



Xi'an Jiaotong-Liverpool University

西交利物浦大學

INT305 Machine Learning

Lecture 5

Neural Network and Back Propagation

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Neural network

Neural Network: without the brain stuff

(**Before**) Linear score function: $f = Wx$

Neural network

Neural Network: without the brain stuff

(Before) Linear score function: $f = Wx$

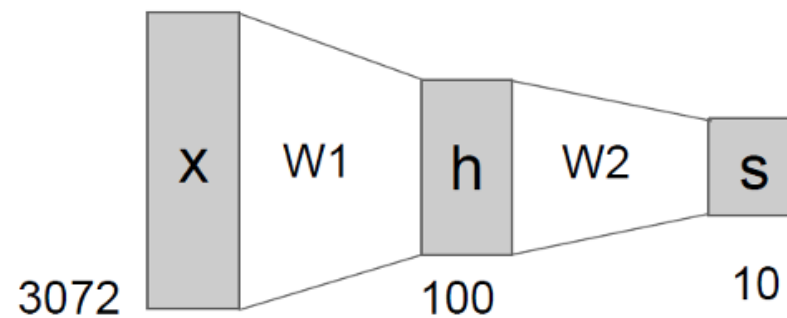
(Now) 2-layer Neural Network: $f = W_2 \max(0, W_1 x)$

Neural network

Neural Network: without the brain stuff

(**Before**) Linear score function: $f = Wx$

(**Now**) 2-layer Neural Network: $f = W_2 \max(0, W_1 x)$



Neural network

Neural Network: without the brain stuff

(Before) Linear score function: $f = Wx$

(Now) 2-layer Neural Network: $f = W_2 \max(0, W_1 x)$

or 3-layer Neural Network:

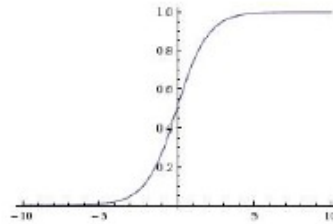
$$f = W_3 \max(0, W_2 \max(0, W_1 x))$$

Activation functions

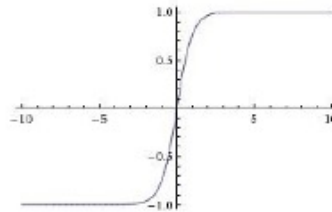
Activation Functions

Sigmoid

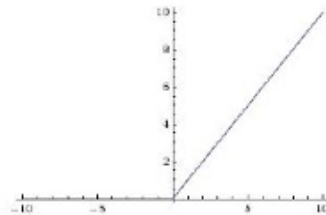
$$\sigma(x) = 1/(1 + e^{-x})$$



tanh $\tanh(x)$

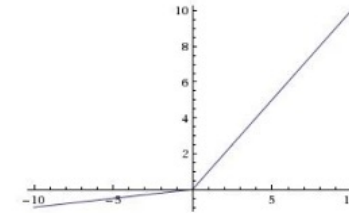


ReLU $\max(0, x)$



Leaky ReLU

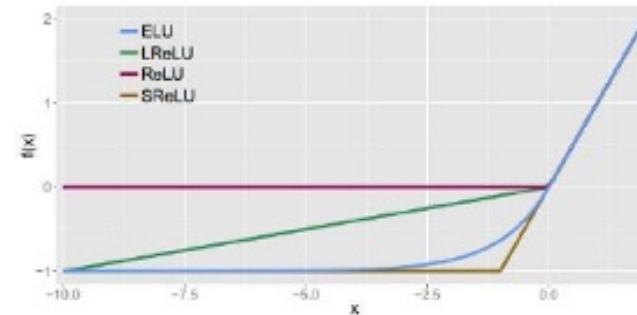
$$\max(0.1x, x)$$



Maxout $\max(w_1^T x + b_1, w_2^T x + b_2)$

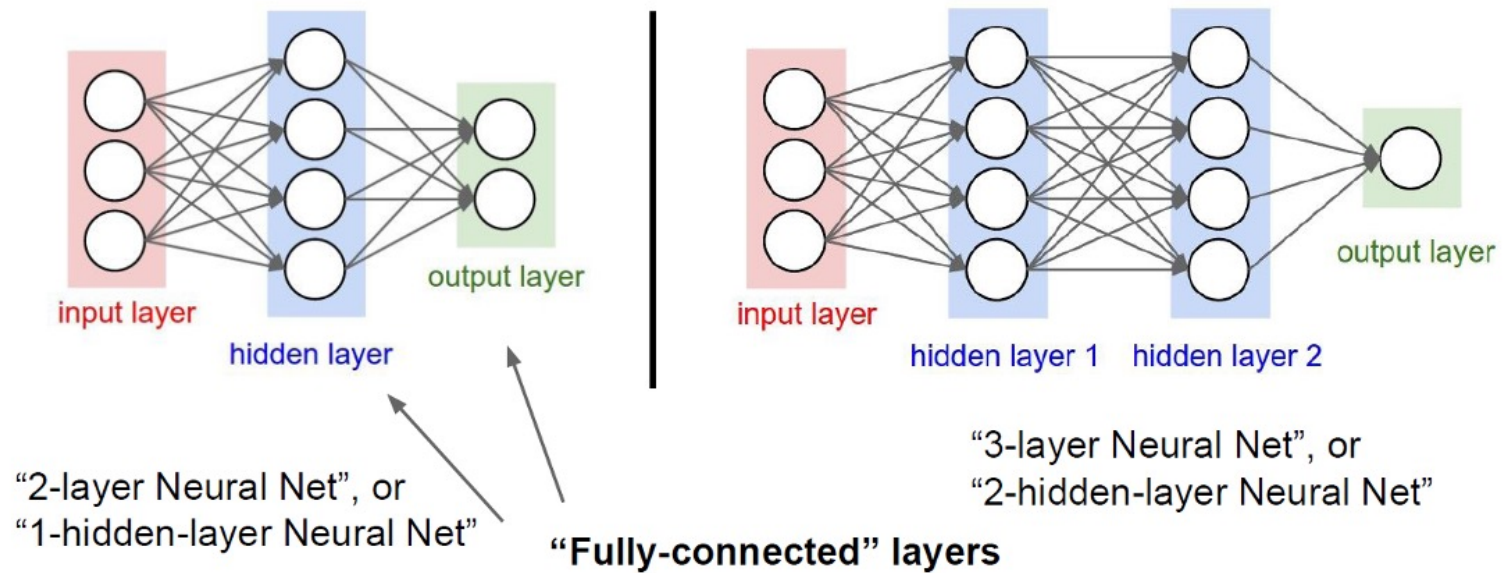
ELU

$$f(x) = \begin{cases} x & \text{if } x > 0 \\ \alpha(\exp(x) - 1) & \text{if } x \leq 0 \end{cases}$$



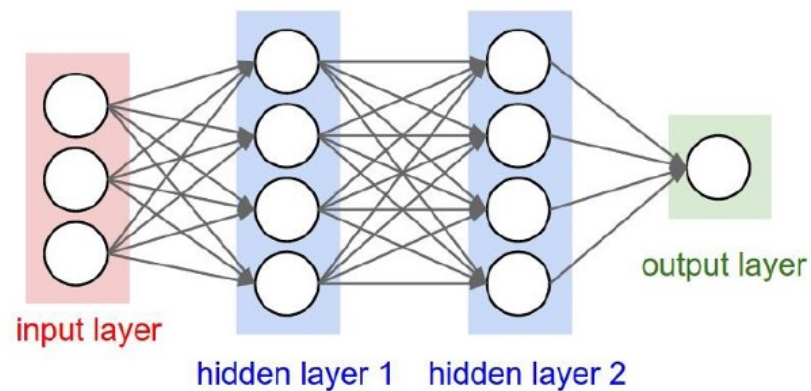
Neural network

Neural Networks: Architectures



Neural network

Example Feed-forward computation of a Neural Network



```
# forward-pass of a 3-layer neural network:  
f = lambda x: 1.0/(1.0 + np.exp(-x)) # activation function (use sigmoid)  
x = np.random.randn(3, 1) # random input vector of three numbers (3x1)  
h1 = f(np.dot(W1, x) + b1) # calculate first hidden layer activations (4x1)  
h2 = f(np.dot(W2, h1) + b2) # calculate second hidden layer activations (4x1)  
out = np.dot(W3, h2) + b3 # output neuron (1x1)
```


Gradient Descent

Where we are...

$$s = f(x; W) = Wx$$

scores function

$$L_i = \sum_{j \neq y_i} \max(0, s_j - s_{y_i} + 1)$$

SVM loss

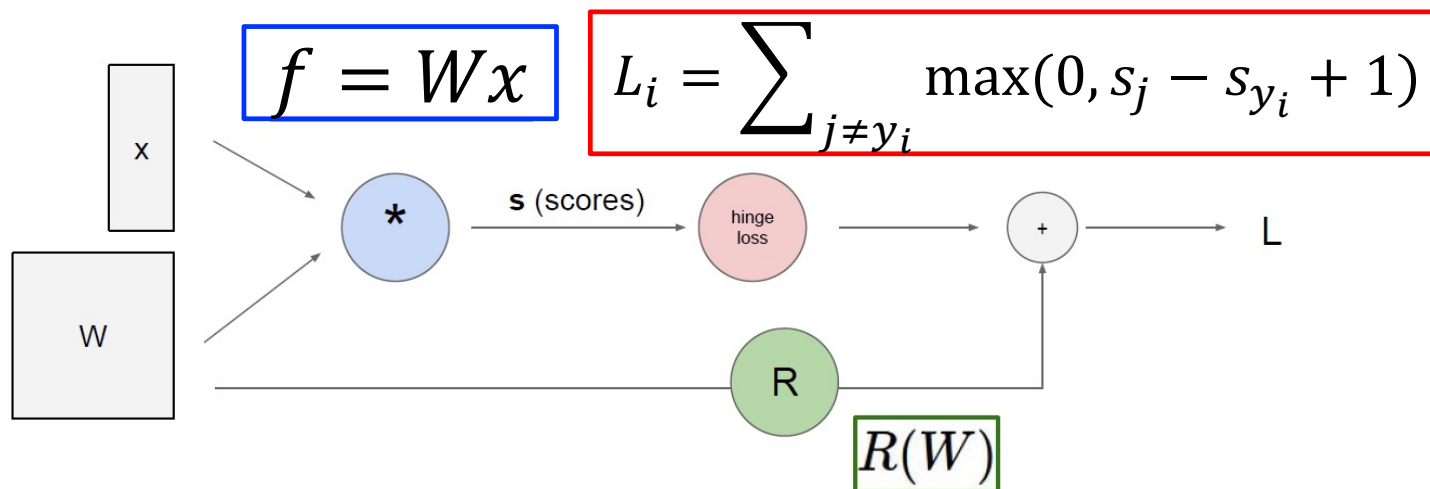
$$L = \frac{1}{N} \sum_{i=1}^N L_i + \sum_k W_k^2$$

data loss + regularization

want $\nabla_W L$

Computational Graph

Computational Graph



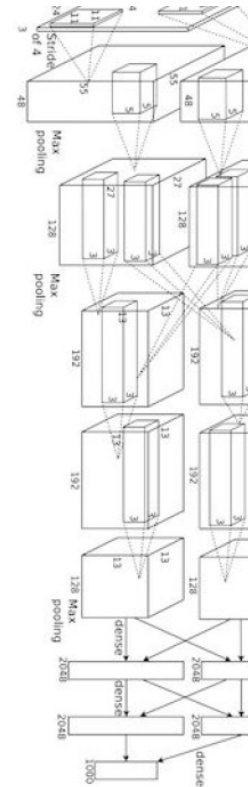
Computational Graph

Convolutional Network
(AlexNet)

