INT104 ARTIFICIAL INTELLIGENCE

LECTURE 3- DIMENSIONALITY REDUCTION

Sichen Liu Sichen.Liu@xjtlu.edu.cn





CONTENT

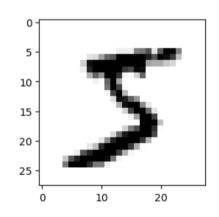
- Why need Dimensionality Reduction
- Principal Component Analysis (PCA)
- Locally Linear Embedding (LLE)
- ➤ Other Dimensionality Reduction Techniques

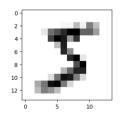


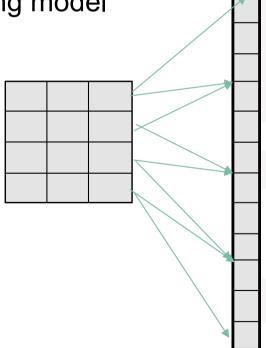
Dimensionality Reduction

Data with high dimensions:

- High computational complexity
- May contain many irrelevant or redundant features
- Difficulty in visualization
- With high risk of getting an overfitting model





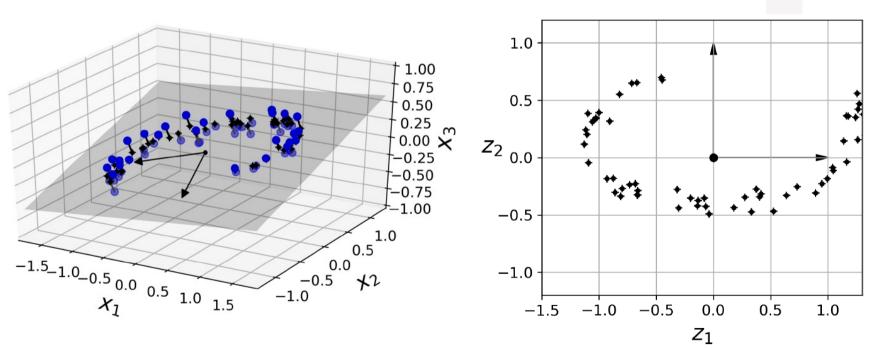




Approaches for Dimensionality Reduction

Projection:

 Data is not spread out uniformly across all dimensions. (All the data lies within (or close to) a much lower-dimensional subspace of the high-dimensional space.





Preserving the Variance:

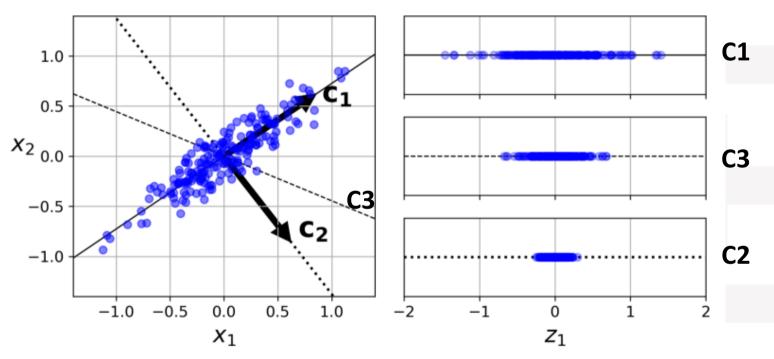


Figure 8-7. Selecting the subspace to project on

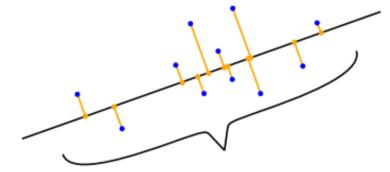
PCA identifies the axis that accounts for the largest amount of variance in the training set.

