

```

num. of constraints = 85
dim. of socp var = 86,    num. of socp blk = 1
dim. of linear var = 1000
*****
SDPT3: Infeasible path-following algorithms
*****

```

version	predcorr	gam	expon	scale_data						
HKM	1	0.000	1	0						
it	pstep	dstep	pinfeas	dinfeas	gap	prim-obj	dual-obj	cputime		
-----										
0	0.000	0.000	1.0e+00	2.6e+01	2.6e+07	4.607070e+04	0.000000e+00	0:0:00	chol	1✓
1	0.996	0.957	4.1e-03	1.2e+00	1.2e+06	5.131201e+04	6.805706e+01	0:0:00	chol	1✓
2	1.000	0.949	1.4e-06	7.1e-02	1.1e+05	4.445777e+04	-1.212359e+02	0:0:01	chol	1✓
3	0.358	0.945	9.9e-07	7.1e-03	4.2e+04	3.653977e+04	-1.579445e+02	0:0:01	chol	1✓
4	1.000	0.772	1.0e-07	2.4e-03	1.5e+04	1.353779e+04	-1.551067e+02	0:0:01	chol	1✓
5	0.886	0.986	5.8e-08	3.4e-04	2.2e+03	2.026233e+03	-1.359643e+02	0:0:01	chol	1✓
6	1.000	0.997	2.2e-08	9.3e-05	6.1e+02	4.707590e+02	-1.298105e+02	0:0:01	chol	1✓
7	0.860	0.940	6.8e-09	1.4e-05	1.7e+02	4.213025e+01	-1.288902e+02	0:0:01	chol	1✓
8	0.789	1.000	2.0e-09	9.3e-07	1.0e+02	-2.343522e+01	-1.280502e+02	0:0:01	chol	1✓
9	1.000	1.000	8.9e-11	9.3e-08	5.8e+01	-6.994090e+01	-1.278171e+02	0:0:01	chol	1✓
10	1.000	1.000	4.8e-13	9.3e-09	1.7e+01	-1.103312e+02	-1.275431e+02	0:0:01	chol	1✓
11	1.000	1.000	9.5e-13	9.3e-10	8.5e+00	-1.188859e+02	-1.273922e+02	0:0:01	chol	1✓
12	1.000	1.000	1.3e-12	9.3e-11	3.4e+00	-1.238918e+02	-1.273251e+02	0:0:01	chol	1✓
13	1.000	1.000	1.2e-12	1.0e-11	2.0e+00	-1.253080e+02	-1.272846e+02	0:0:01	chol	1✓
14	1.000	1.000	7.4e-14	1.9e-12	5.9e-01	-1.266739e+02	-1.272669e+02	0:0:01	chol	1✓
15	1.000	1.000	2.0e-12	1.1e-12	2.2e-01	-1.270435e+02	-1.272591e+02	0:0:01	chol	1✓
16	0.940	0.966	1.7e-11	1.0e-12	2.6e-02	-1.272304e+02	-1.272563e+02	0:0:01	chol	2✓
17	0.869	0.903	6.7e-12	1.6e-12	1.4e-02	-1.272411e+02	-1.272556e+02	0:0:01	chol	2✓
18	1.000	1.000	2.6e-12	1.3e-12	6.7e-03	-1.272487e+02	-1.272554e+02	0:0:01	chol	2✓
19	0.981	0.867	3.4e-11	1.2e-12	7.8e-04	-1.272545e+02	-1.272552e+02	0:0:01	chol	1✓

```

20|0.745|0.842|8.1e-12|1.7e-12|2.7e-04|-1.272550e+02 -1.272552e+02| 0:0:01| chol 2✓
2
21|0.817|0.922|2.8e-12|1.8e-12|6.4e-05|-1.272552e+02 -1.272552e+02| 0:0:01| chol 3✓
3
22|0.987|0.955|6.0e-11|1.1e-12|6.1e-06|-1.272552e+02 -1.272552e+02| 0:0:01|
stop: max(relative gap, infeasibilities) < 1.00e-07

```

```

-----
number of iterations    = 22
primal objective value = -1.27255210e+02
dual   objective value = -1.27255216e+02
gap := trace(XZ)        = 6.10e-06
relative gap            = 2.39e-08
actual relative gap     = 2.39e-08
rel. primal infeas      = 6.04e-11
rel. dual   infeas      = 1.08e-12
norm(X), norm(y), norm(Z) = 3.7e+01, 1.8e+02, 2.1e+01
norm(A), norm(b), norm(C) = 9.1e+02, 3.2e+02, 2.5e+02
Total CPU time (secs)   = 0.86
CPU time per iteration = 0.04
termination code        = 0
DIMACS errors: 1.4e-10  0.0e+00  1.5e-12  0.0e+00  2.4e-08  2.4e-08
-----

