

Biomedical Imaging

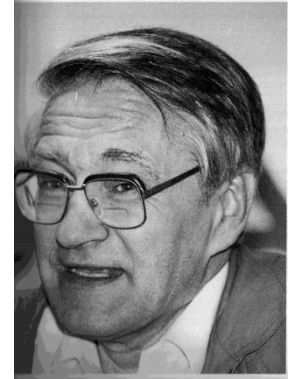
Magnetic Resonance Imaging

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Magnetic Resonance Imaging

- Probe: radiofrequency waves
- Wavelength: **10 – 50 cm**
- Matter interaction: nuclear spin transitions

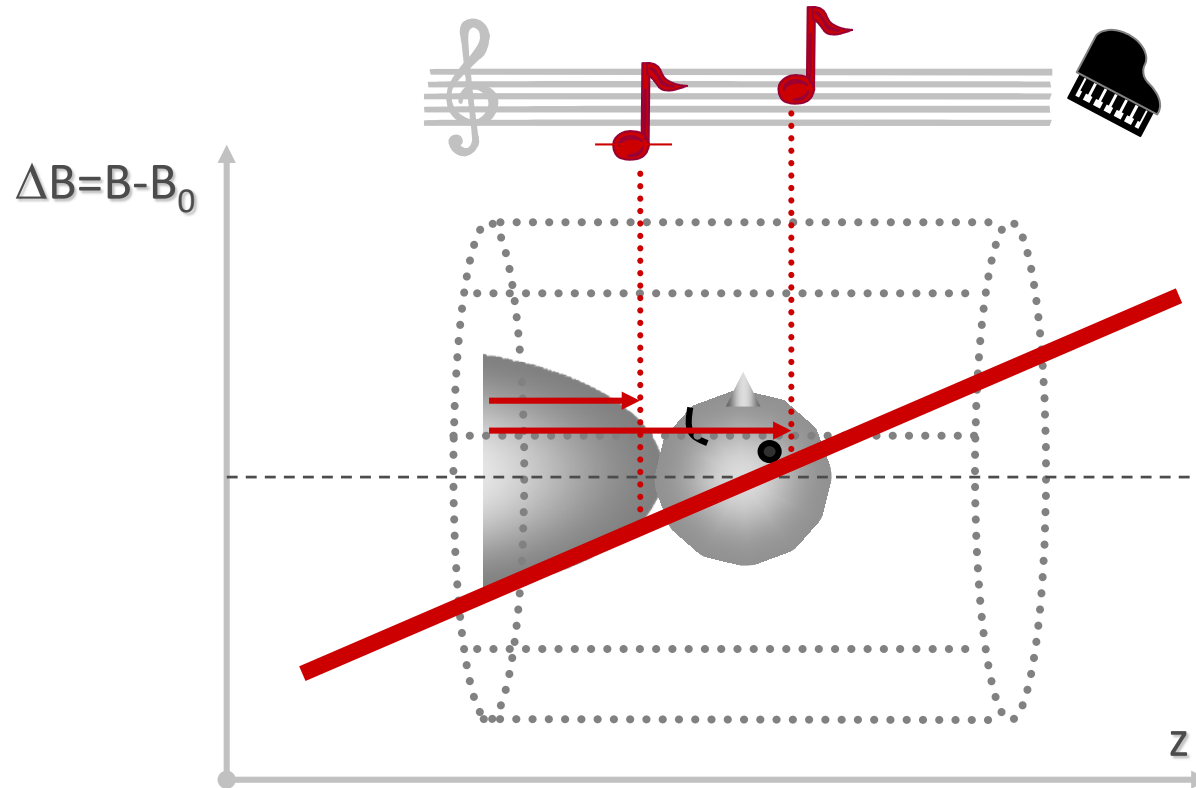


The radio-frequency window, on the other hand, was not exploited until 1972. This is not astonishing considering the achievable resolution, which is usually limited by the wavelength of the applied radiation through the uncertainty relation. The maximum radio-frequency useful for imaging is about 100 MHz, leading to a resolution of 3 m which is not sufficient even for imaging elephants.

The crucial idea, as first proposed by Lauterbur (10.1, 10.2), is to utilize a magnetic field *gradient* to disperse the NMR resonance frequencies of the various volumes along the z -axis.

R.R. Ernst et al. (1987)

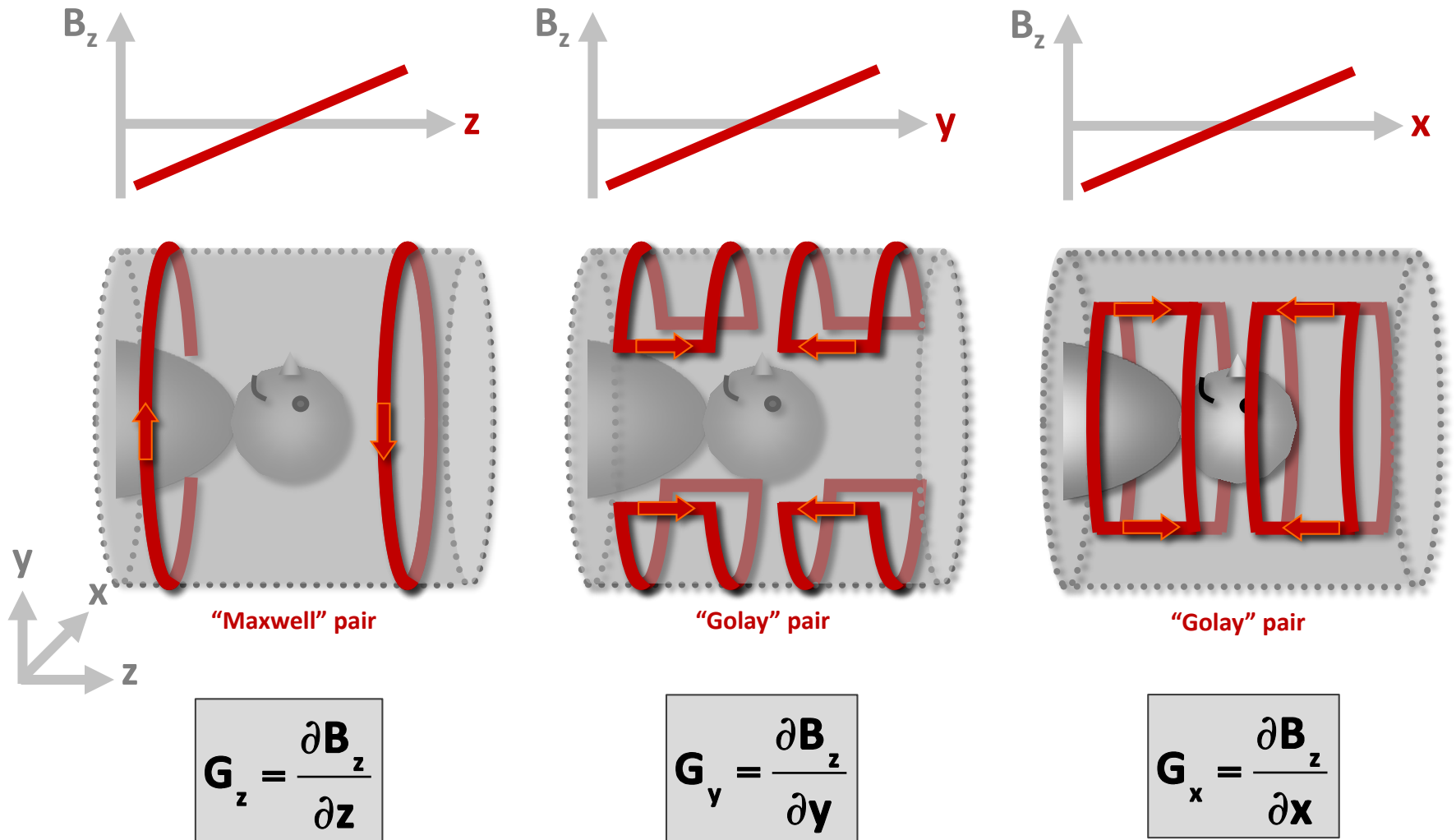
Position → Frequency

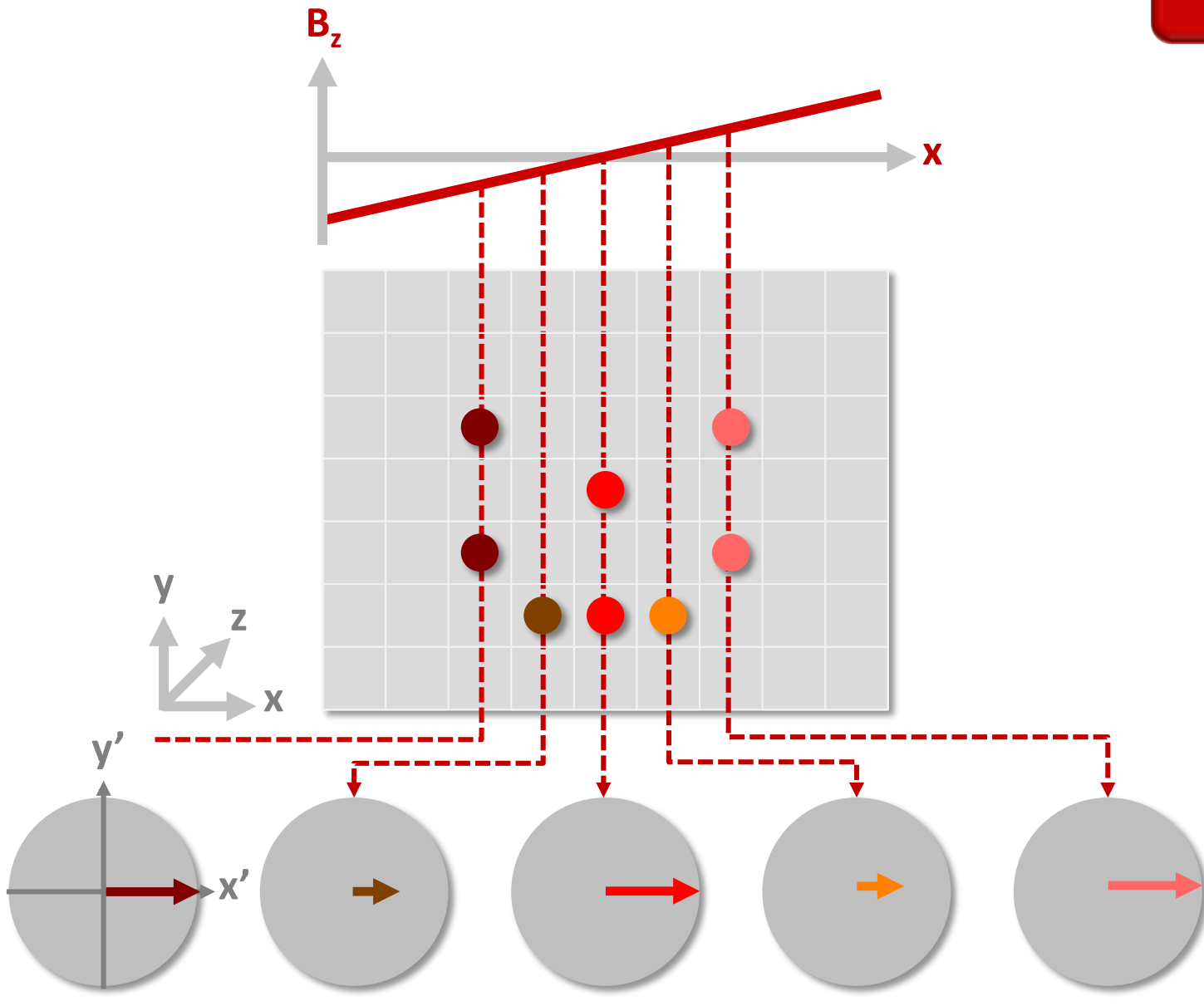


$$\omega(z) = \gamma \left(B_0 + \frac{\partial B_z}{\partial z} z \right)$$

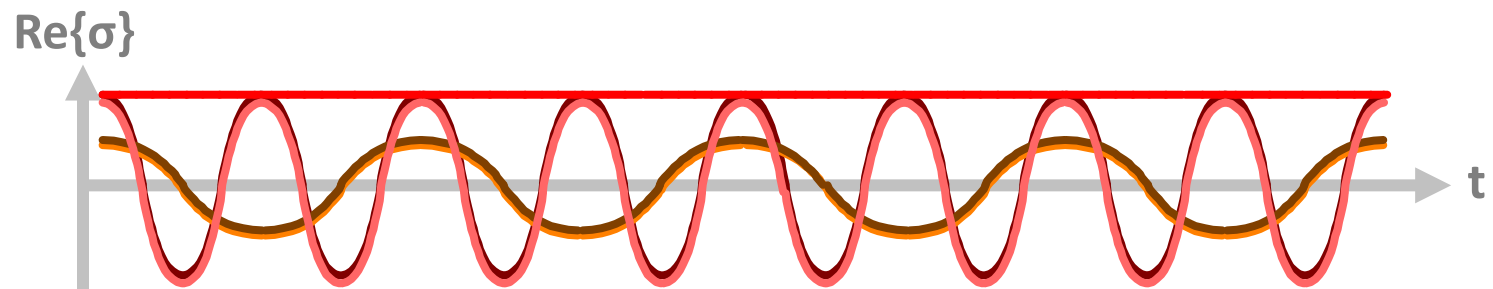
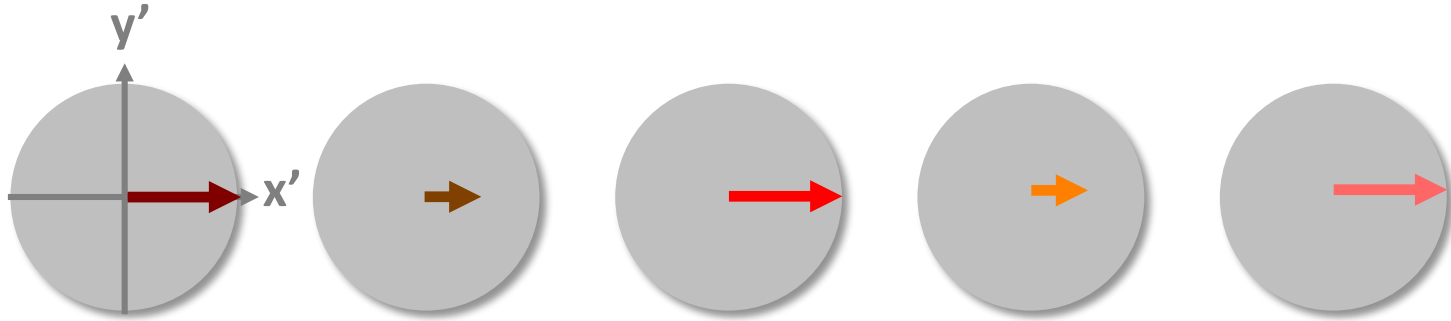


