

Series Monday, Oct 29, 2018 (Deep Learning, Exercise series 5 - solutions)

Solution 1 (Properties of convolutional layer):

1.

$$\begin{aligned}\tau_{(s,t)}(f * k)(x, y) &= \sum_{u=-p}^p \sum_{v=-q}^q f(x-s-v, y-t-v)k(u, v) \\ &= \sum_{u=-p}^p \sum_{v=-q}^q (\tau_{(s,t)}f)(x-v, y-v)k(u, v) \\ &= ((\tau_{(s,t)}f) * k)(x, y).\end{aligned}$$

2. The size of $f * k$ is $(m-2p) \times (n-2q)$, which is smaller than the size of f . To make the output size the same as the input size, we can apply padding around the input image so that the padded image has size $(m+2p) \times (n+2q)$, and then convolute the padded image with the kernel.

Solution 2 (Local connectivity and parameter sharing in CNNs):

Setting clarification: the bias is ignored for simplicity.

1. The total number of outputs of the first layer of the CNN is $3K(m-p+1)^2$. For each channel of the image, the size of the output of the convolution with a kernel is $(m-p+1)^2$. Since there are K kernels, so the size of the output from convolution with all kernels for a channel is $K(m-p+1)^2$. And with 3 channels in the image, the total output size is $3K(m-p+1)^2$. To construct a fully-connected neural networks with the same number of outputs in the first layer, the number of parameters needed for the first layer is $3Km^2(m-p+1)^2$ $9Km^2(m-p+1)^2$.
2. In the CNN, each node in the first layer is only connected with p^2 input nodes. So for the locally-connected neural network that has the same connections between the first layer and the input layer, the number of parameters needed for the first layer is $3Kp^2(m-p+1)^2$.
3. When the image size is $128 \times 128 \times 3$ and kernel size is 5×5 , the first-layer parameter number ratio between the CNN and the locally connected neural network is 2.168×10^{-5} ; and between the CNN and the fully-connected neural network, the ratio is 1.103×10^{-8} .

Remark: We can see from the example that by using local connectivity and parameter sharing, CNNs reduce the number of parameters by a large amount which makes it much more computationally efficient to train them.

Solution 3 (Backpropagation through convolutional layers):

For simplicity, we first compute the derivative of the loss function with respect to each entry $w_{u,v}, \forall u, v \in$

$$\{-k, \dots, 0, \dots, k\},$$

$$\begin{aligned}
\frac{\partial L}{\partial w_{u,v}} &= \sum_i \sum_j \frac{\partial L}{\partial y_{i,j}^{(l)}} \frac{\partial y_{i,j}^{(l)}}{\partial w_{u,v}} \\
&= \sum_i \sum_j \frac{\partial L}{\partial y_{i,j}^{(l)}} \frac{\partial}{\partial w_{u,v}} \left(\sum_s \sum_t y_{i-s,j-t}^{(l-1)} w_{s,t} \right) \\
&= \sum_i \sum_j \frac{\partial L}{\partial y_{i,j}^{(l)}} y_{i-u,j-v}^{(l-1)} \\
&= \sum_i \sum_j \frac{\partial L}{\partial y_{i,j}^{(l)}} y_{-(u-i), -(v-j)}^{(l-1)} \\
&= \sum_i \sum_j \frac{\partial L}{\partial y_{i,j}^{(l)}} \text{rot}_{180^\circ}(y^{(l-1)})_{u-i,v-j} \\
&= (\text{rot}_{180^\circ}(y^{(l-1)}) * \frac{\partial L}{\partial y^{(l)}})_{u,v}.
\end{aligned}$$

Therefore, $\frac{\partial L}{\partial w} = \text{rot}_{180^\circ}(y^{(l-1)}) * \frac{\partial L}{\partial y^{(l)}}$.

Similarly,

$$\begin{aligned}
\frac{\partial L}{\partial y_{m,n}^{(l-1)}} &= \sum_i \sum_j \frac{\partial L}{\partial y_{i,j}^{(l)}} \frac{\partial y_{i,j}^{(l)}}{\partial y_{m,n}^{(l-1)}} \\
&= \sum_i \sum_j \frac{\partial L}{\partial y_{i,j}^{(l)}} \frac{\partial}{\partial y_{m,n}^{(l-1)}} \left(\sum_u \sum_v y_{i-u,j-v}^{(l-1)} w_{u,v} \right) \\
&= \sum_i \sum_j \frac{\partial L}{\partial y_{i,j}^{(l)}} w_{i-m,j-n} \\
&= \sum_i \sum_j \frac{\partial L}{\partial y_{i,j}^{(l)}} \text{rot}_{180^\circ}(w)_{m-i,n-j} \\
&= (\text{rot}_{180^\circ}(w) * \frac{\partial L}{\partial y^{(l)}})_{m,n},
\end{aligned}$$

hence $\frac{\partial L}{\partial y^{(l-1)}} = \text{rot}_{180^\circ}(w) * \frac{\partial L}{\partial y^{(l)}}$.

Solution 4 (Practical: CNNs in tensorflow):

See `train_and_test_MNIST_solution.py`.