

EEE204 Continuous and Discrete Time Signals and Systems II

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Electrical and Electronic Engineering
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Week 7

Find z-transform of the DT Signal



$$x_1[k] = \begin{cases} 1, & k = 10, 11 \\ 2, & k = 12, 15 \\ 0, & \text{otherwise.} \end{cases}$$
$$-\delta[k-10] + \delta[k-1]$$

$$= \delta[k - 10] + \delta[k - 11] + 2\delta[k - 12] + 2\delta[k - 15].$$

$$X_{1}(z) = \sum_{k=-\infty}^{+\infty} x_{1}[k]z^{-k} = \sum_{k=-\infty}^{+\infty} (\delta[k-10] + \delta[k-11] + 2\delta[k-12] + 2\delta[k-15])z^{-k},$$

= $z^{-10} + z^{-11} + 2z^{-12} + 2z^{-15}.$

The ROC is $\mathbb{C} - \{0\}$.

Find z-transform of the DT Signal



 $x_2[k] = 3^{-k+2}u[k] + \sum_{m=1}^4 m\delta[k-m]$

$$X_{2}(z) = \sum_{k=-\infty}^{+\infty} \left(3^{-k+2}u[k] + \sum_{m=1}^{4} m\delta[k-m] \right) z^{-k},$$

$$= \sum_{k=0}^{+\infty} 3^{-k+2}z^{-k} + \sum_{k=-\infty}^{+\infty} (\delta[k-1] + 2\delta[k-2] + 3\delta[k-3] + 4\delta[k-4])z^{-k},$$

$$= 9 \sum_{k=0}^{+\infty} (3z)^{-k} + z^{-1} + 2z^{-2} + 3z^{-3} + 4z^{-4},$$

Find z-transform of the DT Signal



 $x_2[k] = 3^{-k+2}u[k] + \sum_{m=1}^4 m\delta[k-m]$

$$=9\sum_{k=0}^{+\infty} (3z)^{-k} + z^{-1} + 2z^{-2} + 3z^{-3} + 4z^{-4},$$

$$=\frac{9}{1-(3z)^{-1}} + z^{-1} + 2z^{-2} + 3z^{-3} + 4z^{-4}.$$

The ROC is $|(3z)^{-1}| < 1 \cap |z| \neq 0$, which can be simplified to $|z| > \frac{1}{2}$.

$$Z(a^nu[n])=rac{z}{z-a}$$
 and the ROC is $|z|>$

|a|, the exterior of circle.

$$Z(-a^nu[-n-1]) = \frac{z}{z-a}$$
 and the ROC is

|z| < |a|, the interior of circle.

What is the general shape?

The ROC is always an annulus, i.e., $\{r_2 < |z| < r_1\}$.

Note that r_2 can be zero (possibly with \leq) and r_1 can be ∞ (possibly with \leq).



Explanation. Let
$$z=re^{j\theta}$$
 be polar form
$$|X(z)|=\left|\sum_{n=-\infty}^{+\infty}x[n]z^{-n}\right|,$$

$$\leq \sum_{n=-\infty}^{\infty} |x[n]||z|^{-n} = \sum_{n=-\infty}^{\infty} |x[n]|r^{-n},$$

$$= \sum_{n=-\infty}^{-1} |x[n]| r^{-n} + \sum_{n=0}^{+\infty} |x[n]| r^{-n},$$

 $=\sum_{n=0}^{+\infty} |x[-n]|r^n + \sum_{n=0}^{+\infty} \frac{|x[n]|}{r^n}.$

More on ROC



$$|X(z)| = \sum_{n=1}^{+\infty} |x[-n]| r^n + \sum_{n=0}^{+\infty} \frac{|x[n]|}{r^n}$$

The ROC is the subset of \mathbb{C} where both of the above sums are finite.

If the right sum (the "causal part") is finite for some z_2 with magnitude $r_2 = |z_2|$, then that sum will also be finite for any z with magnitude $r \geqslant r_2$, since for such an r each term in the sum is smaller.

So the ROC for the right sum is the subset of \mathbb{C} for which $|z| > r_2$, for some r_2 , which is the exterior of some circle.

