



Xi'an Jiaotong-Liverpool University

西交利物浦大学

INT305 Machine Learning

Lecture 5

Neural Network and Back Propagation

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Neural network

Neural Network: without the brain stuff

(Before) Linear score function: $f = Wx$

Neural network

Neural Network: without the brain stuff

(Before) Linear score function: $f = Wx$

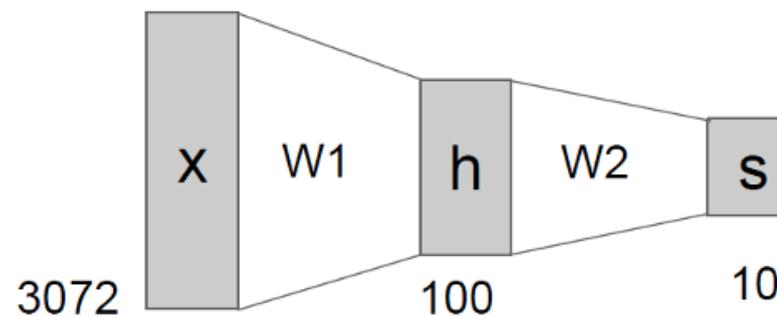
(Now) 2-layer Neural Network: $f = W_2 \max(0, W_1 x)$

Neural network

Neural Network: without the brain stuff

(Before) Linear score function: $f = Wx$

(Now) 2-layer Neural Network: $f = W_2 \max(0, W_1 x)$



Neural network

Neural Network: without the brain stuff

(Before) Linear score function: $f = Wx$

(Now) 2-layer Neural Network: $f = W_2 \max(0, W_1 x)$

or 3-layer Neural Network:

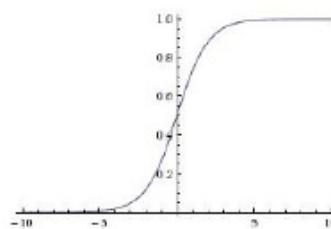
$$f = W_3 \max(0, W_2 \max(0, W_1 x))$$

Activation functions

Activation Functions

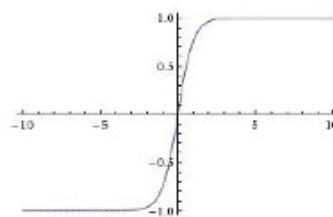
Sigmoid

$$\sigma(x) = 1/(1 + e^{-x})$$



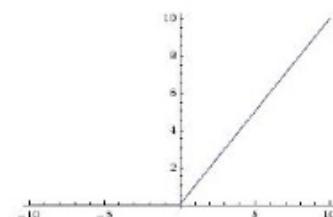
tanh

$$\tanh(x)$$



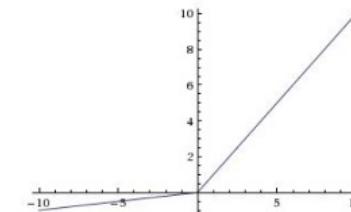
ReLU

$$\max(0, x)$$



Leaky ReLU

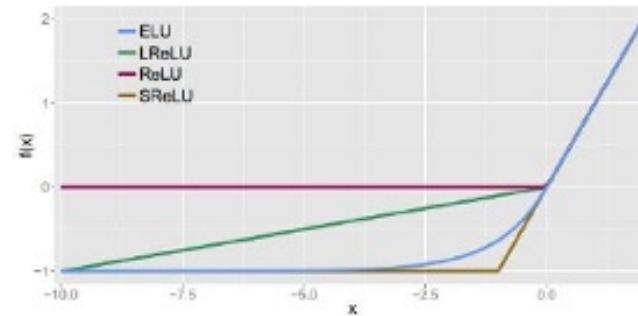
$$\max(0.1x, x)$$



$$\text{Maxout } \max(w_1^T x + b_1, w_2^T x + b_2)$$

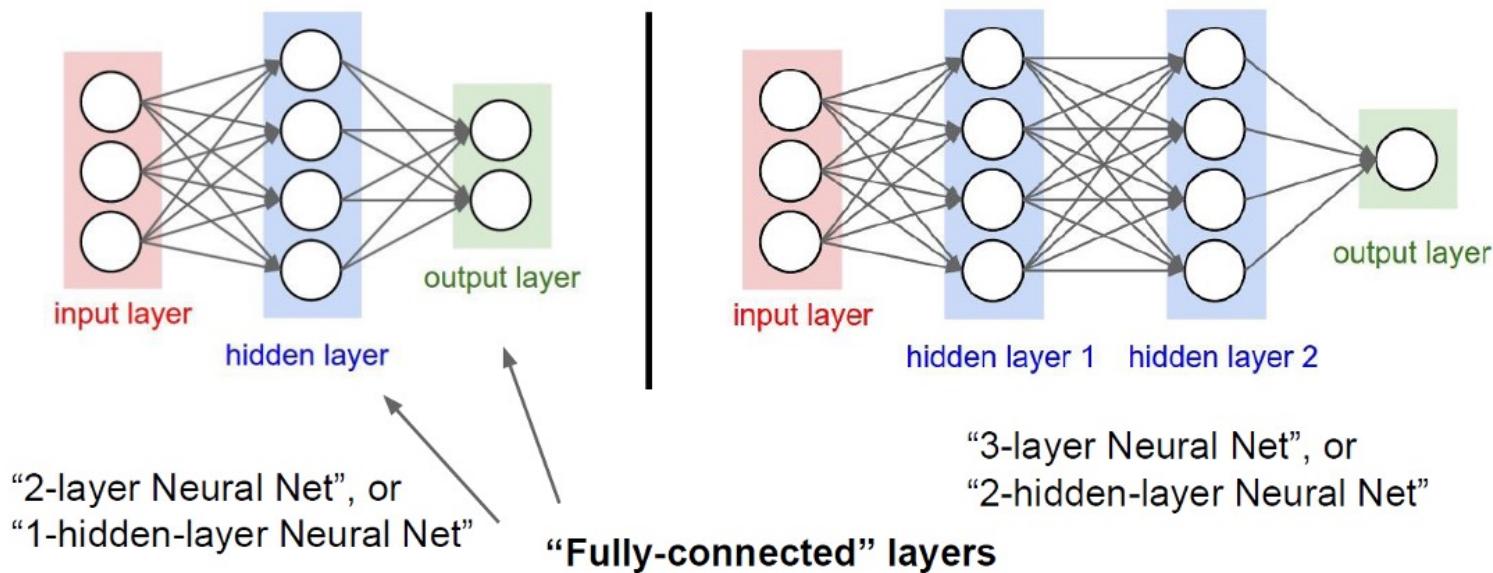
ELU

$$f(x) = \begin{cases} x & \text{if } x > 0 \\ \alpha(\exp(x) - 1) & \text{if } x \leq 0 \end{cases}$$



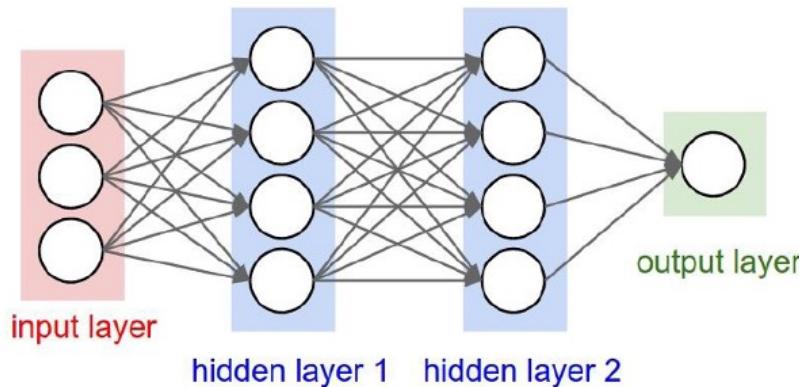
Neural network

Neural Networks: Architectures



Neural network

Example Feed-forward computation of a Neural Network



```
# forward-pass of a 3-layer neural network:  
f = lambda x: 1.0/(1.0 + np.exp(-x)) # activation function (use sigmoid)  
x = np.random.randn(3, 1) # random input vector of three numbers (3x1)  
h1 = f(np.dot(W1, x) + b1) # calculate first hidden layer activations (4x1)  
h2 = f(np.dot(W2, h1) + b2) # calculate second hidden layer activations (4x1)  
out = np.dot(W3, h2) + b3 # output neuron (1x1)
```

Gradient Descent

Where we are...

$$s = f(x; W) = Wx \quad \text{scores function}$$

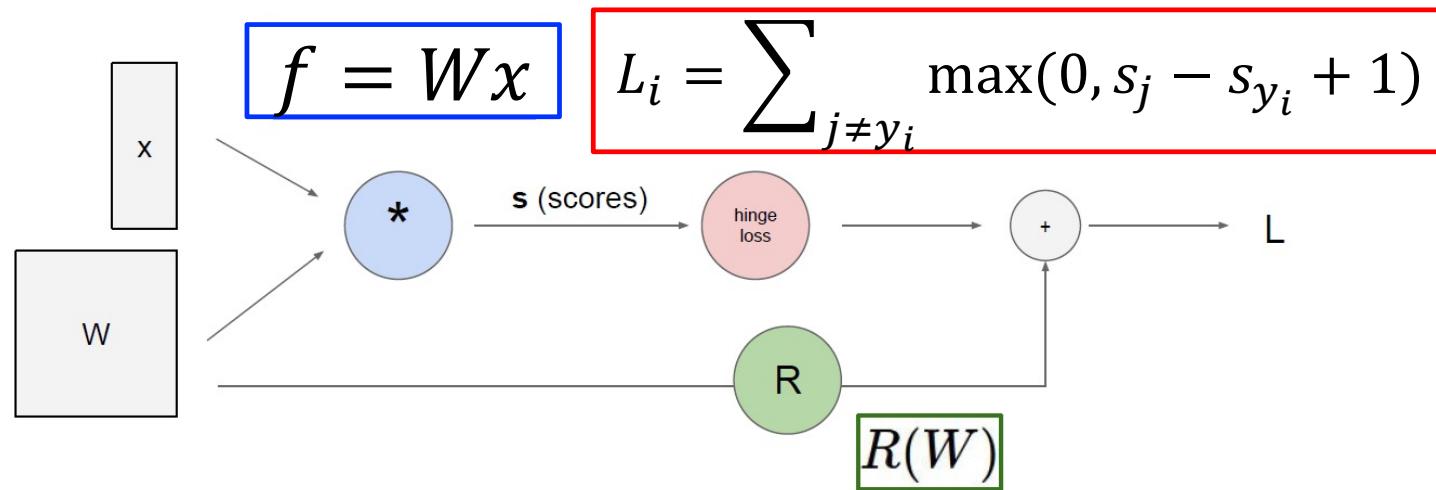
$$L_i = \sum_{j \neq y_i} \max(0, s_j - s_{y_i} + 1) \quad \text{SVM loss}$$

$$L = \frac{1}{N} \sum_{i=1}^N L_i + \sum_k W_k^2 \quad \text{data loss + regularization}$$

want $\nabla_W L$

Computational Graph

Computational Graph

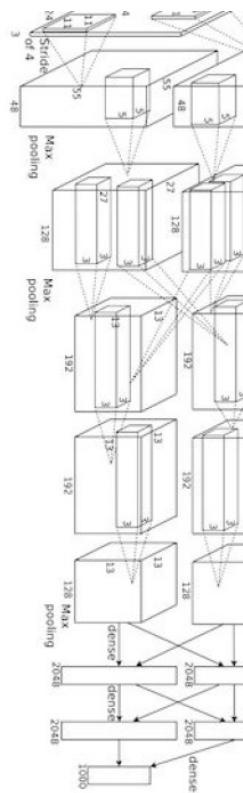


Computational Graph

Convolutional Network (AlexNet)

