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# BIOS 731: Advanced Statistical Computing

## Lecture 2 on Bayesian Computation

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- Monte Carlo integration
  - Suppose  $\theta \sim h(\theta)$  and we seek

$$\gamma \equiv E[f(\theta)] = \int f(\theta)h(\theta)d\theta$$

- If  $\theta_1, \dots, \theta_N \sim h(\theta)$ , we have

$$\widehat{\gamma} = \frac{1}{N} \sum_{j=1}^N f(\theta_j).$$

which converges to  $E[f(\theta)]$  with probability 1 as  $N \rightarrow \infty$ , by the Strong Law of Large Numbers.

- Variance estimate for  $\widehat{\gamma}$  is given by

$$\widehat{\text{Var}}(\widehat{\gamma}) = \frac{1}{N(N-1)} \sum_{j=1}^N [f(\theta_j) - \widehat{\gamma}]^2$$

- Histogram estimate

$$p \equiv P[a < \theta < b \mid \mathbf{y}] = E[I_{(a,b)}(\theta) \mid \mathbf{y}],$$

where  $I_{(a,b)}(\cdot)$  denotes an indicator function of set  $(a, b)$ . An estimate of  $p$  is given by

$$\hat{p} = \frac{\sum_{j=1}^N I_{a,b}(\theta_j)}{N} = \frac{\text{number of } \theta_j \in (a, b)}{N}.$$

What is the distribution of  $N\hat{p}$  and what is the standard error of  $\hat{p}$

- Kernel density estimate

$$\hat{p}(\theta \mid \mathbf{y}) = \frac{1}{Nh_N} \sum_{j=1}^N K\left(\frac{\theta - \theta_j}{h_N}\right),$$

where  $K$  is a “kernel” density (typically a normal or rectangular distribution) and  $h_N$  is a window width satisfying  $h_N \rightarrow 0$  and  $Nh_N \rightarrow \infty$  as  $N \rightarrow \infty$ .

- Let  $Y_i \sim N(\mu, \sigma^2)$ , for  $i = 1, \dots, n$  and suppose we adopt prior  $\pi(\mu, \sigma) = \frac{1}{\sigma}$ .  
Estimate  $E(\mu \mid \mathbf{y})$  and  $E(\mu/\sigma \mid \mathbf{y})$
- The joint posterior of  $\mu$  and  $\sigma^2$  is given by

$$\mu \mid \sigma^2, \mathbf{y} \sim N(\bar{y}, \sigma^2/n)$$

and

$$\sigma^2/K \mid \mathbf{y} \sim \chi_{n-1}^{-2}$$

where  $K = \sum_{i=1}^n (y_i - \bar{y})^2$ .

- Predictive probability  $P(Y_{n+1} > c \mid \mathbf{y})$ ?

- Example: Binomial model with non-conjugate prior.

$$Y \sim \text{Binomial}(n, \pi)$$

- The triangle prior

$$p(\pi) = \begin{cases} 8\pi & \text{if } 0 \leq \pi < 0.25 \\ \frac{8}{3} - \frac{8}{3}\pi & \text{if } 0.25 \leq \pi \leq 1 \\ 0 & \text{otherwise} \end{cases}$$

- The posterior will no longer be in a convenient distributional form.
- To find the posterior, we can use grid approximations

- The unnormalized posterior = the binomial likelihood  $\times$  the non-conjugate prior  
 $p(\pi | y) = f(y | \pi) \times p(\pi)/c$  with  $c = \int f(y | \pi)p(\pi)d\pi$
- How to find the normalized posterior?
- How to sample from the posterior?
- Grid Approximation
  1. Divide the region with positive unnormalized posterior into  $m$  grids, each of width  $k$ , starting from  $\pi_0$ .

