

INT102

Algorithmic Foundations And Problem Solving

The Limitations of Algorithm Power

-- Introduction to Computational Complexity Theory

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What we have learnt so far

methodology \ problems	Asym- ptotic idea	Brute force	Divide & Conquer	Dynamic Programming	Greedy	Space/Ti me	Branch&Bound	Backtra cking
Efficiency	Big-O							
Sorting		Selection Bubble Insertion	Merge- sort			Count sorting		
Searching			Binary- searching					
String				LCS, Sequence Alignment		Horspool algorithm		
Graph		DFS/BFS		Floyed (All pair shortest path) Warshall (Transitive Closure) Assembly-line	Kruskal/Prim for MST Dijkstra's For Shortest path		Traveling salesman, Job assignment	
Combinatory								n-Queens
Complexity	P/NP							

Introduction to Computational Complexity Theory ...

Agenda

- Warm up
 - Decision/Optimisation problems
 - Decision /Undecidable problems
 - Solving/Verifying a problem
 - Knapsack problem
 - Hamiltonian circuit problem
 - One more: Circuit-SAT

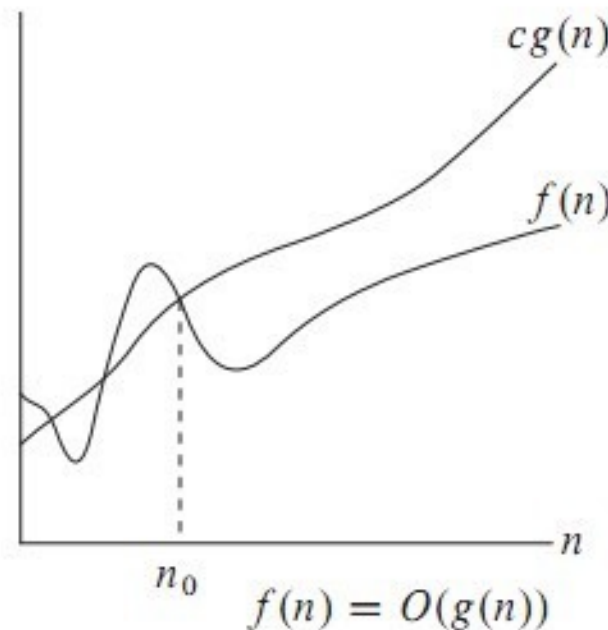
Complexity definitions (seen in 592)

- Big-Oh
- Big-Theta
- Big - Omega

Big Oh (O)

$f(n) = O(g(n))$ *iff* there exist positive constants c and n_0 such that $f(n) \leq cg(n)$ for all $n \geq n_0$

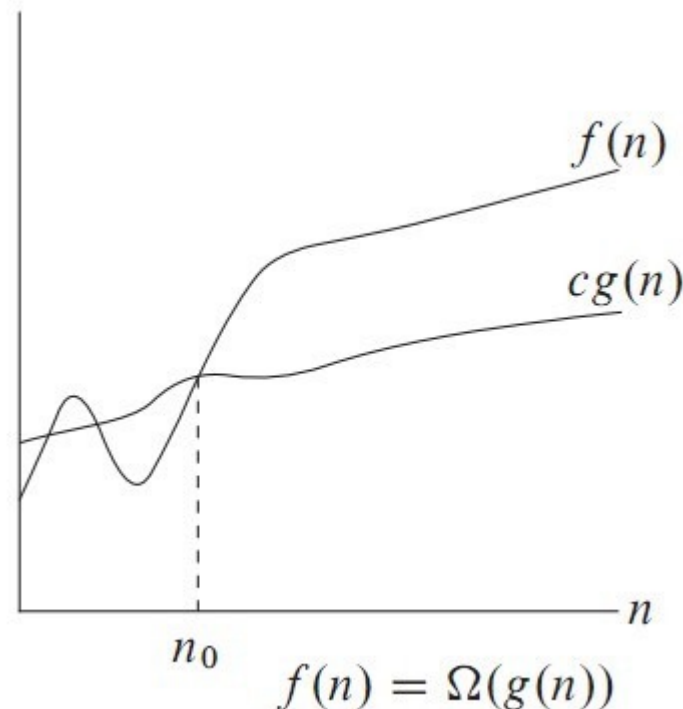
O -notation to give an **upper bound** on a function



Omega Notation

Big oh provides an asymptotic **upper** bound on a function.
Omega provides an asymptotic **lower** bound on a function.

