Discrete image transform

$$y = Tx$$

$$y_i = \sum_{j=0}^{N-1} t_{ij} x_j$$
 For $i = 0, 1, ..., N-1$

$$x = T^{-1}y$$
 T is not singular matrix

Unitary transform:

Unitary matrix:

$$\mathbf{T}^{-1} = (\mathbf{T}^*)^t$$
 and $\mathbf{T}(\mathbf{T}^*)^t = (\mathbf{T}^*)^t \mathbf{T} = \mathbf{I}$

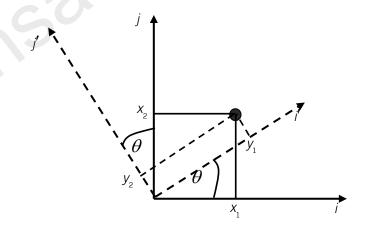
Discrete image transform

Example

$$\begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \begin{bmatrix} \cos(\theta) & \sin(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$x = x_1 i + x_2 j$$

New axis: $i' = \cos(\theta) i + \sin(\theta) j$
New axis: $j' = -\sin(\theta) i + \cos(\theta) j$
Hence: $y = y_1 i' + y_2 j'$



Discrete image transform

Fourier Transform

$$F(k) = \frac{1}{\sqrt{N}} \sum_{i=0}^{N-1} f(x) e^{-j\frac{2\pi k}{N}i}$$
is
$$\frac{1}{\sqrt{N}} e^{-j\frac{2\pi k}{N}i}$$

Let matrix **W** is a matrix with $\mathbf{w}_{i,k}$ is $\frac{1}{\sqrt{N}} e^{-j\frac{2\pi k}{N}i}$ then $\mathbf{F} = \mathbf{W}\mathbf{f}$

If T is real and unitary \rightarrow orthonormal transform

$$\mathsf{T}^{-1} = \mathsf{T}^t$$
 and $\mathsf{T} \ \mathsf{T}^t = \mathsf{T}^t \mathsf{T} = \mathsf{T}$

Inner product of row *i* and *j* of matrix T = 0 except i = j

$$\mathbf{t}_{i}^{t}\mathbf{t}_{j} = \delta_{ij} = \begin{cases} 1 & \text{if } i = j \\ 0 & \text{else} \end{cases}$$

$$G(m,n) = \sum_{i=0}^{N-1} \sum_{k=0}^{N-1} F(i,k) \Im(i,k,m,n)$$

$$\Im = \begin{bmatrix} \begin{bmatrix} \\ \\ \\ \\ \\ \\ \end{bmatrix}_{N\times N} & \begin{bmatrix} \\ \\ \\ \\ \\ \\ \end{bmatrix}_{N\times N} & \cdots & \begin{bmatrix} \\ \\ \\ \\ \\ \\ \end{bmatrix}_{N\times N} & m=1 \\ \vdots & \vdots & \ddots & \vdots \\ M,n & block \end{bmatrix} m = 1$$

$$m = 2$$

$$m = 1$$

$$m = 2$$

$$n = N$$

$$F(i,k) = \sum_{m=0}^{N-1} \sum_{n=0}^{N-1} G(m,n) \Re(i,k,m,n)$$

 \Re \rightarrow inverse transform kernel

If $\mathfrak{F}(i,k,m,n)$ is: $\mathfrak{F}(i,k,m,n) = \mathsf{T}_r(i,m) \; \mathsf{T}_r(k,n) \Rightarrow$ separable transform

$$G(m,n) = \sum_{i=0}^{N-1} \left[\sum_{k=0}^{N-1} F(i,k) T_{c}(k,n) \right] T_{r}(i,m)$$

If $T_r = T_c = T \rightarrow$ symmetry transform. But T does not have to be symmetry matrix.

