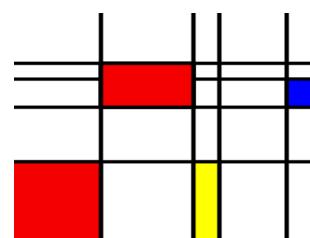
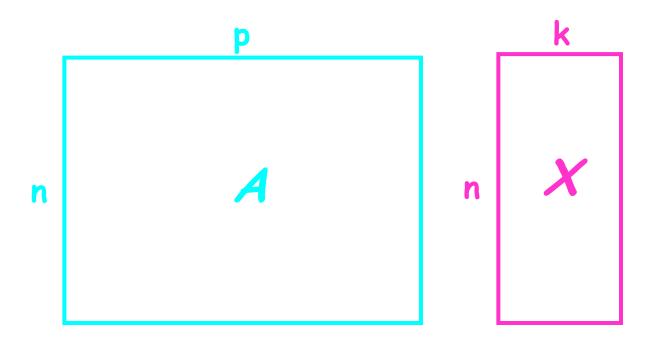


Dimensionality Reduction

Lingqiao Liu



What is dimensionality reduction?



Extract underlying factors





The five factors [edit]

A summary of the factors of the Big Five and their col

- Openness to experience: (inventive/curious vs intellectual curiosity, creativity and a preference for preference for a variety of activities over a strict resperience.
- Conscientiousness: (efficient/organized vs. eas spontaneous behavior.
- Extraversion: (outgoing/energetic vs. solitary/re talkativeness.
- Agreeableness: (friendly/compassionate vs. an one's trusting and helpful nature, and whether a r
- Neuroticism: (sensitive/nervous vs. secure/conf degree of emotional stability and impulse control:

- Reduce data noise
 - Face recognition
 - Applied to image de-noising



(a) Noisy image



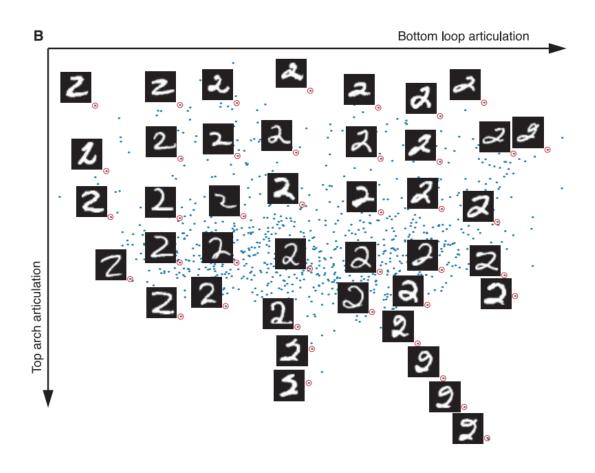
(b) NL means (PSNR=32.90)



(c) Local PCA (PSNR=33.70)

- Reduce the number of model parameters
 - Avoid over-fitting
 - Reduce computational cost

Visualization



Dimensionality Reduction

- General principle:
 - Preserve "useful" information in low dimensional data
- How to define "usefulness"?
 - Many
 - An active research direction in machine learning
- Taxonomy
 - Supervised or Unsupervised
 - Linear or nonlinear
- Commonly used methods:
 - PCA, LDA (linear discriminant analysis), and more.
- Feature Selection vs dimensionality reduction

