

2. 解: (1) 状态空间 $S = \{X_n = -2, X_n = -1, X_n = 0, X_n = 1, X_n = 2\}$

状态转移矩阵:

$$\begin{array}{c} -2 \\ -1 \\ 0 \\ 1 \\ 2 \end{array} \begin{bmatrix} -2 & -1 & 0 & 1 & 2 \\ 1 & 0 & 0 & 0 & 0 \\ q & r & p & 0 & 0 \\ 0 & q & r & p & 0 \\ 0 & 0 & q & r & p \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

(2) 设在甲积1分的情况下, 再赛两局可以结束

$$S_1 = [0 \ 0 \ 0 \ 1 \ 0]^T$$

$$\text{下一局: } S_{1n} = P^1 S_1 = [0 \ 0 \ q \ r \ p]^T$$

$$\text{经过两局: } S_{1+2} = P^2 S_{1n} = [0 \ q^2 \ qr \ r+p \ p+pr]^T$$

故再赛两局可以结束比赛的概率为 $p+pr-p=pr$
(刚好两局)

3. 解: $G_t = R_{t+1} + rR_{t+2} + \dots = \sum_{k=0}^{\infty} r^k R_{t+1+k}$

$$\text{则 } G_0 = \lim_{k \rightarrow \infty} R_1 + rR_2 + r^2R_3 + \dots + r^k R_{k+1}$$

$$= \lim_{k \rightarrow \infty} (6 + 6r + 6r^2 + \dots + 6r^k) - 4$$

$$= \lim_{k \rightarrow \infty} \frac{6(r^{k+1} - 1)}{r - 1} - 4$$

$$= 6 \times \frac{0 - 1}{0.9 - 1} - 4$$

$$= 56$$

$$\text{则 } G_1 = \lim_{k \rightarrow \infty} R_2 + rR_3 + \dots + r^k R_{k+2}$$

$$= 6 \times \lim_{k \rightarrow \infty} (1 + r + \dots + r^k)$$

$$= \lim_{k \rightarrow \infty} \frac{6(r^{k+1} - 1)}{r - 1}$$

$$= 60$$

4. 解:

① 认为 $R_t = -1$ 对所有行动状态成立. 即 $1 \rightarrow 1$ 与 $R_t = -1$ 也成立

$$q_{\pi}(4, \text{left}) = r_4^{\text{left}} + \sum_{s \in S} p_{4s}^{\text{left}} v_{\pi}(s) = -1 + v_{\pi}(3)$$

对于状态值函数:

$v_{\pi}(1), v_{\pi}(5), v_{\pi}(3), v_{\pi}(7)$ 具有如下相同形式:

$$v_{\pi}(1) = -\frac{1}{4} + \frac{v_{\pi}(1)-1}{4} + \frac{v_{\pi}(2)-1}{4} + \frac{v_{\pi}(4)-1}{4}$$

$v_{\pi}(2), v_{\pi}(6)$ 具有如下相同形式:

$$v_{\pi}(2) = \frac{v_{\pi}(2)-1}{2} + \frac{v_{\pi}(3)-1}{4} + \frac{v_{\pi}(1)-1}{4}$$

$v_{\pi}(4)$ 具有如下形式:

$$v_{\pi}(4) = \frac{v_{\pi}(1)-1}{4} + \frac{v_{\pi}(5)-1}{4} + \frac{v_{\pi}(3)-1}{4} + \frac{v_{\pi}(7)-1}{4}$$

$$\text{得: } v_{\pi}(1) = v_{\pi}(5) = v_{\pi}(3) = v_{\pi}(7) = -7$$

$$v_{\pi}(2) = v_{\pi}(6) = -9$$

$$v_{\pi}(4) = -8$$

$$\text{所以 } q_{\pi}(4, \text{left}) = -1 + (-7) = -8$$

$$q_{\pi}(7, \text{right}) = r_7^{\text{right}} = -1$$

② 认为 $R_t = -1$ 只在状态发生转移时成立. 做动作但状态不变认为 $R_t = 0$ ex: 1/1 到 1 R_t 认为 0)

$$q_{\pi}(4, \text{left}) = r_4^{\text{left}} + \sum_{s \in S} p_{4s}^{\text{left}} v_{\pi}(s) = -1 + v_{\pi}(3)$$

对于状态值值函数:

$v_{\pi}(1), v_{\pi}(5), v_{\pi}(3), v_{\pi}(7)$ 具有如下相同形式:

$$v_{\pi}(1) = -\frac{1}{4} + \frac{v_{\pi}(1)}{4} + \frac{v_{\pi}(2)-1}{4} + \frac{v_{\pi}(7)-1}{4}$$

$v_{\pi}(2), v_{\pi}(6)$ 具有如下相同形式:

$$v_{\pi}(2) = \frac{v_{\pi}(2)}{2} + \frac{v_{\pi}(3)-1}{4} + \frac{v_{\pi}(1)-1}{4}$$

$v_{\pi}(4)$ 具有如下形式:

$$v_{\pi}(4) = \frac{v_{\pi}(1)-1}{4} + \frac{v_{\pi}(5)-1}{4} + \frac{v_{\pi}(3)-1}{4} + \frac{v_{\pi}(7)-1}{4}$$

$$\text{得: } v_{\pi}(1) = v_{\pi}(5) = v_{\pi}(3) = v_{\pi}(7) = -5$$

$$v_{\pi}(2) = v_{\pi}(4) = v_{\pi}(6) = -6$$

$$\text{则 } q_{\pi}(4, \text{left}) = -1 + (-5) = -6$$

$$q_{\pi}(7, \text{right}) = r_7^{\text{right}} = -1$$