

Operating systems

ELTE IK.

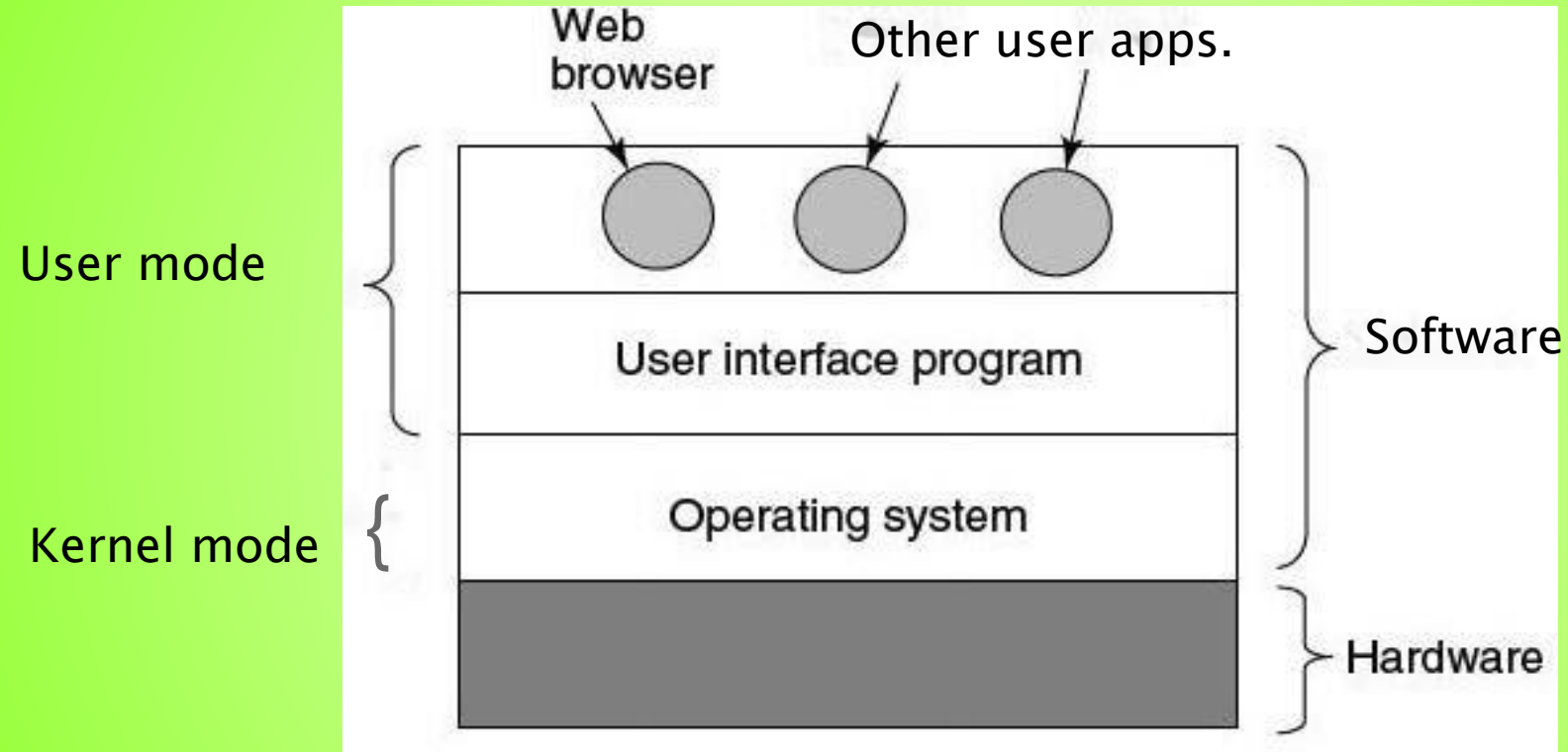
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Introduction

- ▶ Review (Introduction to Comp. Technology)
- ▶ Computer Architecture I.(HW)
- ▶ Computer Architecture II. (SW)
- ▶ Definitions of the „Operating systems”
- ▶ History, evolution of Operating systems
 - Past, Present, Future?
- ▶ Notions, names, conventions in an operating system
- ▶ System calls
- ▶ Structures of operating systems

