

```
>> demo_Polynomial_Dictionary_Learning_Uber
Starting to train the dictionary
solving the quadratic problem with YALMIP...
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```
num. of constraints = 33
dim. of socp var = 34, num. of socp blk = 1
dim. of linear var = 174
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|3.4e+00|3.2e+05| 7.891604e+03  0.000000e+00| 0:0:00| chol 1 1
1|0.969|0.972|3.2e-02|1.6e-01|2.2e+04| 7.877646e+03  8.448593e-01| 0:0:00| chol 1 1
2|1.000|1.000|1.1e-07|2.0e-02|5.3e+03| 3.950313e+03 -2.147091e+01| 0:0:00| chol 1 1
3|0.994|0.993|3.3e-08|6.2e-03|2.0e+02| 1.314456e+02 -1.674565e+01| 0:0:00| chol 1 1
4|1.000|1.000|2.2e-07|6.1e-04|9.7e+01| 7.819411e+01 -1.655998e+01| 0:0:00| chol 1 1
5|0.869|0.864|3.7e-08|1.4e-04|1.4e+01| -2.744027e+00 -1.639756e+01| 0:0:00| chol 1 1
6|1.000|1.000|3.1e-08|6.1e-06|8.0e+00| -8.232582e+00 -1.618431e+01| 0:0:00| chol 1 1
7|0.864|0.865|6.1e-09|1.4e-06|1.3e+00| -1.463143e+01 -1.594599e+01| 0:0:00| chol 1 1
8|0.506|0.707|7.5e-09|4.4e-07|1.0e+00| -1.487374e+01 -1.588979e+01| 0:0:00| chol 1 1
9|0.682|0.965|3.7e-09|2.3e-08|7.6e-01| -1.511360e+01 -1.586944e+01| 0:0:00| chol 1 1
10|0.192|0.322|3.0e-09|1.6e-08|7.1e-01| -1.514142e+01 -1.585266e+01| 0:0:00| chol 1 1
11|0.717|1.000|8.4e-10|6.5e-10|5.0e-01| -1.534067e+01 -1.584539e+01| 0:0:00| chol 1 1
12|1.000|1.000|1.1e-14|1.7e-10|2.4e-01| -1.558856e+01 -1.582813e+01| 0:0:00| chol 1 1
13|1.000|1.000|3.8e-14|1.6e-12|9.6e-02| -1.571858e+01 -1.581468e+01| 0:0:00| chol 1 1
14|1.000|1.000|7.7e-13|1.1e-12|2.7e-02| -1.578332e+01 -1.580995e+01| 0:0:00| chol 1 1
15|1.000|1.000|8.4e-12|1.0e-12|1.0e-02| -1.579822e+01 -1.580868e+01| 0:0:00| chol 1 1
16|0.969|1.000|7.6e-13|1.5e-12|2.3e-03| -1.580603e+01 -1.580828e+01| 0:0:00| chol 2 2
17|1.000|1.000|4.9e-13|1.0e-12|8.9e-04| -1.580734e+01 -1.580822e+01| 0:0:00| chol 2 2
18|0.958|0.973|5.2e-13|1.0e-12|6.3e-05| -1.580814e+01 -1.580820e+01| 0:0:00| chol 2 2
19|0.992|1.000|2.1e-12|1.0e-12|5.0e-06| -1.580820e+01 -1.580820e+01| 0:0:00| chol 2 2
20|1.000|1.000|1.5e-11|1.0e-12|3.4e-07| -1.580820e+01 -1.580820e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
-----
number of iterations = 20
primal objective value = -1.58082016e+01
dual objective value = -1.58082020e+01
gap := trace(XZ) = 3.42e-07
relative gap = 1.05e-08
actual relative gap = 1.05e-08
rel. primal infeas = 1.45e-11
rel. dual infeas = 1.00e-12
norm(X), norm(y), norm(Z) = 3.0e+01, 7.7e+01, 5.4e+01
norm(A), norm(b), norm(C) = 3.4e+01, 1.3e+02, 5.8e+01