```

ans =

127.2552

```

num. of constraints = 85
dim. of socp var   = 86,   num. of socp blk = 1
dim. of linear var = 1000
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
   HKM      1      0.000  1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|2.7e+01|1.1e+08| 2.139525e+05  0.000000e+00| 0:0:00| chol 1✓
1
1|0.986|0.943|1.4e-02|1.6e+00|6.7e+06| 2.161129e+05  2.183454e+03| 0:0:00| chol 1✓
1
2|1.000|0.940|3.4e-07|1.3e-01|6.5e+05| 1.889301e+05  1.332430e+02| 0:0:00| chol 1✓
1
3|0.286|1.000|2.7e-07|1.6e-02|2.3e+05| 1.734008e+05 -3.058419e+02| 0:0:00| chol 1✓
2
4|1.000|1.000|1.4e-07|7.9e-03|9.0e+04| 6.954317e+04 -1.871420e+02| 0:0:00| chol 1✓
1
5|0.883|0.912|3.1e-08|4.3e-03|1.3e+04| 1.079018e+04 -9.263262e+01| 0:0:00| chol 1✓
1
6|0.901|1.000|9.1e-09|1.2e-03|6.9e+03| 6.337375e+03 -7.745690e+01| 0:0:00| chol 2✓
2
7|1.000|1.000|3.8e-09|3.6e-04|3.2e+03| 3.044173e+03 -5.935003e+01| 0:0:00| chol 1✓
1

```

```

8|0.906|1.000|2.0e-09|1.1e-04|7.4e+02| 6.755650e+02 -5.284002e+01| 0:0:00| chol 1✓
1
9|1.000|0.911|5.3e-10|1.9e-05|4.0e+02| 3.535958e+02 -4.779338e+01| 0:0:00| chol 1✓
1
10|0.850|1.000|7.4e-11|1.1e-06|2.6e+02| 2.091653e+02 -4.706715e+01| 0:0:00| chol 1✓
1
11|1.000|0.996|2.9e-12|1.1e-07|1.4e+02| 9.315299e+01 -4.366019e+01| 0:0:00| chol 1✓
1
12|1.000|1.000|1.1e-12|1.1e-08|6.9e+01| 2.557223e+01 -4.333620e+01| 0:0:00| chol 1✓
1
13|1.000|1.000|9.4e-13|1.1e-09|3.1e+01|-1.086126e+01 -4.196911e+01| 0:0:00| chol 1✓
1
14|1.000|1.000|1.3e-13|1.1e-10|9.4e+00|-3.241497e+01 -4.180788e+01| 0:0:00| chol 1✓
1
15|1.000|1.000|1.9e-12|1.2e-11|3.9e+00|-3.772270e+01 -4.164078e+01| 0:0:00| chol 1✓
1
16|0.913|1.000|8.8e-12|2.1e-12|5.7e-01|-4.101628e+01 -4.158462e+01| 0:0:00| chol 1✓
1
17|0.739|1.000|3.2e-12|1.6e-12|2.4e-01|-4.130300e+01 -4.153940e+01| 0:0:00| chol 2✓
2
18|1.000|1.000|4.7e-12|1.0e-12|4.3e-02|-4.149090e+01 -4.153373e+01| 0:0:00| chol 2✓
3
19|0.943|0.888|1.5e-10|1.1e-12|2.1e-02|-4.151086e+01 -4.153216e+01| 0:0:00| chol 3✓
3
20|1.000|1.000|1.0e-09|1.5e-12|1.3e-02|-4.151857e+01 -4.153133e+01| 0:0:00| chol 3✓
3
21|1.000|1.000|2.7e-11|2.3e-12|4.2e-03|-4.152630e+01 -4.153052e+01| 0:0:00| chol 3✓
3
22|1.000|1.000|4.1e-10|3.4e-12|1.7e-03|-4.152859e+01 -4.153028e+01| 0:0:00| chol 3✓
3
23|0.996|1.000|4.2e-10|5.1e-12|2.3e-04|-4.152991e+01 -4.153013e+01| 0:0:00| chol 5✓
5
24|1.000|1.000|1.7e-09|7.6e-12|5.0e-05|-4.153007e+01 -4.153012e+01| 0:0:00| chol 6✓
6
25|1.000|1.000|3.9e-09|1.1e-11|4.7e-06|-4.153011e+01 -4.153011e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07

```

```

-----
number of iterations    = 25
primal objective value = -4.15301068e+01
dual  objective value = -4.15301108e+01
gap := trace(XZ)       = 4.69e-06
relative gap           = 5.58e-08
actual relative gap    = 4.81e-08
rel. primal infeas     = 3.94e-09
rel. dual  infeas     = 1.14e-11
norm(X), norm(y), norm(Z) = 8.9e+01, 3.0e+02, 1.8e+02
norm(A), norm(b), norm(C) = 3.4e+03, 1.7e+03, 2.5e+02
Total CPU time (secs)  = 0.32
CPU time per iteration = 0.01
termination code       = 0
DIMACS errors: 8.3e-09  0.0e+00  1.6e-11  0.0e+00  4.8e-08  5.6e-08
-----

```

ans =

41.5301

Iteration 2 Total error is: 0.021469

num. of constraints = 85

dim. of socp var = 86, num. of socp blk = 1

dim. of linear var = 1000

\*\*\*\*\*

SDPT3: Infeasible path-following algorithms

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version predcorr gam expon scale\_data