$$G(m,n) = \sum_{i=0}^{N-1} T(i,m) \left[\sum_{k=0}^{N-1} F(i,k) T(k,n) \right]$$

$$G = T^{t}FT \text{ and } F = (T^{t})^{-1}GT^{-1}$$

$$G = T^tFT$$
 and $F = (T^t)^{-1}GT^{-1}$

If T : symmetry matrix. G = TFT and $F = T^{-1}GT^{-1}$

if T is unitary matrix $F = (T^{*t})G(T^{*t})$

if T is unitary matrix and real $F = (T^t)G(T^t)$

if T is symmetry F = (T)G(T)

Example Discrete Fourier transform

$$G(m,n) = \frac{1}{\sqrt{N}} \sum_{i=0}^{N-1} \left[\frac{1}{\sqrt{N}} \sum_{k=0}^{N-1} F(i,k) e^{-j2\pi \left(n\frac{k}{N}\right)} \right] e^{-j2\pi \left(m\frac{i}{N}\right)}$$

$$\Im(i,k,m,n) = \left(\frac{1}{\sqrt{N}} e^{-j2\pi \left(n\frac{k}{N}\right)} \right) \left(\frac{1}{\sqrt{N}} e^{-j2\pi \left(m\frac{i}{N}\right)} \right) = W(k,n)W(i,m)$$

$$G = W^{t}FW$$

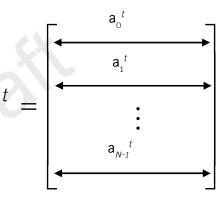
$$F = (W^{*})G(W^{*t})$$

-rows of kernel matrix forms a set of basis vector for an N-dimensional vector space -vector element are usually formed by the same functional form \rightarrow basis function

if T is unitary matrix $F = (T^*)G(T^{*t})$

let
$$A = (T^{*t}) \rightarrow F = (A^t)G(A)$$

Let \mathbf{a}_m^t and $\mathbf{a}_n^t \to \mathbf{m}^{th}$ row vector and \mathbf{n}^{th} row vector of $\mathbf{A}^t \to \mathbf{F}(m,n) = (\mathbf{a}_m^t)\mathbf{G}(\mathbf{a}_n)$



$$\text{let} \quad \mathbf{c}_{pq} = \begin{bmatrix}
 0 & 0 & \cdots & 0 \\
 \vdots & \vdots & & \vdots \\
 0 & 0 & \cdots & 0 \\
 0 & 1 & 0 & \cdots & 0 \\
 \vdots & 0 & \cdots & 0 \\
 0 & \vdots & & 0 \\
 0 & 0 & \cdots & & 0
\end{bmatrix} p$$