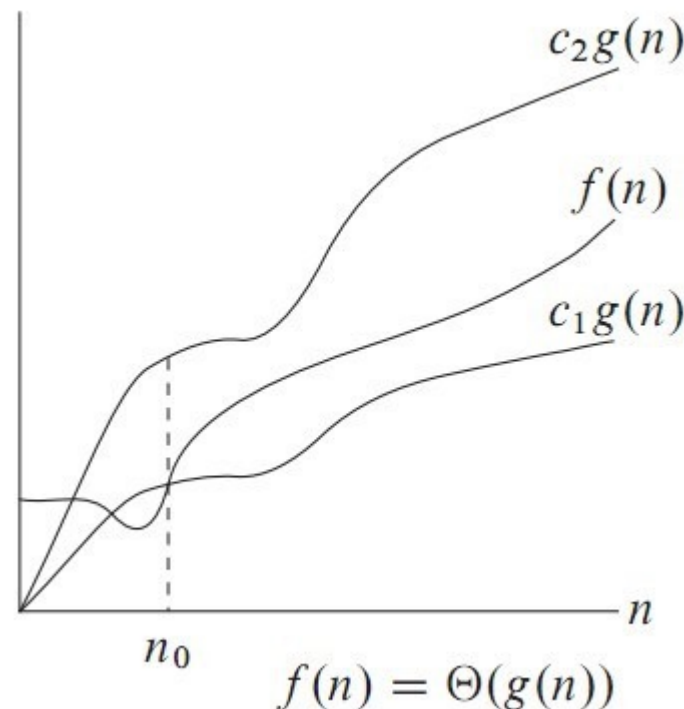
$\Omega(g(n)) = \{f(n) : \text{there exist positive constants } c \text{ and } n_0 \text{ such that}$
 $0 \leq cg(n) \leq f(n) \text{ for all } n \geq n_0\} .$



Theta Notation

Theta notation is used when function f can be bounded **both from above and below** by the same function g

$\Theta(g(n)) = \{f(n) : \text{there exist positive constants } c_1, c_2, \text{ and } n_0 \text{ such that } 0 \leq c_1g(n) \leq f(n) \leq c_2g(n) \text{ for all } n \geq n_0\} .^1$



Example: Bubble Sort

- **Big O (Worst Case):** $O(n^2)$. If the list is in reverse order, bubble sort will compare and swap elements $n(n-1)/2$ times, so the performance grows quadratically with the size of the input list, n .
- **Omega (Best Case):** $\Omega(n)$. If the list is already sorted, bubble sort only needs to pass through the list once, which involves $n-1$ comparisons and no swaps, making the performance grow linearly with the size of the input list, n .
- **Theta (Average Case):** $\Theta(n^2)$. While the best case is linear, the average and worst-case performance are typically quadratic, so bubble sort is often said to have a theta of n^2 .