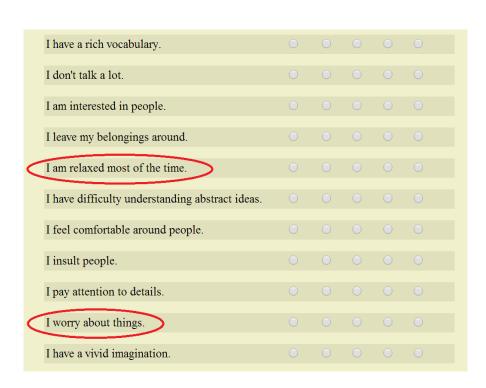
Outline

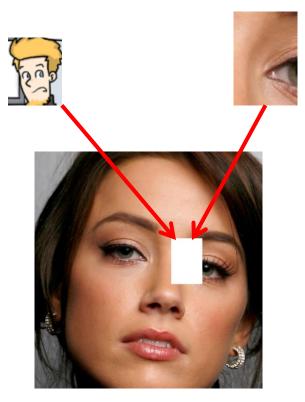
- PCA: theoretic Part
 - PCA explained: two perspectives
 - Mathematic basics
 - PCA objective and solution
- Case study
 - Eigen face
 - Handle high feature dimensionality
- LDA: theoretic Part
 - LDA objective and formulation
 - Compare with PCA
- Other dimensionality reduction methods

PCA explained: Two perspectives

- Data correlation and information redundancy
- Signal-noise ratio maximization

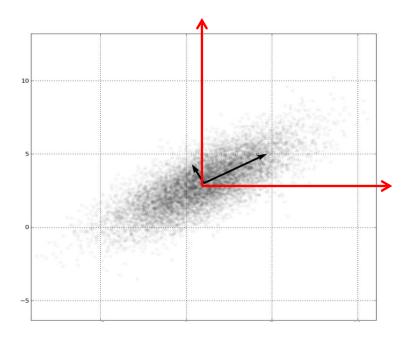
Data correlation & information redundancy

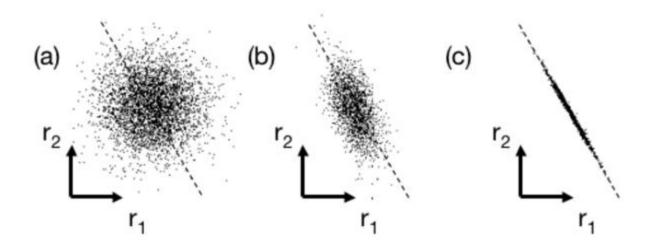


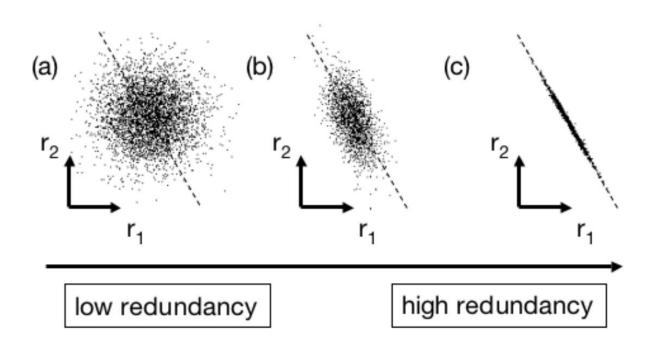


- Dependency vs. Correlation
 - Dependent is a stronger criterion
- Equivalent when data follows Gaussian distribution
- PCA only de-correlates data
 - One limitation of PCA
 - ICA, but it is more complicate

