

```

>> clear
>> learn_from_data
    [1x16 double]    [1x16 double]

Epoch... 1
Epoch... 2

num. of constraints = 33
dim. of socp var = 34,    num. of socp blk = 1
dim. of linear var = 272
*****
SDPT3: Infeasible path-following algorithms
*****
version  predcorr  gam  expon  scale_data
HKM      1      0.000  1      0

it pstep dstep pinfeas dinfeas  gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|5.1e+00|1.0e+06| 1.891756e+04  0.000000e+00| 0:0:00| chol  1  1
1|0.982|0.984|1.8e-02|1.5e-01|4.7e+04| 1.916328e+04 -1.377457e+01| 0:0:00| chol  1  1
2|1.000|1.000|4.7e-07|2.0e-02|9.6e+03| 7.625184e+03 -3.944553e+01| 0:0:00| chol  1  1
3|1.000|1.000|9.8e-08|5.9e-03|1.0e+03| 8.062740e+02 -4.469853e+01| 0:0:00| chol  1  1
4|0.785|0.784|2.9e-07|2.7e-03|5.7e+02| 4.726259e+02 -3.265245e+01| 0:0:00| chol  1  1
5|1.000|0.752|3.1e-08|1.1e-03|3.0e+02| 2.402715e+02 -2.972937e+01| 0:0:00| chol  2  2
6|0.276|0.247|7.4e-08|8.4e-04|2.7e+02| 2.007793e+02 -2.987627e+01| 0:0:00| chol  2  2
7|0.498|0.360|1.0e-07|5.6e-04|2.4e+02| 1.596517e+02 -3.401033e+01| 0:0:00| chol  2  2
8|1.000|0.380|1.0e-07|3.5e-04|2.0e+02| 1.105135e+02 -4.048878e+01| 0:0:00| chol  2  1
9|0.184|0.638|8.7e-08|1.3e-04|1.6e+02| 9.624953e+01 -4.546775e+01| 0:0:00| chol  2  2
10|0.583|0.691|3.6e-08|4.3e-05|1.1e+02| 4.925485e+01 -5.345287e+01| 0:0:00| chol  2  2
11|1.000|1.000|7.5e-10|1.8e-06|4.9e+01| -5.522912e+00 -5.413622e+01| 0:0:00| chol  2  2
12|1.000|0.945|5.6e-10|9.5e-07|9.7e+00| -4.330423e+01 -5.285821e+01| 0:0:00| chol  2  2
13|0.942|0.967|2.3e-09|4.7e-07|8.0e-01| -5.183033e+01 -5.256592e+01| 0:0:00| chol  2  2
14|0.986|0.986|1.5e-09|2.3e-07|1.2e-02| -5.259634e+01 -5.257731e+01| 0:0:00| chol  3  3
15|0.977|0.984|5.1e-08|1.1e-07|3.4e-04| -5.260726e+01 -5.259227e+01| 0:0:00| chol  3  4
16|1.000|0.928|1.6e-07|8.3e-09|1.5e-04| -5.260733e+01 -5.260648e+01| 0:0:00| chol  3  3
17|0.987|0.988|8.9e-08|1.1e-10|1.4e-05| -5.260756e+01 -5.260755e+01| 0:0:00| chol
linsysolve: Schur complement matrix not positive definite
switch to LU factor. lu 30 ^ 8
18|0.667|0.580|5.1e-07|5.6e-11|1.7e-05| -5.260798e+01 -5.260757e+01| 0:0:00| lu 30  2
19|1.000|0.639|1.0e-07|3.0e-11|1.5e-05| -5.260757e+01 -5.260757e+01| 0:0:00| lu  7  2
20|0.970|0.975|1.9e-08|2.5e-12|2.6e-06| -5.260758e+01 -5.260757e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
-----

number of iterations    = 20
primal objective value = -5.26075833e+01
dual  objective value = -5.26075673e+01
gap := trace(XZ)        = 2.63e-06
relative gap            = 2.48e-08
actual relative gap     = -1.50e-07
rel. primal infeas      = 1.94e-08
rel. dual infeas        = 2.55e-12
norm(X), norm(y), norm(Z) = 1.4e+04, 9.7e+01, 6.6e+01
norm(A), norm(b), norm(C) = 2.1e+02, 6.5e+02, 7.5e+01
Total CPU time (secs)   = 0.28
CPU time per iteration = 0.01
termination code         = 0

```

DIMACS errors: 6.4e-08 0.0e+00 3.6e-12 0.0e+00 -1.5e-07 2.5e-08

ans =

52.6076

Epoch... 3

Epoch... 4

num. of constraints = 33
dim. of socp var = 34, num. of socp blk = 1
dim. of linear var = 272

SDPT3: Infeasible path-following algorithms

version predcorr gam expon scale_data

HKM 1 0.000 1 0

it	pstep	dstep	pinfeas	dinfeas	gap	prim-obj	dual-obj	cputime				
0	0.000	0.000	1.0e+00	5.3e+00	2.6e+06	4.923447e+04	0.000000e+00	0:0:00	chol	1	1	
1	0.978	0.973	2.2e-02	2.5e-01	1.6e+05	4.655579e+04	1.979437e+01	0:0:00	chol	1	1	
2	1.000	1.000	2.3e-07	5.5e-02	4.8e+04	2.977240e+04	-8.008988e+01	0:0:00	chol	1	1	
3	1.000	0.998	3.0e-08	1.7e-02	2.7e+03	1.839171e+03	-4.916106e+01	0:0:00	chol	1	1	
4	1.000	0.716	1.8e-07	8.2e-03	1.6e+03	1.218159e+03	-3.272411e+01	0:0:00	chol	1	1	
5	0.586	0.975	7.7e-08	1.7e-03	9.9e+02	8.960248e+02	-3.252913e+01	0:0:00	chol	2	2	
6	0.936	0.595	1.4e-08	9.3e-04	5.9e+02	4.949859e+02	-2.776390e+01	0:0:00	chol	2	2	
7	0.631	0.381	7.1e-08	6.3e-04	4.8e+02	3.668555e+02	-2.830224e+01	0:0:00	chol	2	2	
8	0.794	0.541	6.6e-08	3.2e-04	3.7e+02	2.804108e+02	-3.600600e+01	0:0:00	chol	1	1	
9	0.316	0.587	4.5e-08	1.5e-04	3.2e+02	2.447114e+02	-3.964197e+01	0:0:00	chol	2	2	
10	1.000	0.856	6.1e-10	3.6e-05	1.5e+02	9.210404e+01	-4.677819e+01	0:0:00	chol	2	2	
11	0.926	0.953	1.8e-10	9.7e-06	3.1e+01	-1.639955e+01	-4.557913e+01	0:0:00	chol	2	2	
12	0.947	0.986	1.5e-10	4.3e-06	3.6e+00	-4.210573e+01	-4.516670e+01	0:0:00	chol	2	1	
13	0.509	0.784	1.8e-08	2.6e-06	2.2e+00	-4.345470e+01	-4.533321e+01	0:0:00	chol	2	2	
14	0.591	1.000	7.7e-09	1.0e-06	1.6e+00	-4.411024e+01	-4.553141e+01	0:0:00	chol	2	2	
15	1.000	1.000	6.0e-10	5.2e-07	4.6e-01	-4.517885e+01	-4.557521e+01	0:0:00	chol	2	2	
16	0.970	0.965	3.9e-10	2.7e-07	1.4e-02	-4.561272e+01	-4.559194e+01	0:0:00	chol	2	2	
17	0.992	0.987	6.9e-08	1.3e-07	4.4e-04	-4.562609e+01	-4.560927e+01	0:0:00	chol	5	5	
18	1.000	0.972	1.2e-07	3.9e-09	2.6e-04	-4.562603e+01	-4.562600e+01	0:0:00	chol	4	3	
19	1.000	0.992	6.5e-09	3.8e-11	8.2e-06	-4.562647e+01	-4.562648e+01	0:0:00				

stop: max(relative gap, infeasibilities) < 1.00e-07

number of iterations = 19
primal objective value = -4.56264722e+01
dual objective value = -4.56264769e+01
gap := trace(XZ) = 8.23e-06
relative gap = 8.92e-08
actual relative gap = 5.12e-08
rel. primal infeas = 6.50e-09
rel. dual infeas = 3.83e-11
norm(X), norm(y), norm(Z) = 1.3e+04, 1.0e+02, 7.5e+01
norm(A), norm(b), norm(C) = 3.1e+02, 1.5e+03, 7.5e+01
Total CPU time (secs) = 0.14
CPU time per iteration = 0.01
termination code = 0

DIMACS errors: 2.0e-08 0.0e+00 5.4e-11 0.0e+00 5.1e-08 8.9e-08

ans =

45.6265

Epoch... 5

Epoch... 6

num. of constraints = 33

dim. of socp var = 34, num. of socp blk = 1

dim. of linear var = 272

SDPT3: Infeasible path-following algorithms

version predcorr gam expon scale_data

HKM 1 0.000 1 0

it	pstep	dstep	pinfeas	dinfeas	gap	prim-obj	dual-obj	cputime				
0	0.000	0.000	1.0e+00	5.2e+00	2.1e+06	3.991392e+04	0.000000e+00	0:0:00	chol	1	1	
1	0.977	0.974	2.3e-02	2.4e-01	1.3e+05	3.797711e+04	1.291584e+01	0:0:00	chol	1	1	
2	1.000	1.000	2.6e-07	5.5e-02	3.7e+04	2.275727e+04	-6.219591e+01	0:0:00	chol	1	1	
3	1.000	1.000	4.0e-08	1.6e-02	2.1e+03	1.404088e+03	-3.989682e+01	0:0:00	chol	1	1	
4	0.869	0.758	1.7e-07	7.7e-03	1.3e+03	9.979431e+02	-2.797683e+01	0:0:00	chol	1	1	
5	0.838	0.977	2.9e-08	1.6e-03	7.2e+02	6.400924e+02	-2.719034e+01	0:0:00	chol	1	1	
6	0.973	0.601	9.6e-09	9.2e-04	4.3e+02	3.476910e+02	-2.501145e+01	0:0:00	chol	2	1	
7	0.572	0.360	6.6e-08	6.3e-04	3.5e+02	2.623934e+02	-2.614093e+01	0:0:00	chol	2	2	
8	0.669	0.511	6.6e-08	3.4e-04	2.9e+02	2.074306e+02	-3.338748e+01	0:0:00	chol	2	2	
9	0.288	0.579	4.8e-08	1.6e-04	2.5e+02	1.815920e+02	-3.684866e+01	0:0:00	chol	2	2	
10	1.000	0.790	8.1e-10	4.8e-05	1.1e+02	5.866770e+01	-4.343668e+01	0:0:00	chol	2	2	
11	0.852	0.957	1.8e-10	1.0e-05	3.1e+01	-1.510059e+01	-4.419486e+01	0:0:00	chol	2	2	
12	0.941	0.956	1.8e-10	4.4e-06	2.5e+00	-4.188724e+01	-4.386708e+01	0:0:00	chol	2	2	
13	0.967	0.979	1.5e-09	2.1e-06	1.4e-01	-4.413483e+01	-4.404555e+01	0:0:00	chol	2	3	
14	0.080	0.072	1.1e-08	2.1e-06	1.3e-01	-4.414954e+01	-4.405416e+01	0:0:00	chol	3	3	
15	0.048	0.106	1.3e-08	1.9e-06	1.4e-01	-4.416158e+01	-4.407490e+01	0:0:00	chol	2	3	
16	0.114	0.114	2.5e-08	1.7e-06	1.4e-01	-4.416080e+01	-4.410071e+01	0:0:00	chol	2	2	
17	0.122	1.000	2.2e-08	1.3e-07	1.4e-01	-4.416569e+01	-4.429382e+01	0:0:00	chol	3	3	
18	0.977	0.941	6.1e-09	6.9e-08	1.6e-02	-4.428111e+01	-4.428911e+01	0:0:00	chol	2	3	
19	0.977	0.981	2.5e-09	3.4e-08	5.2e-04	-4.429610e+01	-4.429252e+01	0:0:00	chol	3	3	
20	0.980	0.979	3.2e-08	7.2e-10	1.5e-05	-4.429654e+01	-4.429645e+01	0:0:00	chol			

linsysolve: Schur complement matrix not positive definite

switch to LU factor. lu 30 ^ 7

stop: progress in duality gap has deteriorated, 5.3e-04

21	0.940	0.759	3.2e-08	7.2e-10	1.5e-05	-4.429654e+01	-4.429645e+01	0:0:00				
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number of iterations = 21

primal objective value = -4.42965413e+01

dual objective value = -4.42964549e+01

gap := trace(XZ) = 1.52e-05

relative gap = 1.69e-07

actual relative gap = -9.64e-07

rel. primal infeas = 3.20e-08

rel. dual infeas = 7.24e-10

norm(X), norm(y), norm(Z) = 1.2e+04, 9.9e+01, 7.0e+01

```

norm(A), norm(b), norm(C) = 2.7e+02, 1.2e+03, 7.5e+01
Total CPU time (secs) = 0.13
CPU time per iteration = 0.01
termination code      = -8
DIMACS errors: 9.9e-08  0.0e+00  1.0e-09  0.0e+00  -9.6e-07  1.7e-07
-----

```

```
ans =
```

```
44.2965
```

```
Epoch... 7
```

```
Epoch... 8
```

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 272

```

```
*****
```

```
SDPT3: Infeasible path-following algorithms
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*****
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```
version predcorr gam expon scale_data
```

```
HKM      1      0.000  1      0
```

it	pstep	dstep	pinfeas	dinfeas	gap	prim-obj	dual-obj	cputime			
0	0.000	0.000	1.0e+00	5.2e+00	1.9e+06	3.564479e+04	0.000000e+00	0:0:00	chol	1	1
1	0.976	0.974	2.4e-02	2.4e-01	1.2e+05	3.404755e+04	1.040024e+01	0:0:00	chol	1	1
2	1.000	1.000	3.2e-07	3.3e-02	3.2e+04	2.349371e+04	-6.184024e+01	0:0:00	chol	1	1
3	0.992	0.996	4.3e-08	1.0e-02	1.2e+03	8.317492e+02	-4.024966e+01	0:0:00	chol	1	1
4	0.766	0.533	2.4e-07	6.2e-03	9.2e+02	7.013583e+02	-2.780446e+01	0:0:00	chol	1	1
5	0.612	0.873	9.4e-08	1.6e-03	6.2e+02	5.400914e+02	-2.486878e+01	0:0:00	chol	2	1
6	0.728	0.521	2.8e-08	8.9e-04	4.4e+02	3.604747e+02	-2.439458e+01	0:0:00	chol	2	1
7	0.553	0.293	1.1e-07	6.5e-04	3.8e+02	2.820956e+02	-2.589223e+01	0:0:00	chol	1	2
8	0.280	0.570	9.9e-08	3.0e-04	3.4e+02	2.591260e+02	-3.704888e+01	0:0:00	chol	2	2
9	0.699	0.700	3.0e-08	1.1e-04	2.2e+02	1.606450e+02	-3.893118e+01	0:0:00	chol	2	2
10	1.000	1.000	7.1e-10	1.0e-05	8.6e+01	3.885846e+01	-4.531360e+01	0:0:00	chol	2	2
11	0.923	0.932	3.3e-10	5.3e-06	8.9e+00	-3.491303e+01	-4.322076e+01	0:0:00	chol	2	2
12	0.894	0.931	1.5e-10	2.7e-06	1.3e+00	-4.221666e+01	-4.327026e+01	0:0:00	chol	2	2
13	1.000	0.992	2.4e-09	1.3e-06	5.7e-01	-4.295643e+01	-4.339950e+01	0:0:00	chol	2	2
14	0.325	0.352	5.1e-09	1.0e-06	4.7e-01	-4.307225e+01	-4.342128e+01	0:0:00	chol	2	2
15	1.000	1.000	1.5e-09	3.1e-07	2.3e-01	-4.330672e+01	-4.349736e+01	0:0:00	chol	2	2
16	0.963	0.974	2.2e-09	1.6e-07	9.1e-03	-4.351464e+01	-4.350519e+01	0:0:00	chol	3	3
17	0.976	0.981	9.7e-09	8.0e-08	2.7e-04	-4.352318e+01	-4.351421e+01	0:0:00	chol	3	3
18	0.777	1.000	7.2e-08	1.5e-10	1.9e-04	-4.352327e+01	-4.352342e+01	0:0:00	chol	6	7
19	1.000	0.995	8.7e-09	3.7e-11	4.6e-05	-4.352338e+01	-4.352341e+01	0:0:00	chol	6	9
20	1.000	0.990	1.7e-09	1.4e-12	1.3e-06	-4.352341e+01	-4.352341e+01	0:0:00			

```
stop: max(relative gap, infeasibilities) < 1.00e-07
```

```

-----
number of iterations   = 20
primal objective value = -4.35234086e+01
dual  objective value = -4.35234117e+01
gap := trace(XZ)      = 1.34e-06
relative gap          = 1.53e-08
actual relative gap   = 3.51e-08
rel. primal infeas    = 1.67e-09
rel. dual infeas      = 1.41e-12

```

```

norm(X), norm(y), norm(Z) = 1.1e+04, 9.7e+01, 6.7e+01
norm(A), norm(b), norm(C) = 2.6e+02, 1.1e+03, 7.5e+01
Total CPU time (secs) = 0.11
CPU time per iteration = 0.01
termination code = 0
DIMACS errors: 5.2e-09 0.0e+00 2.0e-12 0.0e+00 3.5e-08 1.5e-08
-----

```

```
ans =
```

```
43.5234
```

```
Epoch... 9
```

```
Epoch... 10
```

```

num. of constraints = 33
dim. of socp var = 34, num. of socp blk = 1
dim. of linear var = 272

```

```
*****
```

```
SDPT3: Infeasible path-following algorithms
```

```
*****
```

```

version predcorr gam expon scale_data
HKM 1 0.000 1 0

```

it	pstep	dstep	pinfeas	dinfeas	gap	prim-obj	dual-obj	cputime			
0	0.000	0.000	1.0e+00	5.3e+00	1.8e+06	3.405499e+04	0.000000e+00	0:0:00	chol	1	1
1	0.975	0.972	2.5e-02	2.1e-01	1.0e+05	3.318282e+04	9.528572e+00	0:0:00	chol	1	1
2	1.000	1.000	3.7e-07	2.0e-02	2.9e+04	2.351302e+04	-5.998854e+01	0:0:00	chol	1	1
3	0.973	0.995	3.7e-08	6.0e-03	1.2e+03	8.888605e+02	-4.130645e+01	0:0:00	chol	1	1
4	0.653	0.536	2.2e-07	3.7e-03	9.1e+02	7.389378e+02	-2.857383e+01	0:0:00	chol	1	1
5	0.423	0.737	1.3e-07	1.4e-03	7.1e+02	6.267872e+02	-2.670369e+01	0:0:00	chol	2	2
6	0.496	0.473	8.2e-08	8.0e-04	5.7e+02	4.874399e+02	-2.342908e+01	0:0:00	chol	2	1
7	0.462	0.309	1.1e-07	5.7e-04	5.0e+02	4.013886e+02	-2.696991e+01	0:0:00	chol	2	2
8	1.000	0.525	6.7e-08	2.8e-04	3.8e+02	2.907646e+02	-3.806373e+01	0:0:00	chol	2	1
9	0.346	0.596	4.6e-08	1.2e-04	3.1e+02	2.391834e+02	-4.013928e+01	0:0:00	chol	2	2
10	1.000	0.924	6.9e-10	1.5e-05	1.4e+02	8.641531e+01	-4.577049e+01	0:0:00	chol	1	2
11	0.877	0.966	1.8e-10	3.4e-06	3.1e+01	-1.276445e+01	-4.350650e+01	0:0:00	chol	2	2
12	0.922	0.933	4.1e-10	1.6e-06	3.6e+00	-3.946120e+01	-4.284462e+01	0:0:00	chol	2	2
13	0.950	0.871	4.7e-10	8.6e-07	5.7e-01	-4.237149e+01	-4.284841e+01	0:0:00	chol	2	2
14	0.786	1.000	2.4e-08	3.8e-07	3.4e-01	-4.259110e+01	-4.289099e+01	0:0:00	chol	2	2
15	0.930	0.908	1.7e-09	2.1e-07	2.8e-02	-4.289468e+01	-4.290028e+01	0:0:00	chol	2	2
16	0.958	1.000	1.9e-08	9.4e-08	9.8e-03	-4.291242e+01	-4.291180e+01	0:0:00	chol	2	2
17	1.000	1.000	1.1e-08	4.7e-08	3.3e-03	-4.291870e+01	-4.291680e+01	0:0:00	chol	2	2
18	0.924	0.996	7.2e-08	5.5e-10	4.3e-04	-4.292150e+01	-4.292188e+01	0:0:00	chol	4	4
19	1.000	0.987	5.3e-09	8.0e-11	8.8e-05	-4.292182e+01	-4.292190e+01	0:0:00	chol	7	7
20	1.000	0.991	6.1e-09	9.0e-12	1.0e-05	-4.292189e+01	-4.292190e+01	0:0:00	chol		
warning: symqmr failed: 0.3											
switch to LU factor. lu 30 3											
21	1.000	0.991	1.8e-08	3.5e-13	3.3e-07	-4.292190e+01	-4.292190e+01	0:0:00			
stop: max(relative gap, infeasibilities) < 1.00e-07											

```

-----
number of iterations = 21
primal objective value = -4.29219040e+01
dual objective value = -4.29218992e+01
gap := trace(XZ) = 3.26e-07

```

```

relative gap          = 3.75e-09
actual relative gap   = -5.57e-08
rel. primal infeas    = 1.75e-08
rel. dual   infeas    = 3.52e-13
norm(X), norm(y), norm(Z) = 1.1e+04, 9.6e+01, 6.5e+01
norm(A), norm(b), norm(C) = 2.6e+02, 1.1e+03, 7.5e+01
Total CPU time (secs) = 0.14
CPU time per iteration = 0.01
termination code      = 0
DIMACS errors: 5.5e-08 0.0e+00 4.9e-13 0.0e+00 -5.6e-08 3.7e-09
-----

```

```
ans =
```

```
42.9219
```

```
Epoch... 11
```

```
Epoch... 12
```

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 272
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|5.3e+00|1.8e+06| 3.355908e+04  0.000000e+00| 0:0:00| chol 1 1
1|0.975|0.972|2.5e-02|2.1e-01|1.0e+05| 3.272984e+04  9.322746e+00| 0:0:00| chol 1 1
2|1.000|1.000|3.7e-07|2.0e-02|2.9e+04| 2.318092e+04 -5.913241e+01| 0:0:00| chol 1 1
3|0.973|0.995|3.7e-08|6.0e-03|1.1e+03| 8.772197e+02 -4.063044e+01| 0:0:00| chol 1 1
4|0.646|0.549|2.1e-07|3.7e-03|9.0e+02| 7.299910e+02 -2.815418e+01| 0:0:00| chol 1 1
5|0.432|0.736|1.2e-07|1.4e-03|7.0e+02| 6.157514e+02 -2.639220e+01| 0:0:00| chol 2 2
6|0.486|0.473|8.2e-08|8.0e-04|5.7e+02| 4.819875e+02 -2.314158e+01| 0:0:00| chol 2 2
7|0.389|0.318|1.0e-07|5.6e-04|5.1e+02| 4.098963e+02 -2.703536e+01| 0:0:00| chol 2 2
8|0.859|0.585|6.8e-08|2.5e-04|3.8e+02| 2.962783e+02 -3.789397e+01| 0:0:00| chol 2 2
9|0.375|0.881|4.6e-08|4.0e-05|3.1e+02| 2.523474e+02 -4.465278e+01| 0:0:00| chol 2 2
10|1.000|0.870|2.8e-10|1.0e-05|6.7e+01| 2.166092e+01 -4.355118e+01| 0:0:00| chol 2 2
11|0.859|0.967|1.4e-10|3.3e-06|1.8e+01| -2.511284e+01 -4.263873e+01| 0:0:00| chol 2 2
12|0.947|0.966|3.5e-10|1.6e-06|1.7e+00| -4.075995e+01 -4.226042e+01| 0:0:00| chol 2 2
13|0.571|0.796|3.5e-09|9.2e-07|1.1e+00| -4.135832e+01 -4.231655e+01| 0:0:00| chol 2 2
14|0.881|1.000|1.3e-09|3.8e-07|2.3e-01| -4.216373e+01 -4.235200e+01| 0:0:00| chol 2 2
15|1.000|1.000|2.2e-08|1.9e-07|8.6e-02| -4.230457e+01 -4.237030e+01| 0:0:00| chol 2 2
16|0.947|0.984|1.7e-09|9.6e-08|4.6e-03| -4.238324e+01 -4.237762e+01| 0:0:00| chol 3 3
17|1.000|0.932|9.0e-08|6.7e-09|2.0e-03| -4.238580e+01 -4.238716e+01| 0:0:00| chol 2 3
18|0.897|0.983|1.1e-08|3.2e-10|2.4e-04| -4.238759e+01 -4.238779e+01| 0:0:00| chol 6 6
19|1.000|0.740|6.1e-08|1.9e-10|1.3e-04| -4.238762e+01 -4.238780e+01| 0:0:00| chol 4 4
20|0.975|0.989|3.4e-09|1.2e-11|1.2e-05| -4.238778e+01 -4.238780e+01| 0:0:00| chol
warning: symgmr failed: 0.3
switch to LU factor. lu 30 6
stop: primal infeas has deteriorated too much, 2.1e-07
21|1.000|0.868|3.4e-09|1.2e-11|1.2e-05| -4.238778e+01 -4.238780e+01| 0:0:00|
-----

