

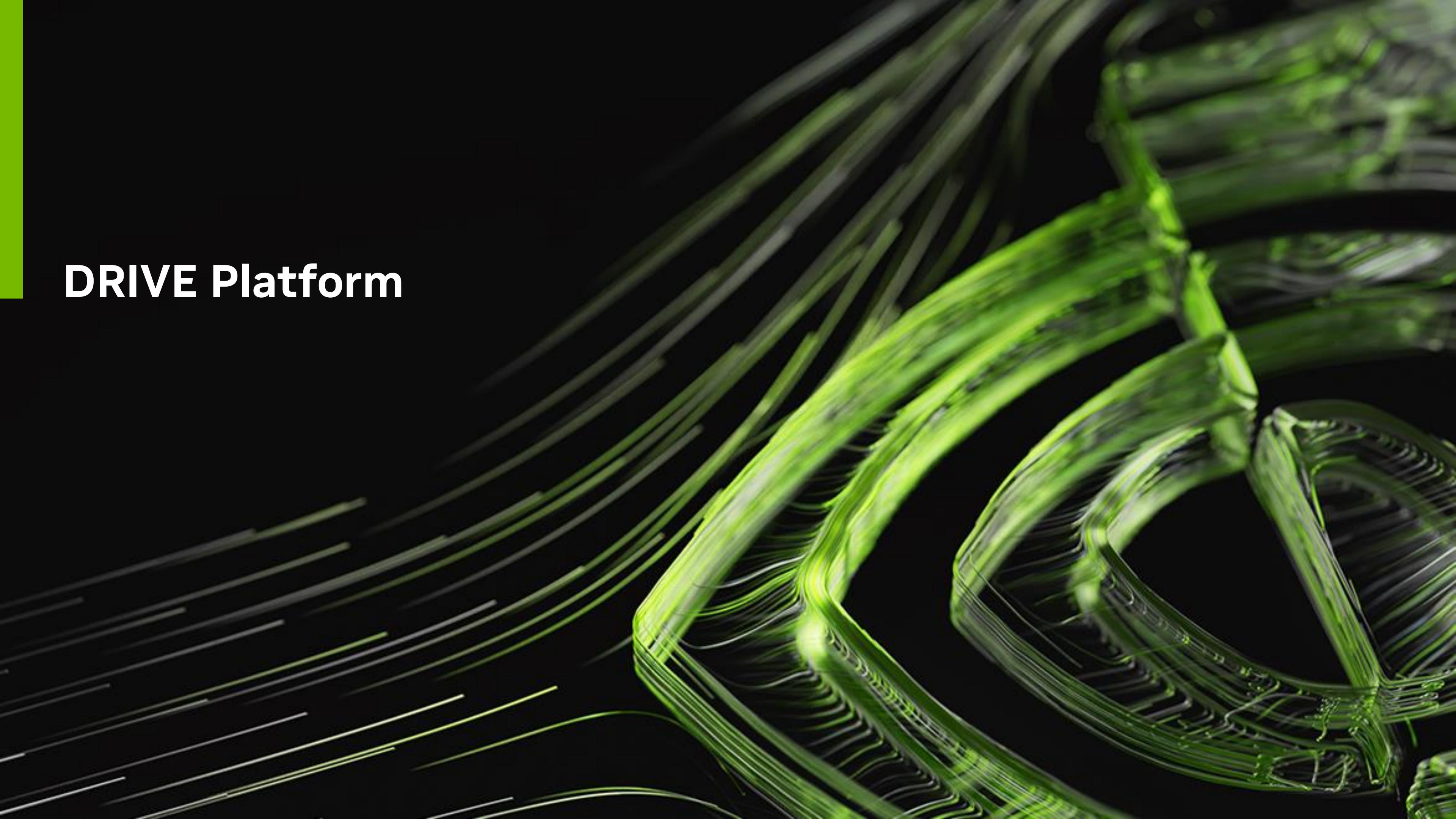


Overview

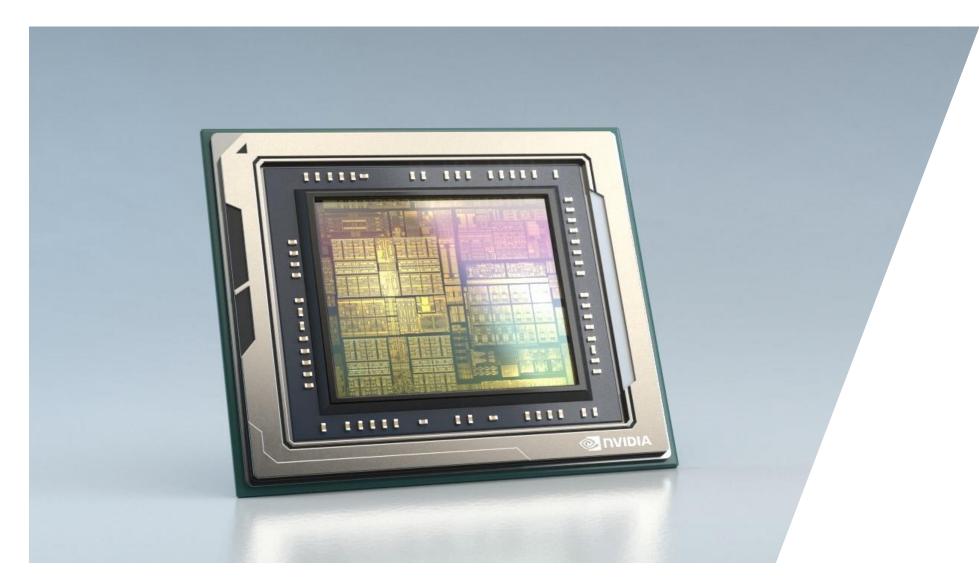
- DRIVE Platform
- DRIVE OS

Link to Latest Online PDF Version

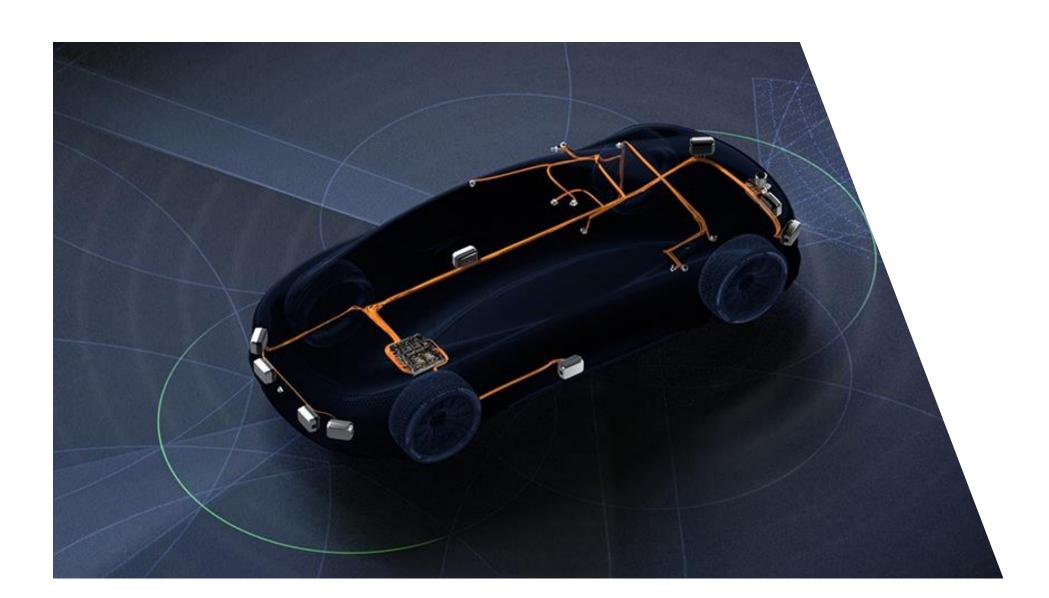




NVIDIA DRIVE End-to-End Solutions for Autonomous Vehicles



DRIVE Orin SoCSoftware-Defined Platform



DRIVE Hyperion

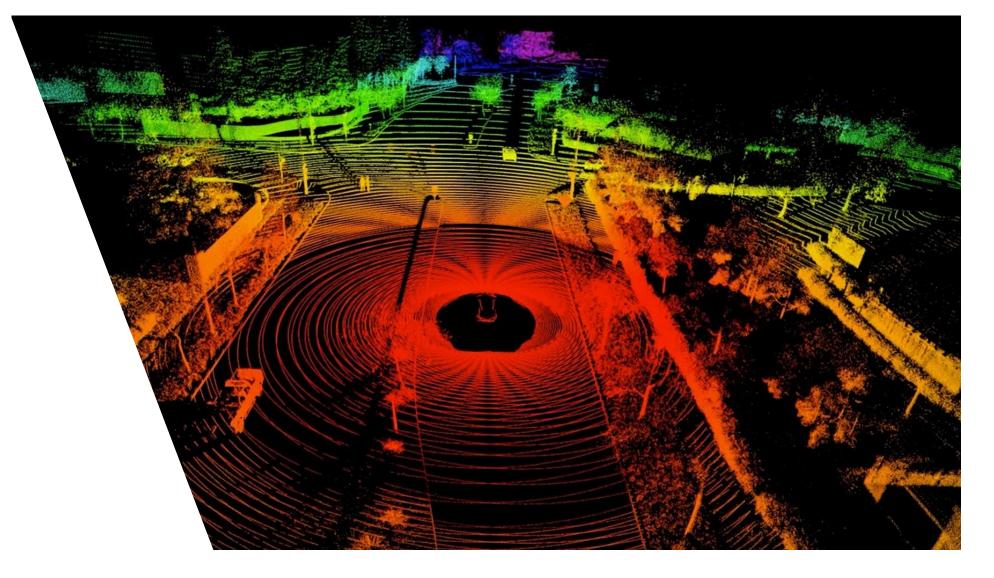
Reference Architecture
with Sensor Specification



