

# Group Members Intro

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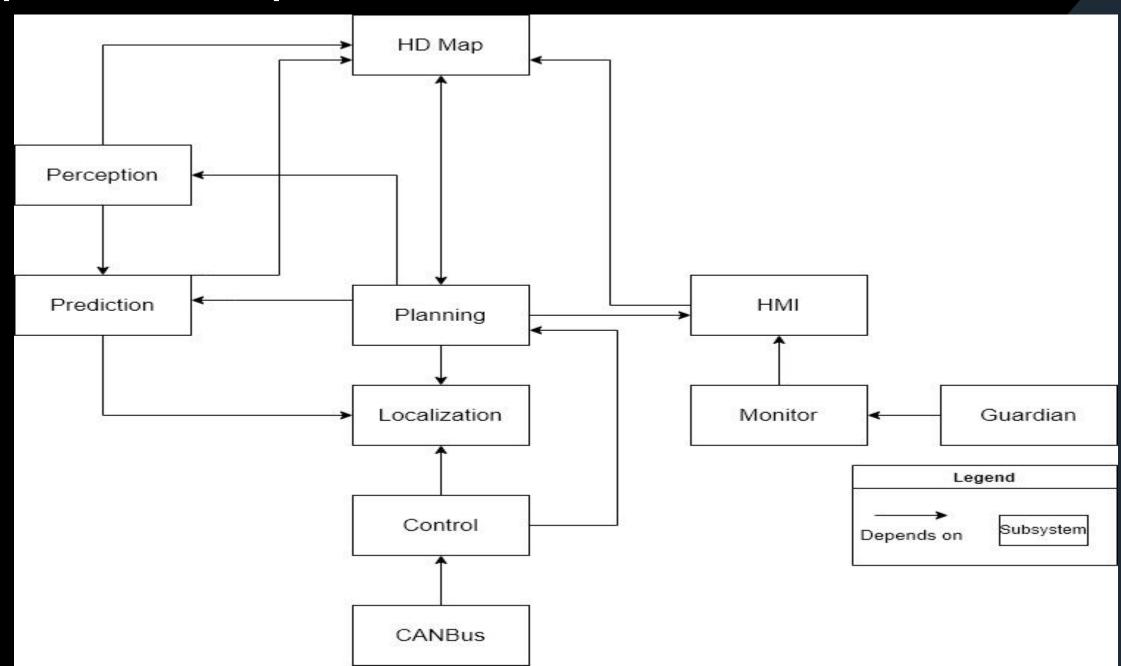
Baisheng Zhang 20094496

