

Camera Mid Term Report.

— Ivan Ouyang

Data Buffer

| CRITERIA | MEETS SPECIFICATIONS |
|-------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| MP.1 Data Buffer Optimization | Implement a vector for <code>dataBuffer</code> objects whose size does not exceed a limit (e.g. 2 elements). This can be achieved by pushing in new elements on one end and removing elements on the other end. |

MP. 1

Implementation:

Check to see if the size of *dataBuffer* equals to the *dataBufferSize*. If so, then erase the first frame of the image because the next image will be pushed into the buffer later.

Keypoints

| CRITERIA | MEETS SPECIFICATIONS |
|-------------------------|---------------------------------------------------------------------------------------------------------------------------------|
| MP.2 Keypoint Detection | Implement detectors HARRIS, FAST, BRISK, ORB, AKAZE, and SIFT and make them selectable by setting a string accordingly. |
| MP.3 Keypoint Removal | Remove all keypoints outside of a pre-defined rectangle and only use the keypoints within the rectangle for further processing. |

MP. 2 Keypoint Detection

Implementation:

Fill in the `detKeypointsModern` function. Take *keypoints*, *imgGray*, *detectorType*, *false* as input parameters. By calling different *detectorType*, the function will process the *imgGray* by making use of different detector function call. Visualize the results at the end of the function.

MP. 3 Keypoint Removal

Implementation:

Use a *for* loop to go through all the keypoints. By making use of the *vehicleRect*, filter out all the key points that are not reside in this rectangle. The key points left over are the key points we are looking for.

Descriptors

| CRITERIA | MEETS SPECIFICATIONS |
|--------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| MP.4 Keypoint Descriptors | Implement descriptors BRIEF, ORB, FREAK, AKAZE and SIFT and make them selectable by setting a string accordingly. |
| MP.5 Descriptor Matching | Implement FLANN matching as well as k-nearest neighbor selection. Both methods must be selectable using the respective strings in the main function. |
| MP.6 Descriptor Distance Ratio | Use the K-Nearest-Neighbor matching to implement the descriptor distance ratio test, which looks at the ratio of best vs. second-best match to decide whether to keep an associated pair of keypoints. |

MP.4 Keypoint Descriptors

Implementation:

Similar to MP.2. We can get the *Keypoints* from Step3. By comparing the *descriptorType*, different descriptor pattern can be chosen. These patten will be applied to the *Keypoints*, the output will be descriptor, ie, a vector of pixels of the image.

MP.5

Implementation:

As SIFT is not similar to other binary descriptor(such as BRIEF, ORB, BRISK, FREAK), by making use of Euclidean distance to compare and match the descriptor will have a performance boost. So a L-2 norm method is used here.

FLANN is short for Fast Library for Approximate Nearest Neighbors. It works way much faster than the Brutal Force matcher for large dataset.

MP. 6

Implementation:

FLANN

According to the paper on “SIFT”, Lowe’s ratio 0.7 is selected while KNN is used.

Performance

| CRITERIA | MEETS SPECIFICATIONS |
|----------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| MP.7 Performance Evaluation 1 | Count the number of keypoints on the preceding vehicle for all 10 images and take note of the distribution of their neighborhood size. Do this for all the detectors you have implemented. |
| MP.8 Performance Evaluation 2 | Count the number of matched keypoints for all 10 images using all possible combinations of detectors and descriptors. In the matching step, the BF approach is used with the descriptor distance ratio set to 0.8. |

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| MP.9 Performance Evaluation 3 | Log the time it takes for keypoint detection and descriptor extraction. The results must be entered into a spreadsheet and based on this data, the TOP3 detector / descriptor combinations must be recommended as the best choice for our purpose of detecting keypoints on vehicles. |
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MP.7

