

```
>> demo_Polynomial_Dictionary_Learning
Starting to train the dictionary
solving the quadratic problem with YALMIP...
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```
num. of constraints = 65
dim. of socp var = 66, num. of socp blk = 1
dim. of linear var = 800
*****
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SDPT3: Infeasible path-following algorithms

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*****
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version	predcorr	gam	expon	scale_data							
HKM	1	0.000	1	0							
it	pstep	dstep	pinfeas	dinfeas	gap	prim-obj	dual-obj	cputime			
0	0.000	0.000	1.1e+00	3.5e+01	4.3e+06	2.221660e+04	0.000000e+00	0:0:00	chol	1✓	
1	1	1.000	0.979	6.1e-06	8.5e-01	1.2e+05	2.217331e+04	-1.135326e+02	0:0:00	chol	1✓
1	2	0.706	0.836	4.8e-06	1.7e-01	4.6e+04	2.404502e+04	-1.606244e+02	0:0:00	chol	1✓
1	3	0.845	1.000	4.8e-07	1.0e-02	1.8e+04	1.706815e+04	-1.985758e+02	0:0:00	chol	1✓
1	4	0.971	0.978	7.6e-07	3.1e-03	5.4e+02	3.426454e+02	-1.842973e+02	0:0:00	chol	1✓
1	5	0.266	0.421	9.3e-07	1.9e-03	5.0e+02	3.548399e+02	-1.381015e+02	0:0:00	chol	1✓
1	6	0.376	1.000	6.0e-07	3.0e-05	4.2e+02	3.183349e+02	-1.003525e+02	0:0:00	chol	1✓
1	7	1.000	1.000	1.5e-09	3.1e-06	2.7e+02	1.826441e+02	-8.408682e+01	0:0:00	chol	1✓
1	8	1.000	1.000	1.3e-09	3.0e-07	1.5e+02	7.447724e+01	-7.071554e+01	0:0:00	chol	1✓
1	9	0.980	1.000	3.4e-10	3.0e-08	6.0e+01	-5.085025e+00	-6.518300e+01	0:0:00	chol	1✓
1	10	1.000	1.000	1.7e-13	3.1e-09	2.8e+01	-2.881547e+01	-5.640647e+01	0:0:00	chol	1✓
1	11	1.000	1.000	2.0e-13	3.0e-10	1.1e+01	-4.318343e+01	-5.411663e+01	0:0:00	chol	1✓
1	12	1.000	1.000	1.9e-14	3.1e-11	4.0e+00	-4.840806e+01	-5.239875e+01	0:0:00	chol	1✓
1	13	1.000	1.000	2.5e-14	4.0e-12	1.4e+00	-5.048710e+01	-5.193013e+01	0:0:00	chol	1✓
1	14	1.000	1.000	2.5e-14	1.3e-12	5.4e-01	-5.113374e+01	-5.167745e+01	0:0:00	chol	1✓
1	15	1.000	1.000	4.1e-14	1.0e-12	1.7e-01	-5.143180e+01	-5.160514e+01	0:0:00	chol	1✓
1	16	1.000	1.000	4.1e-14	1.0e-12	6.8e-02	-5.150606e+01	-5.157425e+01	0:0:00	chol	1✓
1	17	1.000	1.000	3.1e-14	1.0e-12	1.9e-02	-5.154581e+01	-5.156465e+01	0:0:00	chol	1✓
1	18	1.000	1.000	1.3e-12	1.0e-12	7.5e-03	-5.155401e+01	-5.156151e+01	0:0:00	chol	1✓
1	19	0.976	0.924	4.1e-13	1.1e-12	1.6e-03	-5.155891e+01	-5.156048e+01	0:0:00	chol	2✓

```

20|0.941|1.000|1.4e-12|1.0e-12|7.1e-04|-5.155961e+01 -5.156032e+01| 0:0:00| chol 2✓
2
21|1.000|0.954|8.4e-13|1.0e-12|1.6e-04|-5.156010e+01 -5.156026e+01| 0:0:00| chol 2✓
2
22|0.844|1.000|1.6e-12|1.0e-12|6.0e-05|-5.156018e+01 -5.156024e+01| 0:0:00| chol 2✓
2
23|0.848|0.756|6.4e-13|1.2e-12|1.7e-05|-5.156023e+01 -5.156024e+01| 0:0:01| chol 2✓
2
24|0.584|0.872|1.0e-12|1.2e-12|8.4e-06|-5.156023e+01 -5.156024e+01| 0:0:01|
stop: max(relative gap, infeasibilities) < 1.00e-07

```

```

-----
number of iterations    = 24
primal objective value = -5.15602345e+01
dual  objective value = -5.15602429e+01
gap := trace(XZ)       = 8.35e-06
relative gap           = 8.02e-08
actual relative gap    = 8.02e-08
rel. primal infeas     = 1.02e-12
rel. dual  infeas     = 1.16e-12
norm(X), norm(y), norm(Z) = 9.3e-01, 5.2e+01, 2.0e+01
norm(A), norm(b), norm(C) = 6.9e+02, 1.4e+01, 7.7e+01
Total CPU time (secs)   = 0.51
CPU time per iteration = 0.02
termination code        = 0
DIMACS errors: 2.2e-12  0.0e+00  1.7e-12  0.0e+00  8.0e-08  8.0e-08
-----

```

ans =

51.5602