-Variance on C1

$$V_1 = \frac{1}{M} \sum_{i=1}^{M} (\boldsymbol{c}_1^{\mathsf{T}} \boldsymbol{x}^{(i)})^2 = \frac{1}{M} \sum_{i=1}^{M} \boldsymbol{c}_1^{\mathsf{T}} \boldsymbol{x}^{(i)} \boldsymbol{x}^{(i)\mathsf{T}} \boldsymbol{c}_1 = \boldsymbol{c}_1^{\mathsf{T}} (\frac{1}{M} \sum_{i=1}^{M} \boldsymbol{x}^{(i)} \boldsymbol{x}^{(i)\mathsf{T}}) \boldsymbol{c}_1$$
$$= \boldsymbol{c}_1^{\mathsf{T}} S \boldsymbol{c}_1$$

-Data covariance matrix

$$S = \frac{1}{M} \sum_{i=1}^{M} \boldsymbol{x}^{(i)} \boldsymbol{x}^{(i)^{\mathsf{T}}}$$



- S is an N*N matrix, N is the number of features, M is the total number of data points.



-Constrained optimization problem

$$\max_{c_1} c_1^{\mathsf{T}} S c_1$$

subject to $||c_1||^2 = 1$

- -Lagrange equation $\mathcal{L}(\boldsymbol{c}_1, \lambda_1) = \boldsymbol{c}_1^{\mathsf{T}} S \boldsymbol{c}_1 + \lambda_1 (1 \boldsymbol{c}_1^{\mathsf{T}} \boldsymbol{c}_1)$
- -Solve this constrained optimization problem

$$\frac{\partial \mathcal{L}}{\partial c_1} = 2Sc_1 - 2\lambda_1 c_1 \qquad \frac{\partial \mathcal{L}}{\partial \lambda_1} = 1 - c_1^{\mathsf{T}} c_1$$

- Setting these partial derivatives to 0 gives us the relations:

$$S \boldsymbol{c}_1 = \lambda_1 \boldsymbol{c}_1$$
 and $\boldsymbol{c}_1^{\mathsf{T}} \boldsymbol{c}_1 = 1$

Variance on C1

$$V_1 = \boldsymbol{c}_1^{\mathsf{T}} S \boldsymbol{c}_1 = \lambda_1 \boldsymbol{c}_1^{\mathsf{T}} \boldsymbol{c}_1 = \lambda_1$$



Practice: PCA

Given a dataset that consists of the following points below:

$$A=(2, 3), B=(5, 5), C=(6, 6), D=(8,9)$$

- 1. Calculate the covariance matrix for the dataset.
- 2. Calculate the eigenvalues and eigenvectors of the covariance matrix.



Singular Value Decomposition (SVD)

Theorem: Let $A \in \mathbb{R}^{m*n}$ be a rectangular matrix of rank $r \in [0, min(m, n)]$. The SVD of A is a decomposition of the form

$$\mathbf{E} \begin{bmatrix} \mathbf{A} \\ \mathbf{A} \end{bmatrix} = \mathbf{E} \begin{bmatrix} \mathbf{U} \\ \mathbf{V} \end{bmatrix} \mathbf{E} \begin{bmatrix} \mathbf{\Sigma} \\ \mathbf{V}^{\top} \end{bmatrix} \mathbf{E} \mathbf{E} \mathbf{V}$$

- $-U \in \mathbb{R}^{m*m}$ is an orthogonal matrix with column vectors u_i , $i = 1, \dots m$,
- $V \in \mathbb{R}^{n \times n}$ an orthogonal matrix with column vectors v_j , $j = 1, \dots n$.
- Σ is an m × n matrix with $\Sigma_{ii} = \sigma_i \ge 0$ and $\Sigma_{ij} = 0$, $i \ne j$
- The singular value matrix Σ is unique



Singular Value Decomposition (SVD)

$$A = [x_1 \quad \dots \quad x_n]_{m*n} = U \Sigma V^{\mathsf{T}} = [u_1 \quad \dots \quad u_m]_{m*m} \begin{bmatrix} \sigma_1 & 0 & 0 \\ 0 & \ddots & 0 \\ 0 & 0 & \sigma_n \\ 0 & \dots & 0 \\ \vdots & & \vdots \\ 0 & \dots & 0 \end{bmatrix}_{m*n} [v_1 \quad \dots \quad v_n]_{n*n}^{\mathsf{T}}$$