Implementation:

| FRAME # | HARRIS | FAST | BRISK | ORB | AKAZE | SIFT |
|---------|--------|------|-------|-----|-------|------|
| 0 | 50 | 420 | 152 | 91 | 162 | 137 |
| 1 | 54 | 431 | 159 | 102 | 157 | 131 |
| 2 | 53 | 408 | 154 | 106 | 159 | 121 |
| 3 | 55 | 430 | 161 | 113 | 154 | 135 |
| 4 | 56 | 389 | 155 | 109 | 162 | 134 |
| 5 | 58 | 417 | 154 | 124 | 163 | 139 |
| 6 | 57 | 422 | 160 | 129 | 173 | 136 |
| 7 | 61 | 413 | 150 | 127 | 175 | 147 |
| 8 | 60 | 401 | 155 | 124 | 175 | 156 |
| 9 | 57 | 405 | 141 | 125 | 175 | 135 |

MP. 8

Implementation:

Detector: ShiTomasi

| Descriptors/ Frame# | BRISK | ORB | FREAK | AKAZE | SIFT |
|------------------------|-------|------|-------|-------|------|
| 0 | 1370 | 1370 | 1370 | NA | 1370 |
| 1 | 1301 | 1301 | 1301 | NA | 1301 |
| 2 | 1361 | 1361 | 1361 | NA | 1361 |
| 3 | 1358 | 1358 | 1358 | NA | 1358 |
| 4 | 1333 | 1333 | 1333 | NA | 1333 |
| 5 | 1284 | 1284 | 1284 | NA | 1284 |
| 6 | 1322 | 1322 | 1322 | NA | 1322 |
| 7 | 1366 | 1366 | 1366 | NA | 1366 |
| 8 | 1389 | 1389 | 1389 | NA | 1389 |
| 9 | 1339 | 1339 | 1339 | NA | 1339 |

Detector: HARRIS

| Descriptors/ Frame# | BRISK | ORB | FREAK | AKAZE | SIFT |
|------------------------|-------|-----|-------|-------|------|
| 0 | 492 | 492 | 492 | NA | 492 |
| 1 | 502 | 502 | 502 | NA | 502 |
| 2 | 516 | 516 | 516 | NA | 516 |
| 3 | 524 | 524 | 524 | NA | 524 |
| 4 | 523 | 523 | 523 | NA | 524 |
| 5 | 511 | 511 | 511 | NA | 511 |
| 6 | 505 | 505 | 505 | NA | 505 |
| 7 | 510 | 510 | 510 | NA | 510 |
| 8 | 529 | 529 | 529 | NA | 529 |
| 9 | 520 | 520 | 520 | NA | 515 |

Detector: FAST

| Descriptors/ Frame# | BRISK | ORB | FREAK | AKAZE | SIFT |
|------------------------|-------|------|-------|-------|------|
| 0 | 5063 | 5063 | 5063 | NA | 5063 |
| 1 | 4952 | 4952 | 4952 | NA | 4952 |
| 2 | 4863 | 4863 | 4863 | NA | 4863 |
| 3 | 4840 | 4840 | 4840 | NA | 4840 |
| 4 | 4856 | 4856 | 4856 | NA | 4856 |
| 5 | 4899 | 4899 | 4899 | NA | 4899 |
| 6 | 4870 | 4870 | 4870 | NA | 4870 |
| 7 | 4868 | 4868 | 4868 | NA | 4868 |
| 8 | 4996 | 4996 | 4996 | NA | 4996 |
| 9 | 4997 | 4997 | 4997 | NA | 4997 |

Detector: ORB

| Descriptors/ Frame# | BRISK | ORB | FREAK | AKAZE | SIFT |
|------------------------|-------|-----|-------|-------|------|
| 0 | 500 | 500 | 500 | NA | 500 |
| 1 | 500 | 500 | 500 | NA | 500 |
| 2 | 500 | 500 | 500 | NA | 500 |
| 3 | 500 | 500 | 500 | NA | 500 |
| 4 | 500 | 500 | 500 | NA | 500 |
| 5 | 500 | 500 | 500 | NA | 500 |
| 6 | 500 | 500 | 500 | NA | 500 |
| 7 | 500 | 500 | 500 | NA | 500 |
| 8 | 500 | 500 | 500 | NA | 500 |
| 9 | 500 | 500 | 500 | NA | 500 |

