

Data Sheet September 6, 2005 FN8205.1

Single Digitally-Controlled (XDCP™) Potentiometer (Push Button Controlled)

FEATURES

- Push button controlled
- Low power CMOS
 - -Active current, 3mA max
 - -Standby current, 200µA max
- 31 resistive elements
 - —Temperature compensated
 - -±20% end to end resistance range
 - —-5V to +5V range
- 32 wiper tap points
 - -Wiper positioned via two push button inputs
 - -Slow & fast scan modes
 - —AUTOSTORE® option
 - -Manual store option
 - Wiper position stored in nonvolatile memory and recalled on power-up
- 100 year wiper position data retention
- X9511W = $10k\Omega$
- Packages
 - -8 Ld PDIP
 - -8 Ld SOIC
- Pb-free plus anneal available (RoHS compliant)

DESCRIPTION

The Intersil X9511 is a push button controlled potentiometer that is ideal for push button controlled resistance trimming.

The X9511 is a resistor array composed of 31 resistive elements. Between each element and at either end are tap points accessible to the wiper element. The position of the wiper element is controlled by the \overline{PU} and \overline{PD} inputs. The position of the wiper can be automatically stored in E^2 memory and then be recalled upon a subsequent power-on operation.

The resolution of the X9511 is equal to the maximum resistance value divided by 31. As an example, for the X9511W (10k Ω) each tap point represents 323 Ω .

All Intersil nonvolatile products are designed and tested for applications requiring extended endurance and data retention.

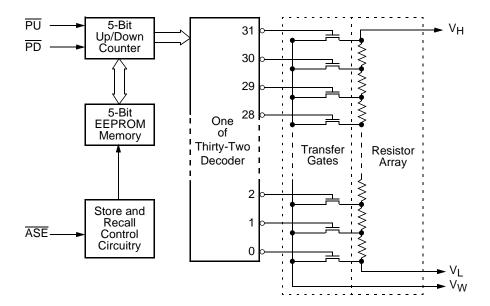
ORDERING INFORMATION

PART NUMBER	PART MARKING	R _{TOTAL} (kΩ)	TEMPERATURE RANGE (°C)	PACKAGE
X9511WP	X9511WP	10	0 to 70	8 Ld PDIP
X9511WPI	X9511WP I		-40 to 85	8 Ld PDIP
X9511WPIZ (Note)	X9511WP Z I		-40 to 85	8 Ld PDIP (Pb-free)
X9511WS*	X9511W		0 to 70	8 Ld SOIC
X9511WSZ* (Note)	X9511W Z		0 to 70	8 Ld SOIC (Pb-free)
X9511WSI*	X9511W I		-40 to 85	8 Ld SOIC
X9511WSIZ* (Note)	X9511W Z I		-40 to 85	8 Ld SOIC (Pb-free)

NOTE: Intersil Pb-free plus anneal products employ special Pb-free material sets; molding compounds/die attach materials and 100% matte tin plate termination finish, which are RoHS compliant and compatible with both SnPb and Pb-free soldering operations. Intersil Pb-free products are MSL classified at Pb-free peak reflow temperatures that meet or exceed the Pb-free requirements of IPC/JEDEC J STD-020.

^{*}Add "T1" suffix for tape and reel.

BLOCK DIAGRAM



PIN DESCRIPTIONS

V_H/R_H and V_L/R_L

The high (VH/RH) and low (VL/RL) terminals of the X9511 are equivalent to the fixed terminals of a mechanical potentiometer. The minimum voltage is -5V and the maximum is +5V. It should be noted that the terminology of VL/RL and VH/RH reference the relative position of the terminal in relation to wiper movement direction selected by the PU and PD inputs, and not the voltage potential on the terminal.

PU

The debounced \overline{PU} input is for incrementing the wiper position. An on-chip pull-up holds the \overline{PU} input HIGH. A switch closure to ground or a LOW logic level will, after a debounce time, move the wiper to the next adjacent higher tap position.

$\overline{\mathsf{PD}}$

The debounced \overline{PD} input is for decrementing the wiper position. An on-chip pull-up holds the \overline{PD} input HIGH. A switch closure to ground or a LOW logic level will, after a debounce time, move the wiper to the next adjacent lower tap position.

