	0:0:00	lu	11	^22
24	0.011	0.022	1.6e-07	2.9e-11	3.4e-06	-1.275559e+01	-1.275597e+01	0:0:00			
stop: progress is bad											
lack of progress in infeas											

```

number of iterations   = 24
primal objective value = -1.27556592e+01
dual   objective value = -1.27559686e+01
gap := trace(XZ)       = 3.82e-06

```

```

relative gap          = 1.44e-07
actual relative gap   = 1.17e-05
rel. primal infeas    = 1.17e-07
rel. dual   infeas    = 9.93e-12
norm(X), norm(y), norm(Z) = 2.3e+03, 4.7e+01, 2.5e+01
norm(A), norm(b), norm(C) = 8.9e+03, 2.9e+03, 4.4e+01
Total CPU time (secs) = 0.18
CPU time per iteration = 0.01
termination code      = -5
DIMACS errors: 1.9e-07 0.0e+00 1.3e-11 0.0e+00 1.2e-05 1.4e-07
-----

```

```
ans =
```

```
12.7560
```

```
Iteration 5 Total error is: 0.073173
```

```

num. of constraints = 33
dim. of socp var = 34, num. of socp blk = 1
dim. of linear var = 48
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|2.3e+02|9.6e+06|-6.522122e+02 0.000000e+00| 0:0:00| chol 1 1
1|0.984|0.944|1.6e-02|1.3e+01|5.4e+05|-1.532828e+01 3.759277e+03| 0:0:00| chol 2 1
2|1.000|0.947|3.1e-07|6.9e-01|3.1e+04| 2.082345e+00 -1.421694e+02| 0:0:00| chol 2 2
3|1.000|0.992|2.1e-07|9.2e-03|5.1e+02| 3.464308e-01 -9.810886e+00| 0:0:00| chol 2 2
4|0.928|0.996|1.9e-08|1.3e-03|5.9e+01|-7.806671e+00 -8.335222e+00| 0:0:00| chol 2 2
5|0.433|0.354|2.2e-08|9.8e-04|4.1e+01|-9.003456e+00 -8.689139e+00| 0:0:00| chol 2 2
6|0.219|0.504|3.8e-08|5.5e-04|2.4e+01|-9.637851e+00 -9.656905e+00| 0:0:00| chol 2 2
7|0.190|0.651|3.4e-08|2.1e-04|1.0e+01|-1.038141e+01 -1.062052e+01| 0:0:00| chol 3 2
8|0.758|0.618|4.4e-08|8.8e-05|5.1e+00|-1.098442e+01 -1.171989e+01| 0:0:00| chol 3 3
9|0.829|0.737|1.6e-08|2.5e-05|2.1e+00|-1.149017e+01 -1.231873e+01| 0:0:00| chol 3 3
10|0.621|0.619|7.9e-09|1.0e-05|1.1e+00|-1.189968e+01 -1.251176e+01| 0:0:00| chol 3 3
11|0.591|0.753|3.6e-09|2.7e-06|5.5e-01|-1.216848e+01 -1.259733e+01| 0:0:00| chol 3 3
12|0.436|1.000|7.2e-09|8.5e-08|3.2e-01|-1.229770e+01 -1.261440e+01| 0:0:00| chol 5 5
13|1.000|1.000|3.9e-09|2.6e-08|9.7e-02|-1.251545e+01 -1.261166e+01| 0:0:00| chol 4 4
14|0.963|1.000|1.9e-08|8.4e-09|1.2e-02|-1.258016e+01 -1.259241e+01| 0:0:00| chol 8 7
15|0.991|0.969|2.3e-08|3.6e-09|6.1e-04|-1.258922e+01 -1.258979e+01| 0:0:00| chol
linsysolve: Schur complement matrix not positive definite
switch to LU factor. lu 19 29
16|0.984|0.984|1.4e-07|8.9e-11|1.1e-05|-1.258984e+01 -1.258969e+01| 0:0:00| lu 30 ^24
17|0.558|0.550|2.0e-07|5.5e-11|5.8e-06|-1.259060e+01 -1.258969e+01| 0:0:00| lu 30 ^21
18|0.453|1.000|2.4e-07|8.8e-12|3.4e-06|-1.259078e+01 -1.258969e+01| 0:0:00| lu 15 ^20
19|0.061|0.061|2.8e-07|1.7e-11|3.6e-06|-1.259043e+01 -1.258969e+01| 0:0:00| lu 30 ^ 5
20|0.783|1.000|1.2e-07|5.8e-12|2.2e-06|-1.259017e+01 -1.258969e+01| 0:0:00| lu 23 ^27
21|0.158|0.331|2.6e-07|9.2e-12|2.0e-06|-1.259021e+01 -1.258969e+01| 0:0:00| lu 11 30
22|0.078|0.152|1.8e-07|1.3e-11|2.0e-06|-1.259025e+01 -1.258969e+01| 0:0:00|
stop: progress is bad
-----

