

$$f_1 = \sqrt{\alpha} e^{-\alpha |x - \frac{\alpha}{2}|}$$
  
 $f_2 = \sqrt{\alpha} e^{-\alpha |x + \frac{\alpha}{2}|}$ 

$$\alpha = \frac{MV_0}{4^2}$$

$$\epsilon = -\frac{MV_0^2}{24^2}$$

$$\hat{H} = \hat{T} + \hat{V} = \hat{T} + \hat{V}_{1} + \hat{V}_{2}$$
whh  $V_{1}(x) = -V_{0} S(x - \alpha_{2})$ 

$$V_{2}(x) = -V_{0} S(x + \alpha_{2})$$

$$\begin{aligned}
(f_{1}|\hat{H}|f_{1}) &= (f_{1}|\hat{T}+\hat{V}_{1}|f_{1}7 + (f_{1}|\hat{V}_{2}|f_{1}7) \\
&= -\varepsilon - V_{0}\int_{-\infty}^{\infty} |x|f_{1}(x)|^{2} \delta(x+v/2) \\
&= -\varepsilon - V_{0}|f_{1}(x=-v/2)|^{2}
\end{aligned}$$

$$\begin{aligned}
H_{11} &= \varepsilon - V_{0} \propto \varepsilon^{-2\alpha\sigma}
\end{aligned}$$

$$H_{12} = \langle f_{1} \hat{f} \hat{f} | f_{2} \rangle + \langle f_{1} \hat{i} \hat{k} | f_{2} \rangle + \langle f_{1} \hat{i} \hat{k} | f_{2} \rangle$$

La By symmetry, those two hove got to be the same - only need to do entry ral once

Now 
$$(f, |\hat{f}|f_3) = \int_{-\infty}^{\infty} dx f_1(x) \frac{-t^2}{am} \frac{d^2}{dx^2} f_2(x)$$

Now we have the slight problem that  $\frac{\int_{-\infty}^{2} f_{z}}{\int_{x^{2}}^{2}}$  is infinite at x=-0/2, so we have to deal who this singularity. Away from this singularity

$$\frac{d^{2} f_{2}(x)}{dx^{2}} = \int \alpha^{\frac{6}{12}} e^{-\alpha(x+\frac{6}{12})} x^{\frac{-6}{12}}$$

$$\begin{cases} \alpha^{\frac{6}{12}} e^{+\alpha(x+\frac{6}{12})} & x > -\frac{6}{12} \end{cases}$$

So
$$\left\langle f_{1} | \hat{T} | f_{2} \right\rangle = \frac{-\frac{1}{2} - \varepsilon}{2m} \left( dx \propto^{\frac{1}{2}} e^{+ \alpha (x - \frac{9}{2})} \right) \sqrt{\frac{1}{2}} e^{\alpha (x + \frac{9}{2})} \rightarrow I_{1}$$

$$+ \frac{2}{2m} \int_{-\frac{\pi}{2}+\epsilon}^{\frac{\pi}{2}} dx \propto \frac{1}{2} e^{+\alpha(x-\frac{\pi}{2})} \propto \frac{1}{2} e^{-\alpha(x+\frac{\pi}{2})} \rightarrow T_2$$

$$+\frac{t^{2}}{2m}\int_{0}^{\infty}dx \propto^{\frac{1}{2}}e^{-\alpha(x-\frac{1}{2})} dx = \frac{1}{2}e^{-\alpha(x+\frac{1}{2})} \rightarrow I_{3}$$

$$-\frac{t^{2}}{2m}\int_{0}^{\infty}dx + f_{1}(x)\frac{d^{2}f_{2}(x)}{dx^{2}} \rightarrow I_{4}$$

All of these integrals are straightforward & fake Im

Pull out 23 (-52)

