

Feature Output

Image

Kernel
Filter
Patch

Image (F)

↓
(F) Kernel (convolving)

↓

Output Feature

$I(5 \times 5)$

$\rightarrow K(3 \times 3)$

$\rightarrow O(3 \times 3)$

$I(5 \times 5)$

$\xrightarrow{K(3 \times 3)} O(3 \times 3)$

25

9

Loss of Info

Image :- $\underline{h} \times \underline{w} \times \underline{d} \rightarrow (1, 3)$

SD $\rightarrow 480$
 FHD $\rightarrow 720$
 4K $\rightarrow 3096$
 8K \rightarrow
 2K $\rightarrow 1500$

$\left\{ \begin{array}{l} \text{B/W} \\ \text{colours} \end{array} \right\}$

High Processing

3	3	2	1	0
0_0	0_1	1_2	3	1
3_2	1_2	2_0	2	3
2_0	0_1	0_2	2	2
2	0	0	0	1

12.0	12.0	17.0
10.0	17.0	19.0
9.0	6.0	14.0

Kernel Value Matrix

$$\begin{bmatrix} 0 & 1 & 2 \\ 2 & 2 & 0 \\ 0 & 1 & 2 \end{bmatrix}$$

Image Matrix

$$\begin{bmatrix} 3 & 3 & 2 & 1 & 0 \\ 0 & 0 & 1 & 3 & 1 \\ 3 & 1 & 2 & 2 & 3 \\ 2 & 0 & 0 & 2 & 2 \\ 2 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$$= (0 \times 3) + (1 \times 3) + (2 \times 2) \neq$$

$$(2 \times 0) + (2 \times 0) + (0 \times 1) = 0$$

$$(0 \times 3) + (1 \times 1) + (2 \times 2) = 5$$

$$\begin{array}{ccc} \text{Image} & \xrightarrow{K(3 \times 3)} & \text{Output} \\ (5 \times 5) & & (3 \times 3) \end{array}$$

$$(5 \times 5) \xrightarrow{K(5 \times 5)} (1 \times 1)$$

$$(7 \times 7) \xrightarrow{K(7 \times 7)} (1 \times 1)$$

$$(7 \times 7) \xrightarrow{K(3 \times 3)} (5 \times 5) \xrightarrow{K(3 \times 3)} 3 \times 3$$

$$\begin{array}{l} I \rightarrow 7 \times 7 \\ \quad \downarrow K(3 \times 3) \\ 5 \times 5 \\ \quad \downarrow K(3 \times 3) \\ 3 \times 3 \end{array}$$

$$9 \times 9$$

$$\downarrow K(3 \times 3)$$

$$7 \times 7$$

$$\downarrow K(3 \times 3)$$

$$5 \times 5$$

$$\downarrow K(5 \times 5)$$

$$1 \times 1$$

Odd Filters

Even (Rare)

