

```
>> demo_Polynomial_Dictionary_Learning
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```
Starting to train the dictionary
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```
solving the quadratic problem with YALMIP...
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```
num. of constraints = 65
```

```
dim. of socp var = 66, num. of socp blk = 1
```

```
dim. of linear var = 800
```

```
*****
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```
SDPT3: Infeasible path-following algorithms
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*****
```

```
version predcorr gam expon scale_data
```

```
HKM 1 0.000 1 0
```

```
it pstep dstep pinfeas dinfeas gap prim-obj dual-obj cputime
```

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```

0	0.000	0.000	1.0e+00	3.5e+01	5.9e+06	2.997384e+04	0.000000e+00	0:0:00	chol	1✓	
1	1										
1	1	1.000	0.998	2.1e-07	1.9e-01	6.3e+04	3.086335e+04	-2.152907e+01	0:0:00	chol	1✓
1	2	1.000	1.000	5.0e-08	3.3e-02	7.4e+03	6.283172e+03	-1.464232e+01	0:0:00	chol	1✓
1	3	0.999	0.998	1.0e-08	3.4e-03	1.6e+02	1.418049e+02	-1.490592e+01	0:0:00	chol	1✓
1	4	0.543	0.651	1.3e-07	1.4e-03	1.3e+02	1.139315e+02	-1.420884e+01	0:0:00	chol	1✓
1	5	0.759	1.000	3.2e-08	3.3e-05	9.4e+01	7.999336e+01	-1.392916e+01	0:0:00	chol	1✓
1	6	1.000	1.000	1.4e-10	3.3e-06	5.1e+01	3.701571e+01	-1.363776e+01	0:0:00	chol	1✓
1	7	1.000	1.000	6.6e-11	3.3e-07	1.9e+01	5.726597e+00	-1.350322e+01	0:0:00	chol	1✓
1	8	1.000	1.000	2.5e-11	3.3e-08	8.2e+00	-5.206812e+00	-1.339794e+01	0:0:00	chol	1✓
2	9	1.000	1.000	8.9e-12	3.3e-09	1.2e+00	-1.214422e+01	-1.336580e+01	0:0:00	chol	1✓
2	10	1.000	1.000	2.0e-13	3.3e-10	2.5e-01	-1.311472e+01	-1.336053e+01	0:0:00	chol	2✓
2	11	0.972	0.973	6.5e-13	4.2e-11	7.2e-03	-1.335288e+01	-1.336010e+01	0:0:00	chol	2✓
3	12	0.976	0.991	1.3e-12	4.7e-12	1.7e-04	-1.335992e+01	-1.336009e+01	0:0:00	chol	3✓
5	13	0.982	1.000	3.5e-11	1.0e-12	1.8e-05	-1.336008e+01	-1.336009e+01	0:0:00	chol	5✓
	14	1.000	1.000	2.6e-10	1.5e-12	2.4e-06	-1.336009e+01	-1.336009e+01	0:0:00		

```
stop: max(relative gap, infeasibilities) < 1.00e-07
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```

```
number of iterations = 14
```

```
primal objective value = -1.33600905e+01
```

```
dual objective value = -1.33600928e+01
```

```
gap := trace(XZ) = 2.36e-06
```

```
relative gap = 8.52e-08
```

```
actual relative gap = 8.36e-08
```

```
rel. primal infeas = 2.63e-10
```

```
rel. dual infeas = 1.50e-12
```

```
norm(X), norm(y), norm(Z) = 2.8e+01, 9.0e+01, 5.7e+01
```

ans =

13.3601

```
num. of constraints = 65
dim. of socp var = 66,   num. of socp blk = 1
dim. of linear var = 800
```

SDPT3: Infeasible path-following algorithms

version	predcorr	gam	expon	scale_data
HKM	1	0.000	1	0

it	pstep	dstep	pinfeas	dinfeas	gap	prim-obj	dual-obj	cputime
----	-------	-------	---------	---------	-----	----------	----------	---------

0	0.000 0.000 1.0e+00 3.5e+01 9.9e+06	5.076538e+04	0.000000e+00	0:0:00	chol	1✓
1	1 1.000 0.997 1.9e-07 2.0e-01 1.1e+05	5.163992e+04	-2.652020e+01	0:0:00	chol	1✓
1	2 1.000 1.000 3.6e-08 3.3e-02 1.3e+04	1.109740e+04	-1.205468e+01	0:0:00	chol	1✓
1	3 0.988 0.982 7.4e-09 1.0e-02 2.9e+02	2.626010e+02	-1.156746e+01	0:0:00	chol	1✓
1	4 0.434 0.686 4.7e-08 3.9e-03 2.5e+02	2.340635e+02	-9.491848e+00	0:0:00	chol	1✓
1	5 0.482 1.000 2.5e-08 1.0e-04 2.1e+02	2.003962e+02	-9.688244e+00	0:0:00	chol	1✓
1	6 1.000 1.000 1.4e-10 1.0e-05 1.3e+02	1.221614e+02	-8.224646e+00	0:0:00	chol	1✓
1	7 0.909 1.000 6.1e-11 1.0e-06 4.7e+01	3.906929e+01	-7.509622e+00	0:0:00	chol	1✓
1	8 1.000 1.000 3.8e-11 1.0e-07 2.6e+01	1.914710e+01	-7.094378e+00	0:0:00	chol	1✓
1	9 1.000 1.000 9.5e-12 1.0e-08 7.7e+00	7.637508e-01	-6.902895e+00	0:0:00	chol	1✓
1	10 1.000 1.000 2.0e-14 1.0e-09 3.3e+00	-3.453657e+00	-6.794262e+00	0:0:00	chol	1✓
1	11 0.954 1.000 1.5e-12 1.0e-10 8.2e-01	-5.940444e+00	-6.760703e+00	0:0:00	chol	1✓
1	12 1.000 1.000 1.3e-11 1.1e-11 3.9e-01	-6.360595e+00	-6.753642e+00	0:0:00	chol	1✓
1	13 0.961 1.000 2.0e-11 2.5e-12 5.0e-02	-6.700275e+00	-6.750523e+00	0:0:00	chol	2✓
2	14 0.964 1.000 1.7e-12 2.3e-12 5.7e-03	-6.744696e+00	-6.750362e+00	0:0:00	chol	2✓
2	15 0.973 0.983 4.3e-11 1.0e-12 2.6e-04	-6.750091e+00	-6.750351e+00	0:0:00	chol	3✓
3						

