For port b), see MATLAB

a) Show that worsefunction satisfies the TISE
$$H = -\frac{k^2 d^2}{2m dx_1^2} - \frac{k^2}{2m} \frac{d^2}{dx_2^2} + V(x_1 x_2)$$

$$V(x_1, x_2) = \begin{cases} 0, 0 < x_1 < 1 \text{ and } 0 < x_2 < 1 \\ \infty, \text{ otherwise} \end{cases}$$

$$t_e = [\beta_1(x_1) \beta_2(x_2) - \beta_1(x_3) \beta_2(x_1)] \times (1) \times (0)$$

 β_1 and β_2 are separately eigenstates of the Hamptonian $\hat{H} \hat{\beta}_1 = E_1 \hat{\beta}_1$

$$\frac{(e.g. - \frac{1}{4}z)^{2}}{am \int_{X_{1}^{2}}^{Z} f(x)} = \sqrt{2} \left(\frac{+\frac{1}{4}z}{2m} \right) sm(\pi x_{1}) \pi^{2} - \frac{1}{2m} \int_{X_{2}^{2}}^{Z} f(x_{1}) dx = \frac{1}{2m} \int_{X_$$

Write
$$\hat{H} = \hat{h}(x_1) + \hat{h}(x_2)$$
 $\hat{h}(x_1) = -\frac{k^2}{2m} \frac{\partial^2}{\partial x_1^2}$
$$\hat{h}(x_2) = -\frac{k^2}{2m} \frac{\partial^2}{\partial x_2^2}$$

$$\hat{h}(x_1) \not = E_1 \not = (x_1)
\hat{h}(x_2) \not = E_2 \not = (x_2)
\hat{h}(x_1) \not = E_2 \not = (x_2)
\hat{h}(x_2) \not= E_2 \not= (x_2)$$

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$$\hat{H} = \hat{h}(x_1) + \hat{h}(x_2)$$

$$\hat{H}Y_{e} = (\hat{h}(x_{1}) + \hat{h}_{2}(x_{2}))(p_{1}(x_{1}) p_{2}(x_{2}) - p_{1}(x_{2}) p_{2}(x_{1}))$$

$$= E_{1} \phi_{1}(x_{1}) \phi_{2}(x_{2}) - E_{2} \phi_{1}(x_{2}) \phi_{2}(x_{1}) + E_{2} \phi_{1}(x_{1}) \phi_{2}(x_{2}) - E_{1} \phi_{1}(x_{2}) \phi_{2}(x_{1})$$

$$= (E_1 + E_2) (\phi_1(x_1) \phi_2(x_2) - \phi_1(x_2) \phi_2(x_1))$$

$$= (E_1 + E_2) \phi_2(x_1) \phi_2(x_2) - \phi_1(x_2) \phi_2(x_1)$$

