

# MTH101: Lecture 17 – 18

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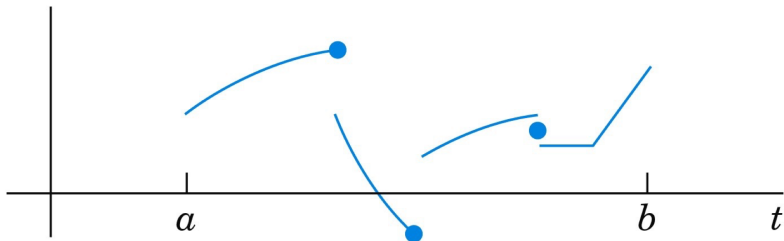
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## Definition

We say a function  $f$  is **piecewise continuous** on an infinite interval, e.g.  $\mathbb{R}_{\geq 0} = [0, \infty)$ , if it is piecewise continuous on any finite subinterval  $[a, b]$ .

It is piecewise continuous on a finite interval  $[a, b]$  if:

- 1  $[a, b]$  can be divided into finitely many open subintervals  $(a_j, a_{j+1})$ ,  $a = a_0 < a_1 < \cdots < a_n = b$ , on which  $f$  is continuous.
- 2 For  $j = 0, 1, \dots, n-1$ ,  $\lim_{t \rightarrow a_j^+} f(t)$  and  $\lim_{t \rightarrow a_{j+1}^-} f(t)$  exist and are finite.
- 3 At the border points  $a_j$  the function  $f$  may take any (finite) values.



## Theorem

*If  $f(t)$  is defined and piecewise continuous on  $\mathbb{R}_{\geq 0}$  and satisfies  $|f(t)| \leq Me^{kt}$  for some  $M, k \in \mathbb{R}$ , then  $\mathcal{L}[f]$  exists and is defined at all points  $s > k$ .*

*If  $\mathcal{L}[f] = \mathcal{L}[g]$  then  $f(t) = g(t)$  “almost everywhere”, i.e. the set of exceptions  $\{t: f(t) \neq g(t)\}$  is somehow smaller than any interval  $[a, a+\varepsilon]$ .*

Proof.

$$\begin{aligned} |\mathcal{L}[f]| &= \left| \int_0^{\infty} e^{-st} f(t) dt \right| \leq \int_0^{\infty} |f(t)| e^{-st} dt \\ &\leq \int_0^{\infty} M e^{kt} e^{-st} dt = \frac{M}{s-k}. \end{aligned}$$



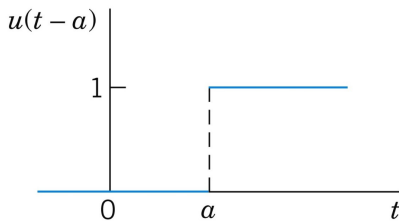
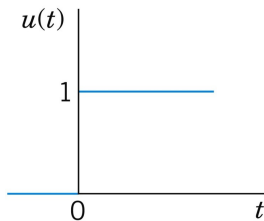
## Definition

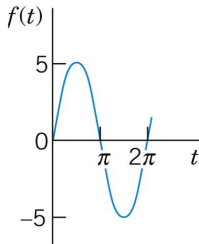
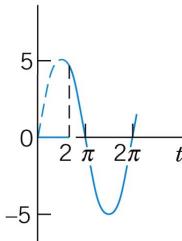
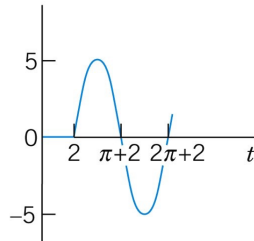
**Heaviside function (or unit step function)**  $u(t - \alpha)$  is defined as follows:

$$u(t - \alpha) = \begin{cases} 0 & \text{if } t < \alpha, \\ 1 & \text{if } t > \alpha. \end{cases}$$

## Remark

*The Heaviside function is a typical **engineering function**, which often involve functions that are either **off** or **on**!*