$$\pi_0 + k, \pi_0 + 2k, \dots, \pi_0 + mk$$

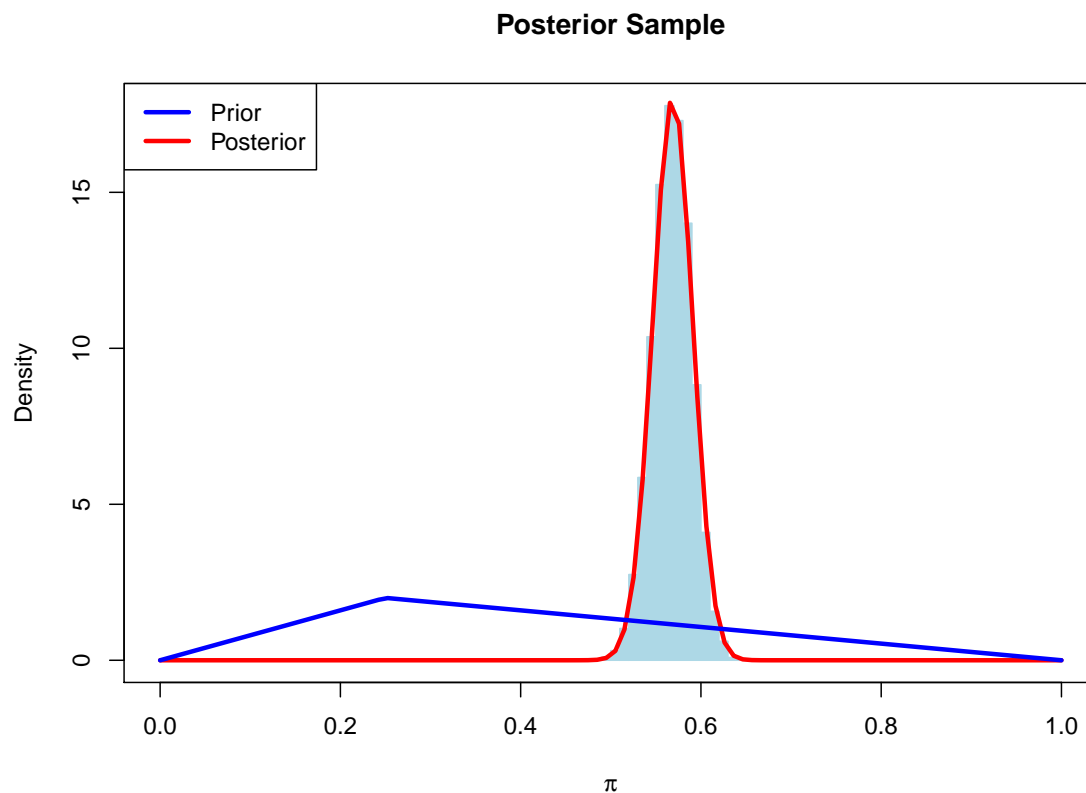
2. Evaluate each grid point  $(\pi_0 + ik)$  at the unnormalized posterior:  
 $f(y | \pi_0 + ik)p(\pi_0 + ik)$  for  $i = 1, \dots, m$ .

- Estimate  $c$  (area under the unnormalized posterior) as the sum of the areas of rectangles of width  $k$  and height at the unnormalized posterior ordinates:

$$c \approx \sum_{i=1}^m k f(y \mid \pi_0 + ik) p(\pi_0 + ik)$$

- Divide the unnormalized posterior ordinates by  $c$  to get the normalized posterior ordinates.

- We can also sample from our normalized posterior. Note that the normalized posterior ordinates are not probabilities, but rather the heights of the density. However, the “sample()” function in R will normalize the ordinates into probabilities.





- Suppose we wish to estimate the posterior mean

$$E[h(\theta) \mid \mathbf{y}] = \frac{\int h(\theta) f(\mathbf{y} \mid \theta) \pi(\theta) d\theta}{\int f(\mathbf{y} \mid \theta) \pi(\theta) d\theta}$$

- Working density  $g(\theta)$  (importance function)

- Roughly estimate  $\pi(\theta \mid \mathbf{y})$
- Can be easily sampled

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$$E[h(\theta) \mid \mathbf{y}] = \frac{\int h(\theta) w(\theta) g(\theta) d\theta}{\int w(\theta) g(\theta) d\theta} \approx \frac{\sum_j h(\theta_j) w(\theta_j)}{\sum_j w(\theta_j)}$$

where  $\theta_j \sim g(\theta)$  and  $w(\theta) = f(\mathbf{y} \mid \theta) \pi(\theta) / g(\theta)$  is a weight function.

- How closely  $g(\theta)$  resembles  $\pi(\theta \mid \mathbf{y})$  controls how good the approximation
  - Good approximation: weights are roughly equal
  - Bad approximation: some of weights are extremely high and some are closed to zero.

- Binomial model with non-conjugate prior (revisit)

$$Y \sim \text{Binomial}(n, \pi)$$

- The triangle prior

$$p(\pi) = \begin{cases} 8\pi & \text{if } 0 \leq \pi < 0.25 \\ \frac{8}{3} - \frac{8}{3}\pi & \text{if } 0.25 \leq \pi \leq 1 \\ 0 & \text{otherwise} \end{cases}$$