```

```

number of iterations    = 21
primal objective value = -4.23877839e+01
dual   objective value = -4.23877970e+01
gap := trace(XZ)       = 1.17e-05
relative gap           = 1.37e-07
actual relative gap    = 1.53e-07
rel. primal infeas     = 3.44e-09
rel. dual   infeas     = 1.20e-11
norm(X), norm(y), norm(Z) = 1.1e+04, 9.6e+01, 6.4e+01
norm(A), norm(b), norm(C) = 2.5e+02, 1.0e+03, 7.5e+01
Total CPU time (secs)   = 0.14
CPU time per iteration = 0.01
termination code        = -7
DIMACS errors: 1.1e-08  0.0e+00  1.7e-11  0.0e+00  1.5e-07  1.4e-07
-----

```

```
ans =
```

```
42.3878
```

```
Epoch... 13
```

```
Epoch... 14
```

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 272

```

```
*****
```

```
SDPT3: Infeasible path-following algorithms
```

```
*****
```

```
version predcorr gam expon scale_data
```

```
HKM      1      0.000  1      0
```

it	pstep	dstep	pinfeas	dinfeas	gap	prim-obj	dual-obj	cputime				
0	0.000	0.000	1.0e+00	5.3e+00	1.8e+06	3.330782e+04	0.000000e+00	0:0:00	chol	1	1	
1	0.975	0.972	2.5e-02	2.1e-01	1.0e+05	3.250638e+04	9.396550e+00	0:0:00	chol	1	1	
2	1.000	1.000	3.7e-07	2.0e-02	2.8e+04	2.311180e+04	-5.887854e+01	0:0:00	chol	1	1	
3	0.973	0.995	3.6e-08	6.0e-03	1.1e+03	8.706580e+02	-4.027474e+01	0:0:00	chol	1	1	
4	0.645	0.551	2.1e-07	3.7e-03	8.9e+02	7.246400e+02	-2.794660e+01	0:0:00	chol	1	1	
5	0.434	0.735	1.2e-07	1.4e-03	6.9e+02	6.104174e+02	-2.620908e+01	0:0:00	chol	2	2	
6	0.477	0.474	8.3e-08	7.9e-04	5.6e+02	4.801542e+02	-2.299662e+01	0:0:00	chol	2	2	
7	0.329	0.333	9.6e-08	5.5e-04	5.1e+02	4.187906e+02	-2.724085e+01	0:0:00	chol	1	2	
8	0.507	0.657	7.5e-08	2.0e-04	4.1e+02	3.404671e+02	-3.786659e+01	0:0:00	chol	2	2	
9	0.585	1.000	4.0e-08	1.2e-05	2.8e+02	2.306817e+02	-4.456771e+01	0:0:00	chol	2	2	
10	1.000	1.000	1.0e-10	6.0e-06	9.5e+01	4.954201e+01	-4.398642e+01	0:0:00	chol	2	2	
11	0.968	0.973	4.4e-10	3.1e-06	1.1e+01	-3.165486e+01	-4.198350e+01	0:0:00	chol	2	2	
12	0.937	0.899	2.0e-10	1.7e-06	1.3e+00	-4.068293e+01	-4.177201e+01	0:0:00	chol	2	2	
13	0.818	1.000	4.7e-09	7.5e-07	7.0e-01	-4.121986e+01	-4.184352e+01	0:0:00	chol	2	2	
14	0.952	0.971	5.0e-10	3.9e-07	4.3e-02	-4.185758e+01	-4.186043e+01	0:0:00	chol	2	2	
15	1.000	1.000	3.2e-08	1.9e-07	6.1e-03	-4.189367e+01	-4.188028e+01	0:0:00	chol	3	3	
16	1.000	1.000	2.5e-08	1.3e-10	4.5e-04	-4.189919e+01	-4.189961e+01	0:0:00	chol	4	3	
17	0.989	0.989	1.1e-09	6.2e-12	5.4e-06	-4.189959e+01	-4.189959e+01	0:0:00				

```
stop: max(relative gap, infeasibilities) < 1.00e-07
```

```

number of iterations    = 17
primal objective value = -4.18995877e+01

```

```

dual    objective value = -4.18995921e+01
gap := trace(XZ)        = 5.42e-06
relative gap            = 6.39e-08
actual relative gap     = 5.20e-08
rel. primal infeas      = 1.10e-09
rel. dual infeas        = 6.19e-12
norm(X), norm(y), norm(Z) = 1.0e+04, 9.5e+01, 6.4e+01
norm(A), norm(b), norm(C) = 2.5e+02, 1.0e+03, 7.5e+01
Total CPU time (secs)   = 0.11
CPU time per iteration = 0.01
termination code        = 0
DIMACS errors: 3.5e-09  0.0e+00  8.7e-12  0.0e+00  5.2e-08  6.4e-08
-----

```

```
ans =
```

```
41.8996
```

```
Epoch... 15
```

```
Epoch... 16
```

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 272
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|5.3e+00|1.8e+06| 3.322529e+04  0.000000e+00| 0:0:00| chol 1 1
1|0.975|0.972|2.5e-02|2.1e-01|1.0e+05| 3.244204e+04  9.556011e+00| 0:0:00| chol 1 1
2|1.000|1.000|3.7e-07|2.0e-02|2.9e+04| 2.315475e+04 -5.887310e+01| 0:0:00| chol 1 1
3|0.973|0.995|3.5e-08|6.0e-03|1.1e+03| 8.665478e+02 -4.004658e+01| 0:0:00| chol 1 1
4|0.647|0.549|2.2e-07|3.7e-03|8.9e+02| 7.211062e+02 -2.781745e+01| 0:0:00| chol 1 1
5|0.432|0.736|1.2e-07|1.4e-03|6.9e+02| 6.079838e+02 -2.605963e+01| 0:0:00| chol 2 2
6|0.471|0.473|8.5e-08|8.0e-04|5.6e+02| 4.801125e+02 -2.292103e+01| 0:0:00| chol 2 1
7|0.309|0.341|9.4e-08|5.4e-04|5.1e+02| 4.222981e+02 -2.731907e+01| 0:0:00| chol 2 2
8|0.447|0.680|7.5e-08|1.9e-04|4.2e+02| 3.493837e+02 -3.769966e+01| 0:0:00| chol 2 2
9|0.628|1.000|3.8e-08|1.2e-05|2.6e+02| 2.173613e+02 -4.403281e+01| 0:0:00| chol 2 2
10|1.000|1.000|7.4e-11|6.0e-06|1.1e+02| 6.215934e+01 -4.392518e+01| 0:0:00| chol 2 2
11|0.920|0.840|7.4e-10|3.5e-06|1.3e+01| -2.927173e+01 -4.173211e+01| 0:0:00| chol 2 2
12|1.000|0.903|1.9e-10|1.7e-06|8.0e-01| -4.068837e+01 -4.131802e+01| 0:0:00| chol 2 2
13|0.861|0.970|6.9e-10|7.8e-07|4.0e-01| -4.104402e+01 -4.136516e+01| 0:0:00| chol 2 2
14|0.952|0.977|4.8e-10|3.8e-07|2.3e-02| -4.140885e+01 -4.139099e+01| 0:0:00| chol 3 3
15|1.000|0.556|8.9e-08|2.8e-07|1.7e-02| -4.141560e+01 -4.140271e+01| 0:0:00| chol 2 2
16|0.119|0.596|7.7e-08|1.7e-07|1.6e-02| -4.141793e+01 -4.141448e+01| 0:0:00| chol 4 3
17|1.000|0.952|2.4e-07|5.3e-08|8.2e-03| -4.142500e+01 -4.142706e+01| 0:0:00| chol 3 3
18|0.528|1.000|1.1e-07|2.5e-10|5.6e-03| -4.142757e+01 -4.143304e+01| 0:0:00| chol 4 4
19|0.955|0.982|3.4e-08|2.3e-10|2.9e-04| -4.143259e+01 -4.143286e+01| 0:0:00| chol 7 7
20|0.989|0.994|3.0e-08|3.5e-11|4.3e-05| -4.143283e+01 -4.143285e+01| 0:0:00| chol 20 21
21|1.000|0.994|6.5e-08|6.1e-12|7.5e-06| -4.143288e+01 -4.143285e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
-----

```



```

number of iterations    = 21
primal objective value = -4.14328776e+01
dual   objective value = -4.14328506e+01
gap := trace(XZ)       = 7.53e-06
relative gap           = 8.98e-08
actual relative gap    = -3.23e-07
rel. primal infeas     = 6.52e-08
rel. dual   infeas     = 6.09e-12
norm(X), norm(y), norm(Z) = 1.2e+04, 9.5e+01, 6.3e+01
norm(A), norm(b), norm(C) = 2.5e+02, 1.0e+03, 7.5e+01
Total CPU time (secs)   = 0.14
CPU time per iteration = 0.01
termination code        = 0
DIMACS errors: 2.0e-07  0.0e+00  8.5e-12  0.0e+00  -3.2e-07  9.0e-08
-----

```

ans =

41.4329

Epoch... 17

Epoch... 18

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 272
*****
SDPT3: Infeasible path-following algorithms
*****
version  predcorr  gam  expon  scale_data
HKM      1      0.000  1      0

it pstep dstep pinfeas dinfeas  gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|5.3e+00|1.8e+06| 3.343865e+04  0.000000e+00| 0:0:00| chol  1  1
1|0.975|0.972|2.5e-02|2.1e-01|1.0e+05| 3.265392e+04  9.994513e+00| 0:0:00| chol  1  1
2|1.000|1.000|3.7e-07|2.0e-02|2.9e+04| 2.341320e+04 -5.945587e+01| 0:0:00| chol  1  1
3|0.973|0.995|3.4e-08|6.0e-03|1.1e+03| 8.671045e+02 -4.008176e+01| 0:0:00| chol  1  1
4|0.659|0.529|2.2e-07|3.8e-03|8.9e+02| 7.208272e+02 -2.787679e+01| 0:0:00| chol  1  1
5|0.417|0.736|1.3e-07|1.4e-03|7.0e+02| 6.126500e+02 -2.603916e+01| 0:0:00| chol  1  1
6|0.468|0.475|8.8e-08|8.0e-04|5.7e+02| 4.844040e+02 -2.292987e+01| 0:0:00| chol  2  2
7|0.344|0.330|9.8e-08|5.5e-04|5.1e+02| 4.203704e+02 -2.713350e+01| 0:0:00| chol  2  2
8|0.550|0.653|7.4e-08|2.1e-04|4.1e+02| 3.372964e+02 -3.776548e+01| 0:0:00| chol  2  2
9|0.559|1.000|4.0e-08|1.2e-05|2.9e+02| 2.388951e+02 -4.400389e+01| 0:0:00| chol  2  2
10|1.000|1.000|2.9e-10|6.0e-06|9.2e+01| 4.778700e+01 -4.298652e+01| 0:0:00| chol  2  2
11|0.975|1.000|3.3e-10|3.0e-06|1.6e+01|-2.538113e+01 -4.132891e+01| 0:0:00| chol  2  2
12|0.946|0.866|4.0e-10|1.7e-06|1.3e+00|-3.976341e+01 -4.090428e+01| 0:0:00| chol  2  2
13|0.977|0.885|1.5e-09|8.6e-07|2.1e-01|-4.081549e+01 -4.092744e+01| 0:0:00| chol  2  2
14|1.000|1.000|1.6e-09|3.8e-07|7.8e-02|-4.093697e+01 -4.097257e+01| 0:0:00| chol  2  2
15|0.975|0.985|4.5e-09|1.9e-07|2.4e-03|-4.100980e+01 -4.099064e+01| 0:0:00| chol  3  3
16|1.000|1.000|1.1e-07|2.7e-10|6.6e-04|-4.101150e+01 -4.101219e+01| 0:0:00| chol  4  4
17|0.983|0.988|4.0e-09|1.3e-11|1.2e-05|-4.101215e+01 -4.101217e+01| 0:0:00| chol
linsysolve: Schur complement matrix not positive definite
switch to LU factor. lu 19 ^20
stop: primal infeas has deteriorated too much, 1.6e-07
18|1.000|0.989|4.0e-09|1.3e-11|1.2e-05|-4.101215e+01 -4.101217e+01| 0:0:00|

```

```

-----
number of iterations    = 18
primal objective value = -4.10121522e+01
dual   objective value = -4.10121680e+01
gap := trace(XZ)       = 1.17e-05
relative gap           = 1.41e-07
actual relative gap    = 1.90e-07
rel. primal infeas     = 4.01e-09
rel. dual   infeas     = 1.25e-11
norm(X), norm(y), norm(Z) = 1.1e+04, 9.5e+01, 6.3e+01
norm(A), norm(b), norm(C) = 2.6e+02, 1.0e+03, 7.5e+01
Total CPU time (secs)   = 0.14
CPU time per iteration = 0.01
termination code        = -7
DIMACS errors: 1.3e-08  0.0e+00  1.8e-11  0.0e+00  1.9e-07  1.4e-07
-----

```

ans =

41.0122

Epoch... 19

Epoch... 20

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 272
*****
SDPT3: Infeasible path-following algorithms
*****
version  predcorr  gam  expon  scale_data
HKM      1      0.000  1      0

it pstep dstep pinfeas dinfeas  gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|5.4e+00|1.9e+06| 3.370421e+04  0.000000e+00| 0:0:00| chol  1  1
1|0.975|0.972|2.5e-02|2.1e-01|1.0e+05| 3.291435e+04  1.026456e+01| 0:0:00| chol  1  1
2|1.000|1.000|3.7e-07|2.0e-02|2.9e+04| 2.365757e+04 -6.017353e+01| 0:0:00| chol  1  1
3|0.974|0.995|3.3e-08|6.0e-03|1.1e+03| 8.685563e+02 -4.020287e+01| 0:0:00| chol  1  1
4|0.672|0.509|2.3e-07|3.9e-03|8.9e+02| 7.213165e+02 -2.800003e+01| 0:0:00| chol  1  1
5|0.402|0.737|1.4e-07|1.4e-03|7.0e+02| 6.176293e+02 -2.612440e+01| 0:0:00| chol  1  1
6|0.465|0.477|9.2e-08|8.1e-04|5.7e+02| 4.886959e+02 -2.296715e+01| 0:0:00| chol  2  2
7|0.370|0.324|1.0e-07|5.6e-04|5.1e+02| 4.198306e+02 -2.700271e+01| 0:0:00| chol  2  2
8|0.618|0.635|7.4e-08|2.2e-04|4.1e+02| 3.318015e+02 -3.776101e+01| 0:0:00| chol  2  2
9|0.489|0.916|4.3e-08|3.0e-05|3.1e+02| 2.563011e+02 -4.302327e+01| 0:0:00| chol  2  2
10|1.000|1.000|2.0e-10|6.0e-06|7.9e+01| 3.597643e+01 -4.218539e+01| 0:0:00| chol  2  2
11|0.841|1.000|2.5e-10|3.0e-06|2.3e+01|-1.840146e+01 -4.092478e+01| 0:0:00| chol  2  2
12|0.965|0.965|4.6e-10|1.6e-06|2.1e+00|-3.853006e+01 -4.048520e+01| 0:0:00| chol  2  2
13|0.865|0.958|2.8e-09|7.9e-07|6.7e-01|-3.995375e+01 -4.053217e+01| 0:0:00| chol  2  2
14|0.963|0.981|5.8e-10|3.8e-07|2.7e-02|-4.057453e+01 -4.055915e+01| 0:0:00| chol  2  2
15|1.000|1.000|4.6e-08|1.9e-07|4.2e-03|-4.059686e+01 -4.058037e+01| 0:0:00| chol  3  3
16|1.000|1.000|4.9e-08|1.7e-10|6.3e-04|-4.060033e+01 -4.060094e+01| 0:0:00| chol  4  4
17|0.988|0.989|1.5e-09|8.9e-12|8.4e-06|-4.060092e+01 -4.060092e+01| 0:0:00| chol
linsysolve: Schur complement matrix not positive definite
switch to LU factor. lu 26 ^ 9
18|1.000|0.990|2.2e-08|3.8e-13|3.6e-07|-4.060094e+01 -4.060092e+01| 0:0:00|

```

```

stop: max(relative gap, infeasibilities) < 1.00e-07
-----
number of iterations    = 18
primal objective value = -4.06009392e+01
dual   objective value = -4.06009224e+01
gap := trace(XZ)       = 3.58e-07
relative gap           = 4.35e-09
actual relative gap    = -2.04e-07
rel. primal infeas     = 2.25e-08
rel. dual   infeas     = 3.85e-13
norm(X), norm(y), norm(Z) = 1.1e+04, 9.4e+01, 6.2e+01
norm(A), norm(b), norm(C) = 2.6e+02, 1.1e+03, 7.5e+01
Total CPU time (secs)   = 0.12
CPU time per iteration = 0.01
termination code        = 0
DIMACS errors: 7.0e-08  0.0e+00  5.4e-13  0.0e+00  -2.0e-07  4.4e-09
-----

```

```
ans =
```

```
40.6009
```

```
Epoch... 21
```

```
Epoch... 22
```

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 272
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|5.4e+00|1.9e+06| 3.395729e+04  0.000000e+00| 0:0:00| chol 1 1
1|0.976|0.972|2.4e-02|2.1e-01|1.0e+05| 3.316462e+04  1.057362e+01| 0:0:00| chol 1 1
2|1.000|1.000|3.6e-07|2.0e-02|2.9e+04| 2.387970e+04 -6.070960e+01| 0:0:00| chol 1 1
3|0.974|0.995|3.2e-08|6.0e-03|1.1e+03| 8.693943e+02 -4.024008e+01| 0:0:00| chol 1 1
4|0.682|0.494|2.4e-07|3.9e-03|9.0e+02| 7.214936e+02 -2.805663e+01| 0:0:00| chol 1 1
5|0.392|0.737|1.5e-07|1.4e-03|7.1e+02| 6.209115e+02 -2.619009e+01| 0:0:00| chol 2 2
6|0.462|0.479|9.6e-08|8.2e-04|5.8e+02| 4.920838e+02 -2.293698e+01| 0:0:00| chol 1 2
7|0.357|0.327|1.0e-07|5.7e-04|5.2e+02| 4.252298e+02 -2.700955e+01| 0:0:00| chol 2 2
8|0.517|0.664|7.7e-08|2.1e-04|4.2e+02| 3.490350e+02 -3.782036e+01| 0:0:00| chol 2 2
9|0.544|0.922|4.1e-08|2.7e-05|3.0e+02| 2.543007e+02 -4.258887e+01| 0:0:00| chol 2 2
10|1.000|1.000|1.6e-10|6.0e-06|8.7e+01| 4.334512e+01 -4.206629e+01| 0:0:00| chol 2 2
11|0.914|1.000|2.4e-10|3.0e-06|2.1e+01| -1.961850e+01 -4.058653e+01| 0:0:00| chol 2 2
12|0.954|0.895|4.8e-10|1.7e-06|1.7e+00| -3.856036e+01 -4.009824e+01| 0:0:00| chol 2 2
13|0.957|0.938|2.7e-09|8.1e-07|3.1e-01| -3.990819e+01 -4.012725e+01| 0:0:00| chol 2 2
14|0.978|0.978|1.1e-09|3.9e-07|9.4e-03| -4.019243e+01 -4.016059e+01| 0:0:00| chol 2 3
15|1.000|1.000|1.9e-08|1.9e-07|1.3e-03| -4.020026e+01 -4.018139e+01| 0:0:00| chol 4 4
16|1.000|0.968|8.4e-08|6.2e-09|5.5e-04| -4.020106e+01 -4.020084e+01| 0:0:00| chol 3 3
17|0.984|0.980|3.5e-09|1.3e-10|9.7e-06| -4.020146e+01 -4.020145e+01| 0:0:00| chol 8 12
18|0.993|0.990|1.4e-08|1.6e-12|2.7e-07| -4.020146e+01 -4.020146e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07

```

```

-----
number of iterations    = 18
primal objective value = -4.02014638e+01
dual   objective value = -4.02014630e+01
gap := trace(XZ)       = 2.67e-07
relative gap           = 3.28e-09
actual relative gap    = -9.49e-09
rel. primal infeas     = 1.41e-08
rel. dual   infeas     = 1.63e-12
norm(X), norm(y), norm(Z) = 1.1e+04, 9.4e+01, 6.2e+01
norm(A), norm(b), norm(C) = 2.6e+02, 1.1e+03, 7.5e+01
Total CPU time (secs)   = 0.13
CPU time per iteration = 0.01
termination code        = 0
DIMACS errors: 4.4e-08  0.0e+00  2.3e-12  0.0e+00  -9.5e-09  3.3e-09
-----

```

ans =

40.2015

Epoch... 23

Epoch... 24

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 272
*****
SDPT3: Infeasible path-following algorithms
*****
version  predcorr  gam  expon  scale_data
HKM      1      0.000  1      0

it pstep dstep pinfeas dinfeas  gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|5.4e+00|1.9e+06| 3.409385e+04  0.000000e+00| 0:0:00| chol  1  1
1|0.976|0.972|2.4e-02|2.2e-01|1.1e+05| 3.330347e+04  1.089310e+01| 0:0:00| chol  1  1
2|1.000|1.000|3.6e-07|2.0e-02|3.0e+04| 2.407618e+04 -6.120714e+01| 0:0:00| chol  1  1
3|0.974|0.994|3.2e-08|6.0e-03|1.1e+03| 8.695325e+02 -4.026653e+01| 0:0:00| chol  1  1
4|0.692|0.481|2.5e-07|4.0e-03|9.0e+02| 7.210206e+02 -2.810824e+01| 0:0:00| chol  1  1
5|0.383|0.738|1.5e-07|1.4e-03|7.1e+02| 6.227308e+02 -2.628437e+01| 0:0:00| chol  1  2
6|0.458|0.482|9.9e-08|8.2e-04|5.8e+02| 4.943437e+02 -2.289300e+01| 0:0:00| chol  2  2
7|0.317|0.336|1.0e-07|5.6e-04|5.3e+02| 4.342824e+02 -2.714315e+01| 0:0:00| chol  1  2
8|0.399|0.734|8.0e-08|1.7e-04|4.3e+02| 3.699591e+02 -3.796647e+01| 0:0:00| chol  2  1
9|0.643|1.000|3.6e-08|1.2e-05|2.8e+02| 2.310127e+02 -4.272692e+01| 0:0:00| chol  2  2
10|1.000|1.000|2.3e-10|6.0e-06|1.0e+02| 5.800061e+01 -4.221183e+01| 0:0:00| chol  2  2
11|1.000|1.000|4.7e-10|3.0e-06|1.4e+01| -2.600491e+01 -3.999010e+01| 0:0:00| chol  2  2
12|0.942|0.870|1.7e-10|1.7e-06|1.2e+00| -3.864850e+01 -3.968766e+01| 0:0:00| chol  2  2
13|0.989|0.929|1.0e-09|8.2e-07|2.8e-01| -3.955014e+01 -3.974092e+01| 0:0:00| chol  2  2
14|0.976|0.982|1.1e-09|3.8e-07|1.0e-02| -3.980475e+01 -3.977513e+01| 0:0:00| chol  3  2
15|1.000|1.000|8.5e-08|1.9e-07|7.7e-04| -3.981404e+01 -3.979521e+01| 0:0:00| chol  4  4
16|1.000|0.994|2.1e-07|1.3e-09|3.8e-04| -3.981436e+01 -3.981466e+01| 0:0:00| chol  3  3
17|0.987|0.988|3.0e-09|2.0e-11|5.4e-06| -3.981477e+01 -3.981477e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
-----
number of iterations    = 17