DRIVE AGX Orin DevKit

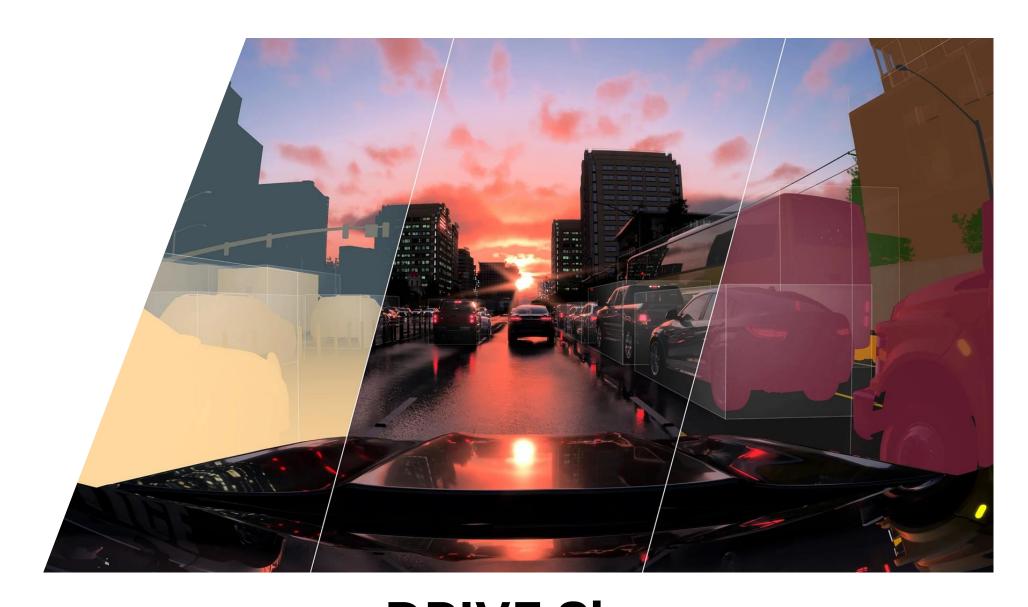
High-Performance
Development Platform

DRIVE AGX Developer Program



DRIVE OS

AV Software Foundation
OS, CUDA & DriveWorks



AV Development and Validation Tools
Built on NVIDIA Omniverse

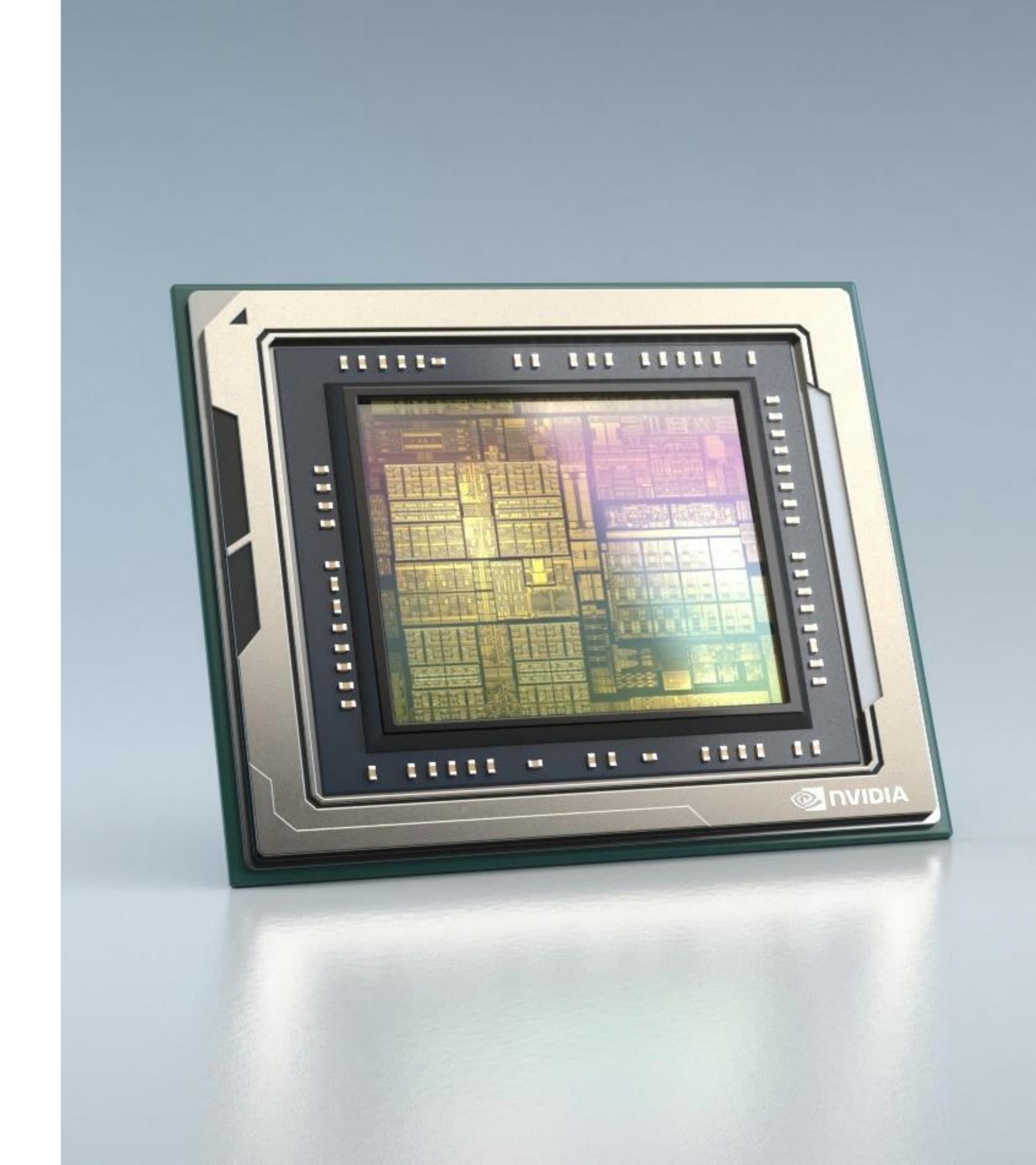
Early Access Program



DRIVE Orin SoC

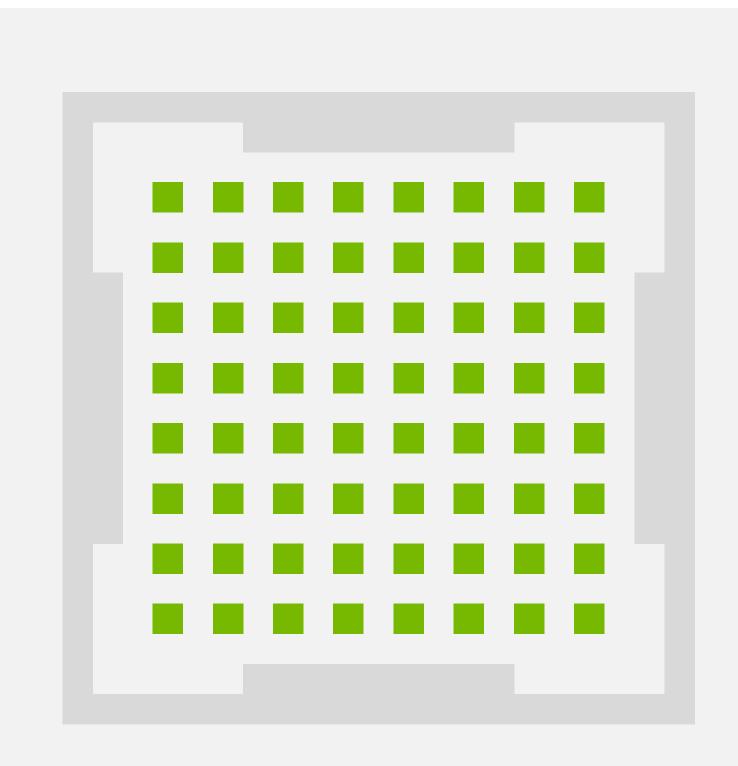
Advanced, software-defined platform for autonomous vehicles

