

EEE205 – Digital Electronics (II)

Lecture 11

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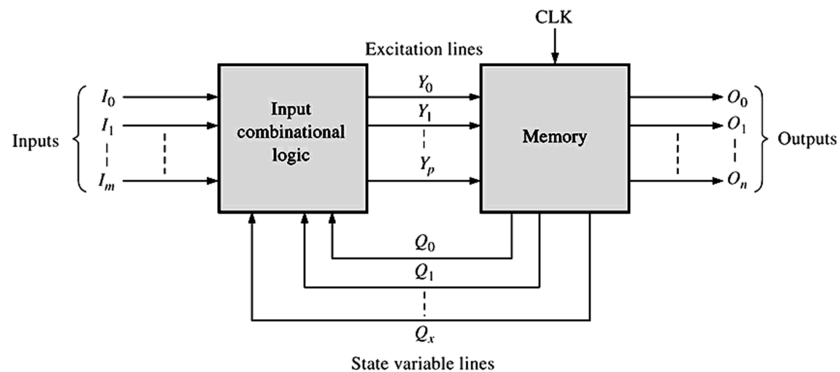
In This Session

- Design of Synchronous Counters

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General Model of Sequential Circuits

- A sequential circuit consists of a combinational logic section and a memory section (flip-flops).
- To design a sequential circuit (**state machine**) is to decide the combinational logic.

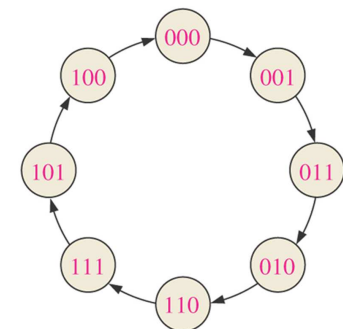


Design of Synchronous Counters

Step 1: State Diagram

- A **state diagram** shows the progression of states when the counter is clocked.

Example: a 3-bit **Gray code counter**, which exhibits only a single bit change from one code number to the next.



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Design of Synchronous Counters

Step 2: Next-State Table

- A **next-state table** lists the present state along with the corresponding next state of the counter.

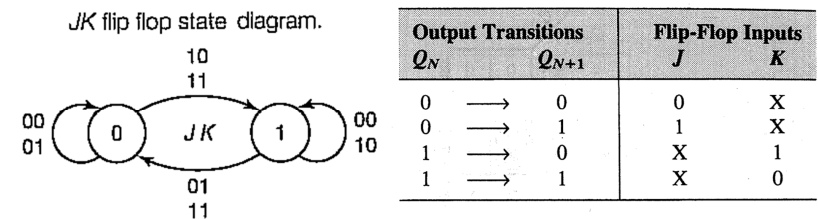
Present State			Next State		
Q_2	Q_1	Q_0	Q_2	Q_1	Q_0
0	0	0	0	0	1
0	0	1	0	1	1
0	1	1	0	1	0
0	1	0	1	1	0
1	1	0	1	1	1
1	1	1	1	0	1
1	0	1	1	0	0
1	0	0	0	0	0

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Design of Synchronous Counters

Step 3: Flip-Flop Transition Table

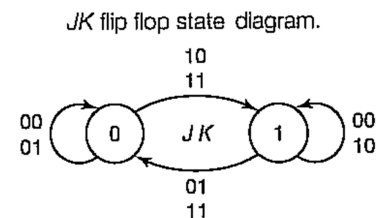
- A transition table lists all possible output transitions and the corresponding inputs.