```

num. of constraints = 65
dim. of socp var   = 66,   num. of socp blk = 1
dim. of linear var = 800
*****
SDPT3: Infeasible path-following algorithms
*****
version  predcorr  gam  expon  scale_data
HKM      1      0.000  1      0
it pstep dstep pinfeas dinfeas  gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|3.5e+01|3.6e+07| 1.870912e+05  0.000000e+00| 0:0:00| chol 1✓
1
1|1.000|0.971|8.4e-07|1.2e+00|1.4e+06| 1.841303e+05 -1.262915e+02| 0:0:00| chol 1✓
1
2|0.663|0.757|2.3e-07|3.7e-01|6.2e+05| 2.073682e+05 -7.602518e+02| 0:0:00| chol 1✓
1
3|0.645|0.636|1.1e-07|1.6e-01|3.9e+05| 2.049981e+05 -1.200886e+03| 0:0:00| chol 1✓
1
4|0.456|0.874|7.5e-08|4.1e-02|2.3e+05| 1.830723e+05 -1.739780e+03| 0:0:00| chol 1✓
1
5|1.000|1.000|2.0e-08|1.2e-02|6.2e+04| 5.620726e+04 -1.664942e+03| 0:0:00| chol 1✓
1

```

```

6|0.739|0.680|1.1e-08|6.0e-03|3.3e+04| 3.052331e+04 -1.192361e+03| 0:0:00| chol 1✓
1
7|1.000|1.000|5.0e-09|1.0e-03|2.2e+04| 2.110984e+04 -9.217236e+02| 0:0:00| chol 1✓
1
8|1.000|1.000|3.1e-10|3.1e-04|1.1e+04| 1.078950e+04 -5.607489e+02| 0:0:00| chol 1✓
1
9|1.000|1.000|9.8e-11|9.3e-05|6.0e+03| 5.556445e+03 -4.591493e+02| 0:0:00| chol 1✓
1
10|1.000|1.000|1.4e-11|2.8e-05|2.7e+03| 2.511482e+03 -2.129753e+02| 0:0:00| chol 1✓
1
11|1.000|1.000|6.3e-12|2.8e-06|1.2e+03| 1.045982e+03 -1.640785e+02| 0:0:00| chol 1✓
1
12|1.000|1.000|6.8e-13|2.8e-07|5.1e+02| 4.297270e+02 -8.318792e+01| 0:0:00| chol 1✓
1
13|1.000|1.000|5.4e-12|2.8e-08|1.8e+02| 1.162650e+02 -6.361477e+01| 0:0:00| chol 1✓
1
14|1.000|1.000|4.5e-14|2.8e-09|7.1e+01| 2.221647e+01 -4.886617e+01| 0:0:00| chol 1✓
1
15|0.972|1.000|4.0e-13|2.8e-10|2.1e+01|-2.271191e+01 -4.337616e+01| 0:0:00| chol 1✓
1
16|1.000|1.000|4.1e-13|2.9e-11|9.8e+00|-3.143819e+01 -4.123834e+01| 0:0:00| chol 1✓
1
17|1.000|1.000|1.2e-11|3.8e-12|3.5e+00|-3.689353e+01 -4.035223e+01| 0:0:00| chol 1✓
1
18|1.000|1.000|9.8e-12|1.8e-12|1.3e+00|-3.858920e+01 -3.989007e+01| 0:0:00| chol 1✓
2
19|1.000|1.000|2.9e-13|2.0e-12|3.8e-01|-3.934081e+01 -3.972235e+01| 0:0:00| chol 2✓
2
20|1.000|1.000|2.3e-12|1.0e-12|1.5e-01|-3.952557e+01 -3.967378e+01| 0:0:00| chol 2✓
2
21|1.000|1.000|4.3e-12|1.0e-12|4.7e-02|-3.960997e+01 -3.965727e+01| 0:0:00| chol 2✓
2
22|1.000|1.000|2.5e-12|1.0e-12|1.9e-02|-3.963365e+01 -3.965268e+01| 0:0:00| chol 2✓
2
23|0.699|1.000|8.9e-12|1.0e-12|9.8e-03|-3.964172e+01 -3.965148e+01| 0:0:00| chol 2✓
2
24|0.778|1.000|1.7e-11|1.5e-12|3.8e-03|-3.964739e+01 -3.965118e+01| 0:0:00| chol 2✓
3
25|0.957|0.911|2.9e-11|2.4e-12|9.6e-04|-3.965011e+01 -3.965107e+01| 0:0:00| chol 3✓
3
26|1.000|1.000|3.9e-11|3.4e-12|3.1e-04|-3.965072e+01 -3.965103e+01| 0:0:00| chol 3✓
3
27|0.933|1.000|9.1e-11|5.1e-12|4.3e-05|-3.965098e+01 -3.965103e+01| 0:0:00| chol 6✓
6
28|0.974|1.000|6.8e-10|7.6e-12|3.1e-06|-3.965102e+01 -3.965103e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
-----
number of iterations    = 28
primal objective value  = -3.96510224e+01
dual   objective value  = -3.96510256e+01
gap := trace(XZ)        = 3.10e-06
relative gap            = 3.86e-08
actual relative gap      = 3.95e-08
rel. primal infeas      = 6.84e-10

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rel. dual   infeas   = 7.59e-12
norm(X), norm(y), norm(Z) = 1.2e+02, 6.3e+01, 2.7e+01
norm(A), norm(b), norm(C) = 1.3e+03, 1.7e+03, 7.7e+01
Total CPU time (secs) = 0.23
CPU time per iteration = 0.01
termination code      = 0
DIMACS errors: 1.5e-09 0.0e+00 1.1e-11 0.0e+00 3.9e-08 3.9e-08
-----