Total CPU time (secs) = 0.09
CPU time per iteration = 0.00
termination code = 0
DIMACS errors: 1.5e-11 0.0e+00 1.4e-12 0.0e+00 1.0e-08 1.0e-08
-----
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ans =
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15.8082

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num. of constraints = 33
dim. of socp var = 34,    num. of socp blk = 1
dim. of linear var = 174
*****
SDPT3: Infeasible path-following algorithms
*****
version  predcorr  gam  expon  scale_data
HKM      1      0.000  1      0

it pstep dstep pinfeas dinfeas  gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|3.4e+00|4.4e+05| 1.084901e+04  0.000000e+00| 0:0:00| chol  1  1
1|0.962|0.971|3.9e-02|1.6e-01|3.1e+04| 1.069925e+04  1.299833e+01| 0:0:00| chol  1  1
2|1.000|1.000|9.4e-08|2.0e-02|7.7e+03| 5.784467e+03 -1.167649e+01| 0:0:00| chol  1  1
3|0.993|0.999|4.3e-08|6.1e-03|2.9e+02| 2.138167e+02 -4.759391e+00| 0:0:00| chol  1  1
4|0.833|1.000|1.3e-07|6.1e-04|1.5e+02| 1.369017e+02 -4.752867e+00| 0:0:00| chol  1  1
5|0.962|0.874|1.3e-08|1.3e-04|1.2e+01| 8.138704e+00 -4.224192e+00| 0:0:00| chol  1  1
6|1.000|1.000|4.3e-09|6.1e-06|6.6e+00| 2.410341e+00 -4.181005e+00| 0:0:00| chol  1  1
7|0.935|0.958|2.0e-09|8.4e-07|7.3e-01| -3.409261e+00 -4.139107e+00| 0:0:00| chol  1  1
8|0.867|1.000|5.7e-09|6.2e-08|1.8e-01| -3.939846e+00 -4.117529e+00| 0:0:00| chol  1  1
9|0.656|0.657|3.3e-09|2.6e-08|1.1e-01| -3.996151e+00 -4.107647e+00| 0:0:00| chol  1  1
10|0.666|0.787|1.1e-09|6.6e-09|7.6e-02| -4.034668e+00 -4.110567e+00| 0:0:00| chol  1  1
11|1.000|0.996|2.2e-13|3.1e-10|1.8e-02| -4.088725e+00 -4.106501e+00| 0:0:00| chol  1  1
12|0.959|0.978|7.0e-11|1.4e-11|7.8e-04| -4.105454e+00 -4.106229e+00| 0:0:00| chol  1  1
13|0.968|0.985|2.4e-11|1.7e-12|2.5e-05| -4.106196e+00 -4.106221e+00| 0:0:00| chol  2  2
14|1.000|1.000|2.7e-11|2.3e-12|2.0e-06| -4.106219e+00 -4.106221e+00| 0:0:00| chol  2  2
15|1.000|1.000|2.2e-12|3.4e-12|2.7e-08| -4.106221e+00 -4.106221e+00| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
-----

number of iterations = 15
primal objective value = -4.10622086e+00
dual objective value = -4.10622090e+00
gap := trace(XZ) = 2.66e-08
relative gap = 2.89e-09
actual relative gap = 3.82e-09
rel. primal infeas = 2.18e-12
rel. dual infeas = 3.37e-12
norm(X), norm(y), norm(Z) = 2.7e+01, 7.6e+01, 5.4e+01
norm(A), norm(b), norm(C) = 3.5e+01, 1.7e+02, 5.8e+01
Total CPU time (secs) = 0.11