Magnetic gradient fields

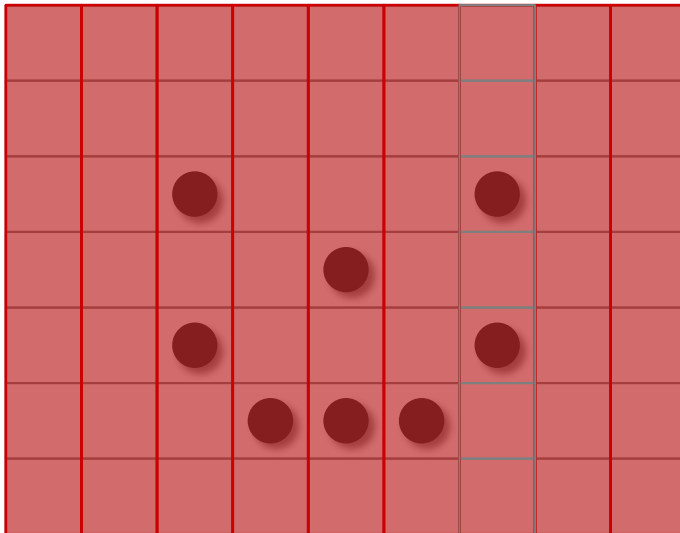




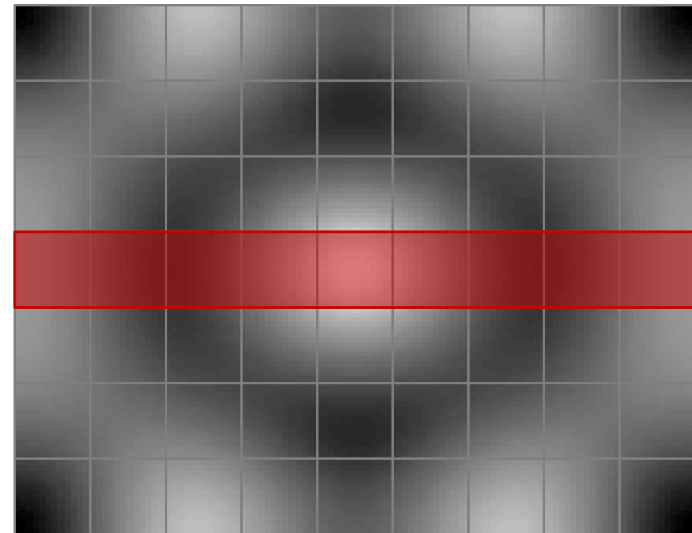
Frequency encoding



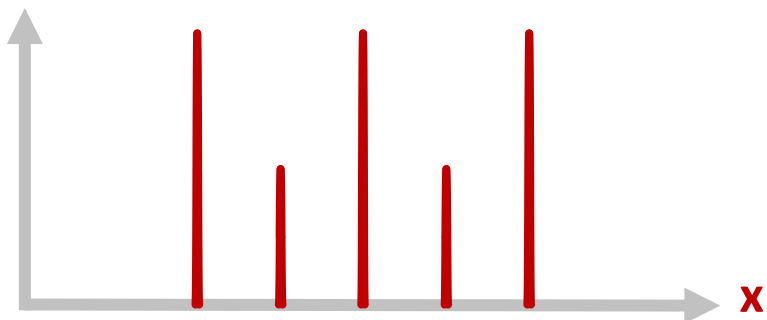
Object space



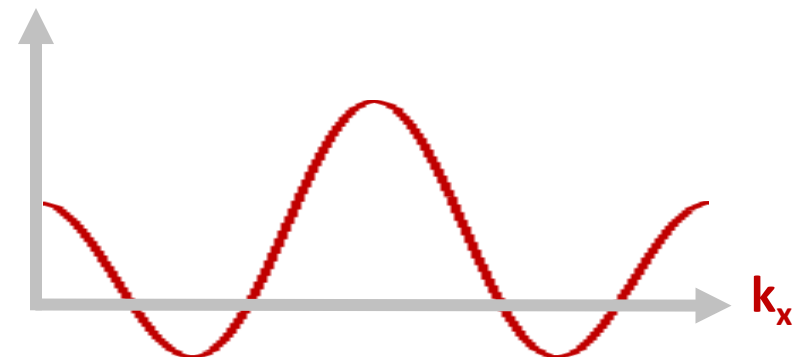
K-space



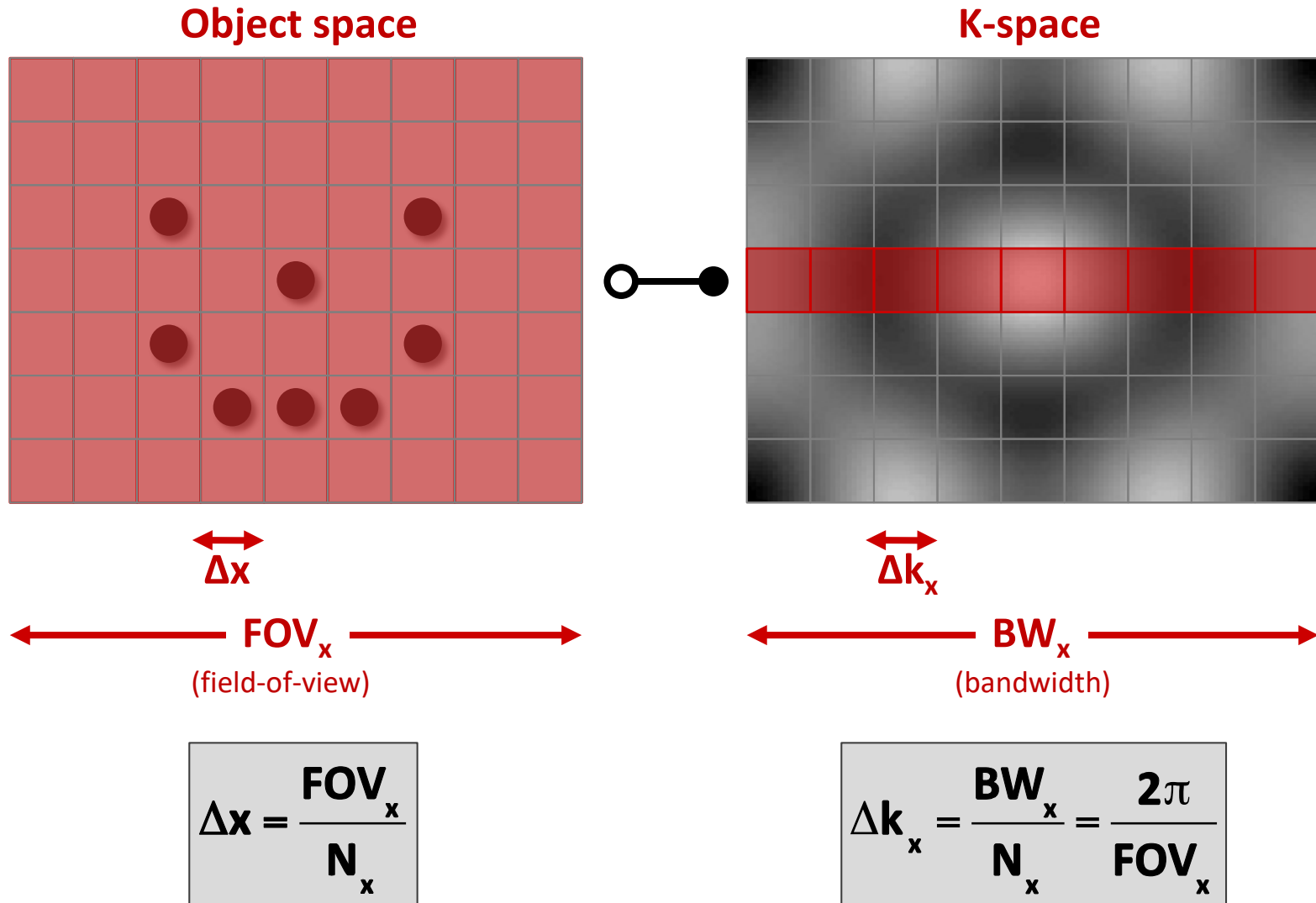
$|FT\{s\}|$



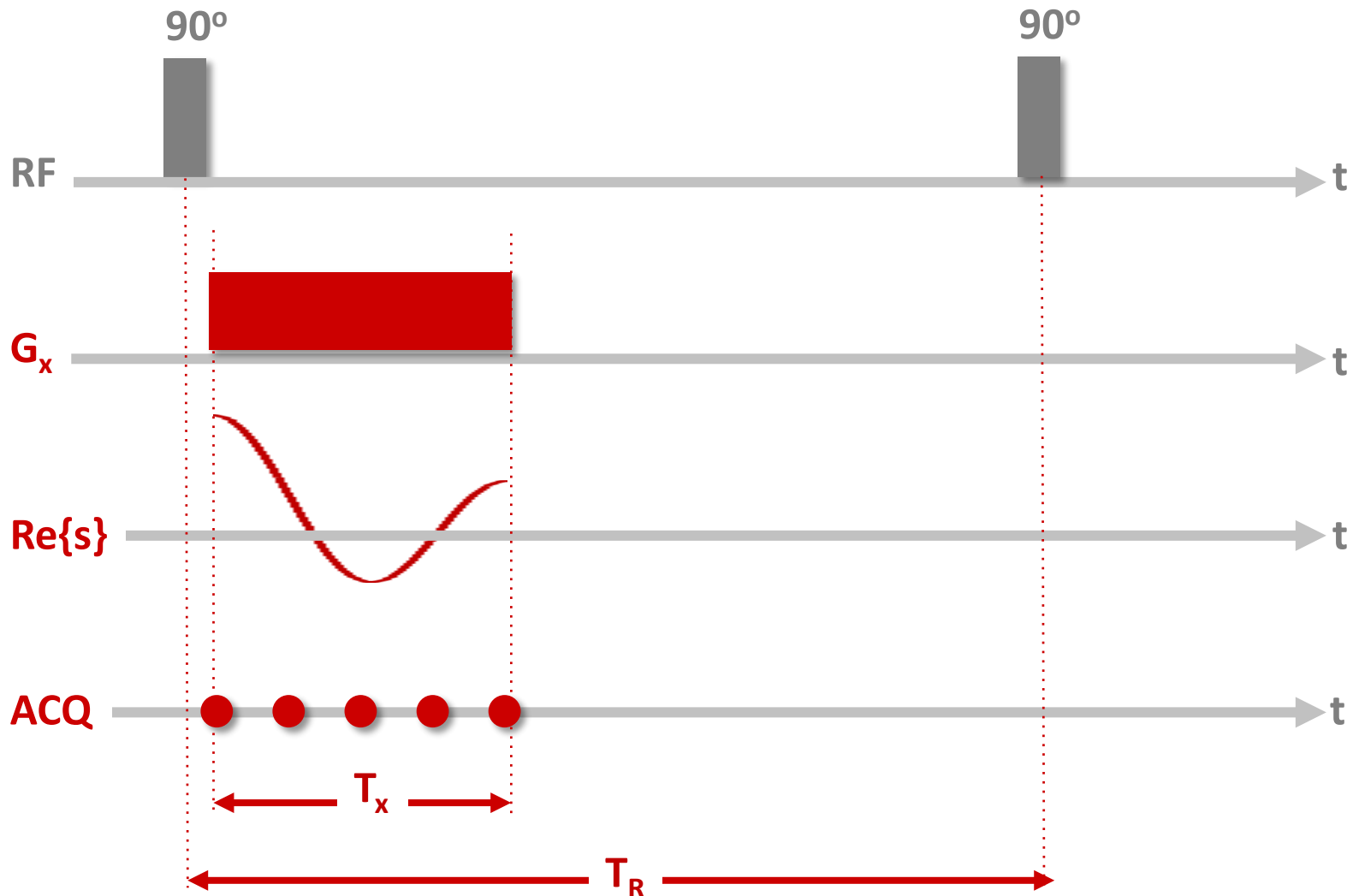
$Re\{s\}$



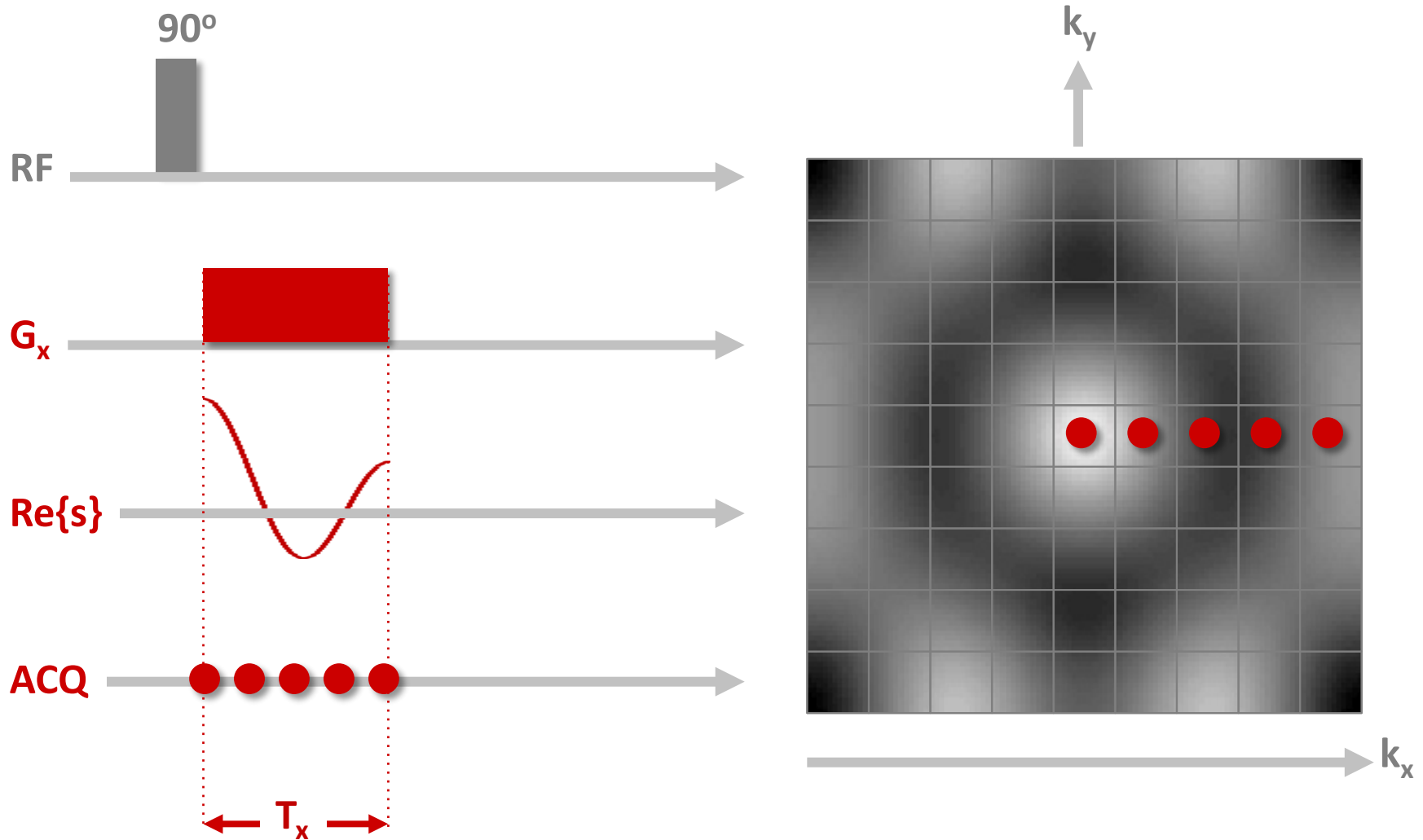
Object and k-space



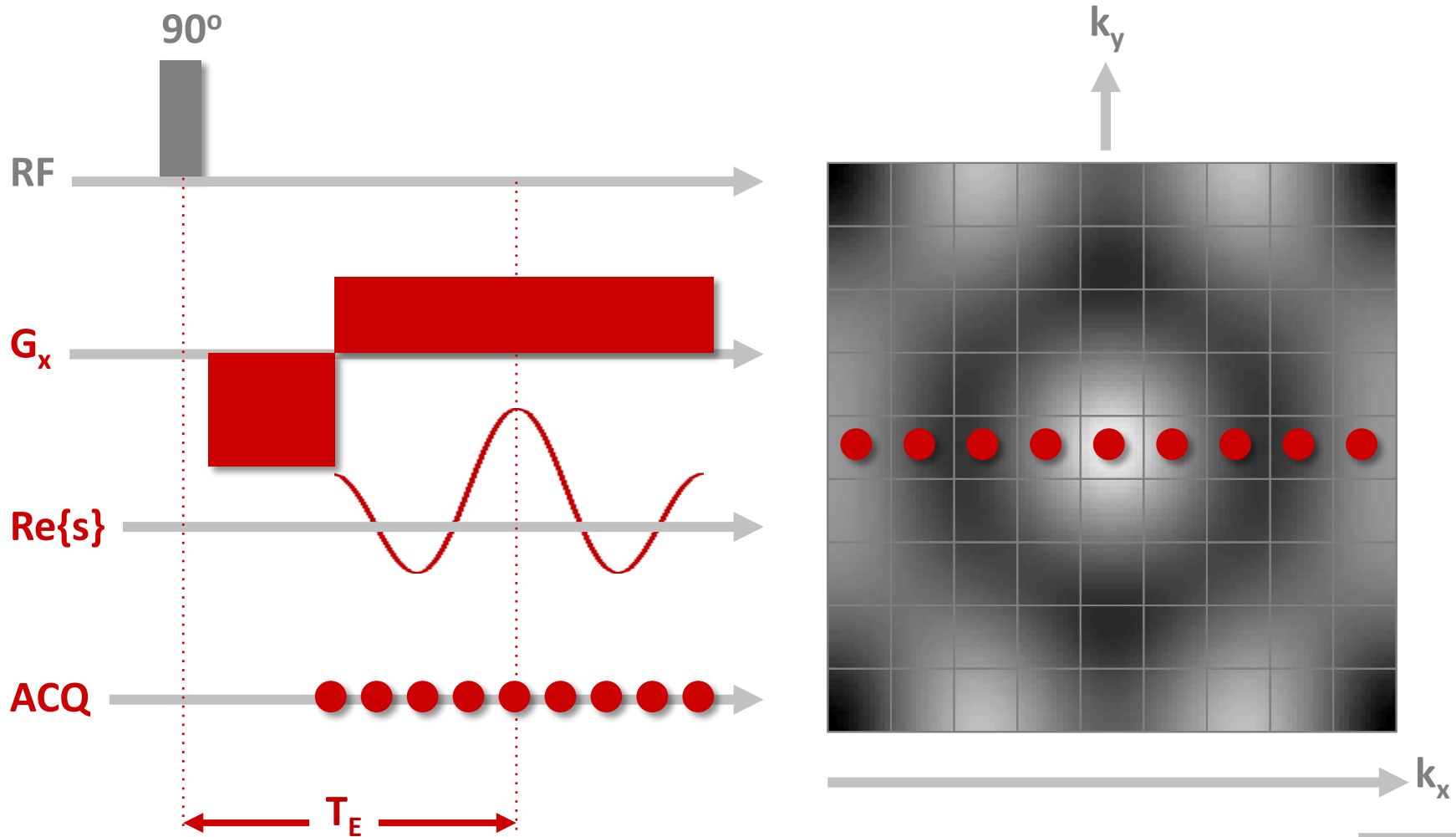
Frequency encoding experiment



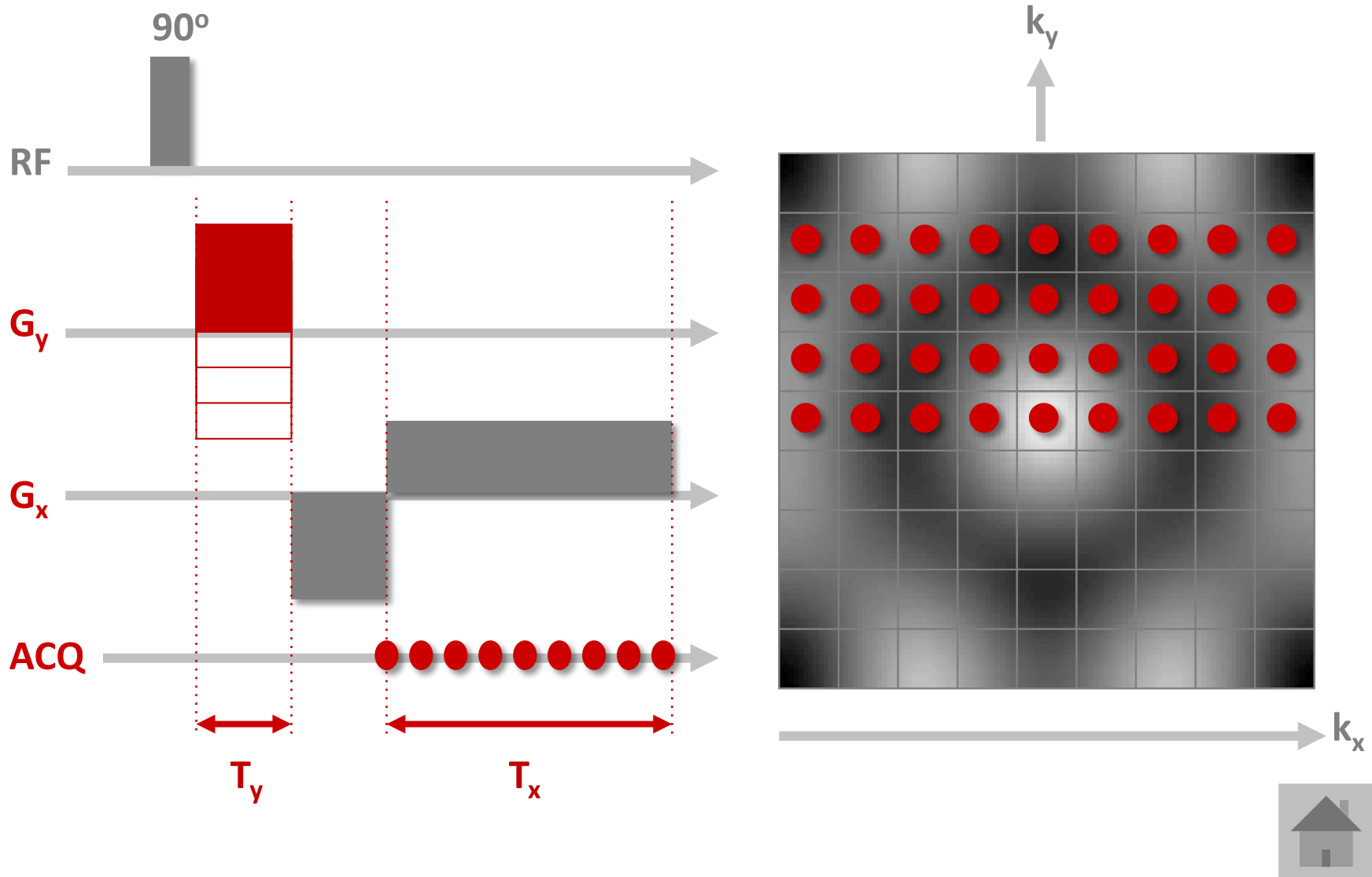
Frequency encoding experiment



Gradient echo encoding experiment



Gradient echo encoding experiment



Gradient Encoding

Gradient in x direction:

$$B(x) = B_0 + G_x x$$

Gradients in all directions:

$$B(x, y, z) = B_0 + G_x x + G_y y + G_z z$$

$$\mathbf{r} = (x, y, z)^T, \mathbf{G} = (G_x, G_y, G_z)^T$$

$$B(\mathbf{r}) = B_0 + \mathbf{G} \cdot \mathbf{r}$$

Frequency at position \mathbf{r} , time t :

$$\omega(\mathbf{r}, t) = \gamma B(\mathbf{r}, t) = \gamma B_0 + \gamma \mathbf{G}(t) \cdot \mathbf{r}$$

