

# Xuan Liu

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## Research Interests

AI4Engineer(Signal Processing, Robotics), Transfer Learning, Diffusion Model, AI4Science

## Education

**Xi'an Jiaotong University**      Supervisor: **Prof. Jinglong Chen**      **Xi'an, Shaanxi, China**

M.S. in Mechanical Engineering; Avg. Score: 86.06

Sept. 2021 - Jun. 2024(Expected)

**Xi'an Jiaotong University**

**Xi'an, Shaanxi, China**

B.E. in Mechanical Engineering; Avg. Score: 87.15 (Top10%)

Sept. 2017 - Jun. 2021

2nd B.E. in Computer Science and Technology; Co-trained by XJTU and CAS

Jul. 2019 - Jun. 2021

## Publications

**X. Liu\***, Z. Li\*, J. Chen, K. Zhang "Intelligent Fault Diagnosis for imbalanced multiple working conditions via Dynamic Unsupervised Domain Adaptation with Sample and Margin Regularization". *Measurement (Under Review)*.

**X. Liu**, J. Chen, K. Zhang, S. Liu, S. He, Z. Zhou "Cross-domain intelligent bearing fault diagnosis under class imbalanced samples via transfer residual network augmented with explicit weight self-assignment strategy based on meta data". *Knowledge-Based Systems*, June 2022. [\[paper\]](#)

Z. Shi, **X. Liu**, J. Chen, Y. Zi, Z. Zhou "A multi-branch redundant adversarial net for intelligent fault diagnosis of multiple components under drastically variable speeds". *ISA transactions*, Jan 2022. [\[paper\]](#)

## Research Experience

**High-quality Vibration Signals Generatation via Diffusion Model**

**Xi'an, Shaanxi**

*Research Assistance*, advised by **Prof. Jinglong Chen**

Jun. 2023 - Current

- \* Developed a diffusion-based model for signal generation across diverse operating conditions.
- \* Explored using cross-modal information as top-down attention to guide the generation process
- \* Conducted initial validation experiments to confirm the method's effectiveness.

**DUIDA for Intelligent Diagnosis under Imbalanced Conditions**

**Xi'an, Shaanxi**

*Research Assistance*, advised by **Prof. Jinglong Chen**

Jul. 2022 - Jan.2023

- \* Co-first author of a paper addressing the challenges of imbalances in unsupervised domain adaption fault diagnosis.
- \* Poroposed a Dynamic Domain Adaptation diagnosis algorithms with Sample and Margin Regularization.
- \* Employed dynamic mechanisms to stabilize training and utilized boundary regularization to refine the decision-making boundary.

**Meta-data Driven Transfer Residual Network with Explicit Weight Strategy**

**Xi'an, Shaanxi**

*Research Assistance*, advised by **Prof. Jinglong Chen**

Jul. 2021 - May.2022

- \* First author of a paper addressing the challenges of imbalances in cross-domain diagnostic performance for intelligent fault diagnosis.
- \* Poroposed a Transfer Residual Network with an Explicit Weight Self-assignment Strategy(TRN-EWM).
- \* Utilized metadata to optimize sample weights, striking a balance for class-imbalance in cross-domain diagnosis.
- \* Carried out validation experiments, achieving over 99% accuracy.

## Projects Experience

### Low-Cost Remote Control Servo Quadruped Robot

Xi'an, Shaanxi

*Product Design Course Project*, advised by **Prof. Dun Lv**

Sept. 2020 - Jan. 2021

- \* Deployed an eight-servo quadrupedal gait with pitch control
- \* Implemented a bluetooth-enabled remote control system with its corresponding mobile application
- \* Mechanism design (via Solidworks) and fabrication (via 3D print)

### Indoor Assistive Robot for Elderly People

Xi'an, Shaanxi

*Role: Leader*, co-advised by **Sr. Eng. Yue Jing & Sr. Eng. Liang Gui**

Aug. 2019 - Nov. 2020

- \* Secured the National First Prize in the Chinese University Students' Mechanical Innovation Competition
- \* Developed and deployed an SSD-based face detection algorithm
- \* Designed a lifting mechanism tailored to the natural curvature of the human body (via Solidworks) and strength check (via Ansys)

### ABU Robocon Competitive Robot Project

Xi'an, Shaanxi

*Role: Mechanism Design*, advised by **Prof. Jun Xu**

Sept. 2018 - Jun. 2019

- \* Secured the National First Prize of Chinese Asian-Oceanian College Robot Competition
- \* Designed and fabricated two competition-ready robots (Including wheeled mobility, obstacle navigation, and projectile tasks)
- \* Mechanism design (via Solidworks, AutoCad) and fabrication (via 3D print, CNC)

## Working Experience

### Teaching Assistant

Xi'an, Shaanxi

*Mechanical Fault Diagnosis Course*, advised by **Prof. Jinglong Chen**

Apr. 2021 - Jun. 2021

- \* Daily course QA; Send and receive assignments
- \* Grade assignments, quizzes, and finals

### Reserch internship

Beijing, China

*CAS*, advised by **Prof. Xue Wang & Prof. Bingshan Liu**

Jul. 2019 - Aug. 2019

- \* Attended lab meetings and gaining a basic understanding of Point Cloud Matching
- \* Gained insights into Visual Navigation and Light-Curing 3D Printing

## Honors and Awards

QU&HE Fault Diagnosis Scholarship	2021
Outstanding Graduate Student, Xi'an Jiaotong University	2021
National First Prize of Chinese University Students' Mechanical Innovation Competition	2020
National First Prize of Chinese Asian-Oceanian College Robot Competition	2019
SMC Scholarships, SMC	2019
School Scholarships, Xi'an Jiaotong University	2018, 2020, 2022
Merit Student, Xi'an Jiaotong University	2018, 2020

## Skills

<b>Programming</b>	Python(Pytorch,Tensorflow), Matlab, LaTeX, C/C++, Linux(Ubuntu)
<b>Mechanical Design</b>	Solidworks, AutoCad, Inventor, Ansys
<b>Productivity Tools</b>	Microsoft Office, Markdown
<b>Languages</b>	Mandarin (Native), English (Fluent)