CPU time per iteration = 0.01
termination code = 0
DIMACS errors: 2.2e-12  0.0e+00  4.7e-12  0.0e+00  3.8e-09  2.9e-09
-----

ans =

4.1062

Iteration 2 Total error is: 0.032393

num. of constraints = 33
dim. of socp var = 34,    num. of socp blk = 1

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dim. of linear var = 174
*****
SDPT3: Infeasible path-following algorithms
*****
version  predcorr  gam  expon  scale_data
HKM      1      0.000  1      0
it pstep dstep pinfeas dinfeas  gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|3.4e+00|4.4e+05| 1.093006e+04  0.000000e+00| 0:0:00| chol  1  1
1|0.961|0.971|3.9e-02|1.6e-01|3.1e+04| 1.077072e+04  1.343884e+01| 0:0:00| chol  1  1
2|1.000|1.000|9.6e-08|2.0e-02|7.9e+03| 5.952075e+03 -1.194480e+01| 0:0:00| chol  1  1
3|0.993|0.999|4.4e-08|6.1e-03|3.0e+02| 2.190524e+02 -4.851869e+00| 0:0:00| chol  1  1
4|0.807|1.000|1.3e-07|6.1e-04|1.5e+02| 1.439471e+02 -4.791963e+00| 0:0:00| chol  1  1
5|0.974|0.872|1.2e-08|1.3e-04|1.3e+01| 9.170879e+00 -4.228785e+00| 0:0:00| chol  1  1
6|1.000|1.000|5.0e-09|6.1e-06|6.5e+00| 2.351973e+00 -4.181722e+00| 0:0:00| chol  1  1
7|0.977|0.943|1.9e-09|9.3e-07|6.1e-01| -3.524957e+00 -4.135459e+00| 0:0:00| chol  1  1
8|0.855|1.000|5.2e-09|6.2e-08|1.7e-01| -3.936808e+00 -4.110698e+00| 0:0:00| chol  1  1
9|0.743|0.619|2.6e-09|2.8e-08|9.1e-02| -4.012735e+00 -4.103426e+00| 0:0:00| chol  1  1
10|0.925|1.000|1.9e-10|1.1e-09|5.1e-02| -4.053577e+00 -4.104776e+00| 0:0:00| chol  1  1
11|0.981|0.948|3.9e-12|1.6e-10|1.9e-03| -4.100446e+00 -4.102395e+00| 0:0:00| chol  1  1
12|0.987|0.987|7.5e-12|9.0e-12|2.4e-05| -4.102290e+00 -4.102315e+00| 0:0:00| chol  1  2
13|1.000|0.992|2.0e-11|1.6e-12|9.2e-07| -4.102313e+00 -4.102314e+00| 0:0:00| chol  2  2
14|1.000|1.000|4.1e-11|2.3e-12|6.4e-08| -4.102313e+00 -4.102314e+00| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
-----
number of iterations = 14
primal objective value = -4.10231344e+00
dual objective value = -4.10231372e+00
gap := trace(XZ) = 6.43e-08
relative gap = 6.98e-09
actual relative gap = 3.06e-08
rel. primal infeas = 4.13e-11
rel. dual infeas = 2.25e-12
norm(X), norm(y), norm(Z) = 2.7e+01, 7.6e+01, 5.4e+01
norm(A), norm(b), norm(C) = 3.5e+01, 1.7e+02, 5.8e+01
Total CPU time (secs) = 0.08
CPU time per iteration = 0.01
termination code = 0
DIMACS errors: 4.1e-11  0.0e+00  3.1e-12  0.0e+00  3.1e-08  7.0e-09
-----

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ans =

4.1023

Iteration 3 Total error is: 0.032339