```

16|1.000|1.000|1.4e-11|1.5e-12|8.1e-06|-6.750342e+00 -6.750350e+00| 0:0:00| chol 5✓
5
17|1.000|1.000|3.4e-11|2.3e-12|1.0e-07|-6.750350e+00 -6.750350e+00| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07

```

```

-----
number of iterations    = 17
primal objective value = -6.75035034e+00
dual   objective value = -6.75035044e+00
gap := trace(XZ)        = 1.01e-07
relative gap           = 6.95e-09
actual relative gap    = 6.89e-09
rel. primal infeas     = 3.40e-11
rel. dual   infeas     = 2.25e-12
norm(X), norm(y), norm(Z) = 3.2e+01, 9.6e+01, 6.7e+01
norm(A), norm(b), norm(C) = 4.4e+02, 6.4e+02, 7.7e+01
Total CPU time (secs)    = 0.16
CPU time per iteration   = 0.01
termination code         = 0
DIMACS errors: 7.4e-11  0.0e+00  3.2e-12  0.0e+00  6.9e-09  7.0e-09
-----

```

```
ans =
```

```
6.7504
```

```
Iteration    2    Total error is: 0.010574
```

```

num. of constraints = 65
dim. of socp var   = 66,   num. of socp blk = 1
dim. of linear var = 800

```

```
*****
```

```
SDPT3: Infeasible path-following algorithms
```

```
*****
```

```
version predcorr gam expon scale_data
```

```
HKM      1      0.000  1      0
```

```
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
```

```

-----
0|0.000|0.000|1.0e+00|3.5e+01|8.2e+06| 4.154641e+04  0.000000e+00| 0:0:00| chol 1✓
1
1|1.000|0.997|2.6e-07|2.1e-01|9.1e+04| 4.231931e+04 -2.287971e+01| 0:0:00| chol 1✓
1
2|1.000|1.000|7.5e-08|3.3e-02|1.2e+04| 1.039207e+04 -1.375499e+01| 0:0:00| chol 1✓
1
3|0.988|0.980|1.4e-08|1.0e-02|2.7e+02| 2.451877e+02 -1.306875e+01| 0:0:00| chol 1✓
1
4|0.382|0.587|6.4e-08|4.9e-03|2.4e+02| 2.221855e+02 -1.018967e+01| 0:0:00| chol 1✓
1
5|0.324|1.000|4.3e-08|1.0e-04|2.1e+02| 2.040604e+02 -1.032818e+01| 0:0:00| chol 1✓
1
6|1.000|1.000|9.3e-11|1.0e-05|1.4e+02| 1.320793e+02 -7.780091e+00| 0:0:00| chol 1✓
1
7|0.889|1.000|2.8e-11|1.0e-06|6.2e+01| 5.494654e+01 -6.615924e+00| 0:0:00| chol 1✓
1
8|1.000|1.000|9.2e-12|1.0e-07|3.4e+01| 2.896662e+01 -5.467403e+00| 0:0:00| chol 1✓

```

```

1
 9|1.000|1.000|3.3e-12|1.0e-08|1.4e+01| 8.811697e+00 -5.172585e+00| 0:0:00| chol 1✓
1
10|1.000|1.000|1.7e-13|1.0e-09|5.9e+00| 1.098788e+00 -4.767015e+00| 0:0:00| chol 1✓
1
11|1.000|1.000|2.4e-13|1.0e-10|1.3e+00|-3.418061e+00 -4.671148e+00| 0:0:00| chol 1✓
1
12|1.000|1.000|7.3e-12|1.1e-11|4.4e-01|-4.201998e+00 -4.645711e+00| 0:0:00| chol 1✓
1
13|0.954|0.962|4.2e-11|2.8e-12|3.0e-02|-4.609753e+00 -4.639675e+00| 0:0:00| chol 2✓
2
14|0.925|0.954|3.5e-12|2.4e-12|2.7e-03|-4.636756e+00 -4.639423e+00| 0:0:00| chol 2✓
2
15|0.956|0.997|1.8e-11|1.0e-12|3.0e-04|-4.639111e+00 -4.639407e+00| 0:0:00| chol 2✓
3
16|1.000|1.000|2.0e-11|1.5e-12|9.7e-06|-4.639396e+00 -4.639406e+00| 0:0:00| chol 4✓
4
17|1.000|1.000|1.8e-11|2.3e-12|1.6e-07|-4.639405e+00 -4.639406e+00| 0:0:00|
  stop: max(relative gap, infeasibilities) < 1.00e-07

```