HKM 1 0.000 1 0

it pstep dstep pinfeas dinfeas gap prim-obj dual-obj cputime

it	pstep	dstep	pinfeas	dinfeas	gap	prim-obj	dual-obj	cputime		
0	0.000	0.000	1.0e+00	2.7e+01	1.1e+08	2.195580e+05	0.000000e+00	0:0:00	chol	1✓
1	1									
1	1									
2	1.000	0.940	2.3e-07	1.3e-01	6.9e+05	1.954291e+05	1.789683e+02	0:0:00	chol	1✓
1	1									
3	0.333	1.000	1.7e-07	1.6e-02	2.4e+05	1.775561e+05	-3.201845e+02	0:0:00	chol	1✓
1	1									
4	1.000	1.000	9.5e-08	7.9e-03	9.6e+04	7.421577e+04	-1.873050e+02	0:0:00	chol	1✓
1	1									
5	0.886	0.909	2.0e-08	4.3e-03	1.4e+04	1.098755e+04	-8.838732e+01	0:0:00	chol	1✓
1	1									
6	0.911	1.000	4.6e-09	1.2e-03	7.0e+03	6.464999e+03	-7.349706e+01	0:0:00	chol	1✓
2	2									
7	1.000	1.000	1.6e-09	3.6e-04	3.3e+03	3.176600e+03	-5.681800e+01	0:0:00	chol	1✓
1	1									
8	0.900	1.000	8.3e-10	1.1e-04	6.6e+02	6.024514e+02	-5.095105e+01	0:0:00	chol	1✓
1	1									
9	1.000	0.958	2.2e-10	1.5e-05	3.8e+02	3.336571e+02	-4.616252e+01	0:0:00	chol	1✓
1	1									
10	1.000	1.000	3.1e-11	1.1e-06	2.5e+02	2.014350e+02	-4.461532e+01	0:0:00	chol	1✓
1	1									
11	1.000	0.826	1.2e-11	2.7e-07	1.4e+02	9.530044e+01	-4.267653e+01	0:0:00	chol	1✓
1	1									
12	1.000	1.000	4.5e-12	1.1e-08	6.0e+01	1.940399e+01	-4.059141e+01	0:0:00	chol	1✓
1	1									
13	1.000	1.000	5.5e-12	1.1e-09	2.9e+01	-1.114934e+01	-3.967549e+01	0:0:00	chol	1✓
1	1									
14	1.000	1.000	7.0e-14	1.1e-10	7.7e+00	-3.149192e+01	-3.923106e+01	0:0:00	chol	1✓
1	1									
15	1.000	1.000	2.3e-14	1.2e-11	2.0e+00	-3.709265e+01	-3.911628e+01	0:0:00	chol	1✓
1	1									
16	0.882	0.977	1.6e-11	2.3e-12	3.1e-01	-3.878326e+01	-3.908829e+01	0:0:00	chol	2✓
2	2									
17	0.685	0.987	3.4e-12	1.6e-12	1.3e-01	-3.894306e+01	-3.907326e+01	0:0:00	chol	2✓
2	2									
18	0.973	1.000	3.9e-12	1.0e-12	5.6e-02	-3.901508e+01	-3.907091e+01	0:0:00	chol	2✓
2	2									
19	0.891	0.890	2.9e-11	1.1e-12	1.3e-02	-3.905533e+01	-3.906848e+01	0:0:00	chol	3✓

```

4
20|0.611|0.833|1.4e-09|1.7e-12|9.8e-03|-3.905871e+01 -3.906854e+01| 0:0:00| chol 3✓
3
21|1.000|1.000|1.2e-09|2.3e-12|5.4e-03|-3.906291e+01 -3.906832e+01| 0:0:00| chol 3✓
3
22|1.000|1.000|9.7e-11|3.4e-12|2.3e-03|-3.906585e+01 -3.906810e+01| 0:0:00| chol 3✓
3
23|0.781|0.937|5.2e-10|5.3e-12|9.0e-04|-3.906717e+01 -3.906807e+01| 0:0:00| chol 4✓
4
24|1.000|1.000|9.0e-10|7.6e-12|3.1e-04|-3.906774e+01 -3.906805e+01| 0:0:00| chol 5✓
5
25|1.000|1.000|8.1e-10|1.1e-11|6.2e-05|-3.906798e+01 -3.906804e+01| 0:0:00| chol 8✓
8
26|0.863|0.997|1.8e-09|1.7e-11|1.4e-05|-3.906803e+01 -3.906804e+01| 0:0:00| chol 17✓
30
27|1.000|1.000|1.7e-09|2.6e-11|1.9e-06|-3.906804e+01 -3.906804e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07

```

```

-----
number of iterations    = 27
primal objective value = -3.90680412e+01
dual   objective value = -3.90680428e+01
gap := trace(XZ)        = 1.86e-06
relative gap            = 2.35e-08
actual relative gap     = 2.11e-08
rel. primal infeas      = 1.73e-09
rel. dual   infeas      = 2.56e-11
norm(X), norm(y), norm(Z) = 9.6e+01, 3.1e+02, 1.9e+02
norm(A), norm(b), norm(C) = 4.0e+03, 2.6e+03, 2.5e+02
Total CPU time (secs)    = 0.33
CPU time per iteration   = 0.01
termination code         = 0
DIMACS errors: 3.6e-09  0.0e+00  3.6e-11  0.0e+00  2.1e-08  2.4e-08
-----