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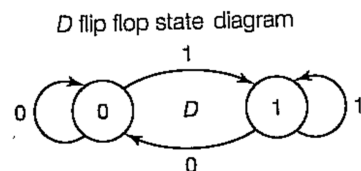
Design of Synchronous Counters

More flip-flop transition tables (q^* for next states)



JK flip flop design table.

q	q^*	J	K
0	0	0	X
0	1	1	X
1	0	X	1
1	1	X	0



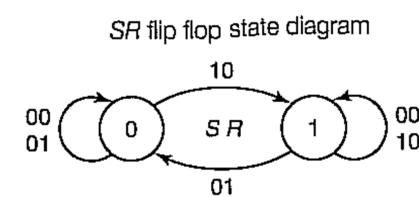
D flip flop design table.

q	q^*	D
0	0	0
0	1	1
1	0	0
1	1	1

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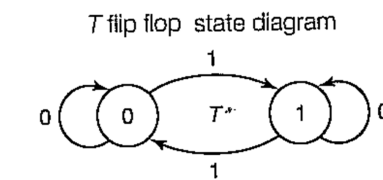
Design of Synchronous Counters

More flip-flop transition tables (q^* for next states)



SR flip flop design table

q	q^*	S	R
0	0	0	X
0	1	1	0
1	0	0	1
1	1	X	0



T flip flop design table

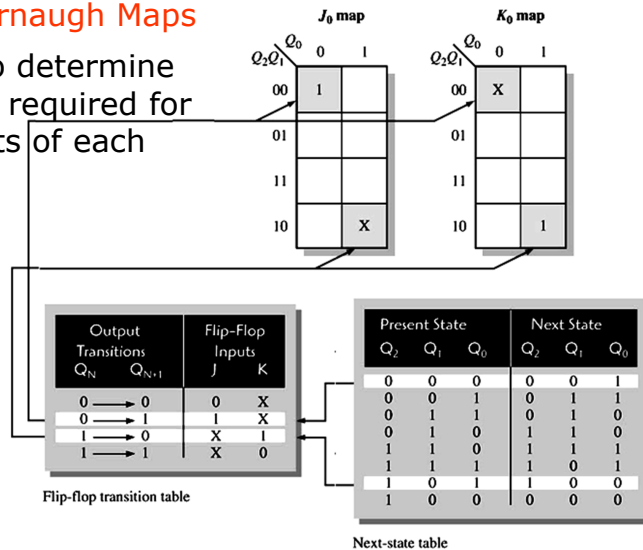
q	q^*	T
0	0	0
0	1	1
1	0	1
1	1	0

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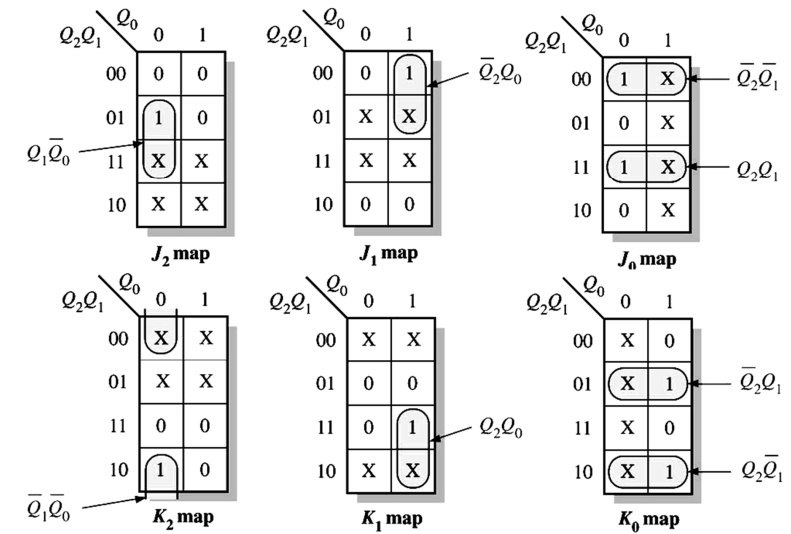
Design of Synchronous Counters

Step 4: Karnaugh Maps

- This is to determine the logic required for the inputs of each flip-flop.