- 254 INT8 TOPS CUDA Tensor Core GPU + DLA
- 12 A78 (Hercules) ARM64 CPUs
- 205 GB/s memory bandwidth
- 4 R52 Lock-step Pairs Integrated Safety Island ASIL-D
- ISO 26262 (FUSA) ASIL-B Chip | ASIL-D Systematic
- Hardware Accelerators:
 - Deep Learning Accelerators (DLA)
 - Programmable Vision Accelerator (PVA)
 - Optical Flow Accelerator (OFA)



DRIVE Orin Hardware Accelerators

Optimal efficiency for diverse workloads



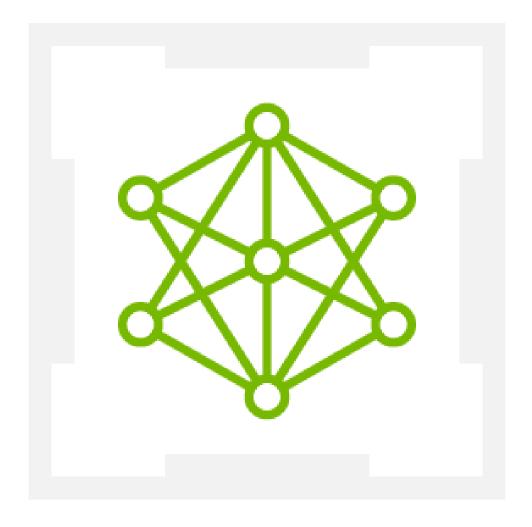
Ampere GPU

Accelerates All Parallelizable Workloads

Maximum Performance and Flexibility

Improvements for Orin:
Increased Performance & Enhanced Tensor Cores

167 INT8 DL TOP/s 83.5 FP16 DL TOP/s



2x Gen2 DLA

Accelerates Deep Neural Networks
Optimal Performance/Watt for DNNs

Improvements for Orin:
Depthwise Convolution & Hardware Scheduler

87 INT8 DL TOP/s total



Gen2 PVA*

Accelerates Computer Vision Algorithms
Highly Specialized, Minimal Power Consumption

Improvements for Orin:
Optical Flow Accelerator & More Performance

2048 INT8 GMAC/s

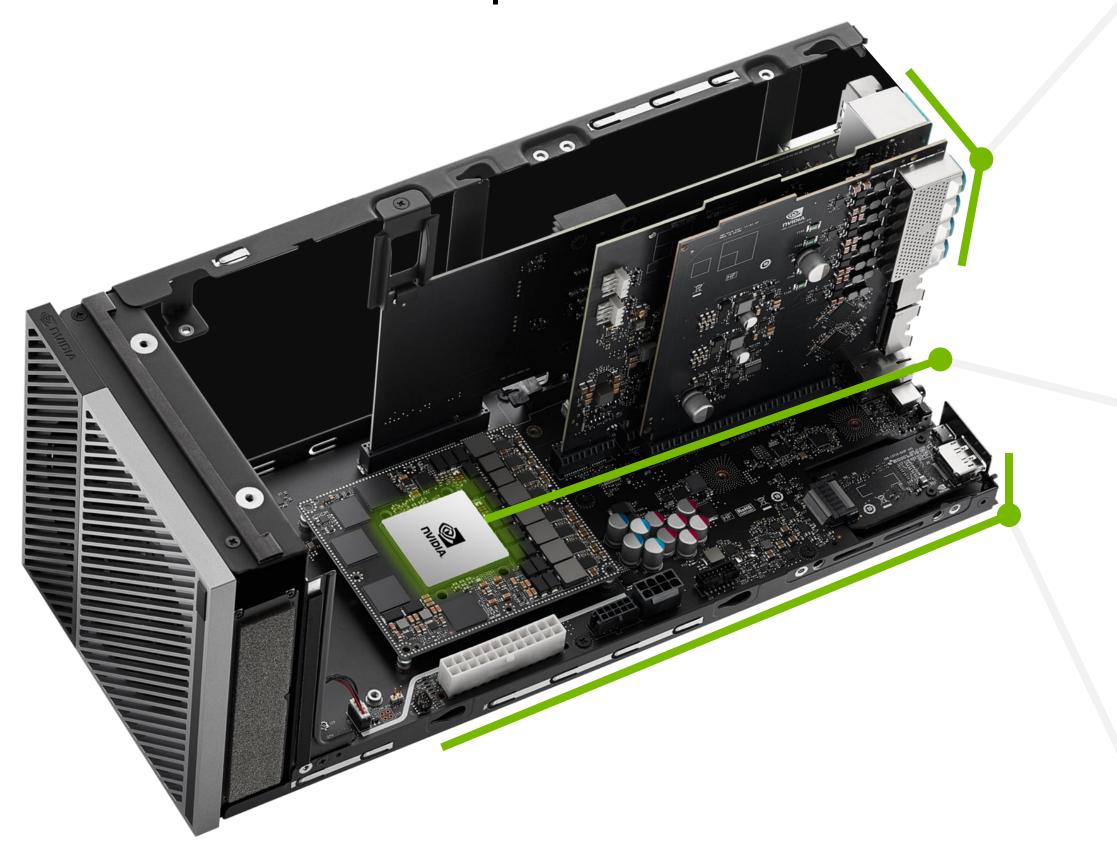


Self-Driving Hardware And Software Development Kit

Open & scalable platform purpose built for automotive

DRIVE AGX Orin DevKit

DRIVE OS – AV SW Foundation Auto-grade Silicon & IO 254 TOPS | 200W



Available Now

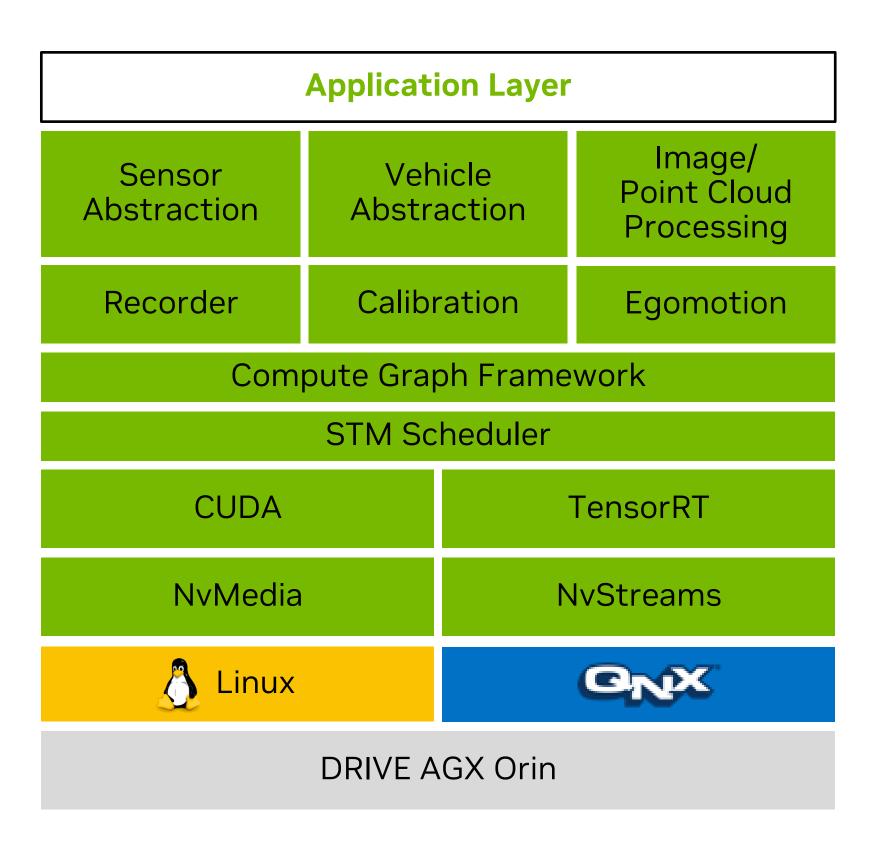
Directly from NVIDIA and Authorized Distributors Like <u>Arrow</u>