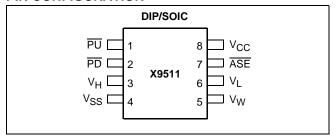
ASE

The debounced $\overline{\mathsf{ASE}}$ (AUTOSTORE enable) pin can be in one of two states:

 V_{IL} - AUTOSTORE is enabled. When V_{CC} powers down, an automatic store cycle takes place.

 V_{IH} - AUTOSTORE is disabled. A LOW to HIGH will initiate a manual store operation. This is for the user who wishes to connect a push button switch to this pin. For every valid push, the X9511 will store the current wiper position to the EEPROM.

PIN CONFIGURATION



PIN NAMES

Symbol	Description	
V _H /R _H	High Terminal	
V _W /R _W	Wiper Terminal	
V _L /R _L	Low Terminal	
V _{SS}	Ground	
V _{CC}	Supply Voltage	
PU	Push Up Input	
PD	Push Down Input	
ĀSĒ	AUTOSTORE Enable Input	

DEVICE OPERATION

There are three sections of the X9511: the input control, counter and decode section; the EEPROM memory; and the resistor array. The input control section operates just like an up/down counter. The output of this counter is decoded to turn on a single electronic switch, connecting a point on the resistor array to the wiper output. Under the proper conditions the contents of the counter can be stored in EEPROM memory and retained for future use. The resistor array is comprised of 31 individual resistors connected in series. At either end of the array and between each resistor is an electronic switch that transfers the potential at that point to the wiper.

The X9511 is designed to interface directly to two push button switches for effectively moving the wiper up or down. The \overline{PU} and \overline{PD} inputs increment or decrement a 5-bit counter respectively. The output of this counter is decoded to select one of the thirty-two wiper positions along the resistive array. The wiper increment input, \overline{PU} and the wiper decrement input, \overline{PD} are both connected to an internal pull-up so that they normally remain HIGH. When pulled LOW by an external push button switch or a logic LOW level input, the wiper will be switched to the next adjacent tap position.

Internal debounce circuitry prevents inadvertent switching of the wiper position if PU or PD remain LOW for less than 40ms, typical. Each of the buttons can be pushed either once for a single increment/decrement or continuously for a multiple increments/decrements. The number of increments/decrements of the wiper position depend on how long the button is being pushed. When making a continuous push, after the second, the increment/decrement increases. For the first second the device will be in the slow scan mode. Then if the button is held for longer than 1 second the device will go into the fast scan mode. As soon as the button is released the X9511 will return to a standby condition.

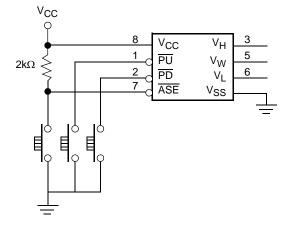
The wiper, when at either fixed terminal, acts like its mechanical equivalent and does not move beyond the last position. That is, the counter does not wrap around when clocked to either extreme.

AUTOSTORE

The value of the counter is stored in EEPROM memory whenever the chip senses a power-down of V_{CC} while \overline{ASE} is enabled (held LOW). When power is restored, the content of the memory is recalled and the counter reset to the last value stored.

If AUTOSTORE is to be implemented, \overline{ASE} is typically hard wired to V_{SS}. If \overline{ASE} is held HIGH during power-up and then taken LOW, the wiper will not respond to the \overline{PU} or \overline{PD} inputs until \overline{ASE} is brought HIGH and held HIGH.

Figure 1. Typical circuit with ASE store pin controlled by push button switch



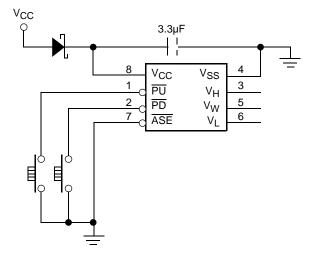
Manual (Push Button) Store

When $\overline{\mathsf{ASE}}$ is not enabled (held HIGH) a push button switch may be used to pull $\overline{\mathsf{ASE}}$ LOW and released to perform a manual store of the wiper position.

R_{TOTAL} with V_{CC} Removed

The end to end resistance of the array will fluctuate once $V_{\mbox{\footnotesize{CC}}}$ is removed.