Design of Synchronous Counters



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Design of Synchronous Counters

Step 5: Logic Expressions for Flip-Flop Inputs

$$J_0 = Q_2 Q_1 + \overline{Q_2} \overline{Q_1} = \overline{Q_2 \oplus Q_1}$$

$$K_0 = Q_2 \overline{Q_1} + \overline{Q_2} Q_1 = Q_2 \oplus Q_1$$

$$J_1 = \overline{Q_2} Q_0$$

$$K_1 = Q_2 Q_0$$

$$J_2 = Q_1 \overline{Q_0}$$

$$K_2 = \overline{Q_1} \overline{Q_0}$$

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Design of Synchronous Counters

Step 6: Counter Implementation

$$J_0 = Q_2 Q_1 + \overline{Q_2} \overline{Q_1} = \overline{Q_2 \oplus Q_1}$$

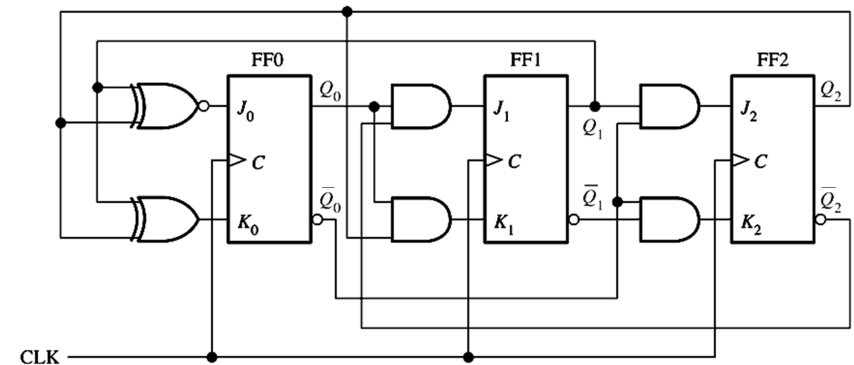
$$K_0 = Q_2 \overline{Q_1} + \overline{Q_2} Q_1 = Q_2 \oplus Q_1$$

$$J_1 = \overline{Q_2} Q_0$$

$$K_1 = Q_2 Q_0$$

$$J_2 = Q_1 \overline{Q_0}$$

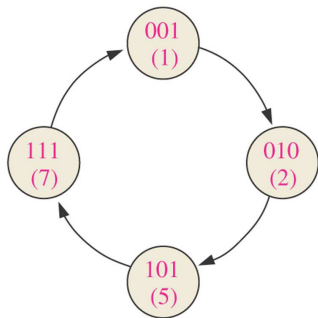
$$K_2 = \overline{Q_1} \overline{Q_0}$$



Design of Synchronous Counters

Example: Design a counter with **missing states**, as shown in the state diagram. Use J-K flip-flops.

State Diagram



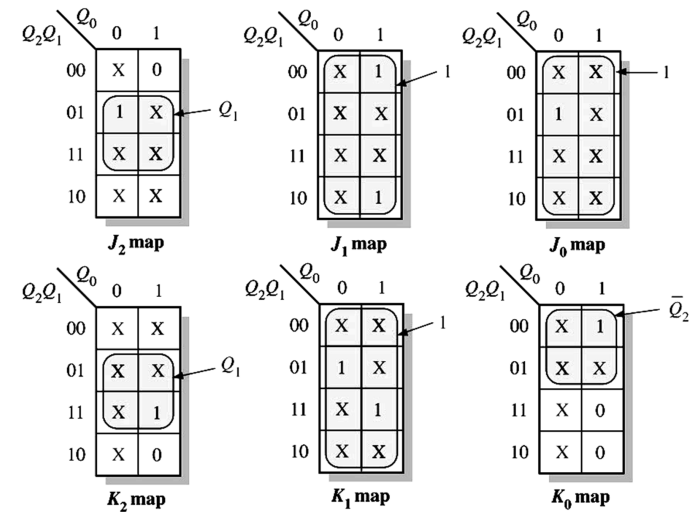
Next-State Table

Present State			Next State		
Q_2	Q_1	Q_0	Q_2	Q_1	Q_0
0	0	1	0	1	0
0	1	0	1	0	1
1	0	1	1	1	1
1	1	1	0	0	1