An overview of a computer



Review

- ▶ As we finished „Introduction Computer technology” ...
- ▶ Script programs
 - Best friend of the system administrator
 - Shell script
 - PowerShell
- ▶ Client–server architecture
 - HW differences
- ▶ Client–server services
 - Administration
 - SW differences

Computer Architecture (HW)

► Computer components

◦ Hardware side

- Stored programs, commands, data are stored (binary, why?) in the memory, same way.
- Central processing Unit (CPU), arithmetical–logical unit (ALU) are controls the commands execution and base arithmetical instructions.
- Input/Output handling, this is the communication between CPU and outside world.
- Neumann principals.

◦ Base parts: Processor, Memories, Pheripherals, data storage

- Connecting element: Bus (data, address, control)

Processor commands

- ▶ All parts are intelligent, no direct communication, main role: processor
- ▶ Registers: special memories inside of the processor
 - Register groups (general, segment, status, ...)
- ▶ Groups of proc. commands
 - Data movement commands (registers–memories)
 - Jump commands (absolute–relativ)
 - I/O port read/write,
 - Interrupt handling etc.

Processor execution levels

- ▶ Intel 80286 – one level (real mode, 20 address lines– protected mode – not often used)
- ▶ Intel 80386 – starts in real mode– switch to protected mode
 - In protected mode there are 4 level (level 0, level 1, level 2, level 3)
 - Level 0 – kernel mode
 - Level 1, 2– not used
 - Level 3 – user mode
- ▶ Level 0 functionality
 - Interrupt handling (IDT)
 - I/O port management
 - Memory management
- ▶ Software interrupt handling (trap) is same as a hardware interrupt handling
- ▶ Interrupt masking – NMI

Using processor commands

- ▶ **Commands, data are in the memory, the CPU executes the commands**
 - `Mov al, 'F'`
 - `Mov ah, 'T'`
 - `Mov bl, 'C'`
 - etc.
- ▶ **Is it fun?**
 - Sure--- (FTC:)... //FTC is a football team 😊
 - ...

Computer Architecture (SW)

- ▶ Execution levels, sw levels
 - Logical circuits– no sw
 - CPU, microprogram, microarchitecture level
 - Assembly,hw devices
 - **Operating system**
 - System application (on user level too)
 - Written in low level, in assembly
 - Written in high level language (usually in c,c++)
 - User applications
 - Like awk, Pasians etc.

Operating system definitions

- ▶ **Operating system:** Such a program (group) which gives to the user an easy to use workplace, hiding the computer(system) elements.
- ▶ **Op. system as a virtual machine**
 - Do not care how to copy, how to play a movie (film), only i need player or a „copy machine”.
- ▶ **Op. System as a resource manager**
 - Printing spool manager
 - Memory manager
- ▶ **Kernel mode**
- ▶ **User mode**
- ▶ **Special controlled mode–embedded systems**

Operating system main task

- ▶ **Giving an easy to use, efficient user interface!**
 - 0. generation: spec. Hw. Switching table
 - Early systems (1940–70): Special terminals
 - The architecture was the same as today..
 - Beginning of 80th : microcomputers (ZX81 etc), Basic
 - PDP compatible TPA1140, serial terminals
 - MS DOS character terminal
 - Unix_X Window system, Xerox, MacOS
 - Windows 3.1, 95, 98, Mill, 2000, XP, Win7
- ▶ **Are they good user interfaces?**

Peripheral communication

- ▶ **Continuous checking (polling)**
 - I/O port continuous reading
 - Often used technic, typically used in synchronic software calls.
- ▶ **Interrupt usage**
 - There is no continuous reading, the program waits for an event (external, data is ready), the handler will read the data.
 - Asynchronic method
- ▶ **DMA, direct memory access**
 - eg. direct memory addressing: 0xb800:0

Application libraries

► Computer command levels:

- Machine code

- E.g.: intel x86, mov ax, 'F', mov eax, 'T', jmp address

- **Normal user API, Application Programming Interface**

- C64 ROM Basic
- DOS (IBM, MS) , IO.sys, msdos.sys, interrupt table
- Windows 98,...Windows 7, Win32 API
- **Unix-Linux system libraries, C language**

- **Script programming (BASH, PowerShell)**

- We saw it in 1th semester! (Fundaments of Computers)

User API's

- ▶ **Layered architecture**
- ▶ **Divided into 2 groups:**
 - **Kernel level calls**
 - Pheripheral communication
 - **User level calls**
 - Wide library support
- ▶ **Which programming language is supported?**
- ▶ **Sure, the C language! And more? C++- etc...😊**
- ▶ **Compatibility!**

What is POSIX?

- ▶ **POSIX = Portable Operating System Interface for uniX**
- ▶ **Official standard: IEEE 1003 – ISO 9945**
- ▶ **The POSIX is a minimal , standard API**
- ▶ **POSIX 1, 1a, 1b,1c ...versions**
- ▶ **ANSI C compatibility**
- ▶ **Every OS has POSIX compatibility**
- ▶ **Windows compatibility, until Windows 8**
 - **Windows Services for Unix**

Main POSIX API features

- ▶ File, directory management
- ▶ Process control
- ▶ Signals
- ▶ Pipes
- ▶ Standard C library
- ▶ Clocks, Timers
- ▶ Semaphors
- ▶ Synchron, asynchron I/O
- ▶ Threads
- ▶ etc.

Function groups

- ▶ Math functions: e.g. sin, cos, tan, atan, atan2, log, exp etc.
- ▶ File management functions: e.g. creat, open, fopen, close, read, write, unlink etc.
- ▶ Directory management functions: e.g. opendir, closedir, mkdir, rmdir, readdir etc.
- ▶ Character, string management: strcpy, strlen, strcmp, strcat, strchr, strstr etc.
- ▶ Memory management: malloc, free, memcpy etc.
- ▶ Communication functions: msgsnd, msgrcv, shmatt, semop, signal, kill, pipe etc.

How can we use in practice?

- ▶ **Our Op. system: Suse Linux Enterprise server**
 - `oprendszerrek.inf.elte.hu`
- ▶ **Text editor: vi, mcedit**
 - Or using locally a graphics editor, and ftp.
- ▶ **Help: man**
 - E.g.: `man exit`, `man strlen`
- ▶ **Compile: `cc -c first first.c`**
 - Try to resolve warnings too!

Operating systems API's

- ▶ So much API's as Op. systems
- ▶ Typical API's
 - Open VMS
 - OS/400
 - System V, BSD , common part: POSIX
 - Win32 API
 - Mac OS API
 - Windows Mobile, CE API
 - Palm OS
 - Nokia S40, S60, S80 API
 - Android x, WP7,8, etc.

Firmware – Middleware

- ▶ We saw: Hardware – Software
- ▶ Hardware is not only the physical device
 - Eg: HDD firmware.
 - BIOS calls.
- ▶ Firmware: An integrated software is build into hw by manufacturer
- ▶ Middleware: A system layer is above Op. System.
 - E.g.: JVM

Operating systems generations I.

- ▶ **Historical generation: Charles Babbage (1792–1871)**
 - Fully mechanics machine, no op.system
 - Operator job
 - Later, one of programmer was Ada Lovelace (Lord Byron's (poet) daughter) (Ada language)
- ▶ **First generation, 1940–1955, switching table, rele, electrical vacuumtube**
 - Neumann János, Institute for Advanced Studies, Princeton
 - Customised comp. machines
 - Machine code, simple math calculations
 - Punched cards as a data, command holder

Operating systems generations II.

- ▶ **Second generation 1955–1965, transistors systems**
 - Trusty, better computer components
 - Mainframes, computer centers
 - Distinct planning, manufacturing, programming, operation
 - Punched cards, tapes systems, batch systems
 - Fortran language
 - Op. system
 - FMS, Fortran monitor system
 - IBM 7094 machine, 1401 input – 7094 evaluation–1401 output unit

Operating systems generations III.