(A)  $f(t) = 5 \sin t$ (B)  $f(t)u(t-2)$ (C)  $f(t-2)u(t-2)$



## Remark

*Laplace transform for the Heaviside function is as follows:*

$$\begin{aligned}\mathcal{L}[u(t - \alpha)] &= \int_0^{\infty} e^{-st} u(t - \alpha) dt = \int_{\alpha}^{\infty} e^{-st} dt \\ &= -\frac{e^{-st}}{s} \Big|_{t=\alpha}^{\infty} = \frac{e^{-s\alpha}}{s}.\end{aligned}$$

## Theorem

### Second shifting theorem, $t$ -Shifting

If  $\mathcal{L}[f(t)] = F(s)$ , then

$$\mathcal{L}[f(t - \alpha)u(t - \alpha)] = e^{-\alpha s}F(s),$$

$$\text{or, } f(t - \alpha)u(t - \alpha) = \mathcal{L}^{-1}[e^{-\alpha s}F(s)].$$

## Proof.

By definition,

$$e^{-\alpha s} F(s) = e^{-\alpha s} \int_0^{\infty} e^{-s\tau} f(\tau) d\tau = \int_0^{\infty} e^{-s(\tau+\alpha)} f(\tau) d\tau.$$

If we define  $t = \tau + \alpha$ , the integral becomes

$$e^{-\alpha s} F(s) = \int_{\alpha}^{\infty} e^{-st} f(t - \alpha) dt = \int_0^{\infty} e^{-st} f(t - \alpha) u(t - \alpha) dt.$$



## Example

*Find the Laplace transform for the following function.*

$$f(t) = \begin{cases} 2 & \text{if } 0 < t < 1, \\ \frac{1}{2}t^2 & \text{if } 1 < t < \frac{1}{2}\pi, \\ \cos t & \text{if } t > \frac{1}{2}\pi. \end{cases}$$

## Example

### Solution

#### Step 1

*The function can be expressed with the help of Heaviside function*

$$f(t) = 2[1 - u(t - 1)] + \frac{1}{2}t^2 \left[ u(t - 1) - u\left(t - \frac{1}{2}\pi\right) \right] \\ + (\cos t) u\left(t - \frac{1}{2}\pi\right).$$

## Example

### Solution

#### Step 2

For each term in  $f(t)$ , we need to write it in the form  $f(t - \alpha)u(t - \alpha)$ .

$$\mathcal{L}[2[1 - u(t - 1)]] = 2\mathcal{L}[1] - 2\mathcal{L}[u(t - 1)] = \frac{2}{s} - \frac{2}{s}e^{-s},$$

$$\begin{aligned}\mathcal{L}\left[\frac{1}{2}t^2u(t - 1)\right] &= \mathcal{L}\left[\left[\frac{1}{2}(t - 1)^2 + (t - 1) + \frac{1}{2}\right]u(t - 1)\right] \\ &= \left(\frac{1}{s^3} + \frac{1}{s^2} + \frac{1}{2s}\right)e^{-s},\end{aligned}$$

## Example

### Solution

#### Step 2

$$\begin{aligned} -\mathcal{L}\left[\frac{1}{2}t^2 u\left(t - \frac{1}{2}\pi\right)\right] &= -\mathcal{L}\left[\left[\frac{1}{2}\left(t - \frac{1}{2}\pi\right)^2 + \frac{\pi}{2}\left(t - \frac{\pi}{2}\right) + \frac{\pi^2}{8}\right]\right. \\ &\quad \left.\times u\left(t - \frac{1}{2}\pi\right)\right] \\ &= -\left(\frac{1}{s^3} + \frac{\pi}{2s^2} + \frac{\pi^2}{8s}\right)e^{-\frac{\pi s}{2}}, \end{aligned}$$

## Example

### Solution

#### Step 2

$$\begin{aligned}\mathcal{L}\left[(\cos t)u\left(t - \frac{1}{2}\pi\right)\right] &= \mathcal{L}\left[-\sin\left(t - \frac{1}{2}\pi\right)u\left(t - \frac{1}{2}\pi\right)\right] \\ &= -\frac{1}{s^2 + 1}e^{-\frac{\pi s}{2}}.\end{aligned}$$