Let
$$B_{pq}(m,n) = (a_m^t)C_{pq}(a_n)$$
 or
$$B_{pq} = \begin{bmatrix} A(m,0) & A(m,1) & \cdots & A(m,N-1) \end{bmatrix} C_{pq} \begin{bmatrix} A(n,0) & A(n,0) & \cdots & A(m,N-1) \end{bmatrix} C_{pq} \begin{bmatrix} A(n,0) & A(n,0) & \cdots & A(m,N-1) \end{bmatrix} C_{pq} \begin{bmatrix} A(n,0) & A(n,0) & \cdots & A(m,N-1) \end{bmatrix} C_{pq} \begin{bmatrix} A(n,0) & A(n,0) & \cdots & A(m,N-1) \end{bmatrix} C_{pq} \begin{bmatrix} A(n,0) & A(n,0) & \cdots & A(m,N-1) \end{bmatrix} C_{pq} \begin{bmatrix} A(n,0) & A(n,0) & \cdots & A(m,N-1) \end{bmatrix} C_{pq} \begin{bmatrix} A(n,0) & A(n,0) & \cdots & A(m,N-1) \end{bmatrix} C_{pq} \begin{bmatrix} A(n,0) & A(n,0) & \cdots & A(m,N-1) \end{bmatrix} C_{pq} \begin{bmatrix} A(n,0) & A(n,0) & \cdots & A(m,N-1) \end{bmatrix} C_{pq} \begin{bmatrix} A(n,0) & A(n,0) & \cdots & A(m,N-1) \end{bmatrix} C_{pq} \begin{bmatrix} A(n,0) & A(n,0) & \cdots & A(m,N-1) \end{bmatrix} C_{pq} \begin{bmatrix} A(n,0) & A(n,0) & \cdots & A(m,N-1) \end{bmatrix} C_{pq} \begin{bmatrix} A(n,0) & A(n,0) & \cdots & A(m,N-1) \end{bmatrix} C_{pq} \begin{bmatrix} A(n,0) & A(n,0) & \cdots & A(m,N-1) \end{bmatrix} C_{pq} \begin{bmatrix} A(n,0) & A(n,0) & \cdots & A(m,N-1) \end{bmatrix} C_{pq} \begin{bmatrix} A(n,0) & A(n,0) & \cdots & A(m,N-1) \end{bmatrix} C_{pq} \begin{bmatrix} A(n,0) & A(n,0) & \cdots & A(m,N-1) \end{bmatrix} C_{pq} \begin{bmatrix} A(n,0) & A(n,0) & \cdots & A(m,N-1) \end{bmatrix} C_{pq} \begin{bmatrix} A(n,0) & A(n,0) & \cdots & A(m,N-1) \end{bmatrix} C_{pq} \begin{bmatrix} A(n,0) & A(n,0) & \cdots & A(m,N-1) \end{bmatrix} C_{pq} \begin{bmatrix} A(n,0) & A(n,0) & \cdots & A(m,N-1) \end{bmatrix} C_{pq} \begin{bmatrix} A(n,0) & A(n,0) & \cdots & A(m,N-1) \end{bmatrix} C_{pq} \begin{bmatrix} A(n,0) & A(n,0) & \cdots & A(m,N-1) \end{bmatrix} C_{pq} \begin{bmatrix} A(n,0) & A(n,0) & \cdots & A(m,N-1) \end{bmatrix} C_{pq} \begin{bmatrix} A(n,0) & A(n,0) & \cdots & A(m,N-1) \end{bmatrix} C_{pq} \begin{bmatrix} A(n,0) & A(n,0) & \cdots & A(m,N-1) \end{bmatrix} C_{pq} \begin{bmatrix} A(n,0) & A(n,0) & \cdots & A(m,N-1) \end{bmatrix} C_{pq} \begin{bmatrix} A(n,0) & A(n,0) & \cdots & A(m,N-1) \end{bmatrix} C_{pq} \begin{bmatrix} A(n,0) & A(n,0) & \cdots & A(m,N-1) \end{bmatrix} C_{pq} \begin{bmatrix} A(n,0) & A(n,0) & \cdots & A(m,N-1) \end{bmatrix} C_{pq} \begin{bmatrix} A(n,0) & A(n,0) & \cdots & A(m,N-1) \end{bmatrix} C_{pq} \begin{bmatrix} A(n,0) & A(n,0) & \cdots & A(m,N-1) \end{bmatrix} C_{pq} \begin{bmatrix} A(n,0) & A(n,0) & \cdots & A(m,N-1) \end{bmatrix} C_{pq} \begin{bmatrix} A(n,0) & A(n,0) & \cdots & A(m,N-1) \end{bmatrix} C_{pq} \begin{bmatrix} A(n,0) & A(n,0) & \cdots & A(m,N-1) \end{bmatrix} C_{pq} \begin{bmatrix} A(n,0) & A(n,0) & \cdots & A(n,N-1) \end{bmatrix} C_{pq} \begin{bmatrix} A(n,0) & A(n,0) & \cdots & A(n,N-1) \end{bmatrix} C_{pq} \begin{bmatrix} A(n,0) & A(n,0) & \cdots & A(n,N-1) \end{bmatrix} C_{pq} \begin{bmatrix} A(n,0) & A(n,0) & \cdots & A(n,N-1) \end{bmatrix} C_{pq} \begin{bmatrix} A(n,0) & A(n,0) & \cdots & A(n,N-1) \end{bmatrix} C_{pq} \begin{bmatrix} A(n,0) & A(n,0) & \cdots & A(n,N-1) \end{bmatrix} C_{pq} \begin{bmatrix} A(n,0) & A(n,0) & \cdots & A(n,N-1) \end{bmatrix} C_{pq} \begin{bmatrix} A(n,0) & A(n,0) & \cdots & A(n,N-1) \end{bmatrix} C_{pq} \begin{bmatrix} A(n,0) & A(n,0) & \cdots & A(n,N-1) \end{bmatrix} C_{pq} \begin{bmatrix} A(n,0) & A(n,0) & \cdots & A(n,N-1) \end{bmatrix} C_{pq} \begin{bmatrix} A(n,0) & A(n,0) & \cdots & A(n,N-1) \end{bmatrix} C_{pq} \begin{bmatrix} A(n,0) & A(n,0) &$$

