

Practical Assignment № 1

Optimal Control



variant number: 6

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Finding the minima using static optimization

- 1. experimental values (Group 6)
- experimental values

№	J(x,u)	c(x,u)
6	$J(x,u) = 6x^2 + 2u^2 + 5xu - 3x - 2u - 12$	$4x^2 + u + 2$

- 2. Finding the global minimum J(x,u) based on necessary and sufficient conditions
- 2.1. without constraints
- analytical method

Organize J(x,y) into the following equation:

$$6x^2 + 2u^2 + 5xu - 3x - 2u - 12 - J = 0 (1)$$

The partial derivative of equation (1) gives:

$$\begin{cases}
12x + 5u - 3 - J_x' = 0 \\
4u + 5x - 2 - J_u' = 0
\end{cases}$$
(2)

 $_{\mathsf{let}}\,J'_x=0,J'_u=0$

$$\begin{cases} x=rac{2}{23} \ u=rac{9}{23} \end{cases}$$

Thus we can obtain the stationary point:

$$P:\left(rac{2}{23},rac{9}{23}
ight)$$
 $A=J_{xx}''|_p=12$ $B=J_{xu}''|_p=5$ $C=J_{uu}''|_p=4$ $B^2-AC=-23<0\Rightarrow ext{ Extreme values exist}$ $A=12>0\Rightarrow ext{ The extreme value is the minimal value}$

In summary, we can obtain the unconstrained extremum of the function as:

$$J_{min} = Jigg(rac{2}{23},rac{9}{23}igg)pprox J(0.0869,0.3913) = -rac{288}{23}pprox -12.5217$$

2.2. under equality constraint c(x, u) = 0

$$J_A(x) = J(x) + \lambda c(x)$$

 $= 6x^2 + 2u^2 + 5xu - 3x - 2u - 12 + \lambda (4x^2 + u + 2)$

$$\begin{bmatrix} 12x^* + 5u^* - 3 + 8\lambda^*x^* = 0 \\ 4u^* + 5x^* - 2 + \lambda^* = 0 \\ 4x^{*2} + u^* + 2 = 0 \end{bmatrix}$$

Solving the above equation we get:

$$(x^*, u^*, \lambda^*) pprox (0.1514, -2.0917, 9.6097) \ x^* pprox egin{bmatrix} 0.1514 \ -2.0917 \end{bmatrix}, J_{ ext{extreme}}(x^*) pprox -0.9664$$

Code

```
clear all
syms x u l
eq1 = 12*x+5*u-3+8*l*x == 0;
eq2 = 4*u+5*x-2+l == 0;
eq3 = 4*x^2 + u + 2 == 0;
[x,u,l] = solve(eq1,eq2,eq3,x,u,l)
x=vpa(x);u=vpa(u);l=vpa(l);
x=x(3);u=u(3);l=l(3);
J = 6*x^2+2*u^2 +5*x*u-3*x-2*u-12
```

2.3. under inequality constraint $c(x, u) \leq 0$

Calculate whether the unconstrained extremum obtained in 2.1 is consistent with the inequality:

$$\begin{split} J_{min} &= J\bigg(\frac{2}{23},\frac{9}{23}\bigg) \approx J(0.0869,0.3913) = -\frac{288}{23} \approx -12.5217 \\ c\bigg(\frac{2}{23},\frac{9}{23}\bigg) &= \frac{1281}{529} > 0 \qquad \text{Inequality constraints are not satisfied} \end{split}$$

By the **Kuhn-Tucker condition**: the extremum is **on the boundary**:

That is, the result in 2.2:

$$x^* pprox iggl[0.1514 \ -2.0917 iggr], J(x^*) pprox -0.9664$$

3. Gradient descent methods.

$$J_1(x,u) = J(x,u)$$

3.1. Using Newton-Raphson method (in optimization) find the extremum with step-by-step calculation.

$$J(x,u) = 6x^2 + 2u^2 + 5xu - 3x - 2u - 12$$

Let $X = \begin{bmatrix} x \\ u \end{bmatrix}$,we can get :

$$J(X) = rac{1}{2}X^TQX - X^Tb, Q = egin{bmatrix} 12 & 5 \ 5 & 4 \end{bmatrix}, b = egin{bmatrix} 3 \ 2 \end{bmatrix}$$

Newton (one step convergence):

The following formula was used for the calculation:

$$\left. x(k+1) = x(k) - H^{-1}(x)
ight|_{x=x(k)} grad^T \{J(x)\}
ight|_{x=x(k)}$$

Where:

$$\operatorname{grad}^T\{J(x)\} = Qx - b$$

calculation

Given any initial value:

$$\begin{split} x(0) &= \begin{bmatrix} 10 \\ 10 \end{bmatrix} \\ x_{\text{extreme}} &= x(1) = x(0) - Q^{-1} \operatorname{grad}_x \{J(x)\}\big|_{x(0)} \approx \begin{bmatrix} 0.0869 \\ 0.3931 \end{bmatrix} \end{split}$$

Code

```
%newton
clear all
x_0 =[10;10];Q = [12 5;5 4];b = [3;2];
x_extremum = x_0 - inv(Q)*grad(x_0,Q,b);
function g = grad(x,Q,b)
g = Q*x-b;
end
```

3.2. Using method of steepest descent (gradient descent method) for two different γ (corresponding to oscillation and aperiodic convergence) find the extrema with step-by-step calculation.

Use the same Q, b, and initial values as in 3.1

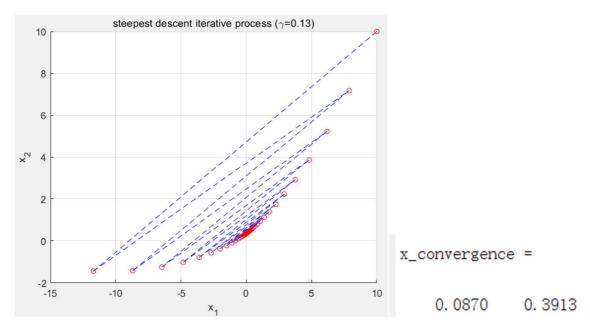
Iterate using the following formula:

$$x(k+1) = x(k) - \gamma \operatorname{grad}_x^T \{J(x)\} ig|_{x=x(k)}$$

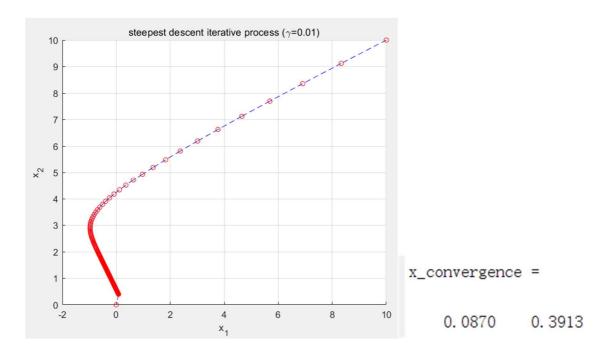
Where:

$$\operatorname{grad}^T\{J(x)\} = Qx - b$$

ullet $\gamma=0.13_{ ext{(OSCillation)}}$



ullet $\gamma=0.01$ (aperiodic convergence)



```
% draw process
xx = X(1,:);yy = X(2,:);x\_convergence = [xx(convergence\_step-
1) ,yy(convergence_step-1)]
figure
for i = 1: length(xx)-1
    hold on
plot([xx(i),xx(i+1)],[yy(i),yy(i+1)],'Color','b','LineStyle','--
');
end
hold on
plot(xx,yy,'LineStyle','none','Marker','o','MarkerSize',5,'Color'
,'r');
hold on
grid on
function g = grad(x,Q,b)
g = Q*x-b;
end
```