```

-----
number of iterations    = 17
primal objective value = -4.63940543e+00
dual  objective value = -4.63940560e+00
gap := trace(XZ)       = 1.62e-07
relative gap           = 1.58e-08
actual relative gap    = 1.57e-08
rel. primal infeas     = 1.81e-11
rel. dual  infeas     = 2.25e-12
norm(X), norm(y), norm(Z) = 3.4e+01, 9.8e+01, 6.9e+01
norm(A), norm(b), norm(C) = 4.4e+02, 4.9e+02, 7.7e+01
Total CPU time (secs)   = 0.14
CPU time per iteration = 0.01
termination code        = 0
DIMACS errors: 5.0e-11  0.0e+00  3.2e-12  0.0e+00  1.6e-08  1.6e-08
-----

```

ans =

4.6394

Iteration 3 Total error is: 0.0087495

```

num. of constraints = 65
dim. of socp var   = 66,   num. of socp blk = 1
dim. of linear var = 800
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000  1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|3.5e+01|8.0e+06| 4.090737e+04  0.000000e+00| 0:0:00| chol 1✓
1

```

```

1|1.000|0.997|2.4e-07|2.2e-01|9.0e+04| 4.167232e+04 -2.398110e+01| 0:0:00| chol 1✓
1
2|1.000|1.000|6.8e-08|3.3e-02|1.2e+04| 1.035715e+04 -1.470397e+01| 0:0:00| chol 1✓
1
3|0.986|0.978|1.3e-08|1.0e-02|3.0e+02| 2.697670e+02 -1.397105e+01| 0:0:00| chol 1✓
1
4|0.349|0.631|6.0e-08|4.5e-03|2.7e+02| 2.483728e+02 -9.999848e+00| 0:0:00| chol 1✓
1
5|0.313|1.000|4.1e-08|1.0e-04|2.4e+02| 2.295980e+02 -1.068653e+01| 0:0:00| chol 1✓
1
6|1.000|1.000|8.1e-11|1.0e-05|1.4e+02| 1.356394e+02 -6.637903e+00| 0:0:00| chol 1✓
1
7|0.822|1.000|3.3e-11|1.0e-06|7.9e+01| 7.362034e+01 -5.794157e+00| 0:0:00| chol 1✓
1
8|1.000|1.000|6.1e-12|1.0e-07|4.1e+01| 3.758137e+01 -3.789149e+00| 0:0:00| chol 1✓
1
9|1.000|1.000|3.7e-12|1.0e-08|1.9e+01| 1.607060e+01 -3.415357e+00| 0:0:00| chol 1✓
1
10|1.000|1.000|1.1e-13|1.0e-09|8.2e+00| 5.576825e+00 -2.619862e+00| 0:0:00| chol 1✓
1
11|1.000|1.000|4.5e-14|1.0e-10|2.6e+00| 1.373247e-01 -2.453626e+00| 0:0:00| chol 1✓
1
12|1.000|1.000|6.3e-12|1.1e-11|9.5e-01|-1.410323e+00 -2.357798e+00| 0:0:00| chol 1✓
1
13|0.947|0.862|6.7e-12|3.6e-12|1.3e-01|-2.211623e+00 -2.337688e+00| 0:0:00| chol 2✓
2
14|1.000|0.981|1.1e-13|1.5e-12|2.2e-02|-2.311834e+00 -2.333883e+00| 0:0:00| chol 2✓
1
15|0.979|0.978|1.7e-11|1.0e-12|4.8e-04|-2.333137e+00 -2.333612e+00| 0:0:00| chol 2✓
2
16|0.987|0.990|3.9e-12|1.5e-12|1.9e-05|-2.333586e+00 -2.333605e+00| 0:0:00| chol 3✓
3
17|0.980|1.000|6.9e-12|1.0e-12|1.5e-06|-2.333603e+00 -2.333605e+00| 0:0:00| chol 8✓
8
18|1.000|1.000|1.9e-10|1.4e-12|1.4e-07|-2.333604e+00 -2.333605e+00| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07

```

```

-----
number of iterations    = 18
primal objective value = -2.33360443e+00
dual  objective value = -2.33360458e+00
gap := trace(XZ)       = 1.44e-07
relative gap           = 2.54e-08
actual relative gap    = 2.66e-08
rel. primal infeas     = 1.95e-10
rel. dual  infeas     = 1.38e-12
norm(X), norm(y), norm(Z) = 3.4e+01, 9.9e+01, 7.0e+01
norm(A), norm(b), norm(C) = 4.4e+02, 5.1e+02, 7.7e+01
Total CPU time (secs)  = 0.13
CPU time per iteration = 0.01
termination code       = 0
DIMACS errors: 4.7e-10  0.0e+00  2.0e-12  0.0e+00  2.7e-08  2.5e-08
-----

```

ans =

2.3336

Iteration 4 Total error is: 0.0061638

```

num. of constraints = 65
dim. of socp var = 66, num. of socp blk = 1
dim. of linear var = 800

```

SDPT3: Infeasible path-following algorithms