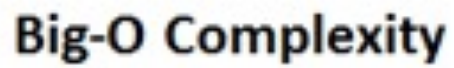
What we have learnt so far

- Polynomial Time

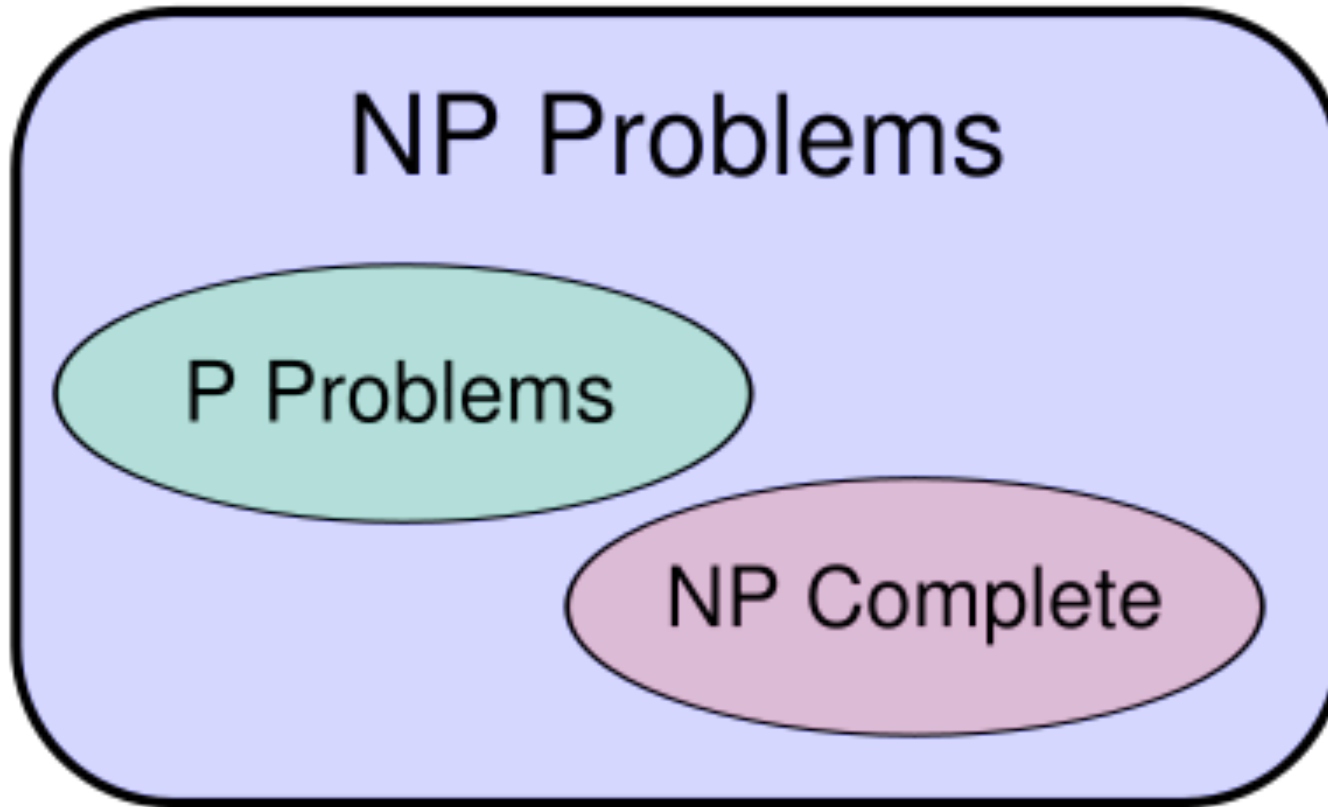
- Linear Search $O(n)$
- Binary Search $O(\log n)$
- Merge Sort $O(n \log n)$
- Matrix Multiplication $O(n^3)$

- Exponential Time

- 0/1 Knapsack $O(2^n)$
- Traveling SP $O(2^n)$
- Hamilton circle $O(2^n)$



Hard Computational Problems



Hard Computational Problems

An algorithm is efficient if its running time is bounded by a *polynomial* of its input size.

Some computational problems seems *hard* to solve.

Despite numerous attempts we *do not know any efficient* algorithms for these problems

We are also far away from *proving* these problems are indeed hard to solve

In more formal language, we don't know whether *$NP = P$ or $NP \neq P$* . This is an important and fundamental question in theoretical computer science!

P = NP? http://www.claymath.org/millennium/P_vs_NP/

- Named as one of the seven "**Millennium Problems**" by the Clay Institute
- can earn you \$1 million for its solution (and a place in mathematical and computer science history).
- Check www.claymath.org/millennium/ to read more about this (select the "P vs NP" link).