Hence
$$F = G(0,0)B_{00} + G(0,1)B_{01} + ... + G(N-1,N-1)B_{N-1N-1}$$

 $B_{pq} \rightarrow Basis image$

Example
$$\mathbf{F} = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$$
 and $\mathbf{T} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$

$$\mathbf{G} = \mathbf{T}^t \mathbf{F} \mathbf{T} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \left(\frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \right) = \begin{bmatrix} 5 & -1 \\ -2 & 0 \end{bmatrix}$$

$$\mathbf{F} = \left(\mathbf{T}^{t}\right)^{-1} \mathbf{G} \mathbf{T}^{-1} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} 5 & -1 \\ -2 & 0 \end{bmatrix} \left(\frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}\right) = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$$

Use basis image

$$B_{00} = \frac{1}{2} \begin{bmatrix} 1 \\ 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \qquad B_{01} = \frac{1}{2} \begin{bmatrix} 1 \\ 1 \end{bmatrix} \begin{bmatrix} 1 & -1 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 & -1 \\ 1 & -1 \end{bmatrix} = B_{10}^t$$

$$B_{11} = \frac{1}{2} \begin{bmatrix} 1 \\ -1 \end{bmatrix} \begin{bmatrix} 1 \\ -1 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$F = G(0,0)B_{00} + G(0,1)B_{01} + G(1,0)B_{10} + G(1,1)B_{11} = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$$

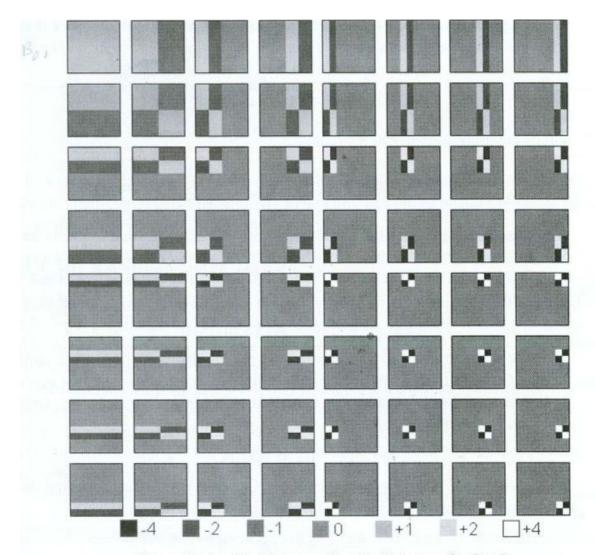


Figure 13–6 The Haar transform basis images for N = 8

Discrete Cosine Transform

Forward
$$G(m,n) = \alpha(m)\alpha(n)\sum_{i=0}^{N-1}\sum_{k=0}^{N-1}F(i,k)\cos\left(\frac{\pi(2i+1)m}{2N}\right)\cos\left(\frac{\pi(2k+1)n}{2N}\right)$$

Inverse
$$F(i,k) = \sum_{m=0}^{N-1} \sum_{n=0}^{N-1} \alpha(m)\alpha(n)G(m,n)\cos\left(\frac{\pi(2i+1)m}{2N}\right)\cos\left(\frac{\pi(2k+1)n}{2N}\right)$$
When $\alpha(0) = \sqrt{\frac{1}{N}}$ and $\alpha(m) = \sqrt{\frac{2}{N}}$ for $1 \le m \le N$

