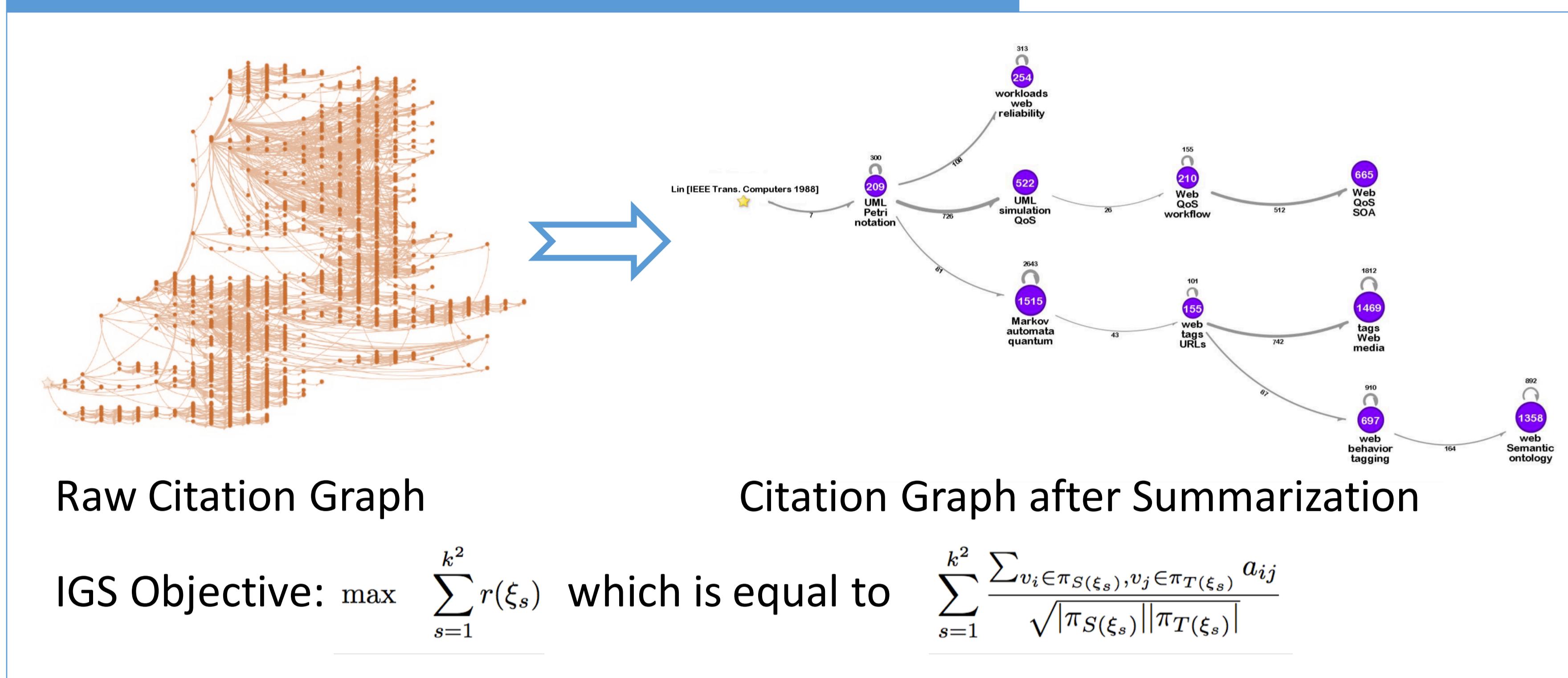


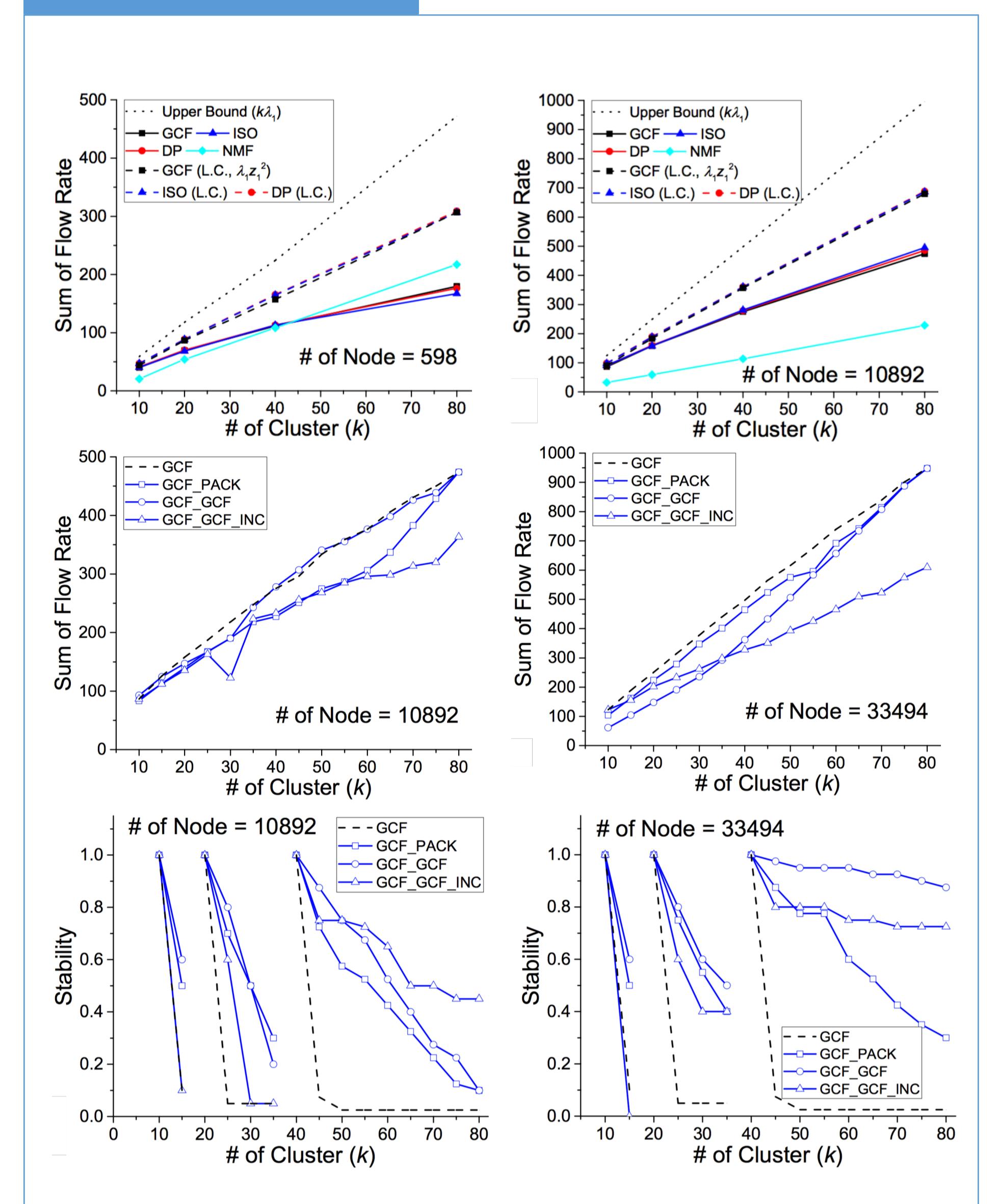
TOPIC: Toward Perfect InfluenCe Graph Summarization

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Influence Graph Summarization



Evaluation



Motivating Problems on IGS

- Optimality ■ Scalability ■ Flexibility

New Perspective on IGS Optimality

$$\max \sum_{s=1}^{k^2} r(\xi_s) = \sum_{s=1}^{k^2} \frac{\sum_{v_i \in \pi_S(\xi_s), v_j \in \pi_T(\xi_s)} a_{ij}}{\sqrt{|\pi_S(\xi_s)| |\pi_T(\xi_s)|}} = \sum_{i=1}^n \sum_{j=1}^n \frac{a_{ij}}{\sqrt{|\pi_C(v_i)| |\pi_C(v_j)|}}$$

(as a quadratic form)

$$\max \sum_{i=1}^n \sum_{j=1}^n a_{ij} x_i x_j = x^T A x = x^T A^* x \text{ where } x = (|\pi_C(v_1)|^{-\frac{1}{2}}, \dots, |\pi_C(v_n)|^{-\frac{1}{2}})^T$$

(by min-max theorem)

