

Starting to train the dictionary
solving the quadratic problem with YALMIP...

```

num. of constraints = 33
dim. of socp var = 34,    num. of socp blk = 1
dim. of linear var = 174
*****
SDPT3: Infeasible path-following algorithms
*****
version  predcorr  gam  expon  scale_data
HKM      1      0.000  1      0
it pstep dstep pinfeas dinfeas  gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|3.4e+00|2.7e+05| 5.924956e+03  0.000000e+00| 0:0:00| chol  1  1
1|0.984|0.987|1.7e-02|1.1e-01|1.5e+04| 6.173781e+03 -8.752245e+00| 0:0:00| chol  1  1
2|1.000|1.000|4.3e-08|2.0e-02|1.8e+03| 1.247902e+03 -1.379325e+01| 0:0:00| chol  1  1
3|0.996|1.000|1.3e-08|6.1e-03|8.4e+01| 4.709167e+01 -1.391827e+01| 0:0:00| chol  1  1
4|1.000|1.000|6.0e-08|6.1e-04|2.5e+01| 9.817245e+00 -1.429354e+01| 0:0:00| chol  1  1
5|0.810|0.808|1.2e-08|1.7e-04|5.7e+00|-8.446394e+00 -1.413819e+01| 0:0:00| chol  1  1
6|1.000|1.000|2.7e-08|6.1e-06|3.2e+00|-1.080202e+01 -1.402246e+01| 0:0:00| chol  1  1
7|0.828|0.641|7.4e-09|2.6e-06|7.4e-01|-1.321835e+01 -1.395671e+01| 0:0:00| chol  1  1
8|1.000|0.977|8.5e-10|1.2e-07|3.7e-01|-1.358163e+01 -1.395285e+01| 0:0:00| chol  1  1
9|0.914|0.967|6.1e-10|1.0e-08|3.9e-02|-1.390421e+01 -1.394283e+01| 0:0:00| chol  1  1
10|1.000|1.000|2.5e-12|7.3e-10|6.3e-03|-1.393624e+01 -1.394250e+01| 0:0:00| chol  1  1
11|0.983|0.984|6.6e-12|7.3e-11|1.1e-04|-1.394233e+01 -1.394244e+01| 0:0:00| chol  1  1
12|1.000|1.000|7.5e-12|1.3e-12|1.5e-06|-1.394244e+01 -1.394244e+01| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
-----
number of iterations = 12
primal objective value = -1.39424422e+01
dual objective value = -1.39424437e+01
gap := trace(XZ) = 1.50e-06
relative gap = 5.19e-08
actual relative gap = 5.19e-08
rel. primal infeas = 7.50e-12
rel. dual infeas = 1.31e-12
norm(X), norm(y), norm(Z) = 2.5e+01, 7.2e+01, 4.8e+01
norm(A), norm(b), norm(C) = 3.0e+01, 1.0e+02, 5.8e+01
Total CPU time (secs) = 0.08
CPU time per iteration = 0.01
termination code = 0
DIMACS errors: 7.6e-12  0.0e+00  1.8e-12  0.0e+00  5.2e-08  5.2e-08
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ans =

13.9424

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num. of constraints = 33
dim. of socp var = 34,    num. of socp blk = 1
dim. of linear var = 174
*****
SDPT3: Infeasible path-following algorithms