input image
weights

loss

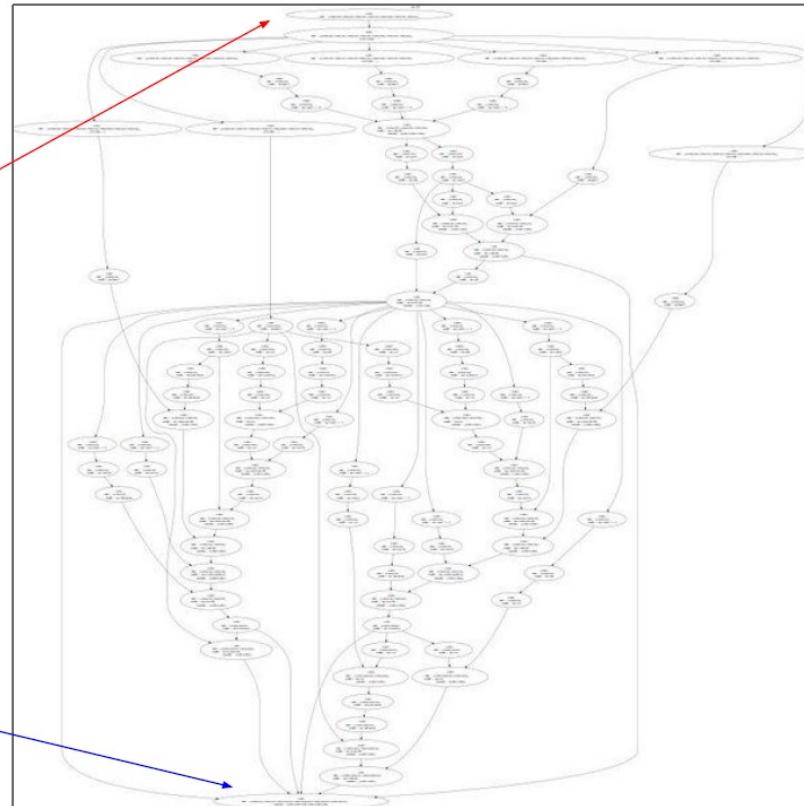


Computational Graph

Neural Turing Machine

input tape

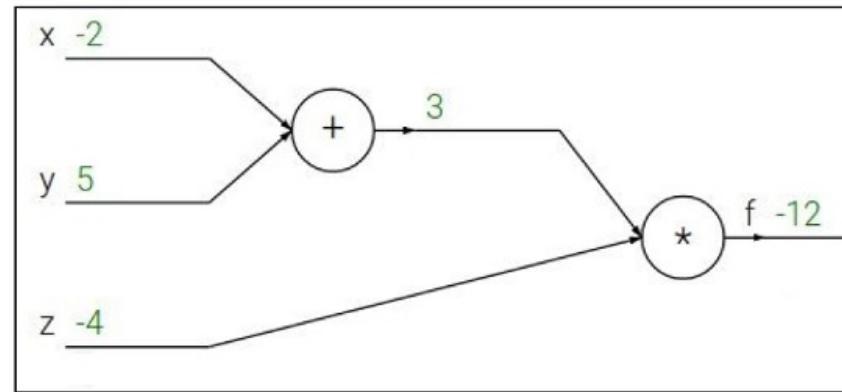
loss



Example 1

$$f(x, y, z) = (x + y)z$$

e.g. $x = -2, y = 5, z = -4$



Example 1

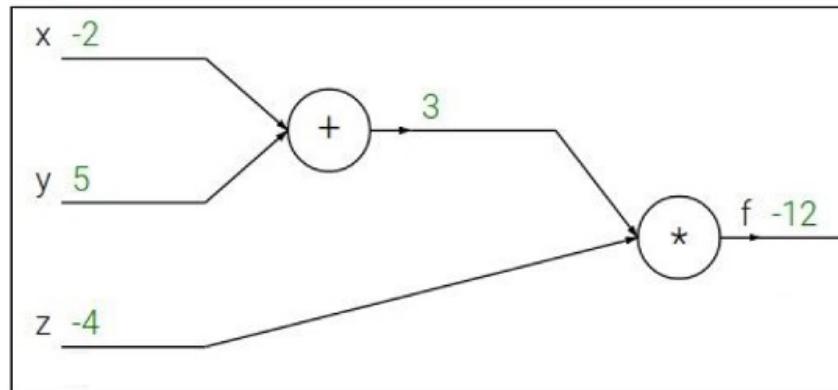
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$$q = x + y \quad \frac{\partial q}{\partial x} = 1, \frac{\partial q}{\partial y} = 1$$

$$f = qz \quad \frac{\partial f}{\partial q} = z, \frac{\partial f}{\partial z} = q$$

Want: $\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z}$



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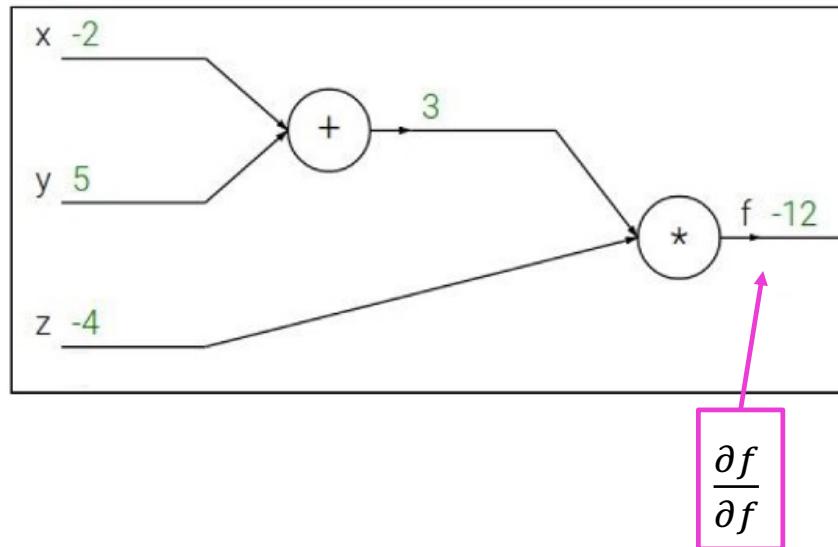
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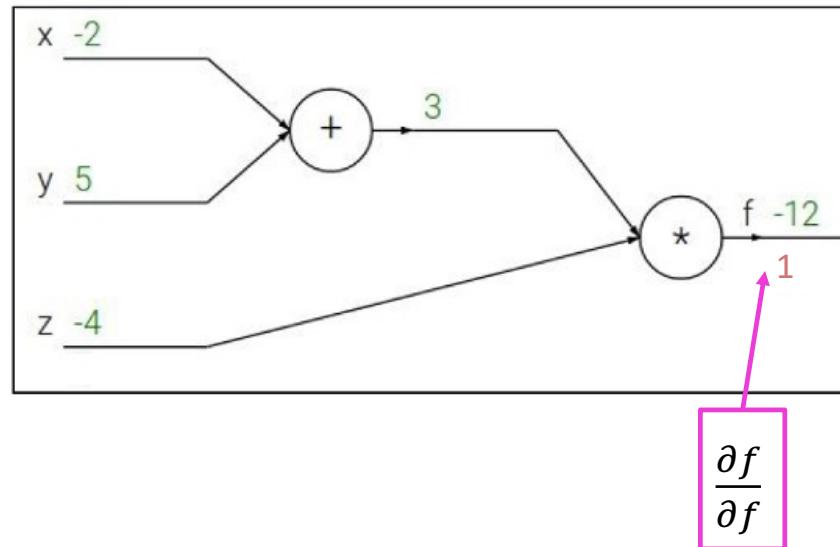
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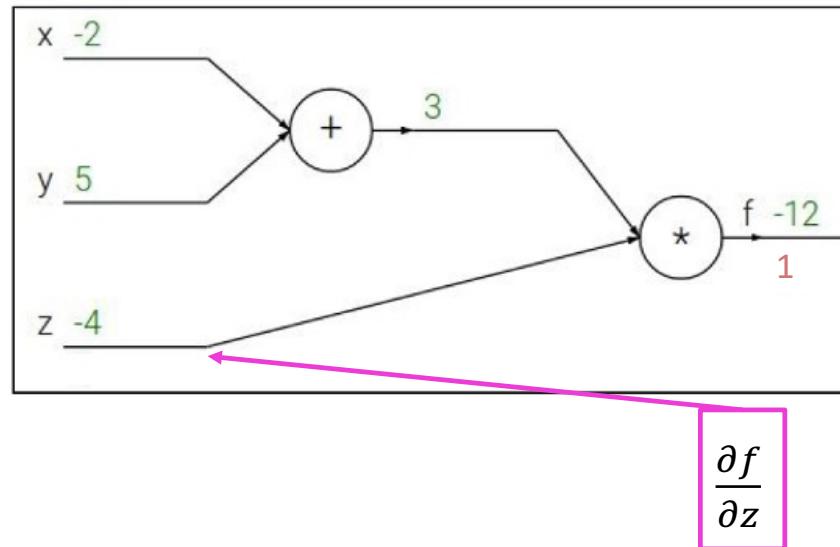
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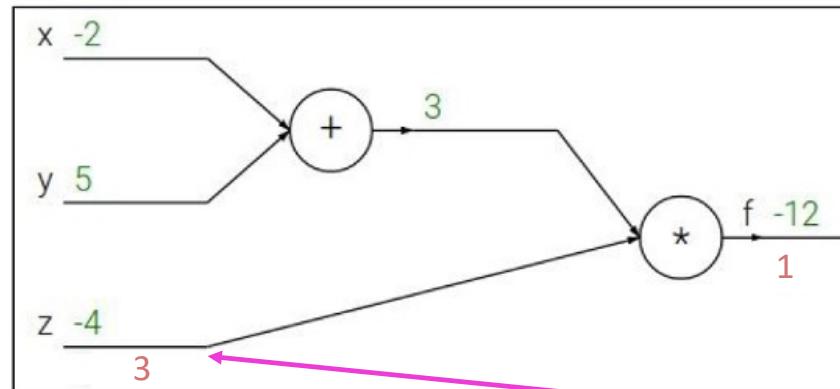
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$$\frac{\partial f}{\partial z}$$

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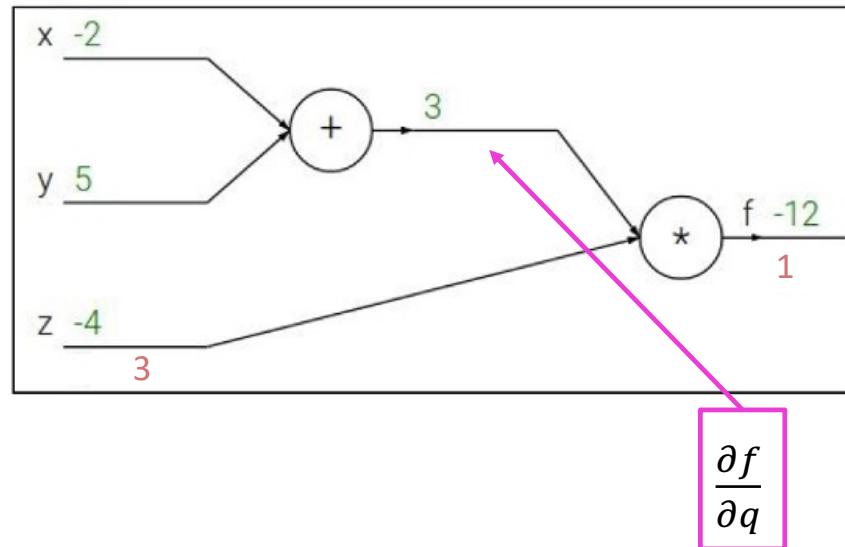
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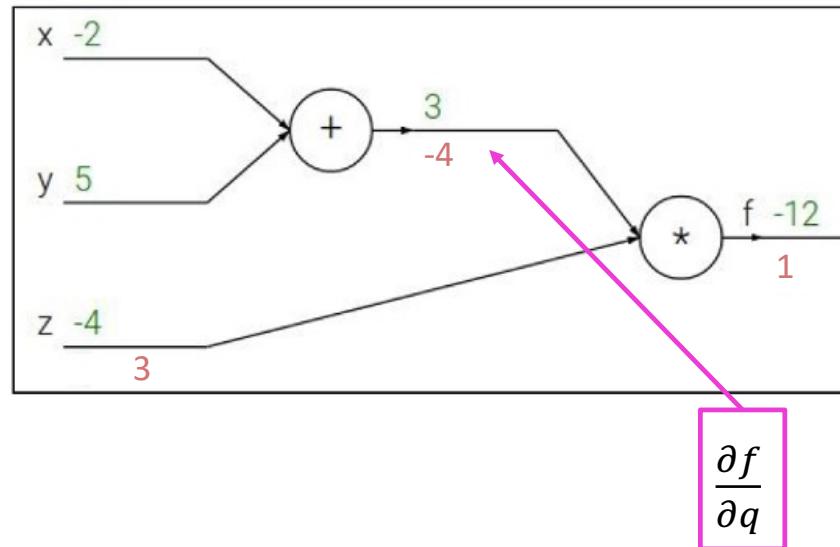
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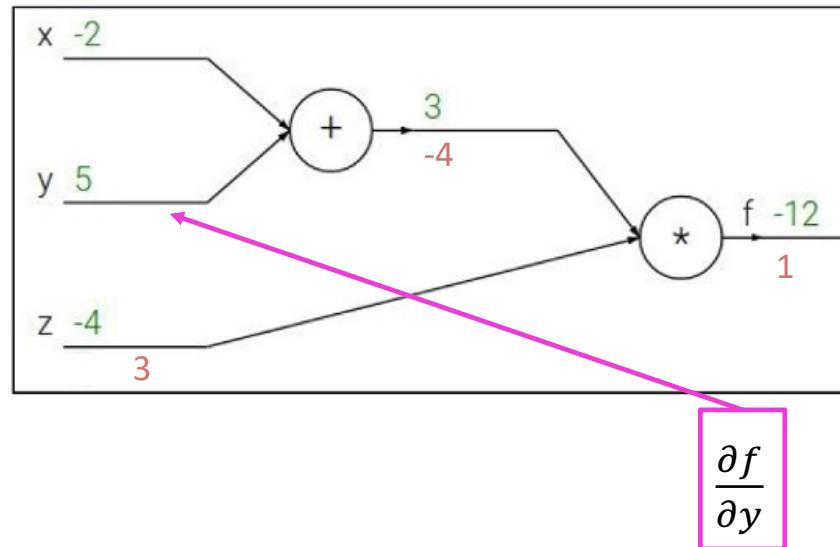
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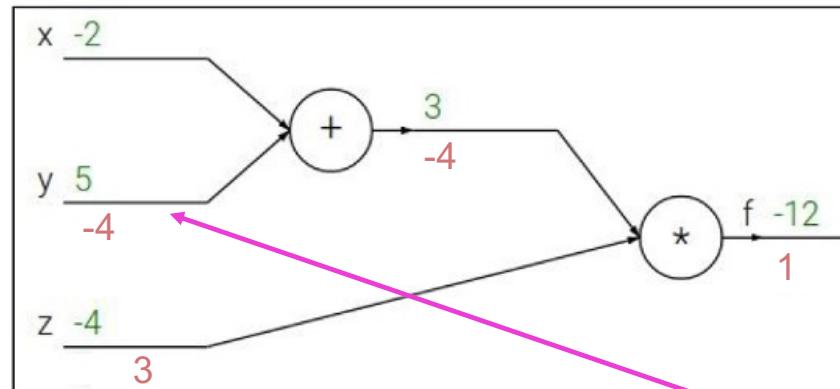
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Want: $\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z}$



$$\frac{\partial f}{\partial y}$$

Chain rule:

$$\frac{\partial f}{\partial y} = \frac{\partial f}{\partial q} \frac{\partial q}{\partial y}$$