$$99 \times 99$$

$$\downarrow K(3 \times 3)$$

$$97 \times 97$$

$$\downarrow K(3 \times 3)$$

$$95 \times 95$$

$$\downarrow K(5 \times 5)$$

$$91 \times 91$$

$$\downarrow K(7 \times 7)$$

$$85 \times 85$$

$$3 \times 3 \rightarrow 2$$

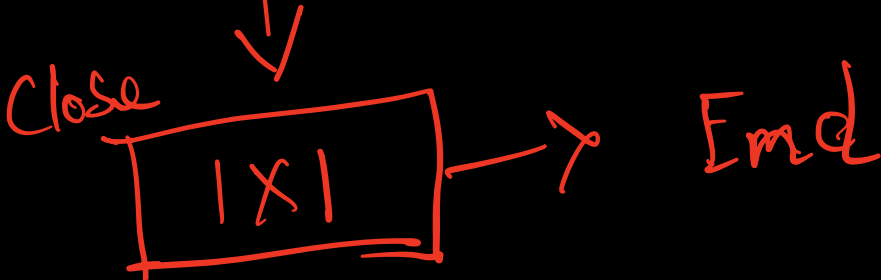
$$5 \times 5 \rightarrow 4$$

$$7 \times 7 \rightarrow 6$$

Assume



Multiple Layers

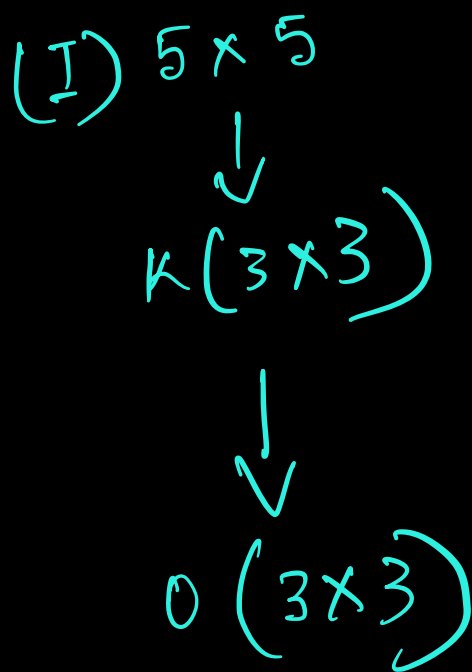


$$3 \times 3$$
$$5 \times 5$$

I have captured all the features

Filter/Kernel \rightarrow looking on image
 \searrow Feature Extractor

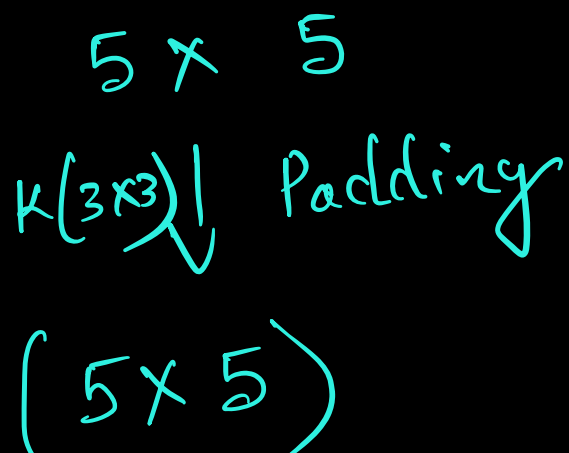
Padding

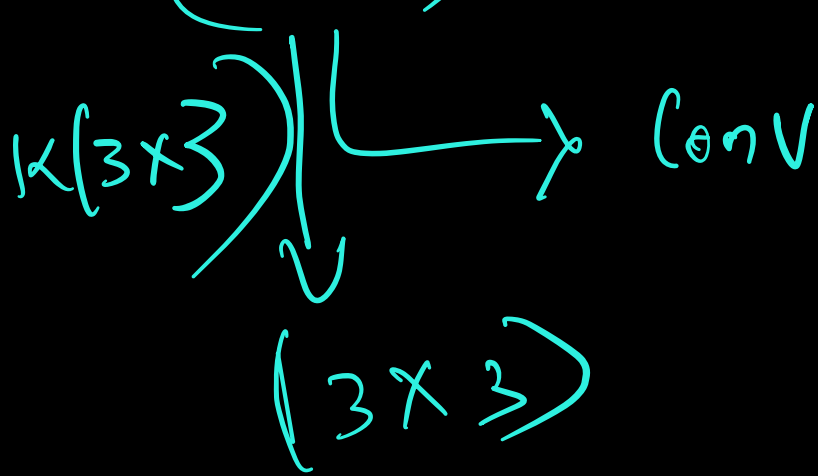


Loss of Info

Dim changed

Retain the dim.





(100×100)
 (3×3)

2
 0 49/50

1×1

Layers
50 layers

(1000×1000)
 $K(3 \times 3)$

= 500 layers

(1×1)

(Max Pooling)

Padding

7 x 7

K(3 x 3) | P = 1

O(5 x 5) | O(7 x 7)

↓

3 x 3

↓

1 x 1

Conv

↓

Kernel / Filter (3 x 3)

↓ K(3 x 3)

5 x 5

↓

3 x 3

↓

1 x 1

CNN Output Size Formula

$$\text{Output Size} = \left\lceil \frac{N - F + 2P}{S} \right\rceil + 1$$

$N \rightarrow$ Input Size ($h \times w$) ($7 \times 7, 100$)