input image

weights

loss

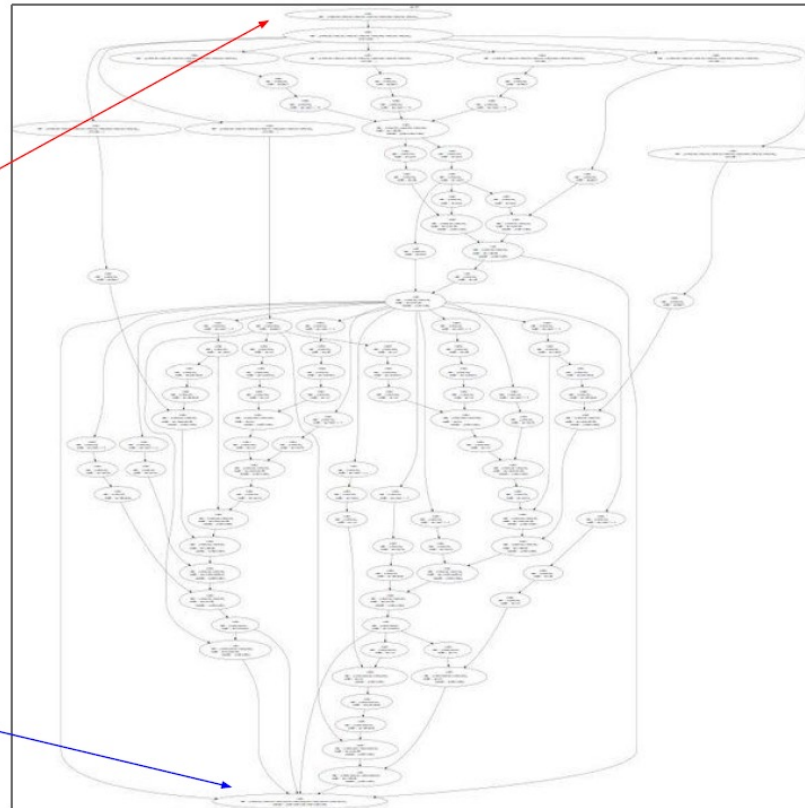


Computational Graph

Neural Turing Machine

input tape

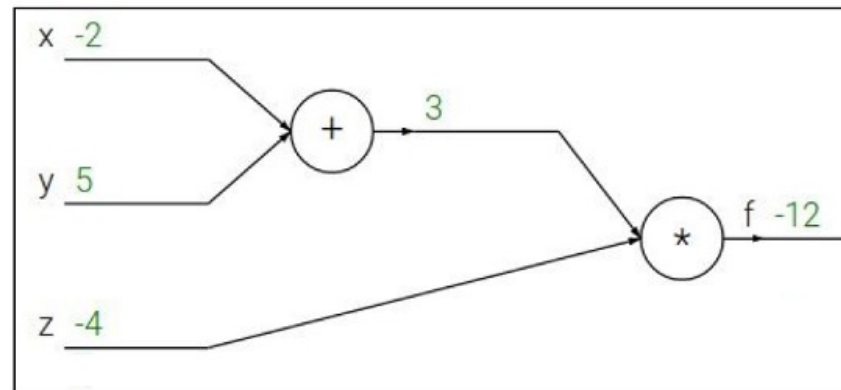
loss



Example 1

$$f(x, y, z) = (x + y)z$$

e.g. $x = -2, y = 5, z = -4$



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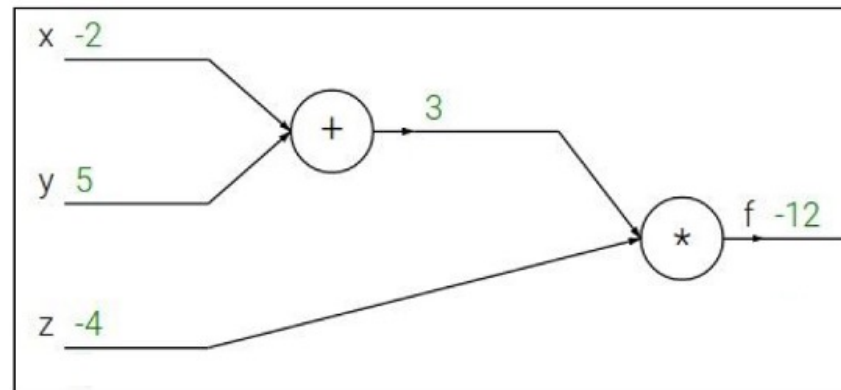
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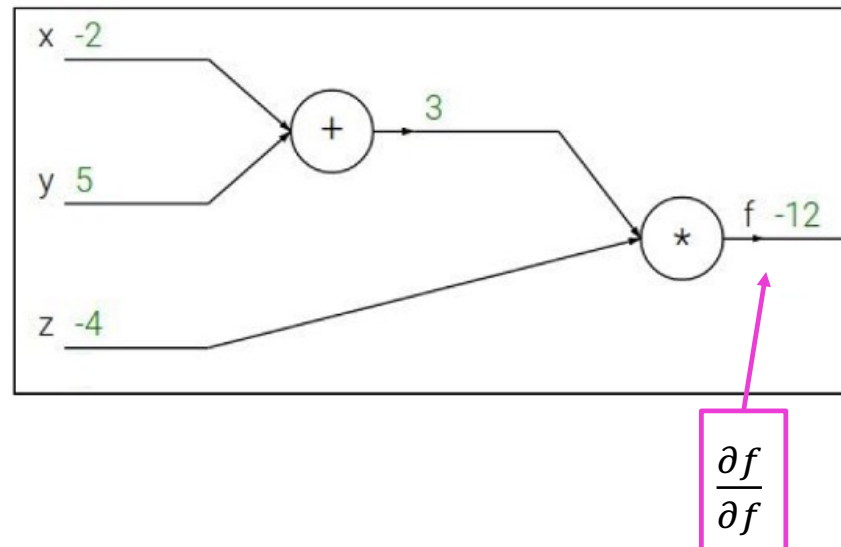
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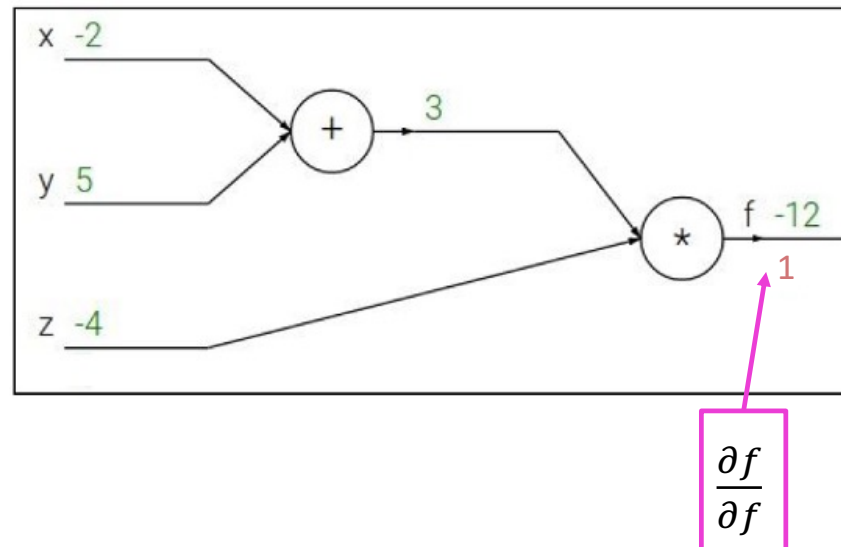
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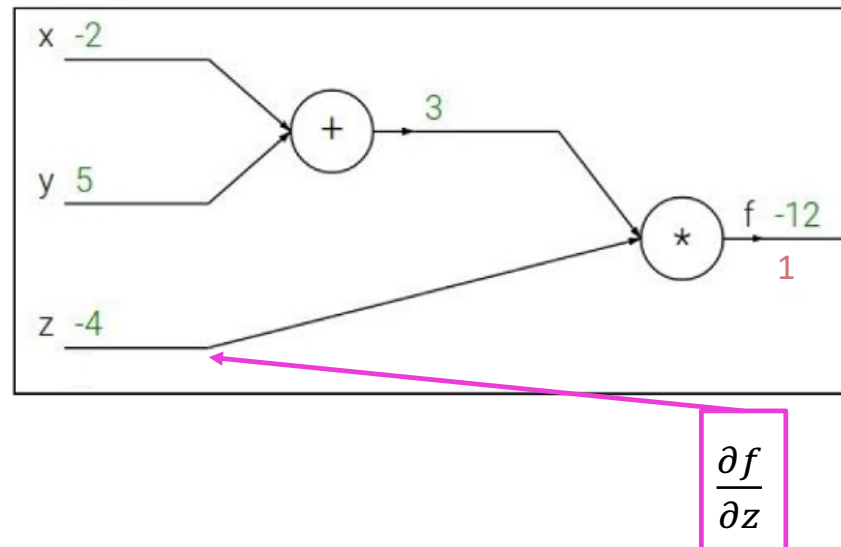
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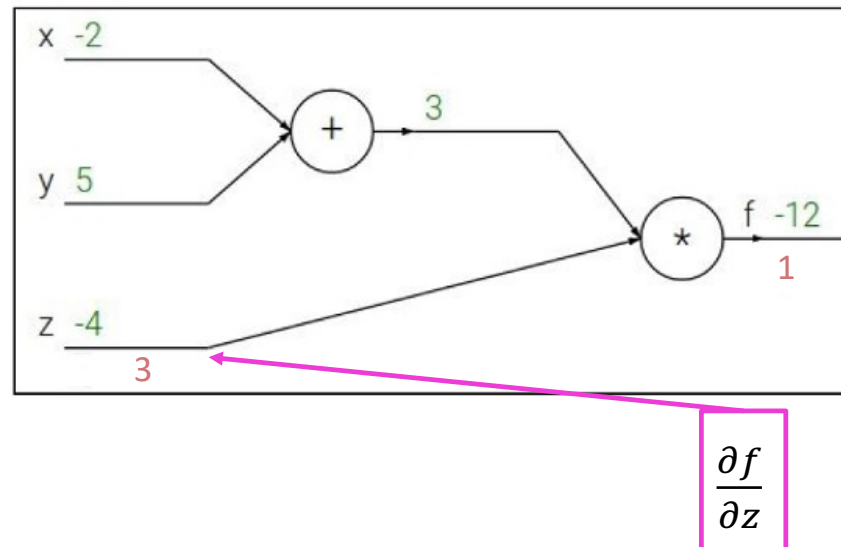
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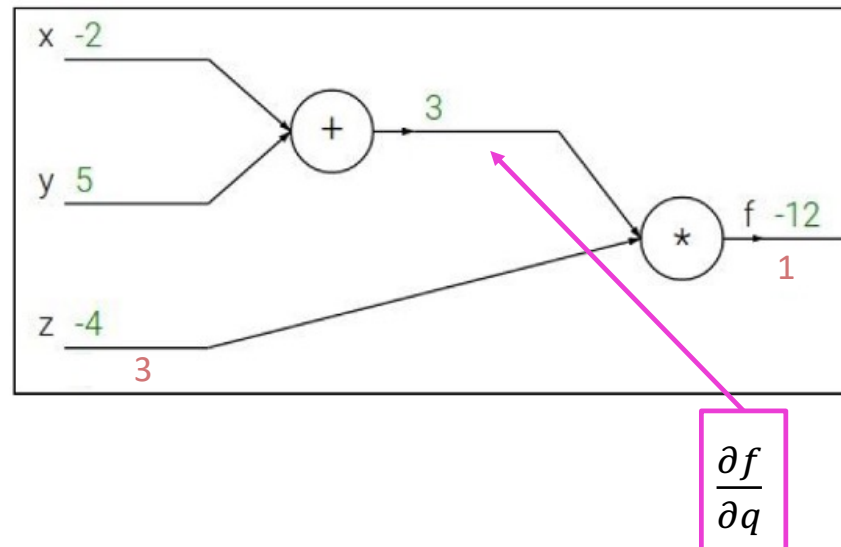
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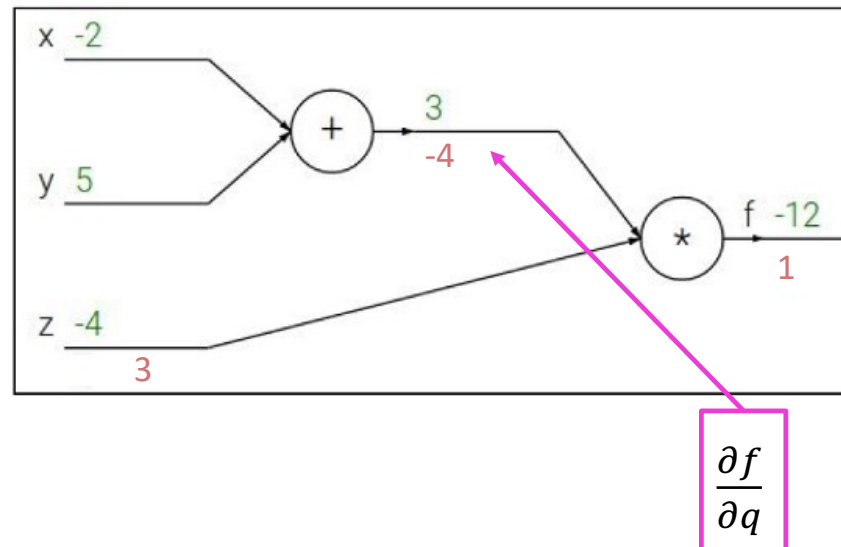
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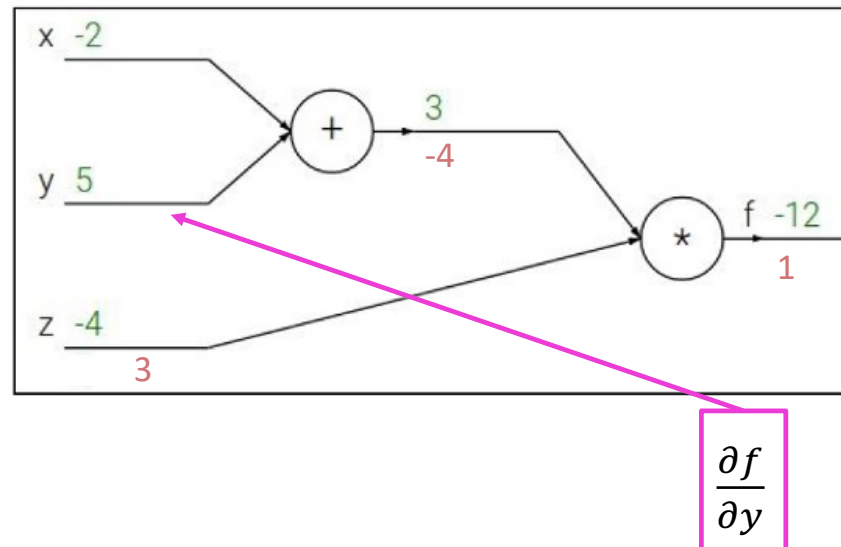
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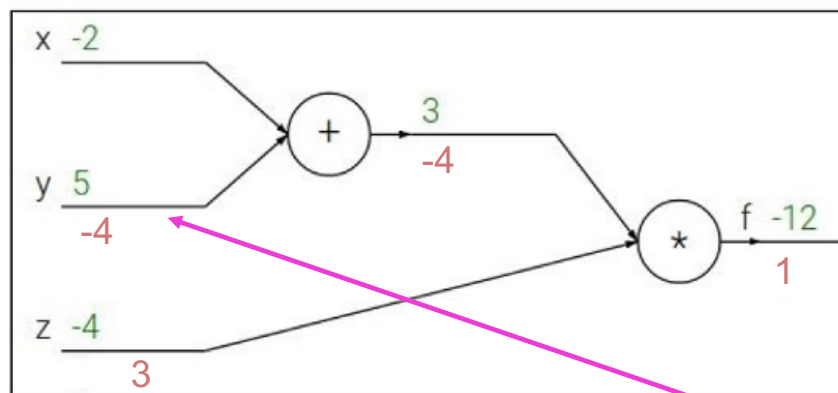
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$$\frac{\partial f}{\partial y}$$