More on ROC



$$|X(z)| = \sum_{n=1}^{\infty} |x[-n]| r^n + \sum_{n=0}^{\infty} \frac{|x[n]|}{r^n}$$

The ROC is the subset of \mathbb{C} where both of the above sums are finite.

Likewise if the left sum (the "anti-causal part") is finite for some z_1 with magnitude $r_1 = |z_1|$, then that sum will also be finite for any z with magnitude $r \leq r_1$, since for such an r each term in the sum is smaller.

So the ROC for the left sum is the subset of \mathbb{C} for which $|z| < r_1$, for some r_1 , which is the interior of some circle.

More on ROC



$$|X(z)| = \sum_{n=1}^{\infty} |x[-n]| r^n + \sum_{n=0}^{\infty} \frac{|x[n]|}{r^n}$$

The ROC of a causal signal is the exterior of a circle of some radius r_2 .

The ROC of an anti-causal signal is the interior of a circle of some radius r_1 .

For a general signal x[n], the ROC will be the intersection of the ROC of its causal and non-causal parts, which is an annulus.

If $r_2 < r_1$, then that intersection is an annulus (nonempty). Otherwise the z-transform is undefined (does not exist).



Example of a signal with empty ROC

$$x[n] = 1 = u[n] + u[-n-1].$$

Recall
$$u[n] \stackrel{z}{\leftrightarrow} U(z) = \frac{z}{z-1}$$
, for $\{|z| > 1\}$,

$$u[-n-1] \stackrel{z}{\leftrightarrow} U'(z) = \frac{-z}{z-1}$$
, for $\{|z| < 1\}$,

ROC for the causal part is $\{|z|>1\}$, ROC for the anti-causal part is $\{|z|<1\}$. The z-transform does not exist.





Linearity

If $x_1[n] \stackrel{z}{\leftrightarrow} X_1(z)$ and $x_2[n] \stackrel{z}{\leftrightarrow} X_2(z)$ then

$$Z\{x[n]\} = Z\{a_1x_1[n] + a_2x_2[n]\},$$

= $a_1X_1(z) + a_2X_2(z).$

The ROC of the sum contains at least as much of the z-plane as the intersection of the two ROC's.



Linearity

Proof:

$$x[n] = a_1 x_1[n] + a_2 x_2[n] \stackrel{z}{\leftrightarrow} a_1 X_1(z) + a_2 X_2(z).$$

$$X(z) = \sum_{n = -\infty} x[n]z^{-n},$$

$$= \sum_{n=-\infty} (a_1 x_1[n] + a_2 x_2[n]) z^{-n},$$

$$= a_1 \sum_{n=-\infty}^{+\infty} x_1[n] z^{-n} + a_2 \sum_{n=-\infty}^{+\infty} x_2[n] z^{-n},$$

$$= a_1 X_1(z) + a_2 X_2(z).$$

$$x[n] = \cos(\omega_0 n + \phi)u[n]$$

$$X(z) = \sum_{n=-\infty}^{+\infty} x[n]z^{-n} = \sum_{n=-\infty}^{+\infty} [\cos(\omega_0 n + \phi)u[n]]z^{-n},$$

$$= \sum_{n=0}^{+\infty} [\cos(\omega_0 n + \phi)]z^{-n},$$

$$= \frac{1}{2}e^{j\phi} \sum_{n=0}^{+\infty} (e^{j\omega_0})^n z^{-n} + \frac{1}{2}e^{-j\phi} \sum_{n=0}^{+\infty} (e^{-j\omega_0})^n z^{-n},$$

$$= \frac{\frac{1}{2}e^{j\phi}}{1 - e^{j\omega_0}z^{-1}} + \frac{\frac{1}{2}e^{-j\phi}}{1 - e^{-j\omega_0}z^{-1}},$$