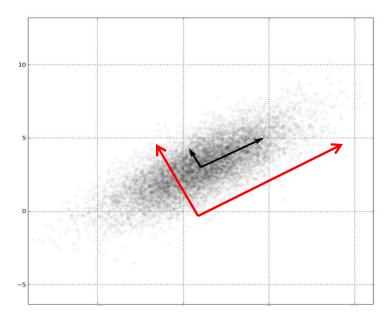
Geometric interpretation of correlation



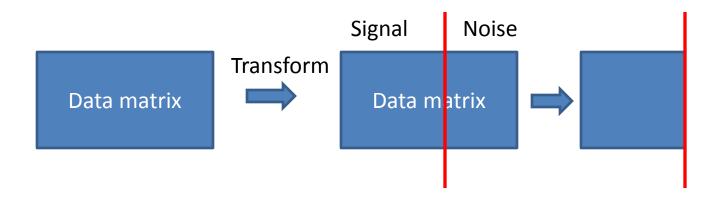




 Correlation can be removed by rotating the data point or coordinate



PCA explained: SNR maximization

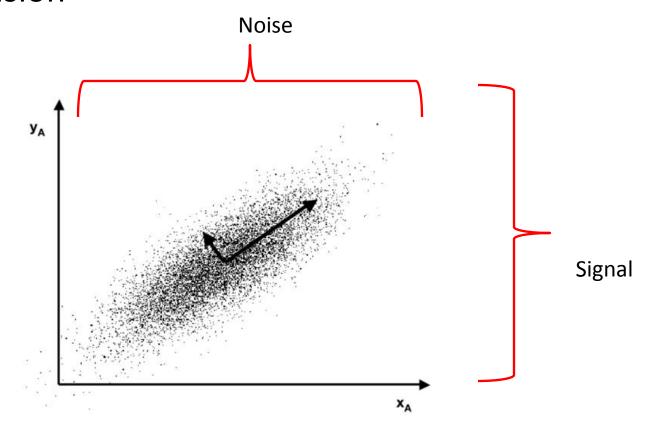


Maximize

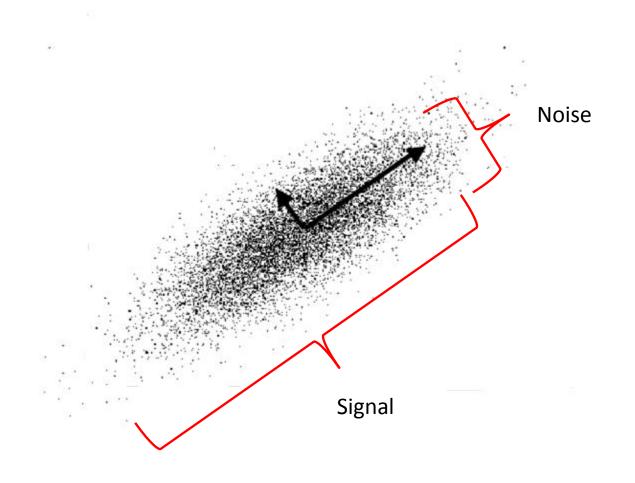
$$SNR = rac{\sigma_{signal}^2}{\sigma_{noise}^2}.$$

PCA explained: SNR maximization

Keep one signal dimension, discard one noisy dimension



PCA explained: SNR maximization



PCA explained

- Target
 - 1: Find a new coordinate system which makes different dimensions zero correlated
 - 2: Find a new coordinate system which aligns (top-k) largest variance
- Method
 - Rotate the data point or coordinate
- Mathematically speaking...
 - How to rotate?
 - How to express our criterion

- Mean, Variance, Covariance
- Matrix norm, trace,
- Orthogonal matrix, basis
- Eigen decomposition

(Sample) Mean

$$\bar{X} = \frac{\sum_{i=1}^{n} X_i}{n}$$

(Sample) Variance

$$s^{2} = \frac{\sum_{i=1}^{n} (X_{i} - \bar{X})^{2}}{(n-1)}$$

(Sample) Covariance

$$cov(X,Y) = \frac{\sum_{i=1}^{n} (X_i - \bar{X})(Y_i - \bar{Y})}{(n-1)}$$

Covariance Matrix

$$C = \begin{pmatrix} cov(x,x) & cov(x,y) & cov(x,z) \\ cov(y,x) & cov(y,y) & cov(y,z) \\ cov(z,x) & cov(z,y) & cov(z,z) \end{pmatrix}$$

$$\mathbf{C} = \frac{1}{n-1} \sum_{i=1}^{n} (\mathbf{X}_i - \bar{\mathbf{X}}) (\mathbf{X}_i - \bar{\mathbf{X}})^T$$

Frobenius norm

$$||A||_F = \sqrt{\sum_{i=1}^m \sum_{j=1}^n |a_{ij}|^2}$$

Trace

$$tr(A) = a_{11} + a_{22} + \dots + a_{nn} = \sum_{i=1}^{n} a_{ii}$$

$$tr(X^{T}Y) = tr(XY^{T}) = tr(Y^{T}X) = tr(YX^{T})$$

$$||A||_{F} = \sqrt{\sum_{i=1}^{m} \sum_{j=1}^{n} |a_{ij}|^{2}} = \sqrt{trace(A^{*}A)}$$