Phase of signal from position \mathbf{r} :

$$\varphi(\mathbf{r}, t) = \gamma B_0 t + \gamma \left(\int_0^t \mathbf{G}(\tau) d\tau \right) \cdot \mathbf{r}$$

Gradient Encoding

Phase of signal from position \mathbf{r} :
$$\varphi(\mathbf{r}, t) = \gamma B_0 t + \underbrace{\left(\gamma \int_0^t \mathbf{G}(\tau) d\tau \right)}_{\mathbf{k}(t)} \cdot \mathbf{r}$$

$$\varphi(\mathbf{r}, t) = \omega_0 t + \mathbf{k}(t) \cdot \mathbf{r}$$

Signal from position \mathbf{r} :

$$s(\mathbf{r}, t) = \rho(\mathbf{r}) e^{j\omega_0 t} e^{j\mathbf{k}(t) \cdot \mathbf{r}}$$

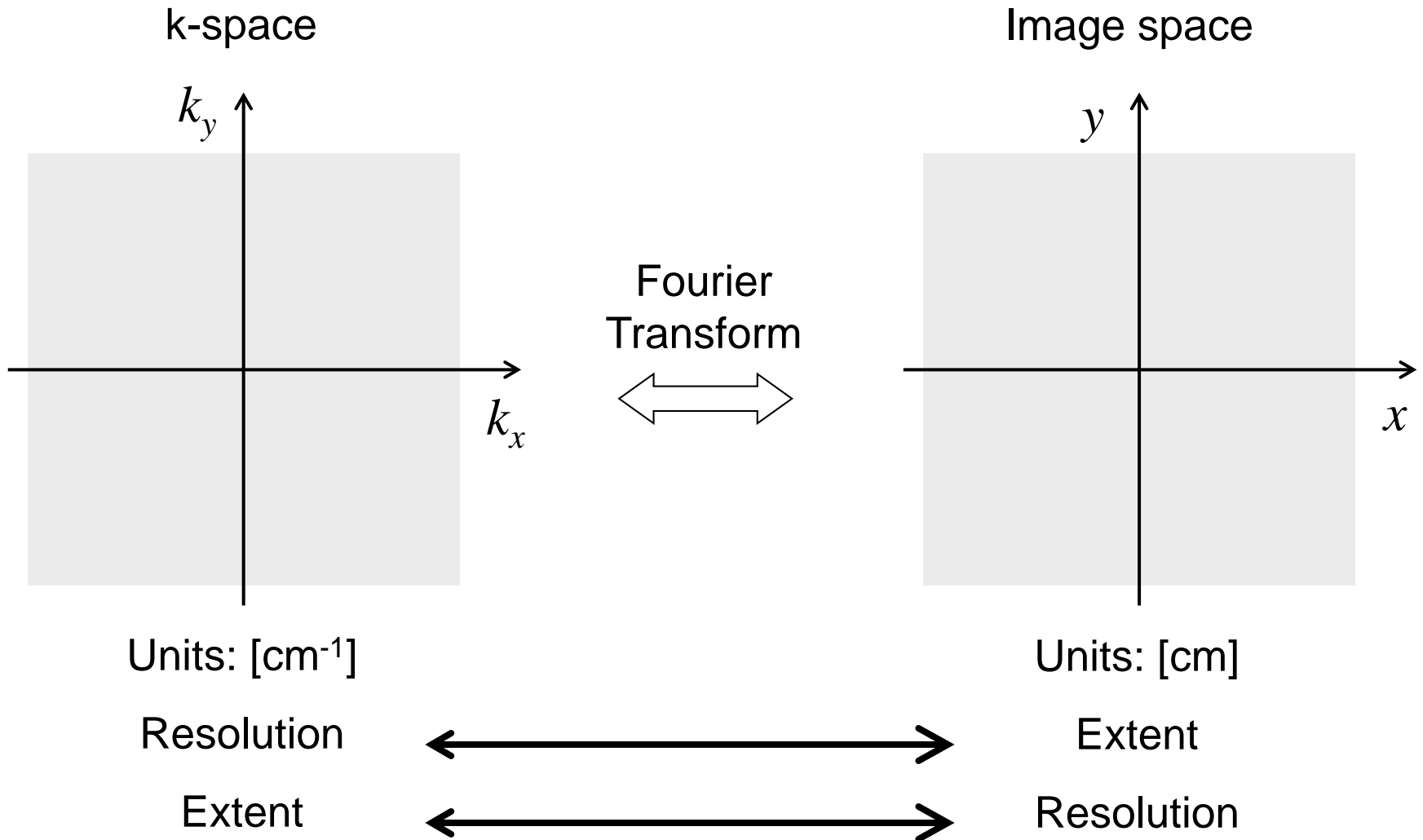
Signal from entire object:

$$S(t) = e^{j\omega_0 t} \int_{obj} \rho(\mathbf{r}) e^{j\mathbf{k}(t) \cdot \mathbf{r}} d^3r$$

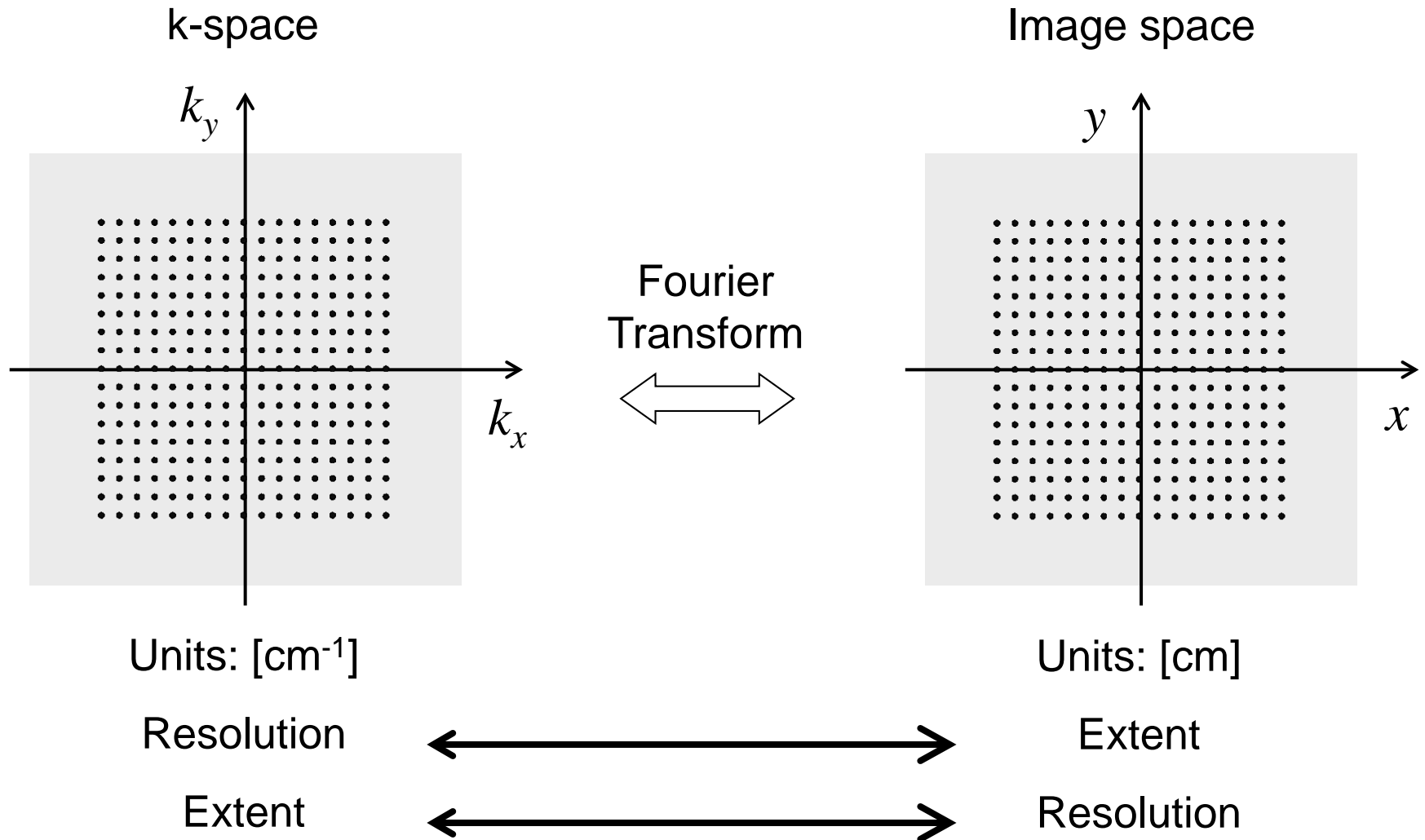
$$S(\mathbf{k}) = e^{j\omega_0 t} \int_{obj} \rho(\mathbf{r}) e^{j\mathbf{k} \cdot \mathbf{r}} d^3r$$

$\underbrace{\int_{obj} \rho(\mathbf{r}) e^{j\mathbf{k} \cdot \mathbf{r}} d^3r}_{\text{Fourier Transform of } \rho(\mathbf{r})}$