### **Derivation Process**

- Update Conceptual Architecture
- Use Understand



#### Updated Conceptual Architecture

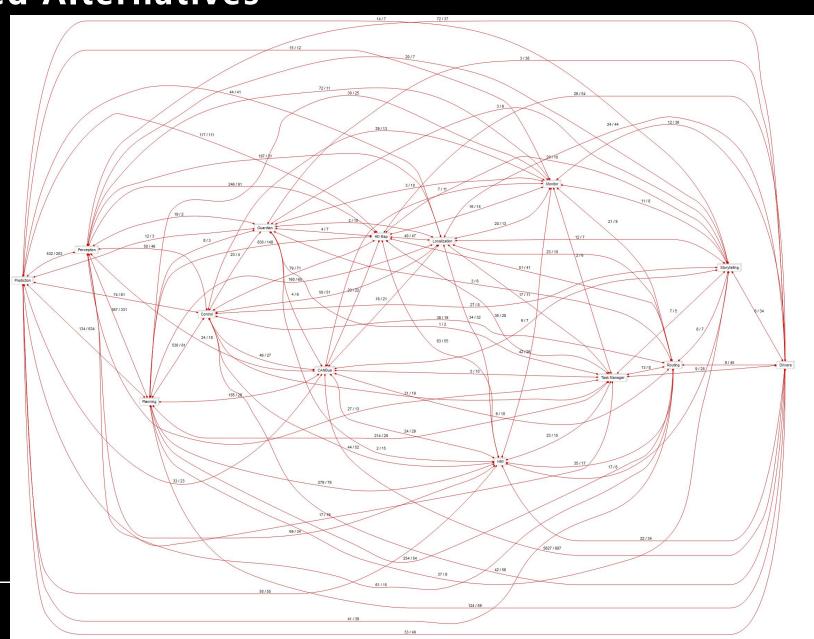


### **Derivation Process**

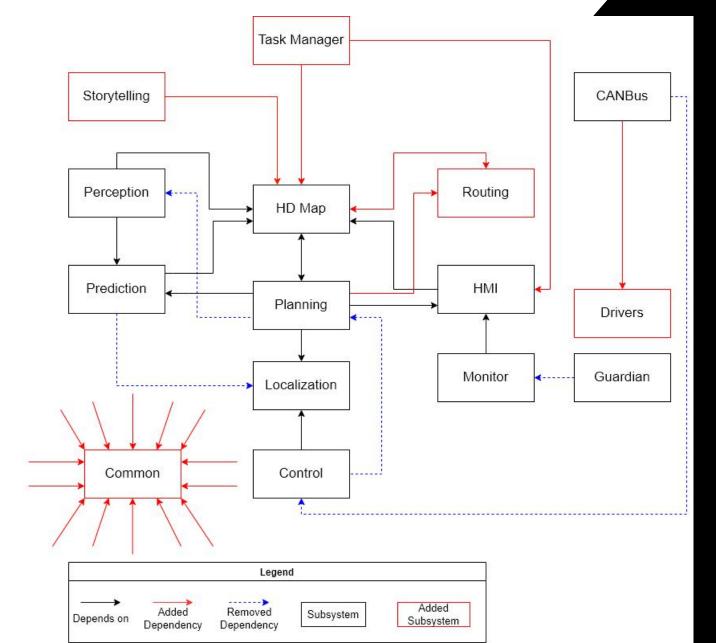
- Update Conceptual Architecture
- Use Understand



#### **Considered Alternatives**



#### **Concrete Architecture**



### Divergences at High Level

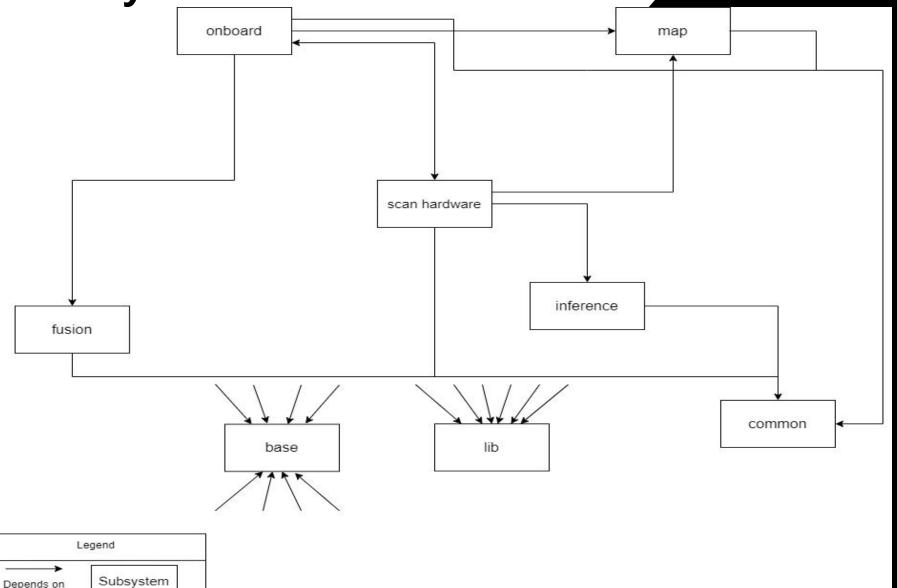
#### Added Dependencies:

- CANBus => Drivers
- TaskManager => HMI
- TaskManager => HD Map
- Everything else => Common
- Storytelling => HD Map
- HD Map <=> Routing
- Planning => Routing

#### Removed Dependencies:

- Planning = > Perception
- Prediction = > Localization
- Control=>Planning
- Guardian = > Monitor
- CANBus=>Control