- Symmetric Matrix $\mathbf{A} = \mathbf{A}^T$
- Covariance matrix is symmetric

$$\mathbf{C} = \frac{1}{n-1} \mathbf{X} \mathbf{X}^T$$

$$C = C^T$$

Orthogonal matrix

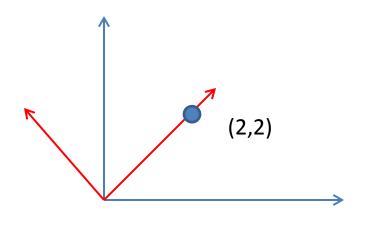
$$Q^{\mathrm{T}}Q = QQ^{\mathrm{T}} = I_{\mathrm{I}}$$

Rotation effect

$$\|\mathbf{Q}\mathbf{x}\|_F = \sqrt{\operatorname{trace}(\mathbf{x}^T\mathbf{Q}^T\mathbf{Q}\mathbf{x})} = \sqrt{\operatorname{trace}(\mathbf{x}^T\mathbf{x})} = \|\mathbf{x}\|_F$$

$$\mathbf{x} = \mathbf{Q}^T \mathbf{Q} \mathbf{x}$$

- Relationship to coordinate system
 - A point = linear combination of bases
 - Combination weight = coordinate
- Each row (column) of Q = basis
 - Not unique
 - Relation to coordinate rotation
- New coordinate Qx



$$\binom{2}{2} = 2 \binom{1}{0} + 2 \binom{0}{1}$$

$$\binom{2}{2} = 2\sqrt{2} \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix} + 0 \begin{pmatrix} \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \end{pmatrix}$$

coordinate
$$\begin{pmatrix} 2\sqrt{2} \\ 0 \end{pmatrix} = \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} 2 \\ 2 \end{pmatrix}$$
 Old

Eigenvalue and Eigenvector

$$\mathbf{A}\mathbf{u} = \lambda \mathbf{u}$$

- Properties
 - Multiple solutions
 - Scaling invariant
 - Relation to the rank of A

Eigen-decomposition

• If **A** is symmetric

$$\mathbf{A} = \mathbf{Q} \mathbf{\Lambda} \mathbf{Q}^T \quad Q^{\mathsf{T}} Q = Q Q^{\mathsf{T}} = I_{\mathsf{T}}$$

PCA: solution

Target 1: de-correlation

$$\mathbf{C}_{X} = \frac{1}{n-1} \mathbf{X} \mathbf{X}^{T}$$

$$\mathbf{Y} = \mathbf{P} \mathbf{X}$$

$$\mathbf{C}_{Y} = \frac{1}{n-1} \mathbf{P} \mathbf{X} (\mathbf{P} \mathbf{X})^{T}$$

$$= \frac{1}{n-1} \mathbf{P} \mathbf{X} \mathbf{X}^{T} \mathbf{P}^{T}$$

$$= \frac{1}{n-1} \mathbf{P} \mathbf{Q} \mathbf{\Lambda} \mathbf{Q}^{T} \mathbf{P}^{T}$$

PCA: solution

$$\mathbf{C}_{Y} = \frac{1}{n-1} \mathbf{P} \mathbf{X} (\mathbf{P} \mathbf{X})^{T} \qquad \text{if } \mathbf{P} = \mathbf{Q}^{T}$$

$$= \frac{1}{n-1} \mathbf{P} \mathbf{X} \mathbf{X}^{T} \mathbf{P}^{T} \qquad \mathbf{C}_{Y} = \frac{1}{n-1} \mathbf{\Lambda}$$

$$= \frac{1}{n-1} \mathbf{P} \mathbf{Q} \mathbf{\Lambda} \mathbf{Q}^{T} \mathbf{P}^{T}$$