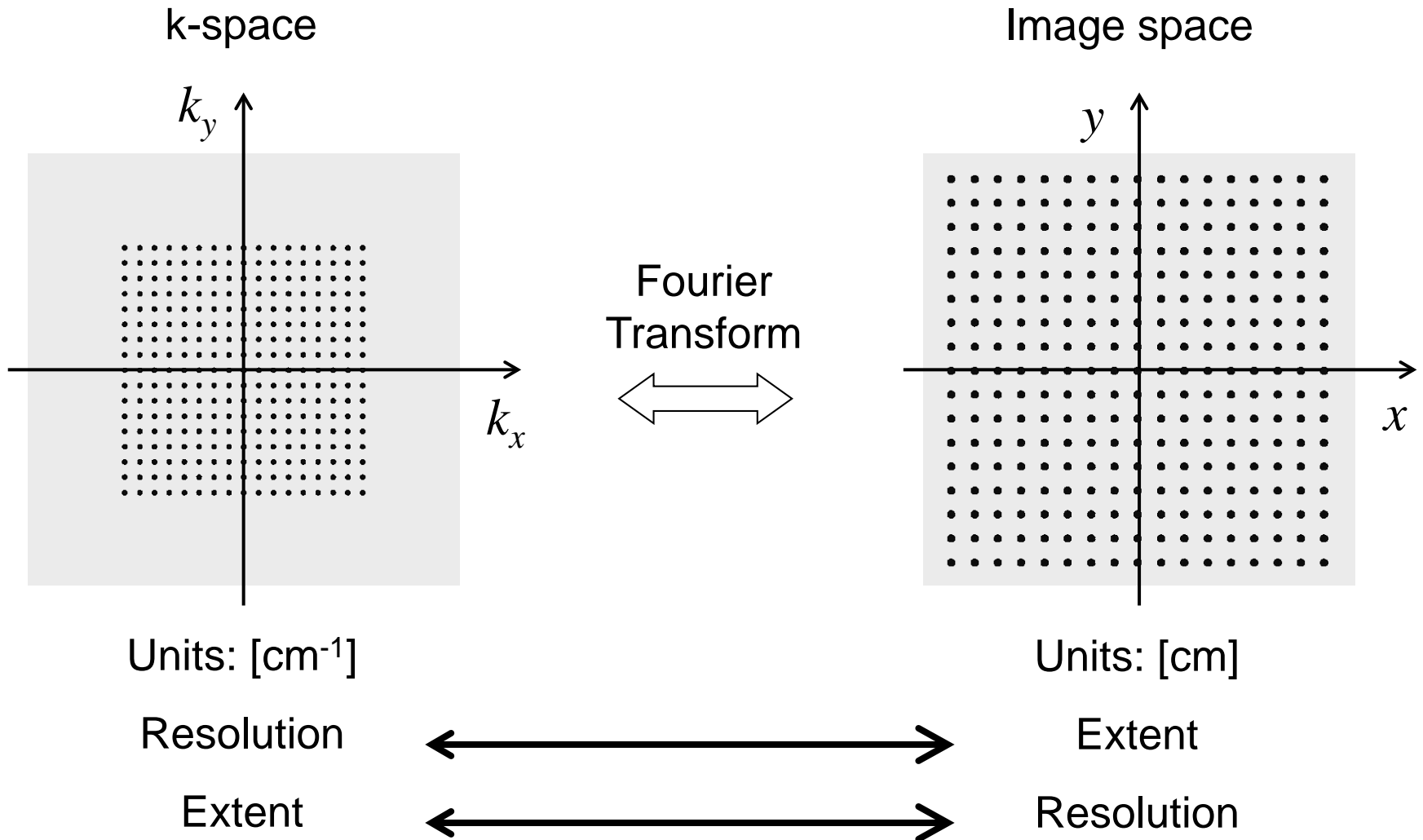
Fourier Imaging



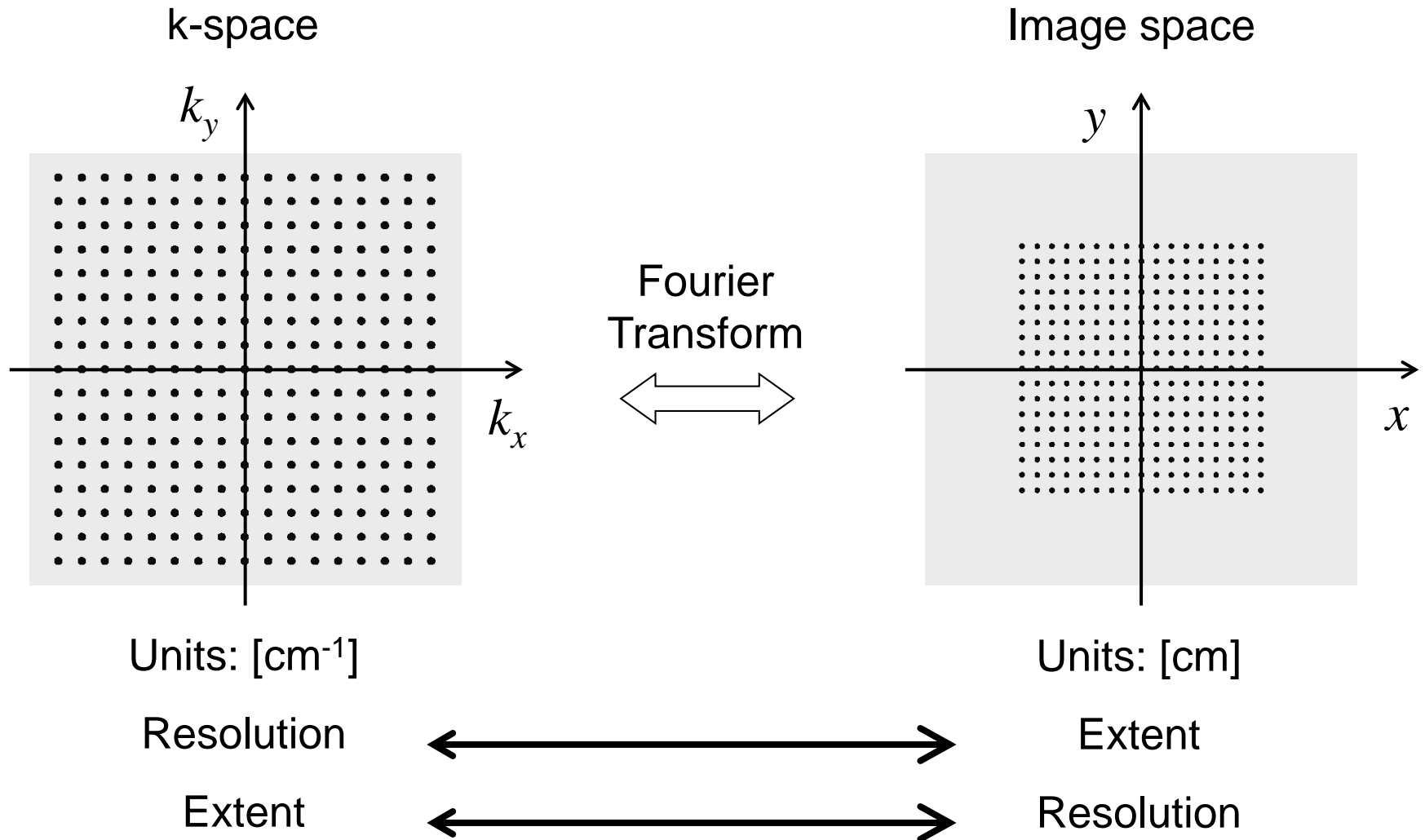
Fourier Imaging



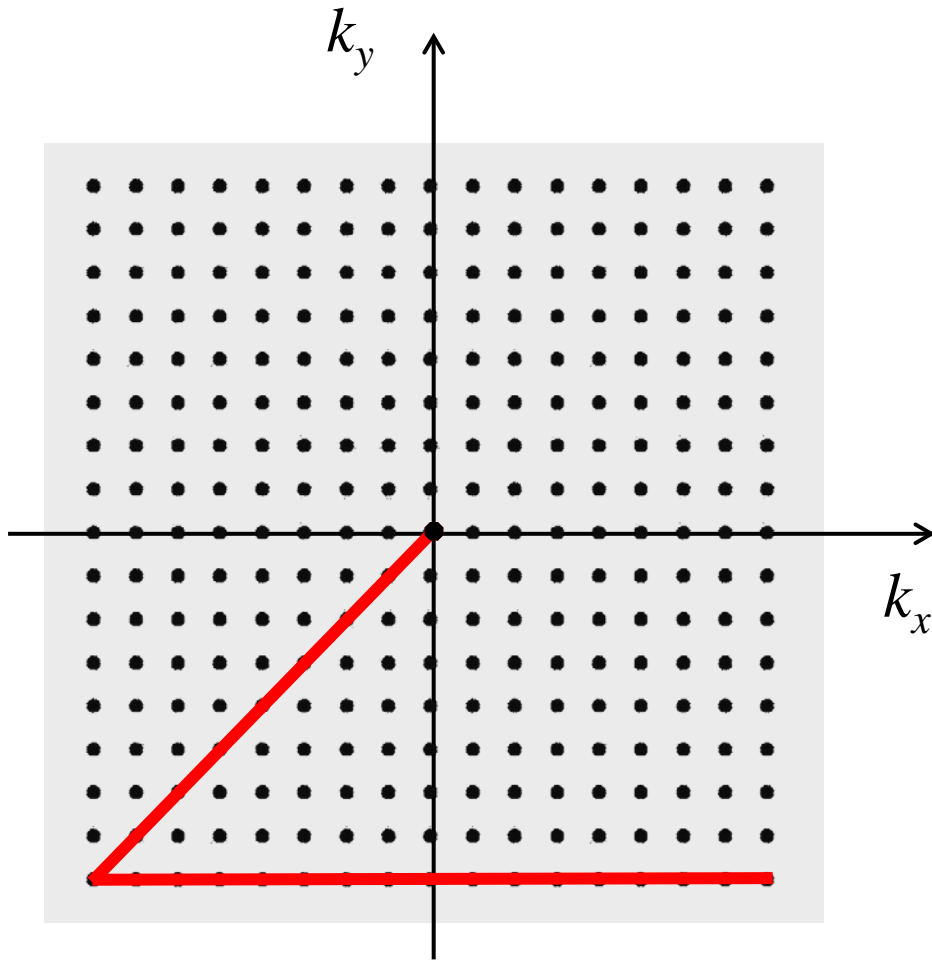
Fourier Imaging



Fourier Imaging



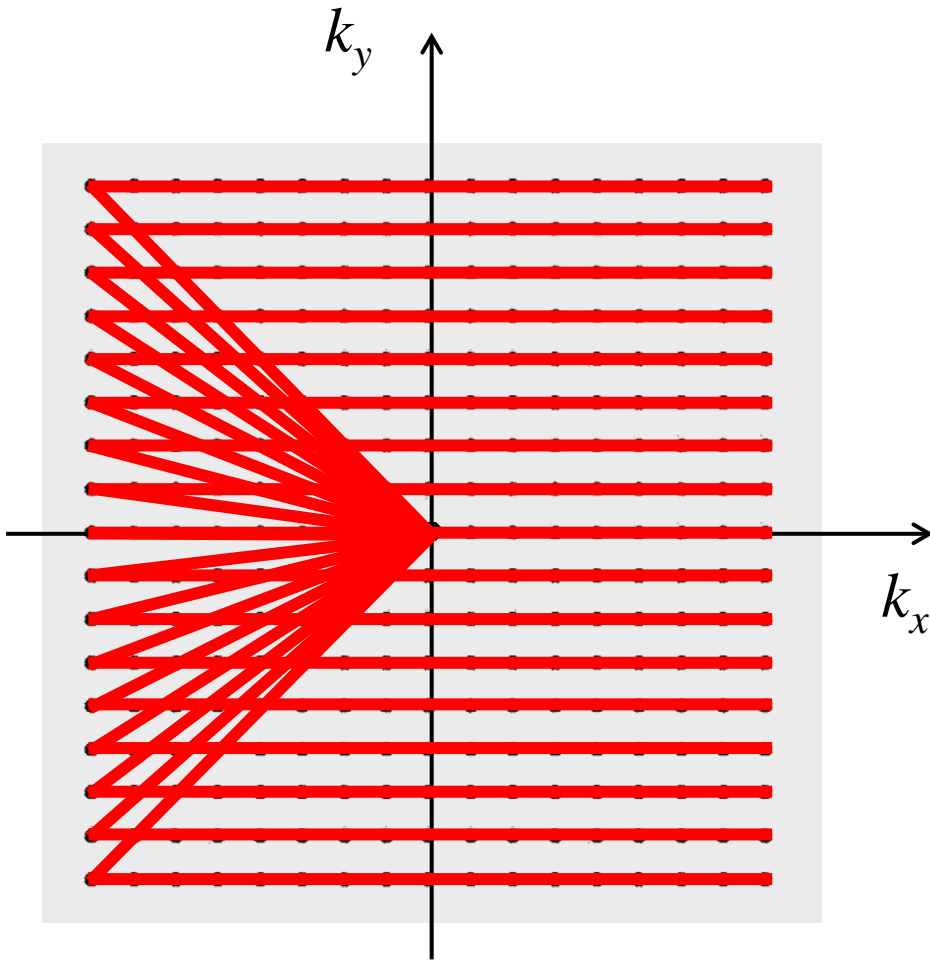
Fourier Imaging



$$\mathbf{k}(t) = \gamma \int_0^t \mathbf{G}(\tau) d\tau$$

$$\dot{\mathbf{k}} = \gamma \mathbf{G}(t)$$

Fourier Imaging



$$\mathbf{k}(t) = \gamma \int_0^t \mathbf{G}(\tau) d\tau$$

$$\dot{\mathbf{k}} = \gamma \mathbf{G}(t)$$

After excitation: $\mathbf{k} = \mathbf{0}$

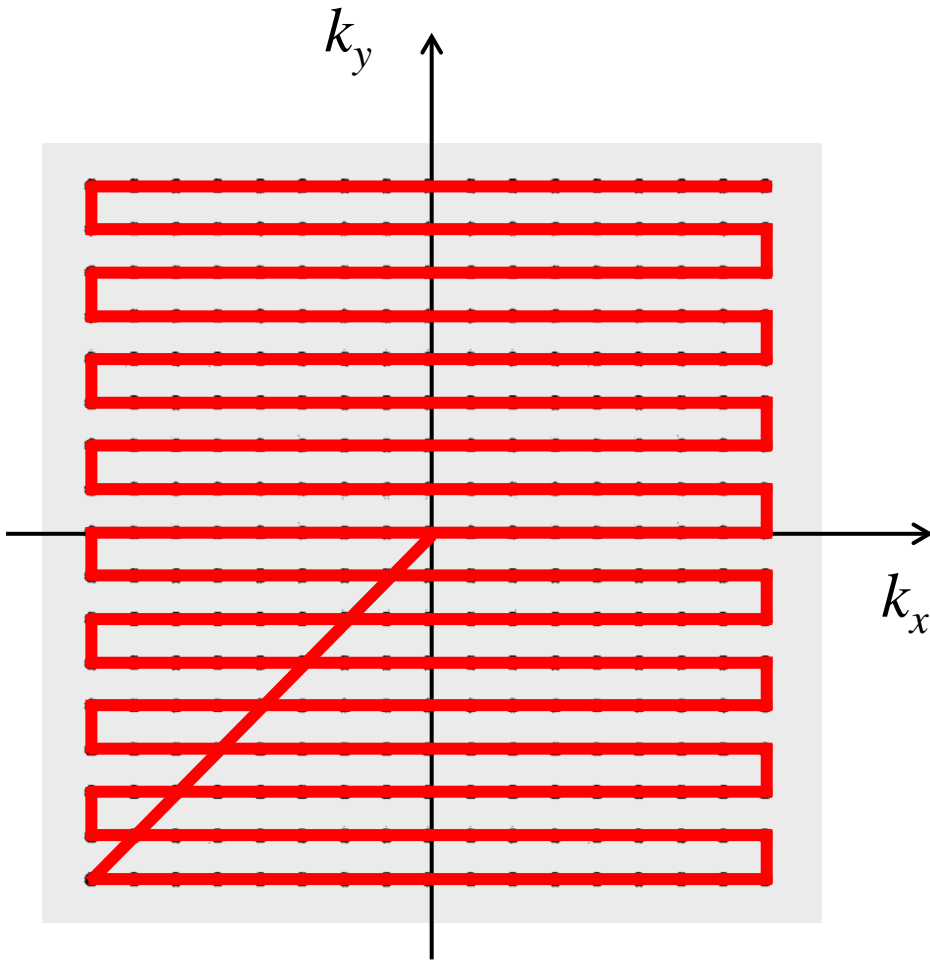
To bottom left with

$$\mathbf{G} = (-1, -1, 0)$$

Then right with

$$\mathbf{G} = (+1, 0, 0)$$

Fourier Imaging



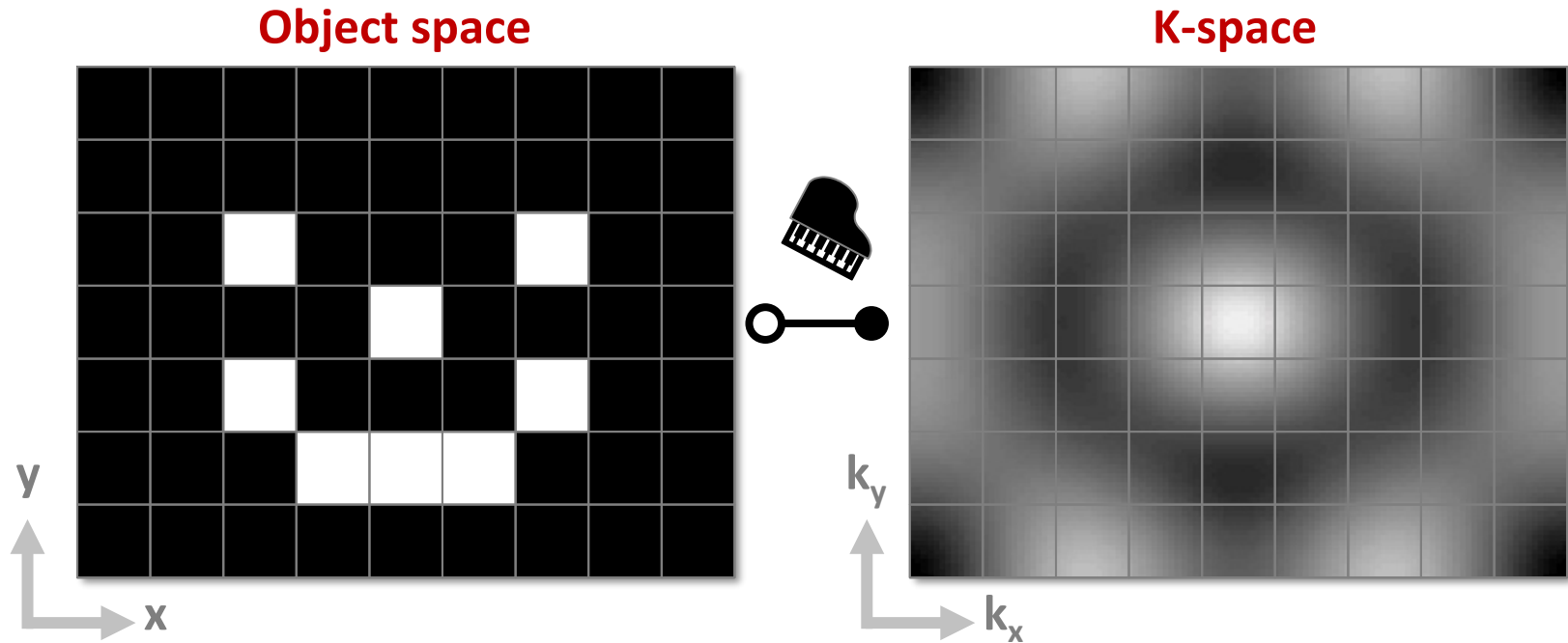
$$\mathbf{k}(t) = \gamma \int_0^t \mathbf{G}(\tau) d\tau$$

$$\dot{\mathbf{k}} = \gamma \mathbf{G}(t)$$

After excitation: $\mathbf{k} = \mathbf{0}$

Any other way of
traversing k-space

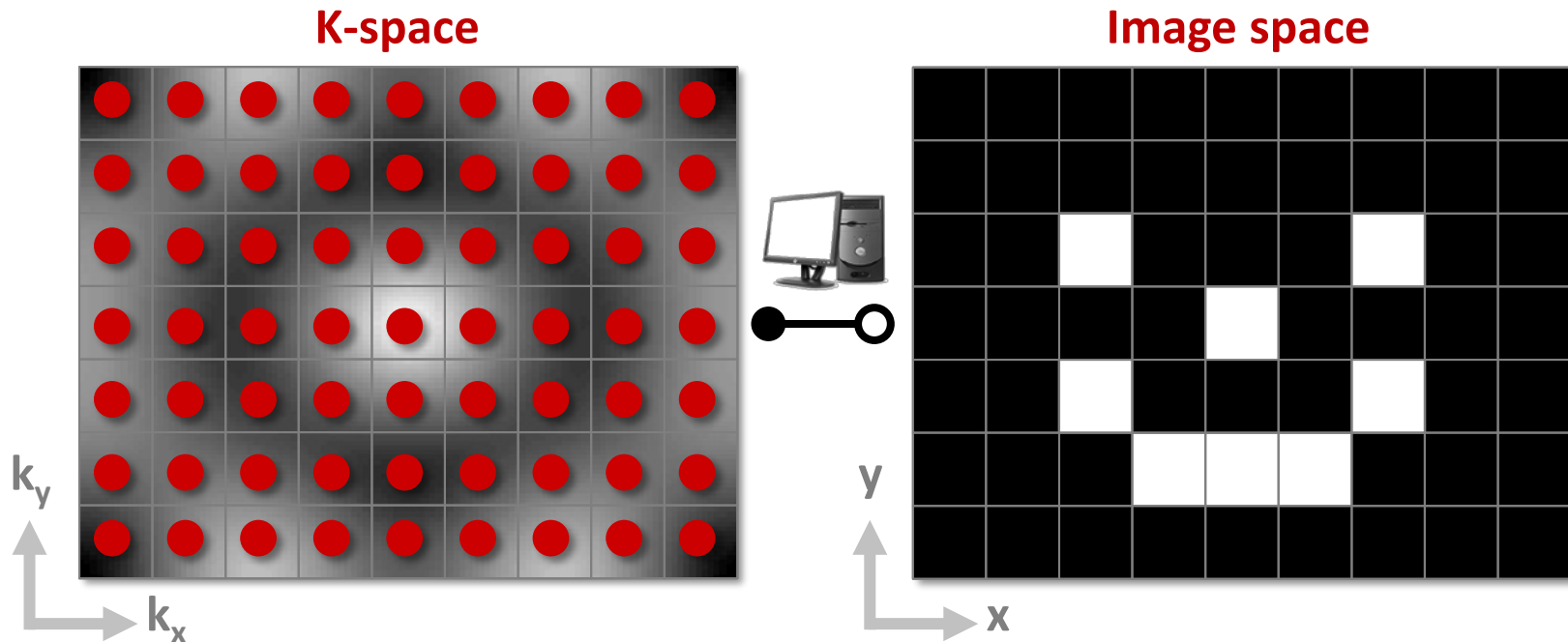
E.g., Meandering
(Echo-planar imaging, EPI)



$$s(k_{xp}, k_{yq}) \propto \sum_i \sum_j \rho(x_i, y_j) e^{j(k_{xp}x_i + k_{yq}y_j)}$$