V contains the unit vectors that define all the principal components that we are looking for.

```
X_centered = (X - X.mean(axis=0))/X.std(axis=0)
U, s, Vt = np.linalg.svd(X_centered)
c1 = Vt.T[:, 0]
c2 = Vt.T[:, 1]
```



Principal components matrix

$$\mathbf{V} = \left(egin{array}{cccc} |&|&&|\ \mathbf{c}_1 & \mathbf{c}_2 & \cdots & \mathbf{c}_n\ |&|&&| \end{array}
ight)$$

 $c_1, c_2 \dots c_n$ are orthogonal

Projecting Down to d Dimension:

$$X_{d-proj} = XV_d$$

 V_d is the first d eigen vectors of data covariance matrix

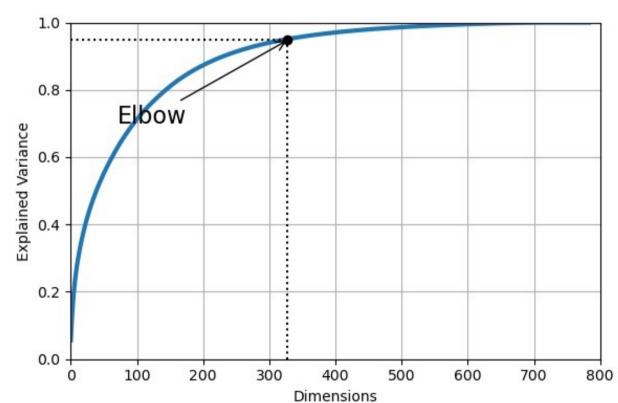
Explained Variance Ratio

$$\frac{\lambda_1}{\lambda_1 + \lambda_2 \dots + \lambda_n}$$
 (eigenvalue/ total eigenvalue)



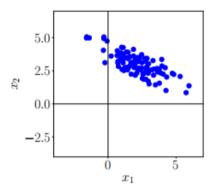
Choosing the Right Number of Dimensions:

- Choose the number of dimensions that add up to sufficiently large portion of the variance (e.g., 95%)
- $\frac{\lambda_1 + \dots + \lambda_d}{\lambda_1 + \lambda_2 \dots + \lambda_n} > 95\%$

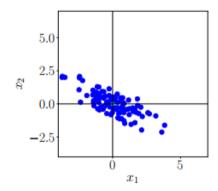




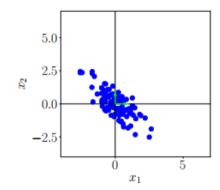
Key steps of PCA in practice



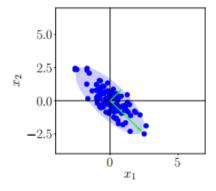
(a) Original dataset.



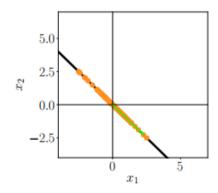
(b) Step 1: Centering by subtracting the mean from each data point.



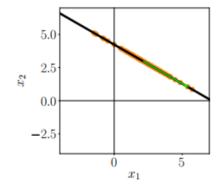
(c) Step 2: Dividing by the standard deviation to make the data unit free. Data has variance 1 along each axis.



(d) Step 3: Compute eigenvalues and eigenvectors (arrows) of the data covariance matrix (ellipse).



(e) Step 4: Project data onto the principal subspace.



(f) Undo the standardization and move projected data back into the original data space from (a).



