



EEE204 Continuous and Discrete Time Signals and Systems II

2018–2019 Semester 2

Electrical and Electronic Engineering

Xi'an Jiaotong-Liverpool University

Week 5

Causality, memory, stability and LTI?



Xi'an Jiaotong-Liverpool University

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Causality, memory, stability and LTI?



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Causality, memory, stability and LTI?



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Causality, memory, stability and LTI?



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Discrete-time(DT) LTI Systems

We know

$$\begin{aligned}y[n] &= T\{x[n]\}, \\&= T\left\{\sum_{k=-\infty}^{+\infty} x[k]\delta[n-k]\right\}, \text{ Slide 28 of Week 1} \\&= \sum_{k=-\infty}^{+\infty} x[k] \cdot T\{\delta[n-k]\}, \\&= \sum_{k=-\infty}^{+\infty} x[k]h[n-k], \text{ Assume } T\{\cdot\} \text{ is LTI} \\&= x[n] * h[n]. \text{ } h[n] \text{ is called the impulse response}\end{aligned}$$

- $$y[n] = x[n] * h[n] = \sum_{k=-\infty}^{+\infty} x[k]h[n-k]$$

is referred to as the **convolution sum**.

- Given $h[n]$, it is possible to calculate the output $y[n]$ due to any input $x[n]$ using the **convolution sum**
- An LTI system is **completely characterised** by its impulse response $h[n]$.



$$y[n] = x[n] * h[n]$$

What is the expression for $y[n - n_0]$?

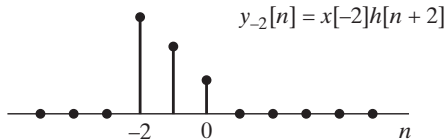
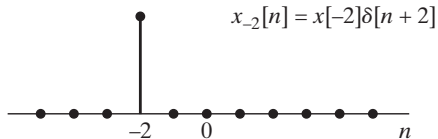
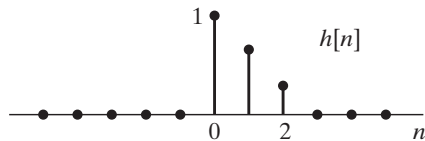
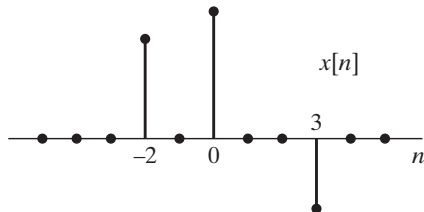
$$y[n] = x[n] * h[n]$$

- $y[n] = x[n] * h[n]$ is shorthand notation for $\sum_{k=-\infty}^{+\infty} x[k]h[n-k]$ and any use of the shorthand form should be referred back to the full expression of convolution sum.
- Blindly trying the substitution or any other transformation may lead to wrong answers.

Example

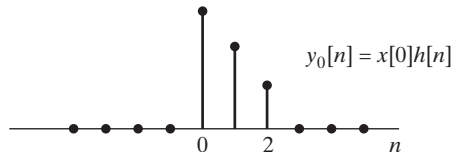
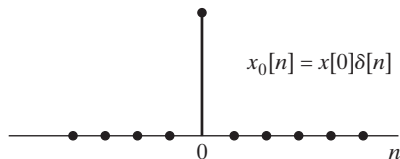
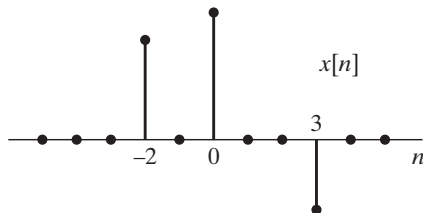


Graphical Approach I

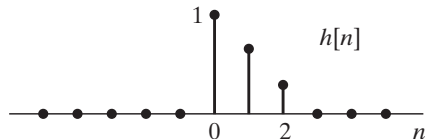
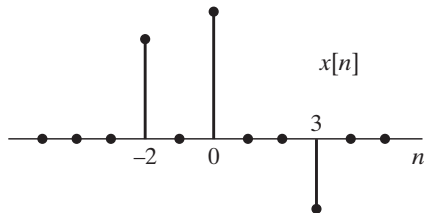