```

ans =

39.0680

Iteration 3 Total error is: 0.020818

```

num. of constraints = 85
dim. of socp var = 86, num. of socp blk = 1
dim. of linear var = 1000
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|2.7e+01|1.1e+08| 2.240490e+05  0.000000e+00| 0:0:00| chol 1✓
1
1|0.990|0.940|1.0e-02|1.7e+00|7.3e+06| 2.261396e+05  2.639316e+03| 0:0:00| chol 1✓
1

```

```

2|1.000|0.937|2.3e-07|1.4e-01|7.2e+05| 1.990591e+05  1.852576e+02| 0:0:00| chol  1✓
1
3|0.317|1.000|1.7e-07|1.6e-02|2.4e+05| 1.826730e+05 -3.358489e+02| 0:0:00| chol  1✓
1
4|1.000|1.000|8.5e-08|7.9e-03|9.7e+04| 7.493540e+04 -1.951760e+02| 0:0:00| chol  1✓
1
5|0.886|0.908|2.0e-08|4.3e-03|1.4e+04| 1.117055e+04 -9.558887e+01| 0:0:00| chol  1✓
1
6|0.926|1.000|5.0e-09|1.2e-03|7.1e+03| 6.560434e+03 -7.945173e+01| 0:0:00| chol  1✓
2
7|1.000|1.000|2.0e-09|3.6e-04|3.4e+03| 3.231999e+03 -6.218760e+01| 0:0:00| chol  1✓
1
8|0.891|1.000|1.2e-09|1.1e-04|7.1e+02| 6.490213e+02 -5.492886e+01| 0:0:00| chol  1✓
1
9|1.000|0.891|2.3e-10|2.1e-05|4.6e+02| 4.068119e+02 -4.824544e+01| 0:0:00| chol  1✓
1
10|1.000|1.000|3.5e-10|1.1e-06|2.9e+02| 2.476005e+02 -4.645667e+01| 0:0:00| chol  1✓
2
11|1.000|0.909|9.0e-13|1.9e-07|1.6e+02| 1.126305e+02 -4.286399e+01| 0:0:00| chol  1✓
1
12|1.000|1.000|2.3e-12|1.1e-08|7.1e+01| 3.062185e+01 -4.041895e+01| 0:0:00| chol  1✓
1
13|1.000|1.000|2.6e-12|1.1e-09|3.0e+01|-8.915637e+00 -3.903502e+01| 0:0:00| chol  1✓
1
14|1.000|1.000|3.3e-14|1.1e-10|9.8e+00|-2.864039e+01 -3.840165e+01| 0:0:00| chol  1✓
1
15|1.000|1.000|1.3e-13|1.2e-11|2.3e+00|-3.591043e+01 -3.817842e+01| 0:0:00| chol  1✓
2
16|1.000|1.000|1.5e-12|2.1e-12|7.2e-01|-3.741114e+01 -3.813485e+01| 0:0:00| chol  2✓
2
17|0.987|1.000|2.0e-12|1.1e-12|1.5e-01|-3.796967e+01 -3.811881e+01| 0:0:00| chol  2✓
2
18|1.000|1.000|1.3e-11|1.0e-12|6.2e-02|-3.805011e+01 -3.811213e+01| 0:0:00| chol  2✓
2
19|0.824|0.946|7.0e-12|1.6e-12|2.0e-02|-3.809097e+01 -3.811068e+01| 0:0:00| chol  2✓
2
20|0.606|1.000|1.1e-10|1.4e-12|1.3e-02|-3.809739e+01 -3.811051e+01| 0:0:00| chol  2✓
2
21|0.812|1.000|8.1e-12|2.1e-12|5.9e-03|-3.810433e+01 -3.811022e+01| 0:0:00| chol  3✓
3
22|0.495|1.000|2.6e-10|1.6e-12|3.7e-03|-3.810654e+01 -3.811020e+01| 0:0:00| chol  3✓
3
23|1.000|1.000|6.7e-10|2.4e-12|1.7e-03|-3.810849e+01 -3.811016e+01| 0:0:00| chol  3✓
3
24|1.000|1.000|1.4e-10|3.6e-12|7.9e-04|-3.810934e+01 -3.811013e+01| 0:0:00| chol  4✓
4
25|1.000|1.000|7.8e-10|5.5e-12|3.3e-04|-3.810979e+01 -3.811012e+01| 0:0:00| chol  4✓
5
26|1.000|1.000|1.9e-10|8.2e-12|1.2e-04|-3.810999e+01 -3.811011e+01| 0:0:00| chol  5✓
5
27|1.000|1.000|6.1e-10|1.2e-11|2.3e-05|-3.811009e+01 -3.811011e+01| 0:0:00| chol  7✓
8
28|0.996|0.993|6.5e-11|1.9e-11|1.3e-06|-3.811011e+01 -3.811011e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07