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```
ans =
```

```
39.6510
```

```
Iteration 2 Total error is: 0.29954
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```

num. of constraints = 65
dim. of socp var = 66, num. of socp blk = 1
dim. of linear var = 800
*****

```

```
SDPT3: Infeasible path-following algorithms
```

```
*****
```

version	predcorr	gam	expon	scale_data	HKM	1	0.000	1	0
it	pstep	dstep	pinfeas	dinfeas	gap	prim-obj	dual-obj	cputime	
0	0.000	0.000	1.0e+00	3.5e+01	6.6e+06	3.369293e+04	0.000000e+00	0:0:00	chol 1✓
1	1.000	0.983	6.4e-06	6.9e-01	1.6e+05	3.397944e+04	-1.298120e+02	0:0:00	chol 1✓
2	0.635	0.632	1.8e-06	2.7e-01	8.7e+04	3.471000e+04	-2.034356e+02	0:0:00	chol 1✓
3	0.467	0.726	9.0e-07	8.2e-02	5.0e+04	3.393370e+04	-3.245244e+02	0:0:00	chol 1✓
4	0.729	1.000	6.0e-07	3.0e-03	2.4e+04	2.363993e+04	-3.806665e+02	0:0:00	chol 1✓
5	1.000	0.819	3.9e-08	1.3e-03	4.6e+03	4.309838e+03	-3.041767e+02	0:0:00	chol 1✓
6	0.339	1.000	5.5e-08	9.0e-05	4.2e+03	3.969303e+03	-2.296696e+02	0:0:00	chol 1✓
7	1.000	1.000	1.2e-09	9.0e-06	2.7e+03	2.500685e+03	-1.554717e+02	0:0:00	chol 1✓
8	1.000	1.000	1.1e-09	9.0e-07	1.4e+03	1.275018e+03	-1.394747e+02	0:0:00	chol 1✓
9	1.000	1.000	1.0e-10	9.0e-08	6.2e+02	5.338308e+02	-8.624635e+01	0:0:00	chol 1✓
10	1.000	1.000	2.6e-10	9.0e-09	2.8e+02	2.078331e+02	-7.698456e+01	0:0:00	chol 1✓
11	1.000	1.000	2.1e-12	9.3e-10	1.3e+02	7.013577e+01	-5.659296e+01	0:0:00	chol 1✓
12	1.000	1.000	1.1e-11	9.1e-11	4.7e+01	-4.252288e+00	-5.122151e+01	0:0:00	chol 1✓
13	1.000	1.000	1.5e-12	1.0e-11	2.0e+01	-2.643092e+01	-4.656375e+01	0:0:00	chol 1✓
14	1.000	1.000	9.7e-13	1.9e-12	6.9e+00	-3.813932e+01	-4.506448e+01	0:0:00	chol 1✓

```

1
15|1.000|1.000|3.2e-13|1.1e-12|2.7e+00|-4.146478e+01 -4.417496e+01| 0:0:00| chol 1✓
1
16|1.000|1.000|7.3e-13|1.0e-12|7.3e-01|-4.311187e+01 -4.384158e+01| 0:0:00| chol 1✓
1
17|1.000|1.000|1.2e-12|1.0e-12|2.7e-01|-4.347533e+01 -4.374594e+01| 0:0:00| chol 1✓
1
18|0.974|0.947|3.1e-12|1.1e-12|4.5e-02|-4.365556e+01 -4.370029e+01| 0:0:00| chol 2✓
2
19|0.685|0.961|1.2e-12|1.0e-12|2.3e-02|-4.367210e+01 -4.369484e+01| 0:0:00| chol 2✓
2
20|0.888|1.000|7.8e-12|1.0e-12|7.6e-03|-4.368558e+01 -4.369320e+01| 0:0:00| chol 2✓
2
21|1.000|0.828|4.3e-11|1.7e-12|3.7e-03|-4.368920e+01 -4.369289e+01| 0:0:00| chol 2✓
2
22|0.984|0.930|1.7e-11|2.4e-12|9.9e-04|-4.369158e+01 -4.369256e+01| 0:0:00| chol 2✓
2
23|0.838|0.770|6.1e-11|3.9e-12|4.7e-04|-4.369205e+01 -4.369252e+01| 0:0:00| chol 2✓
2
24|0.854|0.851|3.9e-11|5.6e-12|1.6e-04|-4.369235e+01 -4.369251e+01| 0:0:00| chol 3✓
3
25|0.951|0.898|1.5e-10|8.1e-12|3.0e-05|-4.369247e+01 -4.369250e+01| 0:0:00| chol 3✓
3
26|0.997|0.978|1.6e-10|1.2e-11|2.0e-06|-4.369250e+01 -4.369250e+01| 0:0:00|
    stop: max(relative gap, infeasibilities) < 1.00e-07

```

```

-----
number of iterations    = 26
primal objective value = -4.36924980e+01
dual   objective value = -4.36925000e+01
gap := trace(XZ)       = 1.98e-06
relative gap           = 2.24e-08
actual relative gap    = 2.24e-08
rel. primal infeas     = 1.55e-10
rel. dual   infeas     = 1.15e-11
norm(X), norm(y), norm(Z) = 2.0e+01, 5.7e+01, 2.1e+01
norm(A), norm(b), norm(C) = 6.7e+02, 1.7e+02, 7.7e+01
Total CPU time (secs)   = 0.20
CPU time per iteration = 0.01
termination code        = 0
DIMACS errors: 5.4e-10  0.0e+00  1.7e-11  0.0e+00  2.2e-08  2.2e-08
-----

```

ans =

43.6925

Iteration 3 Total error is: 0.26241