*****

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```

version  predcorr  gam  expon  scale_data
   HKM      1      0.000  1      0
it pstep dstep pinfeas dinfeas  gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|3.4e+00|3.6e+05| 8.315037e+03  0.000000e+00| 0:0:00| chol  1  1
1|0.976|0.985|2.5e-02|1.1e-01|2.1e+04| 8.495491e+03  2.326143e+00| 0:0:00| chol  1  1
2|1.000|1.000|4.1e-08|2.0e-02|3.0e+03| 2.111313e+03 -5.248631e+00| 0:0:00| chol  1  1
3|0.992|0.999|1.4e-08|6.1e-03|1.4e+02| 9.579494e+01 -3.844123e+00| 0:0:00| chol  1  1
4|1.000|1.000|6.4e-08|6.1e-04|2.8e+01| 2.267427e+01 -4.285695e+00| 0:0:00| chol  1  1
5|0.873|0.885|7.5e-09|1.2e-04|3.6e+00| -6.511270e-01 -4.233748e+00| 0:0:00| chol  1  1
6|1.000|0.805|4.2e-08|2.9e-05|2.0e+00| -2.239641e+00 -4.227972e+00| 0:0:00| chol  1  1
7|0.803|1.000|8.1e-09|6.2e-07|5.0e-01| -3.724779e+00 -4.223204e+00| 0:0:00| chol  1  1
8|1.000|0.831|7.8e-09|1.6e-07|2.3e-01| -3.976895e+00 -4.207933e+00| 0:0:00| chol  1  1
9|0.490|1.000|4.4e-09|7.7e-09|1.6e-01| -4.039725e+00 -4.198744e+00| 0:0:00| chol  1  1
10|0.569|0.688|1.9e-09|3.7e-09|1.0e-01| -4.098710e+00 -4.201795e+00| 0:0:00| chol  1  1
11|1.000|1.000|4.8e-13|4.4e-10|3.8e-02| -4.159743e+00 -4.197884e+00| 0:0:00| chol  1  1
12|0.953|0.965|4.5e-14|2.2e-11|3.2e-03| -4.193751e+00 -4.196991e+00| 0:0:00| chol  1  1
13|0.953|0.982|7.3e-13|2.0e-12|1.7e-04| -4.196728e+00 -4.196898e+00| 0:0:00| chol  1  2
14|1.000|1.000|4.5e-11|1.0e-12|3.2e-05| -4.196865e+00 -4.196896e+00| 0:0:00| chol  1  1
15|1.000|1.000|9.4e-11|1.5e-12|1.1e-06| -4.196895e+00 -4.196896e+00| 0:0:00| chol  2  2
16|1.000|1.000|4.4e-12|2.3e-12|3.9e-08| -4.196896e+00 -4.196896e+00| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07

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```

-----
number of iterations      = 16
primal objective value   = -4.19689600e+00
dual  objective value    = -4.19689604e+00
gap := trace(XZ)         = 3.89e-08
relative gap             = 4.14e-09
actual relative gap      = 4.50e-09
rel. primal infeas       = 4.38e-12
rel. dual  infeas       = 2.25e-12
norm(X), norm(y), norm(Z) = 2.6e+01, 7.6e+01, 5.3e+01
norm(A), norm(b), norm(C) = 3.1e+01, 1.4e+02, 5.8e+01
Total CPU time (secs)    = 0.13
CPU time per iteration   = 0.01
termination code         = 0
DIMACS errors: 4.4e-12  0.0e+00  3.1e-12  0.0e+00  4.5e-09  4.1e-09
-----