Rich IO for Development, Sensors and Vehicle Bus

- Vehicle Bus, GMSL, Ethernet, PCIe, USB, DisplayPort, Wi-Fi, Bluetooth
- ISO 26262 compliant sensors supported via partners

Software Included

- DRIVE OS with DriveWorks
- Middleware, tools and algorithms
- ISO 26262 safety certifiable DRIVE OS QNX, drivers, and platform APIs



Safe and Performant Compute Platform

- Orin SoC with CUDA Tensor Core GPU and 12 A78 (Hercules) ARM64 CPUs
- Architected for safety, production boards available via Tier1s



The state of the s

Spec Overview

Components				
Orin SoC	GPU	Integrated CUDA Tensor Core GPU		
	Accelerators	Deep Learning Accelerators (DLA) Programmable Vision Accelerator (PVA) Optical Flow Accelerator (OFA)		
	CPU	12 A78 (Hercules) ARM64 CPUs		
Safety MCU		Infineon Aurix TC397		
Storage		256 GB UFS		
Power Supply		Built-in		
Wiring Harness		Additional Accessory		

Performance				
DL Inference TOPS (INT8)	254 TOPS			
Memory Bandwidth	205 GB/s			
System RAM	32GB LPDDR5 at 3200 MHz			

Operating Parameters			
Temperature	0 to 45°C		
Power TDP	200W		
Voltage	9V to 16V (Static), 7V to 32V (Transient)		



Auto-Grade and Development Interfaces

Convenient bench development | Reliable in-vehicle operation

Ethernet ~30Gb/s total	2x 10x 6x	10 GbE 1 GbE 100 MbE	1 H-MTD*, 1 RJ45 9 H-MTD*, 1 RJ45 MATEnet*	
Camera	16x	GMSL	MATEAX GMSL 1/2*	
USB	2x 2x	USB 3.2 USB 2.0	Type C Type A	
PCle**	1x	PCIe x8	Mini-SAS	
Video Out	1x		DisplayPort 1.4	
	6x	CAN*	Wiring Harness	
Wiring Harness	1x	LIN*	Connector (DevKit)	
(Opt. Accessory)	1x	FlexRay*	DB9	
	12x	USS*	(Wiring Harness)	





Supported Sensors

Sensors for DRIVE Orin Ecosystem Partners

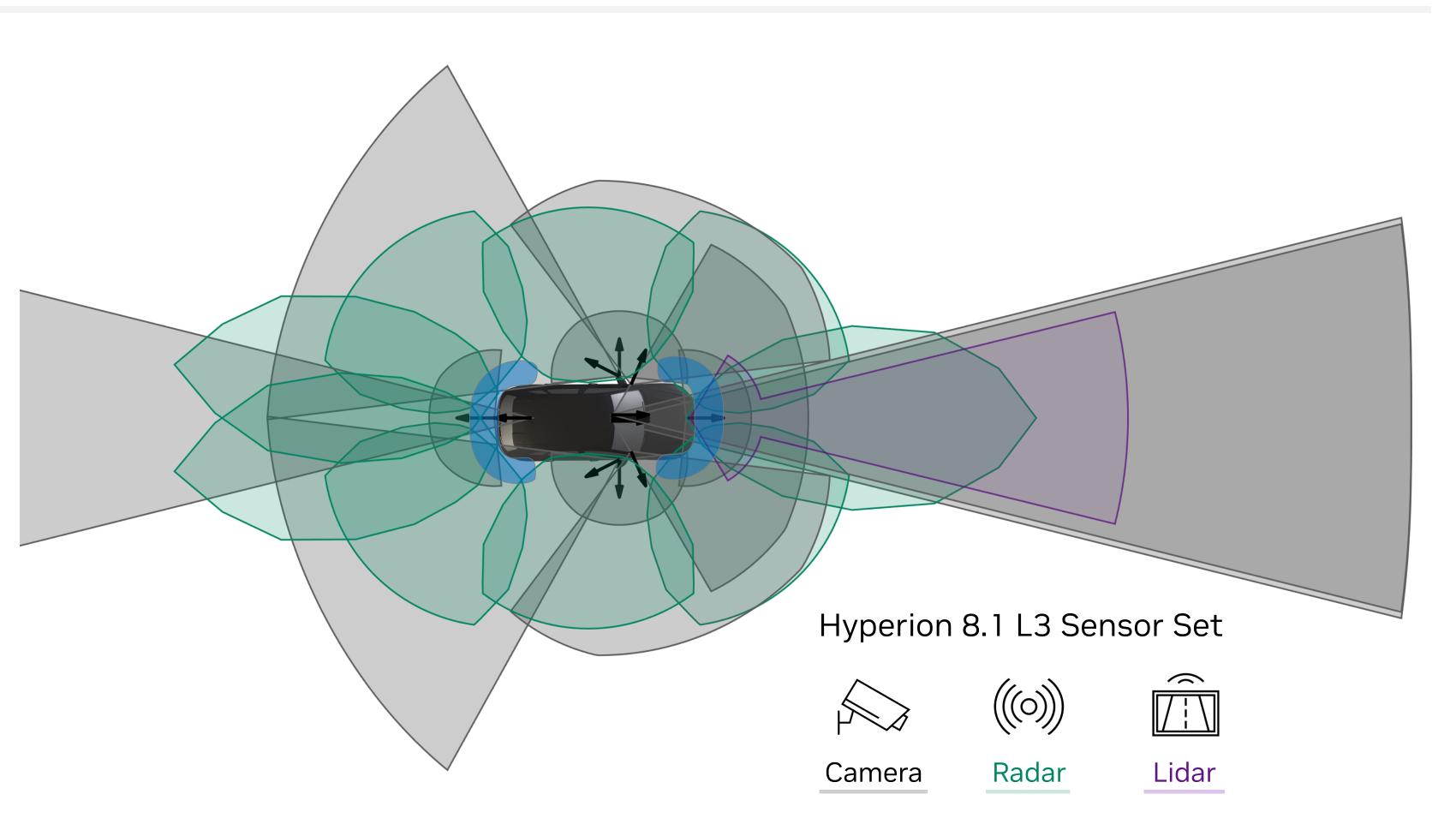
- Sensors supported for ecosystem developers
- See <u>DRIVE AGX Orin Sensors and Accessories</u> for details

