### DSP Homework

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Abstract

## 1 01

#### 2 IDFT

To derive the IDFT formula, we only should derive the expression of  $A^{-1}$ . And since A can be expressed as below

$$\begin{bmatrix} 1 & 1 & 1 & \cdots & 1 \\ 1 & w^{1} & w^{2} & \cdots & w^{N-1} \\ 1 & w^{2} & w^{4} & \cdots & w^{2(N-1)} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & w^{2(N-1)} & w^{4(N-1)} & \cdots & w^{(N-1)^{2}} \end{bmatrix}$$

we note rows in A as  $\alpha_i$ , and rewrite it as below

$$A = \begin{bmatrix} \alpha_0 \\ \alpha_1 \\ \alpha_2 \\ \vdots \\ \alpha_{N-1} \end{bmatrix}$$

See  $\alpha_i \cdot \alpha_j^H$ , if  $i \neq j$ , we let  $\lambda = i - j \in (0, N)$ , and

$$\alpha_{i} \cdot \alpha_{j}^{H} = \begin{bmatrix} 1 & w^{i} & w^{2i} & w^{3i} & \cdots & w^{(N-1)i} \end{bmatrix} \cdot \begin{bmatrix} 1 \\ w^{j} \\ w^{2j} \\ w^{3j} \\ \vdots \\ w^{(N-1)j} \end{bmatrix}$$

$$= 1 + w^{\lambda} + w^{2\lambda} + \cdots + w^{(N-1)\lambda}$$

$$= \frac{1 - w^{N\lambda}}{1 - w^{\lambda}}$$

$$= \frac{1 - e^{j2\pi\lambda} \quad (= 0)}{1 - e^{-j\frac{2\pi}{N}\lambda} \quad (\neq 0)}$$

$$= 0$$
(1)

If i = j, we have

$$\alpha_i \cdot \alpha_i^H = 1 + w^0 + w^{2 \times 0} + \dots + w^{(N-1) \times 0} = N$$
(2)

So, conclude (1) and (2), we have

$$\alpha_i \cdot \alpha_j^H = \begin{cases} 0 & \text{if } i \neq j \\ N & \text{if } i = j \end{cases}$$
 (3)

Therefore, see  $A \cdot A^H$ 

$$A \cdot A^{H} = \begin{bmatrix} \alpha_{0} \\ \alpha_{1} \\ \alpha_{2} \\ \vdots \\ \alpha_{N-1} \end{bmatrix} \cdot \begin{bmatrix} \alpha_{0}^{H} & \alpha_{1}^{H} & \alpha_{2}^{H} & \cdots & \alpha_{N-1} \end{bmatrix}$$

$$= N \cdot \begin{bmatrix} \alpha_{0} \cdot \alpha_{0}^{H} & \alpha_{0} \cdot \alpha_{1}^{H} & \cdots & \alpha_{0} \cdot \alpha_{N-1}^{H} \\ \alpha_{1} \cdot \alpha_{0}^{H} & \alpha_{1} \cdot \alpha_{1}^{H} & \cdots & \alpha_{1} \cdot \alpha_{N-1}^{H} \\ \vdots & \vdots & \ddots & \vdots \\ \alpha_{N-1} \cdot \alpha_{0}^{H} & \alpha_{N-1} \cdot \alpha_{1}^{H} & \cdots & \alpha_{N-1} \cdot \alpha_{N-1}^{H} \end{bmatrix}$$

$$= N \cdot \begin{bmatrix} 1 & 0 & \cdots & 0 \\ 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 1 \end{bmatrix}$$

$$= N \cdot I$$

$$(4)$$

If we multiply  $A^{-1}$  in both side of (4), we have

$$A^{-1} = \frac{1}{N}A^H \tag{5}$$

Therefore, IDFT formula can be expressed as below

$$x = A^{-1}\tilde{x}$$

$$= \frac{1}{N}A^{H}\tilde{x}$$

$$= \frac{1}{N}(A\tilde{x}^{H})^{H}$$

$$= \frac{1}{N}\sum_{k=0}^{N-1}\tilde{x}(k)e^{j2\pi kn/N}$$
(6)

Also, a more symmetric definition is as below

$$\tilde{x}(k) = \frac{1}{\sqrt{N}} \sum_{n=0}^{N-1} x(n) e^{-j2\pi kn/N}$$

$$x(n) = \frac{1}{\sqrt{N}} \sum_{k=0}^{N-1} \tilde{x}(k) e^{j2\pi kn/N}$$

#### 3 03

# 4 Comparison of Codes Running Speed

Assuming N is the total number of the sampling points, I drew a picture of how much time it takes for 3 methods to do the calculations. The x-axis is Log N, and the y-axis is Time t. See Fig. 1

## Appendix A Code Listing

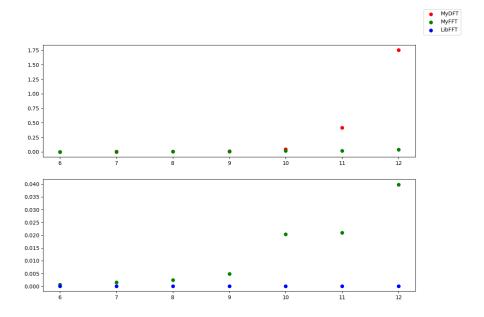


Figure 1: Comparison of the Codes Running Speed

```
import numpy as np
import time
from matplotlib import pyplot as plt
def dft(x):
    N = len(x)
    xt = np.matmul(
         \texttt{np.exp(-1j * 2 * np.pi * np.matmul(np.arange(N).reshape(N, 1), np.arange(N).reshape(1, N)/N)), } 
        )
    return xt
def idft(xt):
    return np.conj(dft(np.conj(xt))) / N
def fft(x):
    N = len(x)
    if N == 1:
        return x
        x0, x1 = x[::2], x[1::2]
        xt0 = fft(x0)
        xt1 = fft(x1)
        tmp = np.exp(-1j*2*np.pi*np.arange(N/2)/N) * xt1
        xt = np.concatenate([xt0 + tmp, xt0 - tmp])
    return xt
def ifft(xt):
    return np.conj(fft(np.conj(xt))) / N
def test(m):
   x = np.random.rand(2**m)
    # MyDFT
    st1 = time.time()
    y1 = dft(x)
    et1 = time.time()
    \# xx1 = idft(y1)
    # MyFFT
    st2 = time.time()
    y2 = fft(x)
    et2 = time.time()
```

```
\# xx2 = idft(y2)
    # LibFFT
    st3 = time.time()
    y3 = np.fft.fft(x)
    et3 = time.time()
    \# xx3 = idft(y3)
    \# err1 = xx1 - x
    \# err2 = xx2 - x
    \# err3 = xx3 - x
    t1 = et1 - st1
t2 = et2 - st2
    t3 = et3 - st3
    return t1, t2, t3
M = [i for i in range(6, 13)]
T1 = []
T2 = []
T3 = []
for m in M:
    tmp1, tmp2, tmp3 = test(m)
    T1.append(tmp1)
    T2.append(tmp2)
    T3.append(tmp3)
fig = plt.figure()
plt.xlabel('LogN')
plt.ylabel('Time')
plt.subplot(211)
plt.scatter(M, T1, label='MyDFT', c='r')
plt.scatter(M, T2, label='MyFFT', c='g')
plt.subplot(212)
plt.scatter(M, T2, c='g')
plt.scatter(M, T3, label='LibFFT', c='b')
fig.legend()
plt.show()
```