Example

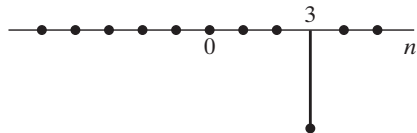
Graphical Approach I



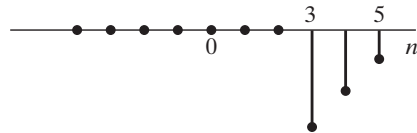
Graphical Approach I



$$x_3[n] = x[3]\delta[n - 3]$$

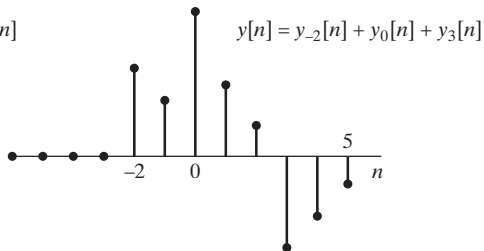
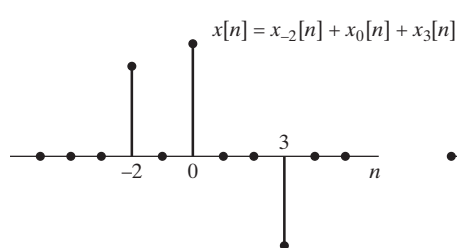
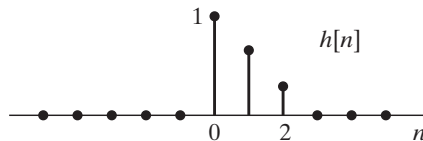
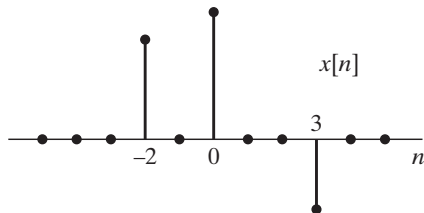


$$y_3[n] = x[3]h[n - 3]$$



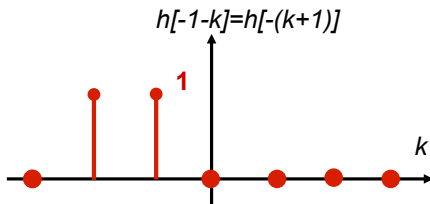
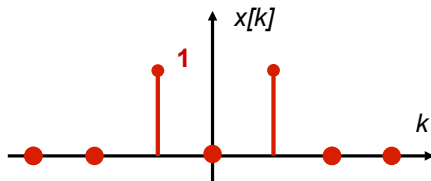
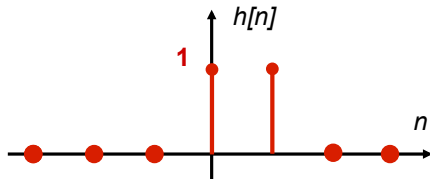
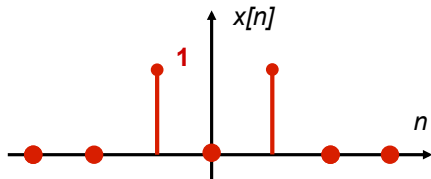
Example

Graphical Approach I



Example

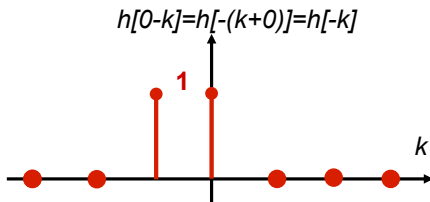
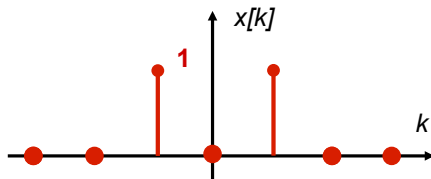
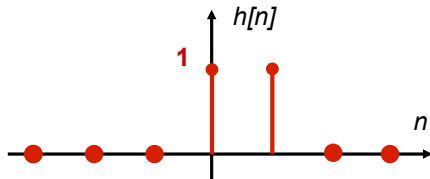
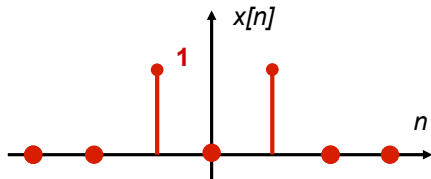
Graphical Approach II