```

```

number of iterations    = 22
primal objective value = -1.25901742e+01
dual   objective value = -1.25896887e+01
gap := trace(XZ)       = 2.24e-06
relative gap           = 8.57e-08
actual relative gap    = -1.85e-05
rel. primal infeas     = 1.24e-07
rel. dual   infeas     = 5.83e-12
norm(X), norm(y), norm(Z) = 2.3e+03, 4.7e+01, 2.5e+01
norm(A), norm(b), norm(C) = 1.0e+04, 3.1e+03, 4.4e+01
Total CPU time (secs)   = 0.18
CPU time per iteration = 0.01
termination code        = -5
DIMACS errors: 2.1e-07  0.0e+00  7.9e-12  0.0e+00  -1.9e-05  8.6e-08

```

ans =

12.5897

Iteration 6 Total error is: 0.072723

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 48

```

SDPT3: Infeasible path-following algorithms

version predcorr gam expon scale_data

HKM 1 0.000 1 0

it	pstep	dstep	pinfeas	dinfeas	gap	prim-obj	dual-obj	cputime				
0	0.000	0.000	1.0e+00	2.3e+02	1.0e+07	-6.535914e+02	0.000000e+00	0:0:00	chol	1	1	
1	0.984	0.944	1.6e-02	1.3e+01	5.6e+05	-1.520224e+01	3.943929e+03	0:0:00	chol	1	1	
2	1.000	0.947	2.7e-07	7.1e-01	3.3e+04	2.308870e+00	-1.485690e+02	0:0:00	chol	2	2	
3	1.000	0.992	5.5e-07	9.4e-03	5.4e+02	6.482571e-01	-9.819828e+00	0:0:00	chol	2	2	
4	0.930	0.997	4.1e-08	1.3e-03	6.2e+01	-7.597703e+00	-8.218862e+00	0:0:00	chol	2	2	
5	0.429	0.357	2.3e-08	9.8e-04	4.3e+01	-8.810534e+00	-8.571250e+00	0:0:00	chol	2	2	
6	0.217	0.511	5.0e-08	5.4e-04	2.4e+01	-9.467315e+00	-9.548832e+00	0:0:00	chol	2	2	
7	0.186	0.652	4.2e-08	2.1e-04	1.1e+01	-1.022452e+01	-1.053262e+01	0:0:00	chol	3	3	
8	0.764	0.625	4.9e-08	8.5e-05	5.2e+00	-1.084952e+01	-1.165816e+01	0:0:00	chol	3	3	
9	0.839	0.743	1.3e-08	2.4e-05	2.1e+00	-1.138647e+01	-1.225364e+01	0:0:00	chol	2	3	
10	0.678	0.628	5.7e-09	9.6e-06	1.0e+00	-1.184713e+01	-1.244338e+01	0:0:00	chol	3	3	
11	0.790	0.868	1.7e-09	1.5e-06	3.9e-01	-1.220522e+01	-1.253102e+01	0:0:00	chol	3	3	
12	0.828	1.000	1.3e-09	8.4e-08	1.5e-01	-1.237805e+01	-1.252760e+01	0:0:00	chol	4	4	
13	1.000	1.000	1.2e-08	2.5e-08	4.6e-02	-1.247268e+01	-1.251788e+01	0:0:00	chol	5	4	
14	0.895	0.941	8.1e-09	9.0e-09	5.3e-03	-1.250332e+01	-1.250817e+01	0:0:00	chol	6	8	
15	0.946	0.981	3.1e-08	3.0e-09	4.1e-04	-1.250707e+01	-1.250727e+01	0:0:00	chol			
linsysolve: Schur complement matrix not positive definite												
switch to LU factor. lu 30 6												
16	0.965	0.978	2.3e-08	1.1e-10	1.5e-05	-1.250743e+01	-1.250729e+01	0:0:00	lu	25	^ 9	
17	1.000	0.856	2.1e-08	2.1e-11	2.2e-06	-1.250734e+01	-1.250729e+01	0:0:00				
stop: max(relative gap, infeasibilities) < 1.00e-07												

number of iterations = 17

```

primal objective value = -1.25073436e+01
dual   objective value = -1.25072866e+01
gap := trace(XZ)       = 2.19e-06
relative gap           = 8.43e-08
actual relative gap    = -2.19e-06
rel. primal infeas     = 2.14e-08
rel. dual   infeas     = 2.12e-11
norm(X), norm(y), norm(Z) = 2.2e+03, 4.8e+01, 2.5e+01
norm(A), norm(b), norm(C) = 1.0e+04, 3.6e+03, 4.4e+01
Total CPU time (secs)   = 0.12
CPU time per iteration = 0.01
termination code        = 0
DIMACS errors: 3.5e-08  0.0e+00  2.9e-11  0.0e+00  -2.2e-06  8.4e-08
-----

```

```
ans =
```

```
12.5073
```

```
Iteration 7 Total error is: 0.07249
```

```

num. of constraints = 33
dim. of socp var = 34, num. of socp blk = 1
dim. of linear var = 48

```