PCA: solution

Variance of each dimension

$$Var(y_k) = \frac{1}{n-1} \mathbf{P}_k \mathbf{X} \mathbf{X}^T \mathbf{P}_k^T$$
$$= \frac{1}{n-1} \mathbf{p}_k \mathbf{Q} \mathbf{\Lambda} \mathbf{Q}^T \mathbf{p}_k^T$$
$$= \frac{1}{n-1} \lambda_k$$

Rank dimensions according to their corresponding eigenvalues

PCA: algorithm

- 1. Subtract mean
- 2. Calculate the covariance matrix
- 3. Calculate eigenvectors and eigenvalues of the covariance matrix
- 4. Rank eigenvectors by its corresponding eigenvalues
- 4. Obtain P with its column vectors corresponding to the top k eigenvectors

PCA: MATLAB code

```
5
6- Mu = mean(fea);
7- fea = fea - repmat(Mu,[size(fea,1),1]);
8- Cov = fea'*fea;
9- [V,D] = eig(Cov);
10- [value,rank_idx] = sort(diag(D),'descend');
11- P = V(:,rank_idx(1:10));
```

PCA: reconstruction

Reconstruct x

$$\hat{\mathbf{x}} = \hat{\mathbf{P}}^T \hat{\mathbf{P}} \mathbf{x}$$

Derive PCA through minimizing the reconstruction error

$$\min_{\mathbf{P}} \|\mathbf{X} - \mathbf{P}^T \mathbf{P} \mathbf{X}\|_F^2$$

$$s.t. \ \mathbf{P} \mathbf{P}^T = \mathbf{I}$$

PCA: reconstruction

Reighley Quotient

$$\max_{\mathbf{P}} \text{ trace}(\mathbf{P}\mathbf{X}\mathbf{X}^T\mathbf{P}^T)$$

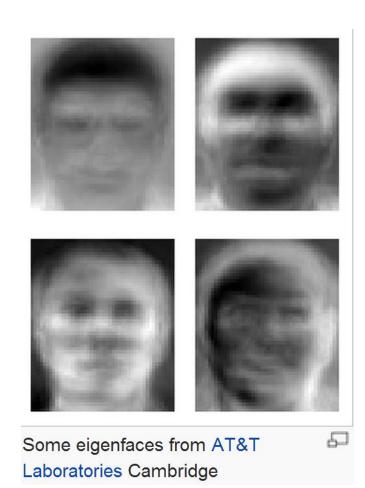
$$s.t. \ \mathbf{P}\mathbf{P}^T = \mathbf{I}$$

• Solution = PCA

Application: Eigen-face method

- Sirovich and Kirby (1987) showed that PCA could be used on a collection of face images to form a set of basis features.
- Not only limited to face recognition
- Steps
 - Image as high-dimensional feature
 - PCA

Application: Eigen-face method



Application: Reconstruction

Reconstructed from top-2 eigenvectors









Application: Reconstruction

Reconstructed from top-15 eigenvectors









Application: Reconstruction

Reconstructed from top-40 eigenvectors



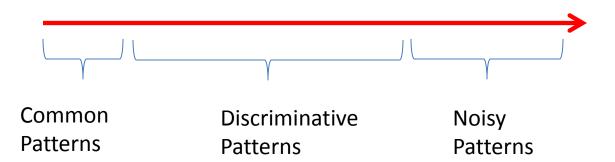






Application: Eigen-face method

From large to small eigenvalues



high dimensionality issue

- For high-dimensional data $C_X = \frac{1}{n-1} X X^T$ can be too large
- The number of samples is relatively small

$$d\gg N$$
 Define $\mathbf{u}=\mathbf{X}\mathbf{v}$ $\mathbf{X}^T\mathbf{X}\mathbf{v}=\lambda\mathbf{v}$ $\mathbf{X}\mathbf{X}^T\mathbf{u}=\lambda\mathbf{u}$ $\mathbf{X}\mathbf{X}^T(\mathbf{X}\mathbf{v})=\lambda(\mathbf{X}\mathbf{v})$