```

num. of constraints = 65
dim. of socp var   = 66,   num. of socp blk = 1
dim. of linear var = 800
*****
SDPT3: Infeasible path-following algorithms
*****

```

```

version  predcorr  gam  expon  scale_data
   HKM      1      0.000   1      0
it pstep dstep pinfeas dinfeas  gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|3.5e+01|1.2e+07| 5.986527e+04  0.000000e+00| 0:0:00| chol  1✓
1
1|1.000|0.988|4.8e-07|5.3e-01|2.4e+05| 6.076065e+04 -7.271565e+01| 0:0:00| chol  1✓
1
2|0.983|0.922|3.3e-07|7.2e-02|7.5e+04| 5.384186e+04 -1.709352e+02| 0:0:00| chol  1✓
1
3|1.000|1.000|7.0e-08|1.0e-02|1.5e+04| 1.414052e+04 -1.841013e+02| 0:0:00| chol  1✓
1
4|0.782|0.770|1.5e-07|4.6e-03|3.3e+03| 3.069519e+03 -1.421126e+02| 0:0:00| chol  1✓
1
5|0.324|1.000|1.1e-07|3.0e-04|3.0e+03| 2.851558e+03 -9.483106e+01| 0:0:00| chol  1✓
1
6|1.000|1.000|8.7e-10|3.0e-05|1.9e+03| 1.871158e+03 -7.695635e+01| 0:0:00| chol  1✓
1
7|1.000|1.000|2.2e-10|3.0e-06|8.4e+02| 7.860662e+02 -5.540613e+01| 0:0:00| chol  1✓
1
8|1.000|1.000|7.8e-11|3.0e-07|3.9e+02| 3.503802e+02 -4.391510e+01| 0:0:00| chol  1✓
1
9|1.000|1.000|1.6e-11|3.0e-08|1.7e+02| 1.391857e+02 -3.161159e+01| 0:0:00| chol  1✓
1
10|1.000|1.000|7.0e-13|3.0e-09|7.1e+01| 4.361613e+01 -2.718016e+01| 0:0:00| chol  1✓
1
11|1.000|1.000|1.8e-14|3.0e-10|3.2e+01| 8.592761e+00 -2.318971e+01| 0:0:00| chol  1✓
1
12|1.000|1.000|1.3e-14|3.1e-11|1.1e+01|-1.050633e+01 -2.186122e+01| 0:0:00| chol  1✓
1
13|1.000|1.000|2.8e-14|4.0e-12|4.6e+00|-1.626321e+01 -2.088007e+01| 0:0:00| chol  1✓
1
14|0.997|1.000|3.3e-14|1.3e-12|1.2e+00|-1.933657e+01 -2.050954e+01| 0:0:00| chol  1✓
1
15|1.000|1.000|2.2e-13|1.0e-12|4.9e-01|-1.990993e+01 -2.040217e+01| 0:0:00| chol  1✓
1
16|1.000|0.933|2.1e-13|1.1e-12|9.9e-02|-2.025092e+01 -2.035017e+01| 0:0:00| chol  1✓
1
17|0.589|0.968|4.1e-12|1.0e-12|5.4e-02|-2.028535e+01 -2.033927e+01| 0:0:00| chol  1✓
1
18|0.930|1.000|2.8e-12|1.0e-12|1.4e-02|-2.032188e+01 -2.033603e+01| 0:0:00| chol  2✓
2
19|1.000|0.924|6.5e-13|1.1e-12|4.3e-03|-2.033075e+01 -2.033502e+01| 0:0:00| chol  1✓
1
20|1.000|1.000|2.7e-11|1.0e-12|8.8e-04|-2.033363e+01 -2.033451e+01| 0:0:00| chol  2✓
2
21|0.918|0.928|1.2e-11|1.6e-12|1.4e-04|-2.033427e+01 -2.033441e+01| 0:0:00| chol  3✓
3
22|1.000|1.000|5.7e-11|2.3e-12|7.8e-05|-2.033432e+01 -2.033440e+01| 0:0:00| chol  3✓
3
23|1.000|1.000|2.8e-11|3.4e-12|2.2e-05|-2.033437e+01 -2.033439e+01| 0:0:00| chol  3✓
3
24|1.000|1.000|1.0e-11|5.1e-12|3.6e-06|-2.033439e+01 -2.033439e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07

```

```

-----
number of iterations    = 24
primal objective value = -2.03343852e+01
dual   objective value = -2.03343888e+01
gap := trace(XZ)       = 3.57e-06
relative gap           = 8.56e-08
actual relative gap    = 8.56e-08
rel. primal infeas     = 1.02e-11
rel. dual   infeas     = 5.06e-12
norm(X), norm(y), norm(Z) = 2.2e+01, 8.2e+01, 4.8e+01
norm(A), norm(b), norm(C) = 5.3e+02, 5.6e+02, 7.7e+01
Total CPU time (secs)   = 0.23
CPU time per iteration = 0.01
termination code        = 0
DIMACS errors: 3.0e-11  0.0e+00  7.2e-12  0.0e+00  8.6e-08  8.6e-08
-----

```

ans =

20.3344

Iteration 4 Total error is: 0.33308