Example 1

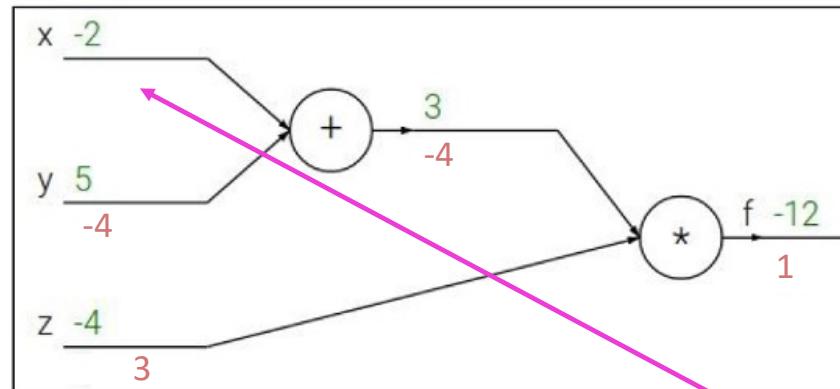
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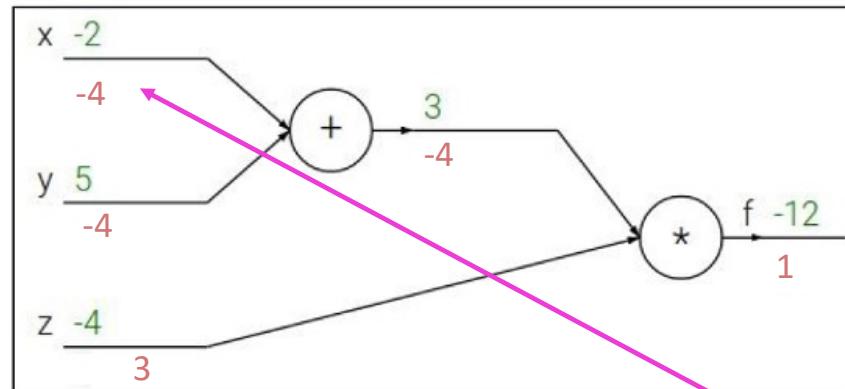
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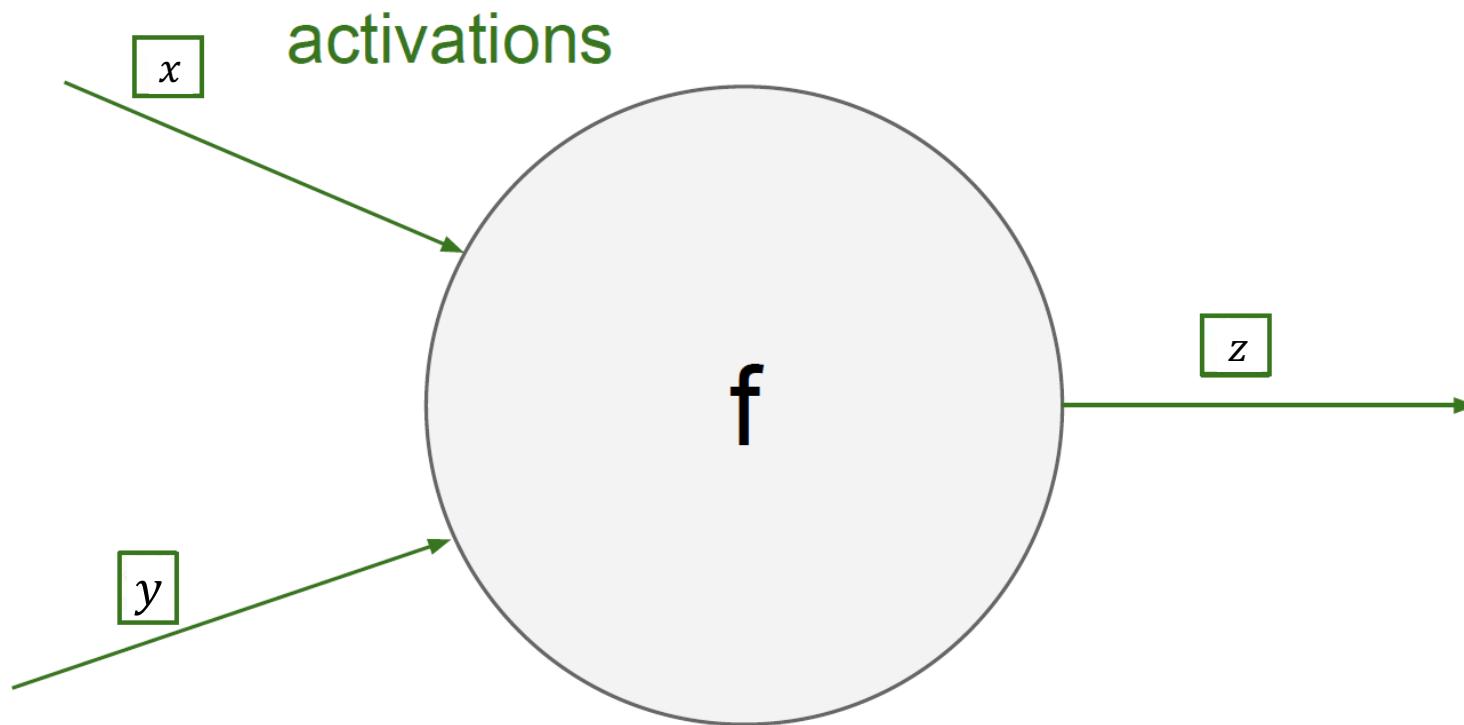
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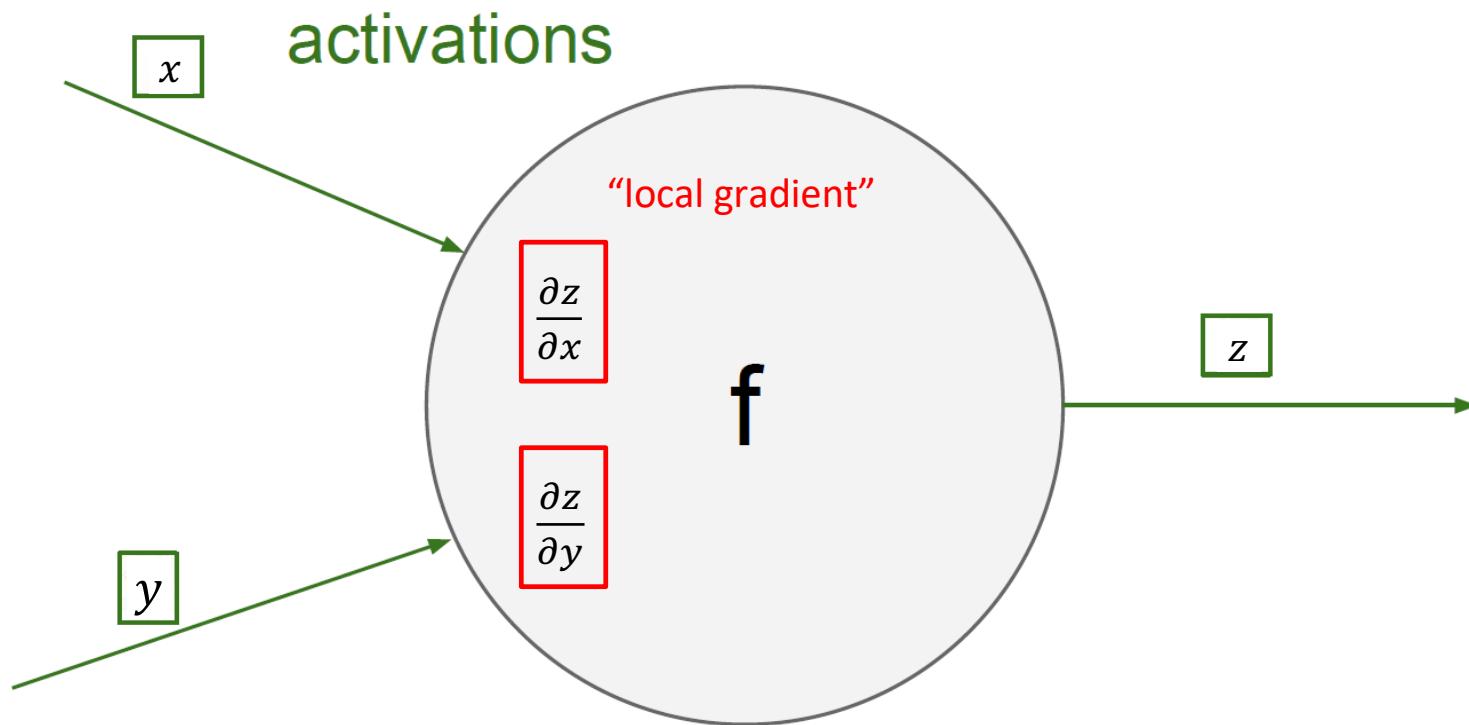
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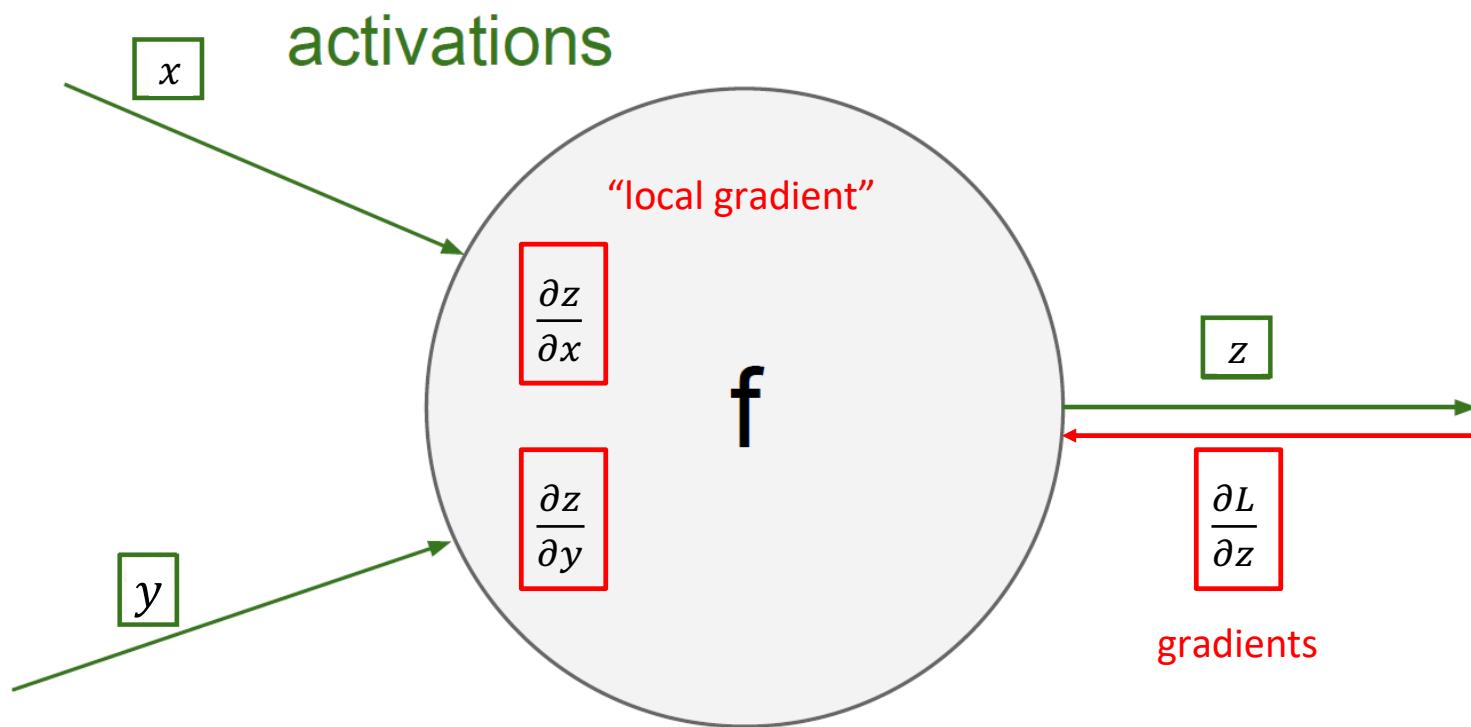
Chain rule