P vs. NP



A list of NP problems

- Hamiltonian Circuit
- Knapsack Problem
- Circuit-SAT

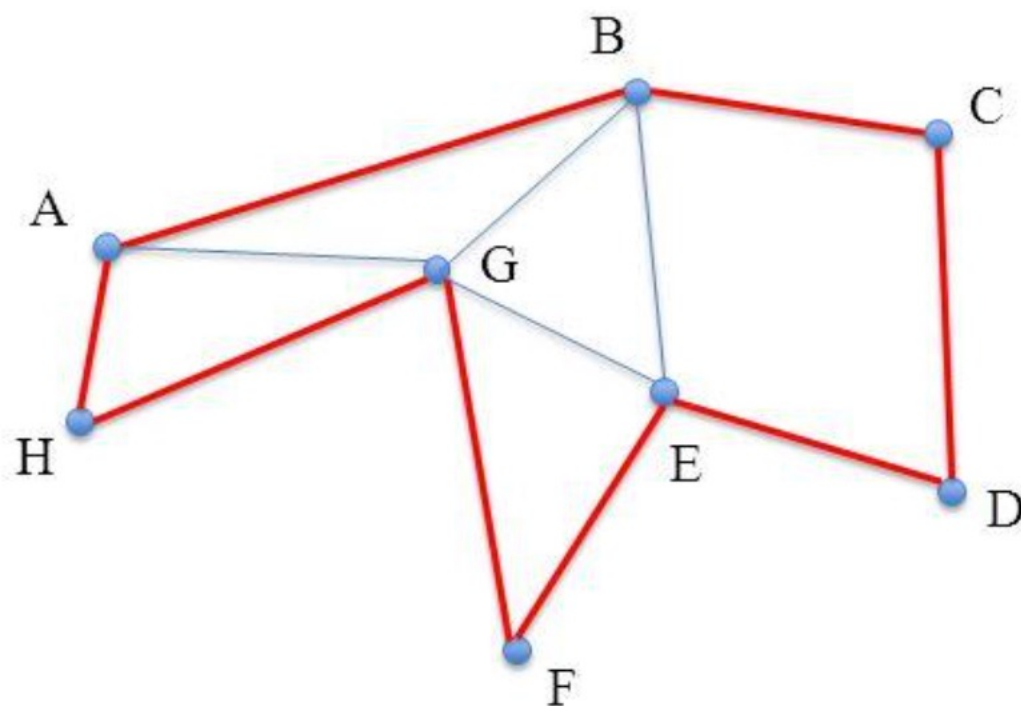
Hamiltonian Circuit

Input: A connected graph G

Question: Does G have a Hamiltonian circuit?
i.e., does G have a circuit that passes through every vertex exactly once, except for the starting and ending vertex?

Hamiltonian Circuit

A circuit that passes through every vertex at most once is called a **Hamiltonian circuit**.



A - H - **G** - F - **E** - D - C - **B** - **A**

Knapsack Problem

Input: Given n items with integer weights w_1, w_2, \dots, w_n and integer values v_1, v_2, \dots, v_n , and a knapsack with capacity W .

Problem (optimisation version): Find a subset of items whose total weight does not exceed W and that maximises the total value.

(taking fractional parts of items is NOT allowed)

Known as 0/1 Knapsack Problem

Knapsack Problem



Boolean Circuit (Circuit-SAT Preparation)

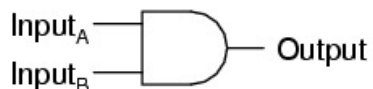
In discrete Math, you learned about *propositional logic*, and the basic operations for combining truth values.

A **Boolean Circuit** is a directed graph where each vertex, called a *logic gate* corresponds to a simple Boolean function, one of **AND**, **OR**, or **NOT**.