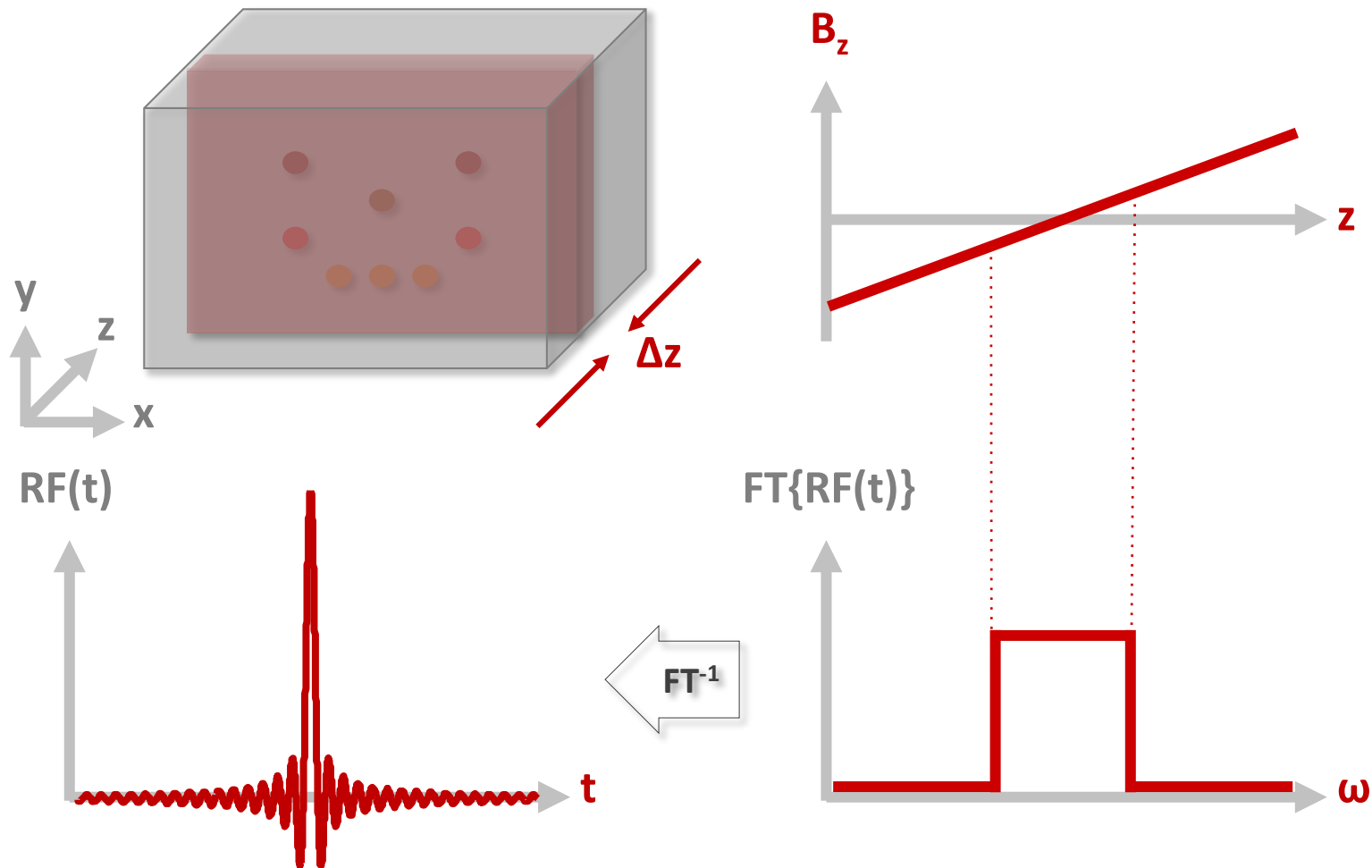
= Fourier Transform

Image reconstruction



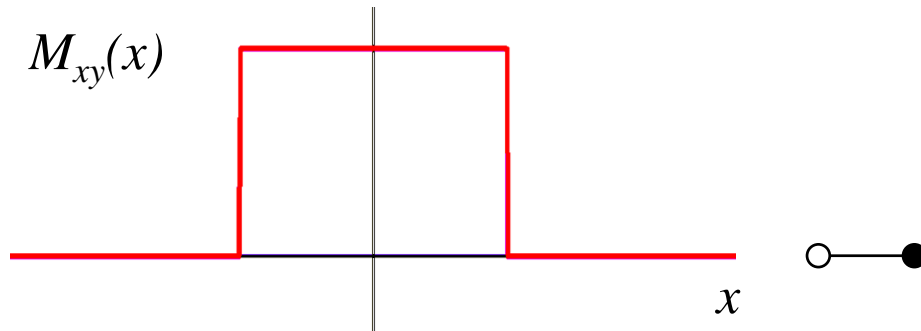
$$i(x_i, y_j) = \sum_p \sum_q s(k_{xp}, k_{yq}) e^{-j(k_{xp}x_i + k_{yq}y_j)}$$

= Inverse Fourier Transform

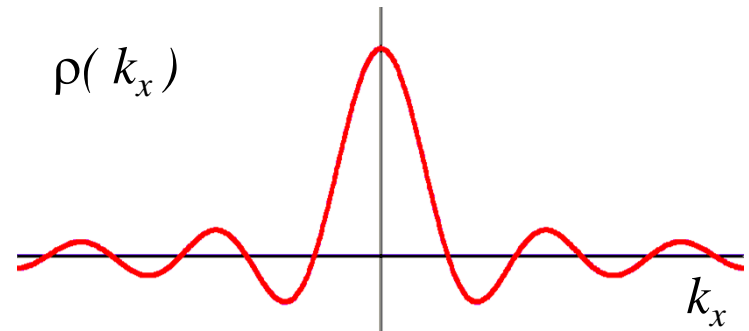


Slice Selection

Ideal slice profile: *Rectangle*

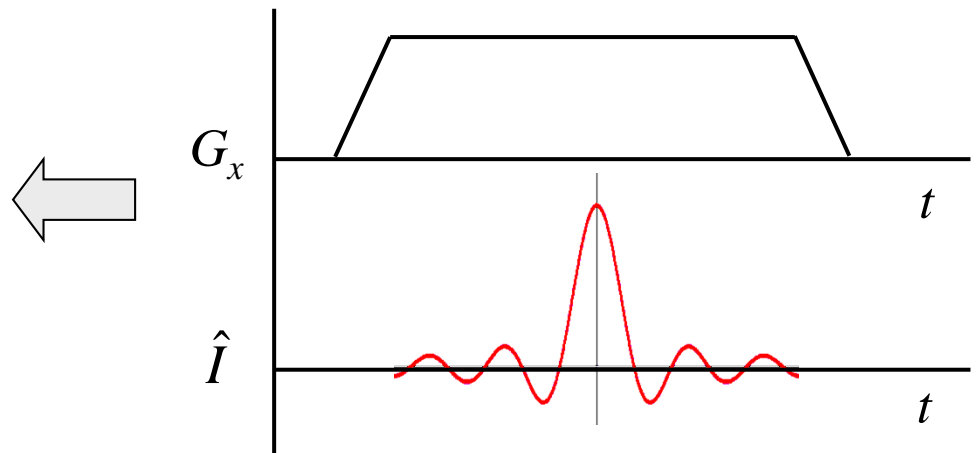


Ideal waveform: *Sinc*



$M_{xy}(x)$

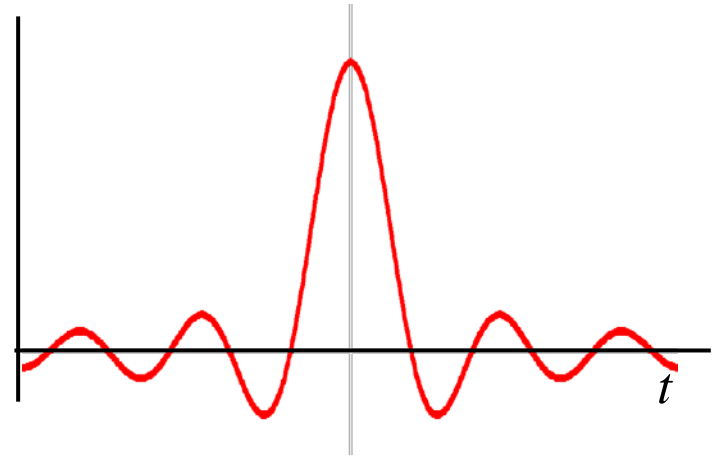
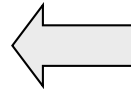
Implementation:



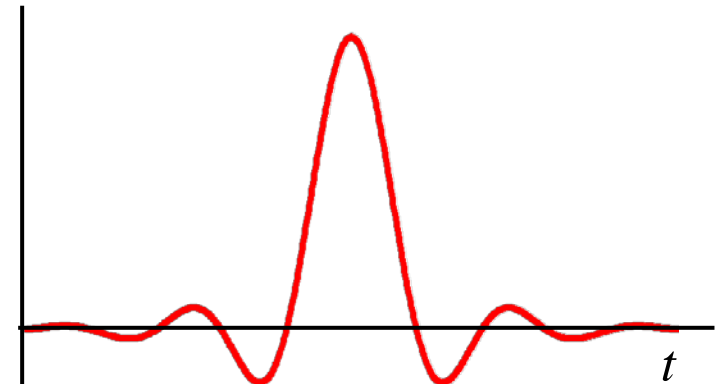
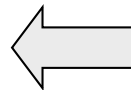
Slice Selection

$M_{xy}(x)$

Plain Sinc



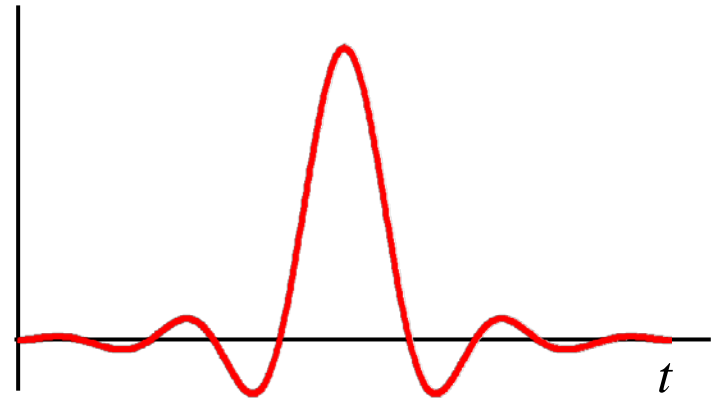
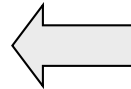
Sinc x Gauss



Slice Selection

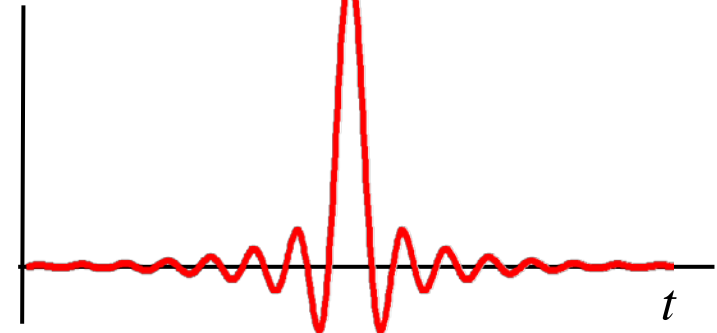
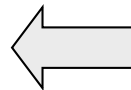
$M_{xy}(x)$

Sinc x Gauss

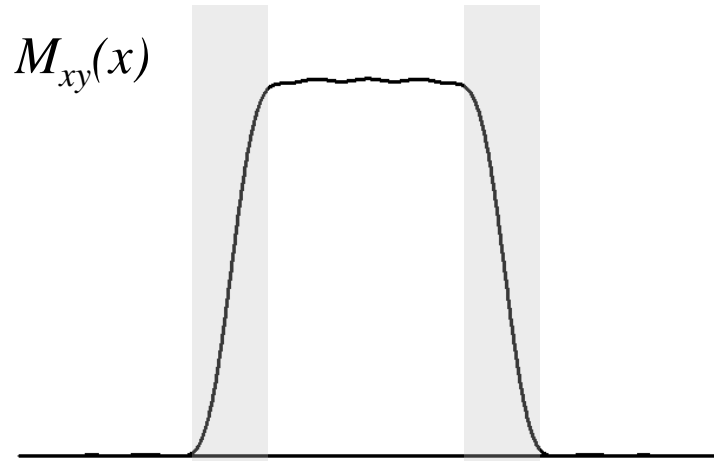


Sinc x Gauss

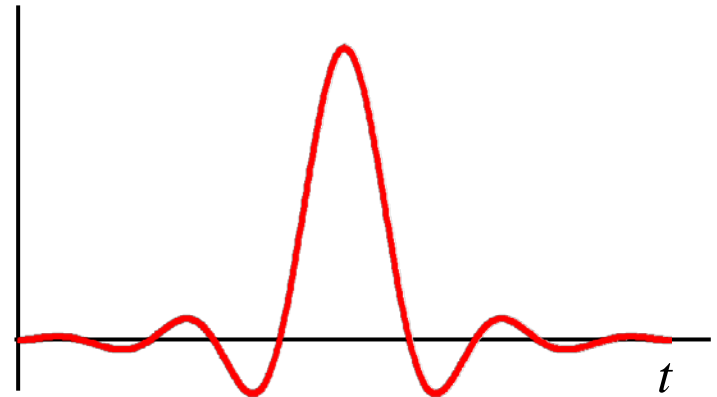
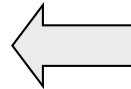
more
sidelobes



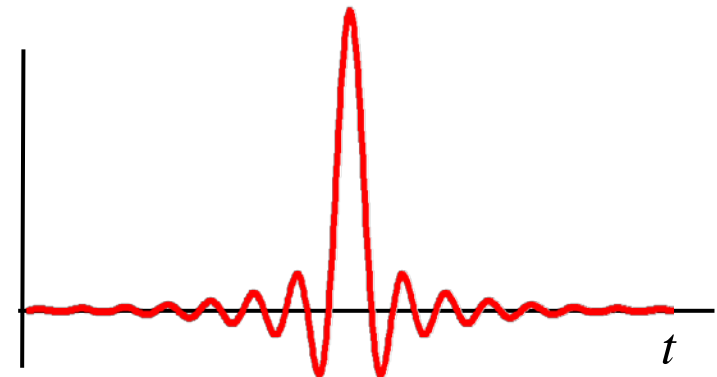
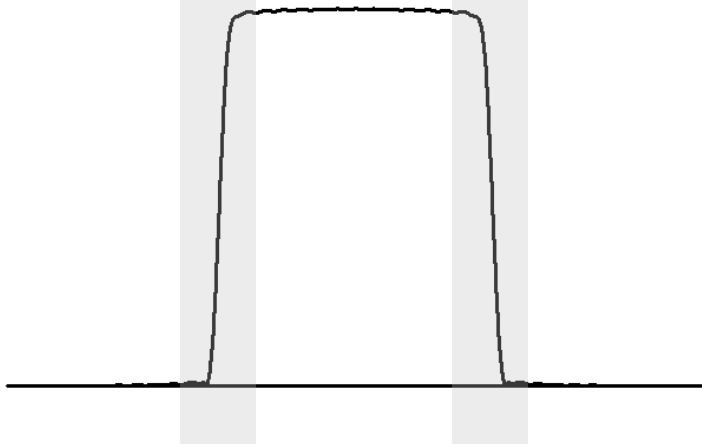
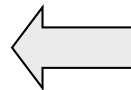
Slice Selection



Sinc x Gauss



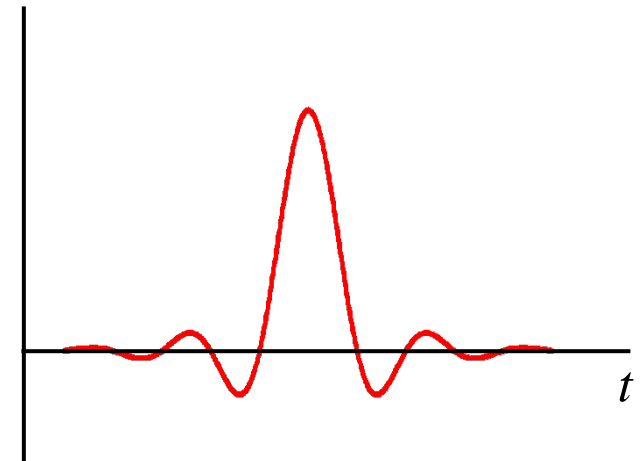
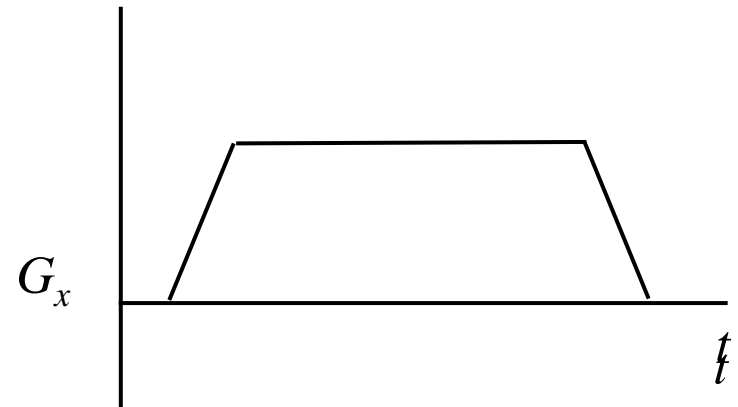
Sinc x Gauss
more
sidelobes



Slice Selection

Sinc x Gauss

— M_x — M_y — $|M_{xy}|$



Linear phase !