Chain rule:

$$\frac{\partial f}{\partial y} = \frac{\partial f}{\partial q} \frac{\partial q}{\partial y}$$

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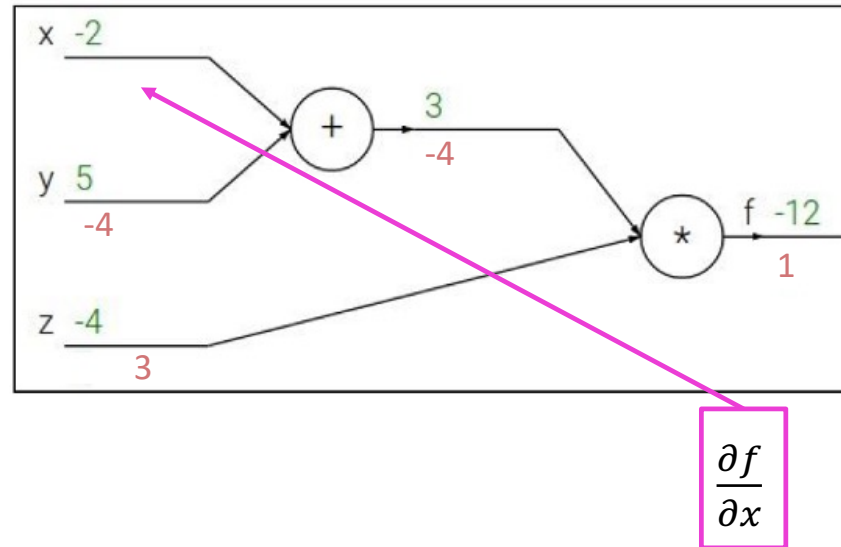
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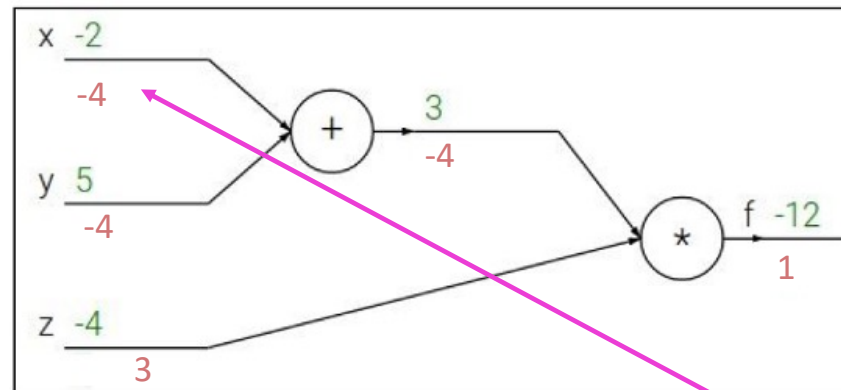
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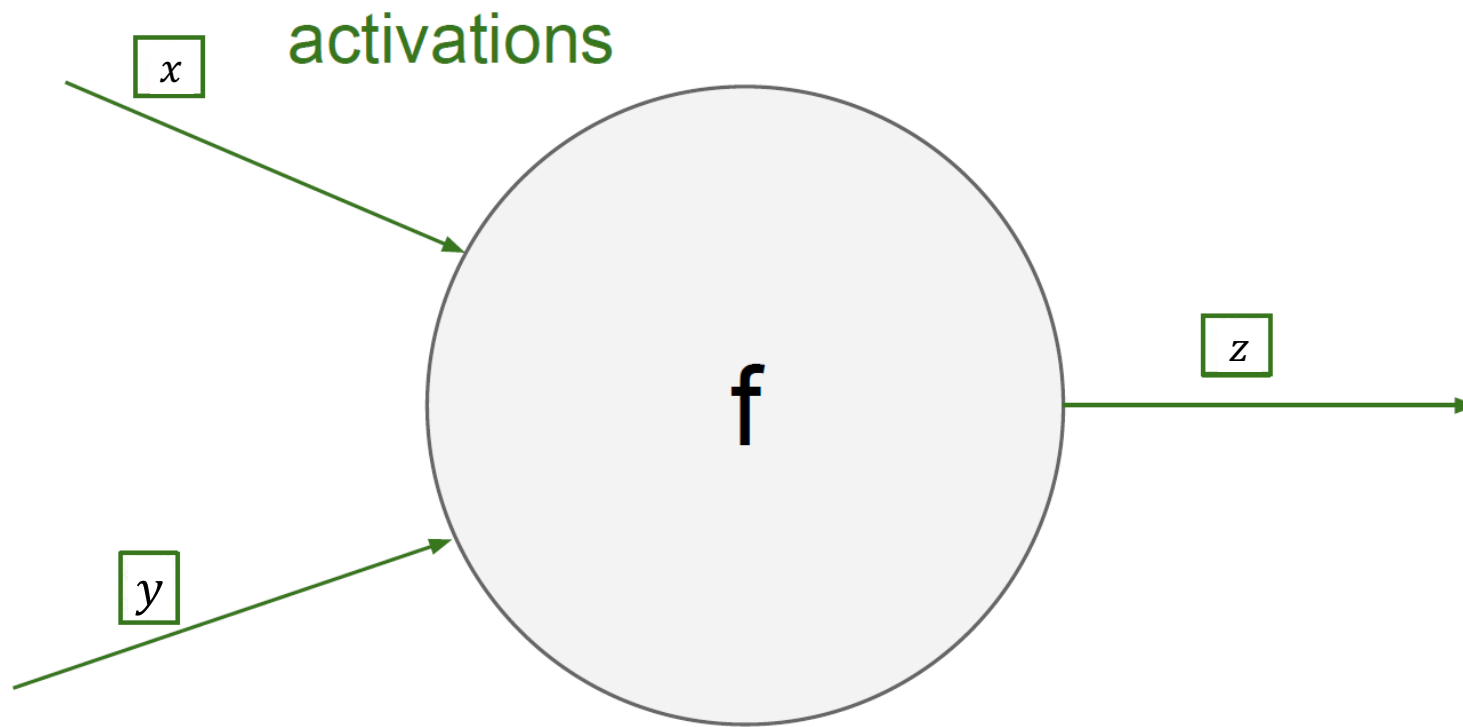