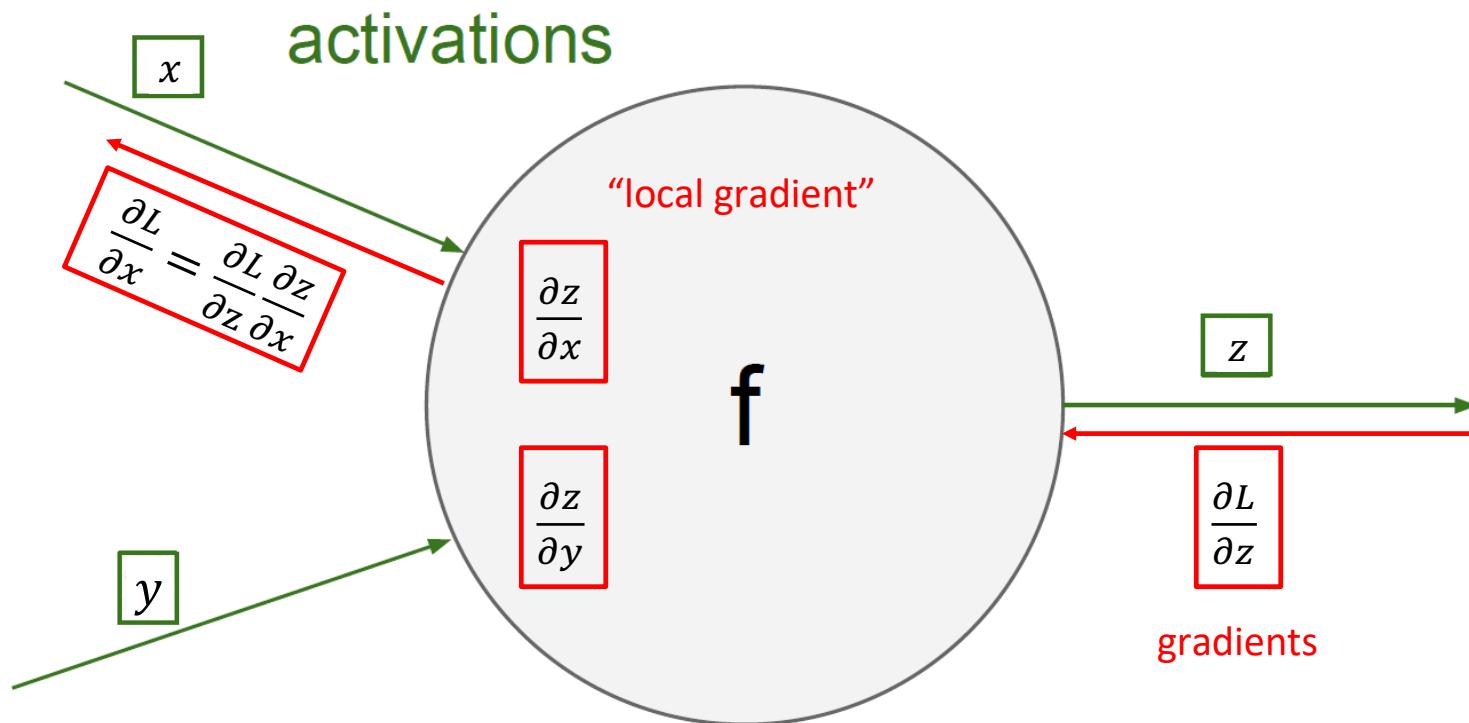
Chain rule



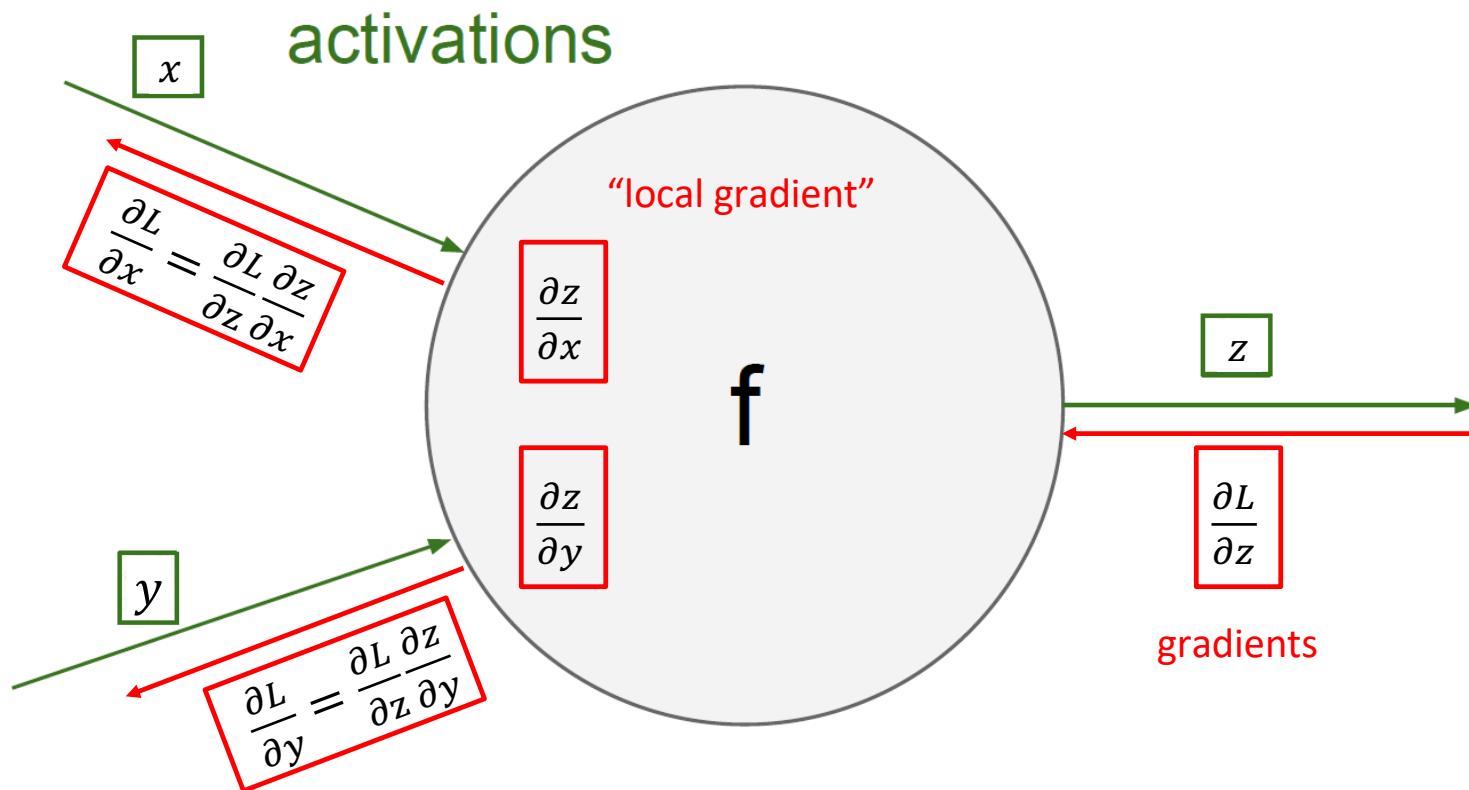
Chain rule



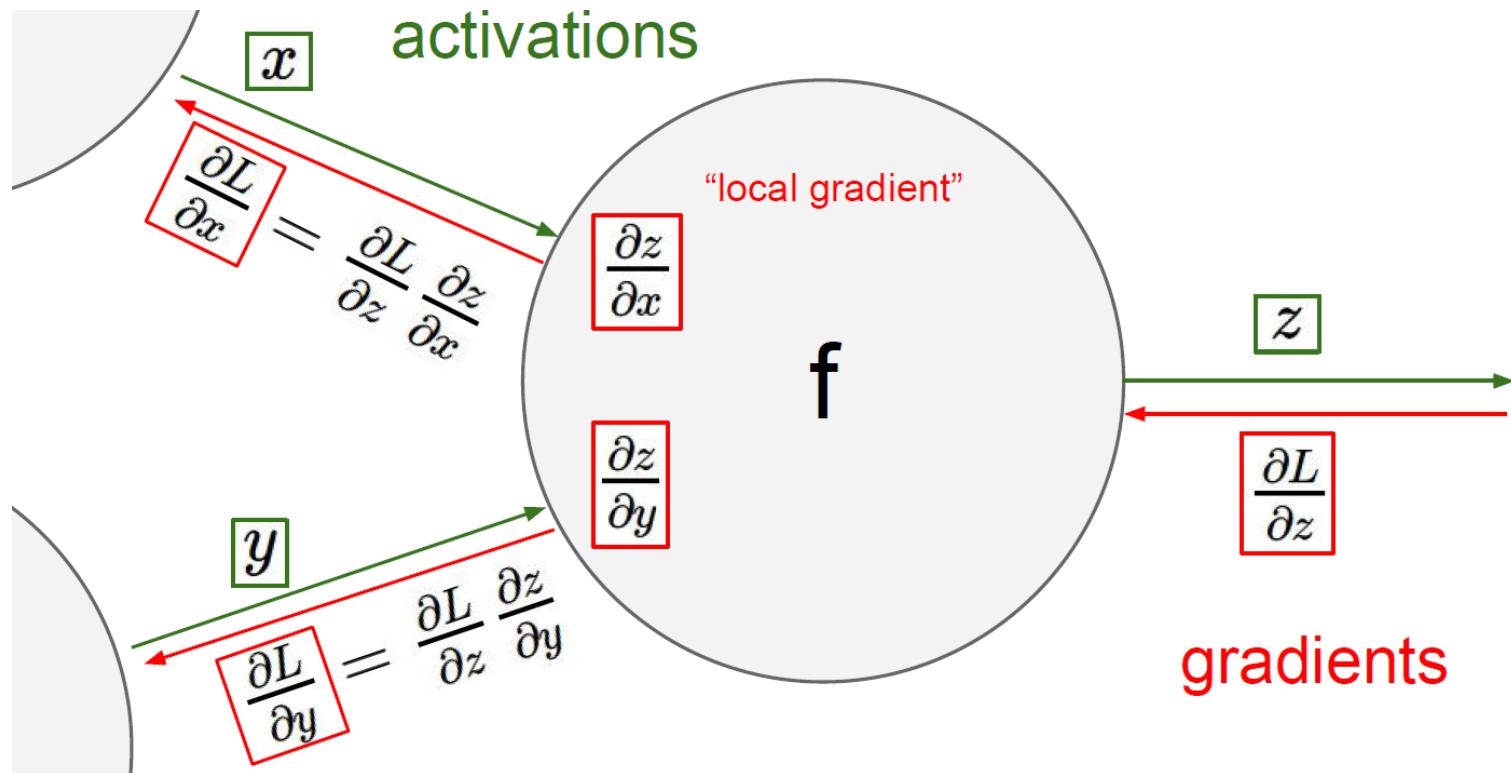
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Chain rule



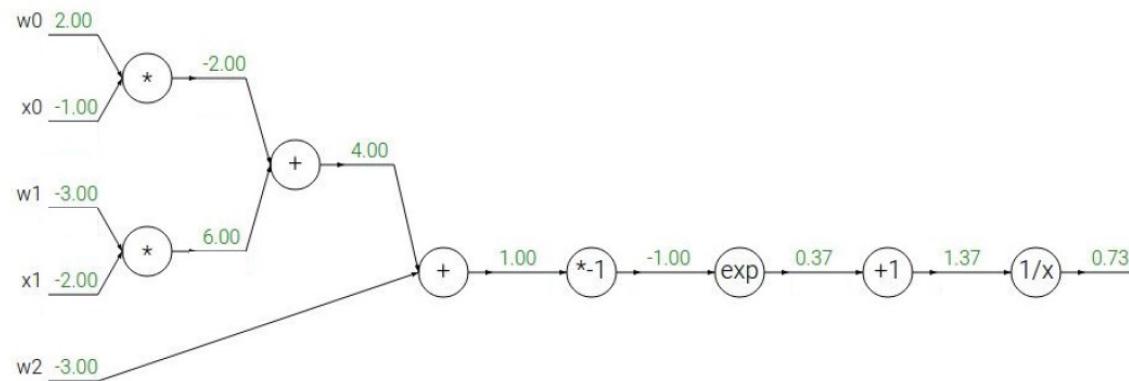
Chain rule



Chain rule

Another example:

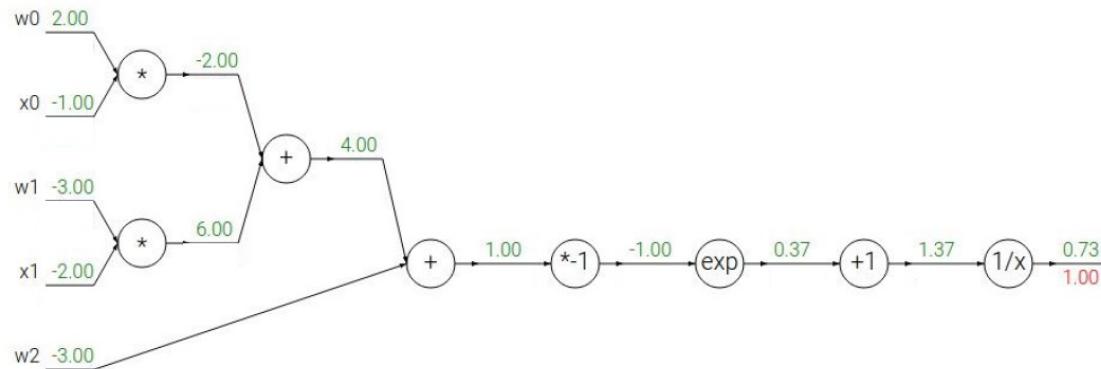
$$f(w, x) = \frac{1}{1 + e^{-(w_0x_0 + w_1x_1 + w_2)}}$$



Chain rule

Another example:

$$f(w, x) = \frac{1}{1 + e^{-(w_0x_0 + w_1x_1 + w_2)}}$$



$$f(x) = e^x$$

→

$$\frac{df}{dx} = e^x$$

$$f_a(x) = ax$$

→

$$\frac{df}{dx} = a$$

$$f(x) = \frac{1}{x}$$

→

$$\frac{df}{dx} = -1/x^2$$

$$f_c(x) = c + x$$

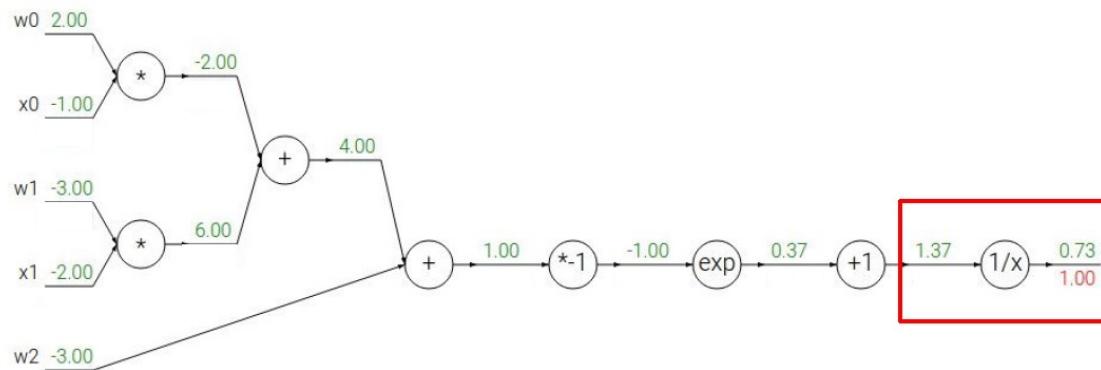
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$$\frac{df}{dx} = 1$$

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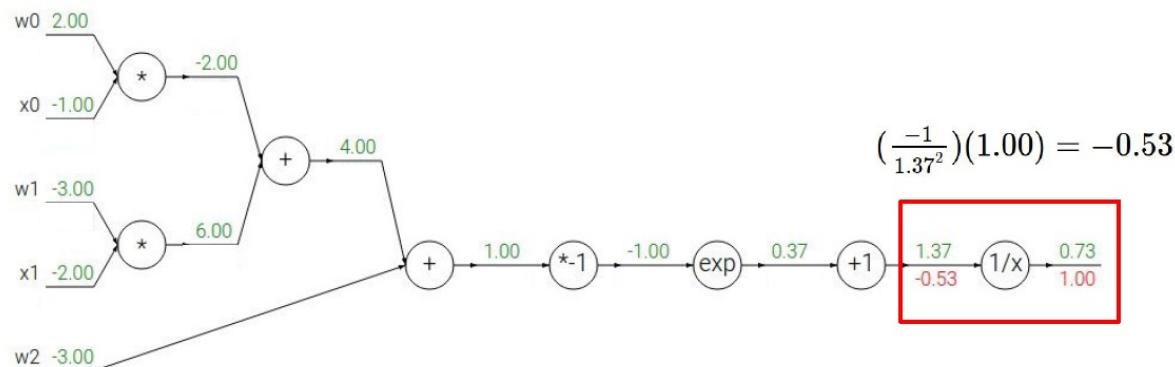
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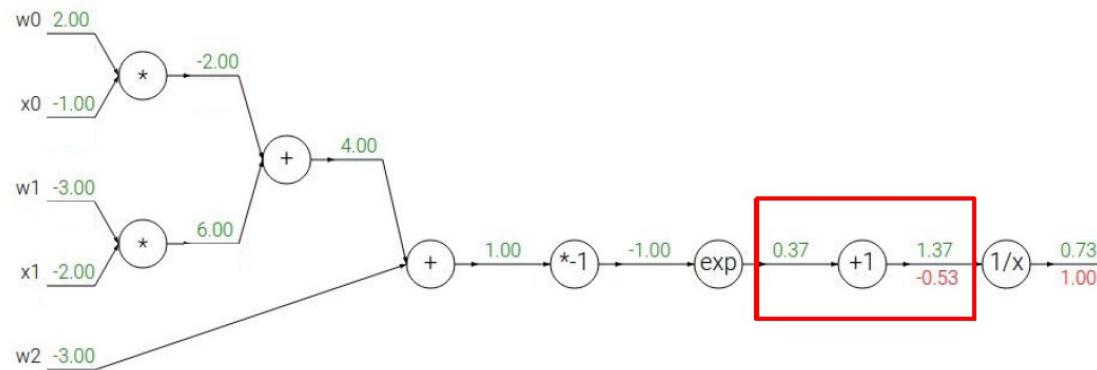
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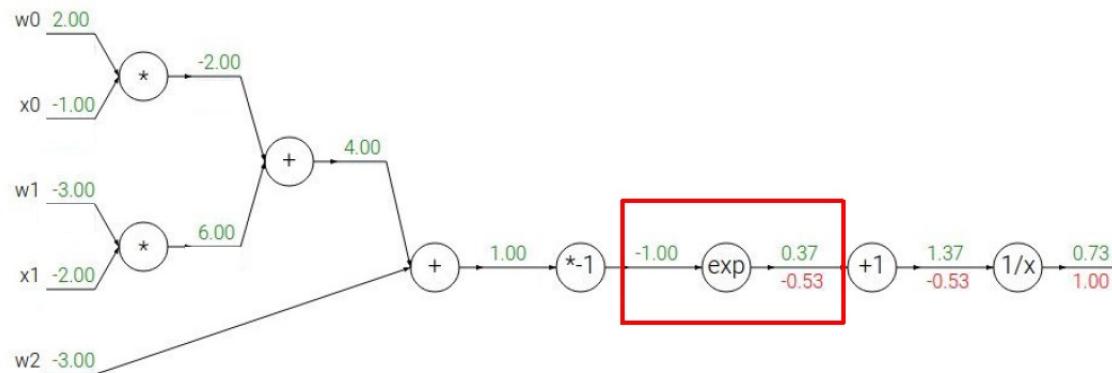
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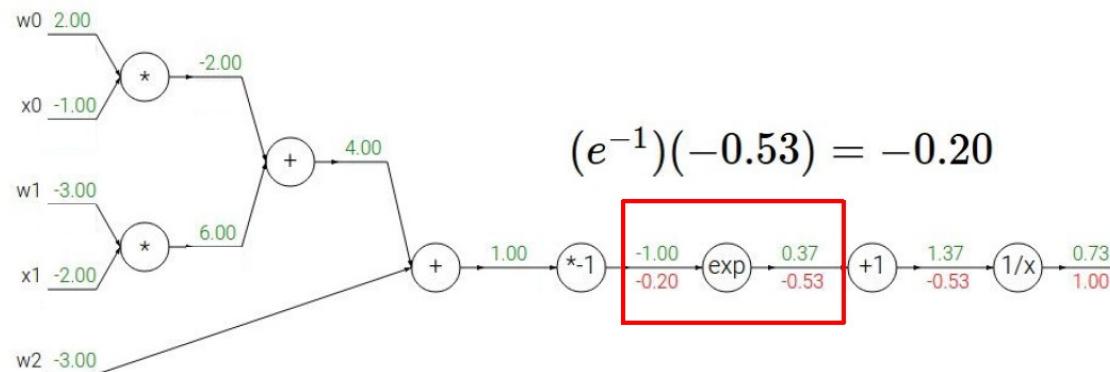
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Chain rule

Another example:

$$f(w, x) = \frac{1}{1 + e^{-(w_0x_0 + w_1x_1 + w_2)}}$$



$$(e^{-1})(-0.53) = -0.20$$

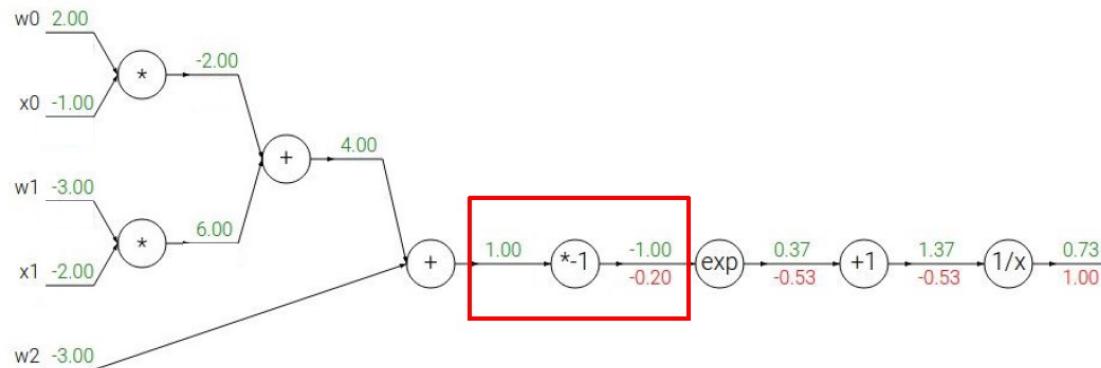
$$\boxed{f(x) = e^x} \quad \rightarrow \quad \frac{df}{dx} = e^x$$
$$f_a(x) = ax \quad \rightarrow \quad \frac{df}{dx} = a$$

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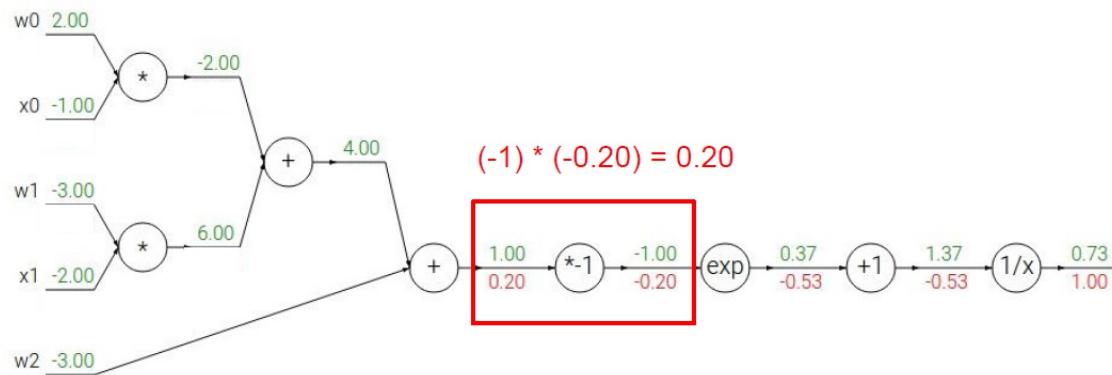
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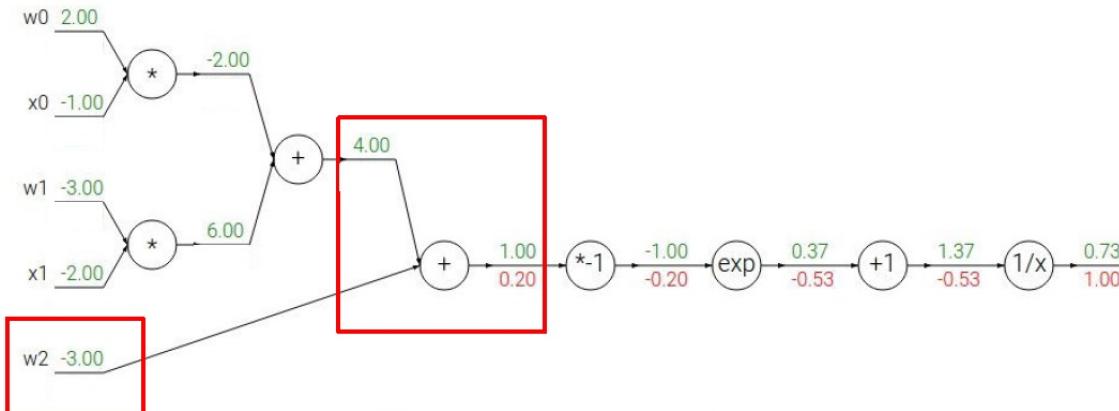