The next state for an invalid state (0, 3, 4 or 6) is "don't care". The J and K inputs are also "don't cares"

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Design of Synchronous Counters



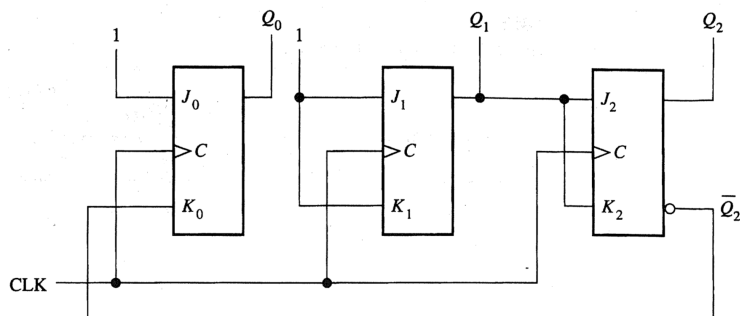
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Design of Synchronous Counters

$$J_0 = 1, K_0 = \bar{Q}_2$$

$$J_1 = K_1 = 1$$

$$J_2 = K_2 = Q_1$$



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Design of Synchronous Counters

Example: Design a 3-bit up/down counter. Use J-K flip-flops.

x	C	B	A	C^*	B^*	A^*
0	0	0	0	0	0	1
0	0	0	1	0	1	0
0	0	1	0	0	1	1
0	0	1	1	1	0	0
0	1	0	0	1	0	1
0	1	0	1	1	1	0
0	1	1	0	1	1	1
0	1	1	1	0	0	0
1	0	0	0	1	1	1
1	0	0	1	0	0	0
1	0	1	0	0	0	1
1	0	1	1	0	1	0
1	1	0	0	0	1	1
1	1	0	1	1	0	0
1	1	1	0	1	0	1
1	1	1	1	1	1	0

x is up/down control, 0 for up and 1 for down.

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Design of Synchronous Counters

BA \ xC	00	01	11	10
00			1	
01	X	X	X	X
11	X	X	X	X
10	1			

J_C

$$J_C = K_C = x'BA + xB'A'$$

BA \ xC	00	01	11	10
00	X	X	X	X
01			1	
11	1			
10	X	X	X	X

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Design of Synchronous Counters

BA \ xC	00	01	11	10
00		1	X	X
01		1	X	X
11	1		X	X
10	1		X	X

J_B

$$J_B = K_B = x'A + xA'$$

BA \ xC	00	01	11	10
00	X	X	1	
01	X	X	1	
11	X	X		1
10	X	X		1

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Design of Synchronous Counters

BA \ xC	00	01	11	10
00	1	X	X	1
01	1	X	X	1
11	1	X	X	1
10	1	X	X	1

J_A

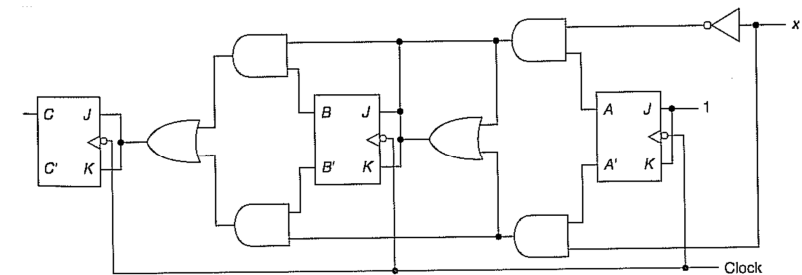
$$J_A = K_A = 1$$

BA \ xC	00	01	11	10
00	X	1	1	X
01	X	1	1	X
11	X	1	1	X
10	X	1	1	X

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Design of Synchronous Counters

3-bit up/down counter



$$J_C = K_C = x'BA + xB'A'$$

$$J_B = K_B = x'A + xA'$$

$$J_A = K_A = 1$$