```

version predcorr gam expon scale_data
HKM      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|3.5e+01|8.0e+06| 4.073492e+04  0.000000e+00| 0:0:00| chol 1✓
1
1|1.000|0.994|2.2e-07|3.0e-01|1.1e+05| 4.149764e+04 -2.042379e+01| 0:0:00| chol 1✓
1
2|1.000|1.000|7.2e-08|3.3e-02|1.8e+04| 1.548179e+04 -1.881862e+01| 0:0:00| chol 1✓
1
3|0.990|0.986|9.7e-09|1.0e-02|3.6e+02| 3.251168e+02 -1.629305e+01| 0:0:00| chol 1✓
1
4|0.444|0.466|6.3e-08|6.0e-03|3.1e+02| 2.880090e+02 -1.194070e+01| 0:0:00| chol 1✓
1
5|0.334|1.000|4.2e-08|1.0e-04|2.7e+02| 2.652981e+02 -8.825748e+00| 0:0:00| chol 1✓
1
6|1.000|1.000|1.1e-10|1.0e-05|2.1e+02| 1.989595e+02 -8.463550e+00| 0:0:00| chol 1✓
1
7|1.000|1.000|1.5e-11|1.0e-06|9.5e+01| 8.934406e+01 -5.273323e+00| 0:0:00| chol 1✓
1
8|1.000|1.000|8.2e-12|1.0e-07|4.2e+01| 3.895369e+01 -2.729853e+00| 0:0:00| chol 1✓
1
9|1.000|1.000|4.3e-12|1.0e-08|2.2e+01| 1.960356e+01 -2.084957e+00| 0:0:00| chol 1✓
1
10|1.000|1.000|2.0e-14|1.0e-09|7.8e+00| 6.530663e+00 -1.235167e+00| 0:0:00| chol 1✓
1
11|1.000|1.000|2.4e-13|1.0e-10|2.6e+00| 1.570691e+00 -1.020605e+00| 0:0:00| chol 1✓
1
12|1.000|1.000|1.1e-12|1.1e-11|6.6e-01|-2.579684e-01 -9.213059e-01| 0:0:00| chol 1✓
1
13|0.921|0.932|1.5e-12|2.7e-12|1.2e-01|-7.907697e-01 -9.079180e-01| 0:0:00| chol 1✓
2
14|1.000|0.984|3.1e-13|1.1e-12|2.3e-02|-8.824437e-01 -9.059023e-01| 0:0:00| chol 2✓
2
15|0.945|0.943|1.8e-12|1.1e-12|2.9e-03|-9.027637e-01 -9.056468e-01| 0:0:00| chol 2✓
2
16|1.000|1.000|6.9e-12|1.0e-12|6.4e-04|-9.049887e-01 -9.056257e-01| 0:0:00| chol 3✓
3
17|1.000|1.000|3.1e-11|1.4e-12|2.3e-04|-9.053962e-01 -9.056231e-01| 0:0:00| chol 3✓
3
18|1.000|1.000|1.6e-11|2.1e-12|3.2e-05|-9.055900e-01 -9.056219e-01| 0:0:00| chol 4✓
4
19|1.000|1.000|3.2e-11|3.1e-12|2.9e-06|-9.056189e-01 -9.056218e-01| 0:0:00| chol 6✓

```

```
5
20|1.000|1.000|5.0e-11|4.6e-12|5.1e-08|-9.056217e-01 -9.056217e-01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
```

```
-----
number of iterations    = 20
primal objective value = -9.05621693e-01
dual   objective value = -9.05621745e-01
gap := trace(XZ)        = 5.05e-08
relative gap            = 1.80e-08
actual relative gap     = 1.83e-08
rel. primal infeas      = 5.01e-11
rel. dual   infeas      = 4.65e-12
norm(X), norm(y), norm(Z) = 3.5e+01, 1.0e+02, 7.2e+01
norm(A), norm(b), norm(C) = 4.6e+02, 5.6e+02, 7.7e+01
Total CPU time (secs)    = 0.16
CPU time per iteration   = 0.01
termination code         = 0
DIMACS errors: 1.1e-10  0.0e+00  6.7e-12  0.0e+00  1.8e-08  1.8e-08
-----
```

```
ans =
```

```
0.9056
```

```
Iteration    5    Total error is: 0.0037638
```

```
num. of constraints = 65
dim. of socp var    = 66,    num. of socp blk    = 1
dim. of linear var  = 800
```

```
*****
```

```
SDPT3: Infeasible path-following algorithms
```

```
*****
```

```
version predcorr gam expon scale_data
HKM      1      0.000  1      0
```

```
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
```

```
-----
0|0.000|0.000|1.0e+00|3.5e+01|8.1e+06| 4.142945e+04  0.000000e+00| 0:0:00| chol 1✓
1
1|1.000|0.993|2.1e-07|3.6e-01|1.2e+05| 4.217442e+04 -1.845061e+01| 0:0:00| chol 1✓
1
2|1.000|1.000|7.4e-08|3.3e-02|2.2e+04| 1.857811e+04 -2.173184e+01| 0:0:00| chol 1✓
1
3|0.991|0.987|9.4e-09|1.0e-02|4.2e+02| 3.759290e+02 -1.766790e+01| 0:0:00| chol 1✓
1
4|0.485|0.441|6.0e-08|6.2e-03|3.5e+02| 3.230836e+02 -1.315591e+01| 0:0:00| chol 1✓
1
5|0.446|0.939|3.4e-08|4.7e-04|3.0e+02| 2.896948e+02 -8.667884e+00| 0:0:00| chol 1✓
1
6|0.423|1.000|1.9e-08|1.0e-05|2.8e+02| 2.629772e+02 -1.280210e+01| 0:0:00| chol 1✓
1
7|1.000|1.000|4.0e-11|1.0e-06|1.9e+02| 1.821511e+02 -7.646150e+00| 0:0:00| chol 1✓
1
8|0.802|0.870|1.1e-11|2.2e-07|6.7e+01| 6.351851e+01 -3.827146e+00| 0:0:00| chol 1✓
1
```