- ▶ Third generation, 1965–1980, appears integrated circuits
 - IBM 1401 and 7094 next one: System/360 family
 - Same architecture, construction, compatibility
 - Developing OS/360 , Fits to all System/360 HW, it results a big, tricky, complicated op. system.
 - Multiprogramming, multitask
 - There are more tasks in the memory at the same time.
 - Spooling, time sharing systems
 - No general on–line access, work

Operating systems generations III.

- ▶ **First time sharing system: M.I.T–en CTSS (CompatibleTime Sharing System)**
- ▶ **MULTICS, Multiplexed Information and Computing System**
 - AT&T Bell labs, General Electric support
 - PL/1 language
- ▶ **Bell Labs, Ken Thompson, Simplifying Multics , PDP 7–>UNIX**
- ▶ **Two main developing stream:**
 - Berkeley University – Berkeley Software Distribution
 - AT&T Bell Labs, System V Unix

Operating systems generations IV.

- ▶ Since 1980 till now, personal computers, MS Windows
- ▶ LSI (large scale integration) circuits, CPU developement
- ▶ Z80– CP/M (Control Program for Microcomputers)
 - ZX-81, ZX-Spectrum– Basic
- ▶ Intel x86 family, IBM PC– DOS, MS DOS
 - Command line desktop
- ▶ GUI– X Window, Mac OS X, MS Windows
- ▶ Network, distributed systems

MINIX 3

- ▶ From the beginning the UNIX source was free, open by AT&T .
- ▶ UNIX – not open, free from AT&T 7. version
- ▶ MINIX – MINI Unix, open source code
 - A.Tanenbaum, Vrije Univ. Amszterdam
 - Written in C language
- ▶ Linus Torvalds, ,Tanenbaum's student'
 - MINIX modification, 1994, LINUs uniX->LINUX
 - Open source
 - LAMP–Linux–Apache–Mysql–Php

System calls

- ▶ **System call:** An operating system library call which connects the user level call to the kernel level.
- ▶ **Two category:**
 - Task or process handling call
 - File management call
- ▶ **The best friend of the programmer: man, ...**

Process management

- ▶ **Process**– a program loaded into the memory and executing it
 - **Own address space**
 - **Process table**
 - Address, register, workfile datas, metadatas
 - **Process start, stop**
 - Shell, child processes
 - **Process pause**
 - Memory map + process table save
 - **Process communication**
 - Signals

File management

- ▶ Only one directory, /
 - Tree structure
 - Two registry entry: file, directory
- ▶ Dir. operations: create, copy, delete, open, read, write
- ▶ Access rights: rwx, – denied the given right
 - SETUID, SETGID, Sticky bit
- ▶ File system connecting (mount), disconnecting (unmount)
- ▶ Specific files:
 - Character, block files, /dev directory
- ▶ Special file: pipe