$f(x) = e^x$ \rightarrow $\frac{df}{dx} = e^x$	$f(x) = \frac{1}{x}$ \rightarrow $\frac{df}{dx} = -1/x^2$
$f_a(x) = ax$ \rightarrow $\frac{df}{dx} = a$	$f_c(x) = c + x$ \rightarrow $\frac{df}{dx} = 1$

Chain rule

Another example:

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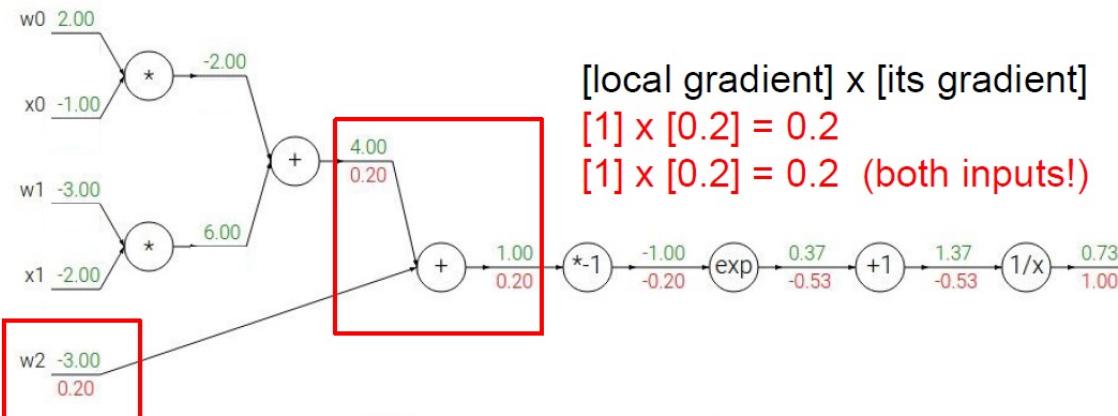
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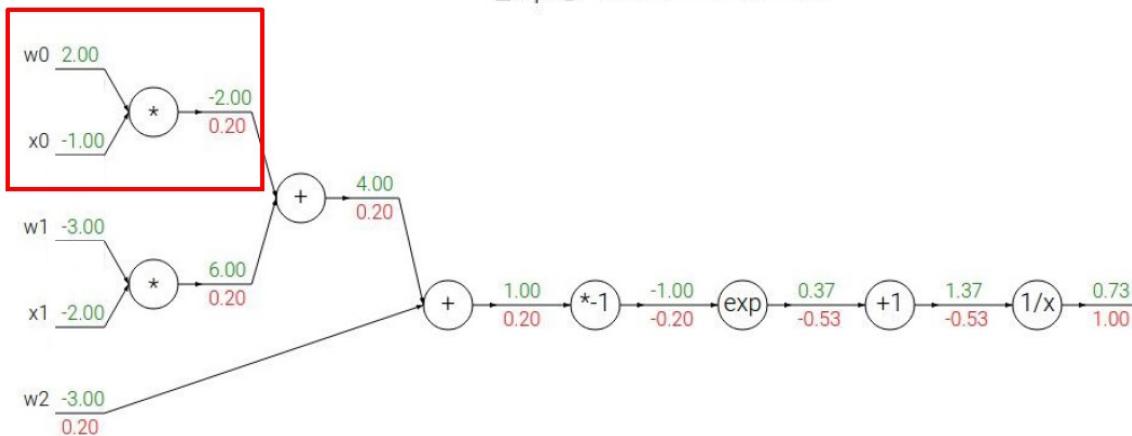
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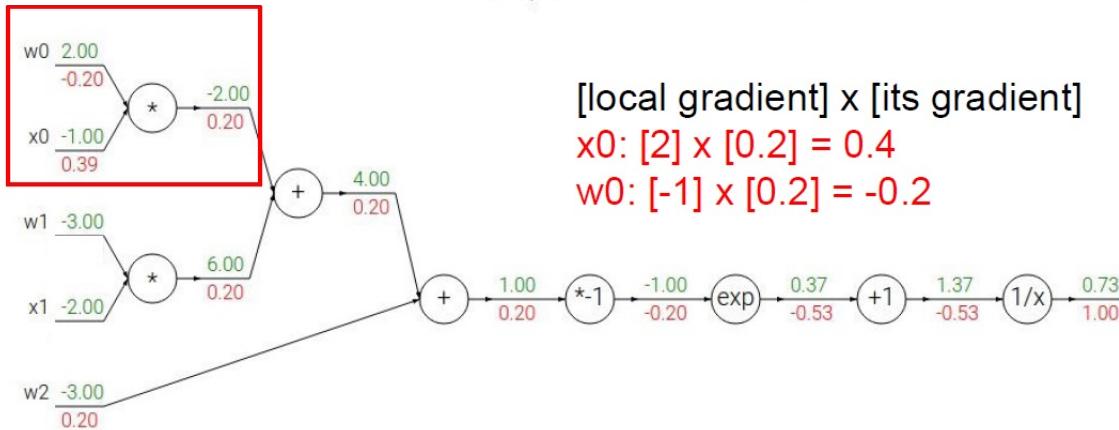
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[local gradient] x [its gradient]
 $x_0: [2] \times [0.2] = 0.4$
 $w_0: [-1] \times [0.2] = -0.2$

$$f(x) = e^x$$

→

$$\frac{df}{dx} = e^x$$

$$f_a(x) = ax$$

→

$$\frac{df}{dx} = a$$

$$f(x) = \frac{1}{x}$$

→

$$\frac{df}{dx} = -1/x^2$$

$$f_c(x) = c + x$$

→

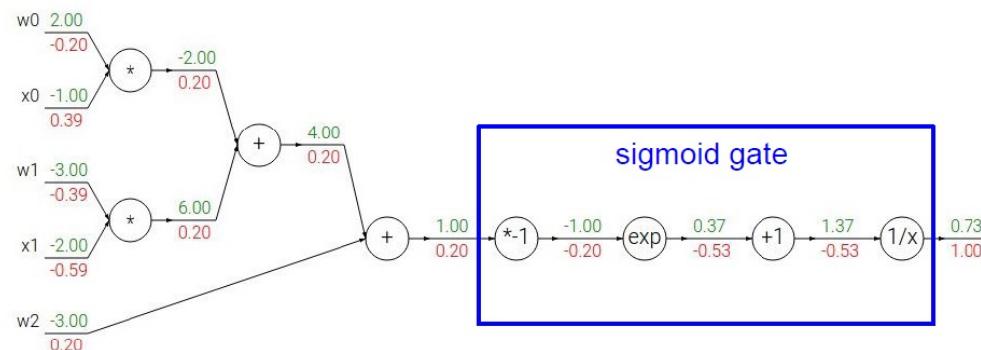
$$\frac{df}{dx} = 1$$

Sigmoid

$$f(w, x) = \frac{1}{1 + e^{-(w_0x_0 + w_1x_1 + w_2)}}$$

$$\sigma(x) = \frac{1}{1 + e^{-x}} \quad \text{sigmoid function}$$

$$\frac{d\sigma(x)}{dx} = \frac{e^{-x}}{(1 + e^{-x})^2} = \left(\frac{1 + e^{-x} - 1}{1 + e^{-x}} \right) \left(\frac{1}{1 + e^{-x}} \right) = (1 - \sigma(x))\sigma(x)$$

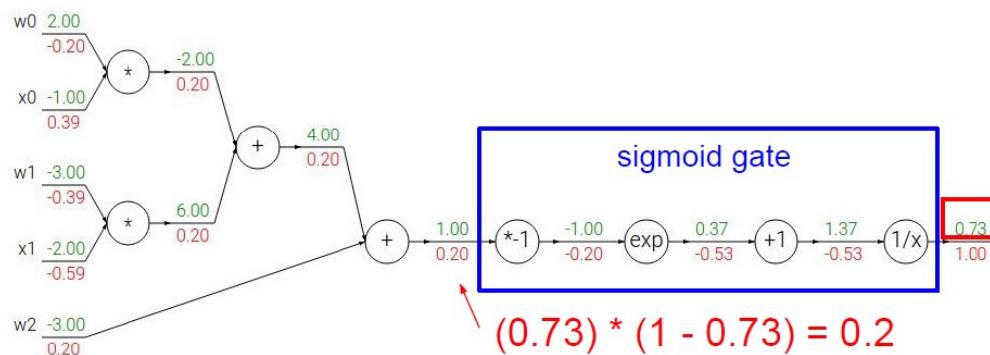


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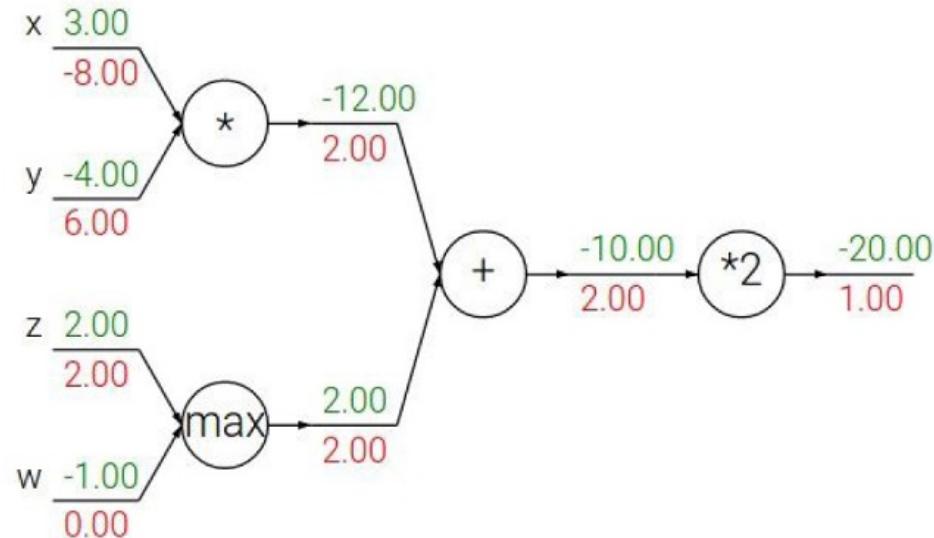
Pattern in backward flow

add gate: gradient distributor

max gate: gradient router

mul gate: gradient... “switcher”?

Patterns in backward flow



Exercise 1

Pooling units take n values x_i , $i \in [1, n]$ and compute a scalar output whose value is invariant to permutations of the inputs.

1. The L p -pooling module takes positive inputs and computes

$$y = (\sum_i x_i^p)^{\frac{1}{p}}, \text{ assuming we know that } y' = \frac{\partial L}{\partial y}, \text{ what is } x'_i = \frac{\partial L}{\partial x_i}?$$

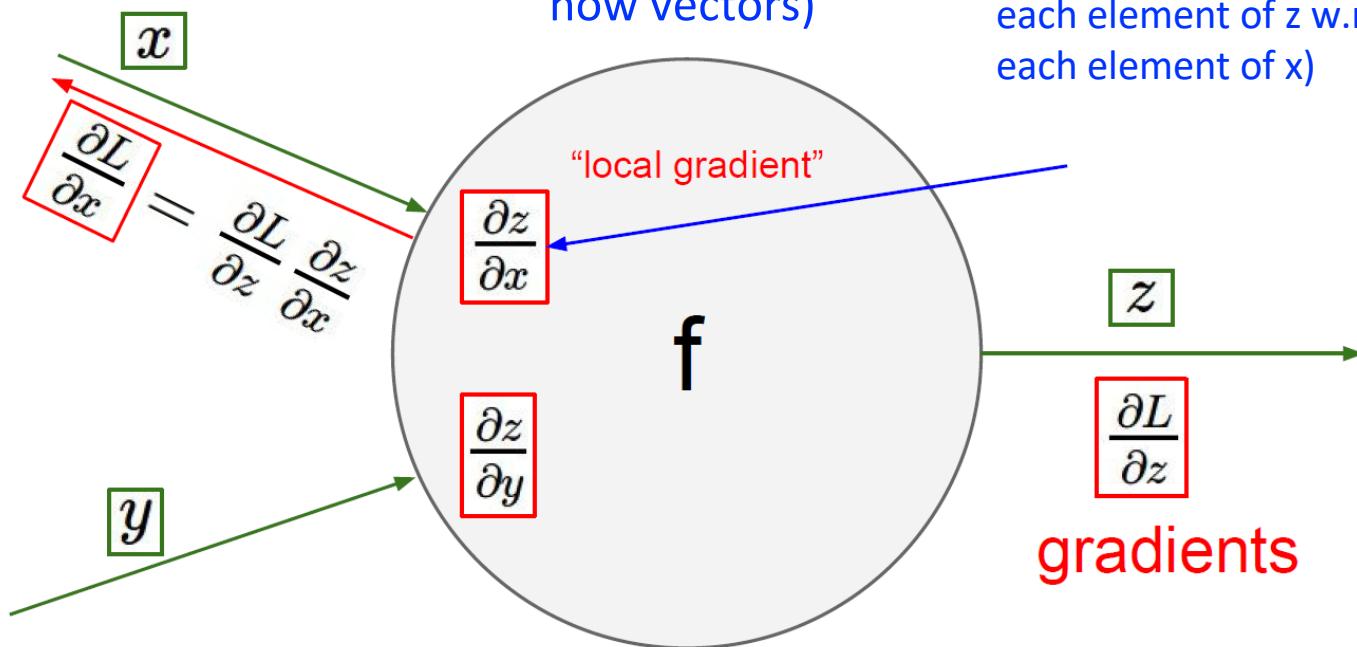
2. The log-average module computes $y = \frac{1}{\beta} \ln(\frac{1}{n} \sum_i \exp(\beta x_i))$, assuming we know that $y' = \frac{\partial L}{\partial y}$, what is $x'_i = \frac{\partial L}{\partial x_i}$?