*The solution is the summation of all the terms.*

$$\begin{aligned}\mathcal{L}[f] &= \frac{2}{s} - \frac{2}{s}e^{-s} + \left(\frac{1}{s^3} + \frac{1}{s^2} + \frac{1}{2s}\right)e^{-s} \\ &\quad - \left(\frac{1}{s^3} + \frac{\pi}{2s^2} + \frac{\pi^2}{8s}\right)e^{-\frac{\pi s}{2}} - \frac{1}{s^2 + 1}e^{-\frac{\pi s}{2}}\end{aligned}$$



### Example

*Find the inverse transform for*

$$F(s) = \frac{e^{-s}}{s^2 + \pi^2} + \frac{e^{-2s}}{s^2 + \pi^2} + \frac{e^{-3s}}{(s+2)^2}.$$

## Example

### Solution

*Without the exponential term, the inverse transform for the three terms are  $\sin \pi t / \pi$ ,  $\sin \pi t / \pi$ , and  $te^{-2t}$ , where we use the  $s$ -shifting theorem for the last term. Hence, by the  $t$ -shifting theorem, we have*

$$f(t) = \frac{1}{\pi} \sin [\pi(t-1)]u(t-1) + \frac{1}{\pi} \sin [\pi(t-2)]u(t-2) \\ + (t-3)e^{-2(t-3)}u(t-3).$$

## Laplace Transform of Derivatives

Laplace transform is a crucial tool for solving ODE, and in order to use it, we need to consider Laplace transform for the derivatives.

### Theorem

*Let  $f(t)$ ,  $f'(t)$ ,  $\dots$ ,  $f^{(n-1)}(t)$  are continuous for  $t \geq 0$  and satisfy the growth restriction condition*

$$\left| f^{(i)}(t) \right| \leq M_i e^{k_i t}, \quad \text{for } i = 0, 1, \dots, n-1,$$

*where  $M_i$  and  $k_i$  are some constants. If  $f^{(n)}(t)$  is piecewise continuous on  $t \geq 0$ , then the transform for  $f^{(n)}(t)$  satisfies*

$$\mathcal{L}[f^{(n)}](s) = s^n \mathcal{L}[f] - s^{n-1}f(0) - s^{n-2}f'(0) - \dots - f^{(n-1)}(0).$$

# Laplace Transform of Derivatives

## Theorem

*In particular, for  $n = 1$  and  $n = 2$ ,*

$$\mathcal{L}[f'] = s\mathcal{L}[f] - f(0), \quad (3.1)$$

$$\mathcal{L}[f''] = s^2\mathcal{L}[f] - sf(0) - f'(0). \quad (3.2)$$

## Laplace Transform of Derivatives

### Proof.

We first prove eq. (3.1) by assuming  $f'(t)$  is **continuous** for  $t \geq 0$ .

$$\begin{aligned}\mathcal{L}[f'] &= \int_0^{\infty} e^{-st} f'(t) dt = [e^{-st} f(t)]_0^{\infty} + s \int_0^{\infty} e^{-st} f(t) dt. \\ &= 0 - f(0) + s\mathcal{L}[f] = s\mathcal{L}[f] - f(0).\end{aligned}$$



The proof can be easily generalized to the case that  $f'(t)$  is only piecewise continuous. In this case the interval of integration need to be broken into finitely many intervals where  $f'(t)$  is continuous in each of them.

## Laplace Transform of Derivatives

### Proof.

The proof of eq. (3.2) follows eq. (3.2).

$$\begin{aligned}\mathcal{L}[f''] &= s\mathcal{L}[f'] - f'(0) = s[s\mathcal{L}[f] - f(0)] - f'(0) \\ &= s^2\mathcal{L}[f] - sf(0) - f'(0).\end{aligned}$$

The proof can be easily generalized to the case  $n = n$  by mathematical induction, and thus

$$\mathcal{L}[f^{(n)}](s) = s^n\mathcal{L}[f] - s^{n-1}f(0) - s^{n-2}f'(0) - \dots - f^{(n-1)}(0).$$



## Laplace Transform of Integrals

The derivatives and integrals (antiderivatives) are inverse operations, and we can easily derive the Laplace transform of integral of a function.

