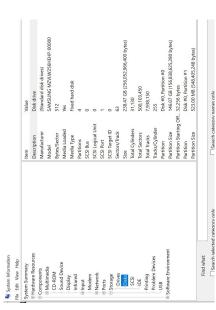
About your Hard Drive

- Windows Click on **Start** and type in msinfo32 and press Enter.

Week 10

Tutorial



Example 2 - Transfer Time



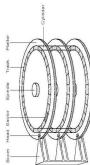
the transfer time will also depend on the block size. If we assume a 4K block size and a transfer rate of 123 MBs we can use the following equation Transfer time = block size / Data (sustained) transfer rate = $4/123 = 3.175 *10^{-5} s = 10^{-5} s =$

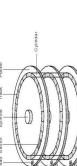
Example 1

LBA of your Hard Drive

CHS of your Hard Drive

CHS (Cylinder/Head/Sector) is an earlier form of hard disk addressing. $CHS = C \times H \times S$





C: cylinder, the valid range is between 0 and 1023 cylinders.

H: Head, the valid range is between 0 and 254 heads (formerly 0-15).

5: Sector, the valid range is between 1 and 63 sectors.

The capacity of hard disk CHS = 16383/16/63

- 16383 (cylinders) x 16 (heads) x 63 (sectors) x 128 (bytes) = 2,113,800,192 bytes (2 GB).
 - physical sector sizes of 128, 256, 512, 1024, 4096 bytes

Example 3

Consider a disk queue with requests for I/O to blocks on cylinders

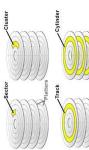
98, 183, 37, 122, 14, 124, 65, 67.

The SCAN scheduling algorithm is used. The head is initially at cylinder number 53. The cylinders are numbered from 0 to 199. Calculate and show with diagram the disk head movement using SCANscheduling algorithm.

It services the requests in the direction of its head movement and continues until it reaches the end of the disk or the last cylinder. After this, it reverses the direction and services the

requests in its path. - the preferred direction of the head movement has to be found first and all the requests in that direction will be serviced.

LBA (Logical block addressing) is what is used on (probably all) modern drives. The drive is logically divided into blocks (512 byte or 4k byte sectors mostly), the first block is block 0, the next one block 1, etc..



LBA = $(c \cdot Nheads + h) \cdot Nsectors + (s - 1)$

LBA - Logical Block Address Nheads - Number of heads on a disk heads-per-disk

Nsectors - Numbers of sectors on a track sectors-per-

c,h,s - is the cylinder, head, sector numbers 24-bits total (10+8+6)

Geometry: (this is defined by the manufacturer) Cylinders - 1020

- Heads- 16
- Sectors 63

In order to convert one style of address to the other, you need to specify the drive geometry:

- . number of cylinders
- . number of heads (per cylinder)
 - . number of sectors per track

Example 5

Consider a disk queue with I/O requests on the following cylinders in their arriving order:

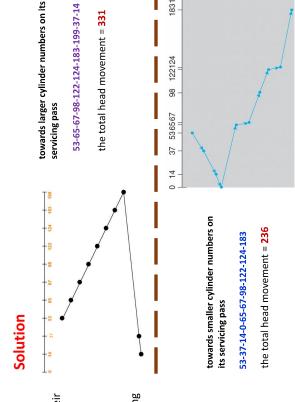
54, 97, 73, 128, 15, 44, 110, 34, 45

The disk head is assumed to be at Cylinder 23

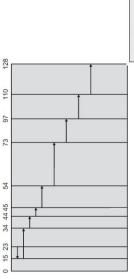
Calculate and show with diagram the total disk head movement using SSTF-scheduling algorithm.

Hint

- it calculates the seek time of all the requests in the queue,
- It selects the appropriate request, and
- It schedules it for the execution.



183199



Total head movement for the request	80	19	10	-	6	19	24	13	18	104 - 400mont
lead movement	23-15	15-34	34-44	44-45	45-54	54-73	73-97	97-110	110-128	Total bood monominate

Example 4

Solution

Consider a disk queue with I/O requests on the following cylinders in their arriving order:

54, 97, 73, 128, 15, 44, 110, 34,

The disk head is assumed to be at Cylinder 23

Calculate and show with diagram the total disk head movement using FCFS-scheduling algorithm.