Conceptual Architecture of 2nd level subsystem



**Concrete Architecture of** 2nd level subsystem onboard map radar camera fusion inference lidar common lib base Legend Added Added Subsystem Depends on Subsystem Dependency

#### Divergences at 2nd Level

#### Added Dependencies:

Onboard => Rader

Rader => Common

Onboard => Lidar

Lidar => Onboard

Lidar => Common

Lidar => Map

Lidar => Inference

Onboard => Camera

Camera => Inference

Camera => Common

#### Removed Dependencies:

Scan Hardware => Onboard

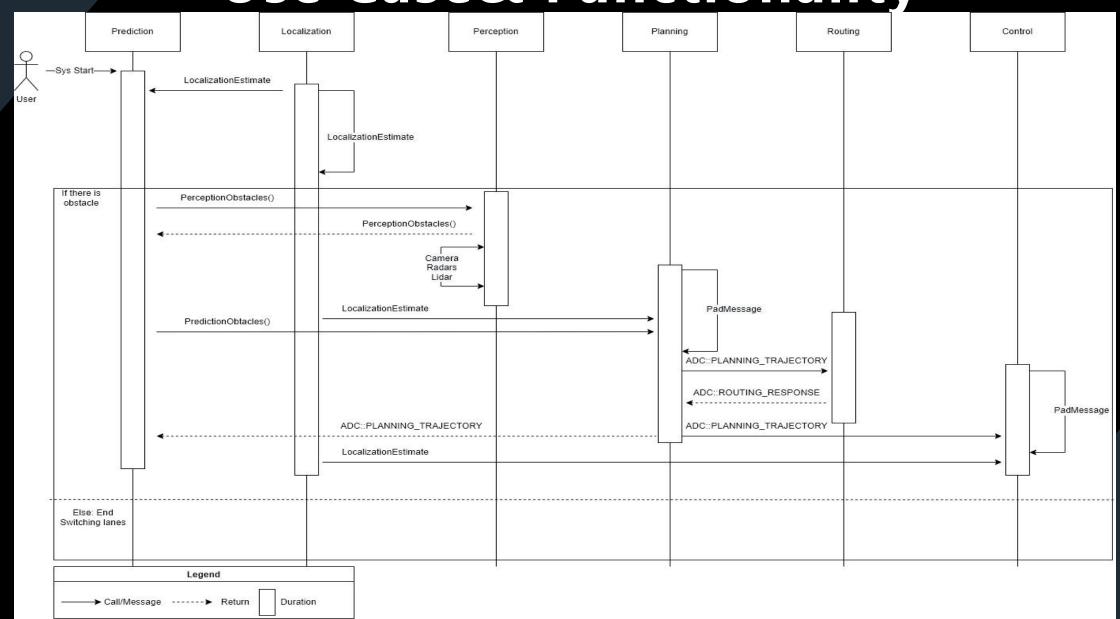
Onboard => Scan Hardware

Scan Hardware => Map

Scan Hardware => Inference

Scan Hardware => Common

**Use Case& Functionality** 



## Concurrency

- Apollo has a particular scheduling system to meet real-time performance needs;
- Apollo's action mode comes from multiple interacting processes;
- Concurrency occurs in the Apollo perception module responsible for checking obstacles around the car, consisting of 5 nodes (LiDAR, Radar, Fusion, Traffic Light preprocessing and Traffic Light process);
- Each node can be regarded as a thread;

### Team Issues

- Apollo's subsystems are very numerous and complex;
- The content of the ReadMe document of some modules is not straightforward.
- Later maintenance will be challenging.

### Lessons Learned

 We understood why conceptual architecture and concrete architecture do not match;

• The most important thing is that we learned how to use Understand to analyze the dependencies between modules;

• We also learned a deep understanding of the importance of teams.

# Limitations of Reported Findings

- Firstly, SciTools Understand is complex software. Using it to analyze the dependencies between modules always takes us much time;
- Secondly, when we analyzed the concrete architecture of Apollo, we discovered that the module 'Task Manager' was not completed. Since Task Manager is a new system of Apollo 7.0, it is still in the development stage, so many functions are not finalized.

# CONCLUSION

# THANK YOU!