```

ans =

4.1969

Iteration 2 Total error is: 0.03319

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 174
*****
SDPT3: Infeasible path-following algorithms
*****
version  predcorr  gam  expon  scale_data
   HKM      1      0.000  1      0
it pstep dstep pinfeas dinfeas  gap      prim-obj      dual-obj      cputime
-----

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```

0|0.000|0.000|1.0e+00|3.4e+00|3.7e+05| 8.381020e+03  0.000000e+00| 0:0:00| chol  1  1
1|0.975|0.985|2.5e-02|1.2e-01|2.1e+04| 8.553903e+03  2.733417e+00| 0:0:00| chol  1  1
2|1.000|1.000|4.3e-08|2.0e-02|3.1e+03| 2.208738e+03 -5.405656e+00| 0:0:00| chol  1  1
3|0.992|0.999|1.4e-08|6.1e-03|1.4e+02| 9.918403e+01 -3.833506e+00| 0:0:00| chol  1  1
4|1.000|1.000|3.8e-08|6.1e-04|1.9e+01| 1.437951e+01 -4.261221e+00| 0:0:00| chol  1  1
5|0.827|0.839|6.1e-09|1.5e-04|3.7e+00|-5.471812e-01 -4.226715e+00| 0:0:00| chol  1  1
6|1.000|1.000|2.2e-08|6.1e-06|2.0e+00|-2.217534e+00 -4.225924e+00| 0:0:00| chol  1  1
7|0.880|1.000|4.0e-09|6.1e-07|2.5e-01|-3.966164e+00 -4.217542e+00| 0:0:00| chol  1  1
8|1.000|0.744|1.0e-08|2.0e-07|1.5e-01|-4.051676e+00 -4.197803e+00| 0:0:00| chol  1  1
9|0.914|0.846|2.0e-09|3.8e-08|8.2e-02|-4.111809e+00 -4.194047e+00| 0:0:00| chol  1  1
10|1.000|1.000|3.5e-13|1.0e-09|4.0e-02|-4.154312e+00 -4.194483e+00| 0:0:00| chol  1  1
11|0.934|0.937|2.5e-13|1.2e-10|3.8e-03|-4.189258e+00 -4.193064e+00| 0:0:00| chol  1  1
12|0.985|0.985|1.0e-12|8.8e-12|5.8e-05|-4.192878e+00 -4.192936e+00| 0:0:00| chol  1  1
13|0.999|0.991|2.7e-11|1.1e-12|8.0e-07|-4.192933e+00 -4.192934e+00| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07

```

```

-----
number of iterations    = 13
primal objective value = -4.19293327e+00
dual   objective value = -4.19293412e+00
gap := trace(XZ)       = 7.96e-07
relative gap           = 8.48e-08
actual relative gap    = 9.05e-08
rel. primal infeas     = 2.68e-11
rel. dual   infeas     = 1.08e-12
norm(X), norm(y), norm(Z) = 2.6e+01, 7.6e+01, 5.3e+01
norm(A), norm(b), norm(C) = 3.1e+01, 1.4e+02, 5.8e+01
Total CPU time (secs)   = 0.11
CPU time per iteration = 0.01
termination code        = 0
DIMACS errors: 2.7e-11  0.0e+00  1.5e-12  0.0e+00  9.1e-08  8.5e-08
-----

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ans =

4.1929

Iteration 3 Total error is: 0.033173

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 174
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000  1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|3.4e+00|3.7e+05| 8.446626e+03  0.000000e+00| 0:0:00| chol  1  1
1|0.975|0.984|2.6e-02|1.2e-01|2.1e+04| 8.611925e+03  3.142482e+00| 0:0:00| chol  1  1
2|1.000|1.000|4.4e-08|2.0e-02|3.2e+03| 2.309808e+03 -5.574921e+00| 0:0:00| chol  1  1
3|0.992|0.999|1.4e-08|6.1e-03|1.4e+02| 1.027319e+02 -3.826690e+00| 0:0:00| chol  1  1
4|1.000|1.000|1.8e-08|6.1e-04|1.4e+01| 8.838210e+00 -4.244056e+00| 0:0:00| chol  1  1
5|0.815|0.824|4.0e-09|1.6e-04|3.8e+00|-4.580439e-01 -4.221880e+00| 0:0:00| chol  1  1
6|1.000|1.000|6.3e-09|6.1e-06|2.0e+00|-2.216835e+00 -4.225077e+00| 0:0:00| chol  1  1

```