Example 6

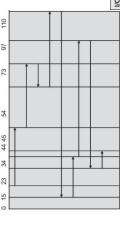
Consider a disk queue with I/O requests on the following cylinders in their arriving order:

6, 10, 12, 54, 97, 73, 128, 15, 44, 110, 34, 45

direction of decreasing number of cylinders. The disk consists of The disk head is assumed to be at Cylinder 23 and moving in the total 150 cylinders.

Calculate and show with diagram the disk head movement using C-SCAN scheduling algorithm.

Solution

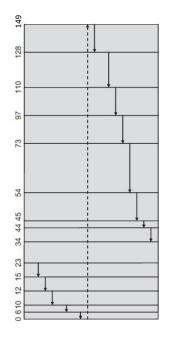


54, 97, 73, 128, 15, 44, 110, 34, 45

for the request	23–54 31	54-97	97-73	73–128 55	113	15-44 29	44-110 66	110–34 76	34-45
cylinder	54 2:	97 54	73 97	128 7:	15 128	44	110 4	34 110	45 34

Solution

the head returns to the beginning of the disk/the end of the disk without serving any request in its path



The total head movement = 138
The head jumps 150 cylinders

PRACTICE PROBLEM BASED ON FCFS DISK SCHEDULING ALGORITHM

FCFS Disk Scheduling Algorithm

- As the name suggests, this algorithm entertains requests in the order they arrive in the disk queue.
- It is the simplest disk scheduling algorithm.

Advantages:

- It is simple, easy to understand and implement.
- It does not cause starvation to any request.

Disadvantages:

- It results in increased total seek time.
- It is inefficient.

Problem

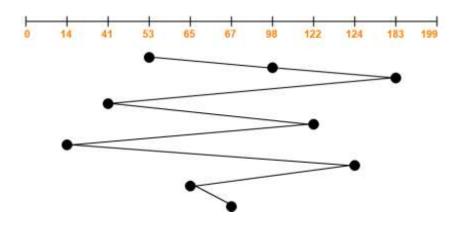
Consider a disk queue with requests for I/O to blocks on cylinders

98, 183, 41, 122, 14, 124, 65, 67.

The FCFS scheduling algorithm is used. The head is initially at cylinder number **53**. The cylinders are numbered from 0 to 199.

Write the sequence in which requested tracks are serviced using FCFS and calculate the total head movement (in number of cylinders) incurred while servicing these requests.

Solution



98-183-41-122-14-124-65-67

Total head movements incurred while servicing these requests

$$= (98 - 53) + (183 - 98) + (183 - 41) + (122 - 41) + (122 - 14) + (124 - 14) + (124 - 65) + (67 - 65)$$

= 45 + 85 + 142 + 81 + 108 + 110 + 59 + 2

PRACTICE PROBLEM BASED ON SCAN DISK SCHEDULING ALGORITHM

SCAN Disk Scheduling Algorithm

- As the name suggests, this algorithm scans all the cylinders of the disk back and forth.
- **Head starts from one end of the disk and move towards the other end** servicing all the requests in between.
- After reaching the other end, head reverses its direction and move towards the starting end servicing all the requests in between.
- The same process repeats.

NOTE

- SCAN Algorithm is also called as *Elevator Algorithm*.
- This is because its working resembles the working of an elevator.

Advantages:

- It is simple, easy to understand and implement.
- It does not lead to starvation.
- It provides low variance in response time and waiting time.

Disadvantages:

- It causes long waiting time for the cylinders just visited by the head.
- It causes the head to move till the end of the disk even if there are no requests to be serviced.

Problem

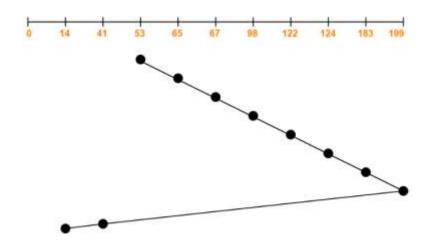
Consider a disk queue with requests for I/O to blocks on cylinders

98, 183, 41, 122, 14, 124, 65, 67.