```

```

-----
number of iterations    = 28
primal objective value = -3.81101098e+01
dual   objective value = -3.81101111e+01
gap := trace(XZ)       = 1.27e-06
relative gap           = 1.65e-08
actual relative gap    = 1.61e-08
rel. primal infeas     = 6.52e-11
rel. dual   infeas     = 1.85e-11
norm(X), norm(y), norm(Z) = 9.7e+01, 3.1e+02, 1.9e+02
norm(A), norm(b), norm(C) = 4.0e+03, 2.5e+03, 2.5e+02
Total CPU time (secs)   = 0.33
CPU time per iteration = 0.01
termination code        = 0
DIMACS errors: 1.3e-10  0.0e+00  2.6e-11  0.0e+00  1.6e-08  1.6e-08
-----

```

ans =

38.1101

Iteration 4 Total error is: 0.020558

```

num. of constraints = 85
dim. of socp var   = 86,   num. of socp blk = 1
dim. of linear var = 1000

```

\*\*\*\*\*

SDPT3: Infeasible path-following algorithms

\*\*\*\*\*

```

version predcorr gam expon scale_data
HKM      1      0.000 1      0

```

```

it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----

```

0	0.000	0.000	1.0e+00	2.7e+01	1.2e+08	2.280864e+05	0.000000e+00	0:0:00	chol	1✓
1	0.993	0.941	6.7e-03	1.7e+00	7.3e+06	2.299843e+05	2.485023e+03	0:0:00	chol	1✓
1	1.000	0.931	2.5e-07	1.4e-01	7.6e+05	2.020517e+05	1.893052e+02	0:0:00	chol	1✓
1	0.314	1.000	1.9e-07	1.6e-02	2.5e+05	1.872647e+05	-3.557829e+02	0:0:00	chol	1✓
1	1.000	1.000	5.9e-08	7.9e-03	9.2e+04	7.073782e+04	-2.052369e+02	0:0:00	chol	1✓
1	0.888	0.901	2.1e-08	4.4e-03	1.3e+04	1.073104e+04	-1.090780e+02	0:0:00	chol	1✓
1	1.000	1.000	6.1e-09	1.2e-03	6.9e+03	6.283128e+03	-8.851768e+01	0:0:00	chol	1✓
2	1.000	1.000	3.3e-09	3.6e-04	3.0e+03	2.814967e+03	-7.074969e+01	0:0:00	chol	1✓
1	0.855	1.000	1.7e-09	1.1e-04	8.5e+02	7.835826e+02	-6.004762e+01	0:0:00	chol	1✓
1	1.000	0.984	2.4e-10	3.3e-05	5.8e+02	5.328155e+02	-5.004794e+01	0:0:00	chol	1✓
1	0.703	1.000	8.4e-11	3.2e-06	3.7e+02	3.206475e+02	-5.153209e+01	0:0:00	chol	1✓

```

1
11|1.000|0.972|2.3e-11|4.0e-07|2.1e+02| 1.621198e+02 -4.290187e+01| 0:0:00| chol 1✓
1
12|1.000|1.000|9.3e-12|3.2e-08|9.2e+01| 4.989769e+01 -4.224663e+01| 0:0:00| chol 1✓
1
13|1.000|1.000|7.0e-12|3.2e-09|4.8e+01| 9.149967e+00 -3.914430e+01| 0:0:00| chol 1✓
1
14|1.000|1.000|1.5e-13|3.2e-10|1.3e+01|-2.584946e+01 -3.836449e+01| 0:0:00| chol 1✓
1
15|1.000|1.000|1.5e-12|3.3e-11|5.5e+00|-3.250410e+01 -3.800701e+01| 0:0:00| chol 1✓
1
16|0.943|0.972|3.2e-13|5.1e-12|9.0e-01|-3.695570e+01 -3.785384e+01| 0:0:00| chol 1✓
2
17|1.000|0.958|3.3e-12|1.5e-12|3.0e-01|-3.754351e+01 -3.784300e+01| 0:0:00| chol 2✓
2
18|1.000|0.976|2.7e-12|1.1e-12|9.0e-02|-3.774165e+01 -3.783201e+01| 0:0:00| chol 2✓
2
19|1.000|1.000|7.6e-11|1.0e-12|3.4e-02|-3.779541e+01 -3.782983e+01| 0:0:00| chol 2✓
2
20|1.000|1.000|5.9e-11|1.5e-12|9.6e-03|-3.781946e+01 -3.782907e+01| 0:0:00| chol 3✓
3
21|1.000|0.778|4.3e-11|2.6e-12|7.5e-04|-3.782809e+01 -3.782884e+01| 0:0:00| chol 2✓
2
22|0.761|0.857|1.0e-11|3.7e-12|2.3e-04|-3.782857e+01 -3.782880e+01| 0:0:00| chol 4✓
4
23|0.900|0.884|1.1e-10|2.5e-12|5.7e-05|-3.782874e+01 -3.782880e+01| 0:0:00| chol 12✓
13
24|0.942|0.966|2.6e-09|3.1e-12|8.3e-06|-3.782879e+01 -3.782880e+01| 0:0:00| chol
linsysolve: Schur complement matrix not positive definite
switch to LU factor. lu 30 ^18
25|0.999|0.897|1.0e-09|4.9e-12|2.7e-07|-3.782880e+01 -3.782880e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07