```

 9|1.000|1.000|1.7e-11|1.0e-08|4.5e+01| 4.258112e+01 -2.218660e+00| 0:0:00| chol 1✓
1
10|0.904|1.000|1.6e-12|1.0e-09|1.6e+01| 1.462299e+01 -1.795184e+00| 0:0:00| chol 1✓
1
11|1.000|1.000|6.6e-14|1.0e-10|7.1e+00| 6.360099e+00 -7.265405e-01| 0:0:00| chol 1✓
1
12|1.000|1.000|7.0e-14|1.1e-11|1.8e+00| 1.288561e+00 -5.421178e-01| 0:0:00| chol 1✓
1
13|1.000|1.000|3.7e-12|2.0e-12|7.3e-01| 2.578989e-01 -4.735056e-01| 0:0:00| chol 1✓
1
14|0.948|0.864|8.7e-12|1.4e-12|8.5e-02|-3.710982e-01 -4.559420e-01| 0:0:00| chol 2✓
2
15|1.000|0.971|3.7e-13|1.5e-12|2.0e-02|-4.331684e-01 -4.531989e-01| 0:0:00| chol 2✓
2
16|0.956|0.945|2.9e-12|1.1e-12|1.1e-03|-4.518785e-01 -4.529560e-01| 0:0:00| chol 3✓
3
17|0.935|0.933|1.9e-11|1.1e-12|9.4e-05|-4.528498e-01 -4.529439e-01| 0:0:00| chol 4✓
4
18|1.000|1.000|1.2e-10|1.5e-12|1.2e-05|-4.529307e-01 -4.529431e-01| 0:0:00| chol 5✓
5
19|1.000|1.000|1.0e-10|2.3e-12|2.4e-07|-4.529428e-01 -4.529431e-01| 0:0:00| chol
linsysolve: Schur complement matrix not positive definite
switch to LU factor. lu 30 ^ 3
20|0.994|0.806|6.7e-10|3.8e-12|6.0e-09|-4.529431e-01 -4.529431e-01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07

```

```

-----
number of iterations    = 20
primal objective value = -4.52943099e-01
dual   objective value = -4.52943087e-01
gap := trace(XZ)       = 6.04e-09
relative gap           = 3.17e-09
actual relative gap    = -6.00e-09
rel. primal infeas     = 6.72e-10
rel. dual   infeas     = 3.81e-12
norm(X), norm(y), norm(Z) = 3.6e+01, 1.0e+02, 7.3e+01
norm(A), norm(b), norm(C) = 4.7e+02, 6.0e+02, 7.7e+01
Total CPU time (secs)   = 0.18
CPU time per iteration = 0.01
termination code        = 0
DIMACS errors: 1.5e-09  0.0e+00  5.5e-12  0.0e+00  -6.0e-09  3.2e-09
-----

```

ans =

0.4529

Iteration 6 Total error is: 0.0025777

```

num. of constraints = 65
dim. of socp var   = 66,   num. of socp blk = 1
dim. of linear var = 800
*****
SDPT3: Infeasible path-following algorithms
*****

```



```

version  predcorr  gam  expon  scale_data
   HKM      1      0.000   1      0
it pstep dstep pinfeas dinfeas  gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|3.5e+01|8.3e+06| 4.228693e+04  0.000000e+00| 0:0:00| chol  1✓
1
1|1.000|0.992|2.0e-07|3.8e-01|1.3e+05| 4.302749e+04 -1.844255e+01| 0:0:00| chol  1✓
1
2|1.000|1.000|7.3e-08|3.3e-02|2.4e+04| 2.032390e+04 -2.379644e+01| 0:0:00| chol  1✓
1
3|0.991|0.987|9.5e-09|1.0e-02|4.6e+02| 4.136846e+02 -1.878990e+01| 0:0:00| chol  1✓
1
4|0.505|0.442|5.8e-08|6.2e-03|3.8e+02| 3.488158e+02 -1.408017e+01| 0:0:00| chol  1✓
1
5|0.480|0.894|3.0e-08|7.4e-04|3.2e+02| 3.102779e+02 -9.335271e+00| 0:0:00| chol  1✓
1
6|0.391|1.000|1.8e-08|1.0e-05|3.0e+02| 2.837561e+02 -1.402989e+01| 0:0:00| chol  1✓
1
7|1.000|1.000|4.6e-11|1.0e-06|2.1e+02| 1.984171e+02 -8.155111e+00| 0:0:00| chol  1✓
1
8|0.804|0.883|1.3e-11|2.1e-07|7.5e+01| 7.067356e+01 -4.110138e+00| 0:0:00| chol  1✓
1
9|1.000|1.000|1.8e-11|1.0e-08|5.0e+01| 4.748399e+01 -2.314654e+00| 0:0:00| chol  1✓
1
10|0.885|1.000|2.1e-12|1.0e-09|1.9e+01| 1.675773e+01 -1.855836e+00| 0:0:00| chol  1✓
1
11|1.000|1.000|1.2e-13|1.0e-10|8.0e+00| 7.392069e+00 -6.220799e-01| 0:0:00| chol  1✓
1
12|1.000|1.000|5.0e-14|1.1e-11|2.3e+00| 1.838351e+00 -4.171888e-01| 0:0:00| chol  1✓
1
13|1.000|1.000|6.7e-13|2.0e-12|9.0e-01| 5.789460e-01 -3.213858e-01| 0:0:00| chol  1✓
1
14|0.943|0.920|5.5e-12|1.3e-12|1.3e-01|-1.643737e-01 -2.962526e-01| 0:0:00| chol  2✓
2
15|1.000|1.000|2.1e-13|1.1e-12|4.1e-02|-2.522103e-01 -2.933883e-01| 0:0:00| chol  2✓
2
16|0.952|0.970|9.5e-13|1.0e-12|2.6e-03|-2.902278e-01 -2.928764e-01| 0:0:00| chol  2✓
2
17|0.934|0.981|5.5e-12|1.0e-12|2.0e-04|-2.926523e-01 -2.928556e-01| 0:0:00| chol  3✓
3
18|0.992|1.000|1.8e-11|1.1e-12|3.3e-05|-2.928223e-01 -2.928551e-01| 0:0:00| chol  4✓
5
19|1.000|1.000|4.8e-11|1.6e-12|3.0e-06|-2.928520e-01 -2.928550e-01| 0:0:00| chol 10✓
10
20|0.998|0.999|1.4e-11|2.5e-12|3.5e-08|-2.928550e-01 -2.928550e-01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
-----
number of iterations    = 20
primal objective value  = -2.92854961e-01
dual  objective value   = -2.92855000e-01
gap := trace(XZ)        = 3.47e-08
relative gap            = 2.19e-08
actual relative gap     = 2.44e-08
rel. primal infeas      = 1.40e-11

```