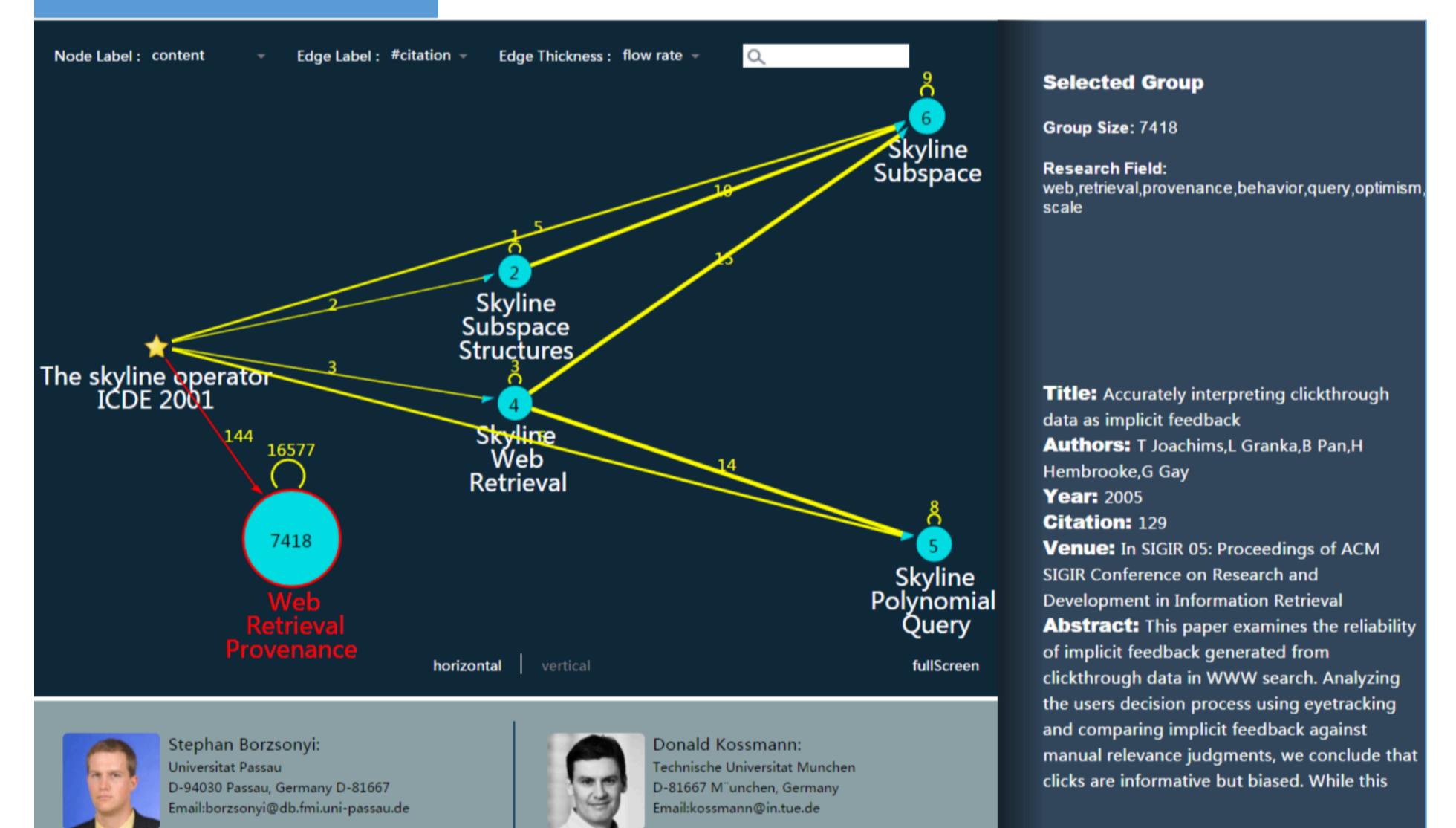
$$\max \frac{x^T A^* x}{x^T x} = \lambda_1 \implies x^T A^* x = k \cdot \lambda_1 \implies x = \sqrt{k} q_1$$

(optimizing the largest component)