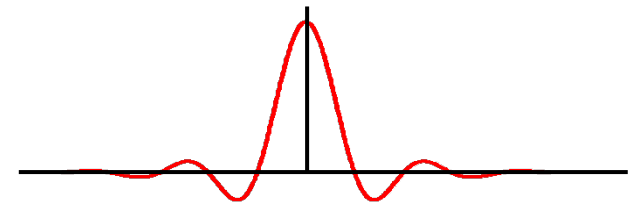
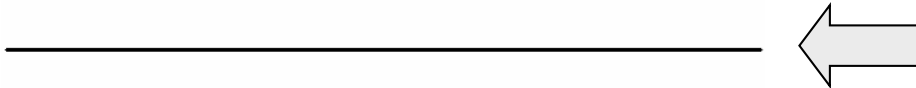
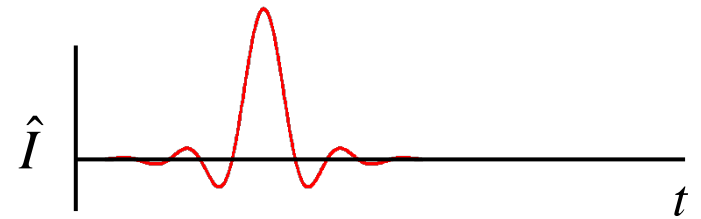
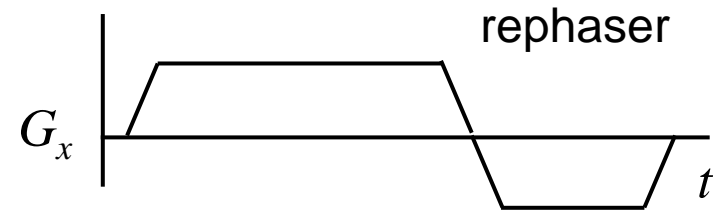


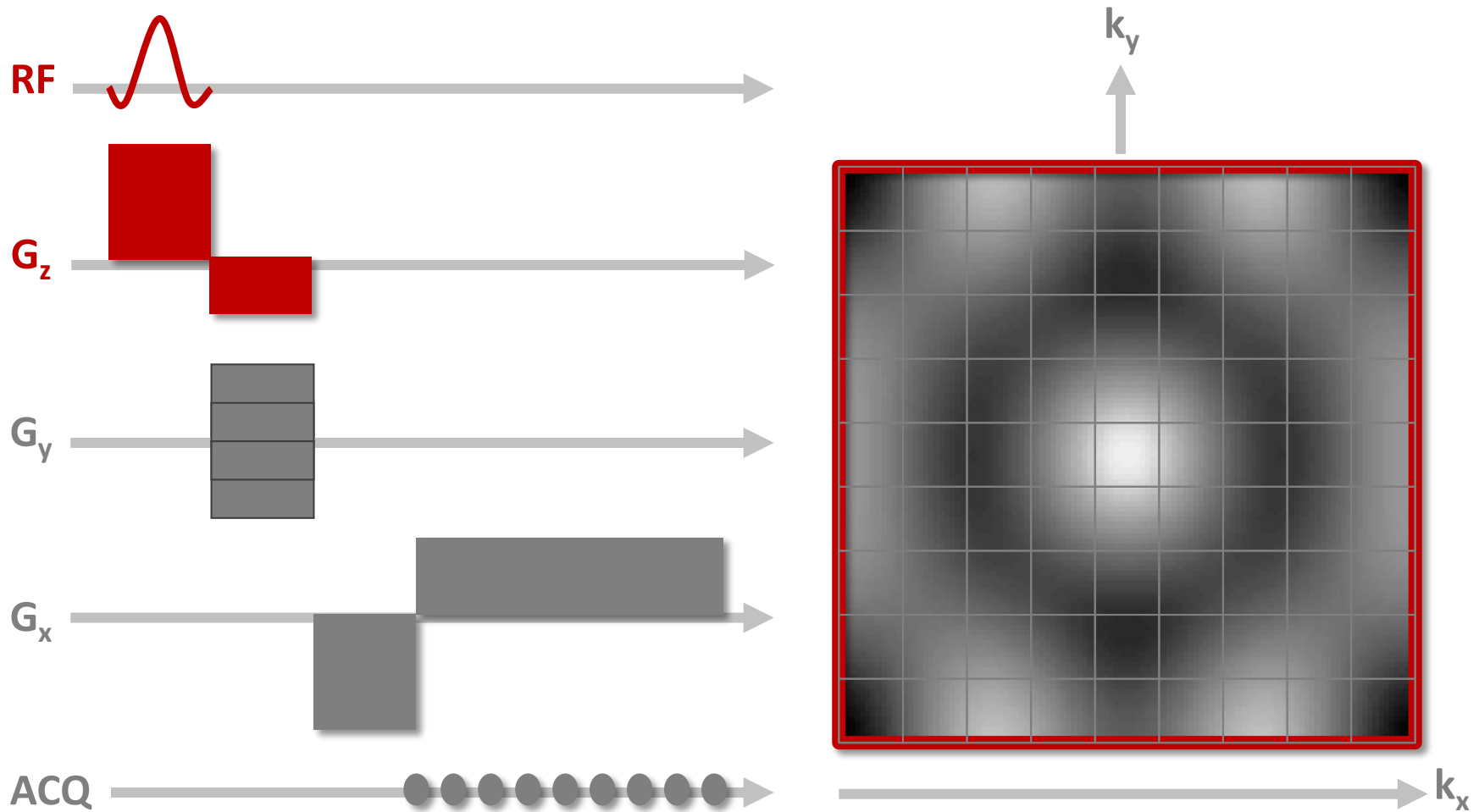
Shifted from center !