$$\frac{\partial f}{\partial x}$$

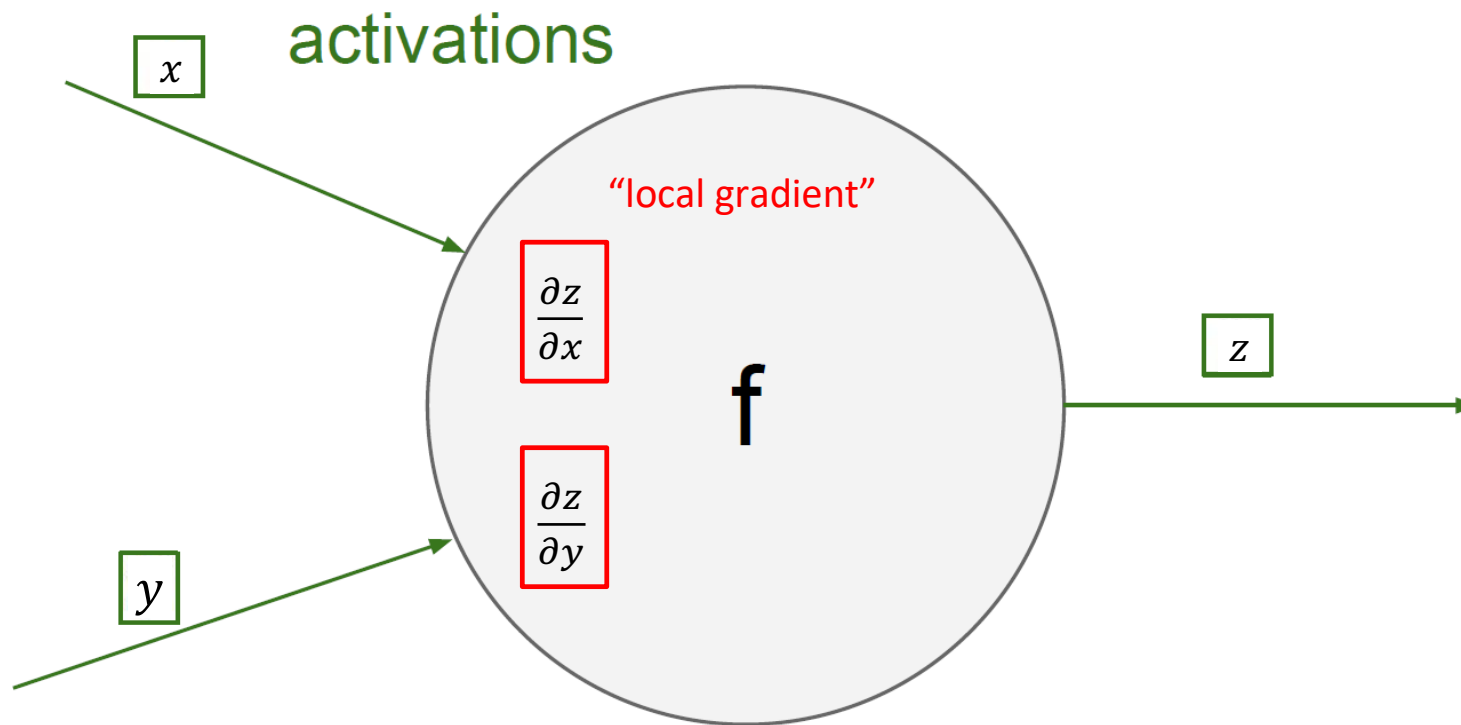
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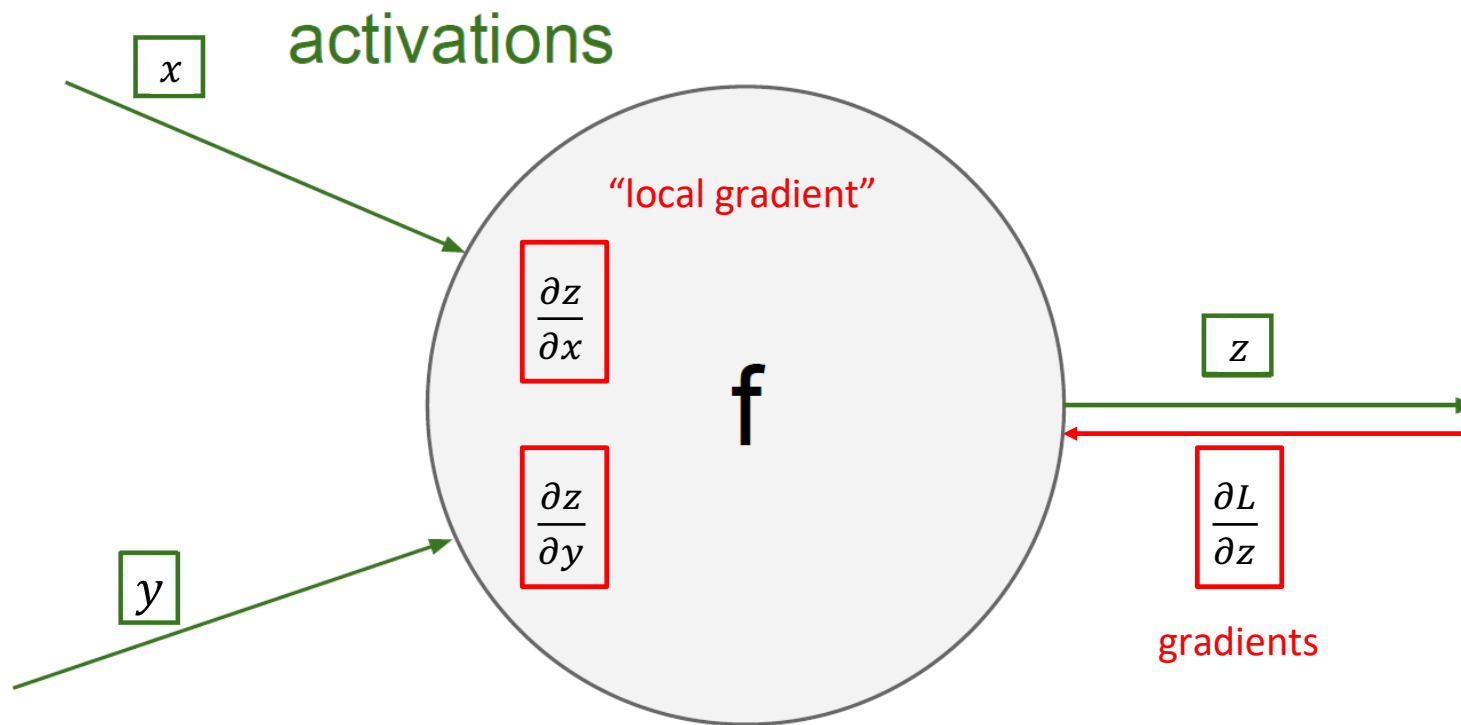
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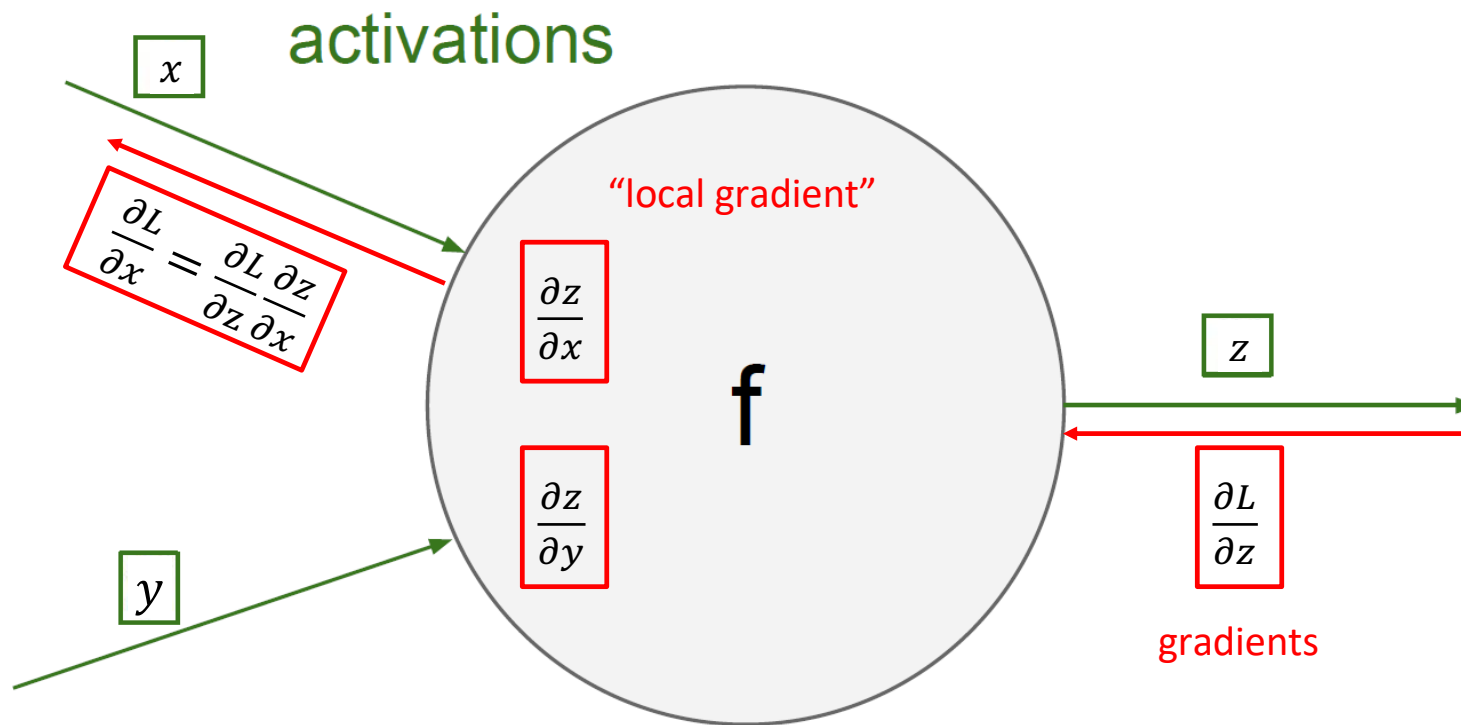
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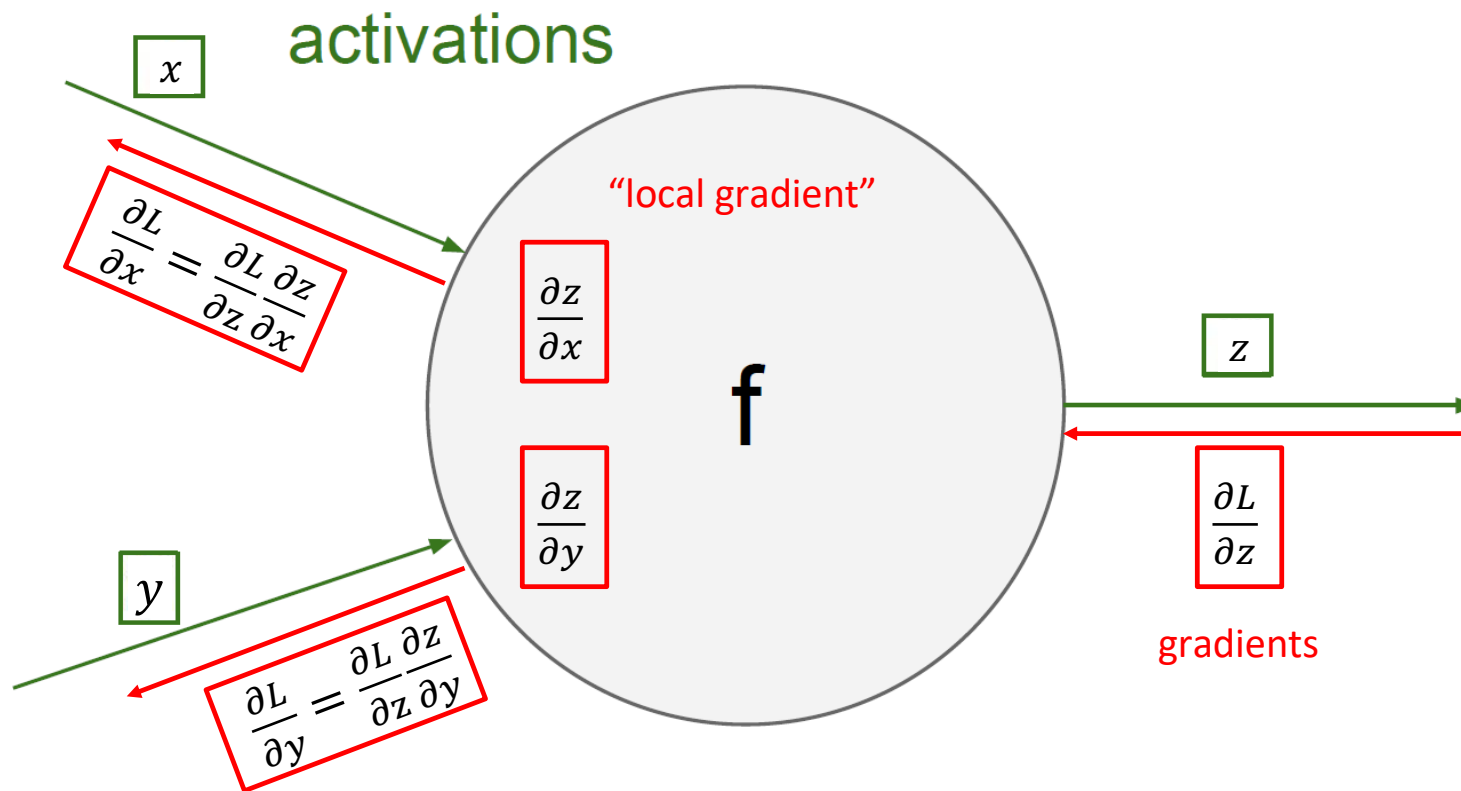
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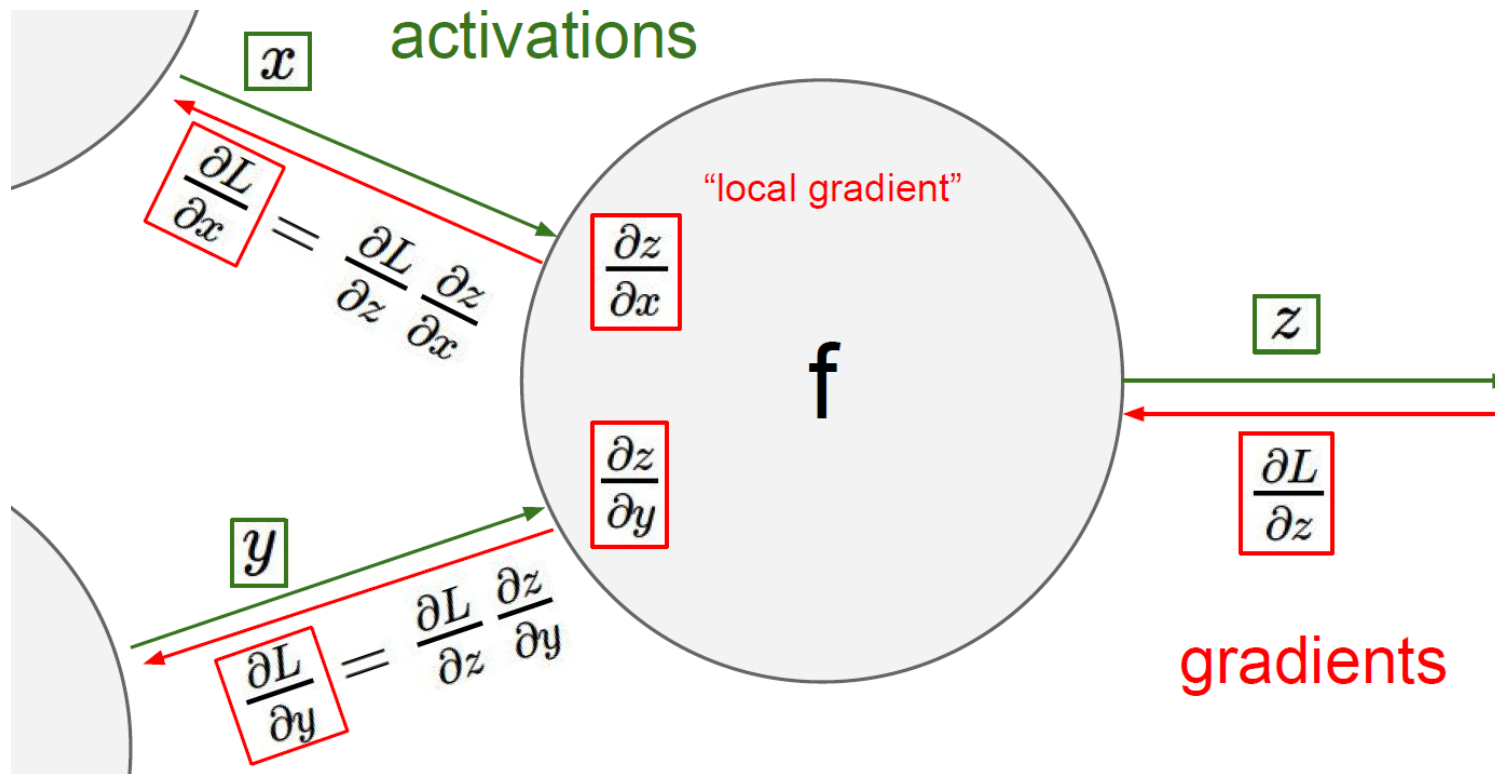
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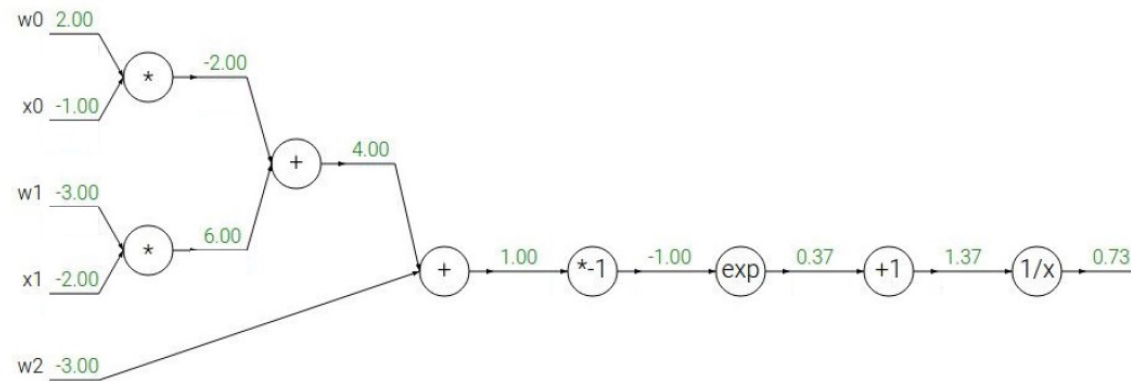