Gradients for vector

Gradients for vectorized code

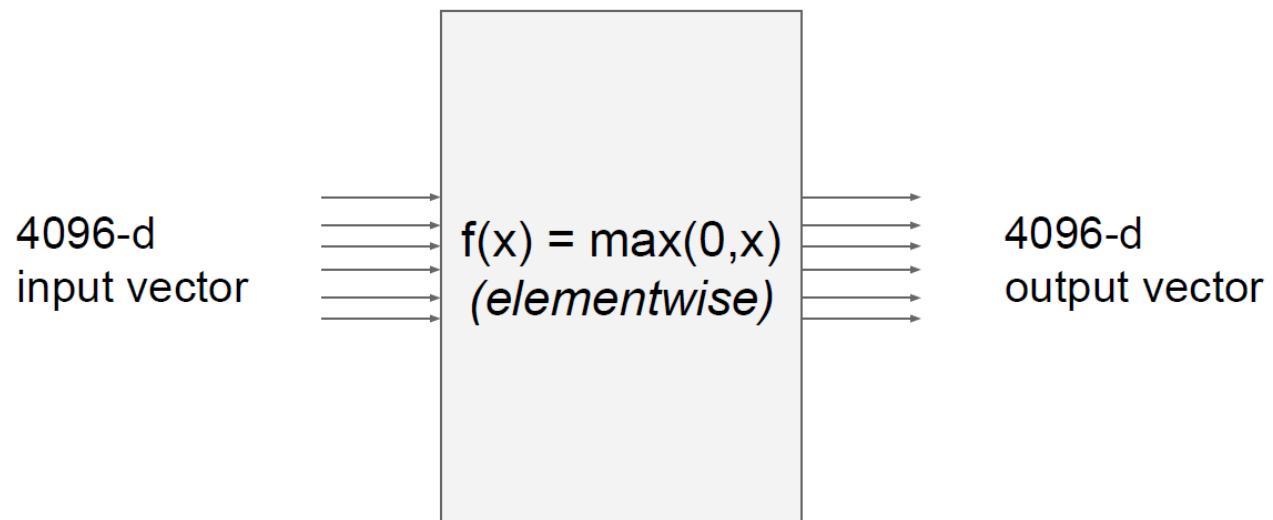
(x, y, z are now vectors)

This is now the **Jacobian matrix** (derivative of each element of z w.r.t. each element of x)



Gradients for vector

Vectorized operation



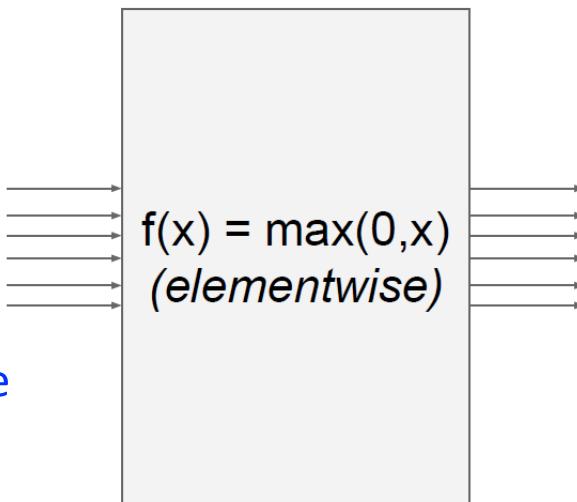
Gradients for vector

Vectorized operation

$$\frac{\partial L}{\partial x} = \boxed{\frac{\partial f}{\partial x}} \frac{\partial L}{\partial f}$$

Jacobian matrix

4096-d
input vector



4096-d
output vector

Q: what is the size
of the Jacobian
matrix

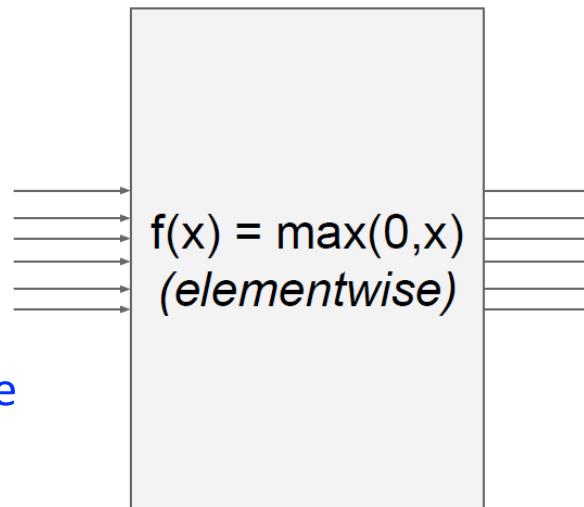
Gradients for vector

Vectorized operation

$$\frac{\partial L}{\partial x} = \boxed{\frac{\partial f}{\partial x}} \frac{\partial L}{\partial f}$$

Jacobian matrix :

4096-d
input vector



4096-d
output vector

Q: what is the size
of the Jacobian
matrix
[4096 x 4096!]

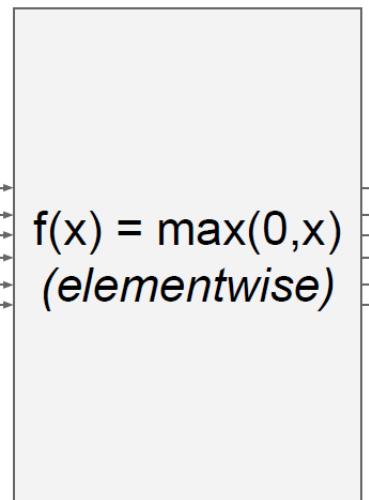
Q2: what does it look
like?

Gradients for vector

Vectorized operation

in practice we process an entire minibatch (e.g. 100) of examples at one time:

100 4096-d
input vectors



100 4096-d
output vectors

i.e. Jacobian would technically be a [409,600 x 409,600] matrix :\
\\

Gradients for vector

A vectorized example: $f(x, W) = \|W \cdot x\|^2 = \sum_{i=1}^n (W \cdot x)_i^2$

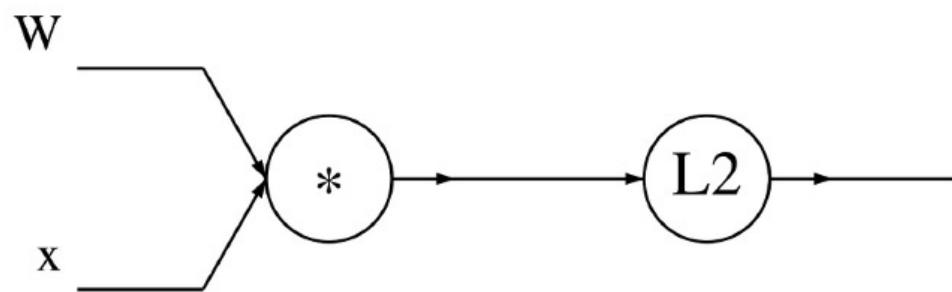
Gradients for vector

A vectorized example: $f(x, W) = \|W \cdot x\|^2 = \sum_{i=1}^n (W \cdot x)_i^2$

$$\begin{matrix} \downarrow & \downarrow \\ \in \mathbb{R}^n & \in \mathbb{R}^{n \times n} \end{matrix}$$

Gradients for vector

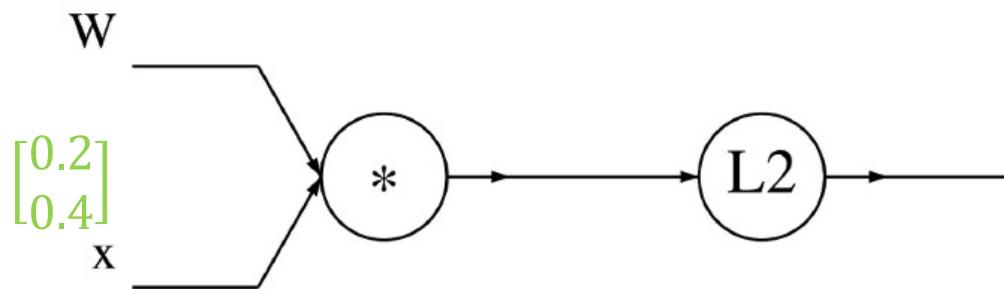
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Gradients for vector

A vectorized example: $f(x, W) = \|W \cdot x\|^2 = \sum_{i=1}^n (W \cdot x)_i^2$

$$\begin{bmatrix} 0.1 & 0.5 \\ -0.3 & 0.8 \end{bmatrix}$$



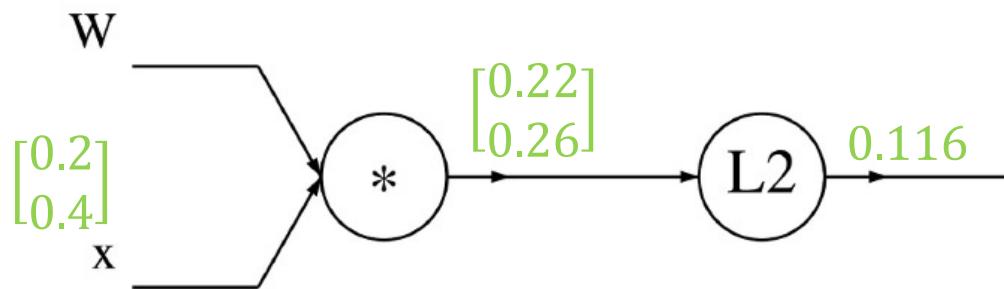
$$q = W \cdot x = \begin{pmatrix} W_{1,1}x_1 + \cdots + W_{1,n}x_n \\ \vdots \\ W_{n,1}x_1 + \cdots + W_{n,n}x_n \end{pmatrix}$$

$$f(q) = \|q\|^2 = q_1^2 + \cdots + q_n^2$$

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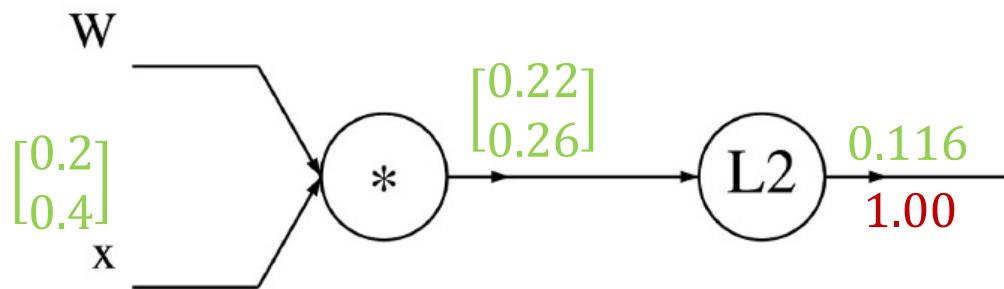
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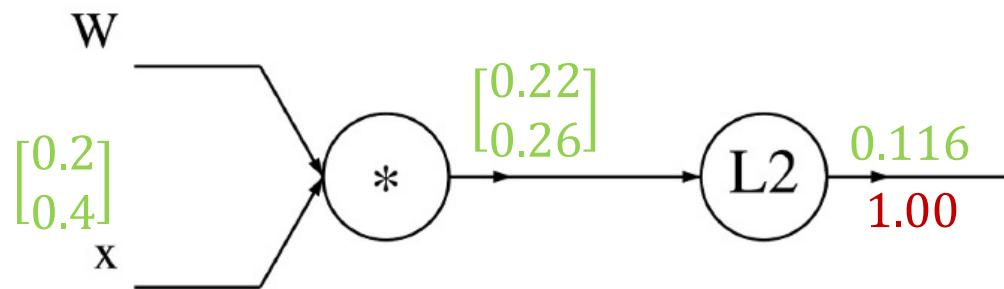
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$$\frac{\partial f}{\partial q_i} = 2q_i$$