```

```

primal objective value = -3.98147659e+01
dual   objective value = -3.98147673e+01
gap := trace(XZ)       = 5.37e-06
relative gap           = 6.66e-08
actual relative gap    = 1.70e-08
rel. primal infeas     = 2.95e-09
rel. dual   infeas     = 2.04e-11
norm(X), norm(y), norm(Z) = 1.0e+04, 9.4e+01, 6.2e+01
norm(A), norm(b), norm(C) = 2.6e+02, 1.1e+03, 7.5e+01
Total CPU time (secs)   = 0.12
CPU time per iteration = 0.01
termination code        = 0
DIMACS errors: 9.2e-09  0.0e+00  2.9e-11  0.0e+00  1.7e-08  6.7e-08
-----

```

```
ans =
```

```
39.8148
```

```
Epoch... 25
```

```
Epoch... 26
```

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 272
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|5.4e+00|1.9e+06| 3.423429e+04  0.000000e+00| 0:0:00| chol 1 1
1|0.976|0.972|2.4e-02|2.2e-01|1.1e+05| 3.344562e+04  1.119813e+01| 0:0:00| chol 1 1
2|1.000|1.000|3.6e-07|2.0e-02|3.0e+04| 2.423812e+04 -6.168260e+01| 0:0:00| chol 1 1
3|0.975|0.994|3.2e-08|6.0e-03|1.1e+03| 8.695259e+02 -4.029268e+01| 0:0:00| chol 1 1
4|0.701|0.466|2.6e-07|4.0e-03|9.0e+02| 7.205699e+02 -2.816904e+01| 0:0:00| chol 1 1
5|0.375|0.737|1.6e-07|1.5e-03|7.1e+02| 6.244683e+02 -2.644073e+01| 0:0:00| chol 2 2
6|0.454|0.479|1.0e-07|8.4e-04|5.8e+02| 4.964136e+02 -2.287804e+01| 0:0:00| chol 2 1
7|0.306|0.339|1.0e-07|5.7e-04|5.3e+02| 4.382331e+02 -2.709126e+01| 0:0:00| chol 2 2
8|0.364|0.770|8.2e-08|1.5e-04|4.4e+02| 3.783988e+02 -3.799201e+01| 0:0:00| chol 2 2
9|0.674|1.000|3.4e-08|1.2e-05|2.7e+02| 2.235928e+02 -4.247758e+01| 0:0:00| chol 2 2
10|1.000|1.000|1.5e-10|6.0e-06|1.0e+02| 6.049522e+01 -4.196714e+01| 0:0:00| chol 2 2
11|1.000|0.824|3.1e-10|3.5e-06|1.4e+01| -2.639800e+01 -3.992476e+01| 0:0:00| chol 2 2
12|0.966|0.863|1.9e-10|1.8e-06|9.5e-01| -3.857511e+01 -3.934619e+01| 0:0:00| chol 2 2
13|0.935|0.920|5.4e-10|8.3e-07|2.7e-01| -3.918597e+01 -3.937143e+01| 0:0:00| chol 2 2
14|0.973|0.978|8.5e-10|3.9e-07|1.6e-02| -3.942748e+01 -3.940414e+01| 0:0:00| chol 2 2
15|0.942|1.000|1.1e-08|1.9e-07|1.8e-03| -3.944096e+01 -3.942371e+01| 0:0:00| chol 3 4
16|1.000|0.970|1.5e-07|5.7e-09|6.9e-04| -3.944198e+01 -3.944220e+01| 0:0:00| chol 3 3
17|0.965|0.986|5.8e-09|1.0e-10|2.6e-05| -3.944273e+01 -3.944274e+01| 0:0:00| chol 6 7
18|1.000|0.995|3.8e-08|7.6e-12|7.9e-06| -3.944271e+01 -3.944275e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
-----
number of iterations   = 18
primal objective value = -3.94427135e+01

```

```

dual    objective value = -3.94427481e+01
gap := trace(XZ)        = 7.91e-06
relative gap            = 9.90e-08
actual relative gap     = 4.33e-07
rel. primal infeas      = 3.79e-08
rel. dual   infeas      = 7.57e-12
norm(X), norm(y), norm(Z) = 1.0e+04, 9.4e+01, 6.2e+01
norm(A), norm(b), norm(C) = 2.6e+02, 1.1e+03, 7.5e+01
Total CPU time (secs)   = 0.11
CPU time per iteration = 0.01
termination code        = 0
DIMACS errors: 1.2e-07  0.0e+00  1.1e-11  0.0e+00  4.3e-07  9.9e-08
-----

```

```
ans =
```

```
39.4427
```

```
Epoch... 27
```

```
Epoch... 28
```

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 272

```

```
*****
```

```
SDPT3: Infeasible path-following algorithms
```

```
*****
```

```
version predcorr gam expon scale_data
```

```
HKM      1      0.000  1      0
```

```
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
```

```

-----
0|0.000|0.000|1.0e+00|5.5e+00|1.9e+06| 3.446139e+04  0.000000e+00| 0:0:00| chol  1  1
1|0.976|0.972|2.4e-02|2.2e-01|1.1e+05| 3.367078e+04  1.150808e+01| 0:0:00| chol  1  1
2|1.000|1.000|3.6e-07|2.0e-02|3.0e+04| 2.446771e+04 -6.222195e+01| 0:0:00| chol  1  1
3|0.975|0.994|3.2e-08|6.0e-03|1.1e+03| 8.708196e+02 -4.034507e+01| 0:0:00| chol  1  1
4|0.711|0.455|2.6e-07|4.1e-03|9.1e+02| 7.211737e+02 -2.822531e+01| 0:0:00| chol  1  1
5|0.369|0.737|1.7e-07|1.5e-03|7.1e+02| 6.264803e+02 -2.657340e+01| 0:0:00| chol  2  2
6|0.449|0.472|1.1e-07|8.5e-04|5.8e+02| 4.990638e+02 -2.288411e+01| 0:0:00| chol  2  2
7|0.314|0.340|1.0e-07|5.8e-04|5.3e+02| 4.393831e+02 -2.698454e+01| 0:0:00| chol  2  2
8|0.361|0.773|8.3e-08|1.5e-04|4.4e+02| 3.810138e+02 -3.792185e+01| 0:0:00| chol  2  2
9|0.679|1.000|3.3e-08|1.2e-05|2.7e+02| 2.264297e+02 -4.220250e+01| 0:0:00| chol  2  2
10|1.000|1.000|2.2e-10|6.0e-06|1.0e+02| 5.981387e+01 -4.160095e+01| 0:0:00| chol  2  2
11|1.000|0.832|2.7e-10|3.5e-06|1.6e+01| -2.437321e+01 -3.957722e+01| 0:0:00| chol  2  2
12|0.966|0.869|2.7e-10|1.8e-06|1.1e+00| -3.807231e+01 -3.898981e+01| 0:0:00| chol  2  2
13|0.958|0.913|4.9e-10|8.4e-07|2.2e-01| -3.886994e+01 -3.900908e+01| 0:0:00| chol  2  2
14|0.979|0.992|7.9e-10|3.8e-07|2.0e-02| -3.906021e+01 -3.904315e+01| 0:0:00| chol  2  2
15|0.943|1.000|9.3e-09|1.9e-07|2.0e-03| -3.907812e+01 -3.906153e+01| 0:0:00| chol  3  3
16|1.000|0.989|7.2e-08|2.3e-09|7.7e-04| -3.907939e+01 -3.907989e+01| 0:0:00| chol  3  3
17|0.957|0.985|2.7e-09|6.6e-11|3.5e-05| -3.908004e+01 -3.908007e+01| 0:0:00| chol  6  7
18|1.000|0.996|2.0e-08|1.2e-11|1.2e-05| -3.908005e+01 -3.908008e+01| 0:0:00| chol 24 30
19|1.000|0.991|2.3e-08|5.5e-13|4.8e-07| -3.908007e+01 -3.908008e+01| 0:0:00|

```

```
stop: max(relative gap, infeasibilities) < 1.00e-07
```

```
-----
number of iterations = 19
```

```
primal objective value = -3.90800653e+01
```

```

dual    objective value = -3.90800751e+01
gap := trace(XZ)        = 4.78e-07
relative gap            = 6.04e-09
actual relative gap     = 1.24e-07
rel. primal infeas      = 2.33e-08
rel. dual   infeas      = 5.48e-13
norm(X), norm(y), norm(Z) = 9.9e+03, 9.4e+01, 6.1e+01
norm(A), norm(b), norm(C) = 2.6e+02, 1.1e+03, 7.5e+01
Total CPU time (secs)   = 0.13
CPU time per iteration = 0.01
termination code        = 0
DIMACS errors: 7.3e-08  0.0e+00  7.7e-13  0.0e+00  1.2e-07  6.0e-09
-----

```

```
ans =
```

```
39.0801
```

```
Epoch... 29
```

```
Epoch... 30
```

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 272
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|5.5e+00|2.0e+06| 3.465401e+04  0.000000e+00| 0:0:00| chol 1 1
1|0.976|0.972|2.4e-02|2.2e-01|1.1e+05| 3.386277e+04  1.182028e+01| 0:0:00| chol 1 1
2|1.000|1.000|3.5e-07|2.0e-02|3.0e+04| 2.470507e+04 -6.279945e+01| 0:0:00| chol 1 1
3|0.975|0.994|3.2e-08|6.0e-03|1.1e+03| 8.724026e+02 -4.042326e+01| 0:0:00| chol 1 1
4|0.720|0.444|2.7e-07|4.1e-03|9.1e+02| 7.220005e+02 -2.829691e+01| 0:0:00| chol 1 1
5|0.364|0.737|1.7e-07|1.5e-03|7.2e+02| 6.283468e+02 -2.673546e+01| 0:0:00| chol 2 1
6|0.445|0.465|1.1e-07|8.7e-04|5.9e+02| 5.017224e+02 -2.290716e+01| 0:0:00| chol 2 2
7|0.324|0.341|1.0e-07|5.9e-04|5.3e+02| 4.402440e+02 -2.689940e+01| 0:0:00| chol 2 1
8|0.358|0.774|8.4e-08|1.5e-04|4.4e+02| 3.832381e+02 -3.786089e+01| 0:0:00| chol 2 2
9|0.686|1.000|3.3e-08|1.2e-05|2.7e+02| 2.288380e+02 -4.191611e+01| 0:0:00| chol 2 2
10|1.000|1.000|2.0e-10|6.0e-06|1.0e+02| 5.929665e+01 -4.126193e+01| 0:0:00| chol 2 2
11|1.000|0.830|2.6e-10|3.5e-06|1.7e+01| -2.293551e+01 -3.925168e+01| 0:0:00| chol 2 2
12|0.970|0.878|2.4e-10|1.7e-06|1.2e+00| -3.760081e+01 -3.864140e+01| 0:0:00| chol 2 2
13|0.969|0.907|5.7e-10|8.4e-07|1.9e-01| -3.854268e+01 -3.865479e+01| 0:0:00| chol 2 2
14|0.994|1.000|1.4e-09|3.8e-07|3.3e-02| -3.869299e+01 -3.868943e+01| 0:0:00| chol 2 2
15|0.969|0.985|8.1e-09|1.9e-07|1.2e-03| -3.872354e+01 -3.870629e+01| 0:0:00| chol 3 4
16|1.000|0.918|1.7e-07|1.6e-08|5.6e-04| -3.872411e+01 -3.872317e+01| 0:0:00| chol 2 2
17|0.902|0.981|2.2e-08|3.6e-10|6.9e-05| -3.872461e+01 -3.872464e+01| 0:0:00| chol 4 6
18|1.000|0.992|2.6e-08|2.5e-11|2.4e-05| -3.872464e+01 -3.872467e+01| 0:0:00| chol 7 8
19|0.987|0.991|4.2e-09|1.6e-12|1.4e-06| -3.872467e+01 -3.872467e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
-----
number of iterations = 19
primal objective value = -3.87246660e+01

```

```

dual    objective value = -3.87246658e+01
gap := trace(XZ)        = 1.41e-06
relative gap            = 1.80e-08
actual relative gap     = -2.62e-09
rel. primal infeas      = 4.21e-09
rel. dual infeas        = 1.56e-12
norm(X), norm(y), norm(Z) = 9.6e+03, 9.3e+01, 6.1e+01
norm(A), norm(b), norm(C) = 2.7e+02, 1.1e+03, 7.5e+01
Total CPU time (secs)   = 0.11
CPU time per iteration = 0.01
termination code        = 0
DIMACS errors: 1.3e-08  0.0e+00  2.2e-12  0.0e+00  -2.6e-09  1.8e-08
-----

```

```
ans =
```

```
38.7247
```

```
Epoch... 31
```

```
Epoch... 32
```

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 272
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|5.5e+00|2.0e+06| 3.488247e+04  0.000000e+00| 0:0:00| chol 1 1
1|0.976|0.974|2.4e-02|2.5e-01|1.2e+05| 3.351862e+04  1.230293e+01| 0:0:00| chol 1 1
2|1.000|1.000|3.1e-07|3.3e-02|3.3e+04| 2.387806e+04 -6.276904e+01| 0:0:00| chol 1 1
3|0.996|0.995|3.0e-08|1.0e-02|1.1e+03| 7.610248e+02 -3.831481e+01| 0:0:00| chol 1 1
4|0.834|0.468|2.9e-07|6.7e-03|8.8e+02| 6.539362e+02 -2.675723e+01| 0:0:00| chol 1 1
5|0.517|0.870|1.4e-07|1.6e-03|6.0e+02| 5.209234e+02 -2.419532e+01| 0:0:00| chol 1 1
6|0.659|0.511|5.0e-08|9.4e-04|4.3e+02| 3.596611e+02 -2.346757e+01| 0:0:00| chol 2 2
7|0.684|0.306|1.3e-07|6.8e-04|3.6e+02| 2.670009e+02 -2.528821e+01| 0:0:00| chol 1 2
8|0.333|0.539|1.1e-07|3.3e-04|3.2e+02| 2.479306e+02 -3.657458e+01| 0:0:00| chol 1 1
9|0.784|0.734|2.4e-08|1.0e-04|2.0e+02| 1.462378e+02 -3.725104e+01| 0:0:00| chol 1 2
10|1.000|0.957|2.5e-10|1.4e-05|7.0e+01| 2.847952e+01 -3.946528e+01| 0:0:00| chol 2 2
11|0.696|0.905|1.2e-10|5.9e-06|2.8e+01| -1.137989e+01 -3.865346e+01| 0:0:00| chol 2 2
12|0.801|0.989|3.6e-10|2.5e-06|8.9e+00| -2.970039e+01 -3.833035e+01| 0:0:00| chol 2 2
13|0.945|0.952|1.8e-09|1.3e-06|5.1e-01| -3.788590e+01 -3.827166e+01| 0:0:00| chol 2 2
14|1.000|1.000|2.3e-09|6.3e-07|1.4e-01| -3.825296e+01 -3.833122e+01| 0:0:00| chol 2 2
15|0.975|0.985|1.3e-09|3.2e-07|4.3e-03| -3.838160e+01 -3.835604e+01| 0:0:00| chol 3 3
16|1.000|1.000|9.0e-08|1.2e-10|2.1e-03| -3.838381e+01 -3.838589e+01| 0:0:00| chol 3 3
17|0.982|0.988|3.2e-09|4.1e-11|4.1e-05| -3.838579e+01 -3.838583e+01| 0:0:00| chol 7 7
18|1.000|0.992|1.3e-08|4.5e-12|4.3e-06| -3.838583e+01 -3.838583e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
-----
number of iterations   = 18
primal objective value = -3.83858319e+01
dual objective value   = -3.83858281e+01

```



```

gap := trace(XZ)          = 4.28e-06
relative gap              = 5.50e-08
actual relative gap       = -4.90e-08
rel. primal infeas        = 1.33e-08
rel. dual infeas          = 4.47e-12
norm(X), norm(y), norm(Z) = 9.4e+03, 9.3e+01, 6.1e+01
norm(A), norm(b), norm(C) = 2.7e+02, 1.1e+03, 7.5e+01
Total CPU time (secs)    = 0.12
CPU time per iteration    = 0.01
termination code          = 0
DIMACS errors: 4.1e-08  0.0e+00  6.3e-12  0.0e+00  -4.9e-08  5.5e-08
-----

```

```
ans =
```

```
38.3858
```

```
Epoch... 33
```

```
Epoch... 34
```

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 272
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|5.5e+00|2.0e+06| 3.502387e+04  0.000000e+00| 0:0:00| chol 1 1
1|0.977|0.974|2.3e-02|2.5e-01|1.2e+05| 3.366206e+04  1.258707e+01| 0:0:00| chol 1 1
2|1.000|1.000|3.1e-07|3.3e-02|3.3e+04| 2.404802e+04 -6.326713e+01| 0:0:00| chol 1 1
3|0.996|0.995|2.9e-08|1.0e-02|1.1e+03| 7.595163e+02 -3.837360e+01| 0:0:00| chol 1 1
4|0.845|0.459|2.9e-07|6.8e-03|8.8e+02| 6.538694e+02 -2.679981e+01| 0:0:00| chol 1 1
5|0.505|0.868|1.5e-07|1.7e-03|6.0e+02| 5.228116e+02 -2.431957e+01| 0:0:00| chol 2 1
6|0.658|0.515|5.3e-08|9.4e-04|4.3e+02| 3.602351e+02 -2.342883e+01| 0:0:00| chol 2 2
7|0.673|0.309|1.3e-07|6.8e-04|3.6e+02| 2.682246e+02 -2.525091e+01| 0:0:00| chol 2 2
8|0.384|0.524|1.0e-07|3.4e-04|3.2e+02| 2.463672e+02 -3.599587e+01| 0:0:00| chol 2 1
9|0.712|0.702|3.1e-08|1.2e-04|2.1e+02| 1.585959e+02 -3.673460e+01| 0:0:00| chol 2 2
10|1.000|0.996|2.2e-10|1.0e-05|8.2e+01| 4.102041e+01 -3.978828e+01| 0:0:00| chol 2 2
11|0.727|0.921|1.4e-10|5.4e-06|3.1e+01| -7.636834e+00 -3.846186e+01| 0:0:00| chol 2 2
12|0.834|0.988|2.7e-10|2.5e-06|8.9e+00| -2.934823e+01 -3.801231e+01| 0:0:00| chol 2 2
13|0.941|0.948|2.0e-09|1.3e-06|5.4e-01| -3.751878e+01 -3.794195e+01| 0:0:00| chol 2 2
14|1.000|1.000|1.8e-09|6.3e-07|1.6e-01| -3.790122e+01 -3.799943e+01| 0:0:00| chol 2 1
15|0.965|0.989|2.8e-08|3.2e-07|7.5e-03| -3.804474e+01 -3.802319e+01| 0:0:00| chol 3 2
16|1.000|1.000|6.4e-08|1.4e-10|2.9e-03| -3.804925e+01 -3.805218e+01| 0:0:00| chol 3 3
17|0.978|0.987|2.4e-09|7.0e-11|6.9e-05| -3.805203e+01 -3.805209e+01| 0:0:00| chol 6 7
18|1.000|0.993|9.1e-09|1.1e-11|1.1e-05| -3.805209e+01 -3.805209e+01| 0:0:00| chol
linsysolve: Schur complement matrix not positive definite
switch to LU factor. lu 30 ^14
19|1.000|0.994|5.3e-08|2.8e-12|2.8e-06| -3.805216e+01 -3.805209e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
-----
number of iterations = 19

```

```

primal objective value = -3.80521613e+01
dual   objective value = -3.80520935e+01
gap := trace(XZ)       = 2.78e-06
relative gap           = 3.61e-08
actual relative gap    = -8.78e-07
rel. primal infeas     = 5.35e-08
rel. dual   infeas     = 2.82e-12
norm(X), norm(y), norm(Z) = 9.2e+03, 9.3e+01, 6.1e+01
norm(A), norm(b), norm(C) = 2.7e+02, 1.1e+03, 7.5e+01
Total CPU time (secs)   = 0.16
CPU time per iteration = 0.01
termination code        = 0
DIMACS errors: 1.7e-07  0.0e+00  4.0e-12  0.0e+00  -8.8e-07  3.6e-08
-----

```

```
ans =
```

```
38.0521
```

```
Epoch... 35
```

```
Epoch... 36
```

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 272
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|5.6e+00|2.0e+06| 3.533267e+04  0.000000e+00| 0:0:00| chol 1 1
1|0.977|0.974|2.3e-02|2.5e-01|1.2e+05| 3.396213e+04  1.283029e+01| 0:0:00| chol 1 1
2|1.000|1.000|3.0e-07|3.3e-02|3.3e+04| 2.429397e+04 -6.392545e+01| 0:0:00| chol 1 1
3|0.996|0.995|2.9e-08|1.0e-02|1.1e+03| 7.598082e+02 -3.850439e+01| 0:0:00| chol 1 1
4|0.857|0.449|3.0e-07|6.8e-03|8.9e+02| 6.556135e+02 -2.687613e+01| 0:0:00| chol 1 1
5|0.493|0.868|1.5e-07|1.7e-03|6.0e+02| 5.256884e+02 -2.446606e+01| 0:0:00| chol 2 1
6|0.656|0.519|5.6e-08|9.5e-04|4.4e+02| 3.618614e+02 -2.340082e+01| 0:0:00| chol 2 2
7|0.658|0.311|1.2e-07|6.8e-04|3.6e+02| 2.707931e+02 -2.522291e+01| 0:0:00| chol 2 2
8|0.442|0.516|9.7e-08|3.5e-04|3.2e+02| 2.448626e+02 -3.548145e+01| 0:0:00| chol 2 1
9|0.646|0.674|3.5e-08|1.3e-04|2.2e+02| 1.685458e+02 -3.626751e+01| 0:0:00| chol 1 2
10|1.000|1.000|2.4e-10|1.0e-05|9.4e+01| 5.234197e+01 -4.001145e+01| 0:0:00| chol 2 2
11|0.962|0.941|1.4e-10|5.3e-06|2.0e+01| -1.901417e+01 -3.806991e+01| 0:0:00| chol 2 2
12|0.857|0.964|4.7e-10|2.6e-06|4.1e+00| -3.369522e+01 -3.757935e+01| 0:0:00| chol 2 2
13|0.908|0.979|1.2e-09|1.3e-06|4.1e-01| -3.732451e+01 -3.761836e+01| 0:0:00| chol 2 2
14|1.000|1.000|5.1e-09|6.3e-07|2.0e-01| -3.753488e+01 -3.767877e+01| 0:0:00| chol 2 2
15|0.957|0.979|1.1e-09|3.2e-07|1.1e-02| -3.771795e+01 -3.770034e+01| 0:0:00| chol 2 2
16|1.000|1.000|5.9e-08|1.6e-07|1.5e-03| -3.772731e+01 -3.771479e+01| 0:0:00| chol 3 3
17|1.000|0.993|5.8e-08|1.3e-09|2.0e-04| -3.772858e+01 -3.772867e+01| 0:0:00| chol 3 3
18|0.996|0.990|1.2e-09|1.7e-11|3.6e-06| -3.772876e+01 -3.772876e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
-----
number of iterations   = 18
primal objective value = -3.77287584e+01

```

```

dual    objective value = -3.77287612e+01
gap := trace(XZ)        = 3.65e-06
relative gap            = 4.77e-08
actual relative gap     = 3.62e-08
rel. primal infeas      = 1.21e-09
rel. dual infeas        = 1.67e-11
norm(X), norm(y), norm(Z) = 9.0e+03, 9.3e+01, 6.1e+01
norm(A), norm(b), norm(C) = 2.7e+02, 1.1e+03, 7.5e+01
Total CPU time (secs)   = 0.12
CPU time per iteration = 0.01
termination code        = 0
DIMACS errors: 3.8e-09  0.0e+00  2.3e-11  0.0e+00  3.6e-08  4.8e-08
-----