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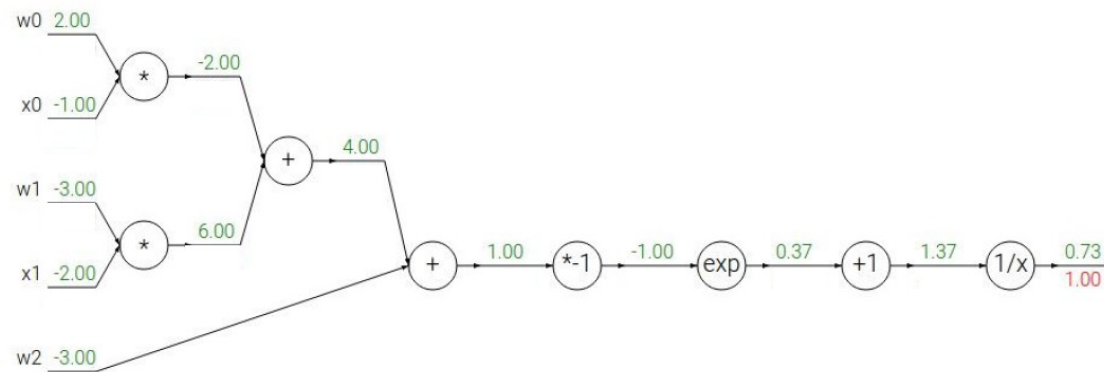
Chain rule

Another example: $f(w, x) = \frac{1}{1 + e^{-(w_0x_0 + w_1x_1 + w_2)}}$



Chain rule

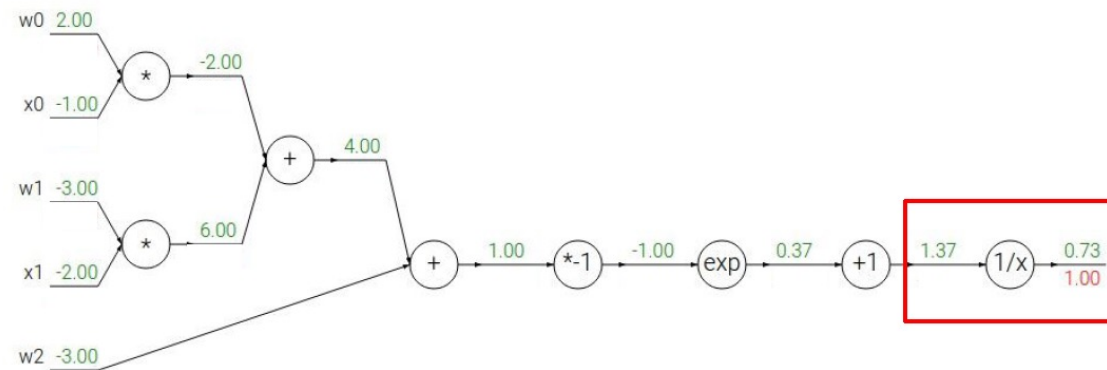
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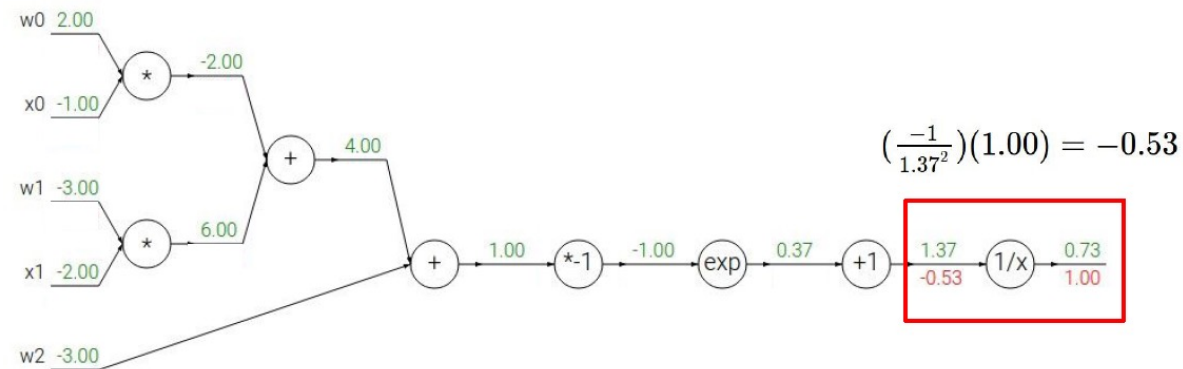
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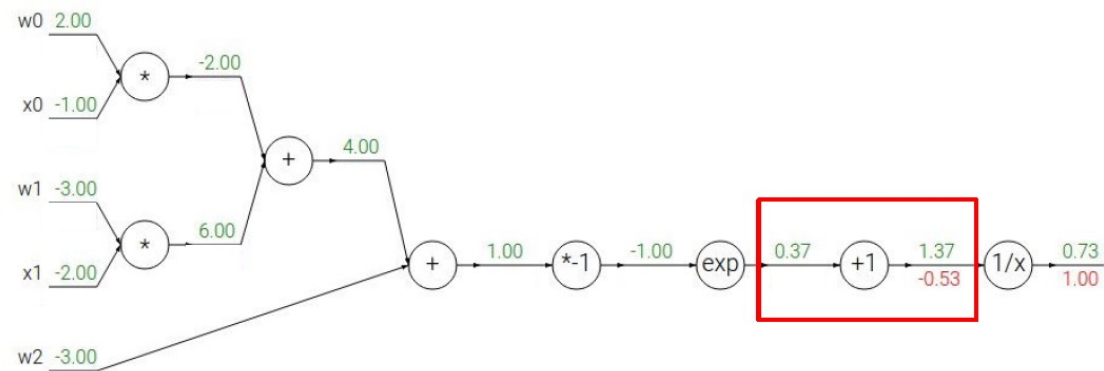
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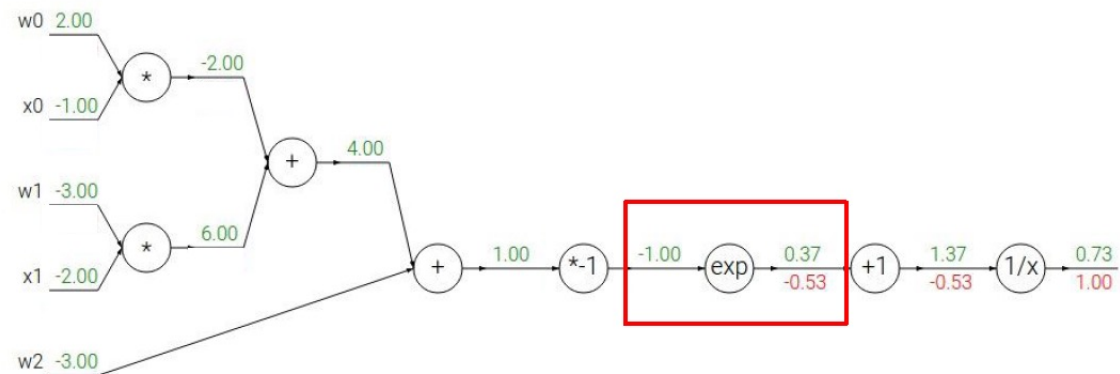
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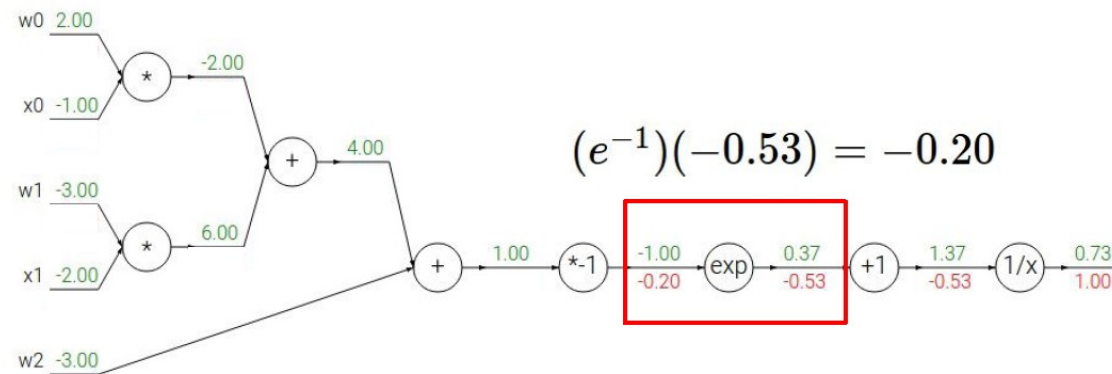
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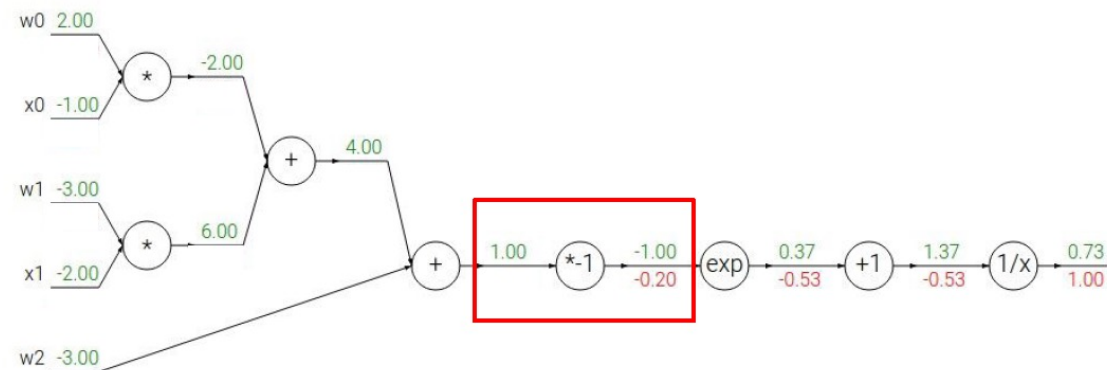