The SCAN scheduling algorithm is used. The head is initially at cylinder number 53 moving towards larger cylinder numbers on its servicing pass. The cylinders are numbered from 0 to 199.

Write the sequence in which requested tracks are serviced using SCAN and calculate the total head movement (in number of cylinders) incurred while servicing these requests.

Solution



53-65-67-98-122-124-183-199-41-14

Total head movements incurred while servicing these requests = (65 - 53) + (67 - 65) + (98 - 67) + (122 - 98) + (124 - 122) + (183 - 124) + (199 - 183) + (199 - 41) + (41 - 14) = 12 + 2 + 31 + 24 + 2 + 59 + 16 + 158 + 27 = 331

Alternatively,

53-65-67-98-122-124-183-199-41-14

Total head movements incurred while servicing these requests = (199 - 53) + (199 - 14)

= 146 + 185

PRACTICE PROBLEM BASED ON C-SCAN DISK SCHEDULING ALGORITHM

C-SCAN Disk Scheduling Algorithm

- Circular-SCAN Algorithm is an improved version of the SCAN Algorithm.
- Head starts from one end of the disk and move towards the other end servicing all the
 requests in between, then it jumps to the last cylinder of the opposite direction
 without servicing any request then it turns back and start moving in that direction
 servicing the remaining requests.
- After reaching the other end, head reverses its direction and then resets at the outer track to begin again.
- It then returns to the starting end without servicing any request in between.
- The same process repeats.

Advantages:

- The waiting time for the cylinders just visited by the head is reduced as compared to the SCAN Algorithm.
- It provides uniform waiting time.
- It provides better response time.

Disadvantages:

- It causes more seek movements as compared to SCAN Algorithm.
- It causes the head to move till the end of the disk even if there are no requests to be serviced.

Problem

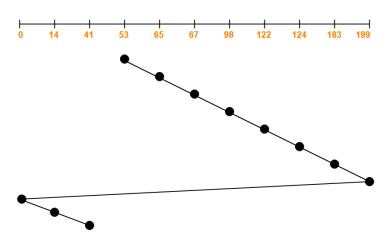
Consider a disk queue with requests for I/O to blocks on cylinders **98**, **183**, **41**, **122**, **14**, **124**, **65**, **67**.

The C-SCAN scheduling algorithm is used. The head is initially at cylinder number **53** moving towards larger cylinder numbers on its servicing pass.

The cylinders are numbered from 0 to 199 (the disk has 200 cylinders).

Write the sequence in which requested tracks are serviced using C-SCAN and calculate the total head movement (in number of cylinders) incurred while servicing these requests.

Solution



53-65-67-98-122-124-183-199-0-14-41

Total head movements incurred while servicing these requests

$$= (65 - 53) + (67 - 65) + (98 - 67) + (122 - 98) + (124 - 122) + (183 - 124) + (199 - 183) + (199 - 0) + (14 - 0) + (41 - 14)$$

= 12 + 2 + 31 + 24 + 2 + 59 + 16 + 200 + 14 + 27
= 187

The head jumps from 199-0 = 200

Alternatively,

Total head movements incurred while servicing these requests

$$= (199 - 53) + (200) + (41 - 0)$$

= 146 + 200 + 41

PRACTICE PROBLEM BASED ON LOOK DISK SCHEDULING ALGORITHM

LOOK Disk Scheduling Algorithm

- LOOK Algorithm is an improved version of the SCAN Algorithm
- Head starts from the first request at one end of the disk and moves towards the last request at the other end servicing all the requests in between.
- After reaching the last request at the other end, head reverses its direction.
- It then returns to the first request at the starting end servicing all the requests in between.
- The same process repeats.

NOTE

The main difference between SCAN Algorithm and LOOK Algorithm is-

- SCAN Algorithm scans all the cylinders of the disk starting from one end to the other end even if there are no requests at the ends.
- LOOK Algorithm scans all the cylinders of the disk starting from the first request at one end to the last request at the other end.

Advantages

- It does not cause the head to move till the ends of the disk when there are no requests to be serviced.
- It provides better performance as compared to SCAN Algorithm.
- It does not lead to starvation.
- It provides low variance in response time and waiting time.

