

Two way improve k-means

repeat better 和 和 和

RBF = only one hd layer, diff activation local approximate

MLP: same activation in layers, inner product, global approximate, more hd.

Example: $3 \times 3, d=3, \{0,1\}, -1$

compute hidden layers

$$P_{11} = 1, P_{12} = \exp(-\frac{(0-0)^2 + (0-1)^2}{2}) = \exp(-1)$$

$$P_{13} = \exp(-0.5) = \dots$$

$$\Rightarrow y = \begin{pmatrix} 0.3679 & 0.6065 & 0.6065 \\ 0.6065 & 0.6065 & 1 \end{pmatrix}$$

calculate related weight vector and predict values of each input

$$W = \frac{(y^T y)^{-1} y^T d}{d^T d} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\Rightarrow W = \begin{pmatrix} 0.0288 & 0.3679 \\ -0.6307 & 0.6065 \end{pmatrix} \Rightarrow \text{prediction}$$

$$\Rightarrow W = \begin{pmatrix} 0.0288 & 0.3679 \\ -0.6307 & 0.6065 \end{pmatrix} \Rightarrow e = \begin{pmatrix} 3 \\ -1 \end{pmatrix}$$

suppose only two examples

$\{1,0\}, \{0,1\}$ are also corners

recalculate $y = \begin{pmatrix} 0.3679 & 0.3679 \\ 0.6065 & 0.6065 \end{pmatrix}$

$\Rightarrow W? \Rightarrow e? y? \neq d$

for input vector $(0,0)$ calculator hd and output with $2, 3$

$\phi \rightarrow \text{把 } (0,0) \text{ 代入 } W$ 且 $\Rightarrow e?$

$y = (0.6065, 0.6065, 0.3679)$

Time-Series Model

时序模型 / wide-sense stationarity

difficulty: limit data / noise / non stationarity

(model maintain state) dynamic network

RBF, MLP (static)

Time-Delayed Network

Elman Network (simple RNN)

$$y = F_w(cz^t), z^t = F_v(cz^{t-1}, x)$$

(context layer)

RNN: $F_c(x(t), s(t-1)) / F_c(s(t))$

unfold to feed forward

Vanish Gradients: BPTT with GC, detectable slope

LSTM

$C(t) = F_c(x(t), y(t-1))$

$z(t) = F_v(C(t), y(t-1))$

CEC (memory cell):

$$C(t) = z(t) \odot i(t) + C(t-1) \odot \neg i(t)$$

$y(t) = h(C(t)) \odot O(t)$

No-decaying error / no fine tune

$h(C(t))$ unbounded

PCA: $AV = \lambda V \Rightarrow |A - \lambda I| = 0$

$S = U \Lambda U^{-1}$ if $S \in \mathbb{R}^{m \times m}$

$\Lambda = \text{diag}(\lambda_1, \dots, \lambda_m)$ V is 单位向量

$A \in \mathbb{R}^{m \times n} = U \Sigma V^T$

$U(AA^T) V(AA^T) G = \tilde{A}$

$\Sigma = \text{diag}(G_1, \dots, G_r), \lambda_1, \dots, \lambda_r$ AAT

Eiginface $b = W^T X$ face V

$V^T X \cdot V = \lambda$

Unsupervised learning

eg. Hebb's rule

QJA's rule $W_{ij}(t+1) = \frac{W_{ij}(t) + y_i(x_j - y_j)}{\sum_{i=1}^n (W_{ij}(t) + y_i(x_j - y_j))}$

$\Rightarrow W_{ij}(t+1) = W_{ij}(t) + y_i(x_j - y_j) / \sum_{i=1}^n (W_{ij}(t) + y_i(x_j - y_j))$

deflation method

PCA in NN encoder/decoder

k-means not optimal

Competitive learning one winner-takes-all units $V_i(t+1) = \text{sgn}(H_i(t+1))$

Winner: $k_j = \sum W_{ji} x_j, W_j \cdot x \geq W_{j'} \cdot x$

$\Rightarrow y_j = 1$ if $j = k$, $y_j = 0$ if $j \neq k$

leaky learning $W(t+1) = W(t) + \eta y_i x_j - \eta y_i W(t)$

losing unit \rightarrow dense $y_w \gg y_l$

Maxnet CWTAE

Ex: $SCL, \Delta W_{ji} = \eta y_i (x_j - W_{ji})$

$y_j = 1$ if $j = k$, $y_j = 0$ if $j \neq k$

2 prototype: Euclidean distance

$0.14, 0.75, 0.71, 0.99, 0.51, 0.37$

$0.73, 0.81, 0.87$

距离 \rightarrow 更新 \rightarrow update 把 6 点

SOM (Self Organize Map) reduce dim / vector quantization

transform input into 1-2d

Competition

Cooperation

Synaptic Adaptation

$W_{ij}(t+1) = W_{ij}(t) + y_i(x_j - W_{ij}(t))$

$\eta \exp(-\frac{t}{\tau}) \cdot \exp(-\frac{d_{ij}}{\sigma})$

Associative Memory & Pattern Association

auto ($x=y$) associate / hetero \rightarrow

The Hopfield Network (dNN / energy)