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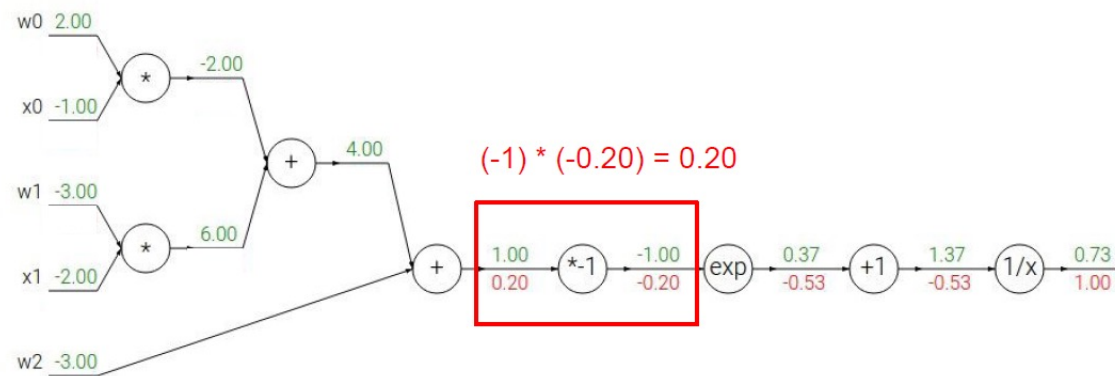
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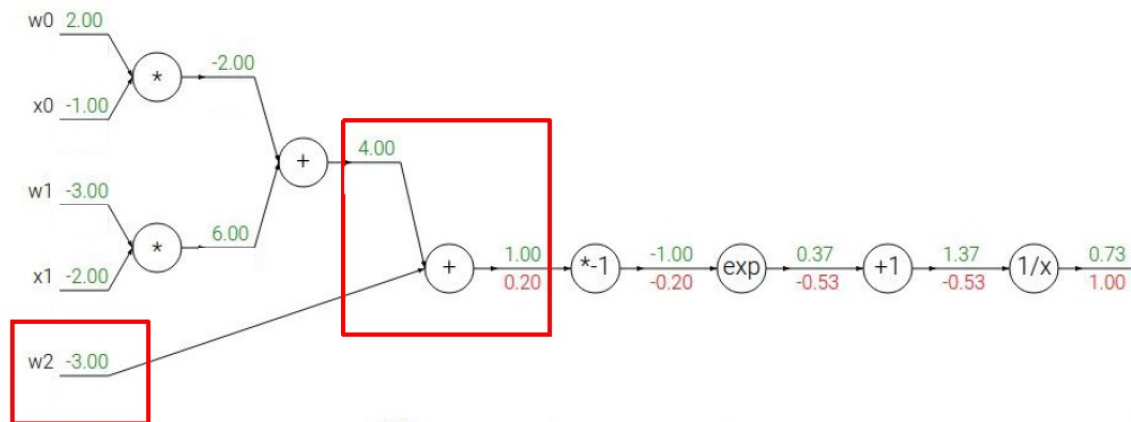
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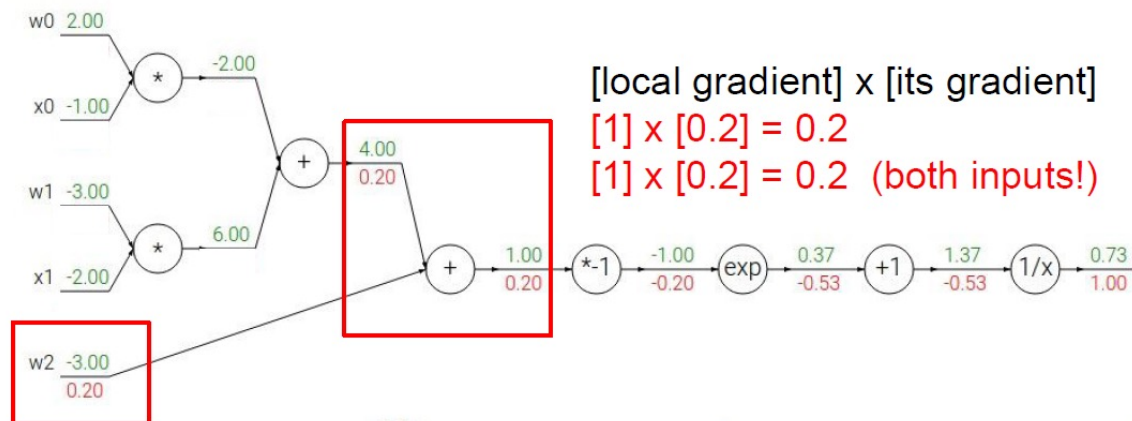
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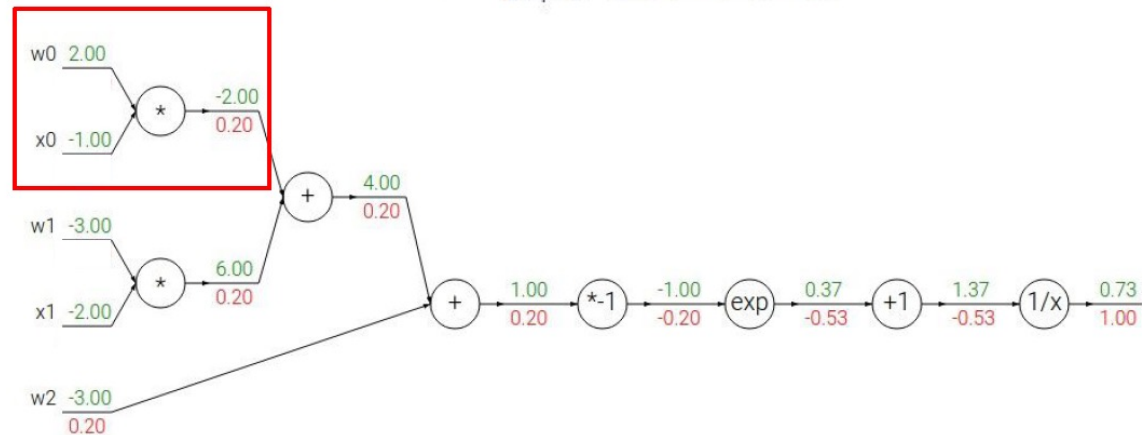


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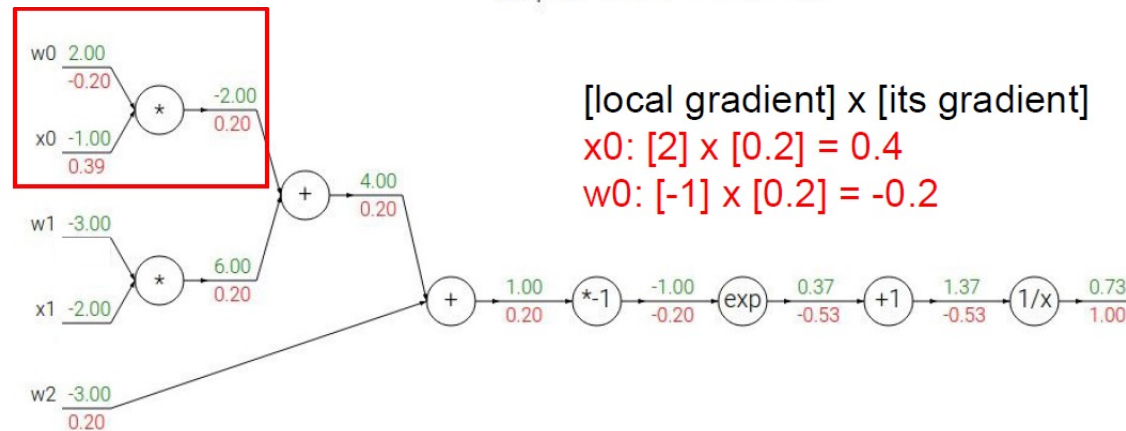
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Chain rule

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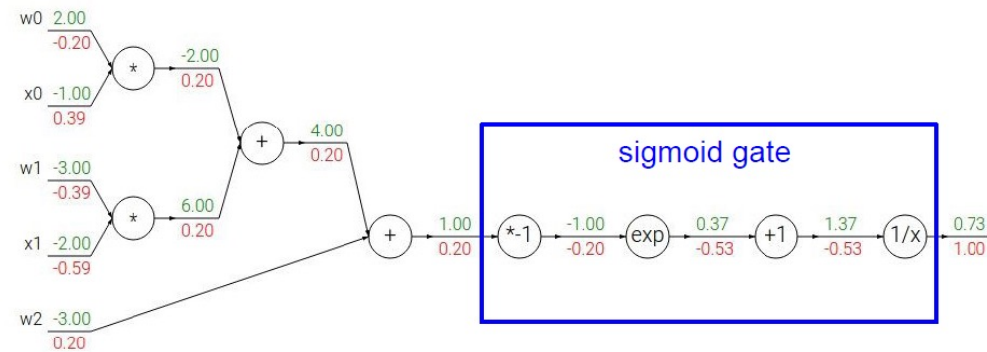
| | | | | | | |
|---------------|---------------|-----------------------|--|----------------------|---------------|--------------------------|
| $f(x) = e^x$ | \rightarrow | $\frac{df}{dx} = e^x$ | | $f(x) = \frac{1}{x}$ | \rightarrow | $\frac{df}{dx} = -1/x^2$ |
| $f_a(x) = ax$ | \rightarrow | $\frac{df}{dx} = a$ | | $f_c(x) = c + x$ | \rightarrow | $\frac{df}{dx} = 1$ |

Sigmoid

$$f(w, x) = \frac{1}{1 + e^{-(w_0x_0 + w_1x_1 + w_2)}}$$

$$\sigma(x) = \frac{1}{1 + e^{-x}} \quad \text{sigmoid function}$$

$$\frac{d\sigma(x)}{dx} = \frac{e^{-x}}{(1 + e^{-x})^2} = \left(\frac{1 + e^{-x} - 1}{1 + e^{-x}} \right) \left(\frac{1}{1 + e^{-x}} \right) = (1 - \sigma(x))\sigma(x)$$

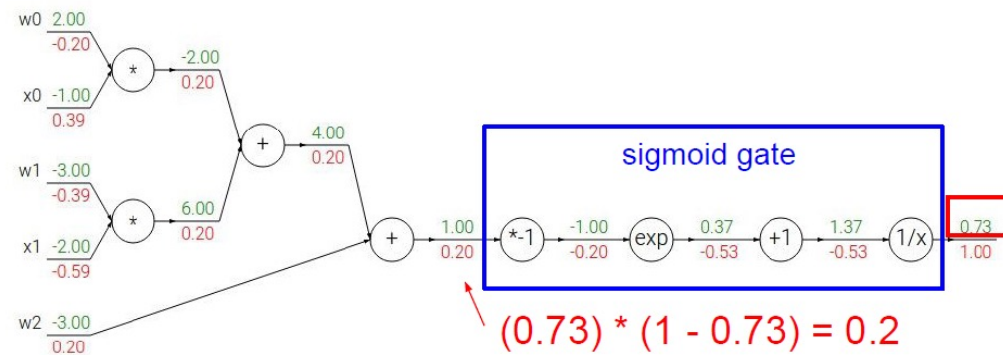


Sigmoid

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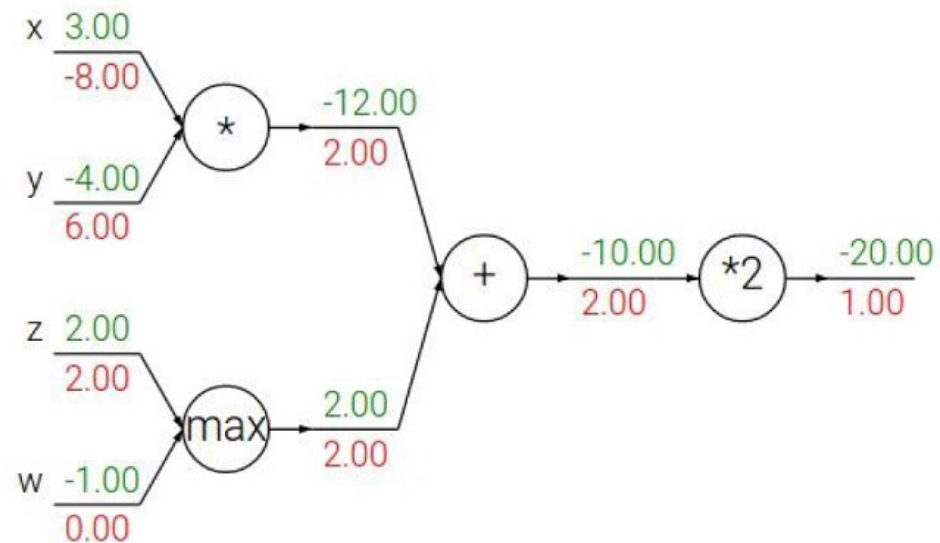
Pattern in backward flow

Patterns in backward flow

add gate: gradient distributor

max gate: gradient router

mul gate: gradient... “switcher”?



Exercise 1

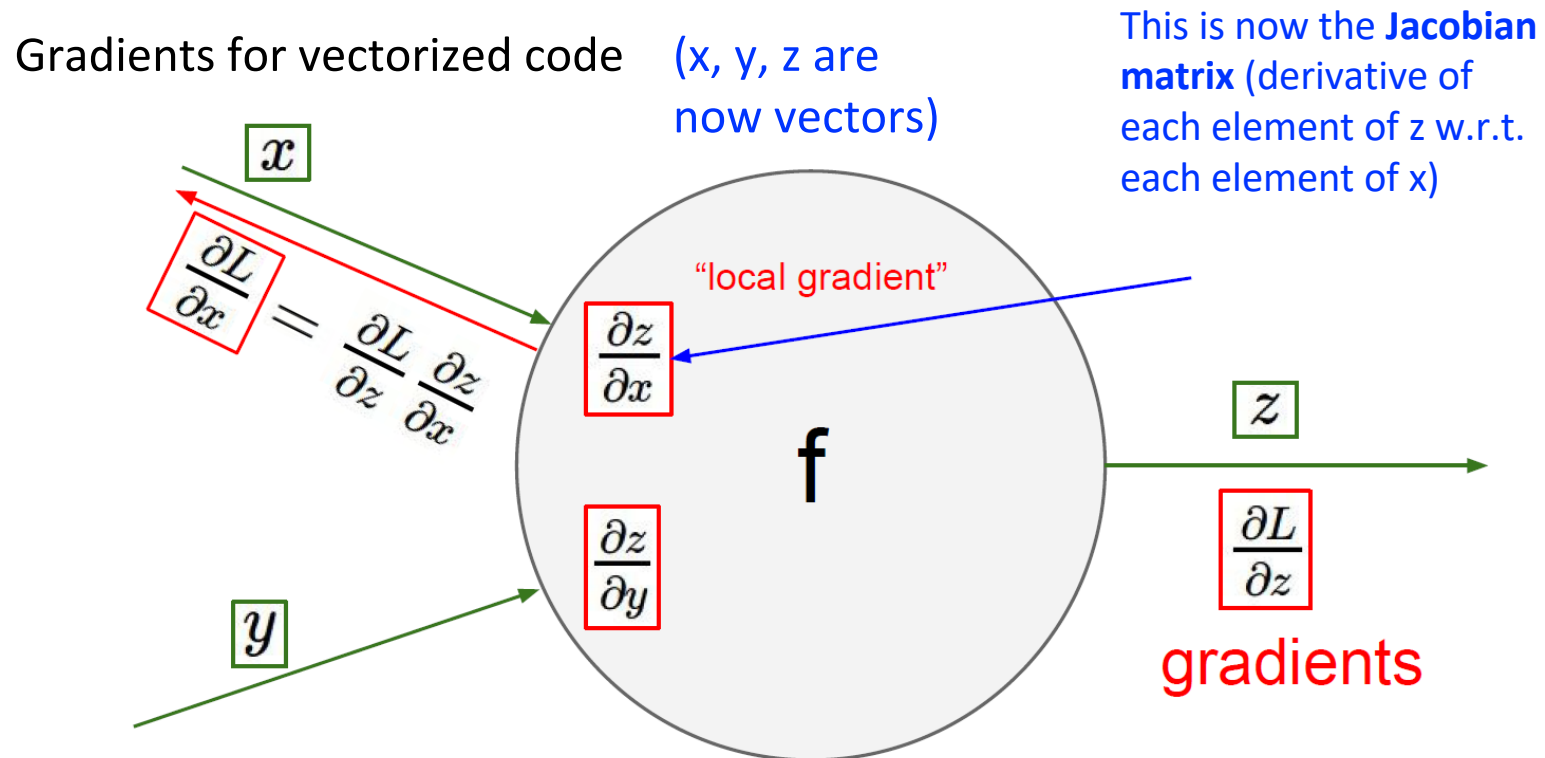
Pooling units take n values x_i , $i \in [1, n]$ and compute a scalar output whose value is invariant to permutations of the inputs.