Fourier Pulse Design

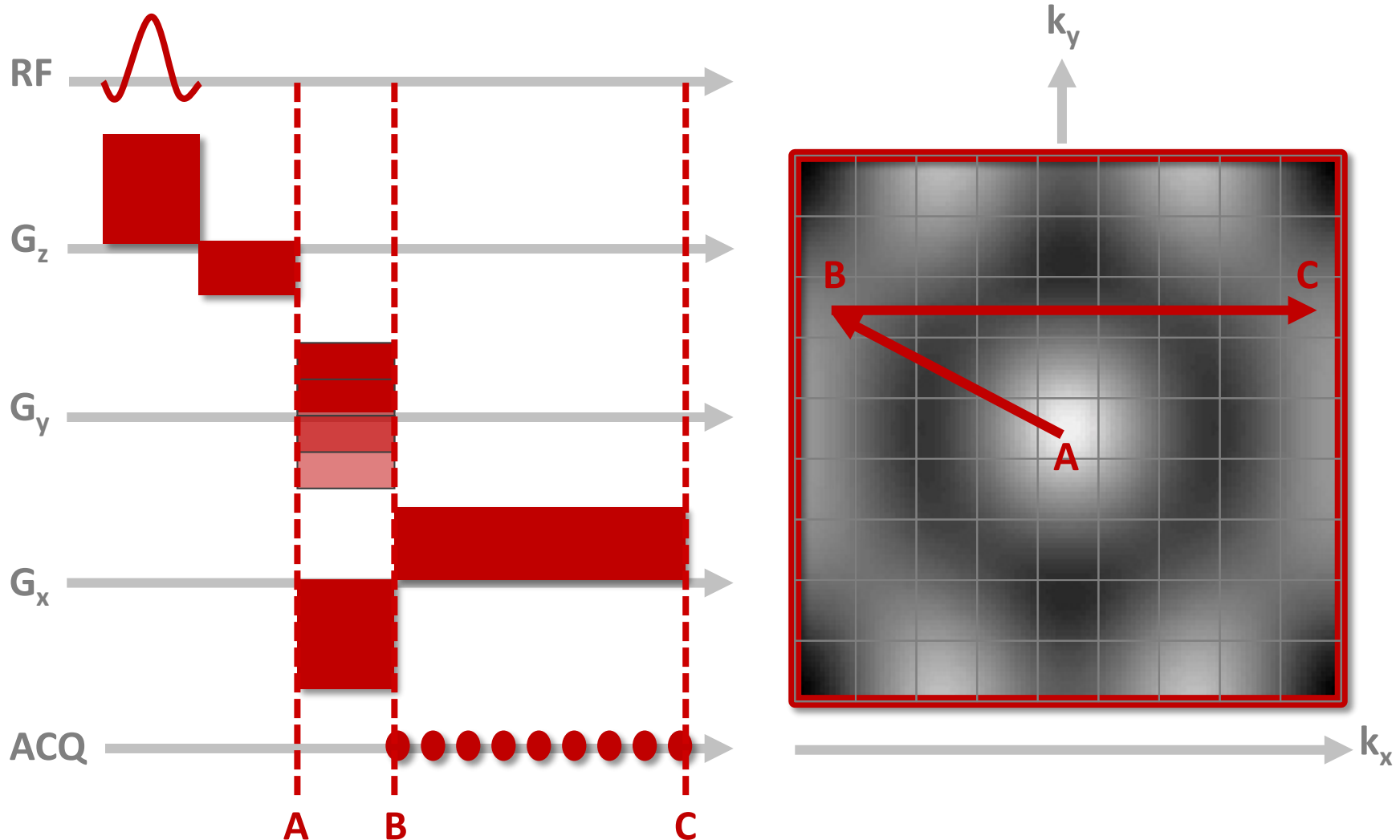
Sinc x Gauss

— M_x — M_y — $|M_{xy}|$

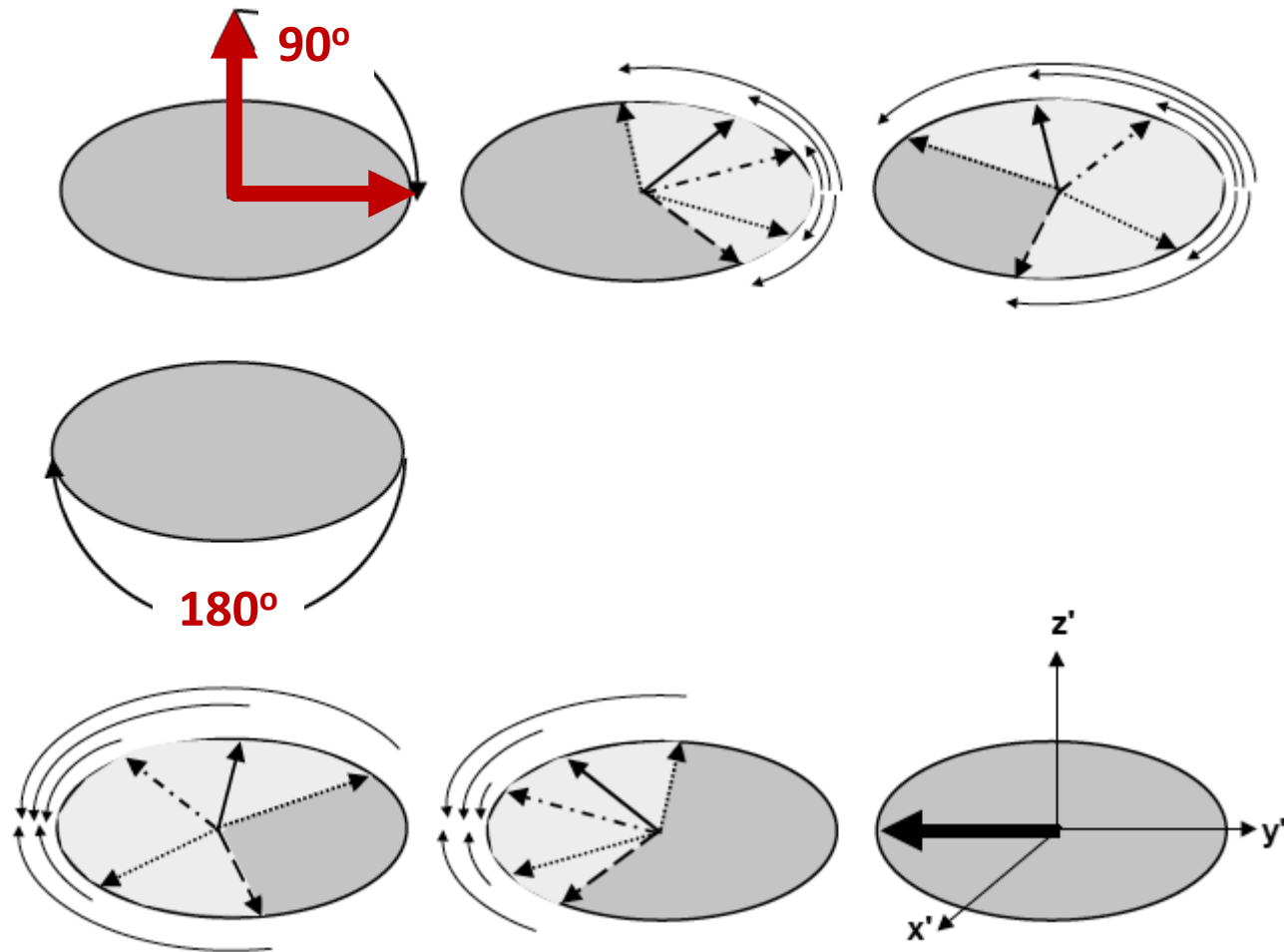




Gradient echo encoding experiment

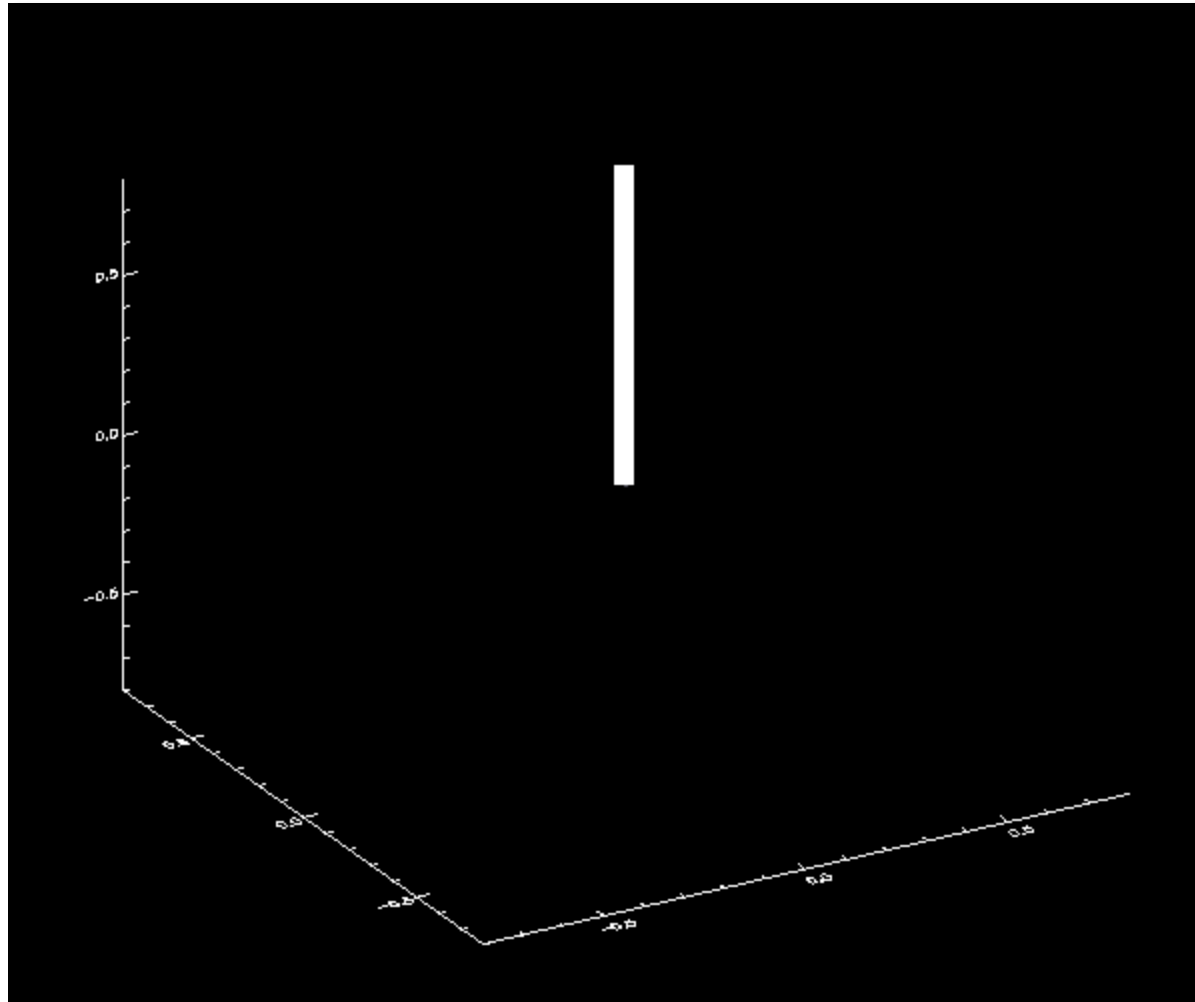


Microscopic B_0 variation and spin echos



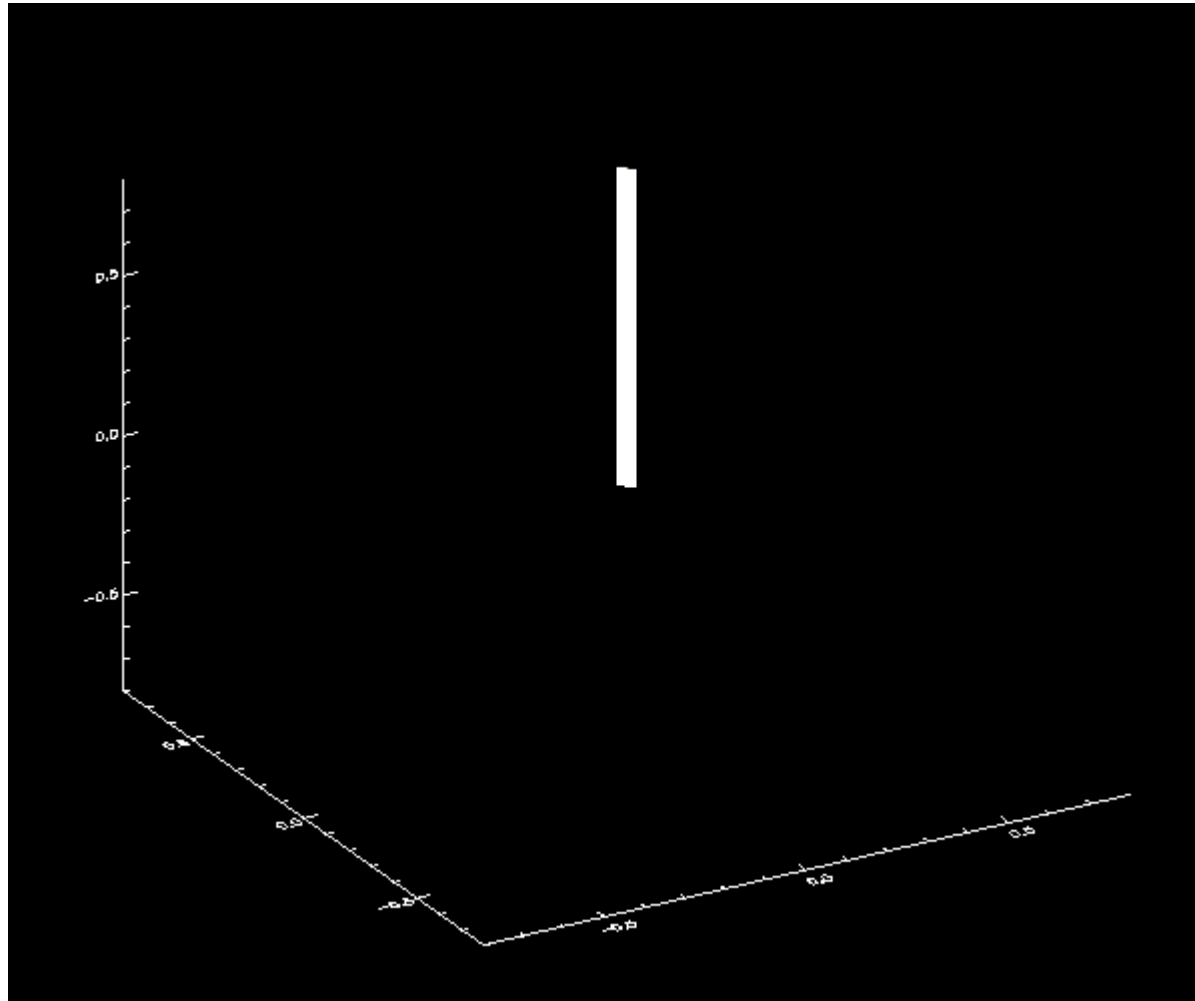
Spin echo formation

Ideal

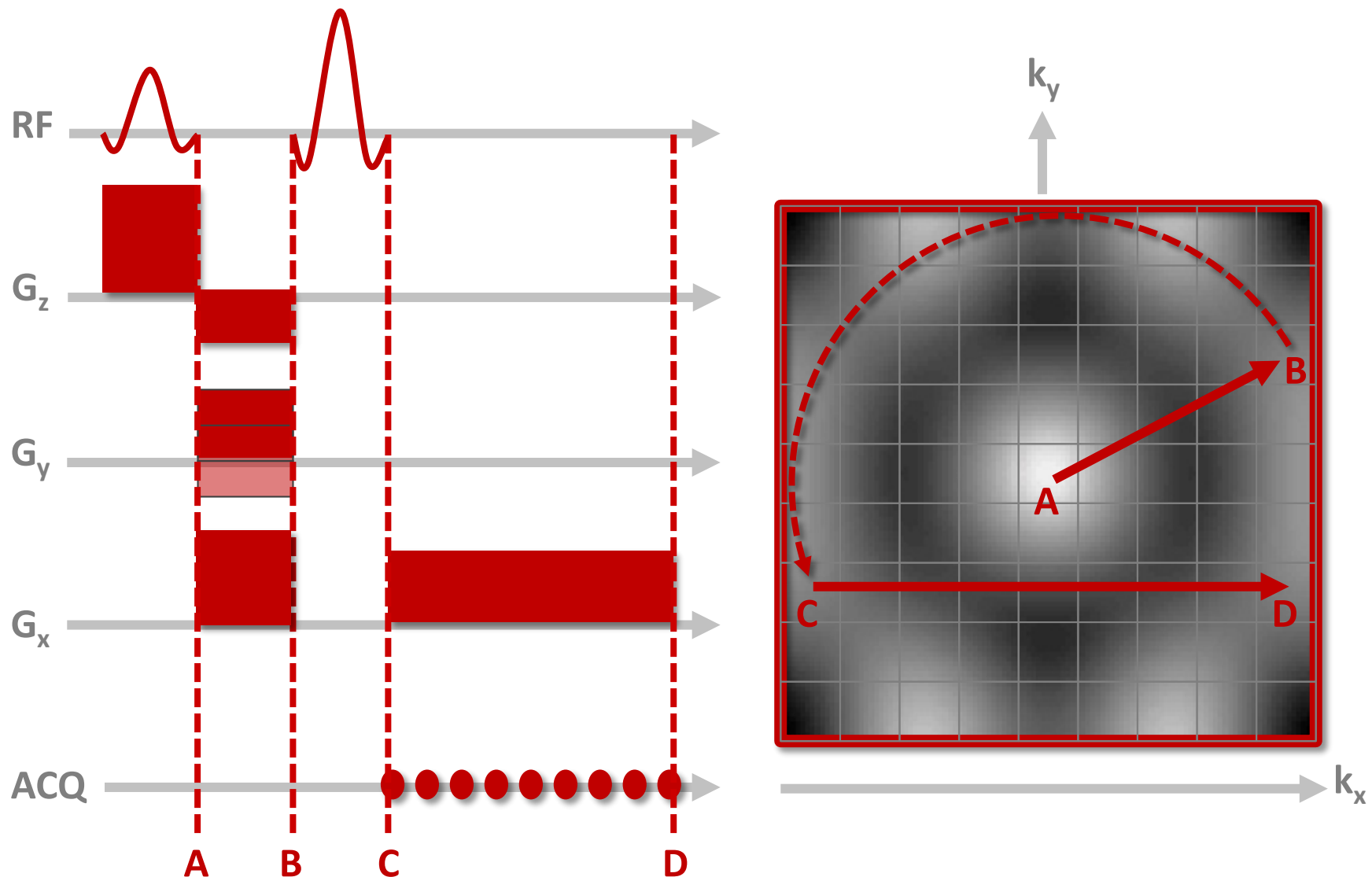


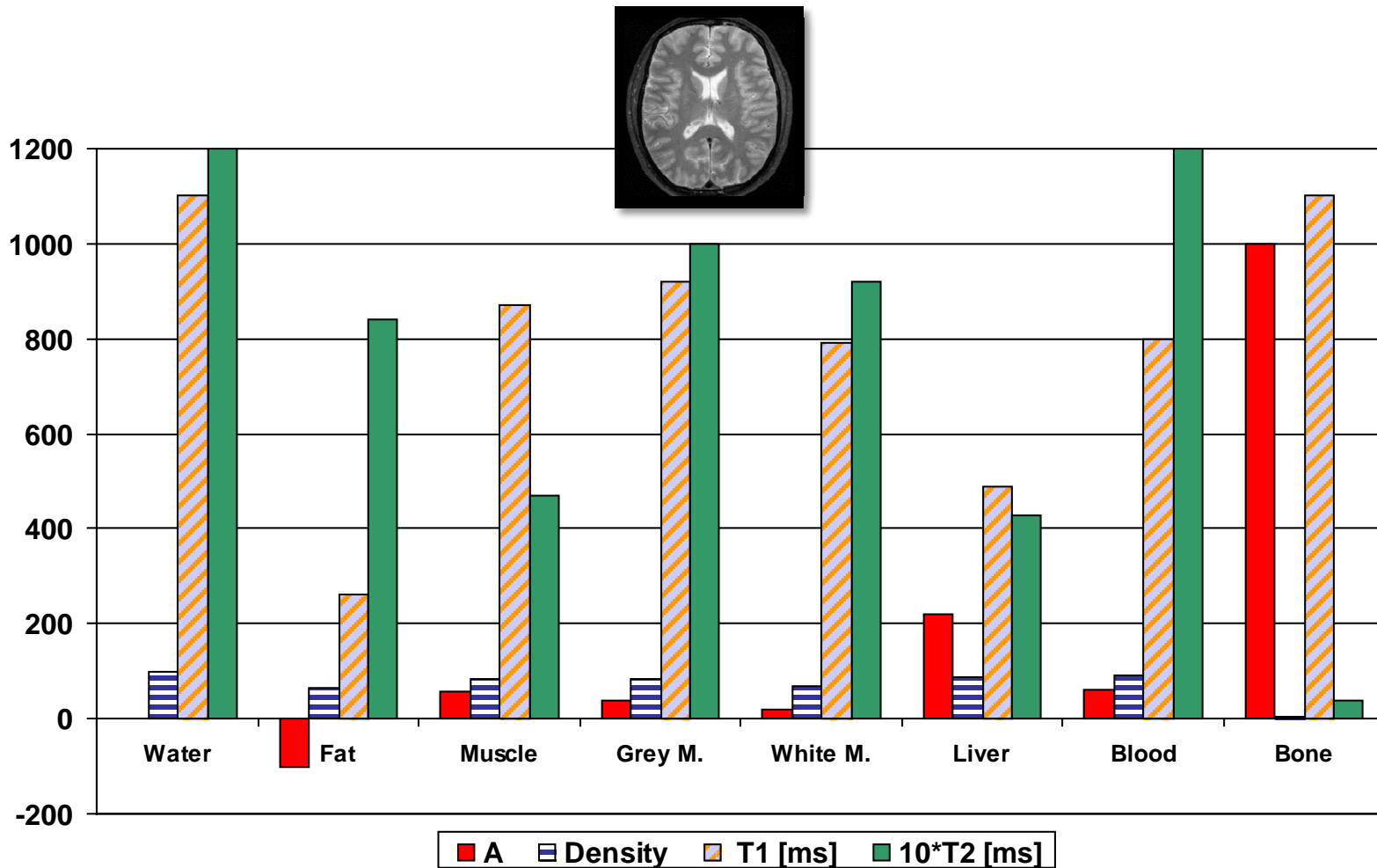
Spin echo formation

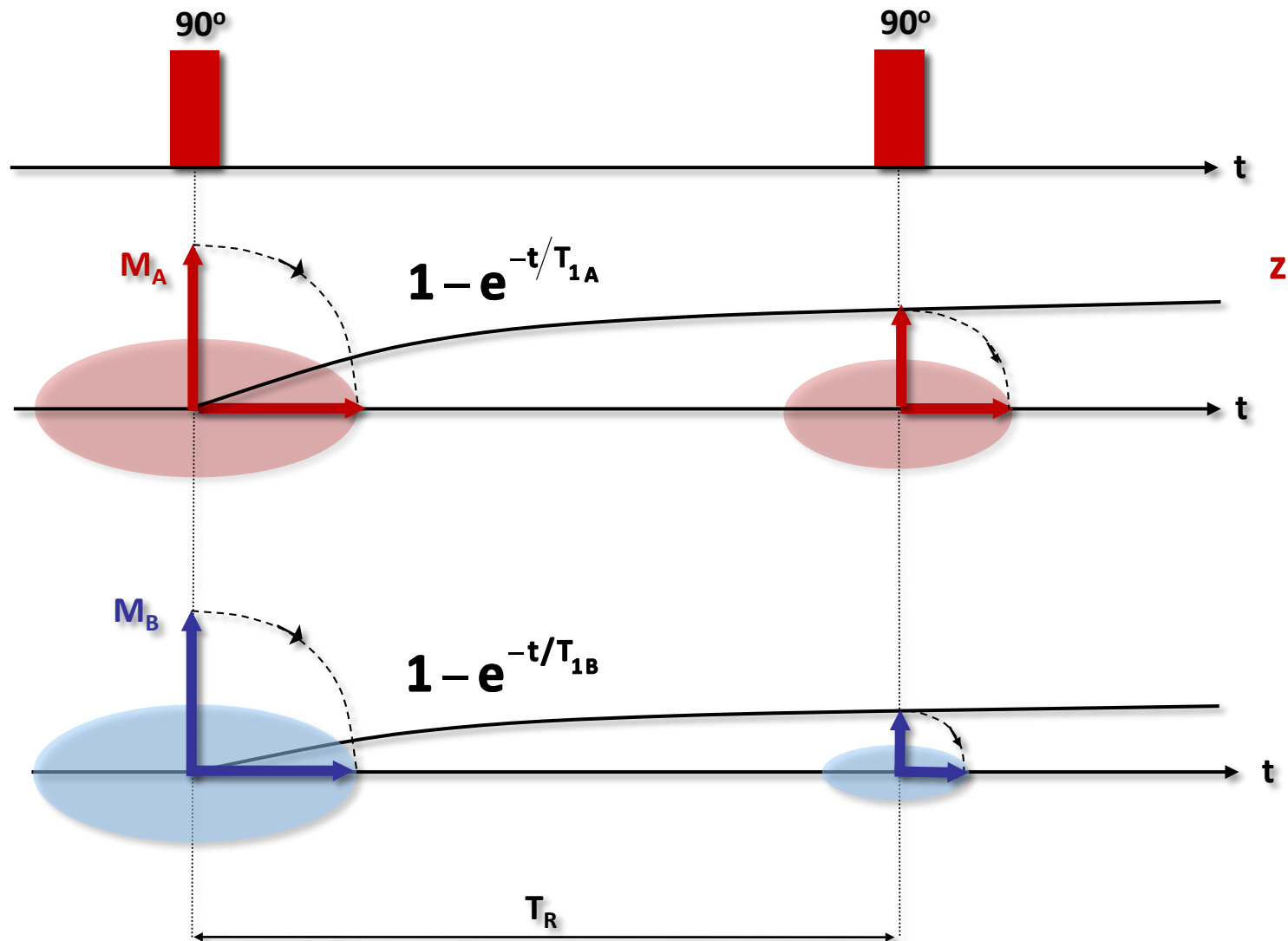
Real



Spin echo encoding experiment with slice selection

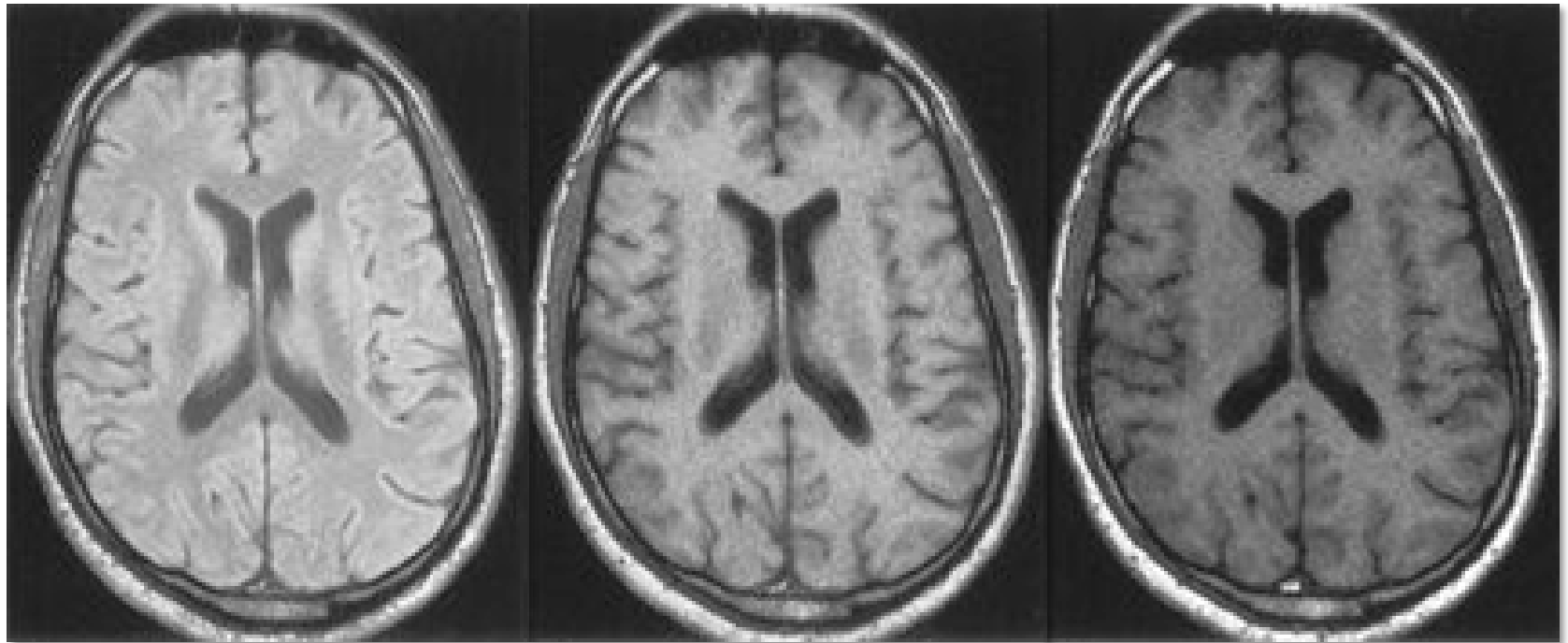