$$W_{ij} = \frac{1}{N} \sum_{i=1}^N x_i y_j, W_{ii} = 0$$

Asynchronous update rule

$$H_i(t+1) = \sum_{j=1}^N W_{ij} V_j(t) + I_i$$

$V_i(t+1) = \text{sgn}(H_i(t+1)) = \begin{cases} 1 & \geq 0 \\ -1 & < 0 \end{cases}$

limitation: number store limited

unstable if shares bits common

Ex: 4-patterns $x_1 = (1, 1, 1, 1), x_2 = (1, 1, 1, 1), x_3 = (1, 1, 1, 1), x_4 = (1, 1, 1, 1)$

compute W

$$W_{11} = W_{22} = \dots = W_{44} = 0$$

$$W_{12} = W_{21} = \frac{1}{4} (1+1+1+1) = 1$$

$$W_{13} = W_{31} = \frac{1}{4} (1+1+1+1) = 1$$

Recover $x_i = (1, 1, 1, 1)$

$y_i(t+1) = \sum_{j=1}^n W_{ij} y_j(t)$

$= \frac{1}{4} (2 \cdot 1 + 0 \cdot 1 + 1 \cdot 1 + 1 \cdot 1) = 1$

node 1, 2, 3, 4 noisy $(1, 1, 1, 1)$

node 1: $y_1(t) = \frac{1}{4} (2 \cdot 1 + 0 \cdot 1 + 1 \cdot 1 + 1 \cdot 1) = 1$

node 2: $y_2(t) = \frac{1}{4} (1 \cdot 1 + 2 \cdot 1 + 0 \cdot 1 + 1 \cdot 1) = 1$

node 3: $y_3(t) = \frac{1}{4} (1 \cdot 1 + 1 \cdot 1 + 2 \cdot 1 + 0 \cdot 1) = 1$

node 4: $y_4(t) = \frac{1}{4} (1 \cdot 1 + 1 \cdot 1 + 1 \cdot 1 + 2 \cdot 1) = 1$

no external

$\Rightarrow \frac{1}{4}, -1$

$\frac{1}{4}, 1$

$\frac{1}{4}, 1$

$-\frac{1}{4}, -1$

MF Neuron (1943)

$$y_i = \sum_{j=1}^n w_{ij} x_j$$

$a_i = 0, b_i = 1$

$W_{ij} = -1$

$st = \sum_{i=1}^n w_{ij} a_i \geq 0$

Heaviside function: $H(x) = \begin{cases} 1, & x \geq 0 \\ 0, & x < 0 \end{cases}$

Hebb's rule: $W_{ij}^k = W_{ij}^0 + \Delta W_{ij}^k$

where $\Delta W_{ij}^k = C a_i^k b_j^k$

\Rightarrow propose correlation of Hebbian synapse

but: it only increase, wash out diff performance in neuron

Supervised learning: Casualty

train set and test set identical

Perceptron: 1958 "error correcting rule"

$S_j = \sum_{i=1}^n w_{ij} a_i$, taken $n+1$ inputs, a bias input

bias is constant, but its weight can be changed

Perceptron learning (weight adjustment / delta rule)

$e_j = (t_j - y_j)$, $y_j = f(S_j)$

$\Delta W_{ij} = e_j a_i$

$W_{ij} = W_{ij}^0 + \Delta W_{ij}$, $\Delta W_{ij} = C \cdot e_j \cdot a_i$

perceptron converges: lr is small; linear separable

perceptron performance: RMS (root-mean-square)

$\sqrt{\frac{\sum (x_i - y_i)^2}{N}}$ only connected with weights

perceptron classification: decision boundary $w \cdot x = 0$

or $\sum_{i=1}^n w_i x_i = 0$, can not solve "XOR" use $w_1 x_1 + w_2 x_2$

Gradient Descent Rule: $E(w) = \frac{1}{2} \sum (y_i - \hat{y}_i)^2$

$w_i = w_i - \eta \frac{\partial E}{\partial w_i}$

$\Delta w_i = \eta (y_i - \hat{y}_i) x_i$

For batch learning: $\Delta w_i = \Delta w_i + \eta (y_i - \hat{y}_i) x_i$ then $w_i = w_i + \Delta w_i$