1. The Lp-pooling module takes positive inputs and computes

$$y = (\sum_i x_i^p)^{\frac{1}{p}}, \text{ assuming we know that } y' = \frac{\partial L}{\partial y}, \text{ what is } x'_i = \frac{\partial L}{\partial x_i} ?$$

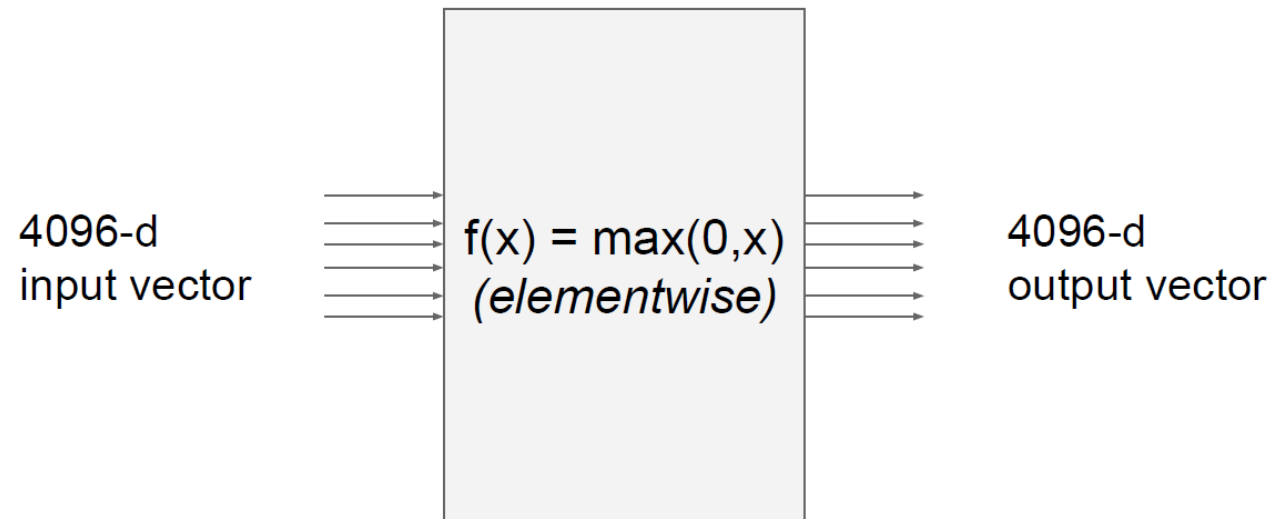
2. The log-average module computes $y = \frac{1}{\beta} \ln(\frac{1}{n} \sum_i \exp(\beta x_i))$,
assuming we know that $y' = \frac{\partial L}{\partial y}$, what is $x'_i = \frac{\partial L}{\partial x_i}$?

Gradients for vector



Gradients for vector

Vectorized operation

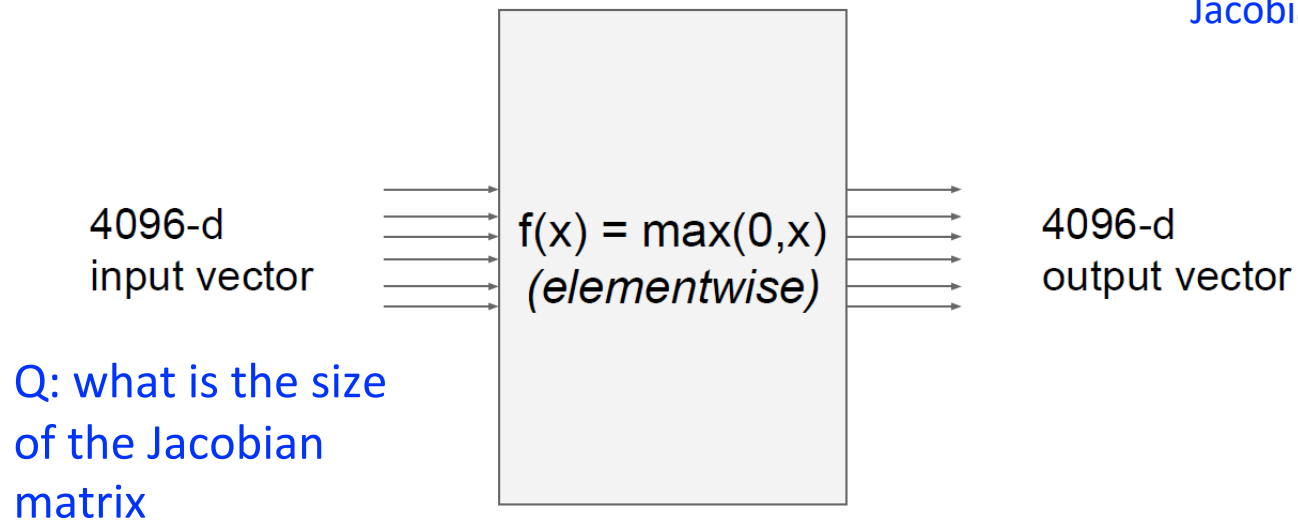


Gradients for vector

Vectorized operation

$$\frac{\partial L}{\partial x} = \boxed{\frac{\partial f}{\partial x}} \frac{\partial L}{\partial f}$$

Jacobian matrix



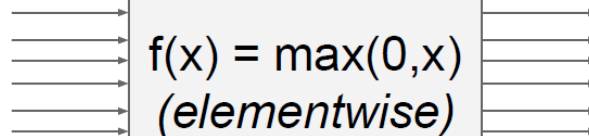
Gradients for vector

Vectorized operation

$$\frac{\partial L}{\partial x} = \boxed{\frac{\partial f}{\partial x}} \frac{\partial L}{\partial f}$$

Jacobian matrix

4096-d
input vector



4096-d
output vector

Q: what is the size
of the Jacobian
matrix
[4096 x 4096!]

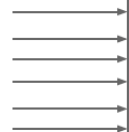
Q2: what does it look
like?

Gradients for vector

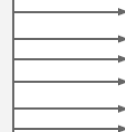
Vectorized operation

in practice we process an entire minibatch (e.g. 100) of examples at one time:

100 4096-d
input vectors



$f(x) = \max(0, x)$
(*elementwise*)



100 4096-d
output vectors

i.e. Jacobian would technically be a
[409,600 x 409,600] matrix :\\

Gradients for vector

A vectorized example: $f(x, W) = \|W \cdot x\|^2 = \sum_{i=1}^n (W \cdot x)_i^2$

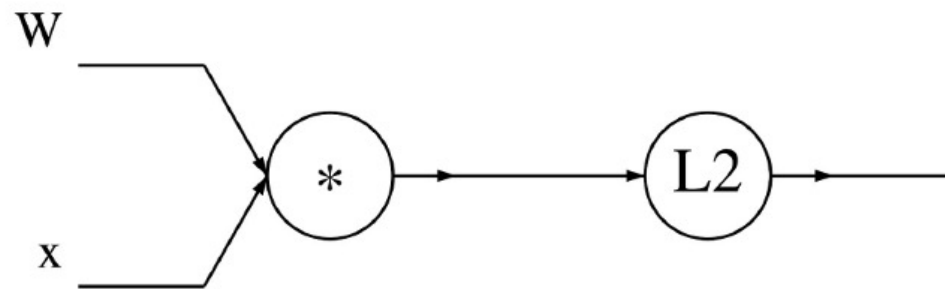
Gradients for vector

A vectorized example: $f(x, W) = \|W \cdot x\|^2 = \sum_{i=1}^n (W \cdot x)_i^2$

$\Downarrow \quad \Downarrow$
 $x \in \mathbb{R}^n \quad W \in \mathbb{R}^{n \times n}$

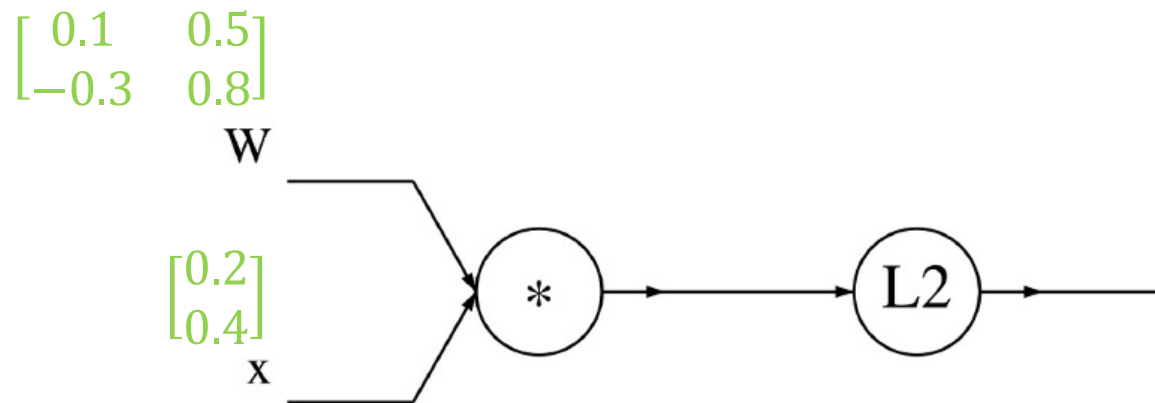
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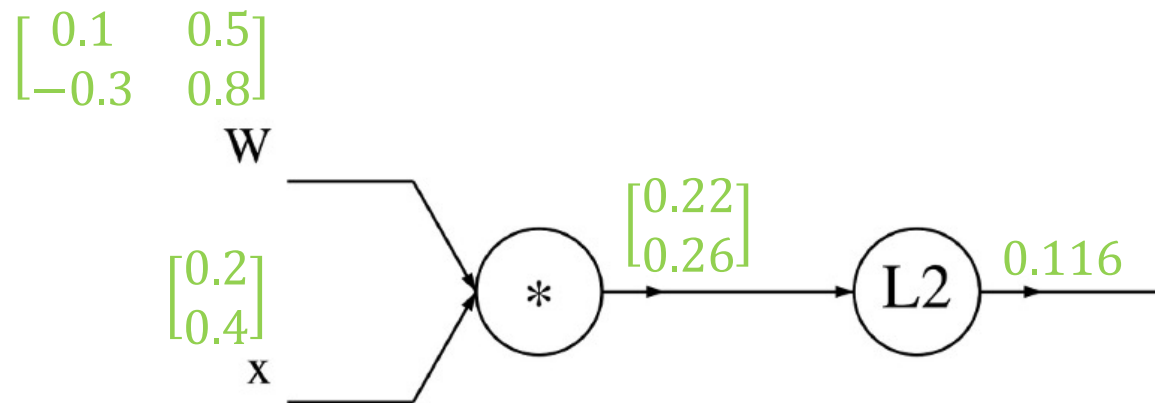


$$q = W \cdot x = \begin{pmatrix} W_{1,1}x_1 + \cdots + W_{1,n}x_n \\ \vdots \\ W_{n,1}x_1 + \cdots + W_{n,n}x_n \end{pmatrix}$$

$$f(q) = \|q\|^2 = q_1^2 + \cdots + q_n^2$$

Gradients for vector

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Gradients for vector

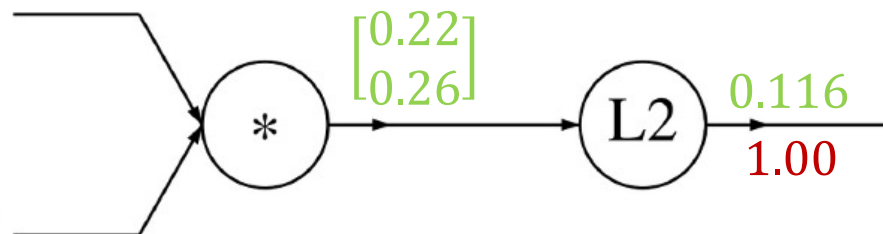
A vectorized example: $f(x, W) = \|W \cdot x\|^2 = \sum_{i=1}^n (W \cdot x)_i^2$

$$\begin{bmatrix} 0.1 & 0.5 \\ -0.3 & 0.8 \end{bmatrix}$$

W

$$\begin{bmatrix} 0.2 \\ 0.4 \end{bmatrix}$$

x



$$q = W \cdot x = \begin{pmatrix} W_{1,1}x_1 + \cdots + W_{1,n}x_n \\ \vdots \\ W_{n,1}x_1 + \cdots + W_{n,n}x_n \end{pmatrix}$$