```

```

-----
number of iterations    = 25
primal objective value = -3.78287955e+01
dual   objective value = -3.78287957e+01
gap := trace(XZ)       = 2.68e-07
relative gap           = 3.50e-09
actual relative gap    = 2.80e-09
rel. primal infeas     = 1.02e-09
rel. dual   infeas     = 4.88e-12
norm(X), norm(y), norm(Z) = 9.7e+01, 3.1e+02, 1.9e+02
norm(A), norm(b), norm(C) = 4.1e+03, 2.4e+03, 2.5e+02
Total CPU time (secs)   = 0.35
CPU time per iteration = 0.01
termination code        = 0
DIMACS errors: 2.0e-09  0.0e+00  6.9e-12  0.0e+00  2.8e-09  3.5e-09
-----

```

ans =

37.8288

Iteration 5 Total error is: 0.020477



```

num. of constraints = 85
dim. of socp var = 86, num. of socp blk = 1
dim. of linear var = 1000
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000  1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|2.7e+01|1.2e+08| 2.298458e+05  0.000000e+00| 0:0:00| chol 1✓
1
1|0.996|0.941|3.9e-03|1.7e+00|7.3e+06| 2.316225e+05  2.378126e+03| 0:0:00| chol 1✓
1
2|1.000|0.928|2.7e-07|1.5e-01|7.8e+05| 2.034214e+05  1.859262e+02| 0:0:00| chol 1✓
1
3|0.334|1.000|2.0e-07|1.6e-02|2.5e+05| 1.881937e+05 -3.628911e+02| 0:0:00| chol 1✓
1
4|1.000|1.000|4.9e-08|7.9e-03|8.1e+04| 6.259367e+04 -2.091518e+02| 0:0:00| chol 1✓
1
5|0.892|0.888|2.5e-08|4.4e-03|1.2e+04| 9.775027e+03 -1.181446e+02| 0:0:00| chol 1✓
1
6|1.000|1.000|8.4e-09|1.2e-03|6.8e+03| 6.237059e+03 -9.113037e+01| 0:0:00| chol 1✓
1
7|1.000|1.000|4.3e-09|3.6e-04|1.8e+03| 1.669267e+03 -7.477347e+01| 0:0:00| chol 1✓
1
8|1.000|0.856|1.5e-09|1.4e-04|8.8e+02| 8.097169e+02 -5.975274e+01| 0:0:00| chol 1✓
1
9|1.000|1.000|2.3e-10|3.2e-05|5.7e+02| 5.148824e+02 -5.288708e+01| 0:0:00| chol 1✓
1
10|1.000|1.000|9.1e-12|3.2e-06|2.6e+02| 2.174386e+02 -4.512214e+01| 0:0:00| chol 1✓
1
11|1.000|1.000|5.7e-11|3.2e-07|1.2e+02| 8.076443e+01 -4.254836e+01| 0:0:00| chol 1✓
1
12|1.000|1.000|3.3e-12|3.2e-08|5.4e+01| 1.470099e+01 -3.933959e+01| 0:0:00| chol 1✓
1
13|1.000|1.000|1.3e-13|3.2e-09|1.5e+01|-2.353384e+01 -3.841319e+01| 0:0:00| chol 1✓
1
14|1.000|1.000|8.5e-13|3.2e-10|6.5e+00|-3.147280e+01 -3.797320e+01| 0:0:00| chol 1✓
1
15|0.938|0.977|2.5e-13|4.0e-11|1.2e+00|-3.656885e+01 -3.779350e+01| 0:0:00| chol 1✓
1
16|1.000|1.000|3.9e-11|4.2e-12|4.9e-01|-3.728655e+01 -3.777358e+01| 0:0:00| chol 2✓
2
17|0.964|0.948|6.1e-12|2.0e-12|1.0e-01|-3.765486e+01 -3.775899e+01| 0:0:00| chol 2✓
2
18|1.000|1.000|1.8e-10|1.3e-12|5.5e-02|-3.770023e+01 -3.775500e+01| 0:0:00| chol 2✓
2
19|1.000|1.000|4.4e-12|1.8e-12|1.1e-02|-3.774284e+01 -3.775348e+01| 0:0:00| chol 2✓
2
20|1.000|1.000|3.5e-12|1.0e-12|2.7e-03|-3.775061e+01 -3.775330e+01| 0:0:00| chol 3✓
3
21|0.989|0.915|2.4e-11|1.1e-12|4.7e-04|-3.775278e+01 -3.775325e+01| 0:0:00| chol 4✓