Example



$$x[n] = \cos(\omega_0 n + \phi)u[n]$$

$$X(z) = \frac{\frac{1}{2}e^{j\phi}}{1 - e^{j\omega_0}z^{-1}} + \frac{\frac{1}{2}e^{-j\phi}}{1 - e^{-j\omega_0}z^{-1}},$$

$$= \frac{\frac{1}{2}e^{j\phi}(1 - e^{-j\omega_0}z^{-1}) + \frac{1}{2}e^{-j\phi}(1 - e^{j\omega_0}z^{-1})}{(1 - e^{j\omega_0}z^{-1})(1 - e^{-j\omega_0}z^{-1})},$$

$$= \frac{\frac{1}{2}e^{j\phi} + \frac{1}{2}e^{-j\phi} - \frac{1}{2}e^{j\phi}e^{-j\omega_0}z^{-1} - \frac{1}{2}e^{-j\phi}e^{j\omega_0}z^{-1}}{1 - e^{j\omega_0}z^{-1} - e^{-j\omega_0}z^{-1} + z^{-2}},$$

$$= \frac{\cos\phi - z^{-1}\cos(\omega_0 - \phi)}{1 - 2z^{-1}\cos\omega_0 + z^{-2}}.$$

The ROC is $|e^{j\omega_0}z^{-1}|<1$ and $|e^{-j\omega_0}z^{-1}|<1$, which yields |z|>1.



Time Shifting

If
$$x[n] \overset{z}{\leftrightarrow} X(z)$$
, then
$$x[n-k] \overset{z}{\leftrightarrow} z^{-k} X(z).$$

The ROC is unchanged, except for adding or deleting
$$|z|=0$$
 or $|z|=\infty$.



Time Shifting

Proof: $x[n-k] \stackrel{z}{\leftrightarrow} z^{-k}X(z)$.

$$Z(x[n-k]) = \sum_{n=-\infty}^{+\infty} x[n-k]z^{-n},$$

$$\frac{m=n-k}{m=-\infty} \sum_{m=-\infty}^{+\infty} x[m]z^{-k-m},$$

$$= z^{-k} \sum_{m=-\infty}^{+\infty} x[m]z^{-m},$$

$$= z^{-k} X(z).$$



Scaling the z-domain

If
$$x[n] \stackrel{z}{\leftrightarrow} X(z)$$
 with ROC= $\{r_1 < |z| < r_2\}$, then

$$a^n x[n] \stackrel{z}{\leftrightarrow} X(a^{-1}z),$$

with ROC= {
$$|a|r_1 < |z| < |a|r_2$$
}.



Scaling the z-domain

Proof: $a^n x[n] \stackrel{z}{\leftrightarrow} X(a^{-1}z)$.

$$Z(a^{n}x[n]) = \sum_{n=-\infty}^{\infty} a^{n}x[n]z^{-n},$$

$$= \sum_{n=-\infty}^{\infty} x[n](a^{-1}z)^{-n},$$

$$= X(a^{-1}z).$$

Example



$$x[n] = \frac{1}{2n} \cos(\omega_0 n) u[n]$$

$$Z(\cos(\omega_0 n + \phi)u[n]) = \frac{\cos \phi - z^{-1}\cos(\omega_0 - \phi)}{1 - 2z^{-1}\cos\omega_0 + z^{-2}},$$

$$\phi = 0, Z(\cos(\omega_0 n)u[n]) = \frac{1 - z^{-1}\cos\omega_0}{1 - 2z^{-1}\cos\omega_0 + z^{-2}},$$

$$\therefore a = \frac{1}{3}, \therefore X(z) = \frac{1 - \frac{1}{3}z^{-1}\cos\omega_0}{1 - \frac{2}{3}z^{-1}\cos\omega_0 + \frac{1}{9}z^{-2}}.$$

The ROC is $|z| > \frac{1}{3}$.



Time Reversal

If
$$x[n] \stackrel{z}{\leftrightarrow} X(z)$$
 with ROC= $\{r_1 < |z| < r_2\}$, then

$$x[-n] \stackrel{z}{\leftrightarrow} X(z^{-1}),$$

with ROC=
$$\{1/r_2 < |z| < 1/r_1\}$$
.



Time Reversal

Proof: $x[-n] \stackrel{z}{\leftrightarrow} X(z^{-1})$.

$$Z(x[-n]) = \sum_{n=-\infty} x[-n]z^{-n},$$

$$\frac{m=-n}{m}\sum_{m=-\infty}^{\infty}x[m]z^m,$$

$$= \sum_{m=-\infty}^{\infty} x[m](z^{-1})^{-m},$$

= $X(z^{-1}).$

Differentiation in z-domain

If
$$x[n] \stackrel{z}{\leftrightarrow} X(z)$$
, then

$$nx[n] \stackrel{z}{\leftrightarrow} -z \frac{\mathrm{d}}{\mathrm{d}z} X(z),$$

The ROC is unchanged.



