有限元方法第五次作业



学 号: 20210290017

课程名称: 有限元方法

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第一题第一问:

整理课堂内容,梳理清楚弹性力学有限元方法的几个重要步骤。本周先梳理清楚以下两点:

- 弹性力学基本方程和第二类边界条件的等效加权参数形式;
- 平面弹性力学三角形单元上的位移、应变的插值公式。

$$\begin{cases} \sigma_{ij,j} + f_1 = 0 \\ \sigma_{ij} = D_{ijkl} (\varepsilon_{kl} - \varepsilon_{kl}^0) \\ \varepsilon_{ij} = \frac{1}{2} (u_{i,j} + u_{j,i}) \end{cases}$$
$$\begin{cases} u_j = \overline{u_i} \\ \sigma_{ij} \eta_j = \overline{F}_i \\ \sigma_{ij} \eta_j = k(u_{i0} - u_i) \end{cases}$$

$$\begin{cases} \sigma_{11,1} + \sigma_{12,2} + \sigma_{13,3} + f_1 = 0 \\ \sigma_{21,1} + \sigma_{22,2} + \sigma_{23,3} + f_2 = 0 \\ \sigma_{31,1} + \sigma_{32,3} + \sigma_{33,3} + f_3 = 0 \end{cases}$$

$$\begin{cases} \int_{\Omega} (\sigma_{11,1} + \sigma_{12,2} + \sigma_{13,3} + f_1) d\Omega = 0 \\ \int_{\Omega} (\sigma_{21,1} + \sigma_{22,2} + \sigma_{23,3} + f_2) d\Omega = 0 \\ \int_{\Omega} (\sigma_{31,1} + \sigma_{32,3} + \sigma_{33,3} + f_3) d\Omega = 0 \end{cases}$$

$$\begin{cases} \int_{\Omega} w_1(\sigma_{1j,j} + f_1) d\Omega = 0 \\ \int_{\Omega} w_2(\sigma_{2j,j} + f_2) d\Omega = 0 \\ \int_{\Omega} w_3(\sigma_{3j,j} + f_3) d\Omega = 0 \end{cases}$$

$$\begin{cases} \int_{\Omega} w_i(\sigma_{ij,j} + f_i) d\Omega = 0 \\ \int_{\Gamma_2} w_i^{(1)}(\sigma_{ij}\eta_j - \overline{F_i}) d\Gamma = 0 \\ \int_{\Gamma_3} w_i^{(2)}(\sigma_{ij}\eta_j - k(u_{i0} - u_i)) d\Gamma = 0 \end{cases}$$

$$\int_{\Omega} w_i(\sigma_{ij,j}) d\Omega = 0$$

$$\Leftrightarrow \int_{\Omega} [(w_i \sigma_{ij})_j - w_{i,j} \sigma_{ij}] d\Omega$$

$$= \oint_{\Omega} w_i \sigma_{ij} \eta_j d\Gamma - \int_{\Omega} w_{i,j} \sigma_{ij} d\Omega$$

$$\begin{split} &\int_{\Omega} (w_i \frac{\partial \sigma_{ij}}{\partial x_j} + f_i) d\Omega + \int_{\Gamma_2} w_i^{(1)} (\sigma_{ij} \eta_j - \overline{F_i}) d\Gamma + \int_{\Gamma_3} w_i^{(2)} (\sigma_{ij} \eta_j - k(u_{i0} - u_i)) d\Gamma = 0 \\ &u_i = \overline{u_i} \\ &\sigma_{ij} = D_{ijkl} (\varepsilon_{kl} - \varepsilon_{kl}^0) \\ &\varepsilon_{ij} = \frac{1}{2} (u_{i,j} + u_{j,i}) \end{split}$$

$$\begin{cases} \frac{\partial \sigma_{x}}{\partial x} + \frac{\partial \tau_{xy}}{\partial y} + f_{(x)} = 0 \\ \frac{\partial \tau_{xy}}{\partial x} + \frac{\partial \sigma_{y}}{\partial y} + f_{(y)} = 0 \end{cases}$$

$$\begin{cases} \int w_{x} \left(\frac{\partial \sigma_{x}}{\partial x} + \frac{\partial \tau_{xy}}{\partial y} + f_{(y)} \right) d\Omega = 0 \\ \int w_{y} \left(\frac{\partial \tau_{xy}}{\partial x} + \frac{\partial \sigma_{y}}{\partial y} + f_{(y)} \right) d\Omega = 0 \end{cases}$$

$$\int \left[w_{x} \left(\frac{\partial \sigma_{x}}{\partial x} + \frac{\partial \tau_{xy}}{\partial y} + f_{(x)} \right) + w_{y} \left(\frac{\partial \tau_{xy}}{\partial x} + \frac{\partial \sigma_{y}}{\partial y} + f_{(y)} \right) \right] d\Omega = 0 \end{cases}$$

$$\Leftrightarrow \int_{\Omega} \left(w_{i} \frac{\partial \sigma_{ij}}{\partial x_{i}} + f_{i} \right) = 0$$

$$\int_{\Omega} \frac{\partial w_i \sigma_{ij}}{\partial x_j} d\Omega = \oint w_i \sigma_{ij} \eta_j d\Gamma$$

$$\int_{\Omega} \left(-\frac{\partial w_i}{\partial x_j} \bullet \sigma_{iy} + w_i f_i \right) d\Omega - \oint w_i \sigma_{ij} \eta_j d\Gamma = 0$$