$$y[-1] = 1$$

Example

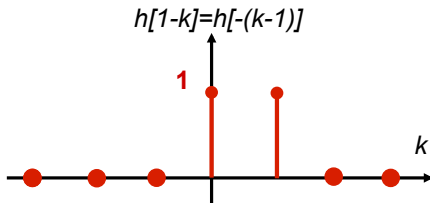
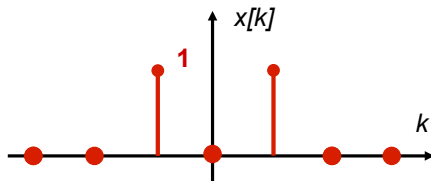
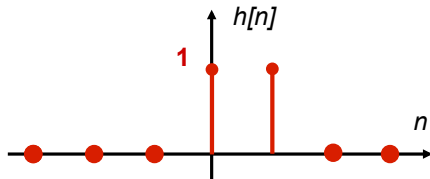
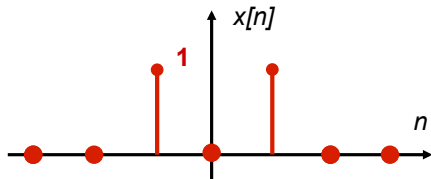
Graphical Approach II



$$y[0] = 1$$

Example

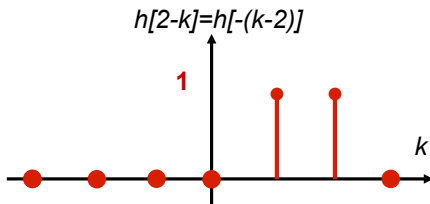
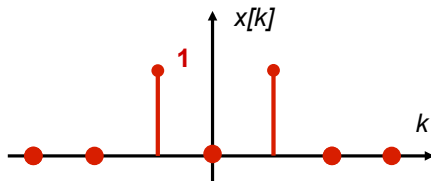
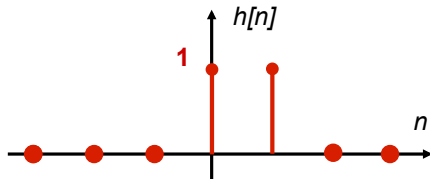
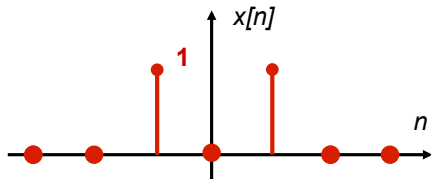
Graphical Approach II



$$y[1] = 1$$

Example

Graphical Approach II

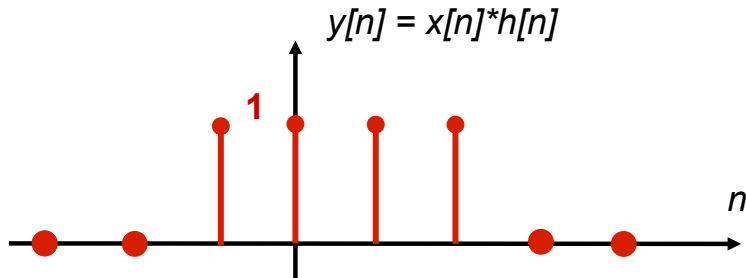
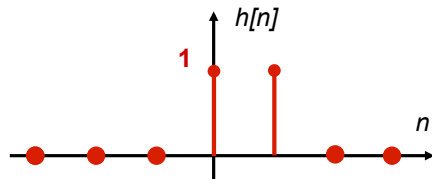
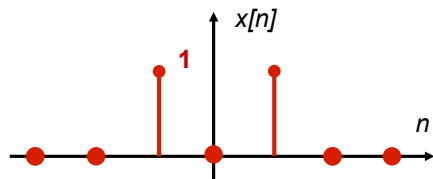


$$y[2] = 1$$

Example



Graphical Approach II



$$y[n] = u[n + 1] - u[n - 3]$$

Analytical Approach

Consider a system with impulse response

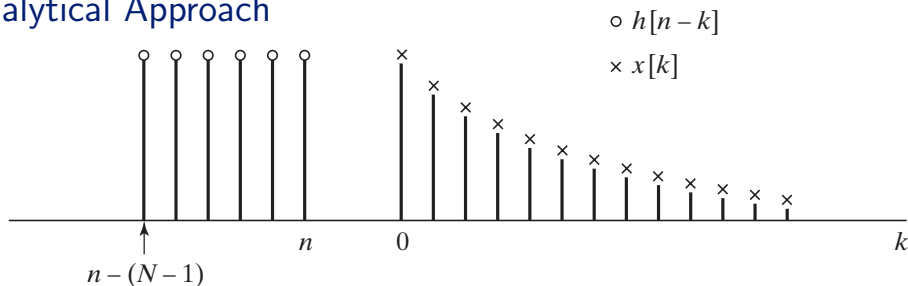
$$h[n] = u[n] - u[n - N].$$

The input is

$$x[n] = a^n u[n].$$

Find the output $y[n]$ at a particular index n .