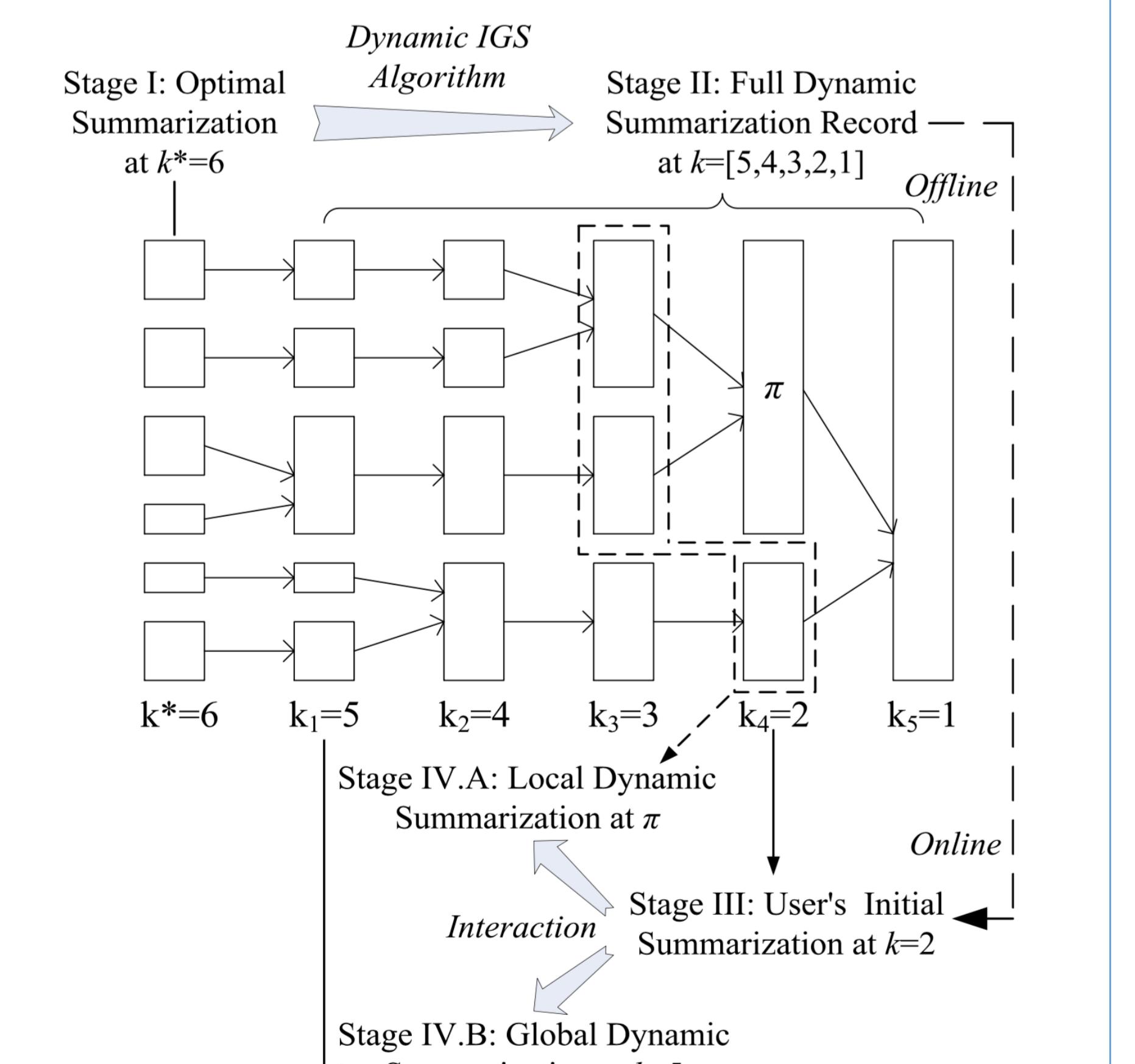
$$\max z_1 = q_1^T x = \sum_{j=1}^k |\pi_j|^{-\frac{1}{2}} \sum_{C(v_i)=j} q_{1i}$$

$$q_1 = \begin{bmatrix} q_{11} & q_{12} & \dots & q_{1n} \\ \hline \pi_1 & \pi_2 & \dots & \pi_k \end{bmatrix} \quad \begin{array}{l} \text{components sorted decreasingly: } q_{11} \geq \dots \geq q_{1n} \\ \text{cluster size increasing: } |\pi_1| \leq \dots \leq |\pi_k| \end{array}$$

System



Dynamic Algorithm



Static Algorithms