```

num. of constraints = 65
dim. of socp var   = 66,   num. of socp blk = 1
dim. of linear var = 800
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000  1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|4.7e+01|1.2e+08| 6.372806e+05  0.000000e+00| 0:0:00| chol 1✓
1
1|1.000|0.982|8.1e-07|1.0e+00|3.4e+06| 6.250414e+05 -6.530005e+02| 0:0:00| chol 1✓
1
2|1.000|0.768|6.3e-07|2.9e-01|1.4e+06| 5.828768e+05 -1.204658e+03| 0:0:00| chol 1✓
1
3|0.427|0.600|4.1e-07|1.4e-01|9.1e+05| 5.264925e+05 -2.163369e+03| 0:0:00| chol 1✓
1
4|0.369|0.601|2.9e-07|7.0e-02|6.6e+05| 4.795080e+05 -3.292742e+03| 0:0:00| chol 1✓
1
5|0.443|0.739|1.7e-07|2.7e-02|4.7e+05| 4.035159e+05 -4.198249e+03| 0:0:00| chol 1✓
1
6|1.000|1.000|3.2e-08|5.8e-03|1.4e+05| 1.321238e+05 -3.676178e+03| 0:0:00| chol 1✓
1
7|0.847|0.878|2.9e-07|3.2e-03|8.5e+04| 8.138088e+04 -2.082704e+03| 0:0:00| chol 1✓
1
8|1.000|1.000|1.1e-07|1.4e-03|5.4e+04| 5.210236e+04 -1.766361e+03| 0:0:00| chol 1✓
1
9|1.000|1.000|1.2e-07|4.3e-04|2.1e+04| 1.973656e+04 -7.578917e+02| 0:0:00| chol 1✓
1
10|1.000|1.000|2.4e-09|1.3e-04|9.9e+03| 9.308275e+03 -5.338387e+02| 0:0:00| chol 1✓

```

```

1
11|1.000|1.000|2.6e-10|3.9e-05|4.0e+03| 3.763265e+03 -2.027160e+02| 0:0:00| chol 1✓
1
12|1.000|1.000|5.8e-10|1.2e-05|1.4e+03| 1.287134e+03 -1.209106e+02| 0:0:00| chol 1✓
1
13|1.000|1.000|2.2e-11|1.2e-06|5.8e+02| 5.105483e+02 -6.619809e+01| 0:0:00| chol 1✓
1
14|1.000|1.000|3.2e-12|1.2e-07|1.6e+02| 1.103778e+02 -4.934428e+01| 0:0:00| chol 1✓
1
15|1.000|1.000|8.2e-12|1.2e-08|7.5e+01| 3.348534e+01 -4.113568e+01| 0:0:00| chol 1✓
1
16|1.000|1.000|1.7e-11|1.2e-09|2.6e+01|-1.282791e+01 -3.842415e+01| 0:0:00| chol 1✓
1
17|1.000|1.000|1.8e-11|1.2e-10|1.3e+01|-2.432699e+01 -3.686831e+01| 0:0:00| chol 1✓
1
18|1.000|1.000|4.2e-12|1.5e-11|3.1e+00|-3.304323e+01 -3.612160e+01| 0:0:00| chol 1✓
1
19|1.000|1.000|4.9e-13|2.2e-12|1.2e+00|-3.465520e+01 -3.589674e+01| 0:0:00| chol 1✓
1
20|0.948|0.986|1.3e-11|1.1e-12|2.0e-01|-3.557871e+01 -3.577676e+01| 0:0:00| chol 1✓
1
21|1.000|1.000|1.5e-12|1.5e-12|6.0e-02|-3.569926e+01 -3.575926e+01| 0:0:00| chol 2✓
1
22|0.695|0.837|3.4e-12|1.2e-12|3.4e-02|-3.572068e+01 -3.575437e+01| 0:0:00| chol 2✓
1
23|0.767|1.000|1.1e-11|1.0e-12|2.1e-02|-3.573184e+01 -3.575291e+01| 0:0:00| chol 2✓
1
24|1.000|1.000|6.7e-12|1.5e-12|9.7e-03|-3.574161e+01 -3.575131e+01| 0:0:00| chol 1✓
1
25|1.000|1.000|1.3e-10|1.3e-12|4.5e-03|-3.574603e+01 -3.575051e+01| 0:0:00| chol 1✓
1
26|1.000|1.000|2.0e-12|2.0e-12|1.7e-03|-3.574830e+01 -3.575001e+01| 0:0:00| chol 1✓
1
27|1.000|1.000|2.6e-11|1.0e-12|6.3e-04|-3.574921e+01 -3.574983e+01| 0:0:00| chol 1✓
2
28|1.000|1.000|6.5e-13|1.5e-12|2.4e-04|-3.574952e+01 -3.574976e+01| 0:0:00| chol 2✓
1
29|1.000|1.000|5.7e-12|1.0e-12|7.3e-05|-3.574967e+01 -3.574974e+01| 0:0:00| chol 2✓
2
30|1.000|1.000|2.3e-12|1.1e-12|2.6e-05|-3.574970e+01 -3.574973e+01| 0:0:00| chol 1✓
2
31|1.000|1.000|3.8e-11|1.0e-12|5.5e-06|-3.574972e+01 -3.574973e+01| 0:0:00|
  stop: max(relative gap, infeasibilities) < 1.00e-07
-----
number of iterations    = 31
primal objective value = -3.57497221e+01
dual   objective value = -3.57497276e+01
gap := trace(XZ)       = 5.51e-06
relative gap           = 7.60e-08
actual relative gap    = 7.60e-08
rel. primal infeas     = 3.81e-11
rel. dual   infeas     = 1.00e-12
norm(X), norm(y), norm(Z) = 1.2e+01, 6.7e+01, 3.0e+01
norm(A), norm(b), norm(C) = 4.4e+03, 1.9e+03, 7.7e+01

```