```

7|0.878|0.961|2.2e-09|8.3e-07|2.5e-01|-3.966859e+00 -4.214235e+00| 0:0:00| chol 1 1
8|0.410|0.910|5.1e-09|1.3e-07|1.9e-01|-3.999119e+00 -4.192522e+00| 0:0:00| chol 1 1
9|0.712|0.702|1.5e-09|4.4e-08|8.9e-02|-4.102917e+00 -4.191916e+00| 0:0:00| chol 1 1
10|1.000|1.000|2.6e-14|9.2e-10|2.6e-02|-4.164587e+00 -4.190305e+00| 0:0:00| chol 1 1
11|0.895|1.000|1.6e-12|6.2e-11|3.9e-03|-4.185753e+00 -4.189626e+00| 0:0:00| chol 1 1
12|1.000|1.000|5.1e-12|7.1e-12|3.0e-04|-4.189294e+00 -4.189589e+00| 0:0:00| chol 1 1
13|0.989|0.989|9.5e-12|1.1e-12|3.4e-06|-4.189583e+00 -4.189587e+00| 0:0:00| chol 2 2
14|0.999|0.998|1.3e-12|1.5e-12|3.8e-08|-4.189587e+00 -4.189587e+00| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07

```

```

-----
number of iterations      = 14
primal objective value = -4.18958673e+00
dual   objective value = -4.18958677e+00
gap := trace(XZ)         = 3.82e-08
relative gap              = 4.07e-09
actual relative gap       = 4.16e-09
rel. primal infeas        = 1.27e-12
rel. dual   infeas        = 1.54e-12
norm(X), norm(y), norm(Z) = 2.7e+01, 7.6e+01, 5.3e+01
norm(A), norm(b), norm(C) = 3.1e+01, 1.4e+02, 5.8e+01
Total CPU time (secs)    = 0.11
CPU time per iteration   = 0.01
termination code         = 0
DIMACS errors: 1.3e-12  0.0e+00  2.2e-12  0.0e+00  4.2e-09  4.1e-09
-----

```

ans =

4.1896

Iteration 4 Total error is: 0.033147

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 174
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|3.4e+00|3.7e+05| 8.512358e+03  0.000000e+00| 0:0:00| chol 1 1
1|0.974|0.984|2.6e-02|1.2e-01|2.2e+04| 8.670055e+03  3.550949e+00| 0:0:00| chol 1 1
2|1.000|1.000|4.6e-08|2.0e-02|3.4e+03| 2.414159e+03 -5.754086e+00| 0:0:00| chol 1 1
3|0.992|0.999|1.5e-08|6.1e-03|1.5e+02| 1.063814e+02 -3.822487e+00| 0:0:00| chol 1 1
4|1.000|1.000|1.1e-08|6.1e-04|1.1e+01| 5.966515e+00 -4.233556e+00| 0:0:00| chol 1 1
5|0.895|0.881|5.9e-09|1.3e-04|4.0e+00| -2.103149e-01 -4.219176e+00| 0:0:00| chol 1 1
6|1.000|1.000|6.2e-09|6.1e-06|2.0e+00| -2.236452e+00 -4.222216e+00| 0:0:00| chol 1 1
7|0.878|0.964|2.1e-09|8.1e-07|2.4e-01| -3.966326e+00 -4.210567e+00| 0:0:00| chol 1 1
8|0.403|0.906|5.0e-09|1.3e-07|1.9e-01| -3.997824e+00 -4.189255e+00| 0:0:00| chol 1 1
9|0.686|0.693|1.6e-09|4.6e-08|9.2e-02| -4.096356e+00 -4.188782e+00| 0:0:00| chol 1 1
10|1.000|1.000|1.0e-13|9.3e-10|2.8e-02| -4.159364e+00 -4.187045e+00| 0:0:00| chol 1 1
11|0.895|1.000|4.1e-13|6.2e-11|4.1e-03| -4.182193e+00 -4.186314e+00| 0:0:00| chol 1 1
12|1.000|1.000|2.5e-11|7.1e-12|3.3e-04| -4.185944e+00 -4.186274e+00| 0:0:00| chol 1 1

```

```

13|0.988|0.988|1.5e-11|1.6e-12|3.9e-06|-4.186267e+00 -4.186271e+00| 0:0:00| chol 1 1
14|0.999|0.998|2.3e-11|2.3e-12|4.4e-08|-4.186271e+00 -4.186271e+00| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07