Differentiation in z-domain

Proof:
$$nx[n] \stackrel{z}{\leftrightarrow} -z \frac{\mathrm{d}}{\mathrm{d}z} X(z)$$
.

$$Z(nx[n]) = \sum_{n=-\infty}^{\infty} nx[n]z^{-n} = z \sum_{n=-\infty}^{\infty} nx[n]z^{-n-1},$$

$$= z \frac{\mathrm{d}}{\mathrm{d}z} \sum_{n=-\infty}^{\infty} \int nx[n]z^{-n-1} \,\mathrm{d}z,$$

$$= z \frac{\mathrm{d}}{\mathrm{d}z} \sum_{n=-\infty}^{\infty} -x[n]z^{-n},$$

$$=-z\frac{\mathrm{d}}{\mathrm{d}z}X(z).$$

x[n] = nu[n] (unit ramp signal)

$$X(z) = -z \frac{\mathrm{d}}{\mathrm{d}z} U(z),$$

$$= -z \left(\frac{z}{z-1}\right)',$$

$$= -z \frac{-1}{(z-1)^2},$$

$$= \frac{z}{(z-1)^2},$$

The ROC is |z| > 1.

Convolution

If
$$x_1[n] \stackrel{z}{\leftrightarrow} X_1(z)$$
 and $x_2[n] \stackrel{z}{\leftrightarrow} X_2(z)$ then

$$x[n] = x_1[n] * x_2[n] \stackrel{z}{\leftrightarrow} X_1(z)X_2(z).$$

The ROC of the convolution contains at least as much of the z-plane as the intersection of the ROC of $X_1(z)$ and the ROC of $X_2(z)$.



Convolution

Proof: $x[n] = x_1[n] * x_2[n] \stackrel{z}{\leftrightarrow} X_1(z)X_2(z)$.

$$X(z) = \sum x[n]z^{-n},$$

$$= \sum_{\mathbf{n}=-\infty}^{\infty} \left[\sum_{k=-\infty}^{\infty} x_1[k] x_2[\mathbf{n}-k] \right] z^{-\mathbf{n}},$$

$$= \sum_{k=-\infty}^{\infty} x_1[k] \left[\sum_{n=-\infty}^{\infty} x_2[n-k]z^{-n} \right],$$

$$= \sum_{k=-\infty} x_1[k]z^{-k}X_2(z) = X_1(z)X_2(z).$$

x[n] = u[n] * u[n-1]

$$X(z) = U(z)Z(u[n-1]),$$

$$= \frac{z}{z-1} \cdot z^{-1} \cdot \frac{z}{z-1},$$

$$= \frac{z}{(z-1)^2}.$$

The ROC is |z| > 1.

This means x[n] = u[n] * u[n-1] = nu[n].

Example



DT LTI System y[n] = x[n] * h[n]

$$h[n] = \delta[n] - \delta[n-1],$$

 $H(z) = 1 - z^{-1}, \text{ ROC} = \mathbb{C} - \{0\}$
 $x[n] = u[n-2],$

$$X[z] = z^{-2} \cdot U(z) = \frac{z^{-1}}{z - 1}, \text{ ROC} = |z| > 1$$

$$Y[z] = X(z)H(z) = \frac{z^{-1}}{z-1}(1-z^{-1}) = z^{-2},$$

 $ROC = \mathbb{C} - \{0\}, \ y[n] = \delta[n-2].$

The ROC of y[n] is bigger than intersection of ROC of x[n] and ROC of h[n].



Understand all the properties in Table 10.1 (P.775)

- Page 748–757, 767–776 read section 10.2 and 10.5 10.7;
- Page 799, Q10.13;
- Page 799, Q10.14;
- Page 804, Q10.30;
- Page 804, Q10.32;
- Page 804, Q10.33: (b).



Thank you for your attention.