### Theorem

*Let  $F(s)$  denotes the Laplace transform of a function  $f(t)$ . By definition,  $f(t)$  has to be piecewise continuous for  $t \geq 0$  and satisfies growth restriction  $|f(t)| \leq Me^{kt}$ . Then, for  $s > k > 0$  and  $t > 0$ ,*

$$\mathcal{L}\left[\int_0^t f(\tau)d\tau\right] = \frac{1}{s}F(s), \quad \text{or,} \quad \int_0^t f(\tau)d\tau = \mathcal{L}^{-1}\left[\frac{1}{s}F(s)\right].$$

## Laplace Transform of Integrals

Proof.

Let  $g(t) \equiv \int_0^t f(\tau) d\tau$ . By the assumption that  $f(t)$  is piecewise continuous,  $g(t)$  is continuous. Therefore,

$$\begin{aligned} |g(t)| &= \left| \int_0^t f(\tau) d\tau \right| \leq \int_0^t |f(\tau)| d\tau \\ &\leq \int_0^t M e^{k\tau} d\tau = \frac{M}{k} e^{k\tau} \Big|_0^t < \frac{M}{k} e^{kt}, \end{aligned}$$

and this shows that  $g(t)$  satisfies the growth restriction.



## Laplace Transform of Integrals

### Proof.

Now, since  $g(t)$  is continuous and satisfies the growth restriction, and  $g'(t) = f(t)$ , which is piecewise continuous, we can use eq. (3.1) and find

$$\mathcal{L}[f] = \mathcal{L}[g'] = s\mathcal{L}[g] - g(0) = s\mathcal{L}[g].$$

For the last equality we used the fact that  $g(0) = 0$ . We can rewrite the equation with the definition of  $F(s)$  and  $g(t)$ , and finally reach

$$F(s) = s\mathcal{L}\left[\int_0^t f(\tau)d\tau\right], \quad \text{or,} \quad \mathcal{L}\left[\int_0^t f(\tau)d\tau\right] = \frac{1}{s}F(s).$$

The idea of using Laplace transform to solve nonhomogeneous linear ODEs is as follows. Consider the following initial value problem

$$y'' + ay' + by = r(t) \quad y(0) = K_0, \quad y'(0) = K_1,$$

where  $a, b, K_0, K_1$  are constants.

To solve this problem with Laplace transform, there are three steps.

**Step 1:** We first transform the ODE into functions of  $s$ :

$$\begin{aligned} [s^2 Y - sy(0) - y'(0)] + a[sY - y(0)] + bY &= R(s), \\ \Rightarrow (s^2 + as + b)Y &= (sK_0 + K_1 + aK_0) + R(s). \end{aligned}$$

**Step 2:** Then we solve  $Y(s)$  by

$$Y(s) = [(s + a)K_0 + K_1] Q(s) + Q(s)R(s),$$

where  $R(s) = \mathcal{L}[r(t)]$ , and

$$Q(s) \equiv \frac{1}{s^2 + as + b} = \frac{1}{\left(s + \frac{1}{2}a\right)^2 + b - \frac{1}{4}a^2}.$$

**Step 3:** After finding  $Y(s)$ , the solution can be found by inverse transform

$$y(t) = \mathcal{L}^{-1}[(s + a)K_0 + K_1] Q(s) + \mathcal{L}^{-1}[Q(s)R(s)].$$

Notice that in general the last term is not easy to be solved, and we will introduce the so-called **convolution** to deal with it later.