```

```

-----
number of iterations    = 14
primal objective value = -4.18627121e+00
dual   objective value = -4.18627126e+00
gap := trace(XZ)       = 4.37e-08
relative gap           = 4.66e-09
actual relative gap    = 4.98e-09
rel. primal infeas     = 2.28e-11
rel. dual   infeas     = 2.25e-12
norm(X), norm(y), norm(Z) = 2.7e+01, 7.6e+01, 5.3e+01
norm(A), norm(b), norm(C) = 3.2e+01, 1.4e+02, 5.8e+01
Total CPU time (secs)   = 0.13
CPU time per iteration = 0.01
termination code        = 0
DIMACS errors: 2.3e-11  0.0e+00  3.1e-12  0.0e+00  5.0e-09  4.7e-09
-----

```

ans =

4.1863

Iteration 5 Total error is: 0.033121

```

num. of constraints = 33
dim. of socp var   = 34,   num. of socp blk = 1
dim. of linear var = 174

```

SDPT3: Infeasible path-following algorithms

version predcorr gam expon scale_data

HKM 1 0.000 1 0

it	pstep	dstep	pinfeas	dinfeas	gap	prim-obj	dual-obj	cputime			
0	0.000	0.000	1.0e+00	3.4e+00	3.7e+05	8.578237e+03	0.000000e+00	0:0:00	chol	1	1
1	0.974	0.983	2.7e-02	1.2e-01	2.2e+04	8.728316e+03	3.958879e+00	0:0:00	chol	1	1
2	1.000	1.000	4.8e-08	2.0e-02	3.5e+03	2.521689e+03	-5.942544e+00	0:0:00	chol	1	1
3	0.992	0.999	1.5e-08	6.1e-03	1.5e+02	1.101281e+02	-3.820949e+00	0:0:00	chol	1	1
4	1.000	1.000	2.1e-08	6.1e-04	9.5e+00	4.856232e+00	-4.227463e+00	0:0:00	chol	1	1
5	0.949	0.901	8.7e-09	1.2e-04	4.3e+00	1.580132e-02	-4.216502e+00	0:0:00	chol	1	1
6	1.000	1.000	2.2e-08	6.1e-06	2.0e+00	-2.191190e+00	-4.218077e+00	0:0:00	chol	1	1
7	0.878	0.989	2.8e-09	6.8e-07	2.5e-01	-3.957045e+00	-4.207111e+00	0:0:00	chol	1	1
8	0.373	0.940	4.5e-09	9.9e-08	2.0e-01	-3.985130e+00	-4.186141e+00	0:0:00	chol	1	1
9	0.768	0.758	1.3e-09	2.9e-08	9.1e-02	-4.094884e+00	-4.185975e+00	0:0:00	chol	1	1
10	1.000	0.996	1.0e-12	9.9e-10	1.3e-02	-4.169664e+00	-4.183151e+00	0:0:00	chol	1	1
11	0.959	0.978	2.3e-12	8.2e-11	6.3e-04	-4.182356e+00	-4.182991e+00	0:0:00	chol	1	1
12	0.970	0.986	5.7e-11	2.2e-12	1.9e-05	-4.182966e+00	-4.182985e+00	0:0:00	chol	2	2
13	1.000	1.000	4.6e-11	1.5e-12	1.2e-06	-4.182984e+00	-4.182985e+00	0:0:00	chol	2	2
14	1.000	1.000	1.5e-11	2.2e-12	1.5e-08	-4.182985e+00	-4.182985e+00	0:0:00			

stop: max(relative gap, infeasibilities) < 1.00e-07

```

-----
number of iterations    = 14
primal objective value = -4.18298509e+00