Ecosystem Sensor Vendors

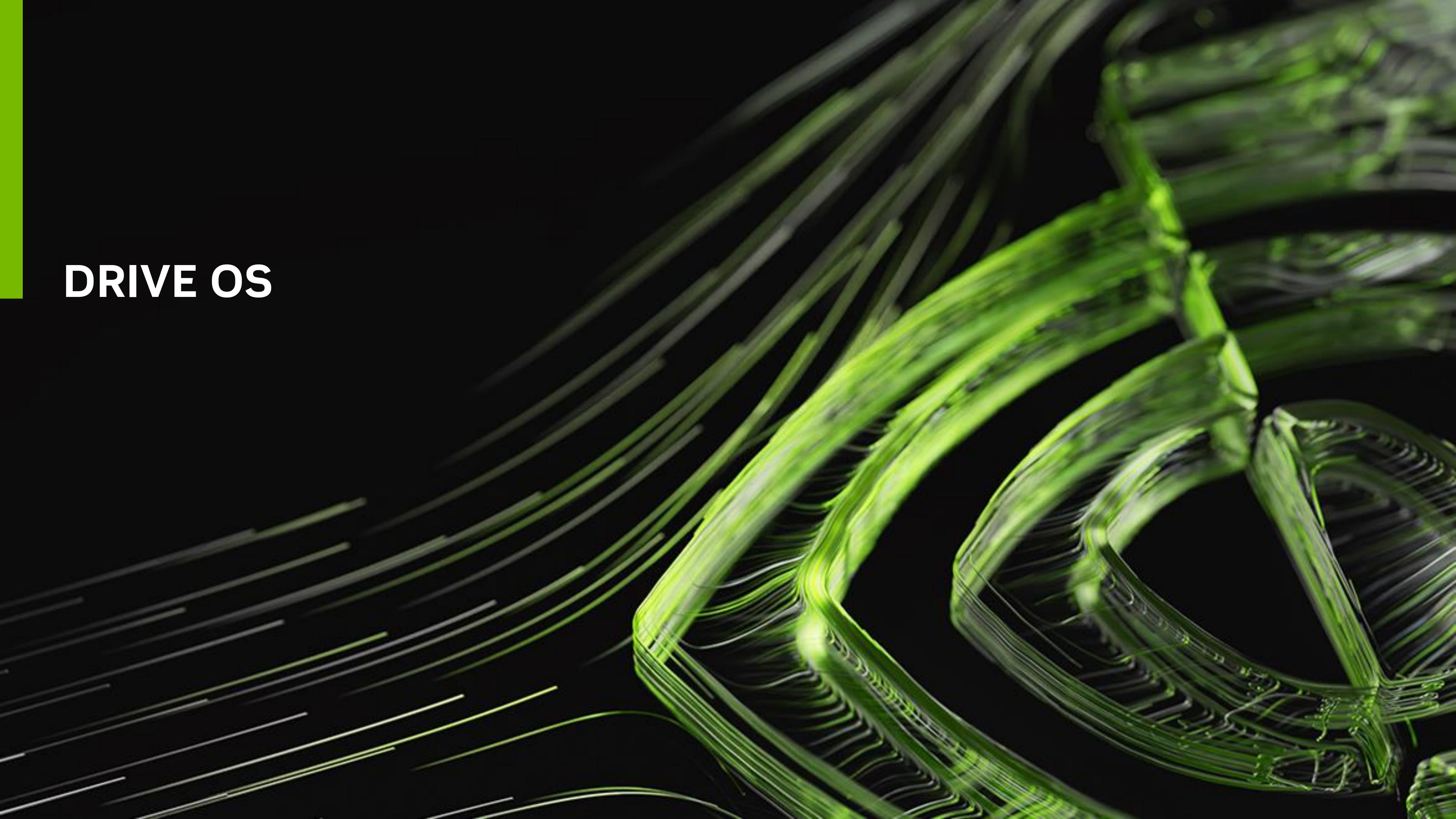
Cameras	Lidars	Radars
 SONY Leopard Omnivision Entron On Semiconductor Sekonix Quanta 	 Velodyne Luminar Hesai Ouster Innoviz AEVA 	ContinentalArbe

Hyperion 8.1 Reference Architecture

- Hyperion 8.1 is NVIDIA's automotive grade L2+ / L3 AV production architecture
- See <u>DRIVE Hyperion 8.1 Sensors and Accessories</u> for details







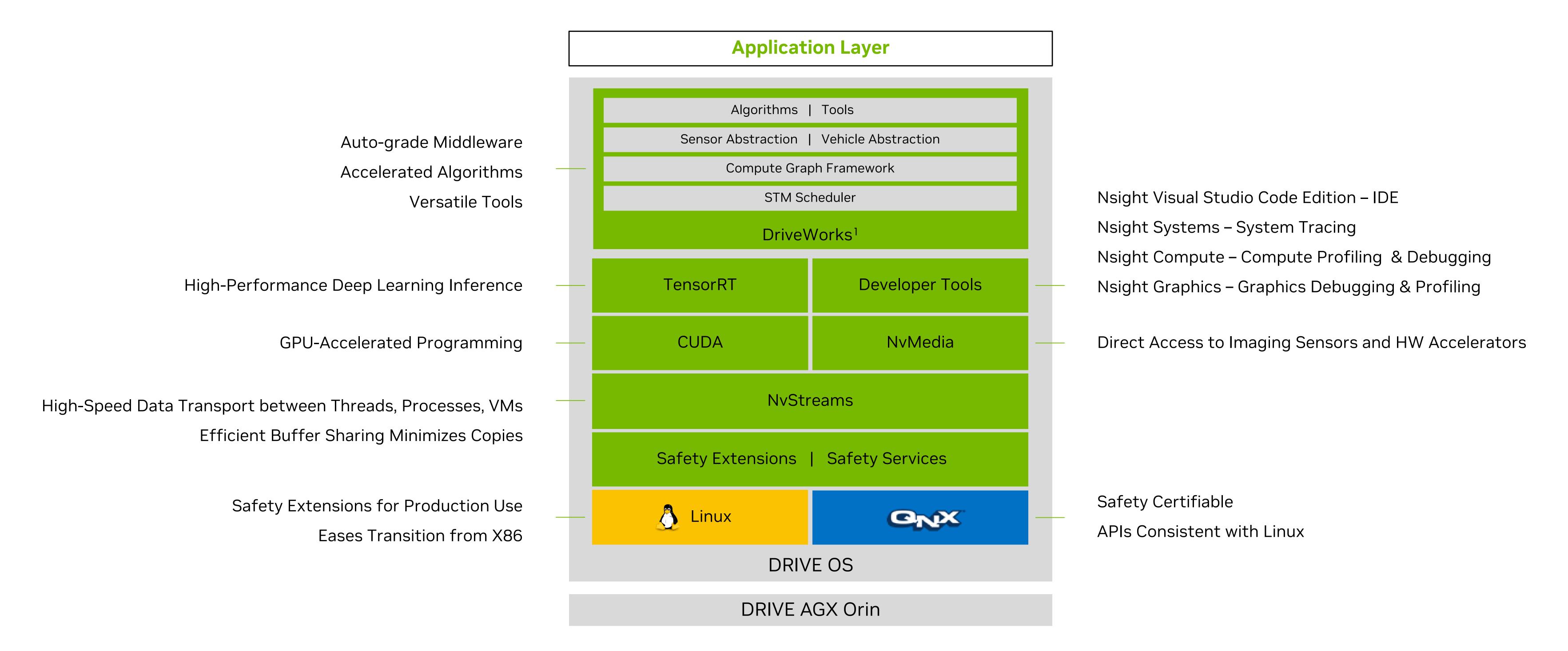
DRIVE OS – NVIDIA's AV Software Foundation

Operating system, foundational libraries, and tools for cutting-edge automotive applications

ISO 26262 & ASPICE Compliant (QNX) Automotive Standards Compliance ISO / SAE 21434 Compliant Support for Complex, High-performance Optimal Utilization of Orin's HW Accelerators Minimal Data Copies via NvStreams **AV Software Stacks** Smooth transition from X86 to DRIVE OS Linux Ease of Programming Safety-compliant CUDA and TensorRT



DRIVE OS Components



Link to DRIVE OS Documentation

Link to DriveWorks Documentation

¹ For development only



New with DRIVE 0S 6

Smoother development experience | All-new middleware features

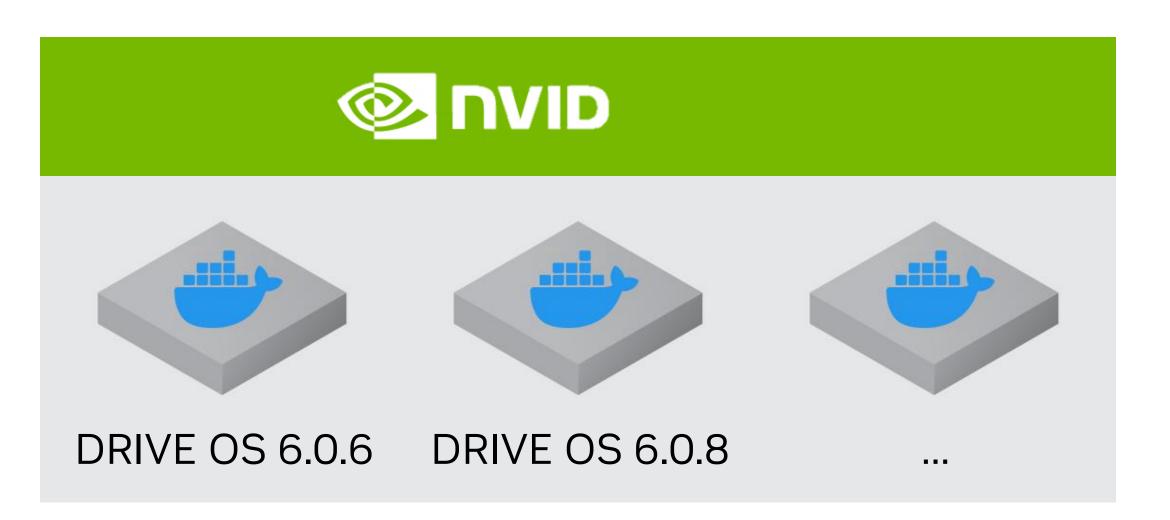
DRIVE OS 6 New Features

- Host and target Docker support
- Linux safety extensions
- Chip-to-chip communication via NvStreams