```

num. of constraints = 33
dim. of socp var = 34, num. of socp blk = 1
dim. of linear var = 174
*****
SDPT3: Infeasible path-following algorithms
*****
version  predcorr  gam  expon  scale_data
HKM      1      0.000  1      0

```

it	pstep	dstep	pinfeas	dinfeas	gap	prim-obj	dual-obj	cputime			
0	0.000	0.000	1.0e+00	3.4e+00	4.5e+05	1.101233e+04	0.000000e+00	0:0:00	chol	1	1
1	0.961	0.970	4.0e-02	1.6e-01	3.2e+04	1.084334e+04	1.387277e+01	0:0:00	chol	1	1
2	1.000	1.000	9.7e-08	2.0e-02	8.1e+03	6.119792e+03	-1.220685e+01	0:0:00	chol	1	1
3	0.993	0.999	4.6e-08	6.1e-03	3.0e+02	2.242042e+02	-4.947512e+00	0:0:00	chol	1	1
4	0.783	1.000	1.3e-07	6.1e-04	1.6e+02	1.508344e+02	-4.833009e+00	0:0:00	chol	1	1
5	0.990	0.874	1.0e-08	1.3e-04	1.5e+01	1.034339e+01	-4.233798e+00	0:0:00	chol	1	1
6	1.000	1.000	5.5e-09	6.1e-06	6.5e+00	2.307724e+00	-4.184061e+00	0:0:00	chol	1	1
7	1.000	0.942	1.8e-09	9.3e-07	7.9e-01	-3.346461e+00	-4.132684e+00	0:0:00	chol	1	1
8	0.829	1.000	3.2e-09	6.2e-08	2.0e-01	-3.912402e+00	-4.111907e+00	0:0:00	chol	1	1
9	0.901	0.664	2.4e-09	2.5e-08	9.9e-02	-4.001076e+00	-4.100526e+00	0:0:00	chol	1	1
10	0.703	0.827	7.3e-10	5.4e-09	6.5e-02	-4.037417e+00	-4.102685e+00	0:0:00	chol	1	1
11	1.000	0.958	3.0e-13	4.3e-10	8.5e-03	-4.090705e+00	-4.099188e+00	0:0:00	chol	1	1
12	0.973	0.983	4.1e-11	1.4e-11	2.3e-04	-4.098782e+00	-4.099011e+00	0:0:00	chol	1	1
13	0.981	0.987	7.2e-11	1.7e-12	4.4e-06	-4.099004e+00	-4.099008e+00	0:0:00	chol	2	2
14	1.000	1.000	1.2e-11	2.3e-12	1.9e-07	-4.099008e+00	-4.099008e+00	0:0:00			

stop: max(relative gap, infeasibilities) < 1.00e-07

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-----
number of iterations      = 14
primal objective value   = -4.09900763e+00
dual  objective value    = -4.09900790e+00
gap := trace(XZ)         = 1.88e-07
relative gap             = 2.04e-08
actual relative gap      = 3.01e-08
rel. primal infeas       = 1.24e-11
rel. dual  infeas        = 2.25e-12
norm(X), norm(y), norm(Z) = 2.7e+01, 7.6e+01, 5.4e+01
norm(A), norm(b), norm(C) = 3.5e+01, 1.7e+02, 5.8e+01
Total CPU time (secs)    = 0.11
CPU time per iteration   = 0.01
termination code         = 0
DIMACS errors: 1.2e-11  0.0e+00  3.1e-12  0.0e+00  3.0e-08  2.0e-08
-----