```

rel. dual   infeas   = 2.46e-12
norm(X), norm(y), norm(Z) = 3.6e+01, 1.0e+02, 7.4e+01
norm(A), norm(b), norm(C) = 4.8e+02, 6.3e+02, 7.7e+01
Total CPU time (secs) = 0.13
CPU time per iteration = 0.01
termination code      = 0
DIMACS errors: 3.0e-11 0.0e+00 3.5e-12 0.0e+00 2.4e-08 2.2e-08
-----

```

```
ans =
```

```
0.2929
```

```
Iteration 7 Total error is: 0.0020061
```

```

num. of constraints = 65
dim. of socp var = 66, num. of socp blk = 1
dim. of linear var = 800
*****

```

```
SDPT3: Infeasible path-following algorithms
```

```
*****
```

version	predcorr	gam	expon	scale_data	HKM	1	0.000	1	0
it	pstep	dstep	pinfeas	dinfeas	gap	prim-obj	dual-obj	cputime	
0	0.000	0.000	1.0e+00	3.5e+01	8.4e+06	4.294106e+04	0.000000e+00	0:0:00	chol 1✓
1	1	1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1	1	1
2	1.000	1.000	7.1e-08	3.3e-02	2.6e+04	2.162055e+04	-2.541807e+01	0:0:00	chol 1✓
1	1	1	1	1	1	1	1	1	1
3	0.991	0.987	9.7e-09	1.0e-02	4.9e+02	4.423316e+02	-1.970487e+01	0:0:00	chol 1✓
1	1	1	1	1	1	1	1	1	1
4	0.521	0.445	5.6e-08	6.2e-03	4.0e+02	3.673725e+02	-1.483654e+01	0:0:00	chol 1✓
1	1	1	1	1	1	1	1	1	1
5	0.506	0.872	2.8e-08	8.8e-04	3.4e+02	3.247605e+02	-9.891467e+00	0:0:00	chol 1✓
1	1	1	1	1	1	1	1	1	1
6	0.372	1.000	1.8e-08	1.0e-05	3.1e+02	2.981878e+02	-1.503917e+01	0:0:00	chol 1✓
1	1	1	1	1	1	1	1	1	1
7	1.000	1.000	4.9e-11	1.0e-06	2.2e+02	2.093915e+02	-8.607808e+00	0:0:00	chol 1✓
1	1	1	1	1	1	1	1	1	1
8	0.802	0.884	1.4e-11	2.0e-07	8.0e+01	7.536709e+01	-4.385553e+00	0:0:00	chol 1✓
1	1	1	1	1	1	1	1	1	1
9	1.000	1.000	1.9e-11	1.0e-08	5.3e+01	5.074904e+01	-2.441480e+00	0:0:00	chol 1✓
1	1	1	1	1	1	1	1	1	1
10	0.874	1.000	2.3e-12	1.0e-09	2.0e+01	1.815881e+01	-1.938439e+00	0:0:00	chol 1✓
1	1	1	1	1	1	1	1	1	1
11	1.000	1.000	1.7e-14	1.0e-10	8.6e+00	8.041742e+00	-5.934776e-01	0:0:00	chol 1✓
1	1	1	1	1	1	1	1	1	1
12	1.000	1.000	8.5e-14	1.1e-11	2.6e+00	2.197703e+00	-3.708511e-01	0:0:00	chol 1✓
1	1	1	1	1	1	1	1	1	1
13	1.000	1.000	1.5e-12	2.0e-12	1.0e+00	7.703774e-01	-2.517114e-01	0:0:00	chol 1✓
1	1	1	1	1	1	1	1	1	1
14	0.942	0.994	2.4e-12	1.1e-12	1.7e-01	-5.203212e-02	-2.192205e-01	0:0:00	chol 2✓