Detector: AKAZE

| Descriptors/ Frame# | BRISK | ORB | FREAK | AKAZE | SIFT |
|------------------------|-------|------|-------|-------|------|
| 0 | 1351 | 1351 | 1351 | 1351 | 1351 |
| 1 | 1327 | 1327 | 1327 | 1327 | 1327 |
| 2 | 1331 | 1331 | 1331 | 1331 | 1331 |
| 3 | 1351 | 1351 | 1351 | 1351 | 1351 |
| 4 | 1360 | 1360 | 1360 | 1360 | 1360 |
| 5 | 1347 | 1347 | 1347 | 1347 | 1347 |
| 6 | 1363 | 1363 | 1363 | 1363 | 1363 |
| 7 | 1331 | 1331 | 1331 | 1331 | 1331 |
| 8 | 1357 | 1357 | 1357 | 1357 | 1357 |
| 9 | 1331 | 1331 | 1331 | 1331 | 1331 |

Detector: SIFT

| Descriptors/ Frame# | BRISK | ORB | FREAK | AKAZE | SIFT |
|------------------------|-------|-----|-------|-------|------|
| 0 | 1438 | NA | 1438 | NA | 1438 |
| 1 | 1371 | NA | 1371 | NA | 1371 |
| 2 | 1380 | NA | 1380 | NA | 1380 |
| 3 | 1335 | NA | 1335 | NA | 1335 |
| 4 | 1305 | NA | 1305 | NA | 1305 |
| 5 | 1370 | NA | 1370 | NA | 1370 |
| 6 | 1396 | NA | 1396 | NA | 1396 |
| 7 | 1382 | NA | 1382 | NA | 1382 |
| 8 | 1463 | NA | 1463 | NA | 1463 |
| 9 | 1422 | NA | 1422 | NA | 1422 |

MP. 9

TIME OF DETECTOR

| | BRISK | ORB | FREAK | AKAZE | SIFT |
|-----------|------------|------------|------------|------------|------------|
| SHITOMASI | 174.41 ms | 148.913 ms | 121.59 ms | NA | 135.619 ms |
| HARRIS | 156.087 ms | 138.279 ms | 124.323 ms | NA | 128.104 ms |
| FAST | 25.6386 ms | 21.3233 ms | 22.1093 ms | NA | 20.8753 ms |
| ORB | 84.8292 ms | 83.7626 ms | 78.5994 ms | NA | 86.9558 ms |
| AKAZE | 838.481 ms | 838.432 ms | 757.233 ms | 798.701 ms | 806.566 ms |
| SIFT | 1128.08 ms | NA | 1336.64 ms | NA | 1071.21 ms |

TIME OF DESCRIPTOR

| | BRISK | ORB | FREAK | AKAZE | SIFT |
|-----------|------------|------------|------------|------------|------------|
| SHITOMASI | 29.35 ms | 8.9328 ms | 385.683 ms | NA | 160.824 ms |
| HARRIS | 14.8603 ms | 7.98811 ms | 380.884 ms | NA | 153.596 ms |
| FAST | 54.8574 ms | 27.3408 ms | 448.119 ms | NA | 385.714 ms |
| ORB | 15.8505 ms | 50.1791 ms | 415.348 ms | NA | 501.998 ms |
| AKAZE | 26.9118 ms | 32.5048 ms | 439.817 ms | 710.898 ms | 263.381 ms |
| SIFT | 17.6061 ms | NA | 434.3 ms | NA | 860.683 ms |

Top 3 best Performer:
FAST/ORB
FAST/BRISK
ORB/BRISK