```

ans =

4.0990

Iteration 4 Total error is: 0.032305

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 174
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000  1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----

```

0	0.000	0.000	1.0e+00	3.4e+00	4.5e+05	1.109550e+04	0.000000e+00	0:0:00	chol	1	1
1	0.960	0.969	4.0e-02	1.7e-01	3.2e+04	1.091676e+04	1.430928e+01	0:0:00	chol	1	1
2	1.000	1.000	9.9e-08	2.0e-02	8.4e+03	6.289208e+03	-1.246683e+01	0:0:00	chol	1	1
3	0.993	0.999	4.7e-08	6.1e-03	3.1e+02	2.293883e+02	-5.048485e+00	0:0:00	chol	1	1

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4|0.761|1.000|1.3e-07|6.1e-04|1.7e+02| 1.576803e+02 -4.877238e+00| 0:0:00| chol 1 1
5|1.000|0.880|9.4e-09|1.3e-04|1.7e+01| 1.279520e+01 -4.239417e+00| 0:0:00| chol 1 1
6|1.000|1.000|5.3e-09|6.1e-06|6.8e+00| 2.653381e+00 -4.190406e+00| 0:0:00| chol 1 1
7|1.000|0.974|1.7e-09|7.6e-07|1.5e+00|-2.599545e+00 -4.130437e+00| 0:0:00| chol 1 1
8|0.834|1.000|1.4e-09|6.2e-08|2.7e-01|-3.843725e+00 -4.117030e+00| 0:0:00| chol 1 1
9|1.000|0.788|3.1e-09|1.8e-08|1.8e-01|-3.922862e+00 -4.099231e+00| 0:0:00| chol 1 1
10|0.748|0.775|7.8e-10|5.0e-09|6.3e-02|-4.035430e+00 -4.098674e+00| 0:0:00| chol 1 1
11|0.958|0.942|3.3e-11|5.0e-10|3.0e-03|-4.092708e+00 -4.095747e+00| 0:0:00| chol 1 1
12|0.982|0.981|5.3e-11|2.2e-11|6.9e-05|-4.095609e+00 -4.095678e+00| 0:0:00| chol 1 1
13|1.000|1.000|2.1e-12|9.9e-12|5.5e-06|-4.095671e+00 -4.095676e+00| 0:0:00| chol 1 1
14|1.000|1.000|1.2e-11|1.0e-12|1.9e-07|-4.095676e+00 -4.095676e+00| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07

```

```

-----
number of iterations    = 14
primal objective value = -4.09567592e+00
dual   objective value = -4.09567611e+00
gap := trace(XZ)       = 1.86e-07
relative gap           = 2.02e-08
actual relative gap    = 2.07e-08
rel. primal infeas     = 1.21e-11
rel. dual   infeas     = 1.00e-12
norm(X), norm(y), norm(Z) = 2.7e+01, 7.7e+01, 5.4e+01
norm(A), norm(b), norm(C) = 3.6e+01, 1.7e+02, 5.8e+01
Total CPU time (secs)   = 0.11
CPU time per iteration = 0.01
termination code        = 0
DIMACS errors: 1.2e-11  0.0e+00  1.4e-12  0.0e+00  2.1e-08  2.0e-08
-----

```

ans =

4.0957

Iteration 5 Total error is: 0.03227

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 174
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|3.4e+00|4.5e+05| 1.117958e+04  0.000000e+00| 0:0:00| chol 1 1
1|0.959|0.969|4.1e-02|1.7e-01|3.2e+04| 1.099098e+04  1.474860e+01| 0:0:00| chol 1 1
2|1.000|1.000|1.0e-07|2.0e-02|8.6e+03| 6.460343e+03 -1.272460e+01| 0:0:00| chol 1 1
3|0.993|0.999|4.8e-08|6.1e-03|3.2e+02| 2.346066e+02 -5.155016e+00| 0:0:00| chol 1 1
4|0.739|1.000|1.3e-07|6.1e-04|1.7e+02| 1.644992e+02 -4.924990e+00| 0:0:00| chol 1 1
5|1.000|0.889|9.7e-09|1.2e-04|2.2e+01| 1.740380e+01 -4.245703e+00| 0:0:00| chol 1 1
6|0.978|1.000|4.8e-09|6.1e-06|8.0e+00| 3.822067e+00 -4.201840e+00| 0:0:00| chol 1 1
7|1.000|0.996|1.7e-09|6.3e-07|2.4e+00|-1.739661e+00 -4.128695e+00| 0:0:00| chol 1 1
8|0.863|0.996|8.7e-10|6.4e-08|3.4e-01|-3.782726e+00 -4.117924e+00| 0:0:00| chol 1 1
9|1.000|0.889|3.3e-09|1.3e-08|2.2e-01|-3.879425e+00 -4.096752e+00| 0:0:00| chol 1 1