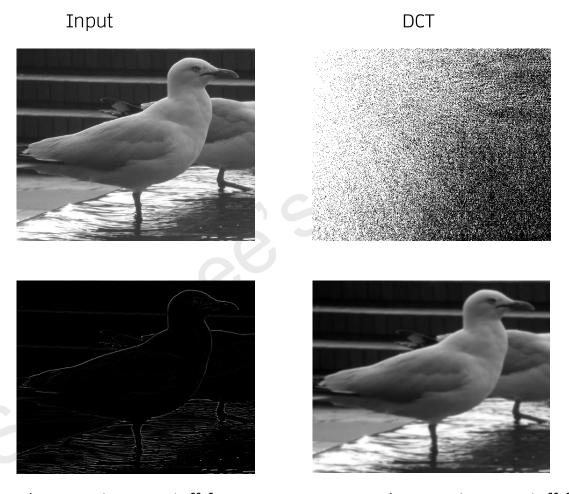
When
$$\alpha(0) = \sqrt{\frac{1}{N}}$$
 and $\alpha(m) = \sqrt{\frac{2}{N}}$ for $1 \le m \le N$

$$c(i,m) = \alpha(m)\cos\left(\frac{\pi(2i+1)m}{2N}\right) \qquad c(k,n) = \alpha(n)\cos\left(\frac{\pi(2k+1)n}{2N}\right)$$
$$G = C^{t}FC \qquad -xform \rightarrow real$$

$$C(k,n) = \alpha(n) \cos\left(\frac{\pi(2k+1)n}{2N}\right)$$

$$G = C^tFC$$

- -Cosine Xform is not the real part of DFT
- -There is a fast version
- -has excellent energy compression properties
- -use in image compression



IDCT and GHPF at 100 cutoff frequency IDCT and GLPF at 100 cutoff frequency

Hartley Transform

Forward
$$G(m,n) = \frac{1}{N} \sum_{i=0}^{N-1} \sum_{k=0}^{N-1} F(i,k) \operatorname{cas} \left(\frac{2\pi}{N} (im + kn) \right)$$

Forward
$$G(m,n) = \frac{1}{N} \sum_{i=0}^{N-1} \sum_{k=0}^{N-1} F(i,k) \cos\left(\frac{2\pi}{N}(im+kn)\right)$$

Inverse $F(i,k) = \frac{1}{N} \sum_{m=0}^{N-1} \sum_{n=0}^{N-1} G(m,n) \cos\left(\frac{2\pi}{N}(im+kn)\right)$

When
$$\cos\left(\frac{2\pi}{N}(im+kn)\right) = \cos\left(\frac{2\pi}{N}(im+kn)\right) + \sin\left(\frac{2\pi}{N}(im+kn)\right) = \sqrt{2}\cos\left(\left(\frac{2\pi}{N}(im+kn)\right) - \frac{\pi}{4}\right)$$