Density weighted

T_1 weighted

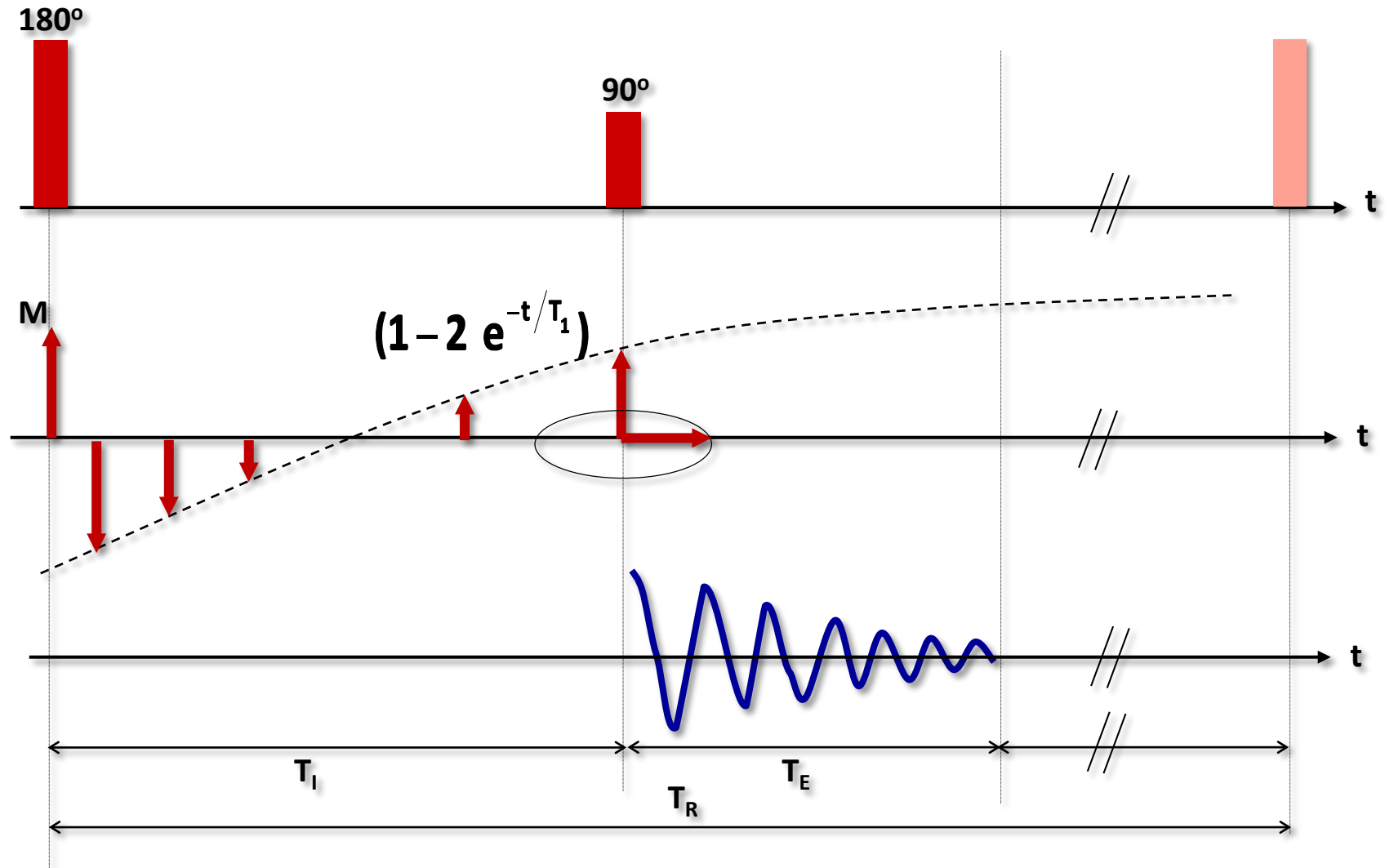


$T_{Rec} = 2000ms$

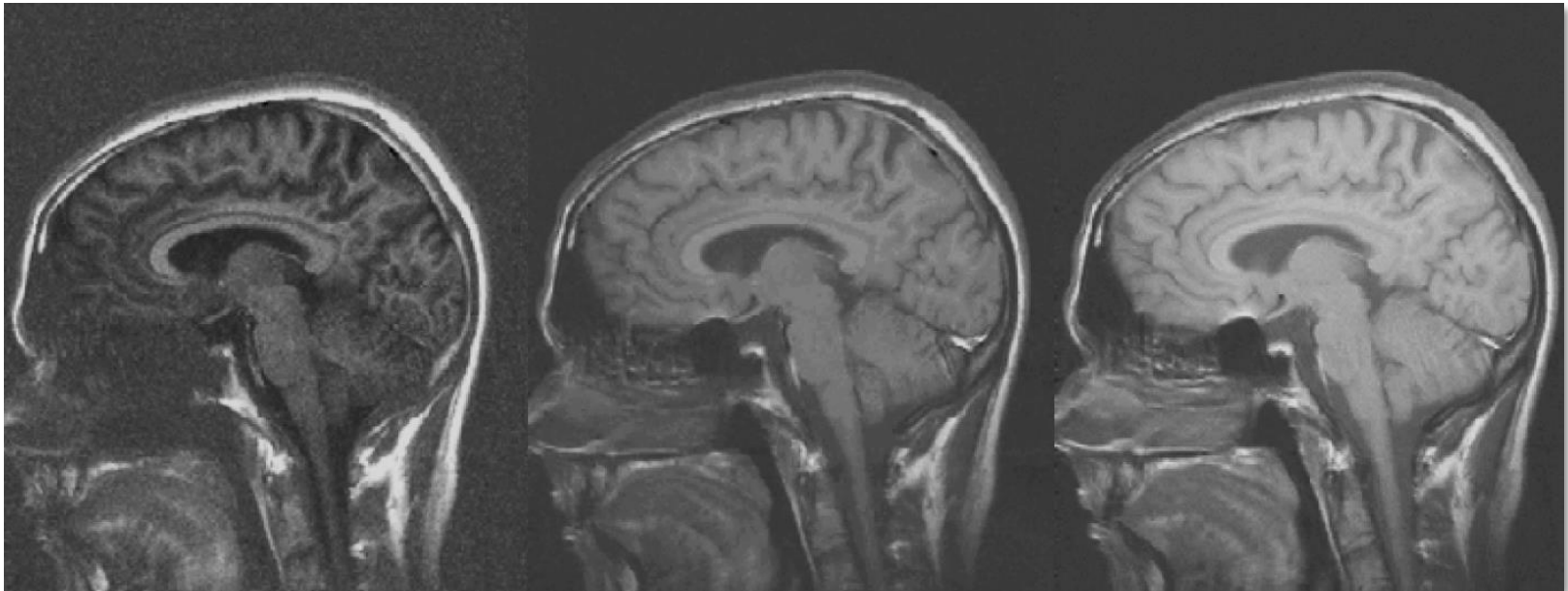
$T_{Rec} = 800ms$

$T_{Rec} = 400ms$

Inversion recovery method



Inversion recovery ($T_R=0.5, 1.5T$)

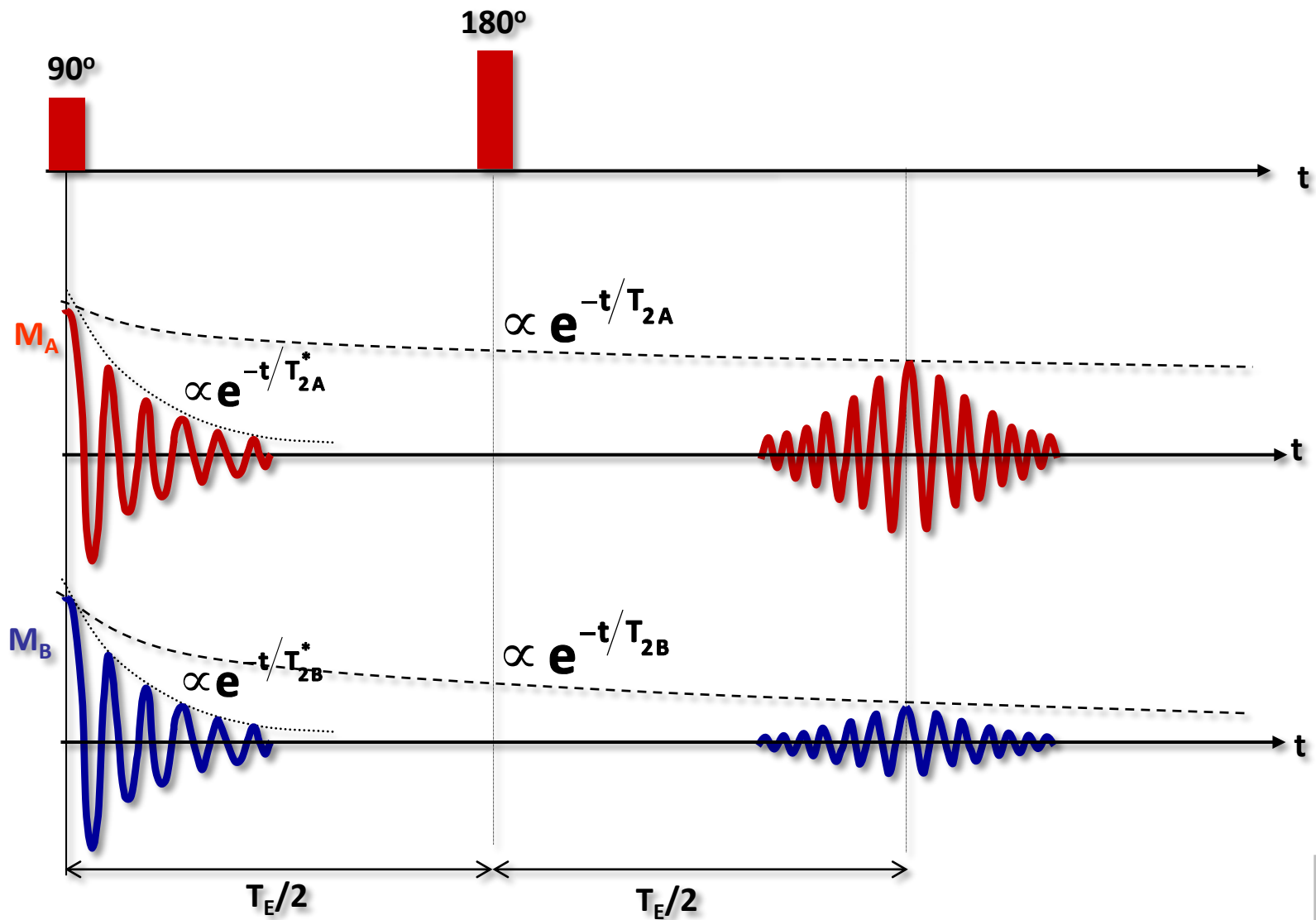


$T_1 = 200\text{ms}$

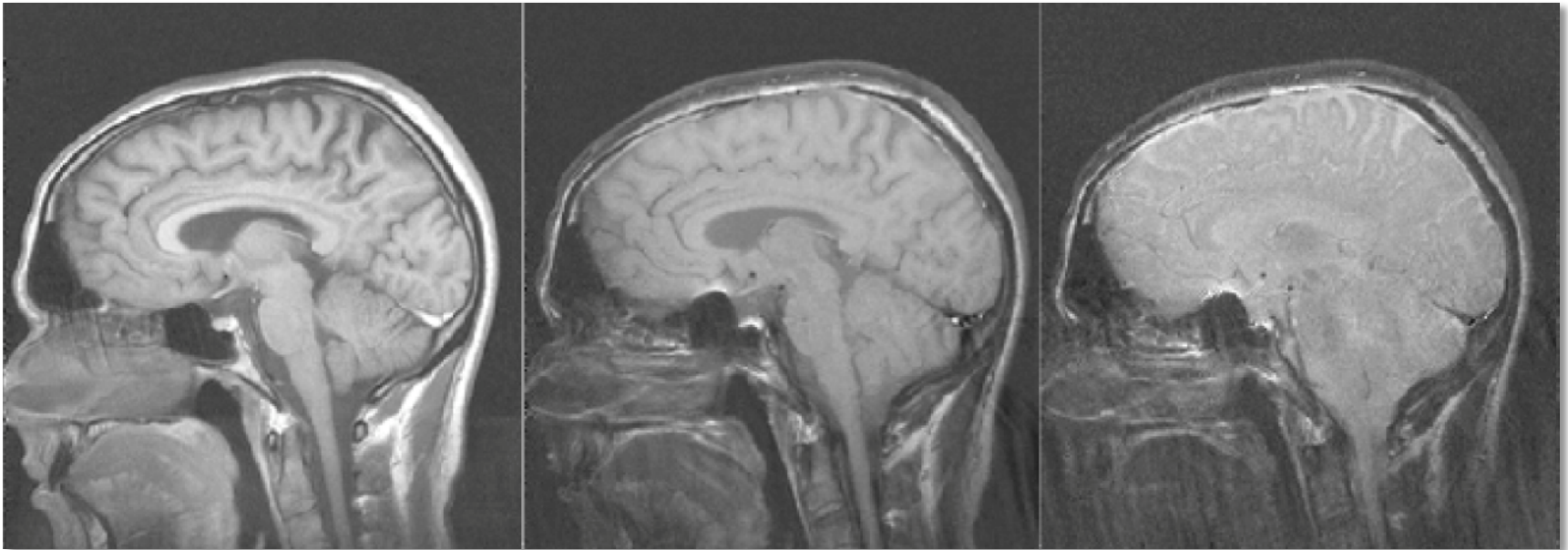
$T_1 = 300\text{ms}$

$T_1 = 400\text{ms}$

Spin-echo method



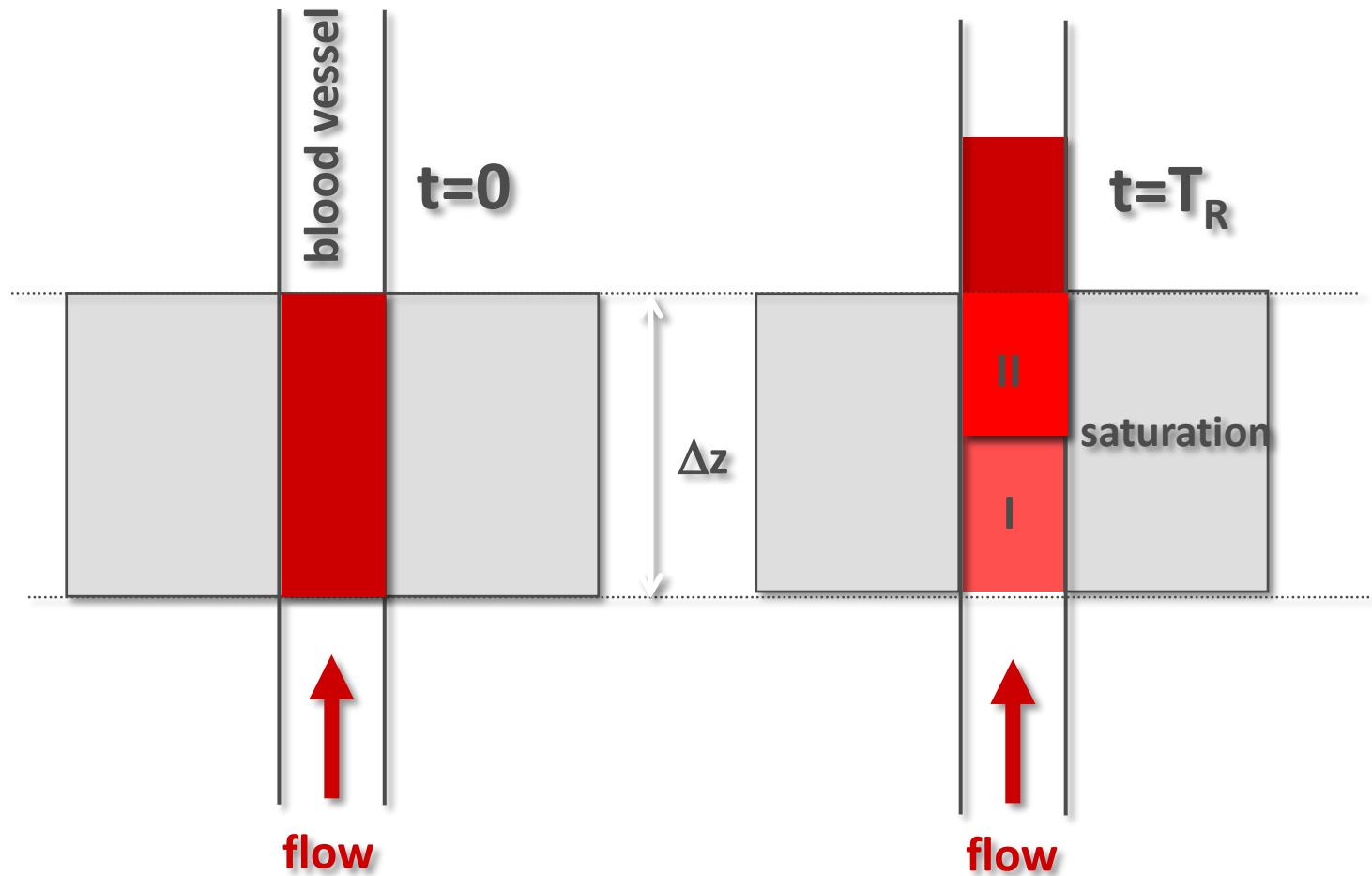
Spin-echo ($T_R=0.5, 1.5T$)



$T_E = 8ms$

$T_E = 50ms$

$T_E = 100ms$



Inflow contrast in brain