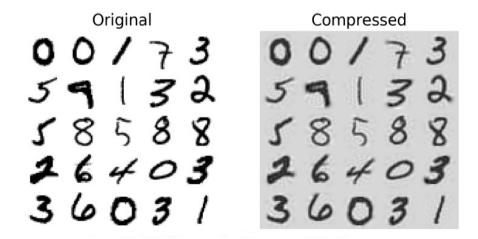
PCA for Compression

Projecting Down to d Dimension

$$X_{d-proj} = XV_d$$

 PCA inverse transformation, back to the original number of dimensions

$$X_{recovered} = X_{d-proj} V_d^{\mathsf{T}}$$

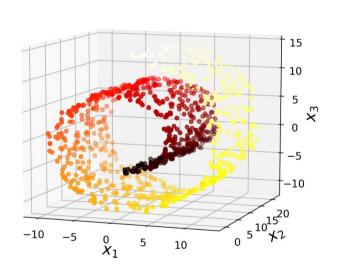


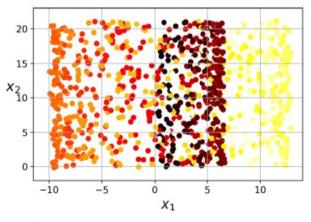


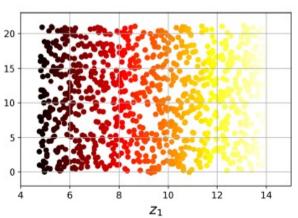
Approaches for Dimensionality Reduction

Manifold Learning

 Data lies on d-dimensional manifold is a part of an ndimensional space (where d < n)







Simply projecting onto a plane

Unrolling the Swiss roll



Locally Linear Embedding (LLE)

LLE is a powerful *nonlinear dimensionality reduction* (NLDR) technique. It is a Manifold Learning technique that does not rely on projections

Step one: Linearly modeling local relationships

$$\begin{split} \widehat{\mathbf{W}} &= \operatorname*{argmin} \sum_{i=1}^m \left(\mathbf{x}^{(i)} - \sum_{j=1}^m w_{i,j} \mathbf{x}^{(j)} \right)^2 \\ \text{subject to} & \begin{cases} w_{i,j} = 0 & \text{if } \mathbf{x}^{(j)} \text{ is not one of the } k \text{ c.n. of } \mathbf{x}^{(i)} \\ \sum_{j=1}^m w_{i,j} = 1 & \text{for } i = 1, 2, \cdots, m \end{cases} \end{split}$$

Step two: Reducing dimensionality while preserving relationships

$$\widehat{\mathbf{Z}} = rgmin_{\mathbf{Z}} \sum_{i=1}^m \left(\mathbf{z}^{(i)} - \sum_{j=1}^m \widehat{w}_{i,j} \mathbf{z}^{(j)}
ight)^2$$



Locally Linear Embedding (LLE)

from sklearn.manifold import LocallyLinearEmbedding

```
lle = LocallyLinearEmbedding(n_components=2, n_neighbors=10)
X_reduced = lle.fit_transform(X)
```

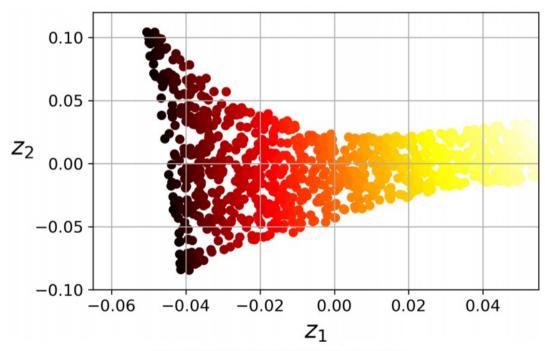


Figure 8-12. Unrolled Swiss roll using LLE



Other Techniques

- Multidimensional Scaling (MDS)
 Trying to preserve the distances between the instances.
- Isomap
 Trying to preserve the geodesic distances between the instances.
- t-Distributed Stochastic Neighbor Embedding (t-SNE)
 Trying to keep similar instances close and dissimilar instances apart.