Basis function
$$T(i,m) = \cos\left(\frac{2\pi}{N}(im)\right)$$

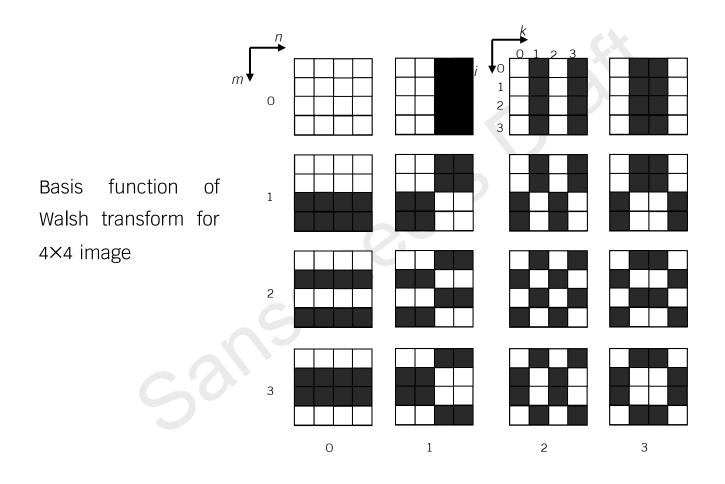
Forward Walsh transform

Forward Walsh transform
$$G(m,n) = \frac{1}{N} \sum_{i=0}^{N-1} \sum_{k=0}^{N-1} F(i,k) \prod_{j=0}^{n-1} (-1)^{\left[b_j(i)b_{n-1-j}(m) + b_j(k)b_{n-1-j}(n)\right]}$$

Inverse Walsh transform

$$F(i,k) = \frac{1}{N} \sum_{m=0}^{N-1} \sum_{n=0}^{N-1} G(m,n) \prod_{j=0}^{n-1} (-1)^{\left[b_j(i)b_{n-1-j}(m) + b_j(k)b_{n-1-j}(n)\right]}$$

When $b_k(z)$ is k-th bit in the binary representation of z. For example n = 3 (N = 8) and z = 4 (binary 100), hence $b_0(z) = 0$, $b_1(z) = 0$ and $b_2(z) = 1$



Forward hadamard transform

Forward hadamard transform
$$G(m,n) = \frac{1}{N} \sum_{i=0}^{N-1} \sum_{k=0}^{N-1} F(i,k) \left(-1\right) \sum_{j=0}^{n-1} \left[b_j(i)b_j(m) + b_j(k)b_j(n)\right]$$

Inverse Hadamard transform

$$F(i,k) = \frac{1}{N} \sum_{m=0}^{N-1} \sum_{n=0}^{N-1} G(m,n) (-1) \sum_{j=0}^{n-1} \left[b_j(i)b_j(m) + b_j(k)b_j(n) \right]$$

When $b_k(z)$ is k-th bit in the binary representation of z. For example n = 3 (N = 8) and z = 4 (binary 100), hence $b_0(z) = 0$, $b_1(z) = 0$ and $b_2(z) = 1$

$$\mathsf{T} = \frac{1}{\sqrt{2}}\mathsf{H}_2 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$$

$$T = \frac{1}{\sqrt{2}} H_2 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$$

$$T = \frac{1}{\sqrt{N}} H_N = \frac{1}{\sqrt{N}} \begin{bmatrix} H_{N/2} & H_{N/2} \\ H_{N/2} & -H_{N/2} \end{bmatrix}$$

Example create T for 8×8 image transform

Reorder rows so that sign change count is in increasing order

Harr Transform

Harr function → change in scale and location

$$\rightarrow$$
 [0,1]

Let
$$0 \le k \le N-1$$
 and $k = 2^p + q - 1$

 $p \rightarrow$ largest integer such that $2^p \le k$, e.g. for $k = 0 \rightarrow p = 0$ and q = 0for $k = 1 \rightarrow p = 0$ and q = 1for $k = 2 \rightarrow p = 1$ and q = 1for $k = 3 \rightarrow p = 1$ and q = 2

Basis function

$$h_{O} = \frac{1}{\sqrt{N}} \begin{bmatrix} 1 & \cdots & 1 \end{bmatrix}_{1 \times N}$$
 when
$$h_{k} = \frac{1}{\sqrt{N}} [h_{k}(x)]_{1 \times N}$$

$$h_k = \frac{1}{\sqrt{N}} \left[h_k(x) \right]_{1 \times N}$$

$$T = \begin{bmatrix} h_0^t \\ h_1^t \\ \vdots \\ h_{N-1}^t \end{bmatrix}$$

$$h_{k}(x) = \begin{cases} \frac{p}{2^{2}} & \text{if } \frac{q-1}{2^{p}} \le x < \frac{q-\frac{1}{2}}{2^{p}} \\ -2^{\frac{p}{2}} & \text{if } \frac{q-\frac{1}{2}}{2^{p}} \le x < \frac{q}{2^{p}} \\ 0 & \text{otherwise} \end{cases}$$