Major process handling calls

fork – To create a new process

exec – To execute a new program in a process

wait – To wait until a created process completes its execution

exit – To exit from a process execution

getpid – To get a process identifier of the current process

getppid – To get parent process identifier

nice – To bias the existing priority of a process

brk – To increase/decrease the data segment size of a process

Major signal handling functions

sigaction – Define action to take on signals

sigreturn – Return from a signal

sigprocmask – Examine or change the signal mask

sigpending – Get the set of blocked signals

sigsuspend – Replace the signal mask and suspend the process

kill – Send a signal to a process

alarm – Set the alarm clock

pause – Suspend the caller until the next signal

Major file management functions

open – Create a file or open an existing file

close – Close a file

read – Read data from a file

write – Write data to a file

lseek – Move the file pointer

stat , fstat – Get various file attributes

fcntl – File locking

Major directory management functions

mkdir – Create a new directory

rmdir – Remove an empty directory

link – Create a link to a file

unlink – Delete the link

mount, umount – Mount/ unmount a filesystem

chdir – Change the current working directory

Operating system structures

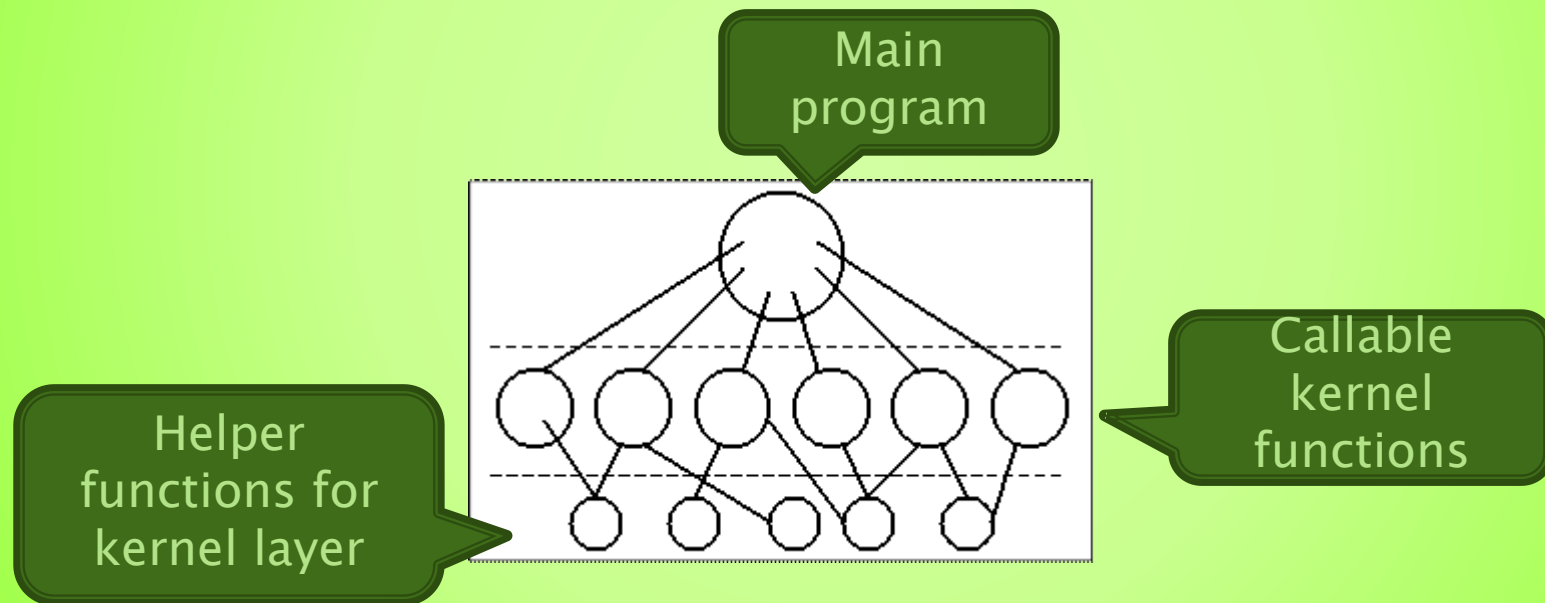
- ▶ **Monolithics systems**
- ▶ **Layered systems**
- ▶ **Virtual machines**
 - Exokernel
- ▶ **Client – Server model**

Monolithic systems

- ▶ Generaly: no defined structure, but...
- ▶ System library is one big system, so every process can use everything.
 - No information hide.
- ▶ Exist software moduls, planning modul groups
 - The predefined entry points(functions) can be called!
- ▶ During a system call the execution level is often switched to kernel mode (CPU execution level 0)
 - Parameters in registers
 - Trap