```

```
ans =
```

```
37.7288
```

```
Epoch... 37
```

```
Epoch... 38
```

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 272
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|5.6e+00|2.0e+06| 3.551078e+04  0.000000e+00| 0:0:00| chol 1 1
1|0.977|0.974|2.3e-02|2.5e-01|1.2e+05| 3.413940e+04  1.313128e+01| 0:0:00| chol 1 1
2|1.000|1.000|3.0e-07|3.3e-02|3.4e+04| 2.450419e+04 -6.451807e+01| 0:0:00| chol 1 1
3|0.997|0.995|2.9e-08|1.0e-02|1.1e+03| 7.597185e+02 -3.860944e+01| 0:0:00| chol 1 1
4|0.868|0.441|3.1e-07|6.9e-03|8.9e+02| 6.568373e+02 -2.694367e+01| 0:0:00| chol 1 1
5|0.484|0.867|1.6e-07|1.7e-03|6.0e+02| 5.277819e+02 -2.463100e+01| 0:0:00| chol 1 1
6|0.653|0.523|5.9e-08|9.5e-04|4.4e+02| 3.631926e+02 -2.336400e+01| 0:0:00| chol 2 2
7|0.640|0.312|1.2e-07|6.8e-04|3.7e+02| 2.737909e+02 -2.518962e+01| 0:0:00| chol 2 2
8|0.492|0.495|9.3e-08|3.5e-04|3.2e+02| 2.447381e+02 -3.512764e+01| 0:0:00| chol 2 1
9|0.578|0.639|4.0e-08|1.4e-04|2.4e+02| 1.795313e+02 -3.597043e+01| 0:0:00| chol 1 2
10|1.000|1.000|2.9e-10|6.0e-06|1.1e+02| 6.469456e+01 -4.052944e+01| 0:0:00| chol 2 2
11|1.000|0.952|2.3e-10|3.1e-06|2.1e+01| -1.763101e+01 -3.783876e+01| 0:0:00| chol 2 2
12|0.911|0.948|3.2e-10|1.6e-06|2.9e+00| -3.460896e+01 -3.734977e+01| 0:0:00| chol 2 2
13|0.894|0.929|1.5e-09|8.1e-07|3.5e-01| -3.707528e+01 -3.735734e+01| 0:0:00| chol 2 2
14|1.000|1.000|2.8e-09|3.8e-07|1.6e-01| -3.727131e+01 -3.739375e+01| 0:0:00| chol 2 2
15|0.959|0.973|6.5e-10|1.9e-07|7.7e-03| -3.741427e+01 -3.740509e+01| 0:0:00| chol 2 2
16|1.000|1.000|4.0e-08|9.4e-08|8.3e-04| -3.742100e+01 -3.741361e+01| 0:0:00| chol 3 3
17|1.000|1.000|5.8e-08|1.7e-10|1.7e-04| -3.742165e+01 -3.742181e+01| 0:0:00| chol 4 4
18|0.997|0.990|8.5e-10|5.9e-12|4.1e-06| -3.742180e+01 -3.742180e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
-----
number of iterations   = 18
primal objective value = -3.74217994e+01
dual objective value   = -3.74218029e+01

```

```

gap := trace(XZ)          = 4.07e-06
relative gap              = 5.36e-08
actual relative gap       = 4.61e-08
rel. primal infeas        = 8.51e-10
rel. dual infeas          = 5.89e-12
norm(X), norm(y), norm(Z) = 8.7e+03, 9.3e+01, 6.0e+01
norm(A), norm(b), norm(C) = 2.7e+02, 1.1e+03, 7.5e+01
Total CPU time (secs)     = 0.09
CPU time per iteration    = 0.01
termination code          = 0
DIMACS errors: 2.6e-09  0.0e+00  8.3e-12  0.0e+00  4.6e-08  5.4e-08
-----

```

```
ans =
```

```
37.4218
```

```
Epoch... 39
```

```
Epoch... 40
```

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 272
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|5.6e+00|2.1e+06| 3.566970e+04  0.000000e+00| 0:0:00| chol 1 1
1|0.977|0.974|2.3e-02|2.5e-01|1.2e+05| 3.429884e+04  1.339554e+01| 0:0:00| chol 1 1
2|1.000|1.000|3.0e-07|3.3e-02|3.4e+04| 2.468365e+04 -6.504020e+01| 0:0:00| chol 1 1
3|0.997|0.995|2.8e-08|1.0e-02|1.1e+03| 7.592009e+02 -3.869220e+01| 0:0:00| chol 1 1
4|0.878|0.433|3.1e-07|7.0e-03|8.9e+02| 6.576797e+02 -2.699845e+01| 0:0:00| chol 1 1
5|0.476|0.866|1.6e-07|1.7e-03|6.1e+02| 5.291651e+02 -2.479015e+01| 0:0:00| chol 2 1
6|0.650|0.528|6.1e-08|9.5e-04|4.4e+02| 3.641991e+02 -2.332048e+01| 0:0:00| chol 2 2
7|0.621|0.313|1.1e-07|6.8e-04|3.7e+02| 2.766956e+02 -2.514793e+01| 0:0:00| chol 2 2
8|0.560|0.492|8.7e-08|3.5e-04|3.2e+02| 2.418270e+02 -3.465400e+01| 0:0:00| chol 1 1
9|0.524|0.617|4.2e-08|1.4e-04|2.4e+02| 1.854496e+02 -3.555022e+01| 0:0:00| chol 2 2
10|1.000|1.000|3.4e-10|6.0e-06|1.1e+02| 7.236893e+01 -4.063565e+01| 0:0:00| chol 2 2
11|1.000|0.970|2.7e-10|3.1e-06|2.3e+01| -1.499706e+01 -3.741574e+01| 0:0:00| chol 2 2
12|0.920|0.953|3.5e-10|1.6e-06|3.0e+00| -3.416966e+01 -3.706004e+01| 0:0:00| chol 2 2
13|0.877|0.940|1.5e-09|8.0e-07|4.8e-01| -3.665659e+01 -3.706557e+01| 0:0:00| chol 2 2
14|1.000|1.000|1.9e-09|3.8e-07|2.3e-01| -3.690603e+01 -3.710084e+01| 0:0:00| chol 2 2
15|0.957|0.970|3.8e-10|1.9e-07|1.2e-02| -3.711470e+01 -3.710964e+01| 0:0:00| chol 2 2
16|1.000|1.000|1.6e-08|9.4e-08|1.2e-03| -3.712480e+01 -3.711793e+01| 0:0:00| chol 3 3
17|1.000|0.996|6.2e-08|4.4e-10|1.4e-04| -3.712578e+01 -3.712591e+01| 0:0:00| chol 3 3
18|0.996|0.991|1.6e-09|7.2e-12|2.9e-06| -3.712593e+01 -3.712593e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
-----
number of iterations      = 18
primal objective value    = -3.71259298e+01
dual objective value      = -3.71259318e+01
gap := trace(XZ)          = 2.93e-06

```

```

relative gap          = 3.89e-08
actual relative gap   = 2.60e-08
rel. primal infeas    = 1.60e-09
rel. dual   infeas    = 7.17e-12
norm(X), norm(y), norm(Z) = 8.5e+03, 9.3e+01, 6.0e+01
norm(A), norm(b), norm(C) = 2.7e+02, 1.1e+03, 7.5e+01
Total CPU time (secs) = 0.11
CPU time per iteration = 0.01
termination code       = 0
DIMACS errors: 5.0e-09  0.0e+00  1.0e-11  0.0e+00  2.6e-08  3.9e-08
-----

```

```
ans =
```

```
37.1259
```

```
Epoch... 41
```

```
Epoch... 42
```

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 272
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|5.6e+00|2.1e+06| 3.589898e+04  0.000000e+00| 0:0:00| chol 1 1
1|0.977|0.974|2.3e-02|2.5e-01|1.2e+05| 3.452432e+04  1.366851e+01| 0:0:00| chol 1 1
2|1.000|1.000|3.0e-07|3.3e-02|3.4e+04| 2.485995e+04 -6.552850e+01| 0:0:00| chol 1 1
3|0.997|0.995|2.8e-08|1.0e-02|1.1e+03| 7.598822e+02 -3.875811e+01| 0:0:00| chol 1 1
4|0.887|0.426|3.2e-07|7.0e-03|9.0e+02| 6.594022e+02 -2.704031e+01| 0:0:00| chol 1 1
5|0.469|0.865|1.7e-07|1.7e-03|6.1e+02| 5.312019e+02 -2.495629e+01| 0:0:00| chol 1 1
6|0.645|0.531|6.4e-08|9.5e-04|4.4e+02| 3.659701e+02 -2.326105e+01| 0:0:00| chol 2 2
7|0.602|0.312|1.1e-07|6.8e-04|3.7e+02| 2.803432e+02 -2.509401e+01| 0:0:00| chol 2 2
8|0.628|0.490|8.1e-08|3.6e-04|3.1e+02| 2.391481e+02 -3.422051e+01| 0:0:00| chol 2 1
9|0.476|0.598|4.3e-08|1.5e-04|2.5e+02| 1.900682e+02 -3.518147e+01| 0:0:00| chol 2 2
10|1.000|1.000|4.0e-10|6.0e-06|1.2e+02| 7.811127e+01 -4.067256e+01| 0:0:00| chol 2 2
11|0.975|0.825|3.0e-10|3.5e-06|2.6e+01| -1.243793e+01 -3.756200e+01| 0:0:00| chol 2 2
12|1.000|0.916|1.9e-10|1.7e-06|3.3e+00| -3.367182e+01 -3.685823e+01| 0:0:00| chol 2 2
13|0.936|0.918|3.7e-10|8.3e-07|2.8e-01| -3.657607e+01 -3.678299e+01| 0:0:00| chol 2 2
14|1.000|0.990|1.5e-09|3.8e-07|1.1e-01| -3.673341e+01 -3.681090e+01| 0:0:00| chol 2 2
15|0.958|1.000|7.1e-10|1.9e-07|1.5e-02| -3.682499e+01 -3.682390e+01| 0:0:00| chol 2 2
16|1.000|1.000|1.1e-08|9.4e-08|1.7e-03| -3.683760e+01 -3.683146e+01| 0:0:00| chol 3 2
17|0.998|1.000|9.9e-08|2.0e-10|4.1e-04| -3.683891e+01 -3.683928e+01| 0:0:00| chol 4 4
18|0.974|0.980|2.4e-09|2.6e-11|2.0e-05| -3.683925e+01 -3.683927e+01| 0:0:00| chol 9 7
19|1.000|0.990|7.9e-10|4.9e-12|4.3e-06| -3.683927e+01 -3.683927e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
-----
number of iterations   = 19
primal objective value = -3.68392680e+01
dual   objective value = -3.68392718e+01
gap := trace(XZ)       = 4.30e-06

```

```

relative gap          = 5.76e-08
actual relative gap   = 5.07e-08
rel. primal infeas    = 7.94e-10
rel. dual   infeas    = 4.93e-12
norm(X), norm(y), norm(Z) = 8.4e+03, 9.3e+01, 6.0e+01
norm(A), norm(b), norm(C) = 2.7e+02, 1.1e+03, 7.5e+01
Total CPU time (secs) = 0.13
CPU time per iteration = 0.01
termination code       = 0
DIMACS errors: 2.5e-09  0.0e+00  6.9e-12  0.0e+00  5.1e-08  5.8e-08
-----

```

```
ans =
```

```
36.8393
```

```
Epoch... 43
```

```
Epoch... 44
```

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 272
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|5.7e+00|2.1e+06| 3.604723e+04  0.000000e+00| 0:0:00| chol 1 1
1|0.977|0.974|2.3e-02|2.5e-01|1.2e+05| 3.467350e+04  1.393779e+01| 0:0:00| chol 1 1
2|1.000|1.000|3.0e-07|3.3e-02|3.4e+04| 2.502949e+04 -6.601833e+01| 0:0:00| chol 1 1
3|0.997|0.995|2.8e-08|1.0e-02|1.2e+03| 7.613016e+02 -3.883007e+01| 0:0:00| chol 1 1
4|0.896|0.421|3.2e-07|7.1e-03|9.0e+02| 6.613285e+02 -2.708562e+01| 0:0:00| chol 1 1
5|0.463|0.864|1.7e-07|1.7e-03|6.1e+02| 5.343324e+02 -2.511778e+01| 0:0:00| chol 1 2
6|0.642|0.535|6.6e-08|9.5e-04|4.4e+02| 3.684172e+02 -2.322136e+01| 0:0:00| chol 2 2
7|0.590|0.312|1.0e-07|6.8e-04|3.7e+02| 2.837866e+02 -2.506133e+01| 0:0:00| chol 1 2
8|0.690|0.490|7.7e-08|3.6e-04|3.1e+02| 2.367182e+02 -3.392407e+01| 0:0:00| chol 1 1
9|0.444|0.587|4.4e-08|1.5e-04|2.5e+02| 1.924744e+02 -3.493373e+01| 0:0:00| chol 2 2
10|1.000|1.000|3.6e-10|6.0e-06|1.2e+02| 8.128050e+01 -4.060492e+01| 0:0:00| chol 2 2
11|0.933|0.698|3.0e-10|3.9e-06|2.5e+01| -1.286536e+01 -3.764067e+01| 0:0:00| chol 2 2
12|1.000|0.919|1.4e-10|1.7e-06|4.6e+00| -3.220618e+01 -3.663444e+01| 0:0:00| chol 2 2
13|0.947|0.935|3.8e-10|8.1e-07|3.3e-01| -3.624686e+01 -3.650524e+01| 0:0:00| chol 2 2
14|1.000|0.907|1.6e-09|4.2e-07|1.1e-01| -3.645340e+01 -3.652708e+01| 0:0:00| chol 2 2
15|1.000|1.000|7.7e-10|1.9e-07|2.7e-02| -3.653065e+01 -3.654241e+01| 0:0:00| chol 2 2
16|1.000|0.960|6.1e-09|9.8e-08|1.1e-03| -3.655593e+01 -3.654898e+01| 0:0:00| chol 3 3
17|1.000|0.984|1.9e-08|1.7e-09|1.6e-04| -3.655675e+01 -3.655680e+01| 0:0:00| chol 3 3
18|1.000|0.990|9.9e-10|2.0e-11|3.2e-06| -3.655692e+01 -3.655692e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
-----
number of iterations   = 18
primal objective value = -3.65569179e+01
dual   objective value = -3.65569198e+01
gap := trace(XZ)       = 3.20e-06
relative gap           = 4.32e-08

```

```

actual relative gap      = 2.53e-08
rel. primal infeas      = 9.95e-10
rel. dual   infeas      = 1.95e-11
norm(X), norm(y), norm(Z) = 8.2e+03, 9.3e+01, 6.0e+01
norm(A), norm(b), norm(C) = 2.8e+02, 1.1e+03, 7.5e+01
Total CPU time (secs)    = 0.08
CPU time per iteration   = 0.00
termination code         = 0
DIMACS errors: 3.1e-09  0.0e+00  2.7e-11  0.0e+00  2.5e-08  4.3e-08
-----

```

```
ans =
```

```
36.5569
```

```
Epoch... 45
```

```
Epoch... 46
```

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 272
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|5.7e+00|2.1e+06| 3.630573e+04  0.000000e+00| 0:0:00| chol 1 1
1|0.978|0.974|2.2e-02|2.5e-01|1.2e+05| 3.492631e+04  1.415120e+01| 0:0:00| chol 1 1
2|1.000|1.000|3.0e-07|3.3e-02|3.5e+04| 2.520174e+04 -6.649638e+01| 0:0:00| chol 1 1
3|0.997|0.995|2.8e-08|1.0e-02|1.2e+03| 7.630006e+02 -3.889280e+01| 0:0:00| chol 1 1
4|0.904|0.415|3.2e-07|7.1e-03|9.1e+02| 6.636966e+02 -2.711916e+01| 0:0:00| chol 1 1
5|0.458|0.862|1.8e-07|1.7e-03|6.2e+02| 5.379694e+02 -2.527399e+01| 0:0:00| chol 1 1
6|0.637|0.538|6.8e-08|9.5e-04|4.4e+02| 3.714763e+02 -2.317130e+01| 0:0:00| chol 2 2
7|0.578|0.312|1.0e-07|6.8e-04|3.8e+02| 2.875810e+02 -2.502533e+01| 0:0:00| chol 2 2
8|0.743|0.489|7.4e-08|3.6e-04|3.1e+02| 2.350676e+02 -3.367940e+01| 0:0:00| chol 2 1
9|0.419|0.579|4.3e-08|1.6e-04|2.5e+02| 1.944200e+02 -3.474012e+01| 0:0:00| chol 2 2
10|1.000|1.000|5.9e-10|6.0e-06|1.2e+02| 8.335223e+01 -4.049024e+01| 0:0:00| chol 2 2
11|0.905|0.647|2.2e-10|4.1e-06|2.5e+01| -1.337643e+01 -3.751061e+01| 0:0:00| chol 2 2
12|0.964|0.921|1.7e-10|1.7e-06|5.6e+00| -3.091934e+01 -3.639399e+01| 0:0:00| chol 2 2
13|0.952|0.938|2.7e-10|8.1e-07|3.7e-01| -3.593448e+01 -3.623668e+01| 0:0:00| chol 2 2
14|0.995|0.878|1.4e-09|4.3e-07|9.5e-02| -3.619402e+01 -3.625465e+01| 0:0:00| chol 2 2
15|1.000|1.000|1.4e-09|1.9e-07|3.5e-02| -3.625069e+01 -3.627065e+01| 0:0:00| chol 2 2
16|0.968|0.942|3.5e-09|9.9e-08|2.7e-03| -3.628204e+01 -3.627673e+01| 0:0:00| chol 3 2
17|1.000|1.000|7.9e-08|1.7e-10|5.8e-04| -3.628405e+01 -3.628462e+01| 0:0:00| chol 3 3
18|0.988|0.989|5.2e-10|1.1e-11|7.6e-06| -3.628460e+01 -3.628460e+01| 0:0:00| chol 26 17
19|1.000|0.990|1.2e-09|2.7e-13|1.5e-07| -3.628460e+01 -3.628460e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
-----
number of iterations      = 19
primal objective value    = -3.62846032e+01
dual   objective value    = -3.62846030e+01
gap := trace(XZ)          = 1.46e-07
relative gap              = 1.98e-09

```

```

actual relative gap      = -2.77e-09
rel. primal infeas      = 1.22e-09
rel. dual   infeas      = 2.71e-13
norm(X), norm(y), norm(Z) = 8.0e+03, 9.3e+01, 6.0e+01
norm(A), norm(b), norm(C) = 2.8e+02, 1.1e+03, 7.5e+01
Total CPU time (secs)    = 0.12
CPU time per iteration   = 0.01
termination code         = 0
DIMACS errors: 3.8e-09  0.0e+00  3.8e-13  0.0e+00  -2.8e-09  2.0e-09
-----

```

```
ans =
```

```
36.2846
```

```
Epoch... 47
```

```
Epoch... 48
```

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 272
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|5.7e+00|2.1e+06| 3.640516e+04  0.000000e+00| 0:0:00| chol 1 1
1|0.978|0.974|2.2e-02|2.5e-01|1.2e+05| 3.502928e+04  1.438168e+01| 0:0:00| chol 1 1
2|1.000|1.000|3.0e-07|3.3e-02|3.5e+04| 2.534648e+04 -6.697827e+01| 0:0:00| chol 1 1
3|0.997|0.994|2.9e-08|1.0e-02|1.2e+03| 7.642899e+02 -3.897615e+01| 0:0:00| chol 1 1
4|0.912|0.410|3.3e-07|7.1e-03|9.1e+02| 6.654660e+02 -2.717436e+01| 0:0:00| chol 1 1
5|0.454|0.861|1.8e-07|1.8e-03|6.2e+02| 5.407105e+02 -2.544473e+01| 0:0:00| chol 1 1
6|0.633|0.541|7.1e-08|9.5e-04|4.5e+02| 3.742253e+02 -2.314247e+01| 0:0:00| chol 2 2
7|0.569|0.312|1.0e-07|6.8e-04|3.8e+02| 2.910578e+02 -2.500787e+01| 0:0:00| chol 2 2
8|0.779|0.490|7.2e-08|3.6e-04|3.1e+02| 2.343366e+02 -3.348210e+01| 0:0:00| chol 2 1
9|0.401|0.575|4.4e-08|1.6e-04|2.6e+02| 1.961207e+02 -3.459055e+01| 0:0:00| chol 2 2
10|1.000|1.000|3.7e-10|6.0e-06|1.3e+02| 8.456595e+01 -4.033219e+01| 0:0:00| chol 2 2
11|0.887|0.630|2.4e-10|4.1e-06|2.4e+01| -1.364162e+01 -3.728554e+01| 0:0:00| chol 2 2
12|0.930|0.917|8.3e-11|1.7e-06|6.4e+00| -2.988026e+01 -3.616663e+01| 0:0:00| chol 2 2
13|0.954|0.937|4.4e-10|8.1e-07|4.0e-01| -3.564055e+01 -3.597784e+01| 0:0:00| chol 2 2
14|0.971|0.870|1.4e-09|4.3e-07|9.0e-02| -3.593597e+01 -3.599219e+01| 0:0:00| chol 2 2
15|1.000|1.000|1.6e-09|1.9e-07|3.4e-02| -3.598822e+01 -3.600793e+01| 0:0:00| chol 2 2
16|1.000|1.000|2.7e-09|9.4e-08|6.1e-03| -3.601564e+01 -3.601438e+01| 0:0:00| chol 2 2
17|1.000|1.000|1.2e-08|8.4e-11|1.2e-03| -3.602046e+01 -3.602162e+01| 0:0:00| chol 4 5
18|1.000|1.000|9.3e-09|1.3e-10|1.4e-04| -3.602146e+01 -3.602159e+01| 0:0:00| chol 3 3
19|1.000|0.991|3.6e-10|4.1e-12|2.5e-06| -3.602158e+01 -3.602158e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
-----
number of iterations      = 19
primal objective value    = -3.60215826e+01
dual   objective value    = -3.60215846e+01
gap := trace(XZ)          = 2.53e-06
relative gap              = 3.46e-08

```



```

actual relative gap      = 2.75e-08
rel. primal infeas      = 3.57e-10
rel. dual   infeas      = 4.06e-12
norm(X), norm(y), norm(Z) = 7.9e+03, 9.2e+01, 6.0e+01
norm(A), norm(b), norm(C) = 2.8e+02, 1.2e+03, 7.5e+01
Total CPU time (secs)    = 0.12
CPU time per iteration   = 0.01
termination code         = 0
DIMACS errors: 1.1e-09  0.0e+00  5.7e-12  0.0e+00  2.7e-08  3.5e-08
-----

```

```
ans =
```

```
36.0216
```

```
Epoch... 49
```

```
Epoch... 50
```

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 272
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|5.7e+00|2.2e+06| 3.656396e+04  0.000000e+00| 0:0:00| chol 1 1
1|0.978|0.974|2.2e-02|2.5e-01|1.3e+05| 3.518847e+04  1.459595e+01| 0:0:00| chol 1 1
2|1.000|1.000|2.9e-07|3.3e-02|3.5e+04| 2.549322e+04 -6.742099e+01| 0:0:00| chol 1 1
3|0.998|0.994|2.9e-08|1.0e-02|1.2e+03| 7.655385e+02 -3.904740e+01| 0:0:00| chol 1 1
4|0.919|0.405|3.3e-07|7.2e-03|9.1e+02| 6.673563e+02 -2.721937e+01| 0:0:00| chol 1 1
5|0.450|0.860|1.8e-07|1.8e-03|6.2e+02| 5.433745e+02 -2.559936e+01| 0:0:00| chol 1 2
6|0.628|0.543|7.3e-08|9.5e-04|4.5e+02| 3.771665e+02 -2.311024e+01| 0:0:00| chol 2 2
7|0.561|0.312|9.9e-08|6.8e-04|3.8e+02| 2.944589e+02 -2.499232e+01| 0:0:00| chol 2 1
8|0.801|0.490|7.1e-08|3.6e-04|3.1e+02| 2.347764e+02 -3.333142e+01| 0:0:00| chol 2 1
9|0.390|0.574|4.4e-08|1.6e-04|2.6e+02| 1.979737e+02 -3.447660e+01| 0:0:00| chol 2 2
10|1.000|1.000|3.4e-10|6.0e-06|1.3e+02| 8.539399e+01 -4.015496e+01| 0:0:00| chol 2 2
11|0.877|0.636|3.3e-10|4.1e-06|2.4e+01| -1.298766e+01 -3.700613e+01| 0:0:00| chol 2 2
12|0.890|0.916|1.9e-10|1.7e-06|7.3e+00| -2.875534e+01 -3.594403e+01| 0:0:00| chol 2 2
13|0.956|0.938|3.5e-10|8.1e-07|4.4e-01| -3.534956e+01 -3.572725e+01| 0:0:00| chol 2 2
14|0.946|0.865|1.2e-09|4.3e-07|8.7e-02| -3.568518e+01 -3.573858e+01| 0:0:00| chol 2 2
15|0.991|1.000|1.1e-09|1.9e-07|3.4e-02| -3.573408e+01 -3.575404e+01| 0:0:00| chol 2 2
16|1.000|1.000|8.1e-09|9.4e-08|1.2e-02| -3.575595e+01 -3.576051e+01| 0:0:00| chol 2 2
17|0.901|0.935|7.1e-09|5.0e-08|1.6e-03| -3.576584e+01 -3.576356e+01| 0:0:00| chol 3 3
18|1.000|1.000|1.2e-08|2.9e-10|7.7e-04| -3.576665e+01 -3.576740e+01| 0:0:00| chol 4 4
19|0.917|0.908|1.8e-09|1.2e-10|8.3e-05| -3.576730e+01 -3.576737e+01| 0:0:00| chol 5 6
20|1.000|0.991|4.4e-09|4.0e-11|3.3e-05| -3.576734e+01 -3.576737e+01| 0:0:00| chol 8 8
21|1.000|0.994|6.2e-09|7.6e-12|6.3e-06| -3.576737e+01 -3.576737e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
-----
number of iterations    = 21
primal objective value  = -3.57673652e+01
dual   objective value  = -3.57673718e+01

```