Incoming edges: inputs for its Boolean function

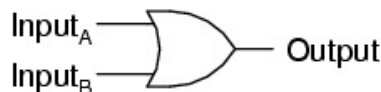
Outgoing edges: outputs

2-input AND gate



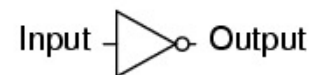
A	B	Output
0	0	0
0	1	0
1	0	0
1	1	1

2-input OR gate



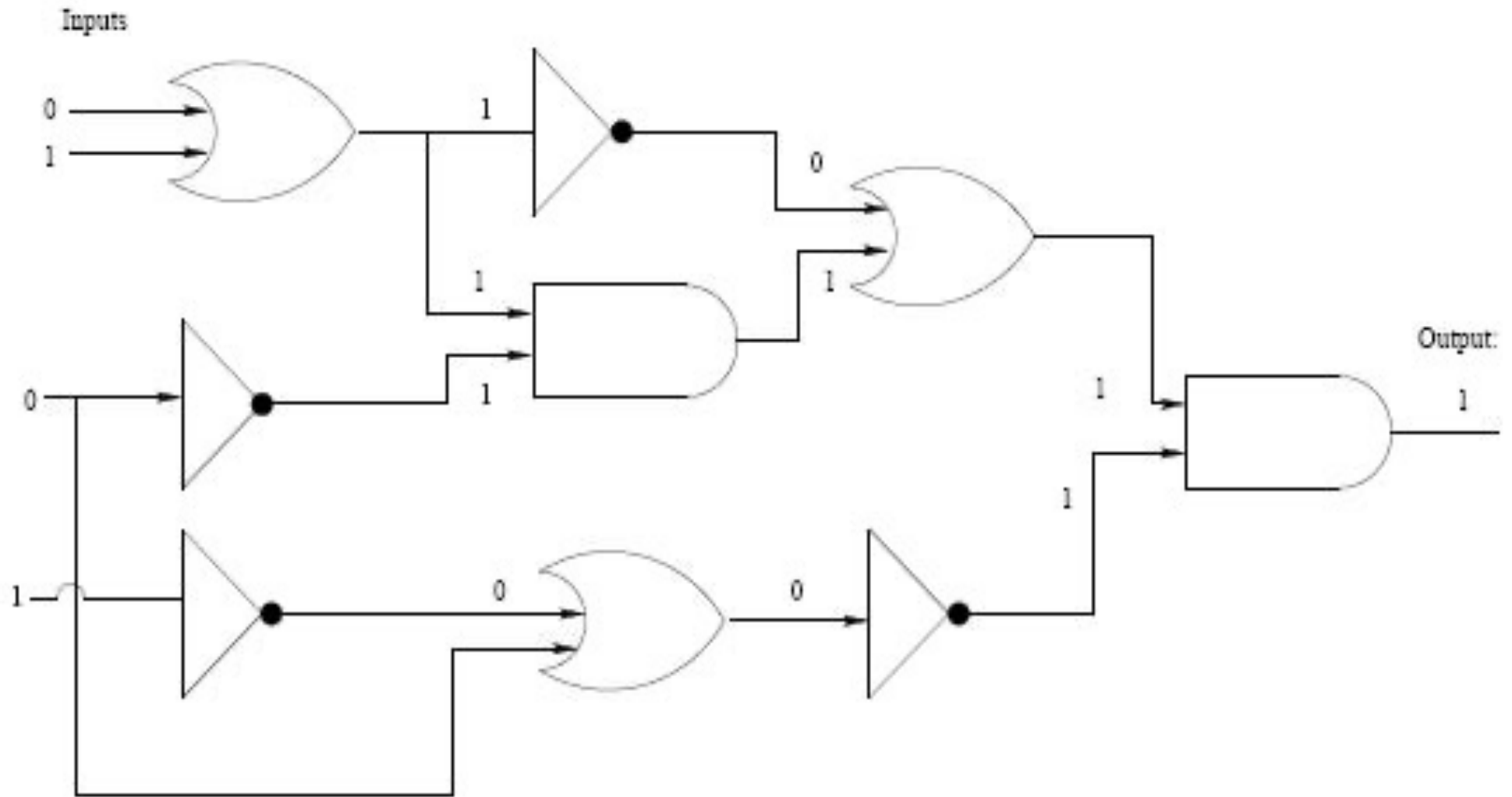
A	B	Output
0	0	0
0	1	1
1	0	1
1	1	1

NOT gate truth table



Input	Output
0	1
1	0

Boolean Circuit - Example



Examples

- We have seen two examples of these difficult problems where no efficient (polynomial) algorithm is known
 - Knapsack problem
 - Hamiltonian circuit problem
 - **One more: Circuit-SAT**

All we know is to exhaust all possible solutions to find the best one

Circuit-SAT

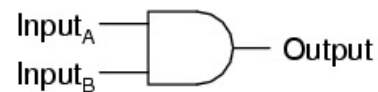
Input: a Boolean Circuit with a single output vertex

Question: is there an assignment of values to the inputs so that the output value is 1?