Disadvantages

- There is an overhead of finding the end requests.
- It causes long waiting time for the cylinders just visited by the head.

Problem

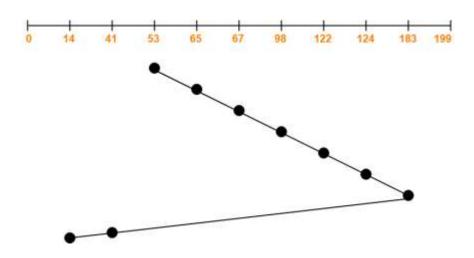
Consider a disk queue with requests for I/O to blocks on cylinders

98, 183, 41, 122, 14, 124, 65, 67.

The LOOK scheduling algorithm is used. The head is initially at cylinder number 53 moving towards larger cylinder numbers on its servicing pass. The cylinders are numbered from 0 to 199.

Write the sequence in which requested tracks are serviced using LOOK and calculate the total head movement (in number of cylinders) incurred while servicing these requests.

Solution



53-65-67-98-122-124-183-41-14

Total head movements incurred while servicing these requests

$$= (65 - 53) + (67 - 65) + (98 - 67) + (122 - 98) + (124 - 122) + (183 - 124) + (183 - 41) + (41 - 14)$$

$$= 12 + 2 + 31 + 24 + 2 + 59 + 142 + 27$$

$$= 299$$

Alternatively,

53-65-67-98-122-124-183-41-14

Total head movements incurred while servicing these requests

- =(183-53)+(183-14)
- = 130 + 169
- = 299

PRACTICE PROBLEMS BASED ON C-LOOK DISK SCHEDULING ALGORITHM

C-LOOK Disk Scheduling Algorithm

- Circular-LOOK Algorithm is an improved version of the LOOK Algorithm.
- Head starts from the first request at one end of the disk and moves towards the last request at the other end servicing all the requests in between.
- After reaching the last request at the other end, head reverses its direction.
- It then returns to the first request at the starting end without servicing any request in between.
- The same process repeats.

Advantages

- It does not cause the head to move till the ends of the disk when there are no requests to be serviced.
- It reduces the waiting time for the cylinders just visited by the head.
- It provides better performance as compared to LOOK Algorithm.
- It does not lead to starvation.
- It provides low variance in response time and waiting time.

Disadvantages

• There is an overhead of finding the end requests.

Problem-01:

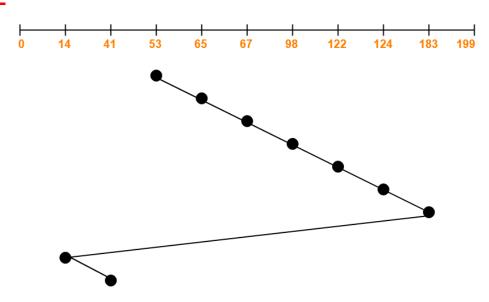
Consider a disk queue with requests for I/O to blocks on cylinders

98, 183, 41, 122, 14, 124, 65, 67.

The C-LOOK scheduling algorithm is used. The head is initially at cylinder number 53 moving towards larger cylinder numbers on its servicing pass. The cylinders are numbered from 0 to 199.

Write the sequence in which requested tracks are serviced using C-LOOK and calculate the total head movement (in number of cylinders) incurred while servicing these requests.

Solution



53-65-67-98-122-124-183-14-41

Total head movements incurred while servicing these requests

$$= (65 - 53) + (67 - 65) + (98 - 67) + (122 - 98) + (124 - 122) + (183 - 124) + (183 - 14) + (41 - 14)$$

$$= 12 + 2 + 31 + 24 + 2 + 59 + 169 + 27$$

$$= 157$$

The head jumps from 183-14 = 169

Alternatively,

Total head movements incurred while servicing these requests

```
= (183 - 53) + (183 - 14) + (41 - 14)
```

= 130 + 169 + 27

= 157

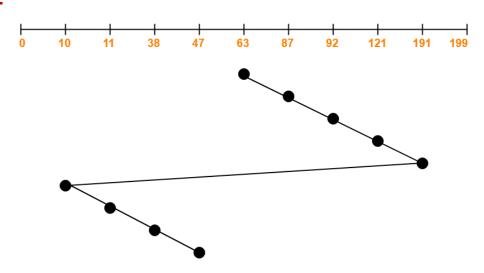
Problem-02:

Consider a disk queue with requests for I/O to blocks on cylinders

The C-LOOK scheduling algorithm is used. The head is initially at cylinder number 63 moving towards larger cylinder numbers on its servicing pass. The cylinders are numbered from 0 to 199.