```

Total CPU time (secs) = 0.28
CPU time per iteration = 0.01
termination code      = 0
DIMACS errors: 8.6e-11  0.0e+00  1.4e-12  0.0e+00  7.6e-08  7.6e-08
-----

```

ans =

35.7497

Iteration 5 Total error is: 0.26048

```

num. of constraints = 65
dim. of socp var = 66, num. of socp blk = 1
dim. of linear var = 800

```

SDPT3: Infeasible path-following algorithms

```

version predcorr gam expon scale_data

```

```

HKM      1      0.000  1      0

```

```

it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----

```

0	0.000	0.000	1.0e+00	4.5e+01	2.1e+08	1.126855e+06	0.000000e+00	0:0:00	chol	1✓	
1	1	1.000	0.978	1.5e-07	1.2e+00	6.9e+06	1.105049e+06	-1.169029e+02	0:0:00	chol	1✓
1	2	1.000	0.821	6.2e-08	2.7e-01	2.6e+06	1.110750e+06	-2.037521e+03	0:0:00	chol	1✓
1	3	0.574	0.551	4.8e-08	1.5e-01	1.7e+06	9.490569e+05	-3.448903e+03	0:0:00	chol	1✓
1	4	0.304	0.618	5.4e-08	7.0e-02	1.2e+06	8.865789e+05	-5.840456e+03	0:0:00	chol	1✓
1	5	0.448	0.636	3.0e-08	3.3e-02	9.0e+05	7.551045e+05	-7.715864e+03	0:0:00	chol	1✓
1	6	0.551	1.000	1.5e-08	5.8e-03	5.7e+05	5.415943e+05	-8.756949e+03	0:0:00	chol	1✓
1	7	1.000	0.868	2.4e-09	3.3e-03	1.1e+05	9.991031e+04	-6.702849e+03	0:0:00	chol	1✓
2	8	0.213	1.000	2.4e-09	1.4e-03	1.0e+05	9.437070e+04	-6.797548e+03	0:0:00	chol	1✓
1	9	1.000	0.786	4.4e-08	8.8e-04	6.1e+04	5.716787e+04	-3.321956e+03	0:0:00	chol	1✓
1	10	1.000	1.000	3.8e-10	3.6e-04	4.1e+04	3.851262e+04	-2.208069e+03	0:0:00	chol	1✓
1	11	1.000	1.000	9.9e-11	1.1e-04	1.7e+04	1.608697e+04	-1.283365e+03	0:0:00	chol	1✓
1	12	1.000	1.000	5.6e-11	3.2e-05	7.7e+03	7.072871e+03	-6.162598e+02	0:0:00	chol	1✓
1	13	1.000	1.000	2.2e-11	9.7e-06	3.0e+03	2.677111e+03	-2.923084e+02	0:0:00	chol	1✓
1	14	1.000	1.000	5.8e-12	2.9e-06	1.2e+03	1.044715e+03	-1.162422e+02	0:0:00	chol	1✓
1	15	1.000	1.000	6.7e-12	2.9e-07	3.8e+02	3.276359e+02	-5.250112e+01	0:0:00	chol	1✓

```

16|1.000|1.000|5.3e-12|2.9e-08|1.5e+02| 1.171417e+02 -2.842545e+01| 0:0:00| chol 1✓
1
17|1.000|1.000|2.4e-12|2.9e-09|3.5e+01| 1.564440e+01 -1.936130e+01| 0:0:00| chol 1✓
1
18|1.000|1.000|2.1e-12|2.9e-10|1.5e+01|-8.861277e-01 -1.630228e+01| 0:0:00| chol 1✓
1
19|1.000|1.000|5.2e-12|3.0e-11|4.4e+00|-1.095650e+01 -1.538158e+01| 0:0:00| chol 2✓
2
20|1.000|1.000|1.2e-12|4.0e-12|2.1e+00|-1.300234e+01 -1.506814e+01| 0:0:00| chol 2✓
2
21|0.994|1.000|7.8e-13|1.3e-12|5.7e-01|-1.434411e+01 -1.491786e+01| 0:0:00| chol 2✓
2
22|1.000|1.000|1.7e-12|1.0e-12|2.9e-01|-1.459034e+01 -1.487834e+01| 0:0:00| chol 2✓
2
23|0.994|1.000|1.4e-12|1.0e-12|7.3e-02|-1.478570e+01 -1.485900e+01| 0:0:00| chol 2✓
2
24|1.000|1.000|1.2e-12|1.0e-12|3.3e-02|-1.482185e+01 -1.485523e+01| 0:0:00| chol 2✓
2
25|1.000|1.000|2.0e-12|1.0e-12|7.0e-03|-1.484627e+01 -1.485329e+01| 0:0:00| chol 2✓
2
26|0.893|0.978|1.3e-12|1.0e-12|2.0e-03|-1.485108e+01 -1.485309e+01| 0:0:00| chol 2✓
3
27|0.961|0.852|5.6e-12|1.2e-12|1.2e-04|-1.485291e+01 -1.485303e+01| 0:0:00| chol 4✓
4
28|0.913|0.917|3.6e-10|1.2e-12|2.5e-05|-1.485300e+01 -1.485303e+01| 0:0:00| chol
linsysolve: Schur complement matrix not positive definite
switch to LU factor. lu 30 30
29|0.980|1.000|1.3e-09|1.7e-12|5.9e-06|-1.485302e+01 -1.485303e+01| 0:0:00| lu 30✓
^21
30|0.982|0.989|1.1e-09|2.5e-12|4.0e-07|-1.485303e+01 -1.485303e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07

```