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```

10|0.732|0.782|8.8e-10|3.5e-09|8.2e-02|-4.012651e+00 -4.094400e+00| 0:0:00| chol 1 1
11|0.993|0.957|5.9e-12|3.9e-10|3.6e-03|-4.088770e+00 -4.092386e+00| 0:0:00| chol 1 1
12|0.992|0.984|1.9e-11|1.3e-11|1.2e-04|-4.092197e+00 -4.092318e+00| 0:0:00| chol 1 1
13|1.000|1.000|7.9e-12|1.8e-12|1.3e-05|-4.092303e+00 -4.092316e+00| 0:0:00| chol 1 1
14|1.000|1.000|3.0e-11|1.6e-12|7.5e-07|-4.092315e+00 -4.092316e+00| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07

```

```

-----
number of iterations      = 14
primal objective value    = -4.09231543e+00
dual   objective value    = -4.09231618e+00
gap := trace(XZ)          = 7.51e-07
relative gap              = 8.18e-08
actual relative gap       = 8.20e-08
rel. primal infeas        = 2.98e-11
rel. dual   infeas        = 1.58e-12
norm(X), norm(y), norm(Z) = 2.7e+01, 7.7e+01, 5.4e+01
norm(A), norm(b), norm(C) = 3.6e+01, 1.7e+02, 5.8e+01
Total CPU time (secs)     = 0.13
CPU time per iteration    = 0.01
termination code          = 0
DIMACS errors: 3.0e-11  0.0e+00  2.2e-12  0.0e+00  8.2e-08  8.2e-08
-----

```

ans =

4.0923

Iteration 6 Total error is: 0.032235

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 174
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|3.4e+00|4.5e+05| 1.126461e+04  0.000000e+00| 0:0:00| chol 1 1
1|0.959|0.968|4.2e-02|1.7e-01|3.3e+04| 1.106605e+04  1.519083e+01| 0:0:00| chol 1 1
2|1.000|1.000|1.0e-07|2.0e-02|8.8e+03| 6.633195e+03 -1.297994e+01| 0:0:00| chol 1 1
3|0.993|0.999|4.9e-08|6.1e-03|3.2e+02| 2.398594e+02 -5.267298e+00| 0:0:00| chol 1 1
4|0.719|1.000|1.3e-07|6.1e-04|1.8e+02| 1.713024e+02 -4.976614e+00| 0:0:00| chol 1 1
5|1.000|0.901|9.8e-09|1.2e-04|2.7e+01| 2.262881e+01 -4.252720e+00| 0:0:00| chol 1 1
6|0.967|1.000|4.2e-09|6.1e-06|9.2e+00| 4.983919e+00 -4.213333e+00| 0:0:00| chol 1 1
7|1.000|1.000|1.6e-09|6.1e-07|3.2e+00| -9.621290e-01 -4.127246e+00| 0:0:00| chol 1 1
8|0.884|0.988|6.3e-10|6.8e-08|3.8e-01| -3.740920e+00 -4.116759e+00| 0:0:00| chol 1 1
9|0.579|0.958|2.1e-09|8.9e-09|2.8e-01| -3.815357e+00 -4.093234e+00| 0:0:00| chol 1 1
10|0.712|0.752|6.1e-10|2.9e-09|1.3e-01| -3.960024e+00 -4.092289e+00| 0:0:00| chol 1 1
11|1.000|1.000|3.6e-13|1.8e-10|2.2e-02| -4.067668e+00 -4.089209e+00| 0:0:00| chol 1 1
12|0.975|0.975|6.0e-11|1.2e-11|6.2e-04| -4.088317e+00 -4.088936e+00| 0:0:00| chol 1 1
13|0.988|0.989|8.4e-12|1.6e-12|7.2e-06| -4.088919e+00 -4.088926e+00| 0:0:00| chol 1 1
14|0.996|0.993|7.2e-12|1.7e-12|9.5e-08| -4.088926e+00 -4.088926e+00| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07