Figure 2. Typical circuit with ASE store pin used in AUTOSTORE mode



ABSOLUTE MAXIMUM RATINGS

Temperature under bias65°C	to +135°C
Storage temperature65°C	to +150°C
Voltage on PU, PD, and V _{CC}	
with respect to V _{SS}	·1V to +7V
Voltage on V _H and V _L	
referenced to V _{SS}	8V to +8V
$\Delta V = V_H - V_L $	
X9511W	10V
Lead temperature (soldering 10 seconds)	300°C
Wiper current	±1mA

ANALOG CHARACTERISTICS

Electrical Characteristics

End-to-end resistance tolerand	ce±20%
Power rating at 25°C	
X9511W	10mW
Wiper current	±1mA Max.
Typical wiper resistance	
Typical noise	< -120dB/√Hz Ref: 1V

Resolution

Linearity

Absolute linearity ⁽¹⁾	±1.0 MI ⁽²⁾
Relative linearity (3)	±0.2 MI ⁽²⁾

COMMENT

Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only; functional operation of the device (at these or any other conditions above those listed in the operational sections of this specification) is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

Temperature Coefficient

-40°C to +85°C	
X9511W+300 pp	om/°C Typical
Ratiometric temperature coefficient	±20 ppm

Wiper Adjustability

Unlimited wiper adjustment	(Non-Store operation)
Wiper position store operations	s100,000
	data changes

Physical Characteristics

Marking Includes
Manufacturer's Trademark
Resistance Value or Code
Date Code

Notes: (1) Absolute linearity is utilized to determine actual wiper voltage versus expected voltage = $(V_{W(n)}(actual) - V_{W(n)}(expected)) = \pm 1$ MI Maximum.

- (2) 1 MI = Minimum Increment = R_{TOT}/31.
- (3) Relative linearity is a measure of the error in step size between taps = $V_{W(n+1)}$ $[V_{w(n)} + MI] = +0.2 MI$

SYMBOL TABLE

WAVEFORM	INPUTS	OUTPUTS
	Must be steady	Will be steady
	May change from Low to High	Will change from Low to High
	May change from High to Low	Will change from High to Low
	Don't Care: Changes Allowed	Changing: State Not Known
	N/A	Center Line is High Impedance

RECOMMENDED OPERATING CONDITIONS

Temp	Min.	Max.		
Commercial	0°C	+70°C		
Industrial	-40°C	+85°C		

Supply Voltage	Limits	
X9511	5V ± 10%	

D.C. OPERATING CHARACTERISTICS (Over recommended operating conditions unless otherwise specified.)

		Limits				
Symbol	Parameter	Min.	Typ. ⁽⁴⁾	Max.	Unit	Test Conditions
Icc	V _{CC} active current		1	3	mA	PU or PD held at V _{IL} the other at V _{IH}
I _{SB}	Standby supply current		100	200	μΑ	$\overline{PU} = \overline{PD} = V_{IH}$
ILI	PU, PD, ASE input leakage current			10	μΑ	$V_{IN} = V_{SS}$ to V_{CC}
V_{IH}	PU, PD, ASE input HIGH voltage	2		V _{CC} + 1	V	
V _{IL}	PU, PD, ASE input LOW voltage	-1		0.8	V	
R _W	Wiper resistance		40	100	Ω	Max. Wiper Current ±1mA
V _{VH}	VH terminal voltage	-5		+5	V	
V_{VL}	VL terminal voltage	-5		+5	V	
C _{IN} ⁽⁵⁾	ASE, PU, PD input capacitance			10	pF	$V_{CC} = 5V$, $V_{IN} = 0V$, $T_A = 25$ °C, $f = 1$ MHz

Notes: (4) Typical values are for $T_A = 25$ °C and nominal supply voltage.

(5) This parameter is periodically sampled and not 100% tested.

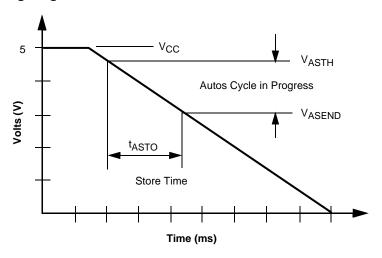
A.C. OPERATING CHARACTERISTICS (Over recommended operating conditions unless otherwise specified.)