```

```

4
22|0.888|0.948|2.7e-10|1.6e-12|1.6e-04|-3.775308e+01 -3.775324e+01| 0:0:00| chol 5✓
6
23|1.000|1.000|3.1e-10|2.2e-12|3.1e-05|-3.775321e+01 -3.775324e+01| 0:0:00| chol 10✓
13
24|1.000|1.000|5.0e-10|3.4e-12|7.9e-06|-3.775323e+01 -3.775324e+01| 0:0:00| chol
    linsysolve: Schur complement matrix not positive definite
    switch to LU factor. lu 30 30
25|0.950|0.765|1.2e-09|5.9e-12|8.2e-07|-3.775324e+01 -3.775324e+01| 0:0:00|
    stop: max(relative gap, infeasibilities) < 1.00e-07
-----
number of iterations    = 25
primal objective value = -3.77532356e+01
dual  objective value = -3.77532359e+01
gap := trace(XZ)       = 8.21e-07
relative gap           = 1.07e-08
actual relative gap    = 3.85e-09
rel. primal infeas     = 1.16e-09
rel. dual  infeas     = 5.86e-12
norm(X), norm(y), norm(Z) = 9.7e+01, 3.1e+02, 2.0e+02
norm(A), norm(b), norm(C) = 4.1e+03, 2.3e+03, 2.5e+02
Total CPU time (secs)   = 0.33
CPU time per iteration = 0.01
termination code        = 0
DIMACS errors: 2.2e-09  0.0e+00  8.3e-12  0.0e+00  3.8e-09  1.1e-08
-----

ans =

    37.7532

Iteration    6    Total error is: 0.020453

num. of constraints = 85
dim. of socp var = 86,    num. of socp blk = 1
dim. of linear var = 1000
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000  1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|2.7e+01|1.2e+08| 2.312901e+05  0.000000e+00| 0:0:00| chol 1✓
1
1|0.997|0.942|3.1e-03|1.7e+00|7.3e+06| 2.330285e+05  2.363773e+03| 0:0:00| chol 1✓
1
2|1.000|0.929|2.8e-07|1.5e-01|7.8e+05| 2.046317e+05  1.835410e+02| 0:0:00| chol 1✓
1
3|0.348|1.000|2.0e-07|1.6e-02|2.5e+05| 1.884173e+05 -3.616881e+02| 0:0:00| chol 1✓
1
4|1.000|1.000|4.9e-08|7.9e-03|7.5e+04| 5.752422e+04 -2.065356e+02| 0:0:00| chol 1✓
1
5|0.881|0.878|2.7e-08|4.4e-03|1.2e+04| 9.872534e+03 -1.185228e+02| 0:0:00| chol 1✓

```

```

1
6|1.000|1.000|8.5e-09|1.2e-03|6.8e+03| 6.226215e+03 -9.340028e+01| 0:0:00| chol 1✓
1
7|1.000|1.000|5.3e-09|3.6e-04|1.7e+03| 1.570386e+03 -7.542606e+01| 0:0:00| chol 1✓
1
8|1.000|0.844|1.4e-09|1.5e-04|9.4e+02| 8.633932e+02 -6.023621e+01| 0:0:00| chol 1✓
1
9|1.000|1.000|1.5e-10|3.2e-05|6.0e+02| 5.458158e+02 -5.416478e+01| 0:0:00| chol 1✓
1
10|1.000|1.000|6.2e-12|3.2e-06|2.7e+02| 2.262777e+02 -4.574911e+01| 0:0:00| chol 1✓
1
11|1.000|1.000|3.0e-11|3.2e-07|1.3e+02| 8.666347e+01 -4.259925e+01| 0:0:00| chol 1✓
1
12|1.000|1.000|1.8e-12|3.2e-08|5.5e+01| 1.576486e+01 -3.945743e+01| 0:0:00| chol 1✓
1
13|1.000|1.000|1.2e-13|3.2e-09|1.5e+01|-2.330703e+01 -3.837907e+01| 0:0:00| chol 1✓
1
14|1.000|1.000|1.9e-13|3.2e-10|6.3e+00|-3.162613e+01 -3.793831e+01| 0:0:00| chol 1✓
1
15|0.941|0.990|3.7e-13|3.6e-11|1.2e+00|-3.652142e+01 -3.776016e+01| 0:0:00| chol 1✓
1
16|1.000|1.000|2.3e-11|4.2e-12|5.1e-01|-3.723443e+01 -3.773976e+01| 0:0:00| chol 1✓
2
17|0.964|0.755|6.9e-13|2.8e-12|8.6e-02|-3.764055e+01 -3.772691e+01| 0:0:00| chol 2✓
2
18|0.714|0.841|4.6e-12|1.5e-12|4.8e-02|-3.767221e+01 -3.772061e+01| 0:0:00| chol 2✓
2
19|1.000|1.000|6.2e-11|1.0e-12|1.4e-02|-3.770519e+01 -3.771929e+01| 0:0:00| chol 2✓
2
20|1.000|0.890|5.0e-12|1.6e-12|1.8e-03|-3.771706e+01 -3.771889e+01| 0:0:00| chol 2✓
2
21|0.769|0.927|1.1e-10|1.1e-12|5.3e-04|-3.771831e+01 -3.771884e+01| 0:0:00| chol 4✓
4
22|0.996|0.945|5.5e-11|1.6e-12|4.8e-05|-3.771878e+01 -3.771883e+01| 0:0:00| chol 8✓
7
23|0.980|0.989|1.9e-10|2.3e-12|2.8e-06|-3.771883e+01 -3.771883e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07

```

```

-----
number of iterations    = 23
primal objective value = -3.77188270e+01
dual   objective value = -3.77188301e+01
gap := trace(XZ)       = 2.75e-06
relative gap           = 3.60e-08
actual relative gap    = 3.98e-08
rel. primal infeas     = 1.93e-10
rel. dual   infeas     = 2.27e-12
norm(X), norm(y), norm(Z) = 9.7e+01, 3.1e+02, 2.0e+02
norm(A), norm(b), norm(C) = 4.1e+03, 2.2e+03, 2.5e+02
Total CPU time (secs)   = 0.28
CPU time per iteration = 0.01
termination code        = 0
DIMACS errors: 3.7e-10  0.0e+00  3.2e-12  0.0e+00  4.0e-08  3.6e-08
-----