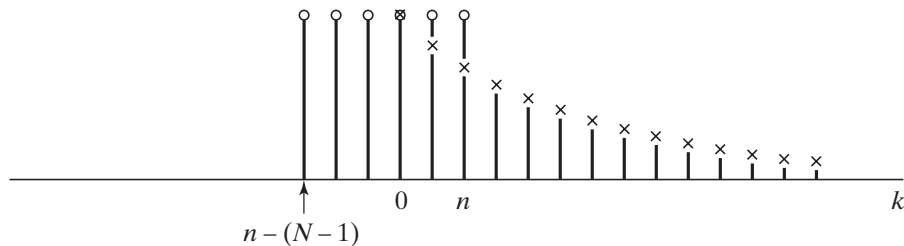
Analytical Approach



All negative values of n give a similar picture; i.e., the nonzero portions of the sequences $x[k]$ and $h[n-k]$ do not overlap, so

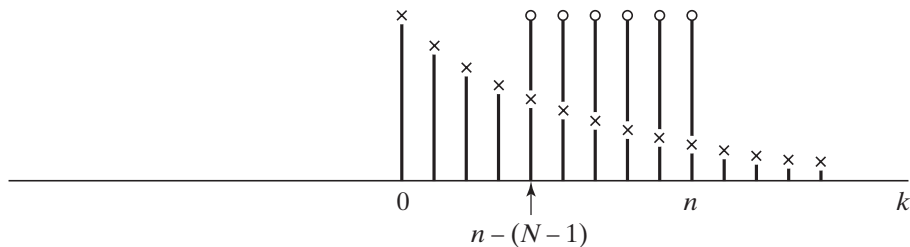
$$y[n] = 0, \text{ for } n < 0.$$

Analytical Approach



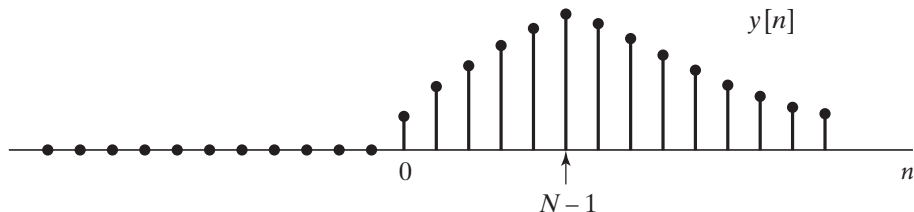
$$\begin{aligned}
 y[n] &= \sum_{k=0}^n x[k]h[n-k], \\
 &= \sum_{k=0}^n a^k = \frac{1 - a^{n+1}}{1 - a}, \text{ for } 0 \leq n \leq N - 1.
 \end{aligned}$$

Analytical Approach



$$\begin{aligned} y[n] &= \sum_{k=n-N+1}^n x[k]h[n-k], \\ &= \sum_{k=n-N+1}^n a^k = \frac{a^{n-N+1}(1-a^N)}{1-a}, \text{ for } n > N-1. \end{aligned}$$

Analytical Approach



$$y[n] = \begin{cases} 0, & n < 0, \\ \frac{1 - a^{n+1}}{1 - a}, & 0 \leq n \leq N - 1, \\ \frac{a^{n-N+1}(1 - a^N)}{1 - a}, & n > N - 1. \end{cases}$$



- Page 74–90, 103–116 read section 2.0–2.1, 2.3;
- Page 137, Q2.1: (a)–(c);
- Page 138, Q2.2;
- Page 138, Q2.3;
- Page 138, Q2.4;
- Page 138, Q2.5;
- Page 138, Q2.6;
- Page 138–139, Q2.7: (a)–(d).

Thank you for your
attention.