```
*****
```

```
SDPT3: Infeasible path-following algorithms
```

```
*****
```

```
version predcorr gam expon scale_data
```

```
HKM 1 0.000 1 0
```

```
it pstep dstep pinfeas dinfeas gap prim-obj dual-obj cputime
```

```

-----
0|0.000|0.000|1.0e+00|2.3e+02|1.0e+07|-6.541606e+02 0.000000e+00| 0:0:00| chol 1 1
1|0.984|0.944|1.6e-02|1.3e+01|5.8e+05|-1.520379e+01 3.970614e+03| 0:0:00| chol 2 2
2|1.000|0.946|2.7e-07|7.1e-01|3.4e+04| 2.571215e+00 -1.596684e+02| 0:0:00| chol 2 2
3|1.000|0.992|2.6e-07|9.5e-03|5.6e+02| 8.971267e-01 -9.844400e+00| 0:0:00| chol 2 2
4|0.930|0.996|2.1e-08|1.3e-03|6.4e+01|-7.449916e+00 -8.122106e+00| 0:0:00| chol 2 2
5|0.432|0.363|2.2e-08|9.7e-04|4.4e+01|-8.695900e+00 -8.484871e+00| 0:0:00| chol 2 2
6|0.217|0.510|1.5e-08|5.4e-04|2.5e+01|-9.361995e+00 -9.468768e+00| 0:0:00| chol 2 2
7|0.184|0.647|1.4e-08|2.1e-04|1.1e+01|-1.012958e+01 -1.045679e+01| 0:0:00| chol 3 3
8|0.768|0.626|1.1e-08|8.6e-05|5.4e+00|-1.076058e+01 -1.161437e+01| 0:0:00| chol 3 3
9|0.855|0.758|3.6e-09|2.3e-05|2.1e+00|-1.131303e+01 -1.223204e+01| 0:0:00| chol 3 3
10|0.678|0.663|4.6e-09|8.4e-06|1.0e+00|-1.179400e+01 -1.241896e+01| 0:0:00| chol 3 3
11|0.966|0.988|1.8e-09|3.8e-07|2.5e-01|-1.226357e+01 -1.249610e+01| 0:0:00| chol 4 3
12|1.000|1.000|1.2e-09|8.4e-08|8.7e-02|-1.239115e+01 -1.247557e+01| 0:0:00| chol 4 4
13|0.920|0.967|1.0e-08|2.7e-08|1.0e-02|-1.245199e+01 -1.246164e+01| 0:0:00| chol 6 6
14|0.860|0.973|2.7e-08|8.5e-09|1.8e-03|-1.245894e+01 -1.246034e+01| 0:0:00| chol 17 15
15|1.000|0.975|2.3e-07|7.8e-10|5.8e-04|-1.245943e+01 -1.246048e+01| 0:0:00| chol
linsysolve: Schur complement matrix not positive definite
switch to LU factor. lu 11 ^20
16|0.715|0.709|7.3e-07|7.1e-10|1.6e-04|-1.245895e+01 -1.246037e+01| 0:0:00| lu 25 ^ 3
17|0.229|1.000|5.5e-07|4.1e-10|1.4e-04|-1.245946e+01 -1.246037e+01| 0:0:00| lu 30 30
18|0.538|0.653|2.9e-07|4.3e-10|9.7e-05|-1.245938e+01 -1.246036e+01| 0:0:00| lu 21 ^ 9
19|0.596|1.000|2.3e-07|1.9e-10|6.2e-05|-1.245887e+01 -1.246035e+01| 0:0:00| lu 11 ^ 6
20|0.047|0.086|2.1e-07|3.6e-10|6.4e-05|-1.245900e+01 -1.246035e+01| 0:0:00| lu 22 ^ 7
21|0.092|0.255|1.8e-07|4.5e-10|6.2e-05|-1.245888e+01 -1.246035e+01| 0:0:00|

```



```
stop: progress is bad
-----
number of iterations    = 21
primal objective value = -1.24588726e+01
dual   objective value = -1.24603530e+01
gap := trace(XZ)       = 6.23e-05
relative gap           = 2.40e-06
actual relative gap    = 5.71e-05
rel. primal infeas     = 2.32e-07
rel. dual   infeas     = 1.85e-10
norm(X), norm(y), norm(Z) = 2.1e+03, 4.8e+01, 2.5e+01
norm(A), norm(b), norm(C) = 1.0e+04, 3.6e+03, 4.4e+01
Total CPU time (secs)   = 0.16
CPU time per iteration = 0.01
termination code        = -5
DIMACS errors: 3.8e-07  0.0e+00  2.5e-10  0.0e+00  5.7e-05  2.4e-06
-----
```

```
ans =
```

```
12.4604
```

```
Iteration    8    Total error is: 0.072346
```

```
The total representation error of the testing signals is: 0.33288
```

```
>>
```