$F \rightarrow$ Filter/Kernel Size

$P \rightarrow$ Padding

$S \rightarrow$ Stride

$$I \quad 30 \times 30 \quad K (3 \times 3) \quad P = 0 \quad S = 1$$

Flow

$$O = \left[\frac{30 - 3 + 2 \cdot 0}{1} \right] + 1$$

$$O = 27 + 1$$

$$O = 28$$

$$I \quad 60 \times 60 \quad K 7 \times 7 \quad P = 0 \quad S = 2$$

$$O = \frac{60 - 7}{2} + 1$$

$$0 = \frac{53}{2} + 1$$

$$= 26.5 + 1$$

$$= 26 + 1$$

$$= 27$$

$$60 \times 60$$

$$27 \times 27$$

$$r = w$$

$$K(5 \times 5)$$

$$p = 1$$

$$s = 1$$

$$h_{50} \times w_{40}$$

$$h_{50} = \left[\frac{50 - 5 + 2}{1} \right] + 1$$

$$= 45 + 3 = 48$$

$$w_0 = 38$$

Filter Size

Input \rightarrow

7×7

5×5

3×3

1×1



$K(3 \times 3)$
 $K(5 \times 5)$

7×7



3×3 $K(3 \times 3)$



1×1

Parameters

$K(3, 3)$

$= 9$

$K(7, 7)$

$= 49$

$= 3(3 \times 3)$

$K(5, 5)$

$= 25$

$= 2(3 \times 3)$

$K = 5 \times 5$

$K = 3$

$$I = 7 \times 7$$

$$K = 7 \times 7$$

$$O = 1 \times 1$$

$$3 \times 3$$

$$3$$

$$\begin{Bmatrix} 7 \times 7 \\ 5 \times 5 \\ 3 \times 3 \\ 1 \times 1 \end{Bmatrix}$$

$$5 \times 5$$

$$2(3 \times 3) \begin{Bmatrix} 3 \times 3 \\ 1 \times 1 \end{Bmatrix}$$

$$5 \times 5$$

$$= 25$$

$$2(3 \times 3)$$

$$= 18$$

$$7 \times 7$$

$$3(3 \times 3)$$

$$= 27$$

$$\left\{ \frac{\text{Less Parameters}}{} \right\}$$

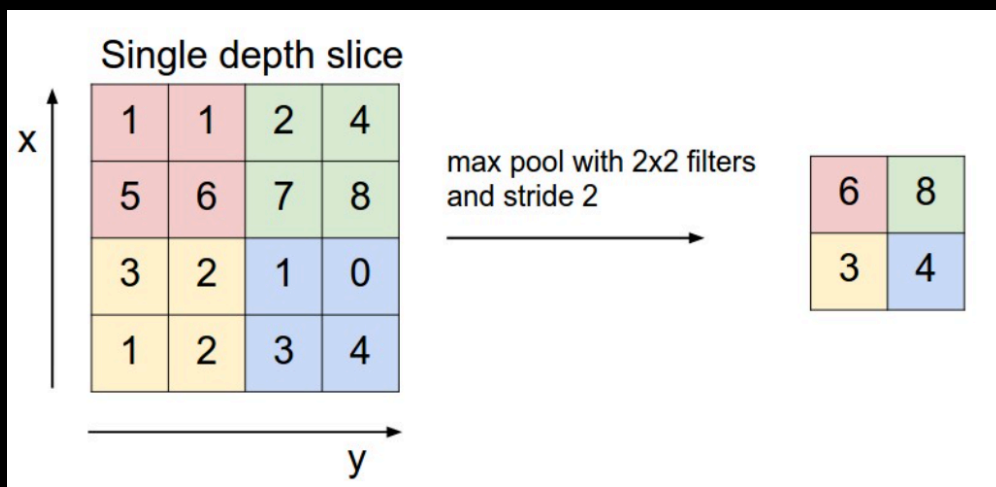
$$80\% (3, 3)$$

$$(5, 5)$$

$$20\%$$

$$(7 \times 7)$$

$$(11 \times 11)$$



Dim loss

$$I = 4 \times 4$$

$$O = 2 \times 2$$

$$= 50\%$$

Info loss = 16

$$4/16 = 25\%$$

75% loss

Pooling

Max, Min, Avg (Mean)

Why?