Write the sequence in which requested tracks are serviced using C-LOOK and calculate the total head movement (in number of cylinders) incurred while servicing these requests.

Solution



63-87-92-121-191-10-11-38-47

Total head movements incurred while servicing these requests

$$= (87-63) + (92-87) + (121-92) + (191-121) + (191-10) + (11-10) + (38-11) + (47-38) \\ = 24 + 5 + 29 + 70 + \frac{181}{12} + 1 + 27 + 9$$

= 165

The head jumps from 191-10 = 181

Alternatively,

Total head movements incurred while servicing these requests

$$=(191-63)+(191-10)+(47-10)$$

$$= 128 + 181 + 37$$

PRACTICE PROBLEMS BASED ON SSTF DISK SCHEDULING ALGORITHM

SSTF Disk Scheduling Algorithm

- SSTF stands for Shortest Seek Time First.
- This algorithm services that request next which requires least number of head movements from its current position regardless of the direction.
- It breaks the tie in the direction of head movement.

Advantages:

- It reduces the total seek time as compared to FCFS.
- It provides increased throughput.
- It provides less average response time and waiting time.

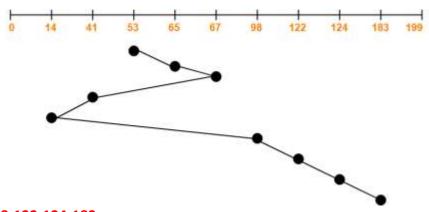
Disadvantages:

- There is an overhead of finding out the closest request.
- The requests which are far from the head might starve for the CPU.
- It provides high variance in response time and waiting time.
- Switching the direction of head frequently slows down the algorithm.

Problem-01:

Consider a disk queue with requests for I/O to blocks on cylinders **98**, **183**, **41**, **122**, **14**, **124**, **65**, **67**. The SSTF scheduling algorithm is used. The head is initially at cylinder number **53** moving towards larger cylinder numbers on its servicing pass. The cylinders are numbered from 0 to 199. Write the sequence in which requested tracks are serviced using SSTF and calculate the total head movement (in number of cylinders) incurred while servicing these requests.

Solution



53-65-67-41-14-98-122-124-183

Total head movements incurred while servicing these requests

$$= (65-53) + (67-65) + (67-41) + (41-14) + (98-14) + (122-98) + (124-122) + (183-124)$$

= 12 + 2 + 26 + 27 + 84 + 24 + 2 + 59

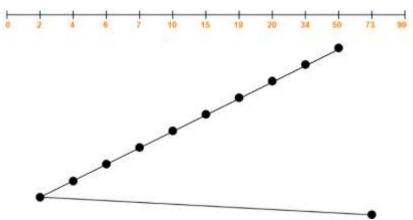
Problem-02:

Consider a disk system with 100 cylinders. The requests to access the cylinders occur in following sequence:

Assuming that the head is currently at cylinder **50**, what is the time taken to satisfy all requests if it takes 1 ms to move from one cylinder to adjacent one and shortest seek time first policy is used?

- A. 95 ms
- B. 119 ms
- C. 233 ms
- D. 276 ms

Solution



50-34-20-19-15-10-7-6-4-2-73

Total head movements incurred while servicing these requests

$$= (50 - 34) + (34 - 20) + (20 - 19) + (19 - 15) + (15 - 10) + (10 - 7) + (7 - 6) + (6 - 4) + (4 - 2) + (73 - 2)$$

$$= 16 + 14 + 1 + 4 + 5 + 3 + 1 + 2 + 2 + 71$$

= 119

Time taken for one head movement = 1 msec.

Time taken for 119 head movements

- = 119 x 1 msec
- = 119 msec

Option (B) is correct.