```

```

dual    objective value = -4.18298502e+00
gap := trace(XZ)        = 1.48e-08
relative gap            = 1.58e-09
actual relative gap     = -6.83e-09
rel. primal infeas      = 1.49e-11
rel. dual   infeas      = 2.25e-12
norm(X), norm(y), norm(Z) = 2.7e+01, 7.6e+01, 5.3e+01
norm(A), norm(b), norm(C) = 3.2e+01, 1.4e+02, 5.8e+01
Total CPU time (secs)   = 0.11
CPU time per iteration = 0.01
termination code        = 0
DIMACS errors: 1.5e-11  0.0e+00  3.1e-12  0.0e+00  -6.8e-09  1.6e-09
-----

```

```
ans =
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```
4.1830
```

```
Iteration    6    Total error is: 0.033095
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```

num. of constraints = 33
dim. of socp var   = 34,    num. of socp blk = 1
dim. of linear var = 174
*****
SDPT3: Infeasible path-following algorithms
*****
version predcorr gam expon scale_data
HKM      1      0.000 1      0
it pstep dstep pinfeas dinfeas gap      prim-obj      dual-obj      cputime
-----
0|0.000|0.000|1.0e+00|3.4e+00|3.8e+05| 8.644286e+03  0.000000e+00| 0:0:00| chol 1 1
1|0.973|0.983|2.7e-02|1.2e-01|2.2e+04| 8.786726e+03  4.366406e+00| 0:0:00| chol 1 1
2|1.000|1.000|5.0e-08|2.0e-02|3.6e+03| 2.632301e+03 -6.139699e+00| 0:0:00| chol 1 1
3|0.992|0.999|1.6e-08|6.1e-03|1.6e+02| 1.139681e+02 -3.822131e+00| 0:0:00| chol 1 1
4|1.000|1.000|3.3e-08|6.1e-04|9.4e+00| 4.713914e+00 -4.223607e+00| 0:0:00| chol 1 1
5|0.998|0.933|1.5e-08|9.8e-05|4.5e+00| 2.734136e-01 -4.214960e+00| 0:0:00| chol 1 1
6|1.000|1.000|4.3e-08|6.1e-06|2.1e+00| -2.087423e+00 -4.213993e+00| 0:0:00| chol 1 1
7|0.853|1.000|5.1e-09|6.2e-07|3.8e-01| -3.828006e+00 -4.205353e+00| 0:0:00| chol 1 1
8|1.000|0.772|8.4e-09|1.9e-07|1.7e-01| -4.014651e+00 -4.187571e+00| 0:0:00| chol 1 1
9|1.000|0.764|2.0e-09|5.1e-08|8.0e-02| -4.100836e+00 -4.181022e+00| 0:0:00| chol 1 1
10|0.714|0.866|5.8e-10|7.8e-09|3.7e-02| -4.144761e+00 -4.181606e+00| 0:0:00| chol 1 1
11|0.976|0.955|1.4e-11|5.3e-10|1.7e-03| -4.178091e+00 -4.179782e+00| 0:0:00| chol 1 1
12|0.967|0.980|9.8e-12|1.9e-11|6.5e-05| -4.179662e+00 -4.179727e+00| 0:0:00| chol 1 1
13|1.000|1.000|4.3e-11|2.0e-12|6.4e-06| -4.179719e+00 -4.179725e+00| 0:0:00| chol 2 2
14|1.000|1.000|2.5e-12|2.9e-12|2.2e-07| -4.179725e+00 -4.179725e+00| 0:0:00|
stop: max(relative gap, infeasibilities) < 1.00e-07
-----

```

```

number of iterations = 14
primal objective value = -4.17972517e+00
dual    objective value = -4.17972541e+00
gap := trace(XZ)        = 2.24e-07
relative gap            = 2.40e-08
actual relative gap     = 2.54e-08
rel. primal infeas      = 2.49e-12
rel. dual   infeas      = 2.93e-12

```

```

norm(X), norm(y), norm(Z) = 2.7e+01, 7.6e+01, 5.3e+01
norm(A), norm(b), norm(C) = 3.2e+01, 1.5e+02, 5.8e+01
Total CPU time (secs) = 0.11
CPU time per iteration = 0.01
termination code = 0
DIMACS errors: 2.5e-12 0.0e+00 4.1e-12 0.0e+00 2.5e-08 2.4e-08
-----