Monolithic system model

- ▶ Monolithic system: typically a 2 layers support



Layered architecture

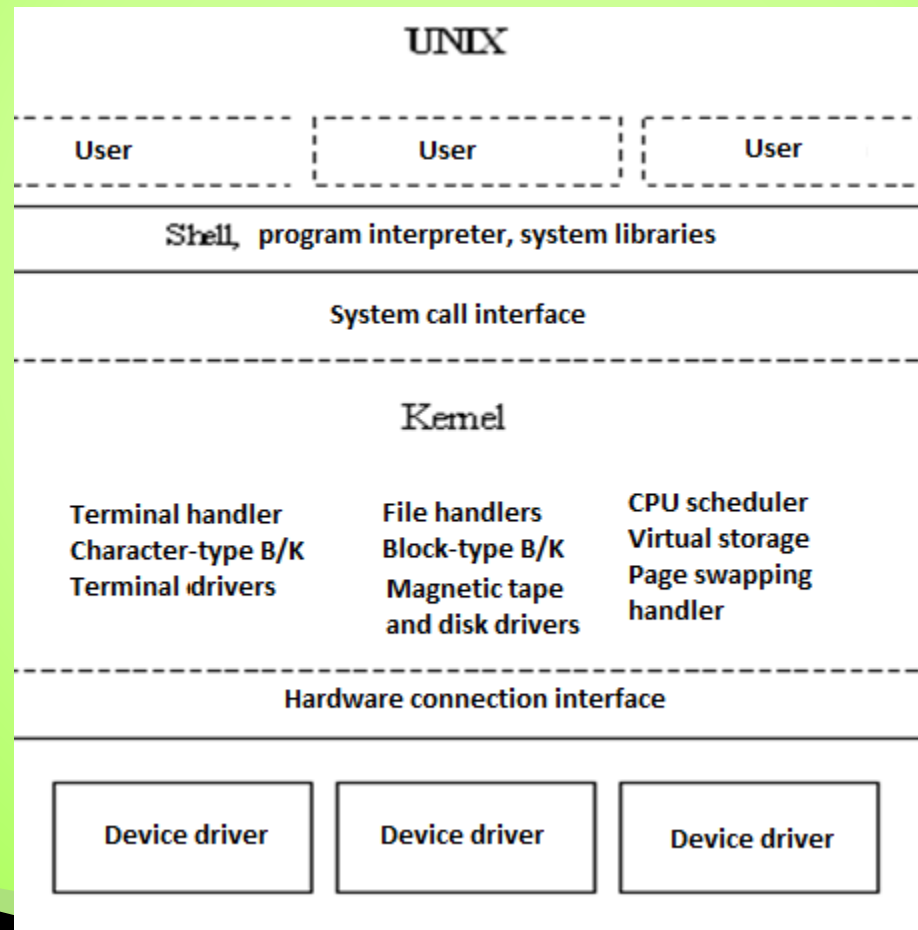
- ▶ Planned by E.W. Dijkstra : THE (1968)

5.	The operator
4.	User applications
3	I/O management
2	Machine-process
1	Memory management
0	CPU management and multiprogramming