⇔
$$\begin{cases} \int_{\Omega} \left(-\frac{\partial w_i}{\partial x_j} \bullet \sigma_{iy} + w_i f_i \right) d\Omega + \int_{\Gamma_2} w_i T_i d\Gamma = 0 \\ w_1 \mid_{\Gamma_1} = 0 \end{cases}$$
 定义:
$$\left[\sigma \right] = \begin{bmatrix} \sigma_x \\ \sigma_y \\ \tau_w \end{bmatrix}, \left[f \right] = \begin{bmatrix} f_x \\ f_y \end{bmatrix}, \left[T \right] = \begin{bmatrix} T_x \\ T_y \end{bmatrix}, \left[w \right] = \begin{bmatrix} w_x \\ w_y \end{bmatrix} \end{cases}$$

$$\left[\delta\varepsilon\right] = \begin{bmatrix} \frac{\partial w_{x}}{\partial x_{x}} \\ \frac{\partial w_{y}}{\partial x_{y}} \\ \frac{\partial w_{x}}{\partial x_{x}} + \frac{\partial w_{y}}{\partial x_{y}} \end{bmatrix} = \left[B_{(x,y)}\right] \left[\delta q\right]$$

$$\begin{bmatrix} u \\ v \\ w \end{bmatrix} = \begin{bmatrix} N_1^{(e)} & N_2^{(e)} & N_3^{(e)} & N_3^{(e)} & N_4^{(e)} & N_4^{(e)}$$

$$= \left[B_{(x,y,z)}\right] \left[q^{(e)}\right]$$

$$\begin{split} &\int_{\Omega} (-\frac{\partial w_{i}}{\partial x_{j}} \bullet \sigma_{iy} + w_{i} f_{i}) d\Omega + \int_{\Gamma_{2}} w_{i} T_{i} d\Gamma = 0 \\ &\Leftrightarrow \int_{\Omega} (-\left[\delta_{\varepsilon}\right]^{T} \left[\sigma\right] + \left[\delta_{u}\right]^{T} \left[f\right]) d\Omega + \int_{\Gamma_{2}} \left[\delta_{u}\right]^{T} \left[\overline{F}\right] d\Gamma = 0 \\ &\int_{\Omega} \left[\delta_{q}\right]^{T} \left[\sigma\right] d\Omega - \int_{\Omega} \left[\delta_{u}\right]^{T} \left[f\right] d\Omega - \int_{\Gamma_{2}} \left[\delta_{u}\right]^{T} \left[\overline{F}\right] d\Gamma = 0 \\ &= \sum_{e} \int_{\Omega_{e}} \left[\delta_{q}\right]^{T} \left[B\right]^{T} \left[D\right] \left[B\right] \left[q\right] d\Omega - \int_{\Omega_{e}} \left[\delta_{q}\right]^{T} \left[N\right]^{T} \left[f\right] d\Omega - \left[\delta_{q}\right]^{T} \int_{\Gamma_{2e}} \left[N\right]^{T} \left[\overline{F}\right] d\Gamma = 0 \\ &= \sum_{e} \left[\int_{\Omega_{e}} \left[\delta_{q}\right]^{T} \left[B\right]^{T} \left[D\right] \left[B\right] \left[q\right] d\Omega - \int_{\Omega_{e}} \left[\delta_{q}\right]^{T} \left[N\right]^{T} \left[f\right] d\Omega - \left[\delta_{q}\right]^{T} \int_{\Gamma_{2e}} \left[N\right]^{T} \left[\overline{F}\right] d\Gamma \right] \\ &= \sum_{e} \left[\left[\delta_{q_{e}}\right]^{T} \left[k_{e}\right] \left[q_{e}\right] - \left[\delta_{q_{e}}\right]^{T} \left[f_{e}\right] - \left[\delta_{q_{e}}\right]^{T} \left[\overline{F}_{e}\right] \right] = \sum_{e} \left[\delta_{q_{e}}\right]^{T} \left(\left[k_{e}\right] \left[q_{e}\right] - \left[P_{e}\right]\right) = 0 \end{split}$$

$$T = \frac{1}{2\Delta}[a_1 + b_1x + c_1y)T_1 + (a_2 + b_2x + c_2y)T_2 + (a_3 + b_3x + c_3y)T_3]$$
类比之后,得到位移差值
$$\begin{cases} u(x,y,z) = N_1^{(e)}(x,y,z)u_1 + N_2^{(e)}(x,y,z)u_2 + N_3^{(e)}(x,y,z)u_3 + N_4^{(e)}(x,y,z)u_4 \\ v(x,y,z) = N_1^{(e)}(x,y,z)v_1 + N_2^{(e)}(x,y,z)v_2 + N_3^{(e)}(x,y,z)v_3 + N_4^{(e)}(x,y,z)v_4 \\ w(x,y,z) = N_1^{(e)}(x,y,z)w_1 + N_2^{(e)}(x,y,z)w_2 + N_3^{(e)}(x,y,z)w_3 + N_4^{(e)}(x,y,z)w_4 \end{cases}$$

$$\begin{cases} \mathcal{E}_{x} \\ \mathcal{E}_{y} \\ \mathcal{E}_{z} \\ \mathcal{Y}_{xy} \\ \mathcal{Y}_{yz} \\ \mathcal{Y}_{zx} \end{cases} = \begin{cases} \frac{\partial u}{\partial x} \\ \frac{\partial v}{\partial y} \\ \frac{\partial w}{\partial z} \\ \frac{\partial u}{\partial z} + \frac{\partial x}{\partial x} \\ \frac{\partial v}{\partial z} + \frac{\partial w}{\partial z} \\ \frac{\partial w}{\partial z} + \frac{\partial w}{\partial$$