E>0

T - (1x 22xx

$$T_{1} = \int dx e^{2\alpha x}$$

$$= \frac{1}{2\alpha} e^{2\alpha x} \Big|_{=\frac{1}{2\alpha}} e^{-2\alpha x} = \frac{1}{2\alpha} e^{-2\alpha x} = T_{1}$$

$$T_2 = \int dx e^{-2\alpha \theta/2}$$

$$I_3 = \int_{0}^{\infty} dx e^{-2\alpha x} = -\frac{1}{2\alpha} e^{-2\alpha x}$$

$$I_3 = \frac{1}{2\alpha} e^{-2\alpha x} \implies same \text{ as } I_1 \text{ } I_2$$

$$I_4 = \lim_{\epsilon \to 0} \int_{-\alpha_k - \epsilon}^{-\alpha_k + \epsilon} dx \, f_i(x) \, \frac{d^2 f_2(x)}{dx}$$

$$=\lim_{\varepsilon\to0}f_1\left(-\frac{a_2}{2}\right)\int_{-\frac{a_2}{2}}^{-\frac{a_2+\varepsilon}{2}}dx\frac{\int_{-\frac{a_2}{2}}^{2}f_2(x)}{dx^2}$$

$$= f_1(-\frac{\alpha}{6}) \lim_{\epsilon \to 0} \left( \frac{2}{dx} \frac{d^2 k}{dx^2} = f_1(-\frac{\alpha}{2}) \left( \frac{-2m \sqrt{6}}{4^2} \right) \frac{4}{5} (0) \right)$$



$$\langle f_1|\hat{T}|f_2\rangle = -\frac{k^2}{\lambda m} \alpha^3 \left(\frac{1}{2\alpha}e^{-\alpha a} + 0e^{-\alpha a} + \frac{1}{2\alpha}e^{-\alpha a}\right)$$

$$=\frac{k^2}{2m}\left(2\alpha^2-\alpha^2-\alpha^3d\right)e^{-\alpha a}$$

$$\int T_{12} = \frac{k^2}{2m} \left( \alpha^2 - \alpha^3 a \right) e^{-\alpha a} = T_{21}$$

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$$H = \left[ \frac{\xi - V_0 \propto e^{-2 \times d}}{\left[ \frac{\xi^2}{2m} (\alpha^2 - \alpha^3 \alpha) - 2V_0 \propto \right]} e^{-2 \times d} \right]$$

$$= \begin{bmatrix} \varepsilon - h_{i}(a) & h_{i}(a) \\ h_{i}(a) & \varepsilon - h_{i}(a) \end{bmatrix}$$

Now for the S motive,  $f_1$  and  $f_2$  are normalized so  $S_{11} = \langle f_1 | f_1 \rangle$  and  $S_{22} = \langle f_2 | f_3 \rangle$  are both one.

$$S_{12} = \langle f_1 | f_2 \rangle = \int_{-\infty}^{\infty} dx \, f_i(x) \, f_2(x)$$

$$= \int_{-\infty}^{-\alpha/2} dx \propto e^{+\alpha(x+\alpha/2)} e^{+\alpha(x-\alpha/2)}$$

$$+ \int_{-\infty}^{\alpha/2} dx \propto e^{-\alpha(x+\alpha/2)} e^{+\alpha(x-\alpha/2)}$$

$$+ \int dx \propto e^{-\alpha(x+0)} e^{-\alpha(x-0)}$$

$$= (\alpha a + 1)e^{-\alpha d} = s(a)$$

$$S = \begin{bmatrix} 1 & S(a) \end{bmatrix}$$

So now the task of to solve

$$(H - SE) \begin{pmatrix} 4 \\ 4 \\ 2 \end{pmatrix} = 0$$

or 
$$S^{-1}H\begin{pmatrix} c_1 \\ c_2 \end{pmatrix} = E\begin{pmatrix} c_1 \\ c_2 \end{pmatrix}$$

The motify 5th dopends on &...

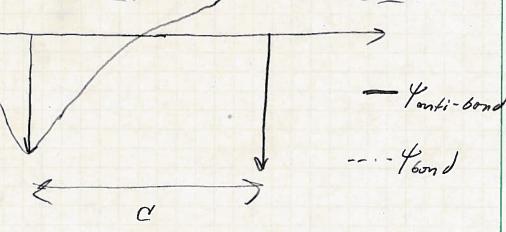
SER MATEAB code,
for solf and plot

By symmetry the only reasonable ergenvectors

$$\frac{1}{2}bond = \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix} \qquad \text{touti-bond} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

Any other ergenvectors (orbital combinations) would fover one side of this motocule more from the other.

As the S-functions get doser together the antibonding orbital has a steeper ond stopper stope between the S-functions



While the bonding orbital remotes smooth.
The kineter energy of the donding orbital
gets very high for the antibonding
orbital and is not compensated for by
the Lower potential energy.

The MATLAB plot shows the energy for the bonding and antibonding orbitals as a fen of a.