```

gap := trace(XZ)          = 6.27e-06
relative gap              = 8.64e-08
actual relative gap       = 9.07e-08
rel. primal infeas        = 6.25e-09
rel. dual infeas          = 7.62e-12
norm(X), norm(y), norm(Z) = 7.7e+03, 9.2e+01, 6.0e+01
norm(A), norm(b), norm(C) = 2.8e+02, 1.2e+03, 7.5e+01
Total CPU time (secs)     = 0.13
CPU time per iteration    = 0.01
termination code          = 0
DIMACS errors: 1.9e-08  0.0e+00  1.1e-11  0.0e+00  9.1e-08  8.6e-08
-----

```

```
ans =
```

```
35.7674
```

```
Epoch... 51
```

```
Epoch... 52
```

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 272
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|5.8e+00|2.2e+06| 3.669741e+04  0.000000e+00| 0:0:00| chol 1 1
1|0.978|0.974|2.2e-02|2.5e-01|1.3e+05| 3.532378e+04  1.483056e+01| 0:0:00| chol 1 1
2|1.000|1.000|2.9e-07|3.3e-02|3.5e+04| 2.564840e+04 -6.787650e+01| 0:0:00| chol 1 1
3|0.998|0.994|2.9e-08|1.0e-02|1.2e+03| 7.668776e+02 -3.912924e+01| 0:0:00| chol 1 1
4|0.925|0.401|3.3e-07|7.2e-03|9.2e+02| 6.693114e+02 -2.727000e+01| 0:0:00| chol 1 1
5|0.447|0.860|1.9e-07|1.8e-03|6.3e+02| 5.458610e+02 -2.574972e+01| 0:0:00| chol 2 2
6|0.623|0.545|7.5e-08|9.5e-04|4.5e+02| 3.799946e+02 -2.308412e+01| 0:0:00| chol 2 2
7|0.554|0.311|9.8e-08|6.8e-04|3.8e+02| 2.976821e+02 -2.498141e+01| 0:0:00| chol 2 1
8|0.810|0.491|6.9e-08|3.6e-04|3.1e+02| 2.361418e+02 -3.320420e+01| 0:0:00| chol 2 1
9|0.382|0.574|4.3e-08|1.6e-04|2.6e+02| 2.000739e+02 -3.437955e+01| 0:0:00| chol 2 2
10|1.000|1.000|2.9e-10|6.0e-06|1.3e+02| 8.600578e+01 -3.995942e+01| 0:0:00| chol 2 2
11|0.871|0.652|3.3e-10|4.1e-06|2.5e+01| -1.174094e+01 -3.670786e+01| 0:0:00| chol 2 2
12|0.848|0.917|1.2e-10|1.7e-06|8.4e+00| -2.748726e+01 -3.572201e+01| 0:0:00| chol 2 2
13|0.961|0.943|3.7e-10|8.1e-07|4.8e-01| -3.505775e+01 -3.547994e+01| 0:0:00| chol 2 2
14|0.924|0.861|1.1e-09|4.4e-07|8.5e-02| -3.543698e+01 -3.548871e+01| 0:0:00| chol 2 2
15|0.949|1.000|1.0e-09|1.9e-07|3.6e-02| -3.548203e+01 -3.550393e+01| 0:0:00| chol 2 2
16|1.000|1.000|2.9e-09|9.4e-08|1.2e-02| -3.550559e+01 -3.551024e+01| 0:0:00| chol 2 2
17|0.924|0.932|5.3e-09|5.0e-08|1.1e-03| -3.551588e+01 -3.551319e+01| 0:0:00| chol 3 3
18|1.000|1.000|1.9e-08|1.9e-10|3.3e-04| -3.551664e+01 -3.551696e+01| 0:0:00| chol 4 4
19|0.987|0.986|8.2e-10|8.2e-12|4.7e-06| -3.551694e+01 -3.551695e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
-----
number of iterations      = 19
primal objective value    = -3.55169416e+01
dual objective value      = -3.55169456e+01

```

```

gap := trace(XZ)          = 4.66e-06
relative gap              = 6.47e-08
actual relative gap       = 5.59e-08
rel. primal infeas        = 8.20e-10
rel. dual infeas          = 8.18e-12
norm(X), norm(y), norm(Z) = 7.5e+03, 9.2e+01, 5.9e+01
norm(A), norm(b), norm(C) = 2.8e+02, 1.2e+03, 7.5e+01
Total CPU time (secs)     = 0.09
CPU time per iteration    = 0.00
termination code          = 0
DIMACS errors: 2.5e-09  0.0e+00  1.1e-11  0.0e+00  5.6e-08  6.5e-08
-----

```

```
ans =
```

```
35.5169
```

```
Epoch... 53
```

```
Epoch... 54
```

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 272
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|5.8e+00|2.2e+06| 3.678514e+04  0.000000e+00| 0:0:00| chol 1 1
1|0.978|0.974|2.2e-02|2.6e-01|1.3e+05| 3.541662e+04  1.505883e+01| 0:0:00| chol 1 1
2|1.000|1.000|2.9e-07|3.3e-02|3.5e+04| 2.577809e+04 -6.823728e+01| 0:0:00| chol 1 1
3|0.998|0.994|2.9e-08|1.0e-02|1.2e+03| 7.676975e+02 -3.917180e+01| 0:0:00| chol 1 1
4|0.930|0.398|3.4e-07|7.2e-03|9.2e+02| 6.707389e+02 -2.729468e+01| 0:0:00| chol 1 1
5|0.445|0.859|1.9e-07|1.8e-03|6.3e+02| 5.476949e+02 -2.585889e+01| 0:0:00| chol 2 2
6|0.617|0.547|7.7e-08|9.5e-04|4.6e+02| 3.826921e+02 -2.304611e+01| 0:0:00| chol 2 2
7|0.549|0.311|9.8e-08|6.8e-04|3.9e+02| 3.006528e+02 -2.496894e+01| 0:0:00| chol 2 2
8|0.808|0.492|6.9e-08|3.6e-04|3.1e+02| 2.382837e+02 -3.310950e+01| 0:0:00| chol 2 1
9|0.380|0.575|4.3e-08|1.6e-04|2.6e+02| 2.023023e+02 -3.429425e+01| 0:0:00| chol 2 2
10|1.000|1.000|3.2e-10|6.0e-06|1.3e+02| 8.666123e+01 -3.976829e+01| 0:0:00| chol 2 2
11|0.866|0.667|2.5e-10|4.0e-06|2.6e+01| -1.055708e+01 -3.641879e+01| 0:0:00| chol 2 2
12|0.809|0.920|7.3e-11|1.7e-06|9.5e+00| -2.618770e+01 -3.550904e+01| 0:0:00| chol 2 2
13|0.966|0.951|4.0e-10|8.0e-07|5.3e-01| -3.476989e+01 -3.524096e+01| 0:0:00| chol 2 2
14|0.909|0.863|1.1e-09|4.3e-07|8.9e-02| -3.519140e+01 -3.524785e+01| 0:0:00| chol 2 2
15|0.949|1.000|1.1e-09|1.9e-07|3.8e-02| -3.523824e+01 -3.526272e+01| 0:0:00| chol 2 2
16|1.000|1.000|4.2e-09|9.4e-08|1.2e-02| -3.526423e+01 -3.526880e+01| 0:0:00| chol 2 2
17|0.931|0.936|3.0e-09|5.0e-08|9.7e-04| -3.527445e+01 -3.527171e+01| 0:0:00| chol 3 3
18|1.000|1.000|1.6e-08|1.1e-10|2.5e-04| -3.527515e+01 -3.527539e+01| 0:0:00| chol 4 4
19|1.000|0.993|7.8e-10|6.4e-12|4.6e-06| -3.527538e+01 -3.527538e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
-----
number of iterations   = 19
primal objective value = -3.52753769e+01
dual objective value   = -3.52753811e+01

```

```

gap := trace(XZ)          = 4.56e-06
relative gap              = 6.37e-08
actual relative gap       = 5.92e-08
rel. primal infeas        = 7.81e-10
rel. dual infeas          = 6.35e-12
norm(X), norm(y), norm(Z) = 7.4e+03, 9.2e+01, 5.9e+01
norm(A), norm(b), norm(C) = 2.8e+02, 1.2e+03, 7.5e+01
Total CPU time (secs)     = 0.16
CPU time per iteration    = 0.01
termination code          = 0
DIMACS errors: 2.4e-09  0.0e+00  8.9e-12  0.0e+00  5.9e-08  6.4e-08
-----

```

```
ans =
```

```
35.2754
```

```
Epoch... 55
```

```
Epoch... 56
```

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 272
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|5.8e+00|2.2e+06| 3.687589e+04  0.000000e+00| 0:0:00| chol 1 1
1|0.978|0.974|2.2e-02|2.6e-01|1.3e+05| 3.551198e+04  1.526126e+01| 0:0:00| chol 1 1
2|1.000|1.000|2.9e-07|3.3e-02|3.6e+04| 2.588984e+04 -6.857548e+01| 0:0:00| chol 1 1
3|0.998|0.994|3.0e-08|1.0e-02|1.2e+03| 7.682813e+02 -3.920843e+01| 0:0:00| chol 1 1
4|0.935|0.394|3.4e-07|7.2e-03|9.2e+02| 6.719710e+02 -2.731771e+01| 0:0:00| chol 1 1
5|0.443|0.859|1.9e-07|1.8e-03|6.3e+02| 5.492407e+02 -2.597016e+01| 0:0:00| chol 2 2
6|0.612|0.548|7.9e-08|9.5e-04|4.6e+02| 3.850641e+02 -2.301044e+01| 0:0:00| chol 2 2
7|0.543|0.311|9.7e-08|6.8e-04|3.9e+02| 3.034039e+02 -2.495394e+01| 0:0:00| chol 2 2
8|0.797|0.493|6.8e-08|3.6e-04|3.2e+02| 2.411014e+02 -3.301198e+01| 0:0:00| chol 1 1
9|0.379|0.577|4.3e-08|1.6e-04|2.6e+02| 2.048922e+02 -3.420831e+01| 0:0:00| chol 2 2
10|1.000|1.000|1.9e-10|6.0e-06|1.3e+02| 8.727278e+01 -3.957355e+01| 0:0:00| chol 2 2
11|0.861|0.682|3.8e-10|4.0e-06|2.7e+01| -9.405768e+00 -3.613699e+01| 0:0:00| chol 2 2
12|0.771|0.924|1.4e-10|1.7e-06|1.1e+01| -2.486800e+01 -3.530677e+01| 0:0:00| chol 2 2
13|0.973|0.963|4.1e-10|7.9e-07|5.7e-01| -3.449869e+01 -3.501080e+01| 0:0:00| chol 2 2
14|0.897|0.870|1.1e-09|4.3e-07|9.4e-02| -3.495433e+01 -3.501659e+01| 0:0:00| chol 2 2
15|0.982|1.000|1.3e-09|1.9e-07|3.9e-02| -3.500539e+01 -3.503116e+01| 0:0:00| chol 2 2
16|1.000|1.000|2.0e-09|9.4e-08|1.1e-02| -3.503286e+01 -3.503701e+01| 0:0:00| chol 2 2
17|0.937|0.939|3.5e-09|5.0e-08|8.1e-04| -3.504270e+01 -3.503987e+01| 0:0:00| chol 3 3
18|1.000|1.000|1.7e-08|2.2e-10|1.9e-04| -3.504331e+01 -3.504348e+01| 0:0:00| chol 3 3
19|1.000|0.991|4.0e-10|6.4e-12|3.5e-06| -3.504347e+01 -3.504347e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
-----
number of iterations    = 19
primal objective value  = -3.50434708e+01
dual objective value    = -3.50434736e+01

```

```

gap := trace(XZ)          = 3.47e-06
relative gap              = 4.88e-08
actual relative gap       = 3.98e-08
rel. primal infeas        = 4.01e-10
rel. dual infeas          = 6.37e-12
norm(X), norm(y), norm(Z) = 7.3e+03, 9.2e+01, 5.9e+01
norm(A), norm(b), norm(C) = 2.8e+02, 1.2e+03, 7.5e+01
Total CPU time (secs)     = 0.13
CPU time per iteration    = 0.01
termination code          = 0
DIMACS errors: 1.2e-09  0.0e+00  8.9e-12  0.0e+00  4.0e-08  4.9e-08
-----

```

```
ans =
```

```
35.0435
```

```
Epoch... 57
```

```
Epoch... 58
```

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 272
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|5.8e+00|2.2e+06| 3.716607e+04  0.000000e+00| 0:0:00| chol 1 1
1|0.978|0.974|2.2e-02|2.6e-01|1.3e+05| 3.579482e+04  1.539533e+01| 0:0:00| chol 1 1
2|1.000|1.000|2.9e-07|3.3e-02|3.6e+04| 2.604742e+04 -6.902747e+01| 0:0:00| chol 1 1
3|0.998|0.994|3.0e-08|1.0e-02|1.2e+03| 7.700795e+02 -3.930521e+01| 0:0:00| chol 1 1
4|0.942|0.390|3.4e-07|7.3e-03|9.3e+02| 6.746130e+02 -2.737374e+01| 0:0:00| chol 1 1
5|0.441|0.858|1.9e-07|1.8e-03|6.3e+02| 5.521377e+02 -2.612177e+01| 0:0:00| chol 1 1
6|0.608|0.550|8.1e-08|9.6e-04|4.6e+02| 3.883479e+02 -2.299211e+01| 0:0:00| chol 2 2
7|0.538|0.311|9.6e-08|6.8e-04|3.9e+02| 3.068200e+02 -2.495402e+01| 0:0:00| chol 2 1
8|0.778|0.495|6.7e-08|3.6e-04|3.2e+02| 2.449572e+02 -3.294016e+01| 0:0:00| chol 2 1
9|0.380|0.582|4.2e-08|1.6e-04|2.7e+02| 2.081016e+02 -3.415382e+01| 0:0:00| chol 2 2
10|1.000|1.000|3.7e-10|6.0e-06|1.3e+02| 8.768605e+01 -3.936164e+01| 0:0:00| chol 2 2
11|0.855|0.697|3.8e-10|3.9e-06|2.8e+01|-8.266344e+00 -3.585543e+01| 0:0:00| chol 2 2
12|0.736|0.929|1.6e-10|1.7e-06|1.2e+01|-2.352898e+01 -3.511052e+01| 0:0:00| chol 2 2
13|0.988|0.986|3.3e-10|7.6e-07|6.5e-01|-3.419351e+01 -3.478636e+01| 0:0:00| chol 2 2
14|0.887|0.881|1.0e-09|4.2e-07|9.7e-02|-3.472314e+01 -3.479003e+01| 0:0:00| chol 2 2
15|1.000|1.000|1.4e-09|1.9e-07|4.1e-02|-3.477667e+01 -3.480434e+01| 0:0:00| chol 2 2
16|1.000|1.000|1.3e-09|9.4e-08|7.0e-03|-3.480955e+01 -3.480986e+01| 0:0:00| chol 2 2
17|0.950|1.000|1.7e-08|1.7e-10|8.3e-04|-3.481553e+01 -3.481635e+01| 0:0:00| chol 3 4
18|0.983|0.981|1.0e-09|2.3e-11|1.6e-05|-3.481632e+01 -3.481633e+01| 0:0:00| chol 8 10
19|1.000|0.990|1.1e-09|1.4e-12|9.3e-07|-3.481633e+01 -3.481633e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
-----
number of iterations   = 19
primal objective value = -3.48163283e+01
dual objective value   = -3.48163293e+01

```

```

gap := trace(XZ)          = 9.26e-07
relative gap              = 1.31e-08
actual relative gap      = 1.48e-08
rel. primal infeas       = 1.09e-09
rel. dual infeas         = 1.40e-12
norm(X), norm(y), norm(Z) = 7.1e+03, 9.2e+01, 5.9e+01
norm(A), norm(b), norm(C) = 2.8e+02, 1.2e+03, 7.5e+01
Total CPU time (secs)    = 0.12
CPU time per iteration    = 0.01
termination code          = 0
DIMACS errors: 3.4e-09  0.0e+00  2.0e-12  0.0e+00  1.5e-08  1.3e-08
-----

```

```
ans =
```

```
34.8163
```

```
Epoch... 59
```

```
Epoch... 60
```

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 272
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|5.8e+00|2.2e+06| 3.724881e+04  0.000000e+00| 0:0:00| chol 1 1
1|0.978|0.974|2.2e-02|2.6e-01|1.3e+05| 3.588255e+04  1.559039e+01| 0:0:00| chol 1 1
2|1.000|1.000|2.8e-07|3.3e-02|3.6e+04| 2.617015e+04 -6.937838e+01| 0:0:00| chol 1 1
3|0.998|0.994|3.0e-08|1.0e-02|1.2e+03| 7.708383e+02 -3.935029e+01| 0:0:00| chol 1 1
4|0.946|0.388|3.4e-07|7.3e-03|9.3e+02| 6.760055e+02 -2.739923e+01| 0:0:00| chol 1 1
5|0.439|0.858|1.9e-07|1.8e-03|6.4e+02| 5.536191e+02 -2.621328e+01| 0:0:00| chol 2 2
6|0.602|0.551|8.2e-08|9.6e-04|4.6e+02| 3.908431e+02 -2.296114e+01| 0:0:00| chol 2 2
7|0.534|0.310|9.6e-08|6.8e-04|4.0e+02| 3.096018e+02 -2.495059e+01| 0:0:00| chol 2 2
8|0.757|0.497|6.8e-08|3.6e-04|3.2e+02| 2.486983e+02 -3.287951e+01| 0:0:00| chol 2 1
9|0.383|0.586|4.2e-08|1.5e-04|2.7e+02| 2.109465e+02 -3.408972e+01| 0:0:00| chol 2 2
10|1.000|1.000|4.7e-10|6.0e-06|1.3e+02| 8.823287e+01 -3.916891e+01| 0:0:00| chol 2 2
11|0.850|0.710|2.6e-10|3.9e-06|2.9e+01| -7.192363e+00 -3.559026e+01| 0:0:00| chol 2 2
12|0.706|0.935|9.0e-11|1.7e-06|1.3e+01| -2.222700e+01 -3.492276e+01| 0:0:00| chol 2 2
13|1.000|0.992|4.8e-10|7.6e-07|8.9e-01| -3.373960e+01 -3.457992e+01| 0:0:00| chol 2 2
14|0.912|0.905|1.1e-09|4.1e-07|8.6e-02| -3.451299e+01 -3.457047e+01| 0:0:00| chol 2 2
15|0.994|1.000|9.4e-10|1.9e-07|3.3e-02| -3.456377e+01 -3.458347e+01| 0:0:00| chol 2 2
16|1.000|1.000|2.6e-09|9.4e-08|1.0e-02| -3.458582e+01 -3.458925e+01| 0:0:00| chol 2 2
17|0.961|0.955|5.7e-09|4.9e-08|4.4e-04| -3.459509e+01 -3.459208e+01| 0:0:00| chol 3 3
18|1.000|1.000|2.1e-08|1.1e-10|8.6e-05| -3.459543e+01 -3.459550e+01| 0:0:00| chol 5 5
19|1.000|0.990|7.1e-10|3.0e-12|1.5e-06| -3.459550e+01 -3.459550e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
-----
number of iterations    = 19
primal objective value  = -3.45954996e+01
dual objective value    = -3.45955014e+01

```

```

gap := trace(XZ)          = 1.51e-06
relative gap              = 2.14e-08
actual relative gap      = 2.48e-08
rel. primal infeas       = 7.12e-10
rel. dual infeas         = 3.02e-12
norm(X), norm(y), norm(Z) = 7.0e+03, 9.2e+01, 5.9e+01
norm(A), norm(b), norm(C) = 2.9e+02, 1.2e+03, 7.5e+01
Total CPU time (secs)    = 0.14
CPU time per iteration   = 0.01
termination code          = 0
DIMACS errors: 2.2e-09  0.0e+00  4.2e-12  0.0e+00  2.5e-08  2.1e-08
-----

```

```
ans =
```

```
34.5955
```

```
Epoch... 61
```

```
Epoch... 62
```

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 272
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|5.9e+00|2.2e+06| 3.732488e+04  0.000000e+00| 0:0:00| chol 1 1
1|0.979|0.974|2.1e-02|2.6e-01|1.3e+05| 3.596362e+04  1.575490e+01| 0:0:00| chol 1 1
2|1.000|1.000|2.8e-07|3.3e-02|3.6e+04| 2.625934e+04 -6.968332e+01| 0:0:00| chol 1 1
3|0.998|0.994|3.1e-08|1.0e-02|1.2e+03| 7.712367e+02 -3.937470e+01| 0:0:00| chol 1 1
4|0.950|0.385|3.5e-07|7.3e-03|9.3e+02| 6.770783e+02 -2.741294e+01| 0:0:00| chol 1 1
5|0.438|0.857|1.9e-07|1.8e-03|6.4e+02| 5.547982e+02 -2.630449e+01| 0:0:00| chol 2 1
6|0.597|0.552|8.4e-08|9.6e-04|4.7e+02| 3.931698e+02 -2.292030e+01| 0:0:00| chol 2 2
7|0.528|0.310|9.5e-08|6.8e-04|4.0e+02| 3.124960e+02 -2.493967e+01| 0:0:00| chol 2 2
8|0.722|0.499|6.9e-08|3.6e-04|3.3e+02| 2.537954e+02 -3.281421e+01| 0:0:00| chol 2 1
9|0.389|0.591|4.2e-08|1.5e-04|2.7e+02| 2.145826e+02 -3.402868e+01| 0:0:00| chol 2 2
10|1.000|1.000|2.5e-10|6.0e-06|1.3e+02| 8.866785e+01 -3.896663e+01| 0:0:00| chol 2 2
11|0.844|0.724|3.5e-10|3.8e-06|3.0e+01| -6.098878e+00 -3.532897e+01| 0:0:00| chol 2 2
12|0.678|0.943|1.7e-10|1.6e-06|1.4e+01| -2.087689e+01 -3.474651e+01| 0:0:00| chol 2 2
13|1.000|1.000|4.7e-10|7.5e-07|1.5e+00| -3.293143e+01 -3.439081e+01| 0:0:00| chol 2 2
14|0.934|0.934|1.3e-09|4.0e-07|1.0e-01| -3.428350e+01 -3.435987e+01| 0:0:00| chol 2 2
15|0.988|0.978|1.1e-09|1.9e-07|3.2e-02| -3.435283e+01 -3.437128e+01| 0:0:00| chol 2 2
16|1.000|1.000|1.7e-09|9.4e-08|1.2e-02| -3.437152e+01 -3.437735e+01| 0:0:00| chol 2 2
17|0.968|0.967|2.3e-09|4.9e-08|4.4e-04| -3.438299e+01 -3.438007e+01| 0:0:00| chol 3 3
18|1.000|1.000|1.6e-08|7.2e-11|5.5e-05| -3.438334e+01 -3.438340e+01| 0:0:00| chol 5 5
19|1.000|0.990|1.9e-09|1.6e-12|6.9e-07| -3.438340e+01 -3.438340e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
-----
number of iterations    = 19
primal objective value  = -3.43833974e+01
dual objective value    = -3.43833982e+01

```

```

gap := trace(XZ)          = 6.91e-07
relative gap              = 9.91e-09
actual relative gap      = 1.07e-08
rel. primal infeas       = 1.90e-09
rel. dual infeas         = 1.61e-12
norm(X), norm(y), norm(Z) = 6.9e+03, 9.2e+01, 5.9e+01
norm(A), norm(b), norm(C) = 2.9e+02, 1.2e+03, 7.5e+01
Total CPU time (secs)    = 0.14
CPU time per iteration    = 0.01
termination code          = 0
DIMACS errors: 5.8e-09  0.0e+00  2.3e-12  0.0e+00  1.1e-08  9.9e-09
-----

```