```

0	0.000 0.000 1.0e+00 2.7e+01 1.2e+08	2.331106e+05	0.000000e+00	0:0:00	chol	1	✓	
1	1	0.998 0.942 2.3e-03 1.6e+00 7.4e+06	2.348065e+05	2.337411e+03	0:0:00	chol	1	✓
1	2	1.000 0.929 2.9e-07 1.5e-01 7.8e+05	2.061237e+05	1.793548e+02	0:0:00	chol	1	✓
1	3	0.363 1.000 2.1e-07 1.6e-02 2.5e+05	1.886182e+05	-3.592996e+02	0:0:00	chol	1	✓
1	4	1.000 1.000 4.8e-08 7.9e-03 6.8e+04	5.193281e+04	-2.030202e+02	0:0:00	chol	1	✓
1	5	0.869 0.866 2.8e-08 4.5e-03 1.2e+04	9.910208e+03	-1.183122e+02	0:0:00	chol	1	✓
1	6	1.000 1.000 8.3e-09 1.2e-03 6.7e+03	6.182023e+03	-9.510849e+01	0:0:00	chol	1	✓
1	7	0.994 1.000 5.0e-09 3.6e-04 1.6e+03	1.508047e+03	-7.560342e+01	0:0:00	chol	1	✓
1	8	1.000 0.898 1.5e-09 1.3e-04 1.0e+03	9.363551e+02	-5.991635e+01	0:0:00	chol	1	✓
1	9	1.000 1.000 1.2e-10 3.2e-05 6.2e+02	5.652893e+02	-5.596191e+01	0:0:00	chol	1	✓
10	1.000 1.000 7.7e-12 3.2e-06 3.1e+02	2.617178e+02	-4.587326e+01	0:0:00	chol	1	✓	
1	11	0.960 1.000 4.8e-12 3.2e-07 1.4e+02	9.653602e+01	-4.432558e+01	0:0:00	chol	1	✓
1	12	1.000 1.000 9.6e-12 3.2e-08 7.8e+01	3.762998e+01	-3.990746e+01	0:0:00	chol	1	✓
1	13	1.000 1.000 5.4e-13 3.2e-09 2.0e+01 -1.830811e+01	-3.857354e+01	0:0:00	chol	1	✓	
1	14	1.000 1.000 1.2e-12 3.2e-10 8.9e+00 -2.914675e+01	-3.800924e+01	0:0:00	chol	1	✓	
1	15	0.940 0.986 3.7e-13 3.7e-11 1.8e+00 -3.598774e+01	-3.776147e+01	0:0:00	chol	1	✓	
1	16	1.000 1.000 7.3e-13 4.2e-12 7.6e-01 -3.697089e+01	-3.772952e+01	0:0:00	chol	1	✓	
1	17	0.974 0.829 3.8e-11 2.0e-12 1.3e-01 -3.758426e+01	-3.771044e+01	0:0:00	chol	2	✓	
2	18	0.590 0.781 1.2e-11 2.0e-12 7.7e-02 -3.762702e+01	-3.770356e+01	0:0:00	chol	2	✓	
2								

```

19|1.000|0.995|3.2e-11|2.3e-12|2.8e-02|-3.767320e+01 -3.770156e+01| 0:0:00| chol 2✓
2
20|0.967|0.795|2.2e-11|3.8e-12|3.1e-03|-3.769766e+01 -3.770073e+01| 0:0:00| chol 2✓
2
21|0.777|0.812|3.8e-11|5.1e-12|1.0e-03|-3.769961e+01 -3.770062e+01| 0:0:00| chol 2✓
2
22|0.783|0.926|2.6e-11|7.0e-12|3.1e-04|-3.770027e+01 -3.770059e+01| 0:0:00| chol 3✓
4
23|0.969|0.985|8.7e-11|5.3e-12|3.3e-05|-3.770055e+01 -3.770058e+01| 0:0:00| chol 7✓
8
24|1.000|1.000|2.8e-10|7.8e-12|1.9e-06|-3.770058e+01 -3.770058e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07

```

```

-----
number of iterations    = 24
primal objective value = -3.77005787e+01
dual   objective value = -3.77005805e+01
gap := trace(XZ)       = 1.86e-06
relative gap           = 2.44e-08
actual relative gap    = 2.37e-08
rel. primal infeas     = 2.77e-10
rel. dual   infeas     = 7.81e-12
norm(X), norm(y), norm(Z) = 9.8e+01, 3.1e+02, 2.0e+02
norm(A), norm(b), norm(C) = 4.1e+03, 2.1e+03, 2.5e+02
Total CPU time (secs)   = 0.29
CPU time per iteration = 0.01
termination code        = 0
DIMACS errors: 5.3e-10  0.0e+00  1.1e-11  0.0e+00  2.4e-08  2.4e-08
-----

```

ans =

37.7006

Iteration 8 Total error is: 0.02044

The total representation error of the testing signals is: 0.20561