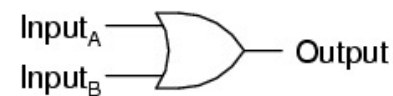
SAT means **satisfiability**

Circuit-SAT

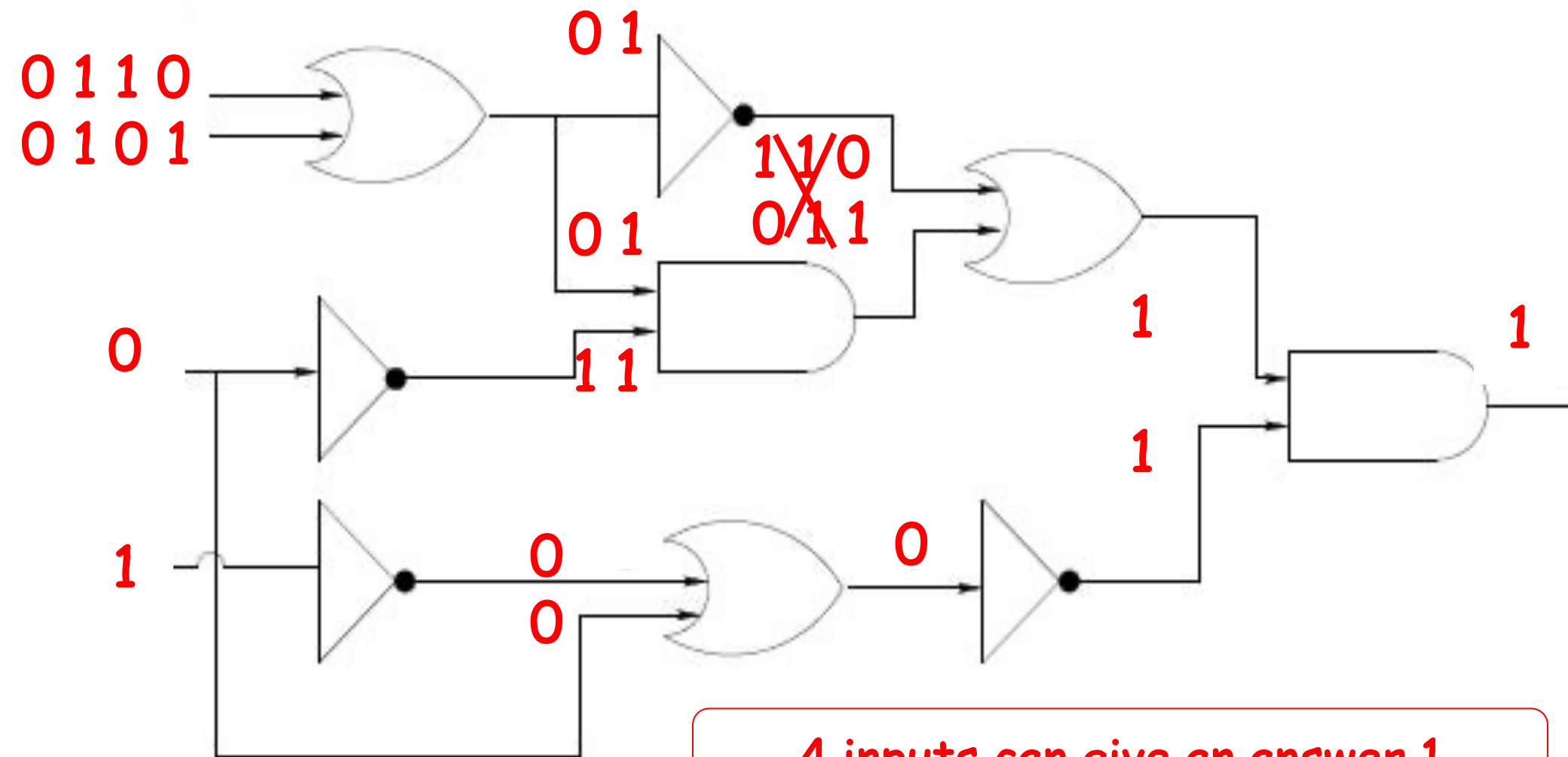
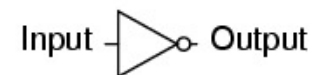
2-input AND gate



2-input OR gate



NOT gate truth table



4 inputs can give an answer 1

why study NP/P?

1. Understanding Computational Limits: Knowing whether a problem is in P or NP helps understand the inherent difficulty of solving certain problems and whether they can be feasibly solved as the size of the input grows.

2. Algorithm Development: If a problem is in P, it can usually be solved efficiently, which encourages the development of effective algorithms. If it's NP-complete or NP-hard, while a polynomial-time solution may not be currently available, it motivates the search for approximate algorithms or heuristics that can solve the problem reasonably well in practice.

3. P vs NP Question: This is one of the seven Millennium Prize Problems for which the Clay Mathematics Institute offers a \$1 million prize for a correct solution. Determining whether P equals NP is fundamental to understanding the limits of what can be computed.