```
ans =
```

```
34.3834
```

```
Epoch... 63
```

```
Epoch... 64
```

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 272
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|5.9e+00|2.3e+06| 3.751399e+04  0.000000e+00| 0:0:00| chol 1 1
1|0.979|0.974|2.1e-02|2.6e-01|1.3e+05| 3.615189e+04  1.594785e+01| 0:0:00| chol 1 1
2|1.000|1.000|2.4e-07|5.5e-02|3.7e+04| 2.284459e+04 -6.318091e+01| 0:0:00| chol 1 1
3|1.000|1.000|2.1e-08|1.6e-02|2.0e+03| 1.385482e+03 -3.647675e+01| 0:0:00| chol 1 1
4|0.959|0.756|1.9e-07|7.8e-03|1.2e+03| 9.412696e+02 -2.561244e+01| 0:0:00| chol 1 1
5|0.610|0.979|7.5e-08|1.6e-03|7.7e+02| 6.948631e+02 -2.555351e+01| 0:0:00| chol 2 2
6|0.660|0.561|3.1e-08|9.6e-04|5.5e+02| 4.745723e+02 -2.295610e+01| 0:0:00| chol 2 2
7|0.541|0.322|8.6e-08|6.9e-04|4.6e+02| 3.728765e+02 -2.485500e+01| 0:0:00| chol 2 2
8|1.000|0.467|5.0e-08|3.9e-04|3.6e+02| 2.710627e+02 -3.257649e+01| 0:0:00| chol 2 1
9|0.307|0.579|3.6e-08|1.8e-04|2.8e+02| 2.219582e+02 -3.396845e+01| 0:0:00| chol 2 2
10|1.000|1.000|5.1e-10|1.0e-05|1.3e+02| 9.124148e+01 -3.869835e+01| 0:0:00| chol 2 2
11|0.844|0.760|4.0e-10|6.2e-06|3.1e+01| -4.011691e+00 -3.485049e+01| 0:0:00| chol 2 2
12|0.599|0.970|1.6e-10|2.6e-06|1.7e+01| -1.810290e+01 -3.454538e+01| 0:0:00| chol 2 2
13|1.000|1.000|3.4e-10|1.3e-06|3.7e+00| -3.064309e+01 -3.423367e+01| 0:0:00| chol 2 2
14|0.960|0.936|2.3e-09|6.7e-07|1.5e-01| -3.402429e+01 -3.413260e+01| 0:0:00| chol 2 2
15|0.933|0.878|9.1e-10|3.6e-07|2.3e-02| -3.414709e+01 -3.414555e+01| 0:0:00| chol 2 2
16|1.000|0.926|2.7e-09|1.7e-07|8.8e-03| -3.415978e+01 -3.415695e+01| 0:0:00| chol 2 2
17|1.000|1.000|2.6e-09|7.8e-08|3.2e-03| -3.416512e+01 -3.416297e+01| 0:0:00| chol 2 2
18|0.985|0.975|4.6e-08|2.1e-09|7.1e-05| -3.416810e+01 -3.416804e+01| 0:0:00| chol 4 4
19|1.000|0.990|1.5e-09|2.3e-11|1.9e-06| -3.416816e+01 -3.416816e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
-----
number of iterations    = 19
primal objective value  = -3.41681619e+01
dual objective value    = -3.41681638e+01

```



```

gap := trace(XZ)          = 1.93e-06
relative gap              = 2.79e-08
actual relative gap       = 2.85e-08
rel. primal infeas        = 1.47e-09
rel. dual infeas          = 2.26e-11
norm(X), norm(y), norm(Z) = 6.8e+03, 9.2e+01, 5.9e+01
norm(A), norm(b), norm(C) = 2.9e+02, 1.2e+03, 7.5e+01
Total CPU time (secs)     = 0.14
CPU time per iteration    = 0.01
termination code          = 0
DIMACS errors: 4.5e-09  0.0e+00  3.2e-11  0.0e+00  2.9e-08  2.8e-08
-----

```

```
ans =
```

```
34.1682
```

```
Epoch... 65
```

```
Epoch... 66
```

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 272
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|5.9e+00|2.3e+06| 3.757295e+04  0.000000e+00| 0:0:00| chol 1 1
1|0.979|0.974|2.1e-02|2.6e-01|1.3e+05| 3.621689e+04  1.610755e+01| 0:0:00| chol 1 1
2|1.000|1.000|2.4e-07|5.5e-02|3.7e+04| 2.293075e+04 -6.347953e+01| 0:0:00| chol 1 1
3|1.000|1.000|2.1e-08|1.6e-02|2.1e+03| 1.390567e+03 -3.653193e+01| 0:0:00| chol 1 1
4|0.965|0.754|1.9e-07|7.8e-03|1.2e+03| 9.414314e+02 -2.563220e+01| 0:0:00| chol 1 1
5|0.602|0.979|7.6e-08|1.6e-03|7.7e+02| 6.985297e+02 -2.558470e+01| 0:0:00| chol 2 1
6|0.654|0.563|3.2e-08|9.6e-04|5.6e+02| 4.790108e+02 -2.294203e+01| 0:0:00| chol 2 2
7|0.534|0.321|8.6e-08|6.9e-04|4.7e+02| 3.778408e+02 -2.484927e+01| 0:0:00| chol 2 2
8|1.000|0.467|4.9e-08|3.9e-04|3.6e+02| 2.745119e+02 -3.259605e+01| 0:0:00| chol 2 1
9|0.311|0.583|3.6e-08|1.7e-04|2.9e+02| 2.253844e+02 -3.394755e+01| 0:0:00| chol 1 2
10|1.000|1.000|3.9e-10|1.0e-05|1.3e+02| 9.203640e+01 -3.853354e+01| 0:0:00| chol 2 2
11|0.840|0.774|2.0e-10|6.1e-06|3.2e+01| -3.117709e+00 -3.460468e+01| 0:0:00| chol 2 2
12|0.580|0.990|7.7e-11|2.5e-06|1.8e+01| -1.683491e+01 -3.439518e+01| 0:0:00| chol 2 2
13|1.000|1.000|3.5e-10|1.3e-06|5.0e+00| -2.921829e+01 -3.408531e+01| 0:0:00| chol 2 2
14|0.964|0.931|2.9e-09|6.7e-07|1.9e-01| -3.378505e+01 -3.393401e+01| 0:0:00| chol 2 2
15|0.924|0.895|8.9e-10|3.5e-07|2.3e-02| -3.394283e+01 -3.394295e+01| 0:0:00| chol 2 2
16|1.000|0.881|1.3e-09|1.8e-07|8.7e-03| -3.395641e+01 -3.395309e+01| 0:0:00| chol 2 2
17|1.000|1.000|5.0e-09|7.8e-08|3.2e-03| -3.396148e+01 -3.395949e+01| 0:0:00| chol 3 3
18|0.985|0.980|4.7e-09|1.7e-09|7.2e-05| -3.396453e+01 -3.396449e+01| 0:0:00| chol 4 4
19|1.000|0.990|1.1e-09|1.8e-11|1.3e-06| -3.396459e+01 -3.396459e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
-----
number of iterations    = 19
primal objective value  = -3.39645916e+01
dual objective value    = -3.39645915e+01

```

```

gap := trace(XZ)          = 1.32e-06
relative gap              = 1.91e-08
actual relative gap       = -2.52e-09
rel. primal infeas        = 1.12e-09
rel. dual infeas          = 1.79e-11
norm(X), norm(y), norm(Z) = 6.7e+03, 9.2e+01, 5.9e+01
norm(A), norm(b), norm(C) = 2.9e+02, 1.2e+03, 7.5e+01
Total CPU time (secs)     = 0.11
CPU time per iteration    = 0.01
termination code          = 0
DIMACS errors: 3.5e-09  0.0e+00  2.5e-11  0.0e+00  -2.5e-09  1.9e-08
-----

```

```
ans =
```

```
33.9646
```

```
Epoch... 67
```

```
Epoch... 68
```

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 272
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|5.9e+00|2.3e+06| 3.761340e+04  0.000000e+00| 0:0:00| chol 1 1
1|0.979|0.974|2.1e-02|2.6e-01|1.3e+05| 3.626468e+04  1.629213e+01| 0:0:00| chol 1 1
2|1.000|1.000|2.4e-07|5.5e-02|3.7e+04| 2.302281e+04 -6.374920e+01| 0:0:00| chol 1 1
3|1.000|1.000|2.1e-08|1.7e-02|2.1e+03| 1.396010e+03 -3.657255e+01| 0:0:00| chol 1 1
4|0.971|0.752|1.9e-07|7.8e-03|1.2e+03| 9.417431e+02 -2.564504e+01| 0:0:00| chol 1 1
5|0.596|0.979|7.8e-08|1.6e-03|7.8e+02| 7.015666e+02 -2.560941e+01| 0:0:00| chol 2 2
6|0.647|0.565|3.3e-08|9.6e-04|5.6e+02| 4.831661e+02 -2.292091e+01| 0:0:00| chol 2 2
7|0.526|0.319|8.6e-08|6.9e-04|4.7e+02| 3.829225e+02 -2.483974e+01| 0:0:00| chol 2 2
8|1.000|0.467|4.8e-08|3.9e-04|3.6e+02| 2.779572e+02 -3.262018e+01| 0:0:00| chol 1 1
9|0.316|0.589|3.5e-08|1.7e-04|2.9e+02| 2.292911e+02 -3.393515e+01| 0:0:00| chol 2 2
10|1.000|1.000|4.1e-10|1.0e-05|1.3e+02| 9.262777e+01 -3.836018e+01| 0:0:00| chol 2 2
11|0.837|0.788|3.2e-10|6.1e-06|3.3e+01| -2.336326e+00 -3.436507e+01| 0:0:00| chol 2 2
12|0.566|1.000|1.3e-10|2.5e-06|1.9e+01| -1.565900e+01 -3.425854e+01| 0:0:00| chol 2 2
13|1.000|1.000|3.6e-10|1.3e-06|5.7e+00| -2.835970e+01 -3.391934e+01| 0:0:00| chol 2 2
14|0.966|0.929|3.4e-09|6.7e-07|2.2e-01| -3.356815e+01 -3.374021e+01| 0:0:00| chol 2 2
15|0.924|0.901|9.6e-10|3.5e-07|2.4e-02| -3.374552e+01 -3.374677e+01| 0:0:00| chol 2 2
16|0.989|0.863|1.8e-09|1.8e-07|8.4e-03| -3.375984e+01 -3.375629e+01| 0:0:00| chol 2 2
17|1.000|1.000|3.2e-09|7.8e-08|3.1e-03| -3.376476e+01 -3.376276e+01| 0:0:00| chol 2 2
18|0.985|0.981|2.0e-08|1.6e-09|7.2e-05| -3.376771e+01 -3.376768e+01| 0:0:00| chol 4 4
19|1.000|0.990|1.0e-09|1.7e-11|1.4e-06| -3.376777e+01 -3.376778e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
-----
number of iterations    = 19
primal objective value  = -3.37677743e+01
dual objective value    = -3.37677756e+01

```

```

gap := trace(XZ)          = 1.37e-06
relative gap              = 2.00e-08
actual relative gap      = 1.79e-08
rel. primal infeas       = 9.99e-10
rel. dual infeas         = 1.74e-11
norm(X), norm(y), norm(Z) = 6.5e+03, 9.2e+01, 5.9e+01
norm(A), norm(b), norm(C) = 2.9e+02, 1.2e+03, 7.5e+01
Total CPU time (secs)    = 0.12
CPU time per iteration    = 0.01
termination code          = 0
DIMACS errors: 3.1e-09  0.0e+00  2.4e-11  0.0e+00  1.8e-08  2.0e-08
-----

```

```
ans =
```

```
33.7678
```

```
Epoch... 69
```

```
Epoch... 70
```

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 272
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|5.9e+00|2.3e+06| 3.765464e+04  0.000000e+00| 0:0:00| chol 1 1
1|0.979|0.974|2.1e-02|2.6e-01|1.3e+05| 3.631280e+04  1.642908e+01| 0:0:00| chol 1 1
2|1.000|1.000|2.4e-07|5.5e-02|3.7e+04| 2.310130e+04 -6.402670e+01| 0:0:00| chol 1 1
3|1.000|0.999|2.1e-08|1.7e-02|2.1e+03| 1.400615e+03 -3.661877e+01| 0:0:00| chol 1 1
4|0.976|0.750|1.9e-07|7.8e-03|1.2e+03| 9.416619e+02 -2.566193e+01| 0:0:00| chol 1 1
5|0.590|0.979|8.0e-08|1.6e-03|7.8e+02| 7.044128e+02 -2.563848e+01| 0:0:00| chol 2 1
6|0.640|0.567|3.4e-08|9.5e-04|5.6e+02| 4.873226e+02 -2.290182e+01| 0:0:00| chol 2 2
7|0.516|0.318|8.5e-08|6.9e-04|4.8e+02| 3.883508e+02 -2.483521e+01| 0:0:00| chol 2 2
8|1.000|0.468|4.7e-08|3.9e-04|3.7e+02| 2.814815e+02 -3.266264e+01| 0:0:00| chol 1 1
9|0.320|0.591|3.4e-08|1.7e-04|3.0e+02| 2.340536e+02 -3.393984e+01| 0:0:00| chol 2 2
10|1.000|1.000|4.1e-10|1.0e-05|1.3e+02| 9.232547e+01 -3.816957e+01| 0:0:00| chol 2 2
11|0.834|0.797|4.6e-10|6.0e-06|3.3e+01| -1.894872e+00 -3.414017e+01| 0:0:00| chol 2 2
12|0.559|1.000|2.1e-10|2.5e-06|2.0e+01| -1.482228e+01 -3.412384e+01| 0:0:00| chol 2 2
13|1.000|1.000|3.7e-10|1.3e-06|5.9e+00| -2.796010e+01 -3.374380e+01| 0:0:00| chol 2 2
14|0.967|0.929|3.6e-09|6.7e-07|2.2e-01| -3.337666e+01 -3.355541e+01| 0:0:00| chol 2 2
15|0.923|0.902|9.5e-10|3.5e-07|2.4e-02| -3.355927e+01 -3.356102e+01| 0:0:00| chol 2 2
16|0.982|0.858|1.2e-09|1.8e-07|8.5e-03| -3.357365e+01 -3.357026e+01| 0:0:00| chol 2 2
17|1.000|1.000|4.6e-09|7.8e-08|3.1e-03| -3.357860e+01 -3.357667e+01| 0:0:00| chol 2 2
18|0.985|0.980|5.2e-08|1.6e-09|7.2e-05| -3.358154e+01 -3.358151e+01| 0:0:00| chol 3 3
19|1.000|0.990|1.7e-09|1.8e-11|1.5e-06| -3.358160e+01 -3.358160e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
-----
number of iterations    = 19
primal objective value  = -3.35816014e+01
dual objective value    = -3.35816019e+01

```

```

gap := trace(XZ)          = 1.49e-06
relative gap              = 2.18e-08
actual relative gap       = 6.66e-09
rel. primal infeas        = 1.66e-09
rel. dual infeas          = 1.81e-11
norm(X), norm(y), norm(Z) = 6.4e+03, 9.2e+01, 5.9e+01
norm(A), norm(b), norm(C) = 2.9e+02, 1.2e+03, 7.5e+01
Total CPU time (secs)     = 0.16
CPU time per iteration    = 0.01
termination code          = 0
DIMACS errors: 5.1e-09  0.0e+00  2.5e-11  0.0e+00  6.7e-09  2.2e-08
-----

```

```
ans =
```

```
33.5816
```

```
Epoch... 71
```

```
Epoch... 72
```

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 272
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|6.0e+00|2.3e+06| 3.780687e+04  0.000000e+00| 0:0:00| chol 1 1
1|0.979|0.974|2.1e-02|2.6e-01|1.3e+05| 3.646603e+04  1.657611e+01| 0:0:00| chol 1 1
2|1.000|1.000|2.4e-07|5.5e-02|3.8e+04| 2.322923e+04 -6.433905e+01| 0:0:00| chol 1 1
3|1.000|0.999|2.1e-08|1.7e-02|2.1e+03| 1.408215e+03 -3.667995e+01| 0:0:00| chol 1 1
4|0.983|0.749|1.9e-07|7.9e-03|1.2e+03| 9.430438e+02 -2.567599e+01| 0:0:00| chol 1 1
5|0.586|0.979|8.1e-08|1.6e-03|7.8e+02| 7.075394e+02 -2.565507e+01| 0:0:00| chol 2 1
6|0.632|0.569|3.5e-08|9.5e-04|5.7e+02| 4.920154e+02 -2.287365e+01| 0:0:00| chol 2 2
7|0.503|0.316|8.5e-08|6.9e-04|4.8e+02| 3.946772e+02 -2.483121e+01| 0:0:00| chol 2 2
8|1.000|0.470|4.5e-08|3.9e-04|3.7e+02| 2.853154e+02 -3.274591e+01| 0:0:00| chol 1 1
9|0.322|0.597|3.3e-08|1.7e-04|3.0e+02| 2.407663e+02 -3.398908e+01| 0:0:00| chol 2 2
10|1.000|1.000|3.8e-10|1.0e-05|1.3e+02| 9.116940e+01 -3.793097e+01| 0:0:00| chol 2 2
11|0.830|0.801|3.8e-10|6.0e-06|3.3e+01| -1.847301e+00 -3.391689e+01| 0:0:00| chol 2 1
12|0.560|1.000|3.7e-10|2.5e-06|2.0e+01| -1.439878e+01 -3.397404e+01| 0:0:00| chol 2 2
13|1.000|1.000|2.1e-10|1.3e-06|5.7e+00| -2.790979e+01 -3.355181e+01| 0:0:00| chol 2 2
14|0.967|0.929|3.5e-09|6.7e-07|2.1e-01| -3.319799e+01 -3.336894e+01| 0:0:00| chol 2 2
15|0.923|0.901|9.7e-10|3.5e-07|2.3e-02| -3.337350e+01 -3.337468e+01| 0:0:00| chol 2 2
16|0.981|0.858|1.6e-09|1.8e-07|8.0e-03| -3.338743e+01 -3.338379e+01| 0:0:00| chol 2 2
17|1.000|1.000|2.5e-09|7.8e-08|2.9e-03| -3.339221e+01 -3.339011e+01| 0:0:00| chol 2 2
18|0.985|0.980|1.0e-08|1.6e-09|6.6e-05| -3.339491e+01 -3.339488e+01| 0:0:00| chol 3 3
19|1.000|0.990|2.8e-09|1.8e-11|1.4e-06| -3.339498e+01 -3.339498e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
-----
number of iterations    = 19
primal objective value  = -3.33949775e+01
dual objective value    = -3.33949783e+01

```

```

gap := trace(XZ)          = 1.43e-06
relative gap              = 2.11e-08
actual relative gap       = 1.17e-08
rel. primal infeas        = 2.75e-09
rel. dual infeas          = 1.80e-11
norm(X), norm(y), norm(Z) = 6.3e+03, 9.2e+01, 5.9e+01
norm(A), norm(b), norm(C) = 2.9e+02, 1.2e+03, 7.5e+01
Total CPU time (secs)     = 0.11
CPU time per iteration    = 0.01
termination code          = 0
DIMACS errors: 8.5e-09  0.0e+00  2.5e-11  0.0e+00  1.2e-08  2.1e-08
-----

```

```
ans =
```

```
33.3950
```

```
Epoch... 73
```

```
Epoch... 74
```

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 272
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|6.0e+00|2.3e+06| 3.786204e+04  0.000000e+00| 0:0:00| chol 1 1
1|0.979|0.974|2.1e-02|2.6e-01|1.3e+05| 3.652682e+04  1.672833e+01| 0:0:00| chol 1 1
2|1.000|1.000|2.4e-07|5.5e-02|3.8e+04| 2.330889e+04 -6.461624e+01| 0:0:00| chol 1 1
3|1.000|0.999|2.1e-08|1.7e-02|2.1e+03| 1.412977e+03 -3.672801e+01| 0:0:00| chol 1 1
4|0.988|0.746|1.9e-07|7.9e-03|1.2e+03| 9.430194e+02 -2.569203e+01| 0:0:00| chol 1 1
5|0.580|0.979|8.2e-08|1.6e-03|7.9e+02| 7.103896e+02 -2.568845e+01| 0:0:00| chol 1 2
6|0.626|0.571|3.6e-08|9.5e-04|5.7e+02| 4.959400e+02 -2.285071e+01| 0:0:00| chol 2 2
7|0.490|0.315|8.4e-08|6.9e-04|4.9e+02| 4.006377e+02 -2.482193e+01| 0:0:00| chol 1 2
8|1.000|0.472|4.4e-08|3.8e-04|3.7e+02| 2.885764e+02 -3.280180e+01| 0:0:00| chol 2 1
9|0.315|0.607|3.3e-08|1.6e-04|3.1e+02| 2.489614e+02 -3.405350e+01| 0:0:00| chol 2 2
10|1.000|1.000|4.4e-10|1.0e-05|1.3e+02| 8.976005e+01 -3.763559e+01| 0:0:00| chol 2 2
11|0.826|0.798|3.8e-10|6.0e-06|3.2e+01| -1.919355e+00 -3.370765e+01| 0:0:00| chol 2 2
12|0.571|1.000|1.6e-10|2.5e-06|2.0e+01| -1.414277e+01 -3.382483e+01| 0:0:00| chol 2 2
13|1.000|1.000|3.0e-10|1.3e-06|5.3e+00| -2.812992e+01 -3.334693e+01| 0:0:00| chol 2 1
14|0.967|0.928|3.3e-09|6.7e-07|2.0e-01| -3.302653e+01 -3.318240e+01| 0:0:00| chol 2 2
15|0.920|0.893|9.9e-10|3.5e-07|2.4e-02| -3.318745e+01 -3.318906e+01| 0:0:00| chol 2 2
16|0.986|0.865|1.3e-09|1.8e-07|8.9e-03| -3.320079e+01 -3.319827e+01| 0:0:00| chol 2 2
17|1.000|1.000|2.3e-09|7.8e-08|3.3e-03| -3.320600e+01 -3.320442e+01| 0:0:00| chol 2 2
18|0.984|0.980|1.6e-08|1.6e-09|7.1e-05| -3.320913e+01 -3.320910e+01| 0:0:00| chol 4 4
19|1.000|0.990|1.2e-09|1.8e-11|1.3e-06| -3.320919e+01 -3.320919e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
-----
number of iterations    = 19
primal objective value  = -3.32091911e+01
dual objective value    = -3.32091928e+01

```

```

gap := trace(XZ)          = 1.34e-06
relative gap              = 1.99e-08
actual relative gap       = 2.40e-08
rel. primal infeas       = 1.23e-09
rel. dual infeas         = 1.80e-11
norm(X), norm(y), norm(Z) = 6.2e+03, 9.2e+01, 5.8e+01
norm(A), norm(b), norm(C) = 2.9e+02, 1.2e+03, 7.5e+01
Total CPU time (secs)    = 0.14
CPU time per iteration    = 0.01
termination code          = 0
DIMACS errors: 3.8e-09  0.0e+00  2.5e-11  0.0e+00  2.4e-08  2.0e-08
-----

```