```

-----
number of iterations    = 30
primal objective value = -1.48530275e+01
dual   objective value = -1.48530278e+01
gap := trace(XZ)       = 4.02e-07
relative gap           = 1.31e-08
actual relative gap    = 7.81e-09
rel. primal infeas     = 1.09e-09
rel. dual   infeas     = 2.52e-12
norm(X), norm(y), norm(Z) = 3.4e+01, 8.4e+01, 5.1e+01
norm(A), norm(b), norm(C) = 5.4e+03, 6.9e+03, 7.7e+01
Total CPU time (secs)   = 0.26
CPU time per iteration = 0.01
termination code        = 0
DIMACS errors: 2.8e-09  0.0e+00  3.6e-12  0.0e+00  7.8e-09  1.3e-08
-----

```

ans =

14.8530

Iteration 6 Total error is: 2.4679

```

num. of constraints = 65
dim. of socp var = 66, num. of socp blk = 1
dim. of linear var = 800
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000  1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|3.5e+01|6.9e+06| 3.513517e+04  0.000000e+00| 0:0:00| chol  1✓
1
1|1.000|0.994|1.5e-06|3.2e-01|9.9e+04| 3.596790e+04 -1.106016e+02| 0:0:00| chol  1✓
1
2|0.841|0.773|1.0e-06|9.9e-02|3.8e+04| 2.469455e+04 -1.334579e+02| 0:0:00| chol  1✓
1
3|0.989|1.000|3.1e-07|1.0e-02|1.3e+04| 1.187430e+04 -1.651651e+02| 0:0:00| chol  1✓
1
4|1.000|0.983|3.5e-07|3.1e-03|4.5e+03| 4.251725e+03 -1.280452e+02| 0:0:00| chol  1✓
1
5|0.415|1.000|2.1e-07|3.0e-04|3.7e+03| 3.556408e+03 -1.267546e+02| 0:0:00| chol  1✓
1
6|1.000|0.901|3.8e-09|5.6e-05|1.6e+03| 1.544520e+03 -8.534716e+01| 0:0:00| chol  1✓
1
7|1.000|1.000|1.6e-09|3.0e-06|9.5e+02| 8.782890e+02 -7.644879e+01| 0:0:00| chol  1✓
1
8|1.000|1.000|1.7e-10|3.0e-07|4.1e+02| 3.543479e+02 -5.479489e+01| 0:0:00| chol  1✓
1
9|1.000|1.000|4.7e-11|3.0e-08|1.8e+02| 1.320676e+02 -5.140019e+01| 0:0:00| chol  1✓
1
10|1.000|1.000|3.7e-14|3.0e-09|8.2e+01| 3.833080e+01 -4.378152e+01| 0:0:00| chol  1✓
1
11|1.000|1.000|2.1e-14|3.0e-10|2.8e+01|-1.262725e+01 -4.108571e+01| 0:0:00| chol  1✓
1
12|1.000|1.000|5.6e-15|3.1e-11|1.3e+01|-2.654680e+01 -3.922883e+01| 0:0:00| chol  1✓
1
13|1.000|1.000|4.2e-14|4.0e-12|3.8e+00|-3.465279e+01 -3.845047e+01| 0:0:00| chol  1✓
1
14|1.000|1.000|3.9e-14|1.3e-12|1.5e+00|-3.659136e+01 -3.814119e+01| 0:0:00| chol  1✓
1
15|1.000|1.000|2.9e-14|1.0e-12|4.3e-01|-3.755545e+01 -3.798827e+01| 0:0:00| chol  1✓
1
16|1.000|1.000|9.1e-14|1.0e-12|1.9e-01|-3.774673e+01 -3.793996e+01| 0:0:00| chol  1✓
1
17|0.986|1.000|9.1e-14|1.0e-12|4.9e-02|-3.786709e+01 -3.791642e+01| 0:0:00| chol  1✓
2
18|1.000|1.000|3.9e-13|1.0e-12|2.2e-02|-3.789123e+01 -3.791301e+01| 0:0:00| chol  1✓
1
19|0.989|0.940|2.0e-11|1.1e-12|4.6e-03|-3.790598e+01 -3.791060e+01| 0:0:00| chol  2✓
2
20|0.666|1.000|6.6e-12|1.5e-12|2.8e-03|-3.790759e+01 -3.791043e+01| 0:0:00| chol  2✓
2
21|1.000|0.978|4.5e-13|1.3e-12|7.1e-04|-3.790960e+01 -3.791031e+01| 0:0:00| chol  2✓
2

```

```

22|0.950|0.999|2.4e-12|1.0e-12|2.2e-04|-3.791007e+01 -3.791029e+01| 0:0:00| chol 2✓
2
23|0.964|1.000|5.1e-12|1.0e-12|4.8e-05|-3.791024e+01 -3.791029e+01| 0:0:00| chol 2✓
2
24|1.000|1.000|2.8e-11|1.0e-12|1.5e-05|-3.791027e+01 -3.791028e+01| 0:0:00| chol 2✓
2
25|1.000|1.000|3.9e-11|1.5e-12|1.7e-06|-3.791028e+01 -3.791028e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07

```

```

-----
number of iterations    = 25
primal objective value = -3.79102824e+01
dual   objective value = -3.79102841e+01
gap := trace(XZ)        = 1.72e-06
relative gap           = 2.24e-08
actual relative gap    = 2.24e-08
rel. primal infeas     = 3.93e-11
rel. dual   infeas     = 1.53e-12
norm(X), norm(y), norm(Z) = 6.4e+00, 5.8e+01, 2.1e+01
norm(A), norm(b), norm(C) = 5.0e+02, 1.1e+02, 7.7e+01
Total CPU time (secs)   = 0.20
CPU time per iteration = 0.01
termination code        = 0
DIMACS errors: 9.2e-11  0.0e+00  2.2e-12  0.0e+00  2.2e-08  2.2e-08
-----

```

ans =

37.9103

Iteration 7 Total error is: 0.079615

