

# Xulun Luo, Software Engineer

Pittsburgh, PA, +1(347)-393-3053,

xulunl@andrew.cmu.edu | <http://www.linkedin.com/in/xulun-luo/> | <https://xl3874.wixsite.com/fieldxulunluo>

## PROFILE

Software engineer with a dual background in film and computer science, specializing in entertainment technology, game design pipelines, and immersive virtual environments. Experienced in virtual production R&D, sensor fusion, and real-time systems integration, as well as Unity-based prototyping and gameplay mechanics.

## EDUCATION

Sep 2021 — May 2025	Bachelor of Arts, New York University <b>Double Major Cinema Studies, Computer Science</b>	New York, NY
Aug 2025 — May 2027	Master of Entertainment Technology, Carnegie Mellon University(CMU)	Pittsburgh, PA

## EXPERIENCE

Feb 2025 — May 2025	Software R&D Intern   WLab Virtual Production – Madwell LLC	New York, NY
<ul style="list-style-type: none"><li>• Prototyped UWB-assisted camera-tracking pipeline to augment OptiTrack under occlusion; streams 6-DoF pose at 25Hz over UDP with sequence IDs and jitter-tolerant buffering.</li><li>• Fused UWB + IMU data with error-state Kalman filter and per-rig extrinsics calibration to stabilize position tracking.</li><li>• Built Python LTC frame-sync system for sensors, cameras, and LED-wall renders; eliminated parallax jitter through rate/buffer tuning. Standardized schemas, calibration procedures, and logging tools for synchronized datasets.</li><li>• Deployed internally for active dataset generation supporting model training.</li></ul>		
Jun 2025 — Sep 2025	Visiting Researcher   AirLab – CMU	Pittsburgh, PA
<ul style="list-style-type: none"><li>• Built UE4 + AirSim research pipeline for 3D reconstruction benchmarking in dynamic scenes with novel view, featuring automated scene packaging, OctoMap navigation, and covisibility-guided evaluation with ground truth validation.</li><li>• Implemented dynamic-scene framework with moving actors, static occupancy mapping, and collision-safe path planning, generating synchronized GT outputs (RGB, depth, optical flow) for reconstruction evaluation.</li><li>• Integrated Fast-Planner for global planning and EGO-Planner for real-time obstacle-aware trajectory refinement.</li><li>• Created UE4 testbed with scripted dynamic objects for planner benchmarking and virtual-drone avoidance testing.</li></ul>		

## PROJECTS

Aug 2025 — Sep 2025	Programmer   Gasoline Transportation Ally   Unity 3D Game	ETC   CMU, Pittsburgh, PA
<ul style="list-style-type: none"><li>• Co-designed custom physical controller integrating Xbox Adaptive Controller with pressure sensors and gyroscope mechanics for accessible gameplay.</li><li>• Architected scalable game system with modular entity management, real-time resource tracking, and state-based logic handling concurrent multi-vehicle interactions.</li><li>• Implemented collision detection, timer mechanics, and priority-based target systems using optimized algorithms and design patterns for maintainable code.</li></ul>		
Sep 2025 — Oct 2025	Programmer   The Nightcap Bar   Unity 3D VR Game	ETC   CMU, Pittsburgh, PA
<ul style="list-style-type: none"><li>• Built complete VR bartending simulation for Meta Quest 3, integrating custom shader programming, liquid pouring mechanics, and event-driven narrative system.</li><li>• Implemented complete drink-making mechanics including shaker physics (shake/blend detection), garnish placement, and disposal system.</li><li>• Designed intuitive VR interactions enabling first-time VR users to complete the full mystery narrative gameplay without assistance, confirmed by playtesting.</li></ul>		

## SKILLS & LANGUAGES

Unreal Engine 4/5 | Unity 3D | C++ | C# | C | Python | Java | Virtual Production | VR/XR Interaction | Real-Time Systems | Raspberry Pi 4/5 | Arduino Nano | Camera Tracking | Sensor Fusion | UDP Networking | Timecode / LTC Sync | Linux | Shell Scripting | Git | Adobe Creative Suite | Avid Media Composer