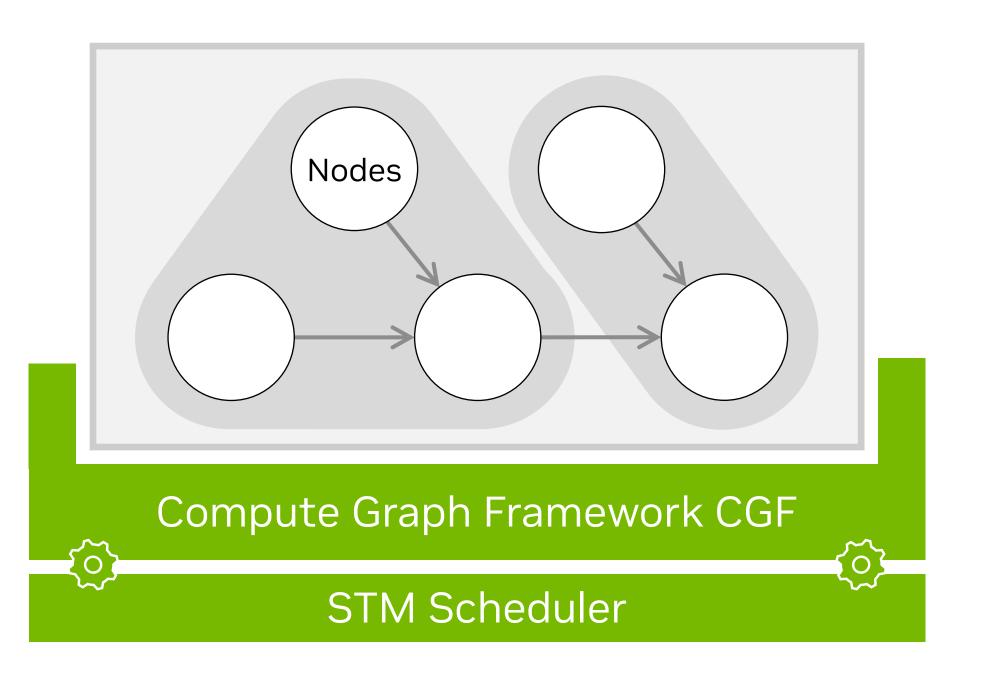
DriveWorks 5 New Features

DriveWorks becomes a full-fledged AV middleware:

- With Compute Graph Framework (CGF), applications can be expressed as graphs and nodes
- System Task Manager (STM) is a static, non-pre-emptive scheduler compiling an optimal schedule for CGF graphs



NGC is NVIDIA's Portal of Enterprise Services, Software, and Support for AI, Digital Twins, and High-Performance Computing





DRIVE OS 6 Software Components

Component	Version
Ubuntu Host Development Environment	20.04
Ubuntu Target Root File System ¹	
Linux Kernel ¹	5.10
Blackberry QNX SDP ²	7.1.1
Blackberry QNX QOS ²	2.2
QCC Toolchain	8.3
GCC Toolchain	9.3
C++ Feature set	17
DriveWorks ⁴	5.x
CUDA Toolkit	11.4
NVIDIA UDA CUDA Driver ¹ (x86)	r470
TensorRT	8.x ³
cuDNN	8.x ³
Vulkan	1.2
Wayland ¹	1.18
PKCS#11	Y

¹ Linux only, not available on QNX



³ Final version number TBD

 ² QNX only, not available on Linux
 ⁴ For development only



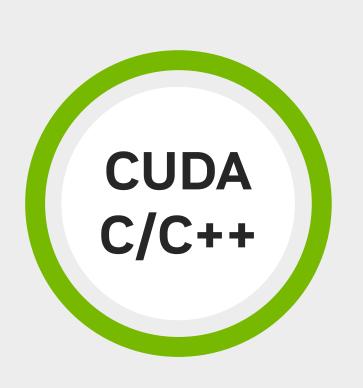
Why QNX for Safety?

Safety OS key selection criteria

- ISO 26262
 - ASIL D certified RTOS
 - TCL3 qualified toolchain
- POSIX PSE52 standards certification
 - Requirement for CUDA support
- Common Unix heritage with Linux
 - Rich dependent library support

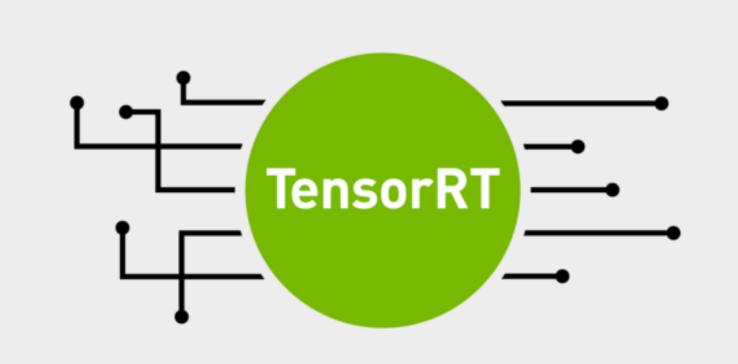
Hardware Accelerated Compute Engines

Open | Scalable | Seamless | End-to-end



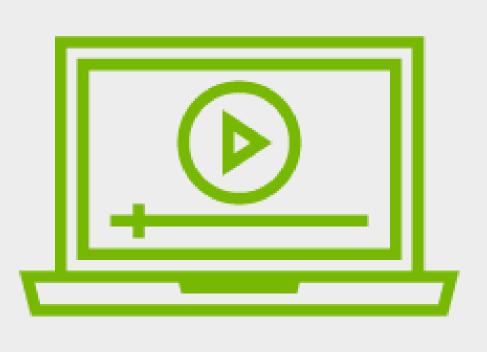
CUDA

Parallel computing model for compute intensive applications



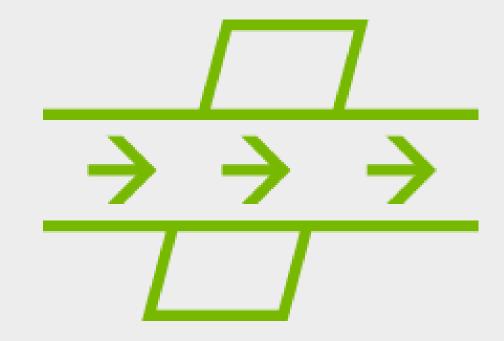
TensorRT

SDK for high-performance deep learning inference



NvMedia

Optimized API providing direct access to hardware accelerated compute engines and sensors, support Orin new Optical Flow Accelerator, DLA, AV1 encode & decode



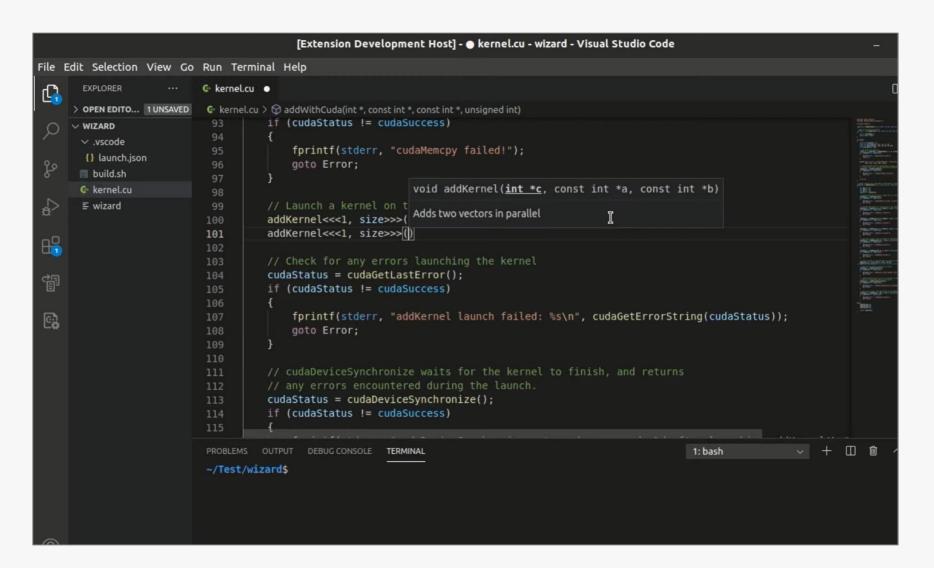
NvStreams

Highly efficient API enabling access to high-speed data transports, support over PCIe & Mellanox accelerated support across inter-ECU boundaries