```

2
15|1.000|1.000|2.4e-13|1.0e-12|6.0e-02|-1.577643e-01 -2.173614e-01| 0:0:00| chol 1✓
2
16|1.000|1.000|4.7e-13|1.0e-12|1.1e-02|-2.051136e-01 -2.165355e-01| 0:0:00| chol 2✓
2
17|0.958|0.978|1.0e-12|1.0e-12|6.7e-04|-2.157792e-01 -2.164539e-01| 0:0:00| chol 2✓
2
18|0.983|1.000|4.7e-11|1.0e-12|5.7e-05|-2.163943e-01 -2.164514e-01| 0:0:00| chol 3✓
4
19|1.000|1.000|2.0e-11|1.5e-12|5.2e-06|-2.164460e-01 -2.164512e-01| 0:0:00| chol 6✓
7
20|1.000|1.000|1.0e-11|2.3e-12|7.6e-08|-2.164511e-01 -2.164512e-01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07

```

```

-----
number of iterations    = 20
primal objective value = -2.16451123e-01
dual  objective value = -2.16451199e-01
gap := trace(XZ)        = 7.57e-08
relative gap           = 5.28e-08
actual relative gap    = 5.31e-08
rel. primal infeas     = 1.01e-11
rel. dual  infeas     = 2.25e-12
norm(X), norm(y), norm(Z) = 3.6e+01, 1.0e+02, 7.5e+01
norm(A), norm(b), norm(C) = 4.8e+02, 6.4e+02, 7.7e+01
Total CPU time (secs)   = 0.15
CPU time per iteration = 0.01
termination code        = 0
DIMACS errors: 2.2e-11  0.0e+00  3.2e-12  0.0e+00  5.3e-08  5.3e-08
-----

```

ans =

0.2165

Iteration 8 Total error is: 0.0016664

```

num. of constraints = 65
dim. of socp var   = 66,   num. of socp blk = 1
dim. of linear var = 800
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000  1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|3.5e+01|8.5e+06| 4.356961e+04  0.000000e+00| 0:0:00| chol 1✓
1
1|1.000|0.991|1.9e-07|4.1e-01|1.4e+05| 4.432901e+04 -1.836504e+01| 0:0:00| chol 1✓
1
2|1.000|1.000|6.9e-08|3.3e-02|2.7e+04| 2.258498e+04 -2.674512e+01| 0:0:00| chol 1✓
1
3|0.991|0.986|9.8e-09|1.0e-02|5.1e+02| 4.651557e+02 -2.052786e+01| 0:0:00| chol 1✓
1

```