For incremental: $w_i = w_i + \eta (y_i - \hat{y}_i) x_i$

Sigmoidal: $GCS = \frac{1}{1+e^{-x}}$

$S = \sum_{i=1}^n w_i x_i$, $GCS = GCS(1-GCS) \cdot x_i$

$W_i = W_i + \eta \sum_{j=1}^n (y_j - \hat{y}_j) GCS_j (1-GCS_j) x_{ij}$

parabolas 椭圆

perceptron: threshold, converges

linear separable

GD: converge min error

MLP: learn arbitrary/continuous/Boolean function

hyperbolic tangent $\sigma = \tanh(x) = \frac{e^x - e^{-x}}{e^x + e^{-x}}$

$\tanh'(x) = \frac{e^x - e^{-x}}{e^x + e^{-x}} \cdot \frac{e^x + e^{-x}}{e^{2x} + e^{-2x}} = \frac{e^x - e^{-x}}{e^{2x} + e^{-2x}}$

$f(x) = GCS \sum_{j=1}^n W_{jk} GCS_j (1-GCS_j) x_{jk}$

$q_j = GCS_j$, $s_j = \frac{1}{1+e^{-x_j}}$, $s_j = \frac{1}{1+e^{-x_j}}$

$o_k = GCS_k$, $s_k = \frac{1}{1+e^{-x_k}}$, $s_k = \frac{1}{1+e^{-x_k}}$

Backpropagation:

$\Delta W_{jk} = \eta \delta_k o_j$, $\Delta W_{ok} = \eta \delta_k$

$\delta_k = o_k(1-o_k) \cdot y_k - o_k$

$\Delta W_{ij} = \eta \delta_j o_i$, $\Delta W_{oj} = \eta \delta_j$

$\delta_j = o_j(1-o_j) \cdot C \sum_{k=1}^n \delta_k W_{jk}$

Revision by example online training

Revision by epoch = Batch learning

random presentation \rightarrow better results

random initialization

hidden layer (not add representation power)

learning rate

Momentum (smooth / fast convergence)

$\Delta W(t) = -\eta \frac{\partial E}{\partial W(t)} + \alpha \Delta W(t-1)$

Generalization Overfitting error small, new data high

Reasons of overfit: number of free param is bigger

Measure: early stop / network pruning / regularization / weight decay (penalty / term)

k-fold cross validation (useful small sets)

MLP limitations: sensitive to hd layers / lr rate

$\{0,0,1\} \{0,1,0\} \{1,0,1\}$ $\Delta W(t) = \eta \frac{\partial E}{\partial W(t)} + \alpha \Delta W(t-1)$ $\eta = 0.2, \alpha = 0.1, \text{max} = 1$

forward: $z_1 = w_{11}x_1 + w_{12}x_2 + w_{13}x_3$ two input, one hidden one output

$= 1 + 0 + 1 = 2$

$k = GCS(2) = \frac{1}{1+e^{-2}} = 0.8808$, $GCS(2) = 0.8808$

$z_2 = w_{21}x_1 + w_{22}x_2 + w_{23}x_3 = 0.8808 + 1 = 1.8808$

$o_k = GCS(z_2) = 0.8675$, $GCS(z_2) = 0.8675$

backward: $\beta_2 = (y - \hat{y}) GCS'(z_2) = -0.0152$

$\beta_1 = \beta_2 \cdot W_{21} \cdot GCS'(z_1) = -0.0016$

$\Rightarrow w_{11}, w_{12}, w_{13}, w_{21}, w_{22}, w_{23}$ 不要把 bias 加

Deep Learning: Function composition

CNN: sparse connectivity (receptive fields)

$N \times N \downarrow m \times m$ filter

$(N-m+1) \times 2$

shared weights (feature map)

convolution $h_{ij} = \tanh(W^k x_{ij} + b_k)$

img \rightarrow convolution \rightarrow non-linearity \rightarrow spatial pooling \rightarrow normalization

(relu) $\max(0, x)$

relative position

spatial resolution

(max) down sample / translation invariance

Transfer learning: share param + new adaptation

RBF Network: $F(x) = \sum_{i=1}^n w_i \phi(\|x - x_i\|)$

Regularization Network: $F(x) = \sum_{i=1}^n w_i \exp(-\|x - x_i\|^2 / 2\sigma_i^2)$

problem: computational inefficient / large ϕ / param

nonlinear-function transform \rightarrow easy linear mapping

RBF: $\phi(x) = \exp(-\|x - x_i\|^2 / 2\sigma_i^2)$

$F(x) = \sum_{i=1}^n w_i \phi(x)$

$\hat{W} = d \Rightarrow W = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix}$

$\hat{W} = d \Rightarrow W = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix}$

k means: k 个 data \rightarrow 每个点 k 距离

not suitable for non-convex shape / sensitive to noise and outlier