Dimension Loss

Pure Conv

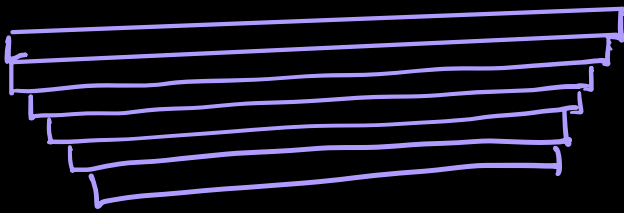
Con + Max

$$100 \times 100$$

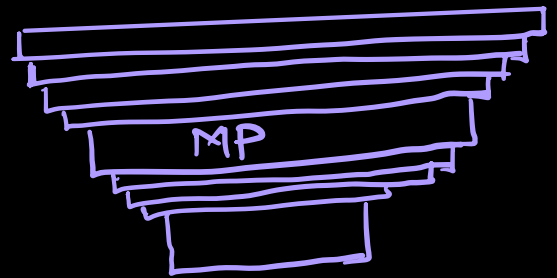
$$= 50 \text{ layers}$$

$$100 \times 100$$

$$\frac{2}{0}$$



100×100
 98×98
 96×96
 94×94
 92×92
 90×90



100×100
 98×98
 96×96
 94×94
 47×47
 45×45
 43×43
 41×41
 20×20

less than

50

50 Layer

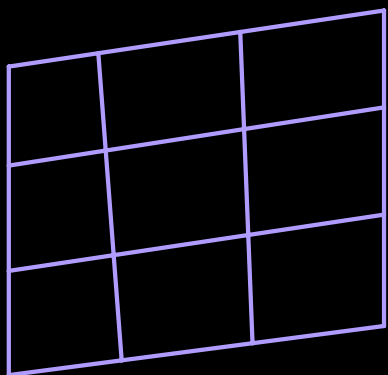
Stride \rightarrow skip
(2)

$N = 100$, $F = 3$, $S = 1$

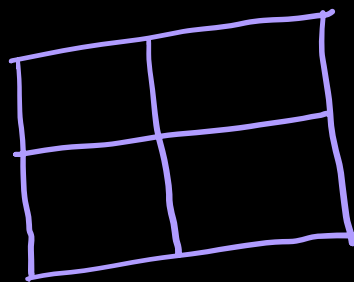
$\{1 \times 1\}$

$\left\{ \begin{array}{l} 2 \times 2 \\ 3 \times 3 \\ 5 \times 4 \end{array} \right\} \quad 4 \times 4$

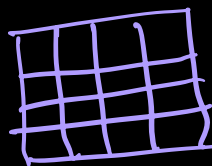
$I(4 \times 4) \quad (2, 2)$
 $K(4, 4) \quad K(2, 2)$
 $\rightarrow 1 \times 1 \leftarrow$



3x3



2x2



Symmetry Issue

Dimensions

$K(3, 3)$

Size

No of Filters

$2^2 (8, 16, 32, 64)$

P, S

Filter \rightarrow Feature Extraction

More Filter \rightarrow More Feature Extraction

32 Filters \rightarrow 32 Features

64 Filters \rightarrow 64 Features

$(3 \times 3) 64$

$(5 \times 5) 128$

Input $(30 \times 30 \times 3)$

Conv 1, $K(3 \times 3)$, No of Filters $\frac{=16}{32}$, $P=0$
 $S=1$

$$I = 30 \times 30 \times 3$$

$$\text{Conv} = 28 \times 28 \times 16$$

$$\text{Conv} = 26 \times 26 \times 32$$

$$I \text{ layer} = 30 \times 30 \times \textcircled{3}$$

Depth



Channels



Feature Map



Feature Output

Kernel High

Increase in Parameters

$$30, 30 \quad 7 \times 7$$

$$\frac{N - K + 2P}{1}$$

=

11

$$30 - \textcircled{7} + 0$$

11

23