## Shifted Data Problem

### Example

*Using Laplace transform to solve the following ODE*

$$y'' + y = 2t, \quad y\left(\frac{\pi}{4}\right) = \frac{\pi}{2}, \quad y'\left(\frac{\pi}{4}\right) = 2 - \sqrt{2}.$$

### Example

*Solution: This is an ODE with initial conditions given at  $t = t_0 > 0$ . In order to use Laplace transform, we need to set  $t = \tilde{t} + t_0$ , and the initial conditions happen at  $\tilde{t} = 0$ .*

## Shifted Data Problem

### Example

*Solution: With  $t_0 = \frac{1}{4}\pi$ , the problem becomes*

$$\tilde{y}''(t) + \tilde{y} = 2 \left( \tilde{t} + \frac{1}{4}\pi \right), \quad \tilde{y}(0) = \frac{1}{2}\pi, \quad \tilde{y}'(0) = 2 - \sqrt{2}.$$

*The Laplace transform becomes*

$$\begin{aligned} s^2 \tilde{Y} - s \cdot \frac{1}{2}\pi - (2 - \sqrt{2}) + \tilde{Y} &= \frac{2}{s^2} + \frac{\frac{1}{2}\pi}{s} \\ \Rightarrow \tilde{Y} &= \frac{2}{(s^2 + 1)s^2} + \frac{\frac{1}{2}\pi}{(s^2 + 1)s} + \frac{\frac{1}{2}\pi s}{(s^2 + 1)} + \frac{(2 - \sqrt{2})}{(s^2 + 1)} \end{aligned}$$

## Shifted Data Problem

### Example

*Solution: By using Laplace transform of integral, we know*

$$\mathcal{L}^{-1}\left[\frac{1}{s^2 + 1}\right] = \sin t,$$

$$\mathcal{L}^{-1}\left[\frac{1}{s(s^2 + 1)}\right] = \int_0^t \sin \tau d\tau = (1 - \cos t)$$

$$\mathcal{L}^{-1}\left[\frac{1}{s^2(s^2 + 1)}\right] = \int_0^t (1 - \cos \tau) d\tau = t - \sin t.$$

## Shifted Data Problem

### Example

*Solution: Therefore*

$$\begin{aligned}\tilde{y} &= 2(\tilde{t} - \sin \tilde{t}) + \frac{1}{2}\pi(1 - \cos \tilde{t}) + \frac{1}{2}\pi \cos \tilde{t} + (2 - \sqrt{2})\sin \tilde{t} \\ &= 2\tilde{t} + \frac{1}{2}\pi - \sqrt{2}\sin \tilde{t},\end{aligned}$$

*therefore*

$$y = 2t - \sqrt{2}\sin\left(t - \frac{1}{4}\pi\right) = 2t - \sin t + \cos t.$$

## Dirac's Delta Function

In engineering, we often faced with problem of describing a quantity that is zero everywhere except at a single point (e.g. short impulses), while at that point it is infinite, the integral over any interval containing that point has a finite value. For this purpose, we need to introduce Dirac's delta function.

### Definition

*Dirac's delta function  $\delta(x - c)$  is defined as follows*

$$\delta(x - c) = \begin{cases} \infty, & x = c, \\ 0, & \text{otherwise} \end{cases}$$

$$f(c) = \int_a^b f(x)\delta(x - c)dx, \quad \text{for } c \in (a, b).$$



# Dirac's Delta Function

## Definition

*In particular, if we let  $f(x) = 1$ , we will have*

$$\int_a^b \delta(x - c) dx = 1, \quad \text{for } c \in (a, b),$$

or

$$\int_{-\infty}^{\infty} \delta(x - c) dx = 1.$$

The only problem is that **no such function exists!**

## Dirac's Delta Function

In practical, we can approximate Dirac's delta function as the limit of a sequence of functions, a distribution.