		Limits			
Symbol	Parameter	Min.	Typ. ⁽⁶⁾	Max.	Unit
t _{GAP}	Time between two separate push button events	0			μs
t _{DB}	Debounce time		30	60	ms
ts slow	After debounce to wiper change on a slow mode	100	250	375	ms
ts fast ⁽⁷⁾	Wiper change on a fast mode	25	50	75	ms
t _{PU} ⁽⁷⁾	Power-up to wiper stable			500	μs
t _R V _{CC} ⁽⁷⁾	V _{CC} power-up rate	0.2		50	mV/µs
t _{ASTO} ⁽⁷⁾	AUTOSTORE cycle time	2			ms
V _{ASTH} ⁽⁷⁾	AUTOSTORE threshold voltage		4		V
V _{ASEND} ⁽⁷⁾	AUTOSTORE cycle end voltage		3.5		V

POWER-UPPOWER-DOWN AND DOWN REQUIREMENTS

The are no restrictions on the sequencing of V_{CC} and the voltage applied to the potentiometer pins during power-up or power-down conditions. During power-up, the data sheet parameters for the DCP do not fully apply until 1ms after V_{CC} reaches its final value. The V_{CC} ramp rate spec is always in effect.

AUTOSTORE Cycle Timing Diagram

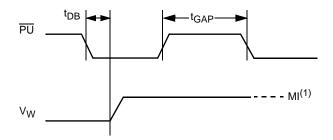


t_{ASTO} - AUTOSTORE cycle time

(6) Typical values are for $T_A = 25^{\circ}C$ and nominal supply voltage.

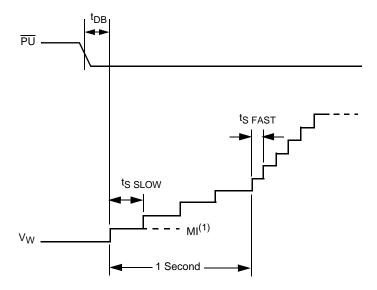
(7) This parameter is periodically sampled and not 100% tested.

Slow Mode Timing



Note: (1) MI in the A.C. timing diagram refers to the minimum incremental change in the wiper voltage.

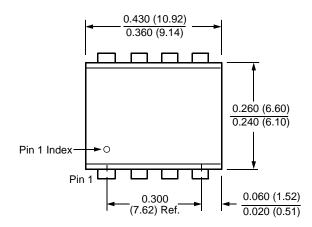
Fast Mode Timing

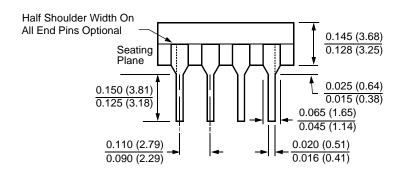


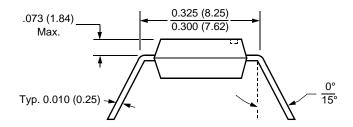
Note: (1) MI in the A.C. timing diagram refers to the minimum incremental change in the wiper voltage.

PACKAGING INFORMATION

8-Lead Plastic Dual In-Line Package Type P





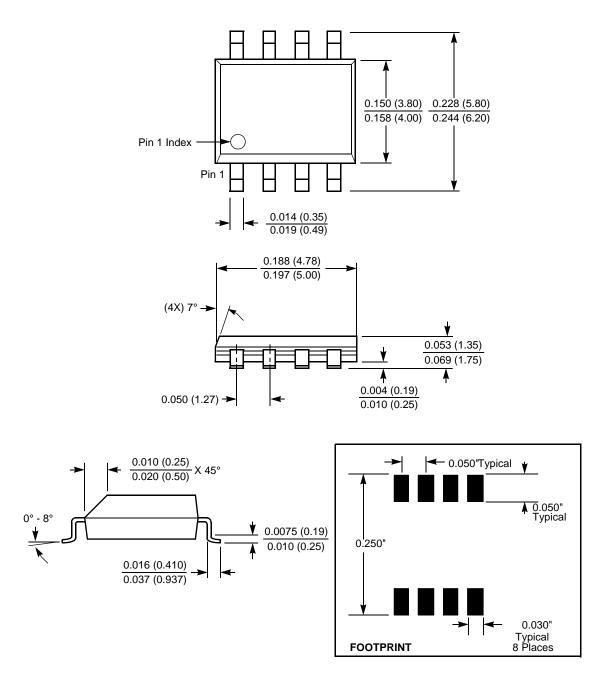


NOTE:

- 1. ALL DIMENSIONS IN INCHES (IN PARENTHESES IN MILLIMETERS)
- 2. PACKAGE DIMENSIONS EXCLUDE MOLDING FLASH

PACKAGING INFORMATION

8-Lead Plastic Small Outline Gull Wing Package Type S



NOTE: ALL DIMENSIONS IN INCHES (IN PARENTHESES IN MILLIMETERS)

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