Any more Problems are NP-hard?

Decision/Optimisation problems

A decision problem is a computational problem for which the output is either *yes* or *no*.

In an optimisation problem, we try to *maximise* or *minimise* some value.

An optimisation problem can be *turned into* a decision problem if we add a parameter k , and then ask whether the optimal value in the optimisation problem is *at most* or *at least* k .

Note that if a decision problem is *hard*, then its related optimisation version must also be *hard*.

Example - MST

Optimisation problem: Given a graph G with integer weights on its edges. What is the weight of a *minimum* spanning tree (MST) in G ?

Decision problem: Given a graph G with integer weights on its edges, and *an integer k* . Does G have a MST of weight *at most k* ?

Example – Knapsack problem

Input: Given n items with integer weights w_1, w_2, \dots, w_n and integer values v_1, v_2, \dots, v_n , a knapsack with capacity W and a value k .

Optimisation problem: Find a subset of items whose total weight does not exceed W and that *maximises* the total value.

Decision problem: For *any integer k* , is there a subset of items whose total weight does not exceed W and whose total value is *at least k* ?

Exercise

State the decision version of the following problems

- Given a **weighted** graph G and a source vertex a , find the **shortest** paths from a to every other vertex

Exercise - Solution

- Given a weighted graph G , a source vertex a and *a value k* , are there shortest paths from a to every other vertex such that each path is of weight *at most k* ?

How can solving a decision problem helps to find solution to the optimization problem?

Can All Decision Problems Be Solved By Algorithms?

- ❑ The Answer is **No**.
- ❑ The problems can not solved by algorithms is called **undecidable** problems.
- ❑ One such a problem is Halting Problem (Alan Turing 1936)
“Given a computer program and an input to it, determine whether the program will halt on that input or continue working indefinitely on it.”

Proof: Short but not easy to understand.

Sketch of proof on Halting Problem

If there is an algorithm A such that for any program P and input I

$$A(P, I) = \begin{cases} 1 & \text{if } P \text{ halts on input } I \\ 0 & \text{if } P \text{ does not halt on input } I \end{cases}$$

Consider the following program Q

$$Q(P) = \begin{cases} \text{Halts, if } A(P, P) = 0, \text{ ie. } P \text{ does not halt on input } P \\ \text{Does not halt, if } A(P, P) = 1, \text{ ie. } P \text{ does halt on input } P \end{cases}$$

Now replace P by Q in $Q(P)$

$$Q(Q) = \begin{cases} \text{Halts, if } A(Q, Q) = 0, \text{ ie. } Q \text{ does not halt on input } Q \\ \text{Does not halt, if } A(Q, Q) = 1, \text{ ie. } Q \text{ does halt on input } Q \end{cases}$$

Solving/Verifying a problem

Solving a problem is different from verifying a problem

- solving: we are given an input, and then we have to FIND the solution
- verifying: in addition to the input, we are given a "certificate" and we verify whether the certificate is indeed a solution

We may not know how to solve a problem efficiently, but we may know how to verify whether a candidate is actually a solution

Example – Hamiltonian circuit problem

Suppose through some (unspecified) means (like good guessing), we find a *candidate* for a Hamiltonian circuit, i.e. a list of vertices and edges that *might be a Hamiltonian circuit* in the input graph G .

It is easy to check if this is indeed a Hamiltonian circuit. Check

- that all the proposed edges exist in G ,
- that we indeed have a cycle, and
- that we hit every vertex in G once.

If the candidate solution is indeed a Hamiltonian circuit, then it is a *certificate* verifying that the answer to the decision problem is "Yes"

Example – 0/1 Knapsack Problem

Consider an instance of the 0/1 Knapsack problem
(decision version)

Suppose someone proposes a subset of items, it is easy
to check

- if those items have **total weight at most W** and
- if the **total value is at least k**
- If both conditions are true, then the subset of items
is a **certificate** for the decision problem
 - i.e., it verifies that the answer to the 0/1 knapsack
decision problem is "Yes"

Example – Circuit-SAT

Consider a Boolean Circuit

Suppose someone proposes an assignment of truth values to the input, it is easy to check

- if the input values lead to a final value of 1 in the output
- this is done by checking every logic gate

If the input truth values give a final value of 1, these values form a *certificate* for the decision problem