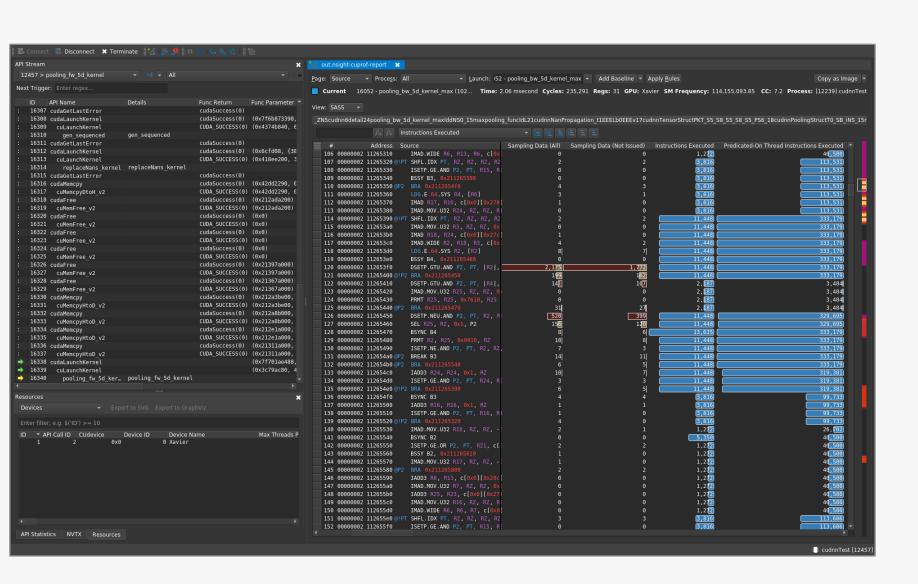
Nsight Developer Tools

For GPU and CPU software debugging and profiling



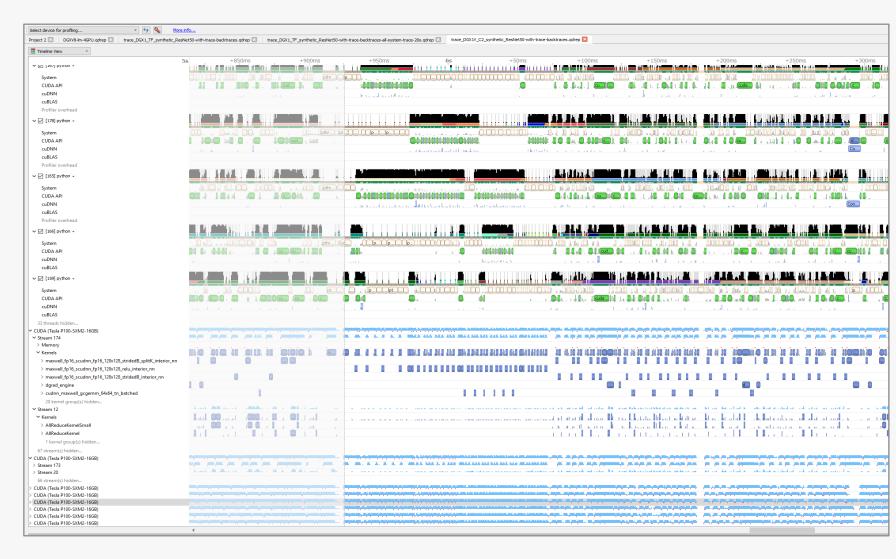
Nsight Visual Studio Code Edition

IDE GPU application development



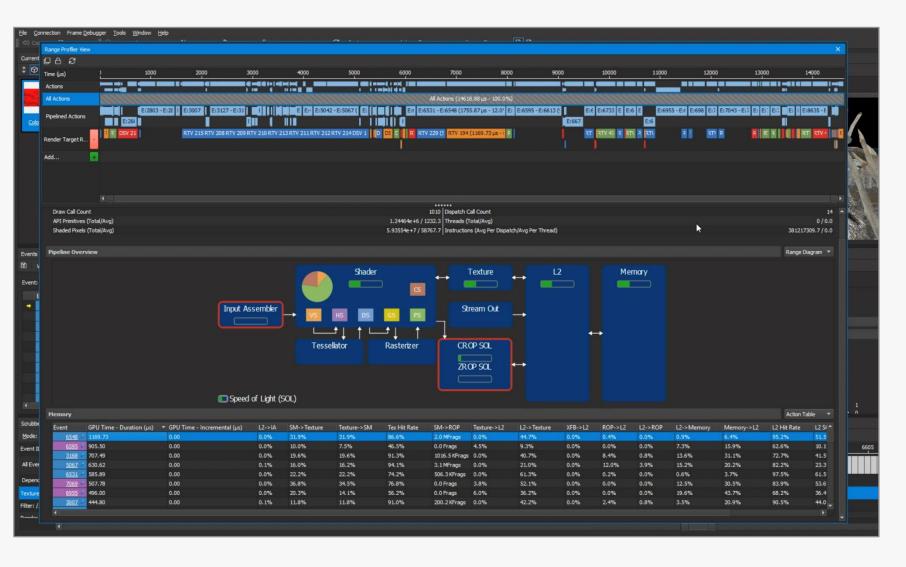
Nsight Compute

Compute profiling



Nsight Systems

System trace



Nsight Graphics

Graphics debugging & profiling

Maximized with NVTX source code instrumentation NVIDIA tools extension



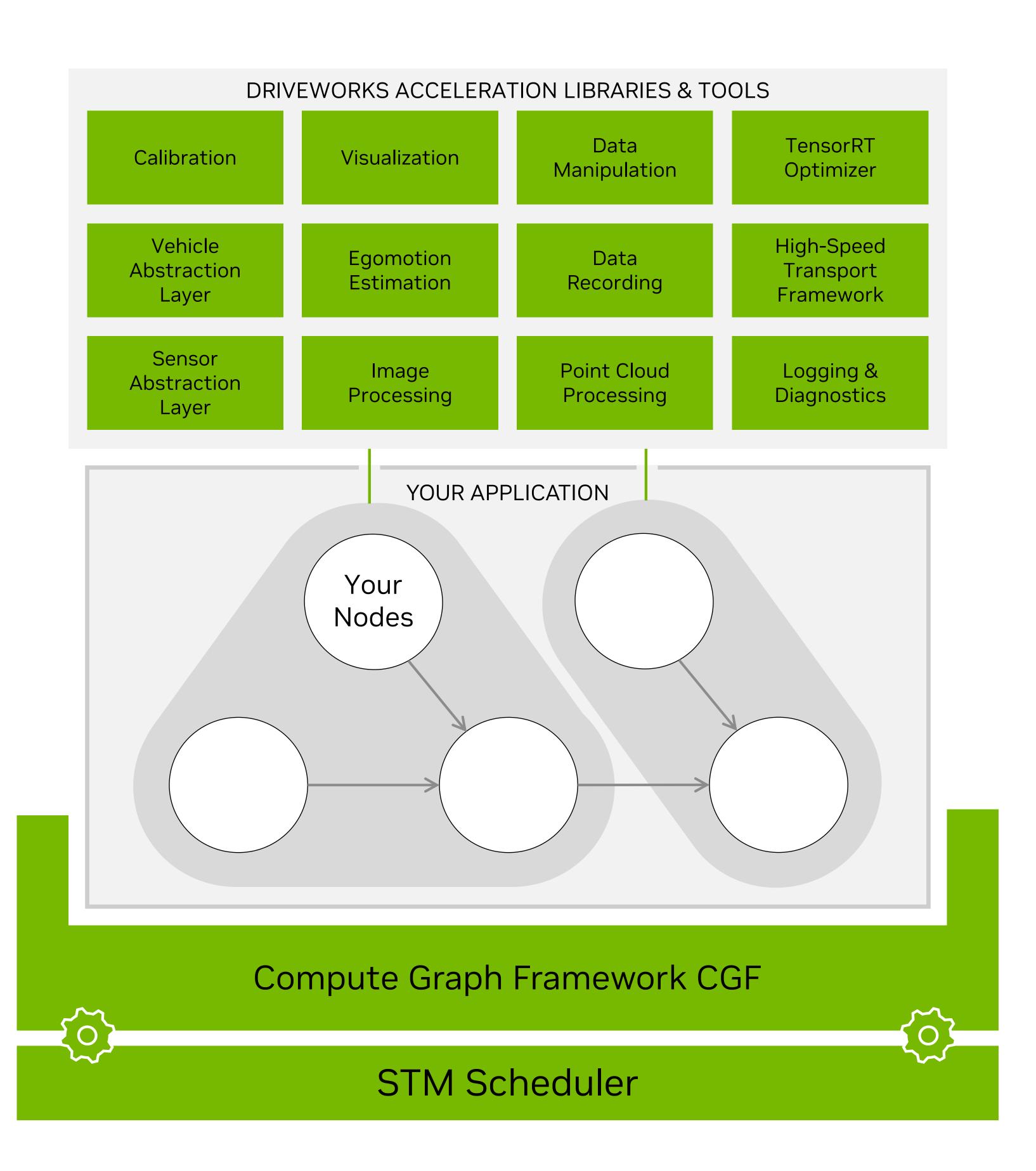
DriveWorks — Comprehensive Middleware Solution