```
ans =
```

```
33.2092
```

```
Epoch... 75
```

```
Epoch... 76
```

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 272
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|6.0e+00|2.3e+06| 3.805024e+04  0.000000e+00| 0:0:00| chol 1 1
1|0.979|0.974|2.1e-02|2.6e-01|1.3e+05| 3.671341e+04  1.685975e+01| 0:0:00| chol 1 1
2|1.000|1.000|2.4e-07|5.5e-02|3.8e+04| 2.340528e+04 -6.488343e+01| 0:0:00| chol 1 1
3|1.000|0.999|2.1e-08|1.7e-02|2.1e+03| 1.418861e+03 -3.678100e+01| 0:0:00| chol 1 1
4|0.995|0.744|1.9e-07|7.9e-03|1.2e+03| 9.435668e+02 -2.570559e+01| 0:0:00| chol 1 1
5|0.575|0.979|8.3e-08|1.6e-03|7.9e+02| 7.134841e+02 -2.572279e+01| 0:0:00| chol 2 2
6|0.620|0.573|3.7e-08|9.5e-04|5.8e+02| 4.997282e+02 -2.283184e+01| 0:0:00| chol 2 2
7|0.478|0.315|8.2e-08|6.9e-04|4.9e+02| 4.061257e+02 -2.481519e+01| 0:0:00| chol 2 2
8|1.000|0.477|4.2e-08|3.8e-04|3.8e+02| 2.912826e+02 -3.286596e+01| 0:0:00| chol 2 1
9|0.298|0.622|3.3e-08|1.6e-04|3.2e+02| 2.587050e+02 -3.414718e+01| 0:0:00| chol 2 2
10|1.000|1.000|2.9e-10|1.0e-05|1.3e+02| 8.759434e+01 -3.723917e+01| 0:0:00| chol 2 2
11|0.850|0.807|3.5e-10|6.0e-06|3.3e+01| -1.126681e+00 -3.356519e+01| 0:0:00| chol 2 2
12|0.637|1.000|1.3e-10|2.5e-06|1.9e+01| -1.449797e+01 -3.367664e+01| 0:0:00| chol 2 2
13|1.000|1.000|2.4e-10|1.3e-06|4.0e+00| -2.915231e+01 -3.310660e+01| 0:0:00| chol 2 2
14|0.964|0.928|2.5e-09|6.7e-07|1.6e-01| -3.288382e+01 -3.299883e+01| 0:0:00| chol 2 2
15|0.922|0.878|9.1e-10|3.6e-07|2.2e-02| -3.300860e+01 -3.300888e+01| 0:0:00| chol 2 2
16|1.000|0.896|1.9e-09|1.8e-07|8.4e-03| -3.302125e+01 -3.301873e+01| 0:0:00| chol 2 2
17|1.000|1.000|2.8e-09|7.8e-08|3.0e-03| -3.302637e+01 -3.302451e+01| 0:0:00| chol 2 2
18|0.984|0.981|3.9e-08|1.6e-09|6.0e-05| -3.302917e+01 -3.302914e+01| 0:0:00| chol 3 3
19|1.000|0.990|3.7e-09|1.7e-11|1.0e-06| -3.302922e+01 -3.302922e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
-----
number of iterations    = 19
primal objective value  = -3.30292246e+01
dual objective value    = -3.30292244e+01

```

```

gap := trace(XZ)          = 1.00e-06
relative gap              = 1.50e-08
actual relative gap       = -3.23e-09
rel. primal infeas        = 3.72e-09
rel. dual infeas          = 1.67e-11
norm(X), norm(y), norm(Z) = 6.1e+03, 9.2e+01, 5.8e+01
norm(A), norm(b), norm(C) = 2.9e+02, 1.2e+03, 7.5e+01
Total CPU time (secs)     = 0.12
CPU time per iteration    = 0.01
termination code          = 0
DIMACS errors: 1.1e-08  0.0e+00  2.3e-11  0.0e+00  -3.2e-09  1.5e-08
-----

```

```
ans =
```

```
33.0292
```

```
Epoch... 77
```

```
Epoch... 78
```

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 272
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|6.0e+00|2.4e+06| 3.817415e+04  0.000000e+00| 0:0:00| chol 1 1
1|0.979|0.974|2.1e-02|2.6e-01|1.3e+05| 3.683897e+04  1.698607e+01| 0:0:00| chol 1 1
2|1.000|1.000|2.4e-07|5.5e-02|3.8e+04| 2.349119e+04 -6.515725e+01| 0:0:00| chol 1 1
3|1.000|0.999|2.2e-08|1.7e-02|2.1e+03| 1.424069e+03 -3.683195e+01| 0:0:00| chol 1 1
4|1.000|0.742|2.0e-07|7.9e-03|1.2e+03| 9.440077e+02 -2.571889e+01| 0:0:00| chol 1 1
5|0.570|0.978|8.5e-08|1.6e-03|7.9e+02| 7.159329e+02 -2.575817e+01| 0:0:00| chol 1 2
6|0.614|0.575|3.8e-08|9.5e-04|5.8e+02| 5.033476e+02 -2.280245e+01| 0:0:00| chol 2 2
7|0.462|0.314|8.1e-08|6.9e-04|5.0e+02| 4.125454e+02 -2.480490e+01| 0:0:00| chol 2 2
8|0.849|0.483|4.6e-08|3.8e-04|3.9e+02| 3.119004e+02 -3.294770e+01| 0:0:00| chol 2 1
9|0.295|0.643|3.6e-08|1.5e-04|3.4e+02| 2.818565e+02 -3.422253e+01| 0:0:00| chol 1 2
10|1.000|1.000|4.5e-10|1.0e-05|1.3e+02| 9.042853e+01 -3.701812e+01| 0:0:00| chol 2 2
11|0.863|0.812|2.8e-10|5.9e-06|3.5e+01| 7.706749e-01 -3.349380e+01| 0:0:00| chol 2 1
12|0.836|1.000|8.8e-10|2.5e-06|1.7e+01| -1.647862e+01 -3.356378e+01| 0:0:00| chol 2 2
13|1.000|0.981|4.4e-10|1.3e-06|2.1e+00| -3.081691e+01 -3.285897e+01| 0:0:00| chol 2 2
14|0.949|0.931|1.6e-09|6.7e-07|1.1e-01| -3.274616e+01 -3.281803e+01| 0:0:00| chol 2 2
15|0.962|0.860|9.3e-10|3.6e-07|2.5e-02| -3.282984e+01 -3.283231e+01| 0:0:00| chol 2 2
16|1.000|1.000|1.8e-09|1.6e-07|9.7e-03| -3.284360e+01 -3.284376e+01| 0:0:00| chol 2 2
17|0.975|0.980|3.1e-09|8.0e-08|3.6e-04| -3.285259e+01 -3.284809e+01| 0:0:00| chol 3 3
18|1.000|1.000|2.2e-08|2.5e-10|1.7e-04| -3.285277e+01 -3.285293e+01| 0:0:00| chol 3 4
19|1.000|0.990|2.8e-10|5.6e-12|2.1e-06| -3.285292e+01 -3.285292e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
-----
number of iterations    = 19
primal objective value  = -3.28529182e+01
dual objective value    = -3.28529200e+01

```

```

gap := trace(XZ)          = 2.11e-06
relative gap              = 3.17e-08
actual relative gap       = 2.66e-08
rel. primal infeas        = 2.76e-10
rel. dual infeas          = 5.60e-12
norm(X), norm(y), norm(Z) = 6.1e+03, 9.1e+01, 5.8e+01
norm(A), norm(b), norm(C) = 2.9e+02, 1.2e+03, 7.5e+01
Total CPU time (secs)    = 0.11
CPU time per iteration    = 0.01
termination code          = 0
DIMACS errors: 8.5e-10  0.0e+00  7.9e-12  0.0e+00  2.7e-08  3.2e-08
-----

```

```
ans =
```

```
32.8529
```

```
Epoch... 79
```

```
Epoch... 80
```

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 272
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|6.0e+00|2.4e+06| 3.823429e+04  0.000000e+00| 0:0:00| chol 1 1
1|0.979|0.974|2.1e-02|2.6e-01|1.3e+05| 3.690451e+04  1.709384e+01| 0:0:00| chol 1 1
2|1.000|1.000|2.4e-07|5.5e-02|3.8e+04| 2.354890e+04 -6.538457e+01| 0:0:00| chol 1 1
3|1.000|0.999|2.2e-08|1.7e-02|2.1e+03| 1.427580e+03 -3.687960e+01| 0:0:00| chol 1 1
4|1.000|0.740|2.0e-07|8.0e-03|1.2e+03| 9.459989e+02 -2.573959e+01| 0:0:00| chol 1 1
5|0.569|0.978|8.5e-08|1.6e-03|7.9e+02| 7.147935e+02 -2.582441e+01| 0:0:00| chol 2 2
6|0.606|0.581|3.9e-08|9.4e-04|5.8e+02| 5.051730e+02 -2.272915e+01| 0:0:00| chol 2 2
7|0.423|0.313|7.7e-08|6.9e-04|5.1e+02| 4.219466e+02 -2.477379e+01| 0:0:00| chol 2 2
8|0.589|0.499|5.2e-08|3.6e-04|4.2e+02| 3.473981e+02 -3.298188e+01| 0:0:00| chol 2 1
9|0.319|0.693|3.9e-08|1.3e-04|3.6e+02| 3.105520e+02 -3.446723e+01| 0:0:00| chol 2 1
10|1.000|1.000|2.2e-09|1.0e-05|1.4e+02| 9.628679e+01 -3.696457e+01| 0:0:00| chol 2 2
11|0.845|0.815|3.9e-10|5.9e-06|3.8e+01| 3.686153e+00 -3.346133e+01| 0:0:00| chol 2 1
12|0.992|1.000|4.0e-10|2.5e-06|1.7e+01| -1.659875e+01 -3.348888e+01| 0:0:00| chol 2 2
13|0.993|0.962|3.4e-10|1.3e-06|1.4e+00| -3.131251e+01 -3.267548e+01| 0:0:00| chol 2 2
14|0.935|0.927|1.3e-10|6.7e-07|1.0e-01| -3.259073e+01 -3.265209e+01| 0:0:00| chol 2 2
15|0.990|0.918|1.3e-09|3.4e-07|3.7e-02| -3.265197e+01 -3.266865e+01| 0:0:00| chol 2 2
16|1.000|1.000|1.0e-09|1.6e-07|1.5e-02| -3.267334e+01 -3.267872e+01| 0:0:00| chol 2 2
17|0.979|0.982|2.4e-09|8.0e-08|3.3e-04| -3.268725e+01 -3.268281e+01| 0:0:00| chol 3 3
18|1.000|1.000|5.2e-08|8.6e-11|1.1e-04| -3.268748e+01 -3.268757e+01| 0:0:00| chol 4 5
19|1.000|0.991|1.5e-09|3.1e-12|1.5e-06| -3.268756e+01 -3.268757e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
-----
number of iterations    = 19
primal objective value  = -3.26875649e+01
dual objective value    = -3.26875655e+01

```



```

gap := trace(XZ)          = 1.54e-06
relative gap              = 2.31e-08
actual relative gap       = 8.88e-09
rel. primal infeas        = 1.48e-09
rel. dual infeas          = 3.07e-12
norm(X), norm(y), norm(Z) = 6.0e+03, 9.1e+01, 5.8e+01
norm(A), norm(b), norm(C) = 2.9e+02, 1.2e+03, 7.5e+01
Total CPU time (secs)     = 0.12
CPU time per iteration    = 0.01
termination code          = 0
DIMACS errors: 4.5e-09  0.0e+00  4.3e-12  0.0e+00  8.9e-09  2.3e-08
-----

```

```
ans =
```

```
32.6876
```

```
Epoch... 81
```

```
Epoch... 82
```

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 272
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|6.1e+00|2.4e+06| 3.827677e+04  0.000000e+00| 0:0:00| chol 1 1
1|0.979|0.974|2.1e-02|2.6e-01|1.3e+05| 3.695336e+04  1.722858e+01| 0:0:00| chol 1 1
2|1.000|1.000|2.3e-07|5.5e-02|3.8e+04| 2.362301e+04 -6.561003e+01| 0:0:00| chol 1 1
3|1.000|0.999|2.2e-08|1.7e-02|2.1e+03| 1.432017e+03 -3.690752e+01| 0:0:00| chol 1 1
4|1.000|0.739|2.0e-07|8.0e-03|1.2e+03| 9.482089e+02 -2.574533e+01| 0:0:00| chol 1 1
5|0.570|0.977|8.4e-08|1.6e-03|7.9e+02| 7.137575e+02 -2.586784e+01| 0:0:00| chol 2 2
6|0.599|0.588|4.0e-08|9.3e-04|5.8e+02| 5.070958e+02 -2.264019e+01| 0:0:00| chol 1 1
7|0.369|0.316|7.3e-08|6.8e-04|5.2e+02| 4.344582e+02 -2.477685e+01| 0:0:00| chol 2 1
8|0.381|0.546|5.6e-08|3.3e-04|4.5e+02| 3.807442e+02 -3.318640e+01| 0:0:00| chol 2 2
9|0.371|0.762|4.0e-08|9.4e-05|3.8e+02| 3.302810e+02 -3.516016e+01| 0:0:00| chol 1 2
10|1.000|1.000|1.9e-10|1.0e-05|1.4e+02| 9.996182e+01 -3.695724e+01| 0:0:00| chol 2 2
11|0.836|0.839|2.6e-10|5.8e-06|4.1e+01| 6.594361e+00 -3.341475e+01| 0:0:00| chol 2 2
12|1.000|1.000|1.7e-11|2.5e-06|2.0e+01| -1.362579e+01 -3.339878e+01| 0:0:00| chol 2 2
13|0.968|0.943|3.0e-10|1.3e-06|1.9e+00| -3.072925e+01 -3.251728e+01| 0:0:00| chol 2 2
14|0.941|0.930|8.4e-11|6.7e-07|1.2e-01| -3.240234e+01 -3.248561e+01| 0:0:00| chol 2 2
15|1.000|0.919|9.1e-10|3.4e-07|4.2e-02| -3.248004e+01 -3.250146e+01| 0:0:00| chol 2 2
16|1.000|1.000|9.1e-10|1.6e-07|1.6e-02| -3.250438e+01 -3.251119e+01| 0:0:00| chol 2 2
17|0.979|0.982|1.6e-09|8.0e-08|3.5e-04| -3.251952e+01 -3.251518e+01| 0:0:00| chol 4 4
18|1.000|1.000|5.1e-08|2.5e-11|1.0e-04| -3.251984e+01 -3.251986e+01| 0:0:00| chol 5 6
19|1.000|0.995|2.9e-09|2.6e-12|1.6e-06| -3.251986e+01 -3.251986e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
-----
number of iterations      = 19
primal objective value    = -3.25198564e+01
dual objective value      = -3.25198605e+01

```

```

gap := trace(XZ)          = 1.62e-06
relative gap              = 2.45e-08
actual relative gap      = 6.19e-08
rel. primal infeas       = 2.94e-09
rel. dual infeas         = 2.62e-12
norm(X), norm(y), norm(Z) = 5.9e+03, 9.1e+01, 5.8e+01
norm(A), norm(b), norm(C) = 2.9e+02, 1.2e+03, 7.5e+01
Total CPU time (secs)    = 0.14
CPU time per iteration   = 0.01
termination code          = 0
DIMACS errors: 9.0e-09  0.0e+00  3.7e-12  0.0e+00  6.2e-08  2.5e-08
-----

```

```
ans =
```

```
32.5199
```

```
Epoch... 83
```

```
Epoch... 84
```

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 272
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|6.1e+00|2.4e+06| 3.849712e+04  0.000000e+00| 0:0:00| chol 1 1
1|0.980|0.974|2.0e-02|2.6e-01|1.4e+05| 3.716942e+04  1.723485e+01| 0:0:00| chol 1 1
2|1.000|1.000|2.3e-07|5.5e-02|3.8e+04| 2.365381e+04 -6.582434e+01| 0:0:00| chol 1 1
3|1.000|0.999|2.2e-08|1.7e-02|2.1e+03| 1.434117e+03 -3.697421e+01| 0:0:00| chol 1 1
4|1.000|0.735|1.9e-07|8.0e-03|1.2e+03| 9.503219e+02 -2.576763e+01| 0:0:00| chol 1 1
5|0.569|0.976|8.4e-08|1.6e-03|7.9e+02| 7.128260e+02 -2.594910e+01| 0:0:00| chol 2 1
6|0.594|0.594|4.0e-08|9.3e-04|5.8e+02| 5.081793e+02 -2.256727e+01| 0:0:00| chol 2 1
7|0.315|0.327|6.5e-08|6.7e-04|5.3e+02| 4.461811e+02 -2.482284e+01| 0:0:00| chol 2 1
8|0.291|0.621|5.4e-08|2.8e-04|4.6e+02| 4.000727e+02 -3.334753e+01| 0:0:00| chol 2 2
9|0.407|0.912|3.8e-08|3.5e-05|3.8e+02| 3.353196e+02 -3.674602e+01| 0:0:00| chol 2 1
10|1.000|1.000|5.4e-09|6.0e-06|1.4e+02| 9.711363e+01 -3.690272e+01| 0:0:00| chol 2 2
11|0.846|0.860|7.3e-10|3.4e-06|4.0e+01| 5.778599e+00 -3.347336e+01| 0:0:00| chol 2 2
12|1.000|1.000|4.0e-11|1.5e-06|2.0e+01| -1.374186e+01 -3.327216e+01| 0:0:00| chol 2 2
13|0.969|0.962|4.0e-10|7.8e-07|2.1e+00| -3.036404e+01 -3.238884e+01| 0:0:00| chol 2 2
14|0.937|0.930|1.7e-09|4.0e-07|1.5e-01| -3.221345e+01 -3.234317e+01| 0:0:00| chol 2 2
15|1.000|1.000|7.4e-10|1.9e-07|5.6e-02| -3.230688e+01 -3.235187e+01| 0:0:00| chol 2 2
16|1.000|1.000|6.4e-10|9.4e-08|4.0e-03| -3.235691e+01 -3.235549e+01| 0:0:00| chol 2 2
17|1.000|0.996|1.0e-08|4.5e-10|1.5e-04| -3.236066e+01 -3.236078e+01| 0:0:00| chol 4 4
18|0.999|0.993|4.5e-10|5.9e-12|1.9e-06| -3.236080e+01 -3.236080e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
-----
number of iterations    = 18
primal objective value  = -3.23607980e+01
dual objective value    = -3.23607990e+01
gap := trace(XZ)        = 1.90e-06

```

```

relative gap          = 2.89e-08
actual relative gap   = 1.45e-08
rel. primal infeas    = 4.52e-10
rel. dual   infeas    = 5.92e-12
norm(X), norm(y), norm(Z) = 5.8e+03, 9.1e+01, 5.8e+01
norm(A), norm(b), norm(C) = 3.0e+02, 1.2e+03, 7.5e+01
Total CPU time (secs) = 0.11
CPU time per iteration = 0.01
termination code       = 0
DIMACS errors: 1.4e-09 0.0e+00 8.3e-12 0.0e+00 1.5e-08 2.9e-08
-----

```

```
ans =
```

```
32.3608
```

```
Epoch... 85
```

```
Epoch... 86
```

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 272
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|6.1e+00|2.4e+06| 3.854927e+04  0.000000e+00| 0:0:00| chol 1 1
1|0.980|0.974|2.0e-02|2.6e-01|1.4e+05| 3.722739e+04  1.734716e+01| 0:0:00| chol 1 1
2|1.000|1.000|2.3e-07|5.5e-02|3.8e+04| 2.370506e+04 -6.599270e+01| 0:0:00| chol 1 1
3|1.000|0.999|2.2e-08|1.7e-02|2.1e+03| 1.437239e+03 -3.698668e+01| 0:0:00| chol 1 1
4|1.000|0.733|1.9e-07|8.0e-03|1.2e+03| 9.518820e+02 -2.576519e+01| 0:0:00| chol 1 1
5|0.569|0.975|8.4e-08|1.6e-03|7.9e+02| 7.119048e+02 -2.598381e+01| 0:0:00| chol 2 2
6|0.587|0.586|4.1e-08|9.4e-04|5.8e+02| 5.098670e+02 -2.256114e+01| 0:0:00| chol 2 2
7|0.320|0.328|6.1e-08|6.8e-04|5.3e+02| 4.467376e+02 -2.475426e+01| 0:0:00| chol 2 2
8|0.291|0.618|5.0e-08|2.8e-04|4.6e+02| 4.009257e+02 -3.325108e+01| 0:0:00| chol 2 2
9|0.403|0.900|3.6e-08|3.9e-05|3.8e+02| 3.374962e+02 -3.650856e+01| 0:0:00| chol 2 1
10|1.000|1.000|2.1e-09|6.0e-06|1.4e+02| 9.722955e+01 -3.678842e+01| 0:0:00| chol 2 2
11|0.844|0.859|4.9e-10|3.4e-06|4.0e+01| 6.546950e+00 -3.334054e+01| 0:0:00| chol 2 2
12|1.000|1.000|3.4e-11|1.5e-06|2.0e+01| -1.295443e+01 -3.312174e+01| 0:0:00| chol 2 2
13|0.967|0.952|2.8e-10|7.9e-07|2.1e+00| -3.019661e+01 -3.223630e+01| 0:0:00| chol 2 2
14|0.945|0.930|9.1e-11|4.0e-07|1.4e-01| -3.207225e+01 -3.218727e+01| 0:0:00| chol 2 2
15|1.000|0.926|7.3e-10|2.0e-07|4.0e-02| -3.216646e+01 -3.219446e+01| 0:0:00| chol 2 2
16|1.000|1.000|5.1e-10|9.4e-08|1.4e-02| -3.219125e+01 -3.219951e+01| 0:0:00| chol 2 2
17|0.983|0.985|1.2e-09|4.8e-08|2.4e-04| -3.220418e+01 -3.220169e+01| 0:0:00| chol 4 4
18|1.000|1.000|2.5e-08|5.2e-11|5.1e-05| -3.220435e+01 -3.220441e+01| 0:0:00| chol 5 5
19|1.000|0.991|1.3e-09|1.7e-12|7.7e-07| -3.220441e+01 -3.220441e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
-----
number of iterations   = 19
primal objective value = -3.22044090e+01
dual   objective value = -3.22044091e+01
gap := trace(XZ)       = 7.67e-07

```

```

relative gap          = 1.17e-08
actual relative gap   = 8.48e-10
rel. primal infeas    = 1.31e-09
rel. dual   infeas    = 1.68e-12
norm(X), norm(y), norm(Z) = 5.7e+03, 9.1e+01, 5.8e+01
norm(A), norm(b), norm(C) = 3.0e+02, 1.2e+03, 7.5e+01
Total CPU time (secs) = 0.12
CPU time per iteration = 0.01
termination code       = 0
DIMACS errors: 4.0e-09  0.0e+00  2.4e-12  0.0e+00  8.5e-10  1.2e-08
-----

```

```
ans =
```

```
32.2044
```

```
Epoch... 87
```

```
Epoch... 88
```

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 272
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|6.1e+00|2.4e+06| 3.857994e+04  0.000000e+00| 0:0:00| chol 1 1
1|0.980|0.974|2.0e-02|2.6e-01|1.4e+05| 3.726479e+04  1.746712e+01| 0:0:00| chol 1 1
2|1.000|1.000|2.3e-07|5.5e-02|3.9e+04| 2.376244e+04 -6.618828e+01| 0:0:00| chol 1 1
3|1.000|0.998|2.3e-08|1.7e-02|2.1e+03| 1.440724e+03 -3.701153e+01| 0:0:00| chol 1 1
4|1.000|0.732|1.9e-07|8.1e-03|1.2e+03| 9.536199e+02 -2.577090e+01| 0:0:00| chol 1 1
5|0.569|0.975|8.4e-08|1.6e-03|7.9e+02| 7.112066e+02 -2.602530e+01| 0:0:00| chol 2 2
6|0.581|0.578|4.1e-08|9.5e-04|5.9e+02| 5.115323e+02 -2.256053e+01| 0:0:00| chol 2 1
7|0.325|0.329|6.0e-08|6.8e-04|5.3e+02| 4.472298e+02 -2.469665e+01| 0:0:00| chol 1 1
8|0.292|0.614|4.9e-08|2.9e-04|4.6e+02| 4.015192e+02 -3.315750e+01| 0:0:00| chol 1 2
9|0.399|0.887|3.5e-08|4.3e-05|3.8e+02| 3.393058e+02 -3.627116e+01| 0:0:00| chol 2 1
10|1.000|1.000|2.0e-09|6.0e-06|1.4e+02| 9.790696e+01 -3.668729e+01| 0:0:00| chol 2 2
11|0.841|0.857|5.6e-10|3.4e-06|4.1e+01| 7.359275e+00 -3.321709e+01| 0:0:00| chol 2 2
12|1.000|1.000|5.4e-11|1.5e-06|2.1e+01| -1.211920e+01 -3.297291e+01| 0:0:00| chol 2 2
13|0.965|0.940|4.2e-10|8.0e-07|2.1e+00| -3.004922e+01 -3.208774e+01| 0:0:00| chol 2 2
14|0.950|0.930|1.6e-10|4.1e-07|1.3e-01| -3.193044e+01 -3.203480e+01| 0:0:00| chol 2 2
15|0.972|0.861|7.7e-10|2.2e-07|3.1e-02| -3.202236e+01 -3.204081e+01| 0:0:00| chol 2 2
16|1.000|1.000|1.1e-09|9.4e-08|1.2e-02| -3.203994e+01 -3.204655e+01| 0:0:00| chol 2 2
17|0.979|0.979|1.1e-09|4.8e-08|2.8e-04| -3.205117e+01 -3.204873e+01| 0:0:00| chol 3 3
18|1.000|1.000|4.5e-08|8.2e-11|7.4e-05| -3.205140e+01 -3.205143e+01| 0:0:00| chol 5 5
19|1.000|0.991|1.0e-09|2.2e-12|9.1e-07| -3.205143e+01 -3.205143e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
-----
number of iterations   = 19
primal objective value = -3.20514303e+01
dual   objective value = -3.20514317e+01
gap := trace(XZ)       = 9.15e-07