- ▶ In MULTICS more generally
 - Round, ring architecture

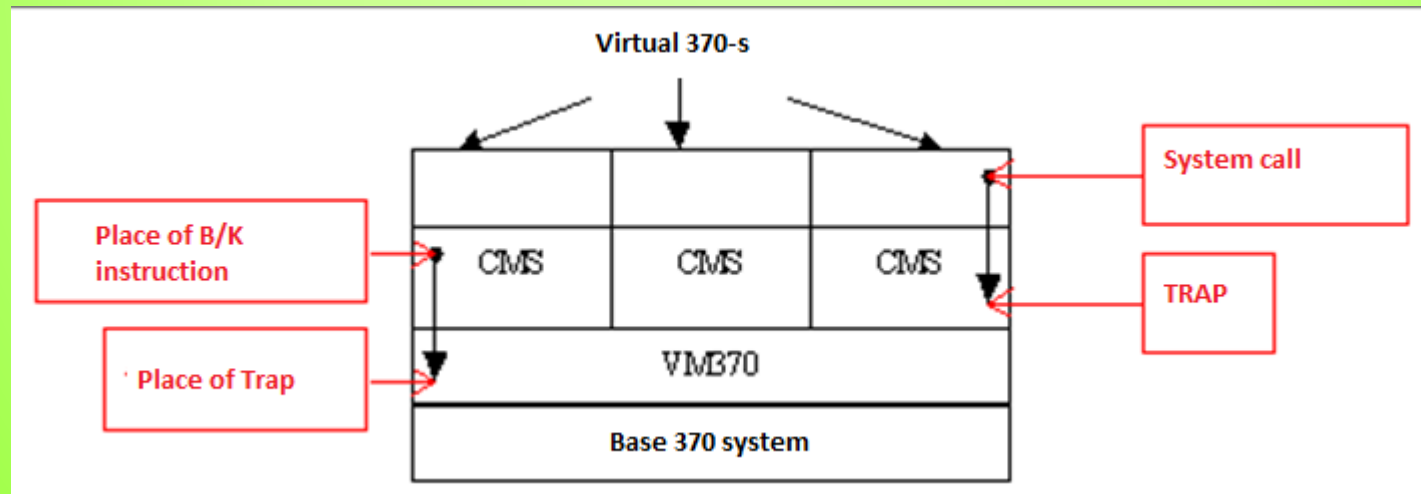
Typical layered structure

- The UNIX typical layered (round) structure.



Virtual machines

- ▶ The idea comes from IBM
- ▶ It was implemented on VM/370 system
- ▶ Virtual machine Monitor: gives a „copy” of the hardware

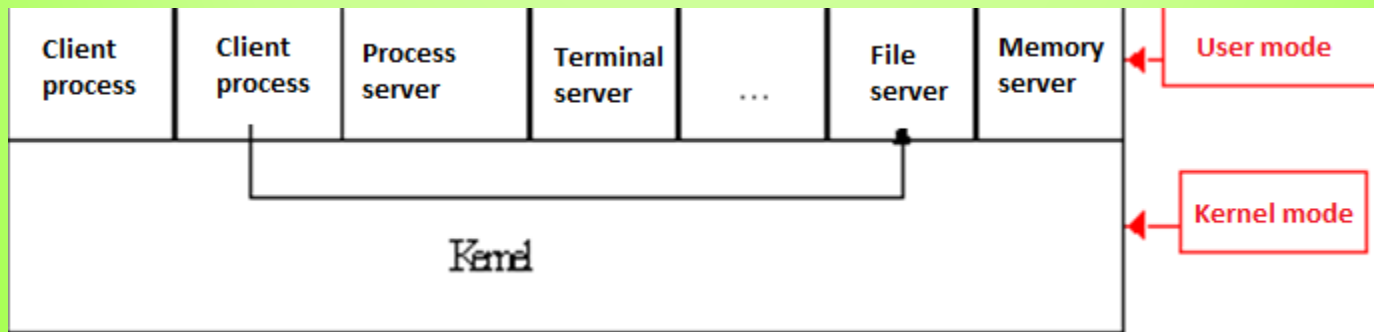


Virtual machines today

- ▶ **VMWare – under Unix– Linux platform**
 - Under Windows too
- ▶ **MS Virtual Server, Virtual PC**
 - Today's processors support virtualization
- ▶ **Microsoft– Hyper–V**
- ▶ **LINUX – XEN–KVM**
- ▶ **Other virtualization:**
 - JVM
 - .NET

Client-Server model

- ▶ Improvement of the idea of vm/370
 - To divide the task to much more parts.
- ▶ User application: client program
- ▶ Service application: server program
- ▶ Both runs in user mode
- ▶ Less and less functions stays in the kernel



Operating system expectations I.

- ▶ **Efficiency, an efficient management of the real resources**
- ▶ **Reliability, Build a reliable system**
 - Working all time without problems
 - Archive datas
 - 3–4 nine... reliability (99.9%, 99.99%)
 - **Failover systems**
 - Redundant systems(both HW and SW too), Server Cluster

Operating system expectations II.

- ▶ **Security**
 - Safe work from outside „attacks“, firewall
 - Data security
- ▶ **Compatibility**
 - Data, program exchange between systems.
 - Role of standards (POSIX)
- ▶ **Low energy occupation**
 - Not only for mobile devices

Operating system expectations III.

- ▶ **Flexibility**
 - Flexibil resource management(memory, processor, today cloud technology)
- ▶ **Manageability**
 - On support and user level too.
- ▶ **Can we offer all expectations?**
 - All manufacturers answer: yes....😊
- ▶ **We'll see later!**

Thanks for your
attention!

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