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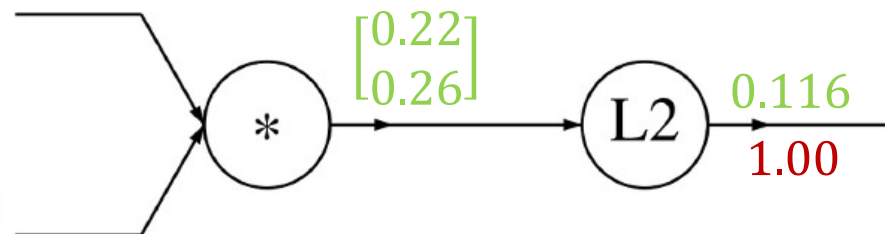
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$$\frac{\partial f}{\partial q_i} = 2q_i$$

$$\boxed{\nabla_q f = 2q}$$

Gradients for vector

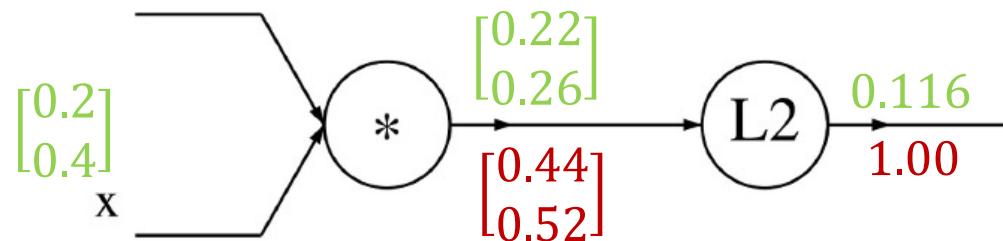
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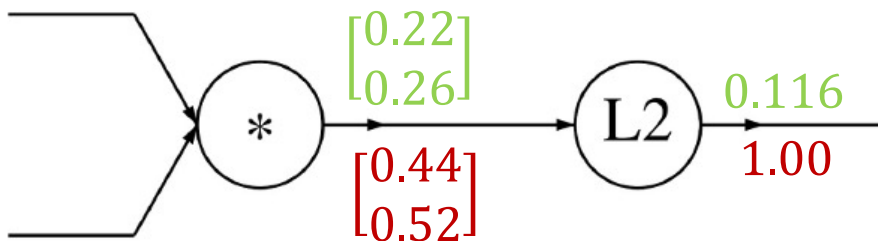
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x



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$$\frac{\partial q_k}{\partial W_{i,j}} = \mathbf{1}_{k=i} x_j$$

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Gradients for vector

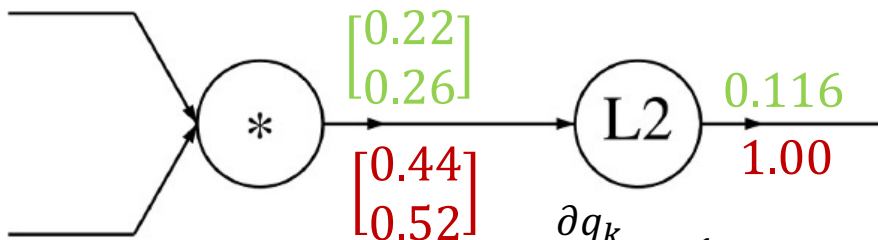
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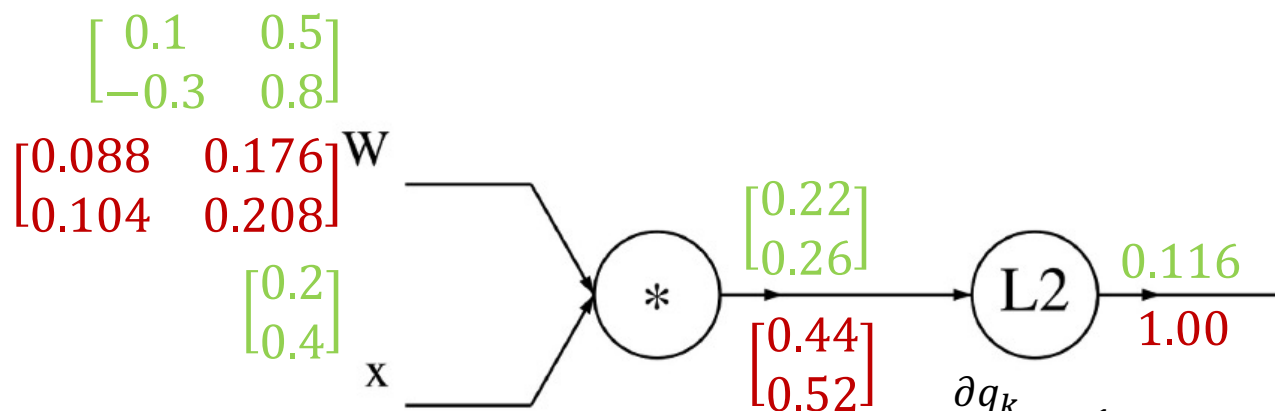
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$$\begin{aligned} \frac{\partial f}{\partial W_{i,j}} &= \sum_k \frac{\partial f}{\partial q_k} \frac{\partial q_k}{\partial W_{i,j}} \\ &= \sum_k (2q_k)(\mathbf{1}_{k=i}x_j) \\ &= 2q_i x_j \end{aligned}$$

Gradients for vector

A vectorized example: $f(x, W) = \|W \cdot x\|^2 = \sum_{i=1}^n (W \cdot x)_i^2$



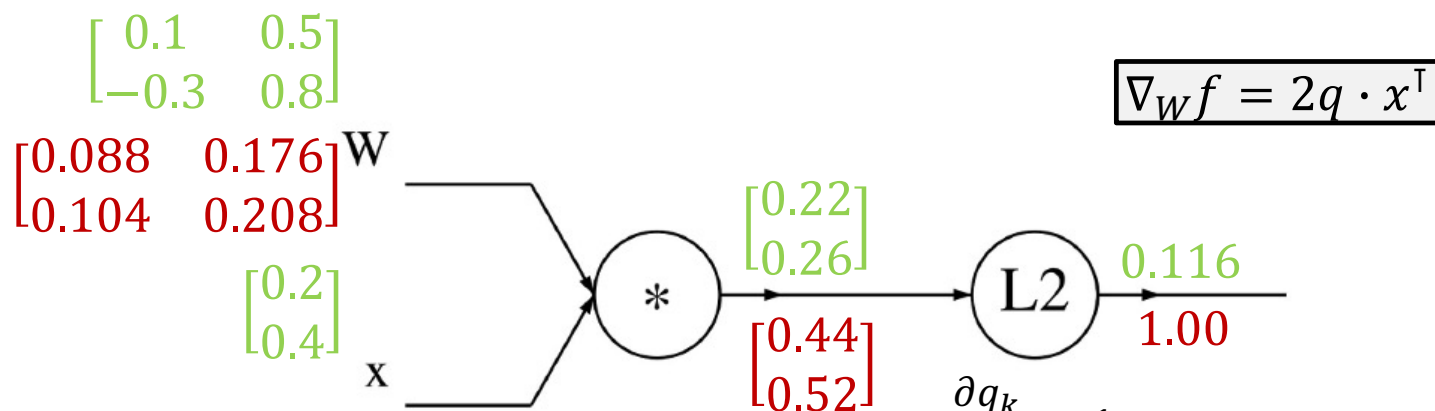
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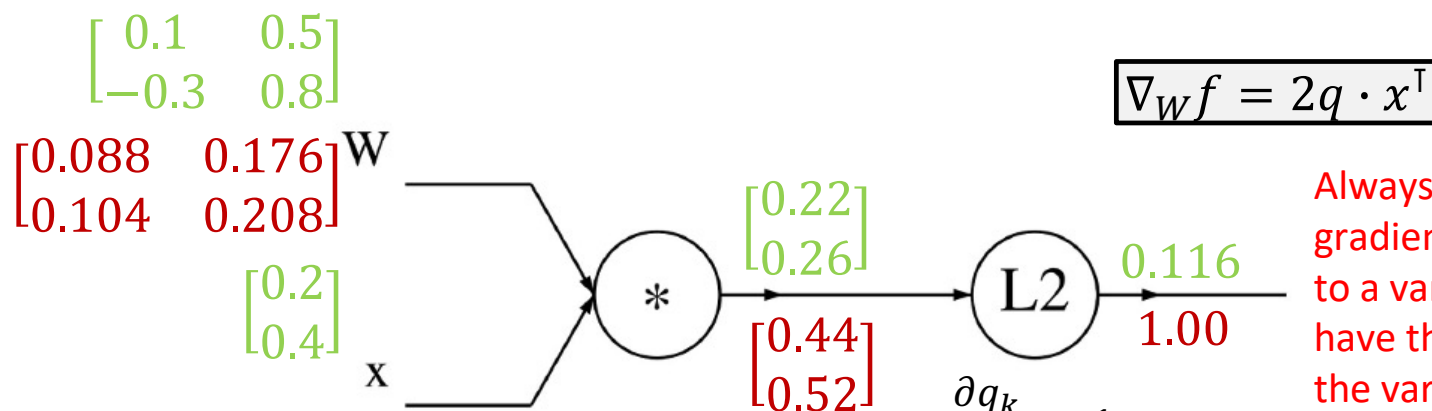
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Gradients for vector

A vectorized example: $f(x, W) = \|W \cdot x\|^2 = \sum_{i=1}^n (W \cdot x)_i^2$



Always check: The gradient with respect to a variable should have the same shape as the variable

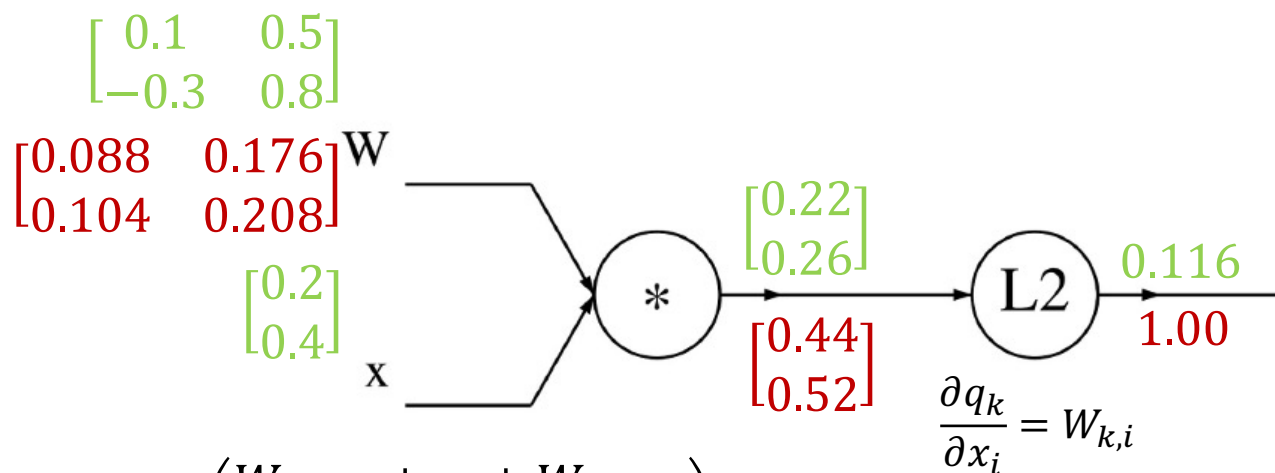
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Gradients for vector

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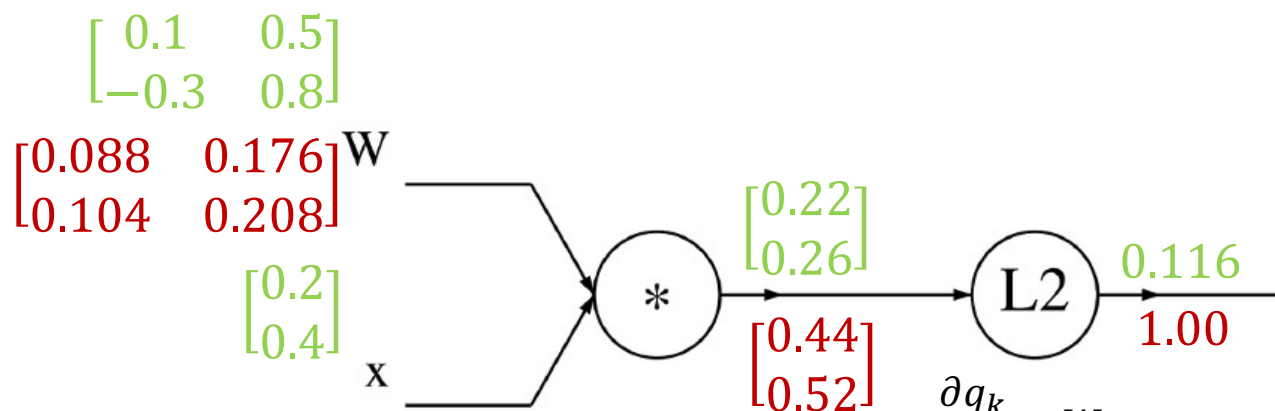


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Gradients for vector

A vectorized example: $f(x, W) = \|W \cdot x\|^2 = \sum_{i=1}^n (W \cdot x)_i^2$