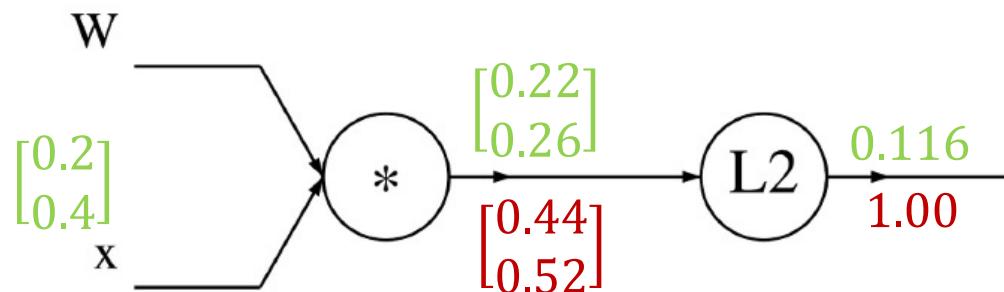
$$\boxed{\nabla_q f = 2q}$$

$$f(q) = \|q\|^2 = q_1^2 + \cdots + q_n^2$$

Gradients for vector

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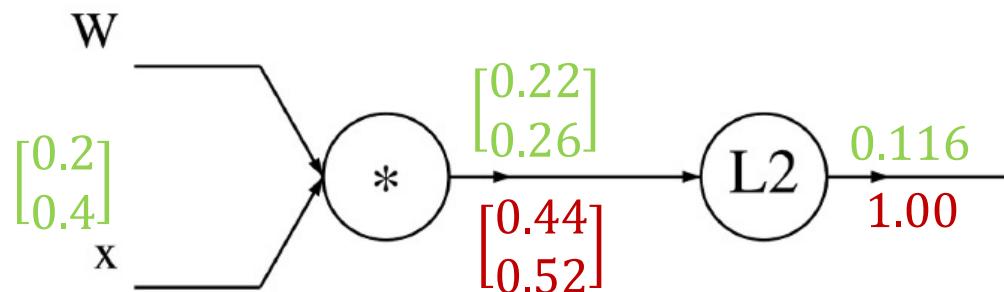
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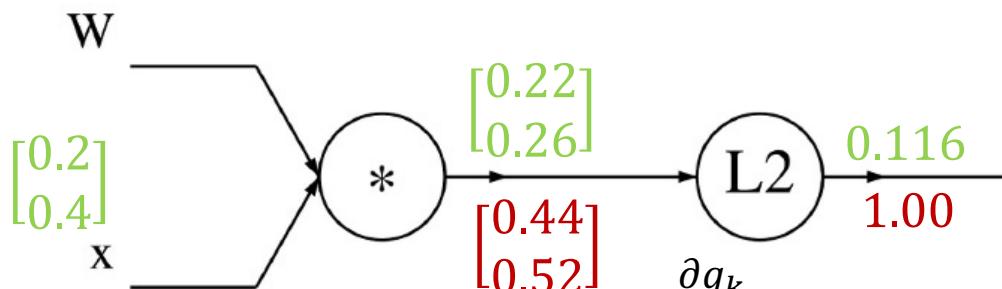
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Gradients for vector

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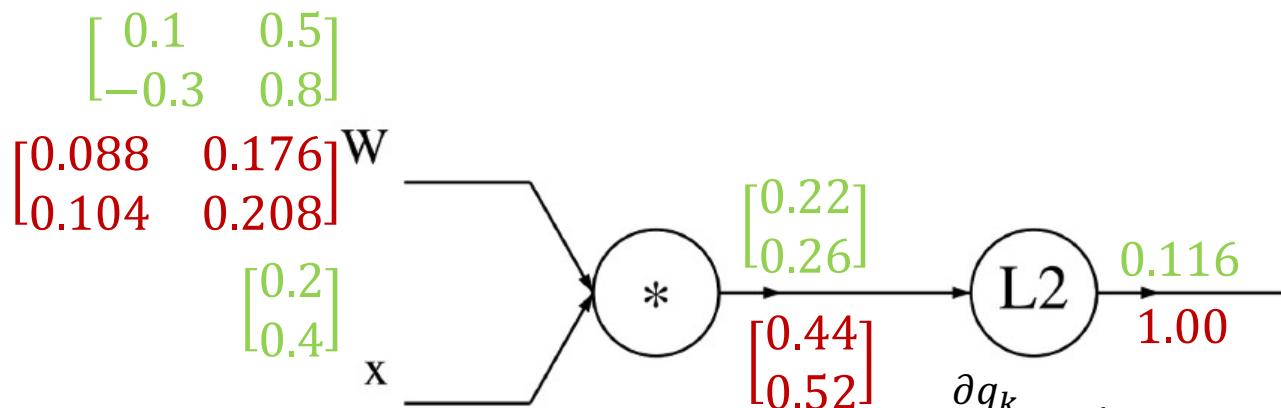
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$$f(q) = \|q\|^2 = q_1^2 + \cdots + q_n^2$$

$$\begin{aligned} \frac{\partial q_k}{\partial W_{i,j}} &= \mathbf{1}_{k=i} x_j \\ \frac{\partial f}{\partial W_{i,j}} &= \sum_k \frac{\partial f}{\partial q_k} \frac{\partial q_k}{\partial W_{i,j}} \\ &= \sum_k (2q_k)(\mathbf{1}_{k=i} x_j) \\ &= 2q_i x_j \end{aligned}$$

Gradients for vector

A vectorized example: $f(x, W) = \|W \cdot x\|^2 = \sum_{i=1}^n (W \cdot x)_i^2$



$$q = W \cdot x = \begin{pmatrix} W_{1,1}x_1 + \cdots + W_{1,n}x_n \\ \vdots \\ W_{n,1}x_1 + \cdots + W_{n,n}x_n \end{pmatrix}$$

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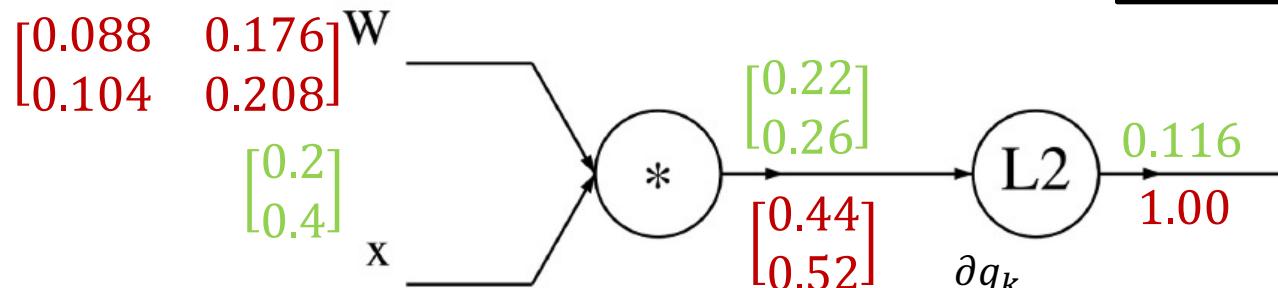
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A vectorized example: $f(x, W) = \|W \cdot x\|^2 = \sum_{i=1}^n (W \cdot x)_i^2$

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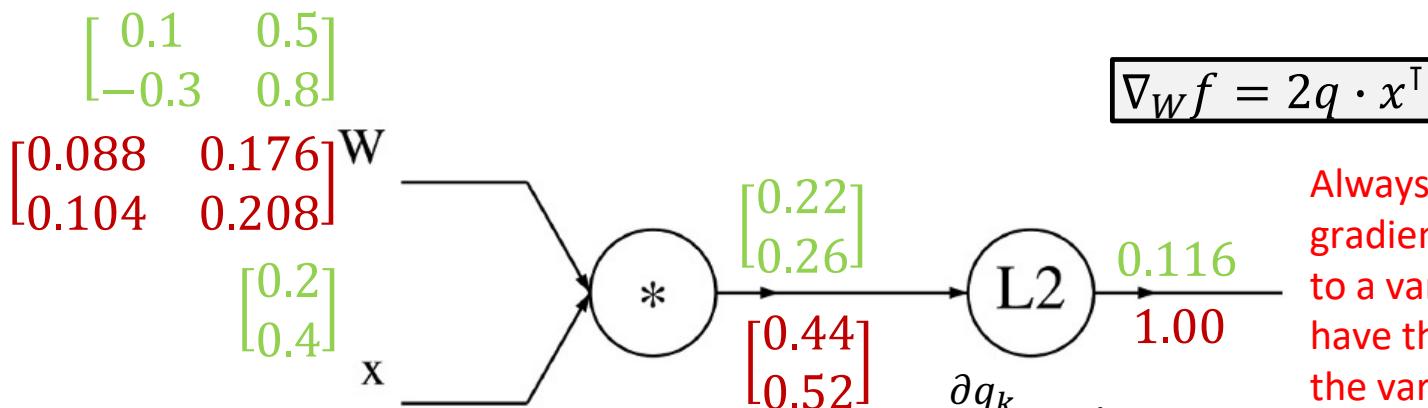
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Gradients for vector

A vectorized example: $f(x, W) = \|W \cdot x\|^2 = \sum_{i=1}^n (W \cdot x)_i^2$



Always check: The gradient with respect to a variable should have the same shape as the variable

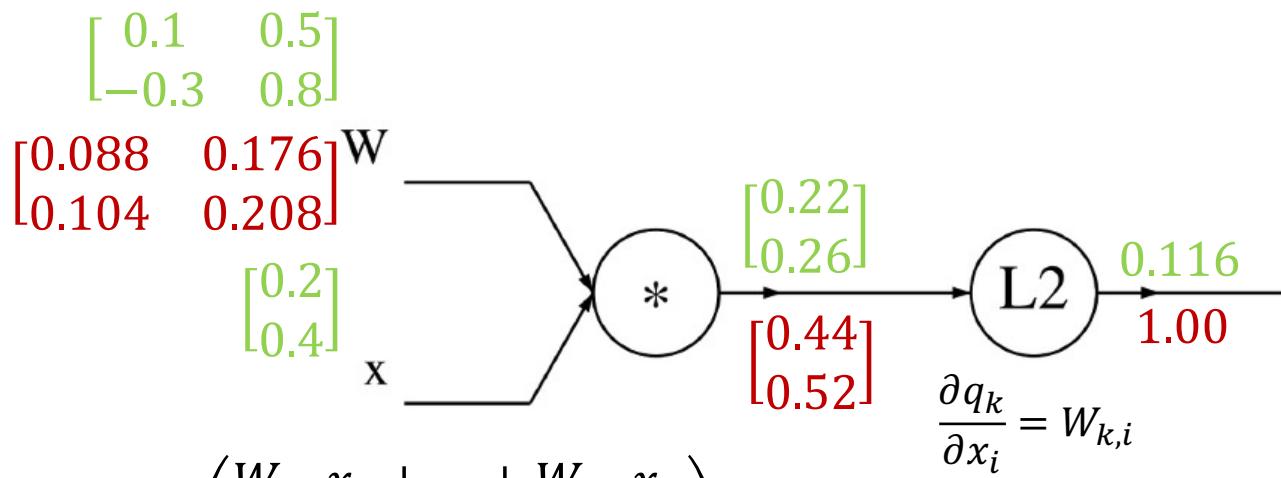
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Gradients for vector

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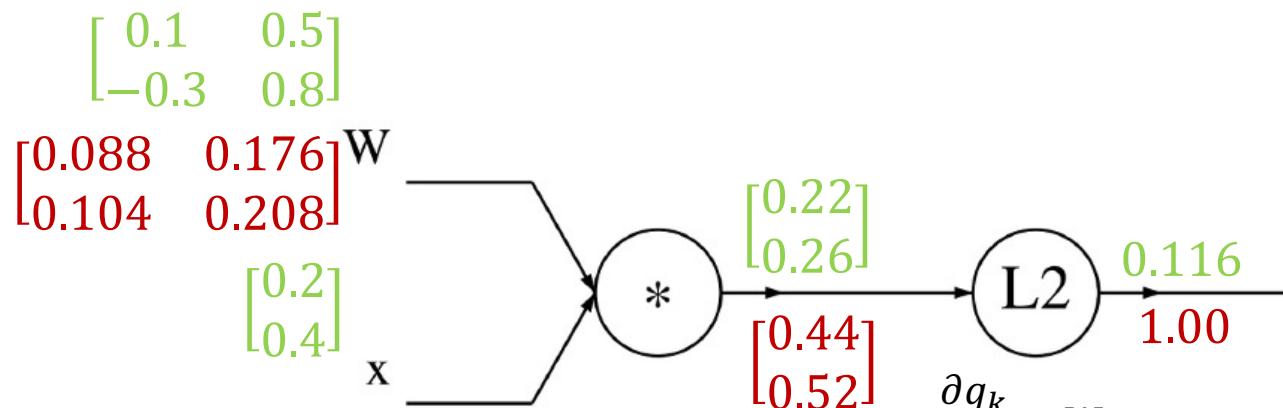


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$$\frac{\partial q_k}{\partial x_i} = W_{k,i}$$

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Gradients for vector

A vectorized example: $f(x, W) = \|W \cdot x\|^2 = \sum_{i=1}^n (W \cdot x)_i^2$

$$\begin{bmatrix} 0.1 & 0.5 \\ -0.3 & 0.8 \end{bmatrix}$$

$$\boxed{\nabla_x f = 2W^\top \cdot q}$$

$$\begin{bmatrix} 0.088 & 0.176 \\ 0.104 & 0.208 \end{bmatrix}^W$$

$$\begin{bmatrix} 0.2 \\ 0.4 \end{bmatrix}^x$$

$$q = W \cdot x = \begin{pmatrix} W_{1,1}x_1 + \cdots + W_{1,n}x_n \\ \vdots \\ W_{n,1}x_1 + \cdots + W_{n,n}x_n \end{pmatrix}$$

$$f(q) = \|q\|^2 = q_1^2 + \cdots + q_n^2$$

$$\begin{bmatrix} 0.22 \\ 0.26 \\ 0.44 \\ 0.52 \end{bmatrix}$$

$$\begin{array}{c} L2 \\ 0.116 \\ 1.00 \end{array}$$

$$\frac{\partial q_k}{\partial x_i} = W_{k,i}$$

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