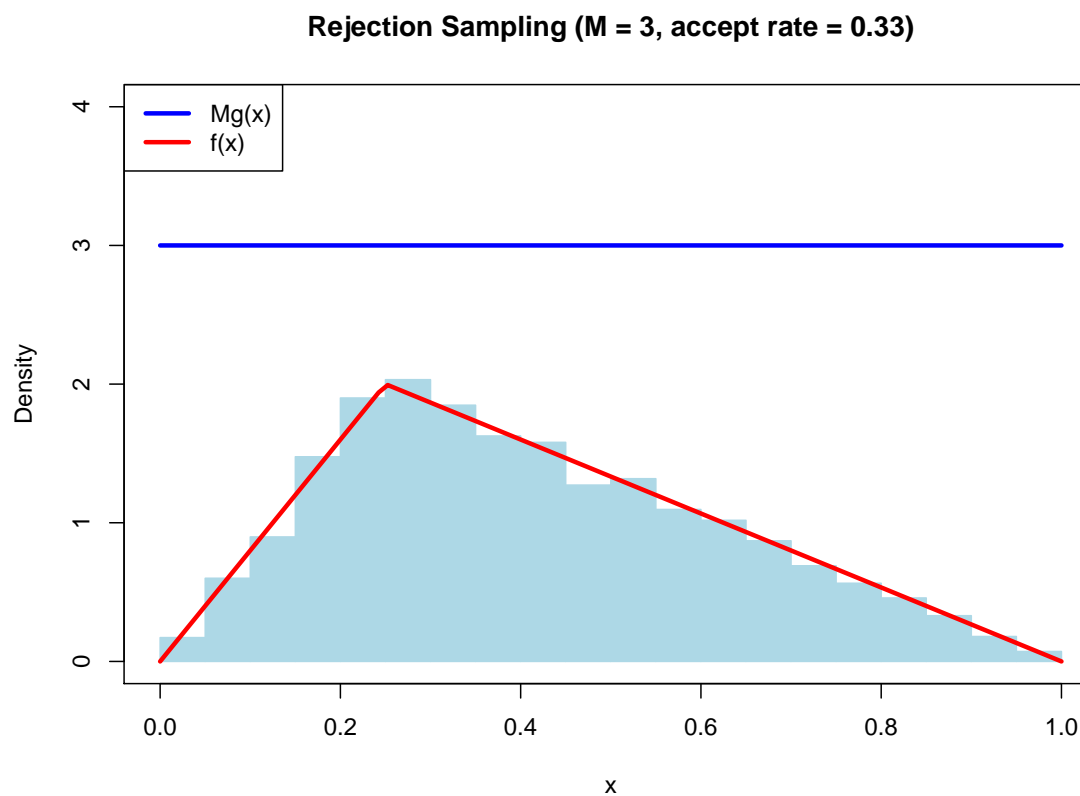
- Suppose we are interested in estimating posterior mean of  $h(\pi) = \pi(1 - \pi)$
- Importance sampling: how to choose  $g(\pi)$ ?

- Suppose we wish to sample from the target density:  $f(x)$  (could be unnormalized density)
- We need to pick a candidate density  $g(x)$  such that  $f(x) \leq Mg(x)$  for all  $x$ , where  $M$  is a constant.
- Repeat the following steps until we get  $m$  accepted draws:
  1. Draw a candidate  $x_c$  from  $g(x)$
  2. Calculate an acceptance probability  $\alpha$  for  $x_c$ 
$$\alpha = \frac{f(x_c)}{Mg(x_c)}$$
  3. Draw a value  $u$  from the Uniform (0,1) distribution
  4. Accept  $x_c$  as a draw from  $f(x)$  if  $\alpha \geq u$ . Otherwise, reject  $x_c$  and go back to step 1

- The target density: (the triangle density)

$$f(x) = \begin{cases} 8x & \text{if } 0 \leq x < 0.25 \\ \frac{8}{3} - \frac{8}{3}x & \text{if } 0.25 \leq x \leq 1 \\ 0 & \text{otherwise} \end{cases}$$

- The candidate density:  $g(x) = 1$  if  $0 \leq x \leq 1$ ,  $g(x) = 0$  otherwise.
- Set  $M = 3$ . Find a better  $M$ ?



- Similar to *sampling-importance resampling algorithm* (Rubin, 1988)
- Unnormalized target density:  $f(\theta)$
- Suppose an  $M$  appropriate for the rejection method is not readily available, but that we do have a sample  $\theta_1, \dots, \theta_N$  from some approximating density  $g(\theta)$ .

Define

$$w_i = \frac{f(\theta_i)}{g(\theta_i)} \quad \text{and} \quad q_i = \frac{w_i}{\sum_{j=1}^N w_i}$$

- Now draw  $\theta^*$  from the discrete distribution over  $\{\theta_1, \dots, \theta_N\}$  which places mass  $q_i$  at  $\theta_i$

$$\theta^* \sim \frac{f(\theta)}{\int f(\theta) d\theta}$$

- Why this is true?

- The target density: (the triangle density) (revisit)

$$f(x) = \begin{cases} 8x & \text{if } 0 \leq x < 0.25 \\ \frac{8}{3} - \frac{8}{3}x & \text{if } 0.25 \leq x \leq 1 \\ 0 & \text{otherwise} \end{cases}$$

- The working density:  $g(x) = 1$  if  $0 \leq x \leq 1$ ,  $g(x) = 0$  otherwise.