```

4|0.534|0.448|5.5e-08|6.1e-03|4.1e+02| 3.823303e+02 -1.549261e+01| 0:0:00| chol 1✓
1
5|0.511|0.865|2.7e-08|9.1e-04|3.5e+02| 3.377952e+02 -1.035420e+01| 0:0:00| chol 1✓
1
6|0.365|1.000|1.7e-08|1.0e-05|3.3e+02| 3.105252e+02 -1.591810e+01| 0:0:00| chol 1✓
1
7|1.000|1.000|4.9e-11|1.0e-06|2.3e+02| 2.171180e+02 -9.049470e+00| 0:0:00| chol 1✓
1
8|0.799|0.873|1.4e-11|2.1e-07|8.3e+01| 7.873724e+01 -4.628097e+00| 0:0:00| chol 1✓
1
9|1.000|1.000|2.0e-11|1.0e-08|5.6e+01| 5.320081e+01 -2.562586e+00| 0:0:00| chol 1✓
1
10|0.871|1.000|2.5e-12|1.0e-09|2.1e+01| 1.909317e+01 -1.973325e+00| 0:0:00| chol 1✓
1
11|1.000|1.000|4.7e-14|1.0e-10|9.1e+00| 8.512417e+00 -5.835957e-01| 0:0:00| chol 1✓
1
12|1.000|1.000|8.9e-14|1.1e-11|2.8e+00| 2.458873e+00 -3.434438e-01| 0:0:00| chol 1✓
1
13|1.000|1.000|1.7e-13|2.0e-12|1.1e+00| 9.047694e-01 -2.048521e-01| 0:0:00| chol 1✓
1
14|0.943|1.000|3.7e-13|1.1e-12|2.0e-01| 2.850458e-02 -1.673662e-01| 0:0:00| chol 2✓
2
15|1.000|1.000|4.9e-13|1.0e-12|7.6e-02|-8.861571e-02 -1.644085e-01| 0:0:00| chol 2✓
2
16|1.000|0.999|6.7e-13|1.0e-12|1.3e-02|-1.504512e-01 -1.631495e-01| 0:0:00| chol 2✓
2
17|1.000|1.000|2.1e-12|1.0e-12|3.0e-03|-1.600421e-01 -1.630495e-01| 0:0:00| chol 2✓
2
18|1.000|0.999|1.8e-12|1.0e-12|3.7e-04|-1.626629e-01 -1.630300e-01| 0:0:00| chol 2✓
2
19|0.996|1.000|3.3e-11|1.0e-12|1.5e-05|-1.630142e-01 -1.630287e-01| 0:0:00| chol 4✓
4
20|0.998|1.000|2.7e-11|1.5e-12|2.5e-07|-1.630284e-01 -1.630287e-01| 0:0:00| chol
linsysolve: Schur complement matrix not positive definite
switch to LU factor. lu 30 30
21|0.997|0.973|2.3e-10|2.3e-12|3.3e-09|-1.630286e-01 -1.630287e-01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
-----
number of iterations    = 21
primal objective value = -1.63028639e-01
dual   objective value = -1.63028658e-01
gap := trace(XZ)       = 3.34e-09
relative gap           = 2.52e-09
actual relative gap    = 1.41e-08
rel. primal infeas     = 2.27e-10
rel. dual   infeas     = 2.29e-12
norm(X), norm(y), norm(Z) = 3.7e+01, 1.0e+02, 7.5e+01
norm(A), norm(b), norm(C) = 4.8e+02, 6.6e+02, 7.7e+01
Total CPU time (secs)  = 0.16
CPU time per iteration = 0.01
termination code       = 0
DIMACS errors: 4.9e-10 0.0e+00 3.3e-12 0.0e+00 1.4e-08 2.5e-09
-----

```

0	0.000 0.000 1.0e+00 3.5e+01 8.6e+06	4.406663e+04	0.000000e+00	0:0:00	chol	1	✓
1	1 1.000 0.991 1.9e-07 4.1e-01 1.5e+05	4.483374e+04	-1.864678e+01	0:0:00	chol	1	✓
1	2 1.000 1.000 6.7e-08 3.3e-02 2.7e+04	2.325858e+04	-2.776812e+01	0:0:00	chol	1	✓
1	3 0.991 0.986 1.0e-08 1.0e-02 5.3e+02	4.819796e+02	-2.121360e+01	0:0:00	chol	1	✓
1	4 0.543 0.449 5.4e-08 6.1e-03 4.2e+02	3.940013e+02	-1.601603e+01	0:0:00	chol	1	✓
1	5 0.504 0.863 2.7e-08 9.2e-04 3.6e+02	3.491109e+02	-1.070244e+01	0:0:00	chol	1	✓
1	6 0.366 1.000 1.7e-08 1.0e-05 3.4e+02	3.207670e+02	-1.662121e+01	0:0:00	chol	1	✓
1	7 1.000 1.000 4.7e-11 1.0e-06 2.3e+02	2.222957e+02	-9.417276e+00	0:0:00	chol	1	✓
1	8 0.795 0.858 1.4e-11 2.3e-07 8.6e+01	8.086444e+01	-4.800060e+00	0:0:00	chol	1	✓
1	9 1.000 1.000 1.8e-11 1.0e-08 5.8e+01	5.485732e+01	-2.645647e+00	0:0:00	chol	1	✓
1	10 0.873 1.000 2.3e-12 1.0e-09 2.2e+01	1.962716e+01	-1.976039e+00	0:0:00	chol	1	✓
1	11 1.000 1.000 8.8e-15 1.0e-10 9.4e+00	8.821757e+00	-5.804795e-01	0:0:00	chol	1	✓
1	12 1.000 1.000 9.0e-14 1.1e-11 2.9e+00	2.611170e+00	-3.264960e-01	0:0:00	chol	1	✓
1	13 1.000 1.000 2.9e-13 2.0e-12 1.2e+00	9.846600e-01	-1.768418e-01	0:0:00	chol	1	✓
2	14 0.945 1.000 2.5e-12 1.1e-12 2.2e-01	8.028336e-02	-1.359621e-01	0:0:00	chol	2	✓
2	15 1.000 1.000 1.8e-13 1.0e-12 8.7e-02	-4.523717e-02	-1.319393e-01	0:0:00	chol	2	✓
2	16 0.975 0.992 6.0e-13 1.0e-12 1.4e-02	-1.163007e-01	-1.302217e-01	0:0:00	chol	2	✓
2	17 1.000 1.000 2.4e-12 1.0e-12 4.7e-03	-1.254321e-01	-1.300867e-01	0:0:00	chol	2	✓
2	18 1.000 1.000 1.1e-12 1.0e-12 8.2e-04	-1.292190e-01	-1.300433e-01	0:0:00	chol	2	✓

```

19|1.000|1.000|7.5e-12|1.0e-12|2.3e-04|-1.298086e-01 -1.300395e-01| 0:0:00| chol 2✓
2
20|1.000|1.000|5.3e-11|1.5e-12|4.2e-05|-1.299960e-01 -1.300383e-01| 0:0:00| chol 3✓
3
21|1.000|1.000|3.0e-12|2.3e-12|2.5e-06|-1.300356e-01 -1.300381e-01| 0:0:00| chol 7✓
6
22|1.000|1.000|6.4e-11|1.0e-12|3.7e-08|-1.300380e-01 -1.300381e-01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07

```

```

-----
number of iterations    = 22
primal objective value = -1.30038040e-01
dual   objective value = -1.30038076e-01
gap := trace(XZ)       = 3.73e-08
relative gap           = 2.96e-08
actual relative gap    = 2.92e-08
rel. primal infeas     = 6.41e-11
rel. dual   infeas     = 1.00e-12
norm(X), norm(y), norm(Z) = 3.7e+01, 1.0e+02, 7.5e+01
norm(A), norm(b), norm(C) = 4.8e+02, 6.8e+02, 7.7e+01
Total CPU time (secs)   = 0.16
CPU time per iteration = 0.01
termination code        = 0
DIMACS errors: 1.4e-10  0.0e+00  1.4e-12  0.0e+00  2.9e-08  3.0e-08
-----

```

ans =

0.1300

Iteration 10 Total error is: 0.001169

The total representation error of the testing signals is: 0.011753