Rich Library of Algorithms and Tools

to accelerate your applications

Compute Graph Framework

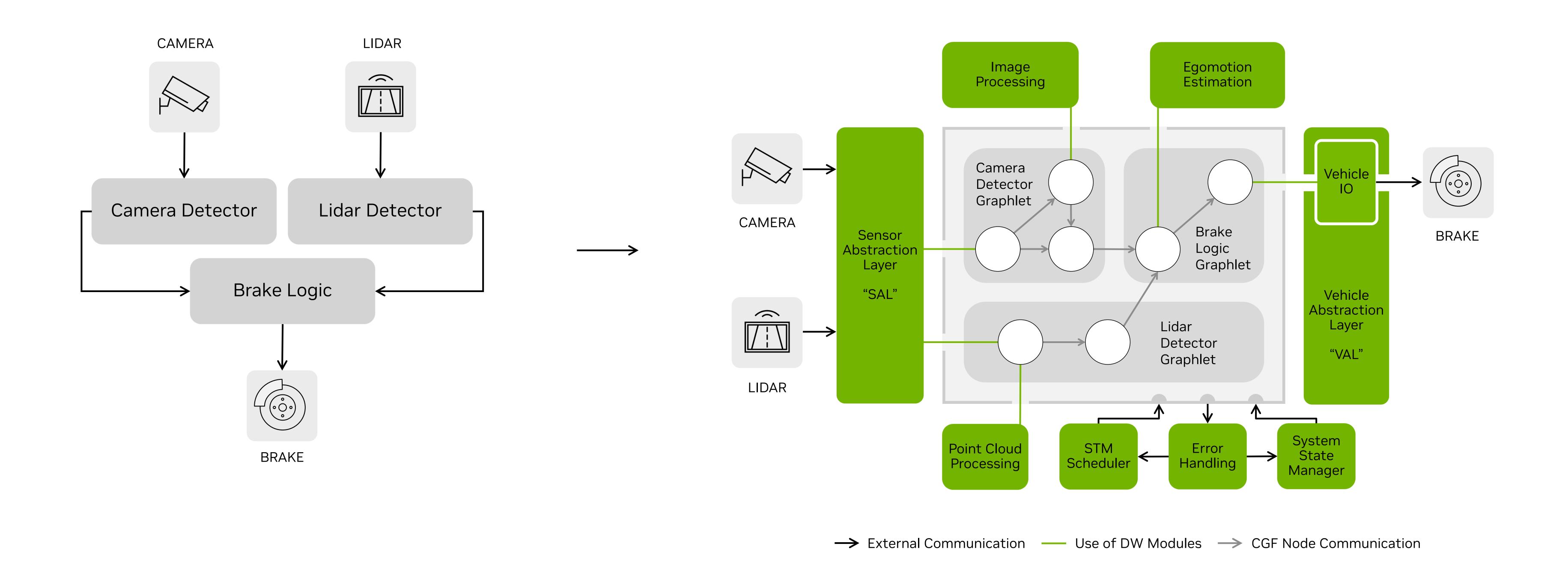
to leverage deterministic scheduling





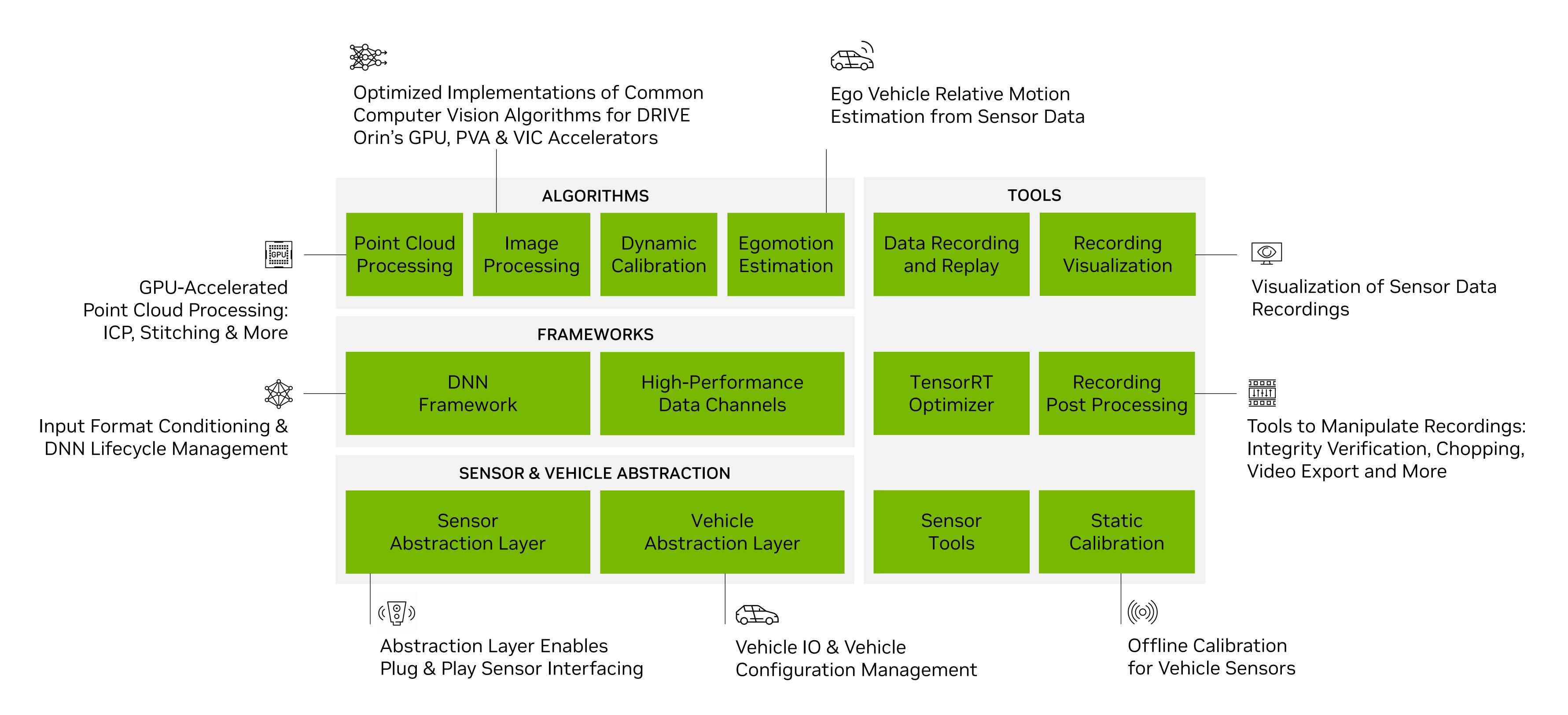
Exemplary Application as a Compute Graph

CGF enables structured and dependable software



DriveWorks Modules

A rich library of algorithms and tools to bootstrap AV development



Get Started with DRIVE SDK

Extensive documentation & training material available on NVIDIA Developer

Learn More

- Visit the <u>DRIVE training</u> page for webinars and other resources
- Check out information related to <u>DRIVE Hyperion</u>, <u>DRIVE AGX Orin</u> and <u>DRIVE SDK</u>

Get Access

- Join the <u>DRIVE AGX SDK Program</u> on NVIDIA Developer
- Read the docs for DRIVE OS and DriveWorks documentation
- <u>Download DRIVE OS</u> which includes DriveWorks, NvMedia, CUDA, cuDNN and TensorRT

Contact Us

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