High dimensionality issue

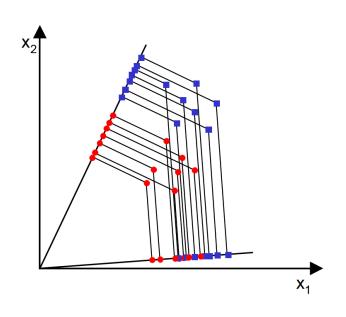
- 1. Centralize data
- 2. Calculate the kernel matrix
- 3. Perform Eigen-decomposition on the kernel matrix and obtain its eigenvector ${f v}$
- 4. Obtain the Eigenvector of the covariance matrix by $\mathbf{u} = \mathbf{X}\mathbf{v}$
- Question? How many eigenvectors you can obtain in this way?

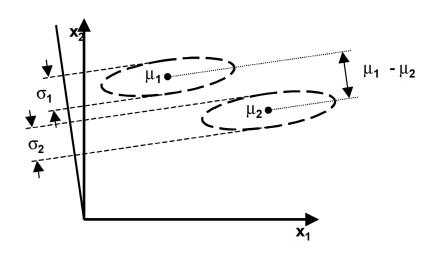
Discriminative dimensionality reduction

- General principle:
 - Preserve "useful" information in low dimensional data
 - PCA: measure ``usefulness'' through reconstruction error or covariance structure.
 - Useful for reconstruction ≠ useful for classification
- General principle for discriminative dimensionality reduction
 - Preserve "discriminative" information in low dimensional data

Linear Discriminant Analysis (LDA), Objective

• Two classes:

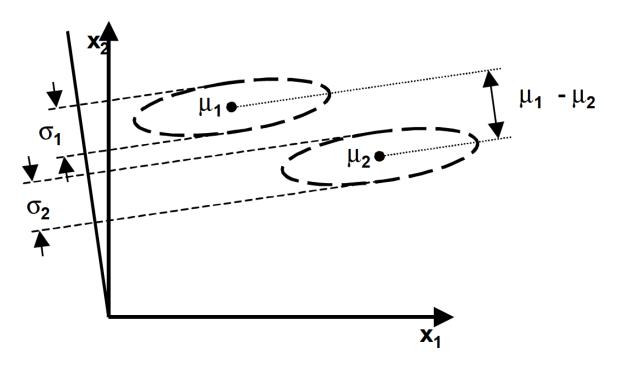




maximize
$$\frac{(\mu_1 - \mu_2)^2}{\sigma_1^2 - \sigma_2^2}$$

Linear Discriminant Analysis, Objective

Two classes:



maximize
$$\frac{\left(\mu_1 - \mu_2\right)^2}{\sigma_1^2 - \sigma_2^2}$$

$$SNR = \frac{\sigma_{signal}^2}{\sigma_{noise}^2}.$$

Linear Discriminant Analysis (LDA), Objective

Mean after projection:

$$\hat{\mu} = \frac{1}{N} \sum_{i=1}^{N} \mathbf{p}^{T} \mathbf{x}_{i} = \mathbf{p}^{T} \frac{1}{N} \sum_{i=1}^{N} \mathbf{x}_{i} = \mathbf{p}^{T} \mu$$

Variance after projection:

$$\hat{\sigma}^2 = \frac{1}{N} \sum_{i=1}^N (\mathbf{p}^T \mathbf{x}_i - \mathbf{p}^T \mu)^2$$

$$= \frac{1}{N} \sum_{i=1}^N \mathbf{p}^T (\mathbf{x}_i - \mu) (\mathbf{x}_i - \mu)^T \mathbf{p}$$

$$= \mathbf{p}^T \left(\frac{1}{N} \sum_{i=1}^N (\mathbf{x}_i - \mu) (\mathbf{x}_i - \mu)^T \right) \mathbf{p}$$