### Remark

$$f_k(t - a) = \begin{cases} \frac{1}{k} & \text{if } a \leq t \leq a + k \\ 0 & \text{otherwise,} \end{cases}$$

*one can check for any  $k$ , the integral of  $f_k$  equals to one if the region  $(a, a + k)$  is in the integral interval. We thus have*

$$\delta(t - a) = \lim_{k \rightarrow 0} f_k(t - a),$$

*which satisfies all the property of the delta function.*

# Dirac's Delta Function

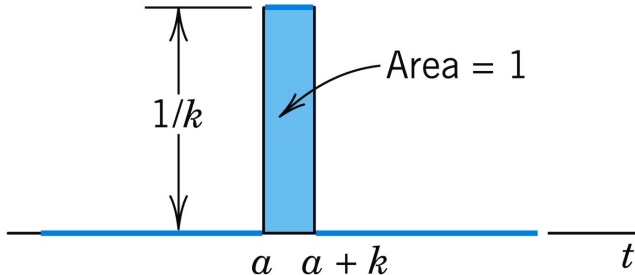


Figure:  $f_k(t-a)$

## Dirac's Delta Function

The Laplace transform of  $\delta(t - a)$  can be obtained with the help of Heaviside function.

### Claim

$$\mathcal{L}[\delta(t - a)] = e^{-as}$$

### Proof.

We first express the function  $f_k(t - a)$  as follows:

$$f_k(t - a) = \frac{1}{k} [u(t - a) - u(t - (a + k))].$$

## Dirac's Delta Function

Proof.

By definition

$$\begin{aligned}\mathcal{L}[\delta(t-a)] &= \mathcal{L}\left[\lim_{k \rightarrow 0} f_k(t-a)\right] = \lim_{k \rightarrow 0} \mathcal{L}[f_k(t-a)] \\ &= \lim_{k \rightarrow 0} \frac{1}{k} \left[ \frac{e^{-as}}{s} - \frac{e^{-(a+k)s}}{s} \right] = \lim_{k \rightarrow 0} \frac{e^{-as} - e^{-(a+k)s}}{ks} \\ &= e^{-as}.\end{aligned}$$



## Example

*Solve the following ODE*

$$y'' + 3y' + 2y = \delta(t - 1), \quad y(0) = 0, \quad y'(0) = 0.$$

## Example

*Solution:*

*The Laplace transform of the equation is*

$$\begin{aligned} s^2 Y + 3sY + 2Y &= e^{-s} \\ \Rightarrow Y &= \frac{e^{-s}}{(s+1)(s+2)} = \left( \frac{1}{s+1} - \frac{1}{s+2} \right) e^{-s} \end{aligned}$$

## Example

*Solution:*

*Therefore*

$$\begin{aligned}y &= \mathcal{L}^{-1}\left[\frac{1}{(s+1)}e^{-s}\right] - \mathcal{L}^{-1}\left[\frac{1}{(s+2)}e^{-s}\right] \\ \Rightarrow y &= e^{-(t-1)}u(t-1) - e^{-2(t-1)}u(t-1).\end{aligned}$$

## More on Partial Functions

### Remark

*If  $g(x)$ ,  $h(x)$  are polynomials, with  $g(x)$  of lower degree than  $h(x)$ , by fundamental theorem of algebra, we can write  $h(x)$  as*

$$h(x) = c(x - \alpha_1)^{a_1} \cdots (x - \alpha_k)^{a_k} \times \\ \left[ (x - \beta_1)^2 + \gamma_1^2 \right]^{b_1} \cdots \left[ (x - \beta_l)^2 + \gamma_l^2 \right]^{b_l},$$

*with real constants  $\alpha$ ,  $\beta$ ,  $\gamma$ , and integers constants  $a$ ,  $b$ .*



## More on Partial Functions

### Remark

*The function  $g(x)/h(x)$  can be written in the form*

$$\frac{g(x)}{h(x)} = \sum_{i=1}^k \sum_{j=1}^{a_i} \frac{A_{ij}}{(x - \alpha_i)^j} + \sum_{i=1}^l \sum_{j=1}^{b_i} \frac{B_{ij}x + C_{ij}}{\left[(x - \beta_i)^2 + \gamma_i^2\right]^j},$$

*with unique set of real constants  $A_{ij}$ ,  $B_{ij}$ ,  $C_{ij}$ .*

# Bibliography

- 1 *Kreyszig, E. Advanced Engineering Mathematics*. Wiley, 10th Edition.