```

num. of constraints = 65
dim. of socp var = 66, num. of socp blk = 1
dim. of linear var = 800
*****

```

SDPT3: Infeasible path-following algorithms

```

version predcorr gam expon scale_data
HKM      1      0.000  1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----

```

```

0|0.000|0.000|1.0e+00|3.5e+01|9.7e+06| 4.893222e+04  0.000000e+00| 0:0:00| chol 1✓
1
1|1.000|0.998|3.0e-07|1.8e-01|9.9e+04| 5.016692e+04 -4.472065e+01| 0:0:00| chol 1✓
1
2|1.000|1.000|2.8e-08|3.3e-02|1.0e+04| 8.838600e+03 -2.627582e+01| 0:0:00| chol 1✓
1
3|0.994|1.000|1.4e-08|1.0e-02|1.8e+02| 1.489988e+02 -2.554760e+01| 0:0:00| chol 1✓
1
4|0.840|0.380|1.3e-07|6.6e-03|1.5e+02| 1.167983e+02 -2.399937e+01| 0:0:00| chol 1✓
1
5|0.450|0.520|6.9e-08|3.2e-03|1.3e+02| 1.043416e+02 -2.276622e+01| 0:0:00| chol 1✓
1
6|0.329|1.000|4.6e-08|1.0e-05|1.1e+02| 8.965394e+01 -2.426751e+01| 0:0:00| chol 1✓

```

```

1
7|1.000|1.000|2.8e-11|1.0e-06|6.3e+01| 4.058921e+01 -2.209081e+01| 0:0:00| chol 1✓
1
8|0.952|0.975|2.8e-11|1.2e-07|2.6e+01| 4.635773e+00 -2.094522e+01| 0:0:00| chol 1✓
1
9|1.000|1.000|8.5e-11|1.0e-08|1.7e+01|-3.898057e+00 -2.046305e+01| 0:0:00| chol 1✓
1
10|1.000|1.000|1.3e-13|1.0e-09|5.6e+00|-1.423650e+01 -1.982661e+01| 0:0:00| chol 1✓
1
11|1.000|1.000|5.0e-13|1.0e-10|3.0e+00|-1.653594e+01 -1.958302e+01| 0:0:00| chol 1✓
1
12|1.000|1.000|4.9e-13|1.1e-11|1.1e+00|-1.827976e+01 -1.939914e+01| 0:0:00| chol 1✓
1
13|1.000|1.000|8.6e-12|2.0e-12|3.9e-01|-1.891383e+01 -1.930875e+01| 0:0:00| chol 1✓
2
14|1.000|1.000|1.3e-12|1.6e-12|1.4e-01|-1.913992e+01 -1.928130e+01| 0:0:00| chol 2✓
1
15|1.000|1.000|1.1e-11|1.0e-12|5.7e-02|-1.921221e+01 -1.926958e+01| 0:0:00| chol 1✓
2
16|1.000|1.000|2.3e-12|1.5e-12|1.5e-02|-1.924990e+01 -1.926523e+01| 0:0:00| chol 2✓
2
17|0.673|1.000|2.4e-12|1.0e-12|8.7e-03|-1.925588e+01 -1.926461e+01| 0:0:00| chol 2✓
2
18|0.987|0.938|5.6e-12|1.1e-12|2.7e-03|-1.926160e+01 -1.926431e+01| 0:0:00| chol 2✓
2
19|0.599|0.972|1.3e-12|1.2e-12|1.5e-03|-1.926273e+01 -1.926419e+01| 0:0:00| chol 2✓
2
20|0.975|0.969|9.8e-12|1.0e-12|3.6e-04|-1.926381e+01 -1.926417e+01| 0:0:00| chol 2✓
2
21|1.000|1.000|8.9e-11|1.5e-12|8.5e-05|-1.926407e+01 -1.926416e+01| 0:0:00| chol 3✓
3
22|1.000|1.000|2.8e-11|2.3e-12|2.3e-05|-1.926413e+01 -1.926416e+01| 0:0:00| chol 3✓
4
23|1.000|1.000|3.2e-11|3.4e-12|6.4e-06|-1.926415e+01 -1.926416e+01| 0:0:00| chol 3✓
4
24|1.000|1.000|3.0e-11|5.1e-12|6.4e-07|-1.926415e+01 -1.926416e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07

```

```

-----
number of iterations    = 24
primal objective value = -1.92641550e+01
dual   objective value = -1.92641556e+01
gap := trace(XZ)       = 6.36e-07
relative gap           = 1.61e-08
actual relative gap    = 1.60e-08
rel. primal infeas     = 2.97e-11
rel. dual   infeas     = 5.06e-12
norm(X), norm(y), norm(Z) = 2.1e+01, 8.1e+01, 4.6e+01
norm(A), norm(b), norm(C) = 3.7e+02, 3.7e+02, 7.7e+01
Total CPU time (secs)  = 0.16
CPU time per iteration = 0.01
termination code       = 0
DIMACS errors: 7.0e-11  0.0e+00  7.2e-12  0.0e+00  1.6e-08  1.6e-08
-----

```

```
ans =
```

```
19.2642
```

```
Iteration    8    Total error is: 0.040532
```

```
The total representation error of the testing signals is: 0.032309
```

```
>>
```