Linear Discriminant Analysis (LDA), Objective

Objective

$$(\mathbf{p}^T \mu_1 - \mathbf{p}^T \mu_2)^2 = \mathbf{p}^T (\mu_1 - \mu_2) (\mu_1 - \mu_2)^T \mathbf{p}$$

$$\mathbf{S}_b = (\mu_1 - \mu_2) (\mu_1 - \mu_2)^T$$

$$\mathbf{S}_w = \frac{1}{N} \sum_{i=1}^N (\mathbf{x}_i - \mu) (\mathbf{x}_i - \mu)^T$$

maximize
$$\frac{\mathbf{p}^T \mathbf{S}_b \mathbf{p}}{\mathbf{p}^T \mathbf{S}_w \mathbf{p}}$$

Linear Discriminant Analysis (LDA), Solution

Solution

maximize
$$\frac{\mathbf{p}^T \mathbf{S}_b \mathbf{p}}{\mathbf{p}^T \mathbf{S}_w \mathbf{p}}$$
 maximize $\mathbf{p}^T \mathbf{S}_b \mathbf{p}$

$$s.t. \ \mathbf{p}^T \mathbf{S}_w \mathbf{p} = 1$$

$$L = \mathbf{p}^T \mathbf{S}_b \mathbf{p} - \lambda (\mathbf{p}^T \mathbf{S}_w \mathbf{p} - 1)$$

$$\frac{\partial L}{\partial \mathbf{p}} = 0 \quad \Rightarrow \quad \mathbf{S}_w^{-1} \mathbf{S}_b \mathbf{p} = \lambda \mathbf{p}$$

• Top eigenvector of $\mathbf{S}_w^{-1}\mathbf{S}_b$

Linear Discriminant Analysis, Multi-class

Generalized to multiple classes

$$\mathbf{S}_{b} = \sum_{i=1,j=1}^{C} (\mu_{i} - \mu_{j}) (\mu_{i} - \mu_{j})^{T} = \sum_{i} (\mu_{i} - \mu) (\mu_{i} - \mu)^{T}$$

$$\mathbf{S}_{w} = \sum_{j=1}^{C} \sum_{i \in \mathcal{C}_{j}} (\mathbf{x}_{i} - \mu) (\mathbf{x}_{i} - \mu)^{T}$$

$$\max imize \quad \frac{\operatorname{trace} (\mathbf{P}^{T} \mathbf{S}_{b} \mathbf{P})}{\operatorname{trace} (\mathbf{P}^{T} \mathbf{S}_{w} \mathbf{P})}$$

- Solution:
 - Top c eigenvectors of $\mathbf{S}_w^{-1}\mathbf{S}_b$
 - Discussion: how many projections you can have?

LDA vs PCA

- LDA vs PCA
 - Discriminative vs generative
 - LDA projection is not necessarily orthogonal

Case study: character recognition

Other dimensionality reduction methods

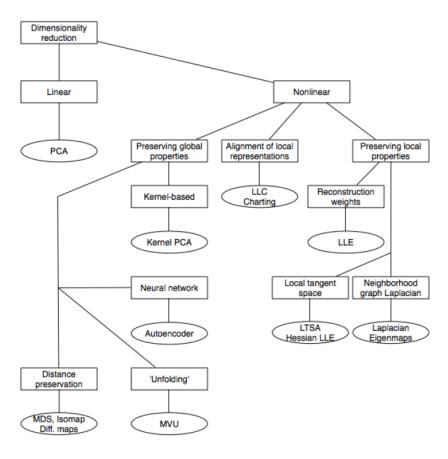


Fig. 1. Taxonomy of dimensionality reduction techniques.

Image courtesy of L.J.P. van der Maaten , E. O. Postma , H. J. van den Herik; **Dimensionality Reduction:** A Comparative Review 2008

Other dimensionality reduction methods

- Some popular idea:
 - Kernel trick, e.g. kernel PCA
 - Preserve localized information
 - Local similarity preserving, e.g. LLE
 - Local discriminative dimensionality reduction, e.g. LFDA
 - Nonlinear reconstruction through neural network
 - Auto-encoder
- How to develop a new dimensionality reduction method?
 - Define your own objective
 - Define your reduction function
 - Optimization