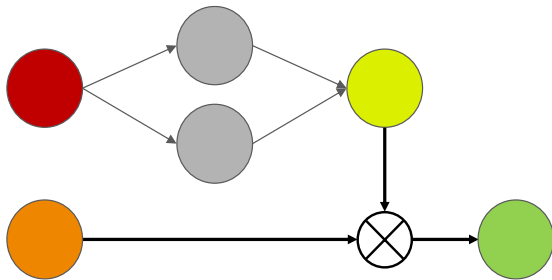


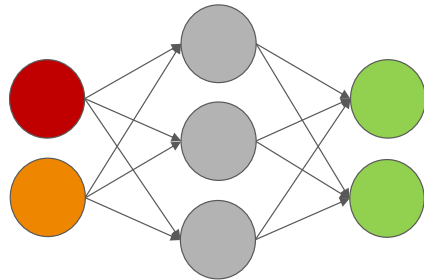
$$\hat{u}_t = u_t$$

a) DKUC



$$\hat{u}_t = g_\phi(x_t) \cdot u_t$$

b) DKUC



$$\hat{u}_t = g_\phi(x_t, u_t)$$

c) DKN