```

```
ans =
```

```
4.1797
```

```
Iteration 7 Total error is: 0.033068
```

```

num. of constraints = 33
dim. of socp var = 34, num. of socp blk = 1
dim. of linear var = 174

```

```
*****
```

```
SDPT3: Infeasible path-following algorithms
```

```
*****
```

```
version predcorr gam expon scale_data
```

```
HKM 1 0.000 1 0
```

it	pstep	dstep	pinfeas	dinfeas	gap	prim-obj	dual-obj	cputime
0	0.000	0.000	1.0e+00	3.4e+00	3.8e+05	8.710630e+03	0.000000e+00	0:0:00
1	0.973	0.982	2.8e-02	1.2e-01	2.2e+04	8.845394e+03	4.774786e+00	0:0:00
2	1.000	1.000	5.2e-08	2.0e-02	3.8e+03	2.746145e+03	-6.345472e+00	0:0:00
3	0.992	0.999	1.7e-08	6.1e-03	1.6e+02	1.179081e+02	-3.826163e+00	0:0:00
4	1.000	1.000	4.4e-08	6.1e-04	9.9e+00	5.204102e+00	-4.221203e+00	0:0:00
5	1.000	1.000	1.9e-08	6.1e-05	5.1e+00	8.740776e-01	-4.214919e+00	0:0:00
6	1.000	1.000	3.9e-08	6.1e-06	2.0e+00	-2.258753e+00	-4.213965e+00	0:0:00
7	0.912	1.000	2.7e-09	6.2e-07	2.3e-01	-3.975144e+00	-4.200624e+00	0:0:00
8	0.868	0.748	8.9e-09	2.0e-07	1.2e-01	-4.055610e+00	-4.178871e+00	0:0:00
9	0.517	0.513	4.3e-09	1.0e-07	9.5e-02	-4.085177e+00	-4.179934e+00	0:0:00
10	0.473	1.000	2.2e-09	1.5e-09	6.8e-02	-4.110089e+00	-4.178014e+00	0:0:00
11	1.000	1.000	8.7e-13	5.1e-10	2.9e-02	-4.148471e+00	-4.177384e+00	0:0:00
12	0.954	0.954	1.2e-13	3.0e-11	1.8e-03	-4.174741e+00	-4.176548e+00	0:0:00
13	0.982	0.985	1.4e-12	2.1e-12	3.2e-05	-4.176455e+00	-4.176488e+00	0:0:00
14	1.000	0.994	1.1e-11	1.0e-12	1.3e-06	-4.176485e+00	-4.176487e+00	0:0:00
15	1.000	1.000	5.9e-11	1.5e-12	4.2e-08	-4.176487e+00	-4.176487e+00	0:0:00

```
stop: max(relative gap, infeasibilities) < 1.00e-07
```

```

-----
number of iterations = 15
primal objective value = -4.17648667e+00
dual objective value = -4.17648661e+00
gap := trace(XZ) = 4.17e-08
relative gap = 4.46e-09
actual relative gap = -7.15e-09
rel. primal infeas = 5.90e-11
rel. dual infeas = 1.50e-12
norm(X), norm(y), norm(Z) = 2.7e+01, 7.6e+01, 5.3e+01
norm(A), norm(b), norm(C) = 3.2e+01, 1.5e+02, 5.8e+01
Total CPU time (secs) = 0.13
CPU time per iteration = 0.01
termination code = 0

```

```
DIMACS errors: 5.9e-11  0.0e+00  2.1e-12  0.0e+00  -7.2e-09  4.5e-09
```

```
-----
```

```
ans =
```

```
4.1765
```

```
Iteration    8    Total error is: 0.033041
```

```
The total representation error of the testing signals is: 0.026364
```

```
>>
```