```

```

-----
number of iterations    = 14
primal objective value = -4.08892610e+00
dual   objective value = -4.08892619e+00
gap := trace(XZ)       = 9.47e-08
relative gap           = 1.03e-08
actual relative gap    = 1.00e-08
rel. primal infeas     = 7.21e-12
rel. dual   infeas     = 1.69e-12
norm(X), norm(y), norm(Z) = 2.7e+01, 7.7e+01, 5.4e+01
norm(A), norm(b), norm(C) = 3.6e+01, 1.8e+02, 5.8e+01
Total CPU time (secs)   = 0.13
CPU time per iteration = 0.01
termination code        = 0
DIMACS errors: 7.2e-12  0.0e+00  2.4e-12  0.0e+00  1.0e-08  1.0e-08
-----

```

ans =

4.0889

Iteration 7 Total error is: 0.032199

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 174
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|3.4e+00|4.6e+05| 1.135061e+04  0.000000e+00| 0:0:00| chol 1 1
1|0.958|0.968|4.2e-02|1.7e-01|3.3e+04| 1.114199e+04  1.563610e+01| 0:0:00| chol 1 1
2|1.000|1.000|1.0e-07|2.0e-02|9.0e+03| 6.807778e+03 -1.323267e+01| 0:0:00| chol 1 1
3|0.993|0.999|5.0e-08|6.1e-03|3.3e+02| 2.451477e+02 -5.385540e+00| 0:0:00| chol 1 1
4|0.699|1.000|1.3e-07|6.1e-04|1.9e+02| 1.781004e+02 -5.032495e+00| 0:0:00| chol 1 1
5|1.000|0.916|1.0e-08|1.1e-04|3.3e+01| 2.839801e+01 -4.260552e+00| 0:0:00| chol 1 1
6|0.963|1.000|3.8e-09|6.1e-06|1.0e+01| 6.083974e+00 -4.224663e+00| 0:0:00| chol 1 1
7|1.000|1.000|1.6e-09|6.1e-07|3.7e+00| -3.821031e-01 -4.124738e+00| 0:0:00| chol 1 1
8|0.896|0.996|5.7e-10|6.4e-08|4.0e-01| -3.713667e+00 -4.114533e+00| 0:0:00| chol 1 1
9|0.573|0.983|2.1e-09|7.2e-09|2.9e-01| -3.796145e+00 -4.089833e+00| 0:0:00| chol 1 1
10|0.729|0.758|5.8e-10|2.4e-09|1.3e-01| -3.954175e+00 -4.088650e+00| 0:0:00| chol 1 1
11|1.000|1.000|1.4e-13|1.8e-10|1.9e-02| -4.066572e+00 -4.085733e+00| 0:0:00| chol 1 1
12|0.978|0.977|5.0e-11|1.1e-11|4.6e-04| -4.085054e+00 -4.085511e+00| 0:0:00| chol 1 1
13|0.989|0.989|4.7e-12|1.6e-12|5.2e-06| -4.085499e+00 -4.085504e+00| 0:0:00| chol 1 1
14|0.997|0.994|8.8e-11|1.0e-12|7.1e-08| -4.085504e+00 -4.085504e+00| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
-----

```

```

number of iterations    = 14
primal objective value = -4.08550409e+00
dual   objective value = -4.08550415e+00
gap := trace(XZ)       = 7.12e-08
relative gap           = 7.76e-09

```

```
actual relative gap      = 6.45e-09
rel. primal infeas       = 8.76e-11
rel. dual   infeas       = 1.01e-12
norm(X), norm(y), norm(Z) = 2.7e+01, 7.7e+01, 5.4e+01
norm(A), norm(b), norm(C) = 3.6e+01, 1.8e+02, 5.8e+01
Total CPU time (secs)    = 0.11
CPU time per iteration   = 0.01
termination code         = 0
DIMACS errors: 8.8e-11  0.0e+00  1.4e-12  0.0e+00  6.4e-09  7.8e-09
-----
```

```
ans =
```

```
4.0855
```

```
Iteration    8    Total error is: 0.032163
```

```
The total representation error of the testing signals is: 0.02636
```

```
>>
```