```

```

relative gap          = 1.41e-08
actual relative gap   = 2.27e-08
rel. primal infeas    = 1.04e-09
rel. dual   infeas    = 2.23e-12
norm(X), norm(y), norm(Z) = 5.6e+03, 9.1e+01, 5.8e+01
norm(A), norm(b), norm(C) = 3.0e+02, 1.2e+03, 7.5e+01
Total CPU time (secs) = 0.14
CPU time per iteration = 0.01
termination code      = 0
DIMACS errors: 3.2e-09 0.0e+00 3.1e-12 0.0e+00 2.3e-08 1.4e-08
-----

```

```
ans =
```

```
32.0514
```

```
Epoch... 89
```

```
Epoch... 90
```

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 272
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|6.1e+00|2.4e+06| 3.862194e+04  0.000000e+00| 0:0:00| chol 1 1
1|0.980|0.974|2.0e-02|2.6e-01|1.4e+05| 3.731279e+04  1.760760e+01| 0:0:00| chol 1 1
2|1.000|1.000|2.3e-07|5.5e-02|3.9e+04| 2.383420e+04 -6.639741e+01| 0:0:00| chol 1 1
3|1.000|0.998|2.3e-08|1.7e-02|2.1e+03| 1.445076e+03 -3.704174e+01| 0:0:00| chol 1 1
4|1.000|0.731|1.9e-07|8.1e-03|1.2e+03| 9.557997e+02 -2.577814e+01| 0:0:00| chol 1 1
5|0.570|0.974|8.4e-08|1.7e-03|7.9e+02| 7.107401e+02 -2.606518e+01| 0:0:00| chol 2 1
6|0.575|0.571|4.2e-08|9.6e-04|5.9e+02| 5.133871e+02 -2.256048e+01| 0:0:00| chol 2 2
7|0.330|0.331|5.8e-08|6.9e-04|5.3e+02| 4.478518e+02 -2.464758e+01| 0:0:00| chol 2 2
8|0.294|0.610|4.7e-08|2.9e-04|4.7e+02| 4.020741e+02 -3.307343e+01| 0:0:00| chol 2 1
9|0.395|0.876|3.4e-08|4.7e-05|3.8e+02| 3.408629e+02 -3.604807e+01| 0:0:00| chol 2 2
10|1.000|1.000|1.1e-10|6.0e-06|1.4e+02| 9.910409e+01 -3.659619e+01| 0:0:00| chol 2 2
11|0.838|0.854|3.5e-10|3.4e-06|4.2e+01| 8.181275e+00 -3.310350e+01| 0:0:00| chol 2 2
12|1.000|1.000|4.6e-11|1.5e-06|2.2e+01| -1.123322e+01 -3.281986e+01| 0:0:00| chol 2 2
13|0.963|0.927|2.8e-10|8.1e-07|2.1e+00| -2.992248e+01 -3.193990e+01| 0:0:00| chol 2 2
14|0.955|0.930|1.9e-10|4.1e-07|1.2e-01| -3.178753e+01 -3.188224e+01| 0:0:00| chol 2 2
15|0.953|0.847|9.5e-10|2.2e-07|2.6e-02| -3.187397e+01 -3.188764e+01| 0:0:00| chol 2 2
16|1.000|1.000|1.7e-09|9.4e-08|9.8e-03| -3.188893e+01 -3.189348e+01| 0:0:00| chol 2 2
17|0.988|0.981|8.2e-10|4.8e-08|2.2e-04| -3.189816e+01 -3.189571e+01| 0:0:00| chol 3 3
18|1.000|1.000|2.7e-08|6.9e-11|6.9e-05| -3.189829e+01 -3.189837e+01| 0:0:00| chol 5 4
19|1.000|0.991|1.2e-09|2.0e-12|8.5e-07| -3.189837e+01 -3.189837e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
-----
number of iterations   = 19
primal objective value = -3.18983667e+01
dual   objective value = -3.18983665e+01
gap := trace(XZ)       = 8.48e-07

```

```

relative gap          = 1.31e-08
actual relative gap   = -2.11e-09
rel. primal infeas    = 1.24e-09
rel. dual   infeas    = 2.01e-12
norm(X), norm(y), norm(Z) = 5.6e+03, 9.1e+01, 5.8e+01
norm(A), norm(b), norm(C) = 3.0e+02, 1.2e+03, 7.5e+01
Total CPU time (secs) = 0.14
CPU time per iteration = 0.01
termination code      = 0
DIMACS errors: 3.8e-09 0.0e+00 2.8e-12 0.0e+00 -2.1e-09 1.3e-08
-----

```

```
ans =
```

```
31.8984
```

```
Epoch... 91
```

```
Epoch... 92
```

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 272
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|6.2e+00|2.4e+06| 3.864888e+04  0.000000e+00| 0:0:00| chol 1 1
1|0.980|0.974|2.0e-02|2.6e-01|1.4e+05| 3.734604e+04  1.772259e+01| 0:0:00| chol 1 1
2|1.000|1.000|2.3e-07|5.5e-02|3.9e+04| 2.389169e+04 -6.663049e+01| 0:0:00| chol 1 1
3|1.000|0.998|2.3e-08|1.7e-02|2.1e+03| 1.448601e+03 -3.709202e+01| 0:0:00| chol 1 1
4|1.000|0.729|1.9e-07|8.1e-03|1.2e+03| 9.577287e+02 -2.580132e+01| 0:0:00| chol 1 1
5|0.569|0.974|8.4e-08|1.7e-03|7.9e+02| 7.105827e+02 -2.612540e+01| 0:0:00| chol 2 2
6|0.570|0.565|4.2e-08|9.7e-04|5.9e+02| 5.150919e+02 -2.257129e+01| 0:0:00| chol 1 2
7|0.336|0.332|5.7e-08|6.9e-04|5.3e+02| 4.482682e+02 -2.461203e+01| 0:0:00| chol 2 2
8|0.299|0.605|4.6e-08|3.0e-04|4.7e+02| 4.019822e+02 -3.297467e+01| 0:0:00| chol 2 2
9|0.392|0.863|3.3e-08|5.1e-05|3.9e+02| 3.418753e+02 -3.581213e+01| 0:0:00| chol 2 1
10|1.000|1.000|6.8e-09|6.0e-06|1.4e+02| 1.010245e+02 -3.652688e+01| 0:0:00| chol 2 2
11|0.833|0.851|1.4e-09|3.5e-06|4.2e+01| 9.055969e+00 -3.300638e+01| 0:0:00| chol 2 2
12|1.000|1.000|3.9e-11|1.5e-06|2.3e+01| -1.027302e+01 -3.267494e+01| 0:0:00| chol 2 2
13|0.963|0.914|3.3e-10|8.2e-07|2.0e+00| -2.981024e+01 -3.180155e+01| 0:0:00| chol 2 2
14|0.957|0.930|1.5e-10|4.1e-07|1.1e-01| -3.164862e+01 -3.173828e+01| 0:0:00| chol 2 2
15|0.944|0.849|7.4e-10|2.2e-07|2.4e-02| -3.173111e+01 -3.174325e+01| 0:0:00| chol 2 2
16|1.000|1.000|8.4e-10|9.4e-08|9.1e-03| -3.174509e+01 -3.174900e+01| 0:0:00| chol 2 2
17|1.000|1.000|8.2e-10|4.7e-08|8.9e-04| -3.175298e+01 -3.175128e+01| 0:0:00| chol 3 3
18|0.984|0.982|1.0e-08|8.9e-10|1.7e-05| -3.175380e+01 -3.175379e+01| 0:0:00| chol 5 6
19|1.000|0.990|1.8e-09|9.4e-12|4.5e-07| -3.175384e+01 -3.175383e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
-----
number of iterations   = 19
primal objective value = -3.17538355e+01
dual   objective value = -3.17538349e+01
gap := trace(XZ)       = 4.53e-07

```

```

relative gap          = 7.03e-09
actual relative gap   = -9.27e-09
rel. primal infeas    = 1.80e-09
rel. dual   infeas    = 9.35e-12
norm(X), norm(y), norm(Z) = 5.5e+03, 9.1e+01, 5.8e+01
norm(A), norm(b), norm(C) = 3.0e+02, 1.2e+03, 7.5e+01
Total CPU time (secs) = 0.11
CPU time per iteration = 0.01
termination code       = 0
DIMACS errors: 5.5e-09 0.0e+00 1.3e-11 0.0e+00 -9.3e-09 7.0e-09
-----

```

```
ans =
```

```
31.7538
```

```
Epoch... 93
```

```
Epoch... 94
```

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 272
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|6.2e+00|2.5e+06| 3.868783e+04  0.000000e+00| 0:0:00| chol 1 1
1|0.980|0.974|2.0e-02|2.6e-01|1.4e+05| 3.739092e+04  1.783532e+01| 0:0:00| chol 1 1
2|1.000|1.000|2.3e-07|5.5e-02|3.9e+04| 2.393897e+04 -6.680108e+01| 0:0:00| chol 1 1
3|1.000|0.998|2.3e-08|1.7e-02|2.1e+03| 1.451539e+03 -3.711780e+01| 0:0:00| chol 1 1
4|1.000|0.727|1.9e-07|8.1e-03|1.2e+03| 9.592212e+02 -2.580908e+01| 0:0:00| chol 1 1
5|0.569|0.973|8.4e-08|1.7e-03|7.9e+02| 7.102048e+02 -2.616757e+01| 0:0:00| chol 1 2
6|0.565|0.559|4.3e-08|9.8e-04|5.9e+02| 5.166386e+02 -2.257276e+01| 0:0:00| chol 2 1
7|0.341|0.333|5.5e-08|7.0e-04|5.3e+02| 4.486271e+02 -2.457684e+01| 0:0:00| chol 2 2
8|0.304|0.602|4.5e-08|3.0e-04|4.7e+02| 4.019098e+02 -3.289350e+01| 0:0:00| chol 2 2
9|0.390|0.853|3.3e-08|5.5e-05|3.9e+02| 3.426023e+02 -3.560543e+01| 0:0:00| chol 2 2
10|1.000|1.000|1.2e-10|6.0e-06|1.4e+02| 1.020786e+02 -3.642741e+01| 0:0:00| chol 2 2
11|0.830|0.848|2.8e-10|3.5e-06|4.3e+01| 9.693894e+00 -3.289423e+01| 0:0:00| chol 2 1
12|1.000|1.000|1.1e-10|1.5e-06|2.3e+01| -9.539003e+00 -3.252730e+01| 0:0:00| chol 2 2
13|0.962|0.904|2.6e-10|8.2e-07|2.0e+00| -2.969957e+01 -3.166231e+01| 0:0:00| chol 2 2
14|0.958|0.930|2.0e-10|4.1e-07|1.1e-01| -3.150683e+01 -3.159413e+01| 0:0:00| chol 2 2
15|0.939|0.853|6.7e-10|2.2e-07|2.4e-02| -3.158655e+01 -3.159876e+01| 0:0:00| chol 2 2
16|1.000|0.952|9.2e-10|1.0e-07|9.2e-03| -3.160031e+01 -3.160412e+01| 0:0:00| chol 2 2
17|1.000|1.000|1.9e-09|4.7e-08|2.1e-03| -3.160714e+01 -3.160668e+01| 0:0:00| chol 2 3
18|0.986|0.984|3.0e-09|8.3e-10|3.4e-05| -3.160913e+01 -3.160912e+01| 0:0:00| chol 4 4
19|1.000|0.990|1.6e-09|9.1e-12|6.2e-07| -3.160916e+01 -3.160916e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
-----
number of iterations   = 19
primal objective value = -3.16091592e+01
dual   objective value = -3.16091583e+01
gap := trace(XZ)       = 6.17e-07

```

```

relative gap          = 9.60e-09
actual relative gap   = -1.43e-08
rel. primal infeas    = 1.56e-09
rel. dual   infeas    = 9.08e-12
norm(X), norm(y), norm(Z) = 5.4e+03, 9.1e+01, 5.8e+01
norm(A), norm(b), norm(C) = 3.0e+02, 1.2e+03, 7.5e+01
Total CPU time (secs) = 0.12
CPU time per iteration = 0.01
termination code      = 0
DIMACS errors: 4.8e-09 0.0e+00 1.3e-11 0.0e+00 -1.4e-08 9.6e-09
-----

```

```
ans =
```

```
31.6092
```

```
Epoch... 95
```

```
Epoch... 96
```

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 272
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|6.2e+00|2.5e+06| 3.886082e+04  0.000000e+00| 0:0:00| chol 1 1
1|0.980|0.974|2.0e-02|2.6e-01|1.4e+05| 3.756325e+04  1.795111e+01| 0:0:00| chol 1 1
2|1.000|1.000|2.3e-07|5.5e-02|3.9e+04| 2.404684e+04 -6.700352e+01| 0:0:00| chol 1 1
3|1.000|0.998|2.3e-08|1.7e-02|2.2e+03| 1.458104e+03 -3.714963e+01| 0:0:00| chol 1 1
4|1.000|0.728|1.9e-07|8.1e-03|1.2e+03| 9.625265e+02 -2.580888e+01| 0:0:00| chol 1 1
5|0.571|0.973|8.3e-08|1.7e-03|7.9e+02| 7.099351e+02 -2.619162e+01| 0:0:00| chol 1 2
6|0.558|0.552|4.3e-08|9.9e-04|5.9e+02| 5.189395e+02 -2.256698e+01| 0:0:00| chol 2 2
7|0.346|0.336|5.5e-08|7.0e-04|5.3e+02| 4.497298e+02 -2.454115e+01| 0:0:00| chol 2 2
8|0.303|0.603|4.5e-08|3.0e-04|4.7e+02| 4.032742e+02 -3.288580e+01| 0:0:00| chol 1 1
9|0.390|0.847|3.2e-08|5.7e-05|3.9e+02| 3.441316e+02 -3.546570e+01| 0:0:00| chol 2 1
10|1.000|1.000|2.4e-09|6.0e-06|1.4e+02| 1.029474e+02 -3.633535e+01| 0:0:00| chol 2 2
11|0.828|0.845|5.5e-10|3.5e-06|4.3e+01| 1.024546e+01 -3.278920e+01| 0:0:00| chol 2 2
12|1.000|1.000|6.2e-11|1.5e-06|2.4e+01| -8.902104e+00 -3.238461e+01| 0:0:00| chol 2 2
13|0.963|0.896|2.4e-10|8.3e-07|2.0e+00| -2.958833e+01 -3.152688e+01| 0:0:00| chol 2 2
14|0.960|0.931|1.1e-10|4.1e-07|1.1e-01| -3.136987e+01 -3.145431e+01| 0:0:00| chol 2 2
15|0.934|0.859|6.2e-10|2.2e-07|2.3e-02| -3.144771e+01 -3.145868e+01| 0:0:00| chol 2 2
16|1.000|0.925|9.0e-10|1.0e-07|8.7e-03| -3.146065e+01 -3.146379e+01| 0:0:00| chol 2 2
17|1.000|1.000|2.2e-09|4.7e-08|2.2e-03| -3.146679e+01 -3.146649e+01| 0:0:00| chol 2 2
18|0.986|0.983|9.1e-09|8.6e-10|3.6e-05| -3.146890e+01 -3.146889e+01| 0:0:00| chol 4 4
19|1.000|0.990|8.5e-10|9.6e-12|7.7e-07| -3.146893e+01 -3.146893e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
-----
number of iterations   = 19
primal objective value = -3.14689345e+01
dual   objective value = -3.14689333e+01
gap := trace(XZ)       = 7.70e-07

```



```

relative gap          = 1.20e-08
actual relative gap   = -1.90e-08
rel. primal infeas    = 8.45e-10
rel. dual   infeas    = 9.61e-12
norm(X), norm(y), norm(Z) = 5.3e+03, 9.1e+01, 5.8e+01
norm(A), norm(b), norm(C) = 3.0e+02, 1.2e+03, 7.5e+01
Total CPU time (secs) = 0.16
CPU time per iteration = 0.01
termination code       = 0
DIMACS errors: 2.6e-09  0.0e+00  1.3e-11  0.0e+00  -1.9e-08  1.2e-08
-----

```

```
ans =
```

```
31.4689
```

```
Epoch... 97
```

```
Epoch... 98
```

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 272

```

```
*****
```

```
SDPT3: Infeasible path-following algorithms
```

```
*****
```

```
version predcorr gam expon scale_data
```

```
HKM      1      0.000  1      0
```

```
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
```

```

-----
0|0.000|0.000|1.0e+00|6.2e+00|2.5e+06| 3.888547e+04  0.000000e+00| 0:0:00| chol  1  1
1|0.980|0.974|2.0e-02|2.6e-01|1.4e+05| 3.759443e+04  1.804990e+01| 0:0:00| chol  1  1
2|1.000|1.000|2.3e-07|5.5e-02|3.9e+04| 2.409219e+04 -6.717000e+01| 0:0:00| chol  1  1
3|1.000|0.998|2.4e-08|1.7e-02|2.2e+03| 1.460897e+03 -3.717308e+01| 0:0:00| chol  1  1
4|1.000|0.727|1.9e-07|8.1e-03|1.2e+03| 9.638655e+02 -2.581579e+01| 0:0:00| chol  1  1
5|0.571|0.972|8.3e-08|1.7e-03|7.9e+02| 7.096235e+02 -2.622703e+01| 0:0:00| chol  1  2
6|0.554|0.548|4.3e-08|1.0e-03|6.0e+02| 5.202413e+02 -2.256792e+01| 0:0:00| chol  2  2
7|0.351|0.337|5.4e-08|7.1e-04|5.3e+02| 4.499477e+02 -2.451364e+01| 0:0:00| chol  2  2
8|0.308|0.600|4.4e-08|3.1e-04|4.7e+02| 4.029372e+02 -3.280969e+01| 0:0:00| chol  2  2
9|0.388|0.839|3.2e-08|5.9e-05|3.9e+02| 3.444036e+02 -3.528483e+01| 0:0:00| chol  1  1
10|1.000|1.000|5.5e-09|6.0e-06|1.4e+02| 1.038755e+02 -3.623502e+01| 0:0:00| chol  2  2
11|0.825|0.842|1.0e-09|3.5e-06|4.4e+01| 1.074353e+01 -3.268257e+01| 0:0:00| chol  2  1
12|1.000|1.000|7.5e-11|1.5e-06|2.4e+01|-8.295145e+00 -3.224234e+01| 0:0:00| chol  2  2
13|0.963|0.888|3.6e-10|8.4e-07|2.0e+00|-2.948882e+01 -3.139478e+01| 0:0:00| chol  2  2
14|0.961|0.924|1.4e-10|4.1e-07|1.0e-01|-3.123596e+01 -3.131814e+01| 0:0:00| chol  2  2
15|0.929|0.873|6.6e-10|2.2e-07|2.1e-02|-3.131210e+01 -3.132171e+01| 0:0:00| chol  2  2
16|1.000|0.894|1.8e-09|1.1e-07|8.2e-03|-3.132390e+01 -3.132646e+01| 0:0:00| chol  2  2
17|1.000|1.000|1.6e-09|4.7e-08|2.4e-03|-3.132938e+01 -3.132931e+01| 0:0:00| chol  2  3
18|0.983|0.979|4.6e-09|1.1e-09|4.7e-05|-3.133168e+01 -3.133166e+01| 0:0:00| chol  4  4
19|1.000|0.990|7.6e-10|1.5e-11|2.8e-06|-3.133171e+01 -3.133171e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07

```

```

-----
number of iterations   = 19
primal objective value = -3.13317098e+01
dual   objective value = -3.13317111e+01
gap := trace(XZ)       = 2.78e-06

```

```

relative gap          = 4.36e-08
actual relative gap   = 1.95e-08
rel. primal infeas    = 7.59e-10
rel. dual   infeas    = 1.50e-11
norm(X), norm(y), norm(Z) = 5.3e+03, 9.1e+01, 5.8e+01
norm(A), norm(b), norm(C) = 3.0e+02, 1.2e+03, 7.5e+01
Total CPU time (secs) = 0.12
CPU time per iteration = 0.01
termination code       = 0
DIMACS errors: 2.3e-09  0.0e+00  2.1e-11  0.0e+00  1.9e-08  4.4e-08
-----

```

```
ans =
```

```
31.3317
```

```
Epoch... 99
```

```
Epoch... 100
```

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 272
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|6.2e+00|2.5e+06| 3.897395e+04  0.000000e+00| 0:0:00| chol 1 1
1|0.980|0.974|2.0e-02|2.7e-01|1.4e+05| 3.768589e+04  1.815028e+01| 0:0:00| chol 1 1
2|1.000|1.000|2.2e-07|5.5e-02|3.9e+04| 2.417306e+04 -6.739710e+01| 0:0:00| chol 1 1
3|1.000|0.998|2.4e-08|1.7e-02|2.2e+03| 1.465820e+03 -3.722239e+01| 0:0:00| chol 1 1
4|1.000|0.726|1.9e-07|8.1e-03|1.2e+03| 9.664386e+02 -2.583301e+01| 0:0:00| chol 1 1
5|0.571|0.972|8.2e-08|1.7e-03|7.9e+02| 7.097120e+02 -2.626967e+01| 0:0:00| chol 2 2
6|0.549|0.543|4.4e-08|1.0e-03|6.0e+02| 5.220441e+02 -2.257403e+01| 0:0:00| chol 2 1
7|0.356|0.339|5.4e-08|7.1e-04|5.3e+02| 4.505620e+02 -2.449225e+01| 0:0:00| chol 2 1
8|0.312|0.598|4.4e-08|3.1e-04|4.7e+02| 4.030665e+02 -3.275872e+01| 0:0:00| chol 1 1
9|0.387|0.833|3.2e-08|6.2e-05|3.9e+02| 3.449664e+02 -3.512585e+01| 0:0:00| chol 2 2
10|1.000|1.000|1.3e-10|6.0e-06|1.4e+02| 1.048725e+02 -3.614233e+01| 0:0:00| chol 2 2
11|0.822|0.839|3.7e-10|3.5e-06|4.4e+01| 1.120855e+01 -3.258243e+01| 0:0:00| chol 2 2
12|1.000|1.000|6.7e-11|1.5e-06|2.5e+01| -7.722309e+00 -3.210345e+01| 0:0:00| chol 2 2
13|0.960|0.881|3.5e-10|8.4e-07|2.0e+00| -2.930447e+01 -3.126606e+01| 0:0:00| chol 2 2
14|0.962|0.915|1.6e-10|4.2e-07|1.1e-01| -3.110175e+01 -3.118577e+01| 0:0:00| chol 2 2
15|0.919|0.886|6.4e-10|2.1e-07|1.9e-02| -3.118045e+01 -3.118835e+01| 0:0:00| chol 2 2
16|1.000|0.865|8.5e-10|1.1e-07|7.7e-03| -3.119089e+01 -3.119282e+01| 0:0:00| chol 2 2
17|1.000|1.000|2.1e-09|4.7e-08|2.4e-03| -3.119588e+01 -3.119579e+01| 0:0:00| chol 2 2
18|0.985|0.980|1.4e-08|1.0e-09|4.2e-05| -3.119813e+01 -3.119812e+01| 0:0:00| chol 4 4
19|1.000|0.990|7.6e-10|1.3e-11|1.8e-06| -3.119816e+01 -3.119816e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
-----
number of iterations   = 19
primal objective value = -3.11981609e+01
dual   objective value = -3.11981621e+01
gap := trace(XZ)       = 1.78e-06

```

```
relative gap          = 2.81e-08
actual relative gap   = 1.93e-08
rel. primal infeas    = 7.55e-10
rel. dual   infeas    = 1.28e-11
norm(X), norm(y), norm(Z) = 5.2e+03, 9.1e+01, 5.8e+01
norm(A), norm(b), norm(C) = 3.0e+02, 1.2e+03, 7.5e+01
Total CPU time (secs)  = 0.12
CPU time per iteration = 0.01
termination code       = 0
DIMACS errors: 2.3e-09  0.0e+00  1.8e-11  0.0e+00  1.9e-08  2.8e-08
-----
```

```
ans =
```

```
31.1982
```

```
>>
```